



A Three Element Viscoelastic Isolator

FAC-1

**Presented at : Damping '91
February 13-15, 1991
Catamaran Hotel
San Diego, CA**

**S. S. Simonian
14 February 1991**

AGENDA

- **PROBLEM**
- **STRUCTURE CONFIGURATION**
- **BASELINE RWA ISOLATOR DESIGN**
- **ISOLATOR CHARACTERISTICS**
- **SOME TEST RESULTS**

FA-C-2

PROBLEM

- **EXCESSIVE SENSOR LOS DISTURBANCES**
- **REACTION WHEEL INDUCED DISTURBANCES**
 - **STATIC UNBALANCE**
 - **DYNAMIC UNBALANCE**
 - **BEARING NOISE**
- **LOW STRUCTURAL DAMPING**

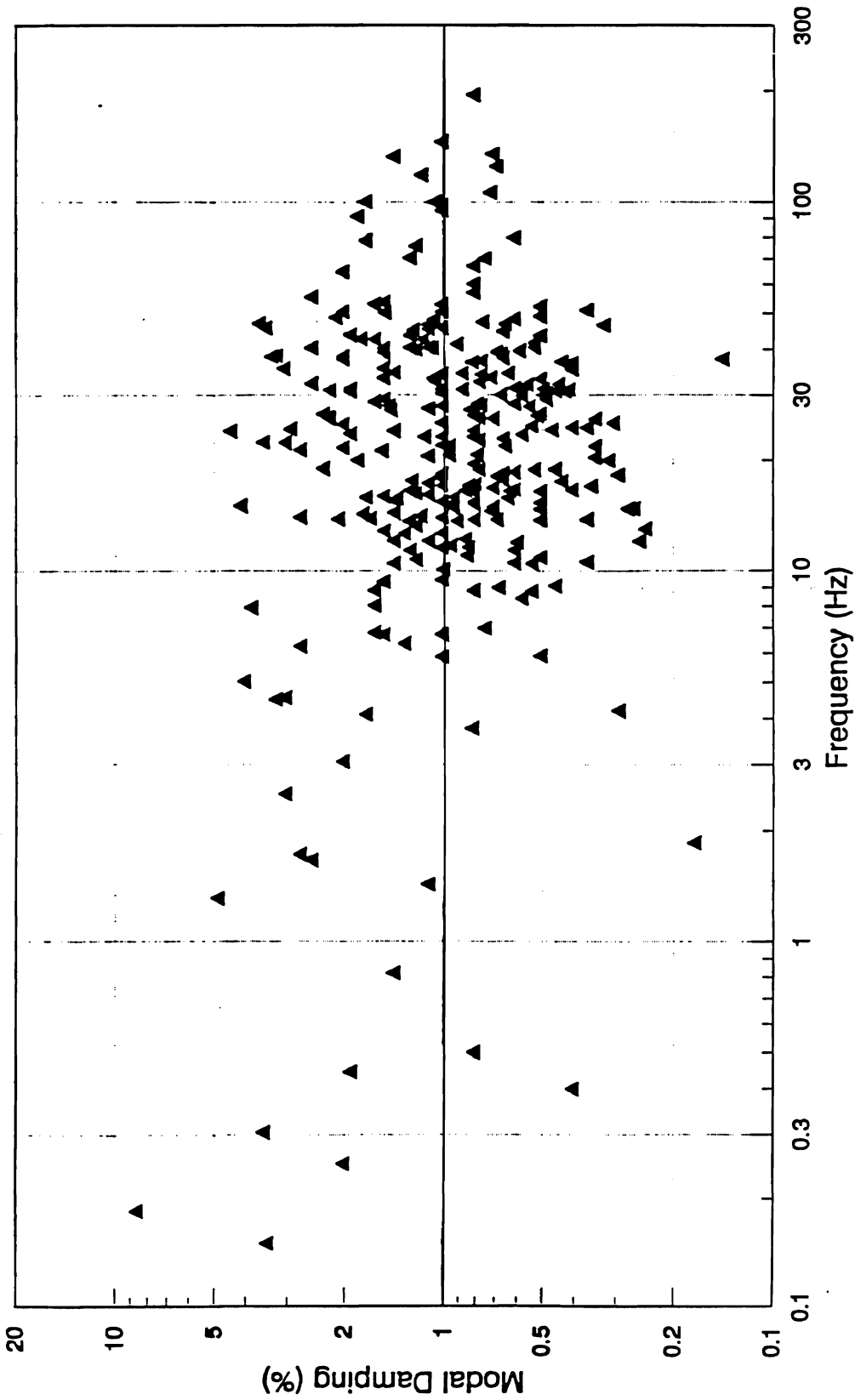
FAC-3

SPACECRAFT INHERENT DAMPING

- DATA OBTAINED FROM MEASUREMENTS OF 23 SATELLITES UNDER LOW EXCITATION INPUTS, MOSTLY DURING SINE DWELL MODAL SURVEY TESTS
- A TOTAL OF 290 SAMPLE DATA POINTS
- STRUCTURE FREQUENCY RANGE 0.15 - 195 HERTZ
- FURTHER DETAILS AND STATISTICAL DAMPING MODELS REPORTED IN:

S.S. SIMONIAN, "SURVEY OF SPACECRAFT DAMPING MEASUREMENTS: APPLICATION TO ELECTRO-OPTIC JITTER PROBLEMS", THE ROLE OF DAMPING IN VIBRATION AND NOISE CONTROL, ASME PUBLICATION DE-VOL.5, SEPTEMBER, 1987.

Low Amplitude Modal Damping Database

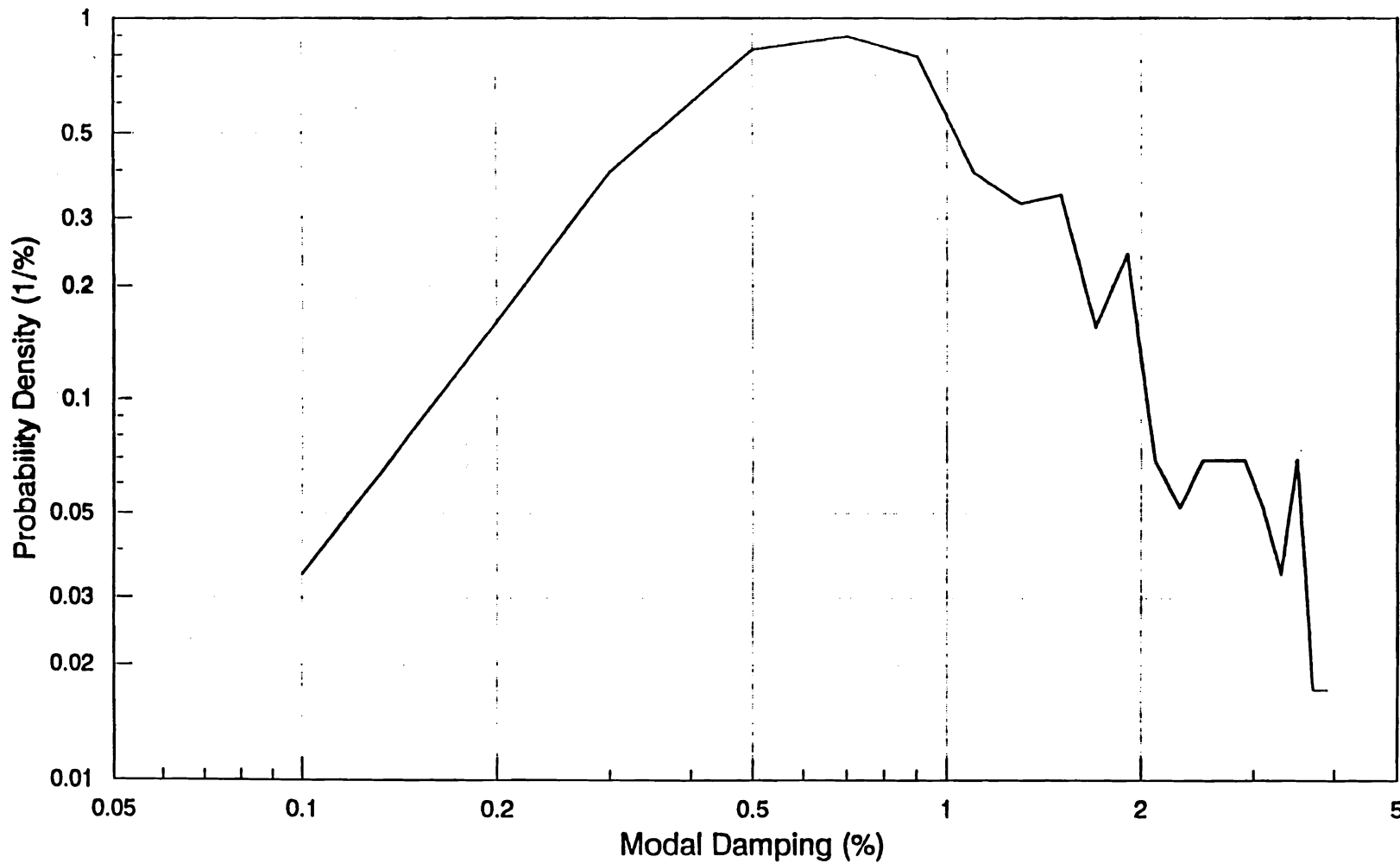


FAC-5

Data collected by S.S. Simonian
Several spacecraft are represented
DSP data has similar distribution

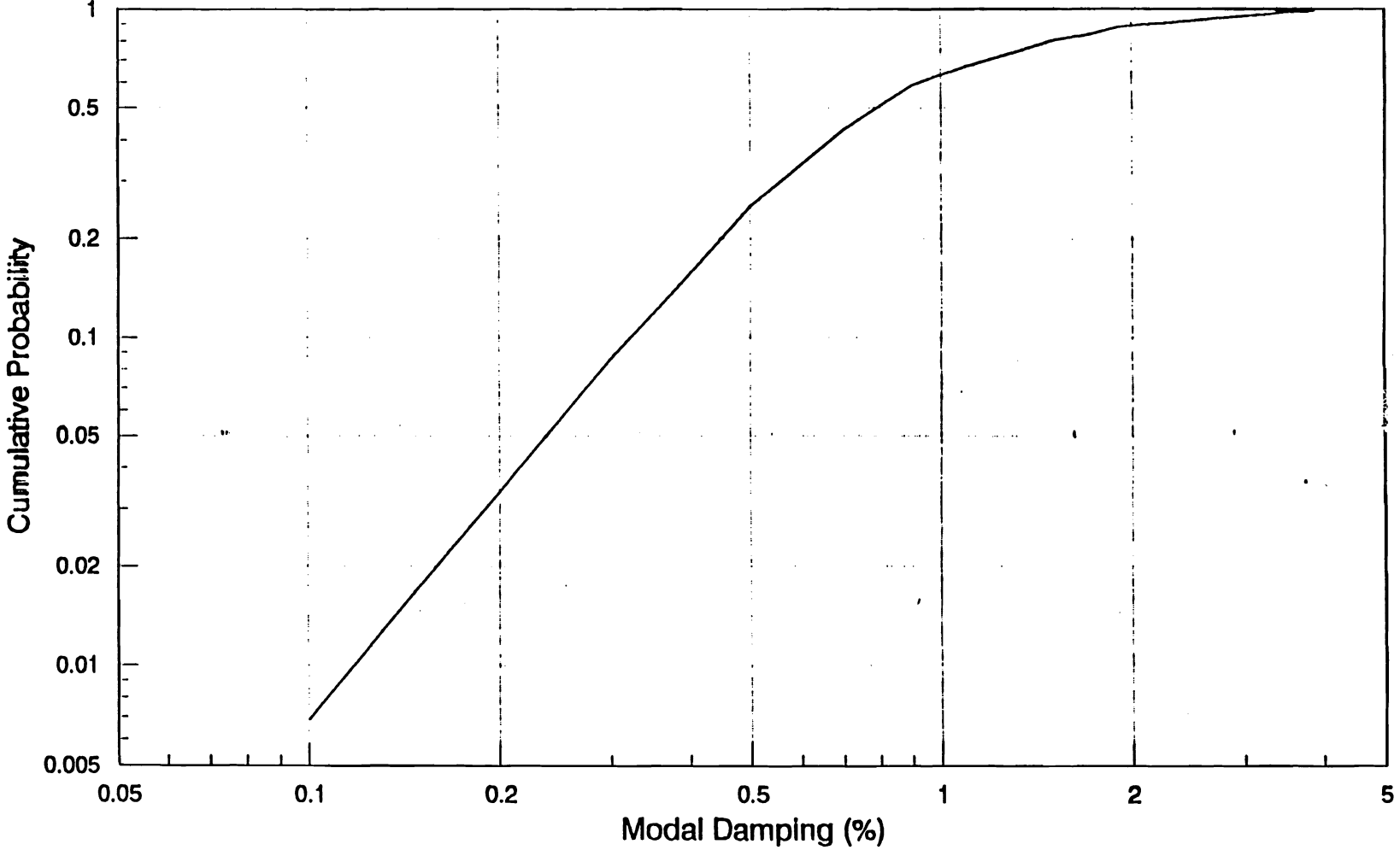
Low Amplitude Damping - Probability Density

FA-C-6



Data collected by S.S. Simonian
Several spacecraft are represented
DSP data has similar distribution

Low Amplitude Damping - Cumulative Probability



FAC-7

Data collected by S.S. Simonian
Several spacecraft are represented
DSP data has similar distribution

ROTOR STATIC & DYNAMIC UNBALANCE

FORCE OR MOMENT

$$F = \delta \cdot M \cdot \Omega^2$$

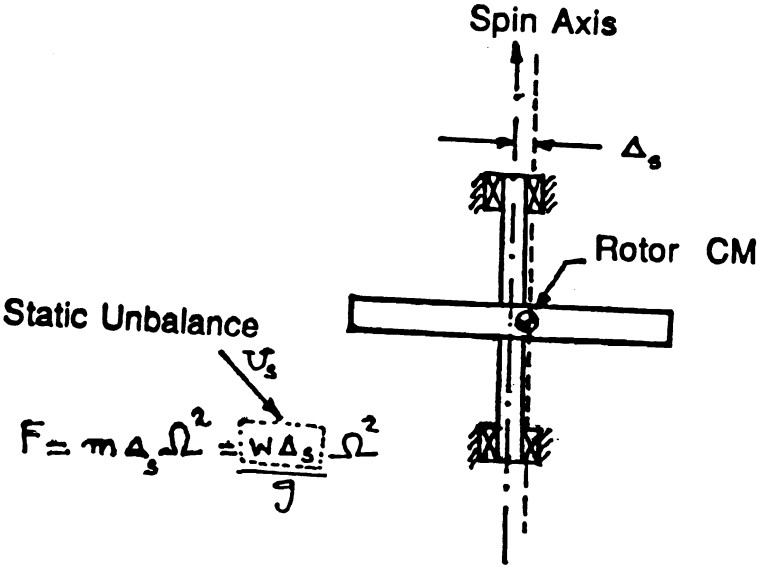
F = FORCE OR MOMENT (LB OR IN-LB)

M = ROTOR MASS (LB-SEC²/IN)

Ω = WHEEL SPEED (RAD/SEC)

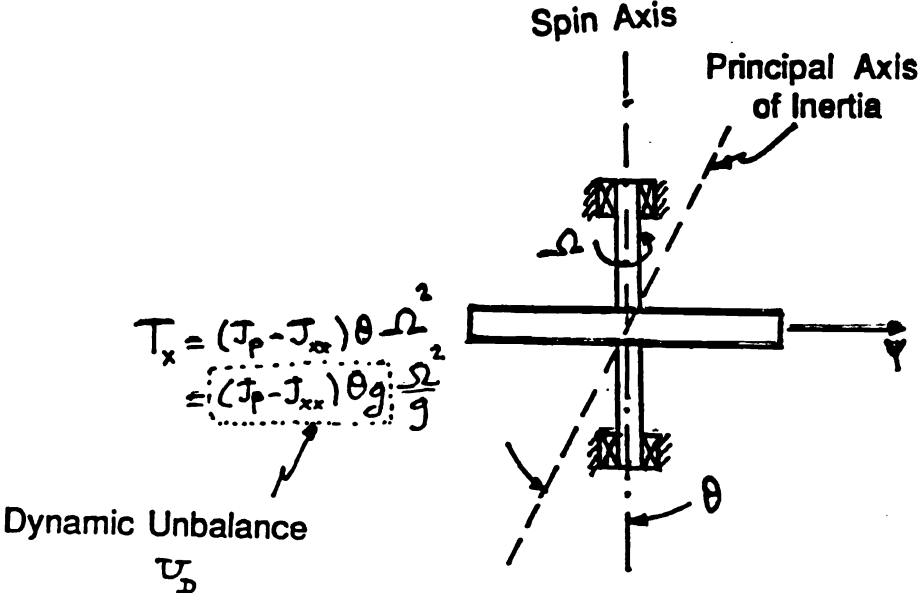
δ = CONSTANT OF PROPORTIONALITY (TABULATED)

FAC-8



Static Unbalance \mathcal{U}_s

$$F = m \Delta_s \Omega^2 = \frac{W \Delta_s}{g} \Omega^2$$

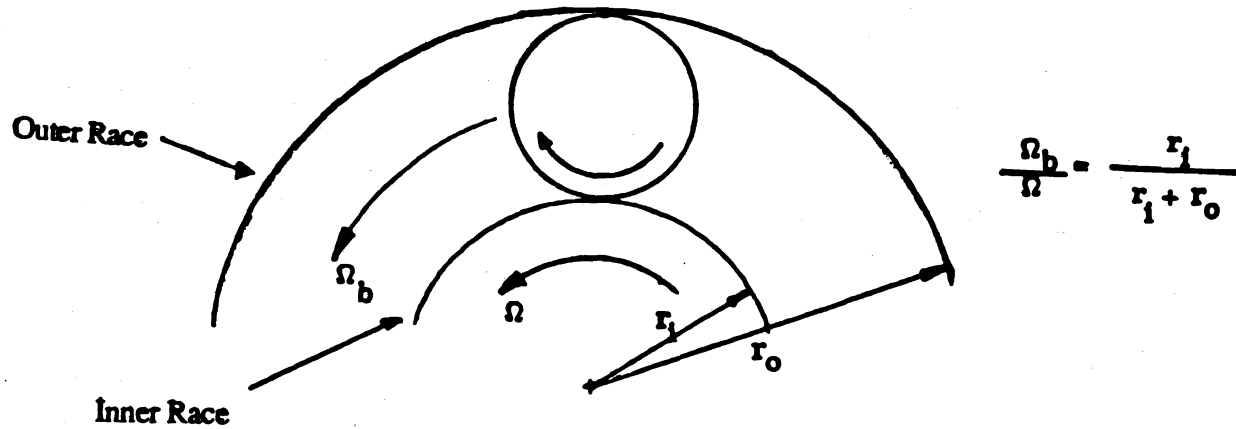


Dynamic Unbalance \mathcal{U}_D

$$T_x = (J_p - J_{xx}) \theta \Omega^2 = \frac{(J_p - J_{xx}) \theta g}{g} \Omega^2$$

BALL BEARING DISTURBANCES

BALL BEARING GEOMETRY



$$\frac{\Omega_b}{\Omega} = \frac{r_i}{r_i + r_o}$$

<u>COMPONENT</u>	<u>SPEED</u>
ROTOR/OUTER RACE	$N \times \Omega$
ROTOR/BALL GROUP	$N \times (\Omega - \Omega_b)$
BALL GROUP/OUTER RACE	$N \times \Omega_b$
BALLS/OUTER RACE	$N \times N_b \times \Omega_b$
ROTOR/BALLS	$N \times N_b \times (\Omega - \Omega_b)$

N_b = Number of balls

N = Harmonics of rotor speed, $N = 1, 2, 3, \dots$

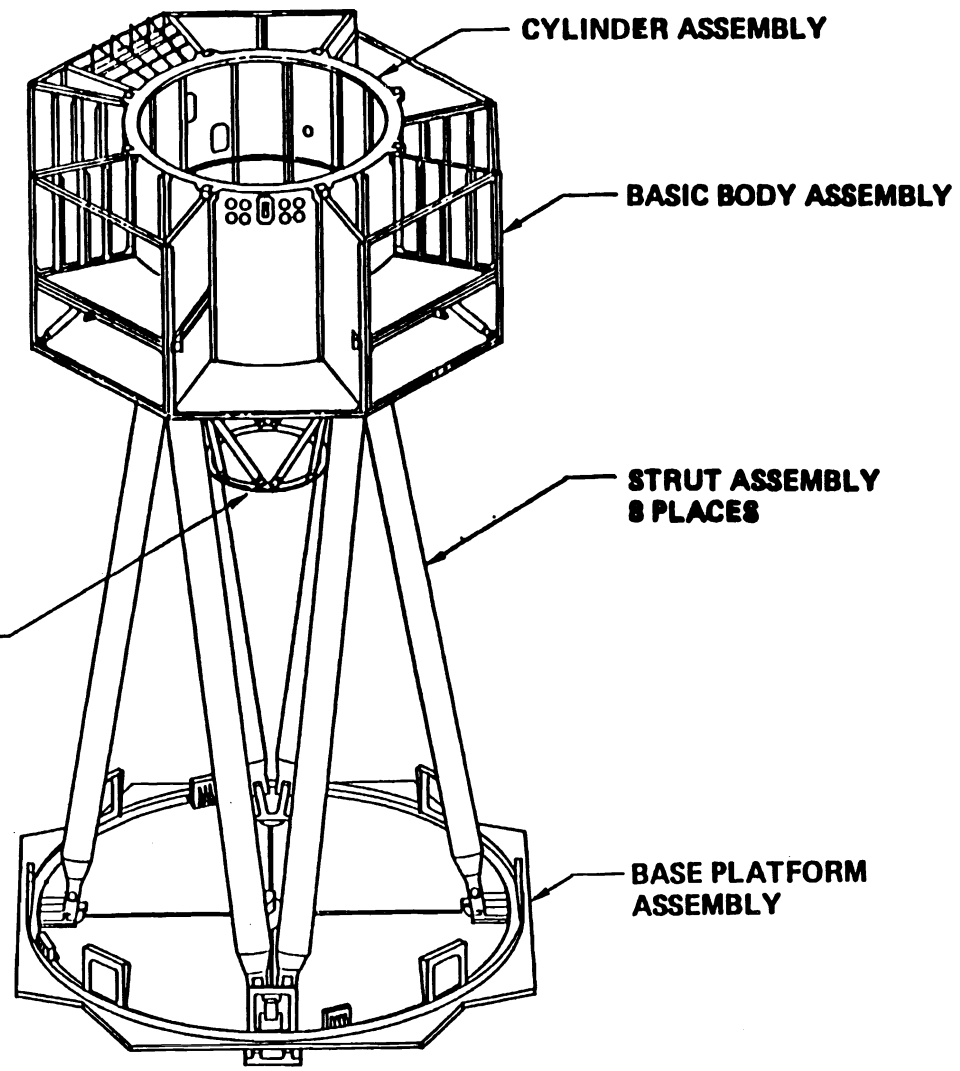
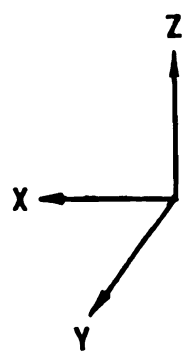
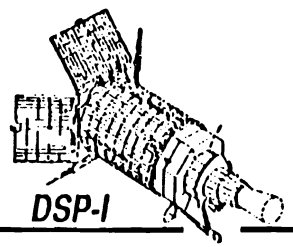
MEASURED REACTION WHEEL DISTURBANCE MODELS

● PROPORTIONALITY CONSTANTS FOR TWO TRW REACTION WHEELS

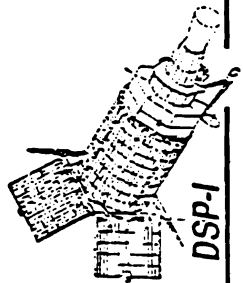
Disturbance	Harmonic	Axial Force	Lateral Force (Y)	Lateral Force (Z)	Radial Force (avg)	Lateral Moment (Y)	Lateral Moment (Z)	Radial Moment (avg)
		(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in ² · 10 ⁻⁶)	(in ² · 10 ⁻⁶)	(in ² · 10 ⁻⁶)
Ball Group / Outer Race (0.418 x Wheel Speed)	1	0.061	0.150	0.200	0.175	6.0	5.0	5.5
	2	0.081	0.040	0.040	0.040	1.5	5.0	3.3
	3	0.098	0.040	0.080	0.060	3.0	3.0	3.0
	4	0.175	0.150	0.200	0.175	1.5	3.0	2.3
Ball Group / Inner Race (0.582 x Wheel Speed)	1	0.051	0.030	0.020	0.025	2.0	2.0	2.0
	2	0.177	0.020	0.090	0.055	2.0	4.0	3.0
	3	0.179	0.200	0.200	0.200	4.0	4.0	4.0
Inner / Outer Race (1.000 x Wheel Speed)	1	13.500	1.300	1.800	1.550	550.0	500.0	530.0
	2	1.180	0.800	1.500	1.150	20.0	20.0	20.0

Disturbance	Harmonic	Axial Force	Lateral Force (Y)	Lateral Force (Z)	Radial Force (avg)	Lateral Moment (Y)	Lateral Moment (Z)	Radial Moment (avg)
		(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in · 10 ⁻⁶)	(in ² · 10 ⁻⁶)	(in ² · 10 ⁻⁶)	(in ² · 10 ⁻⁶)
Ball Group / Outer Race (0.418 x Wheel Speed)	1	0.015	0.500	0.500	0.500	6.0	6.0	6.0
	2	0.010	0.030	0.070	0.050	3.0	0.7	1.9
	3	0.091	0.090	0.110	0.100	2.0	6.0	4.0
	4	0.371	0.200	0.110	0.155	2.0	1.5	1.8
Ball Group / Inner Race (0.582 x Wheel Speed)	1	0.026	0.020	0.020	0.020	3.0	3.0	3.0
	2	0.382	0.040	0.050	0.045	4.0	4.0	4.0
	3	0.383	0.200	0.100	0.150	7.0	7.0	7.0
Inner / Outer Race (1.000 x Wheel Speed)	1	1.230	3.000	2.500	2.750	400.0	400.0	400.0
	2	1.450	0.500	0.700	0.600	10.0	10.0	10.0

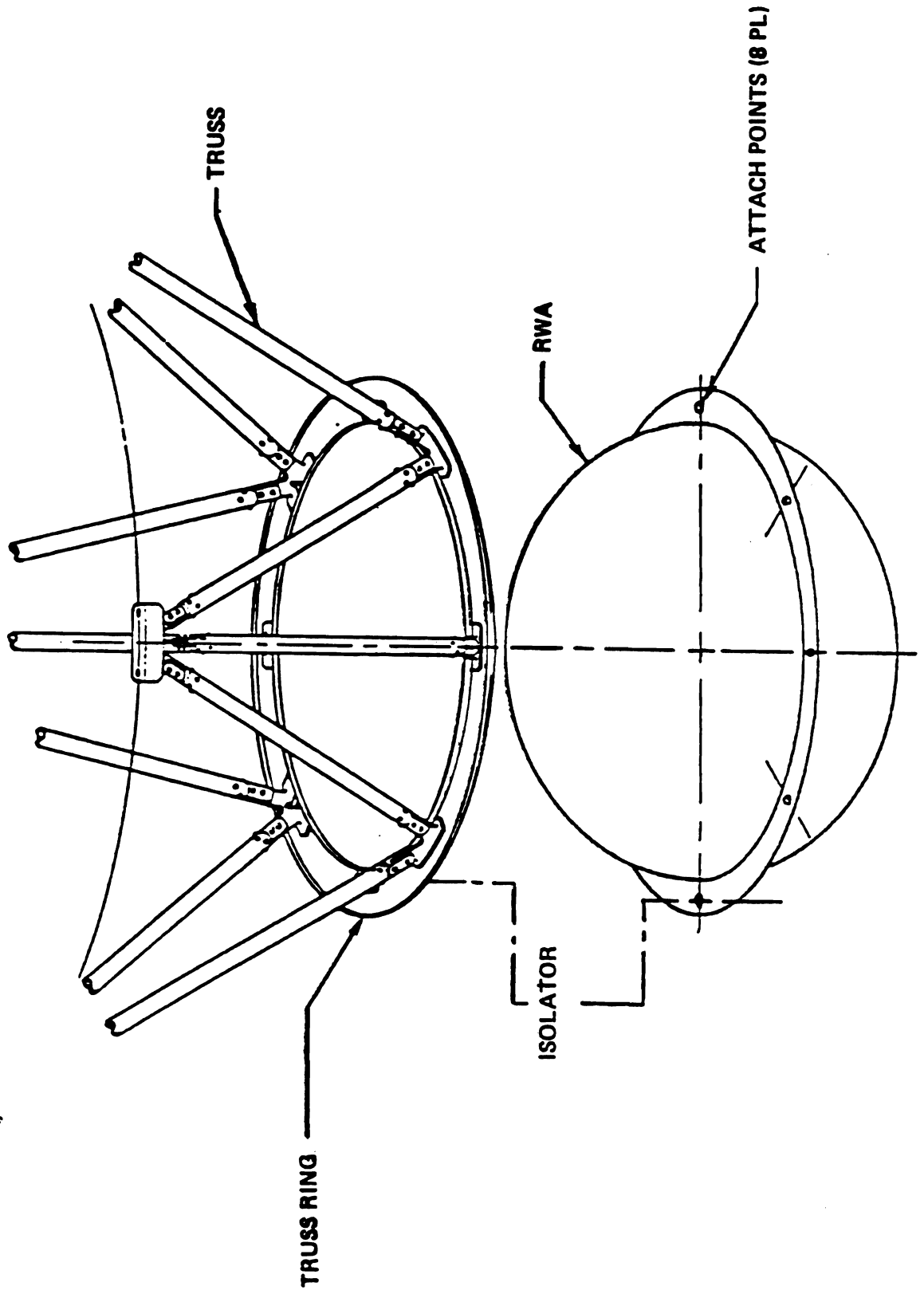
DSP Basic Structure Assembly

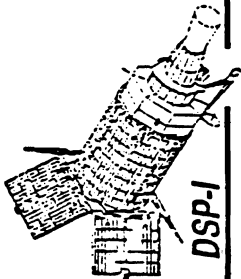


FAC-11



RWA and Truss Assembly

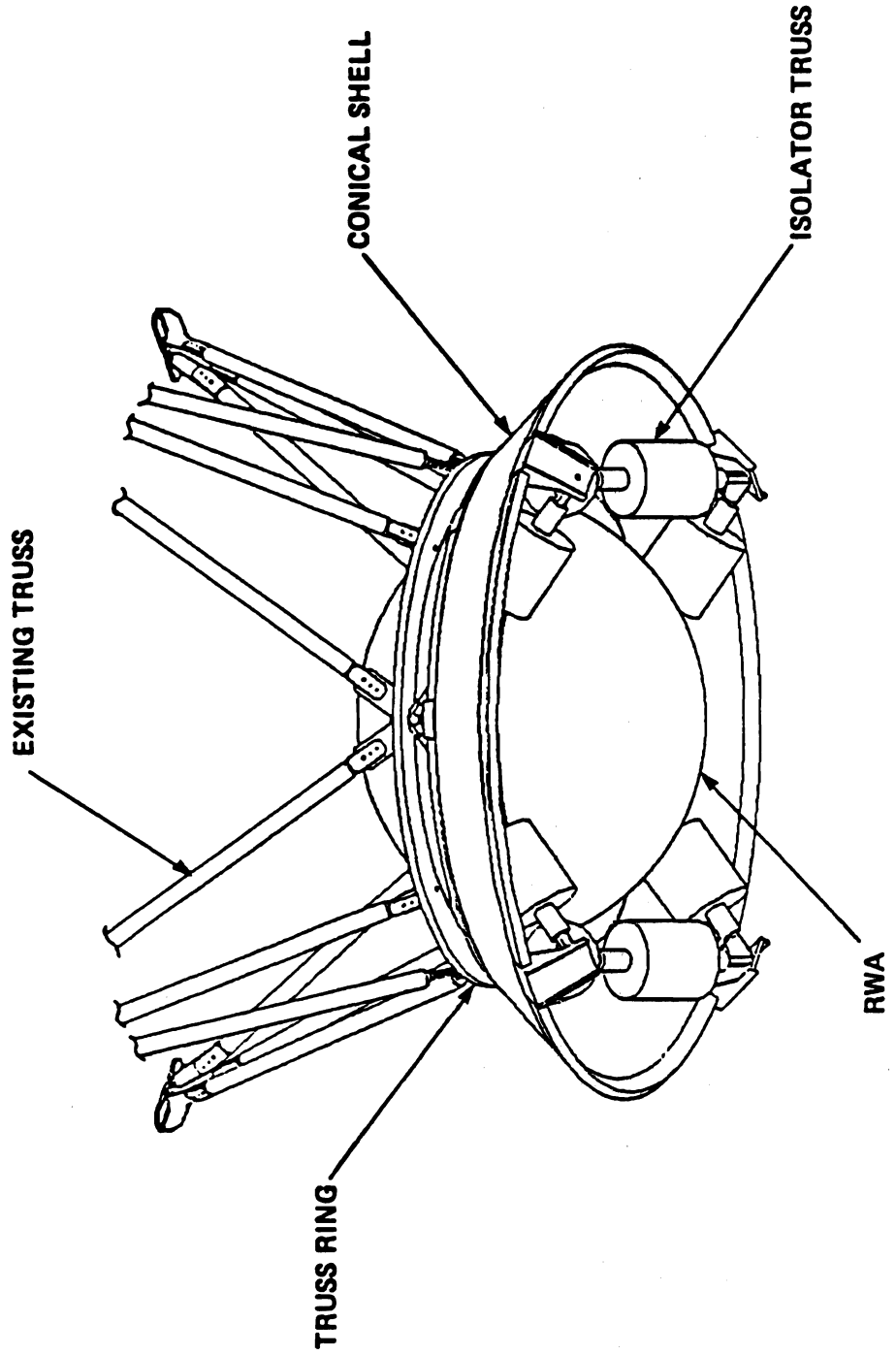


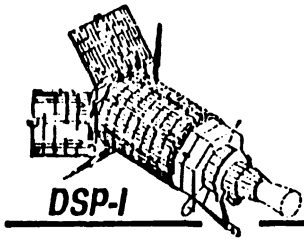


DSP-1



Baseline RWA Isolator Design

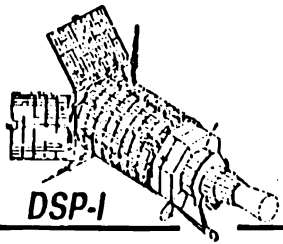




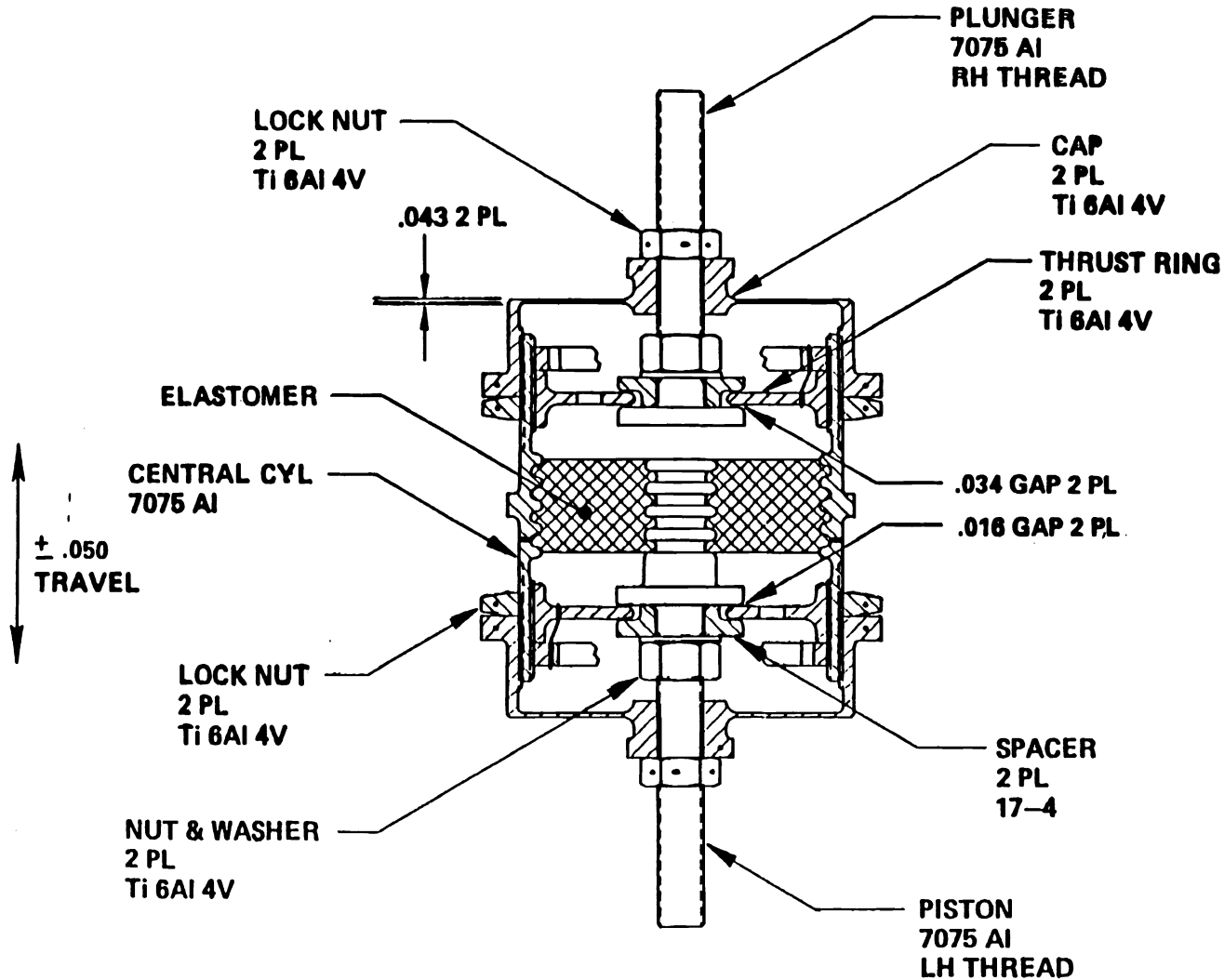
Isolator Unit Section View

- All parts are screwed together and lockwired
- Elastomer is injection molded to central cylinder and piston
- Cap has thin wall (0.043 in.) for "oil can" motion
- All parts are fabricated using standard machining practices
- 3 engineering demonstration units completed in one month

Isolator Unit Section View



FAC-15



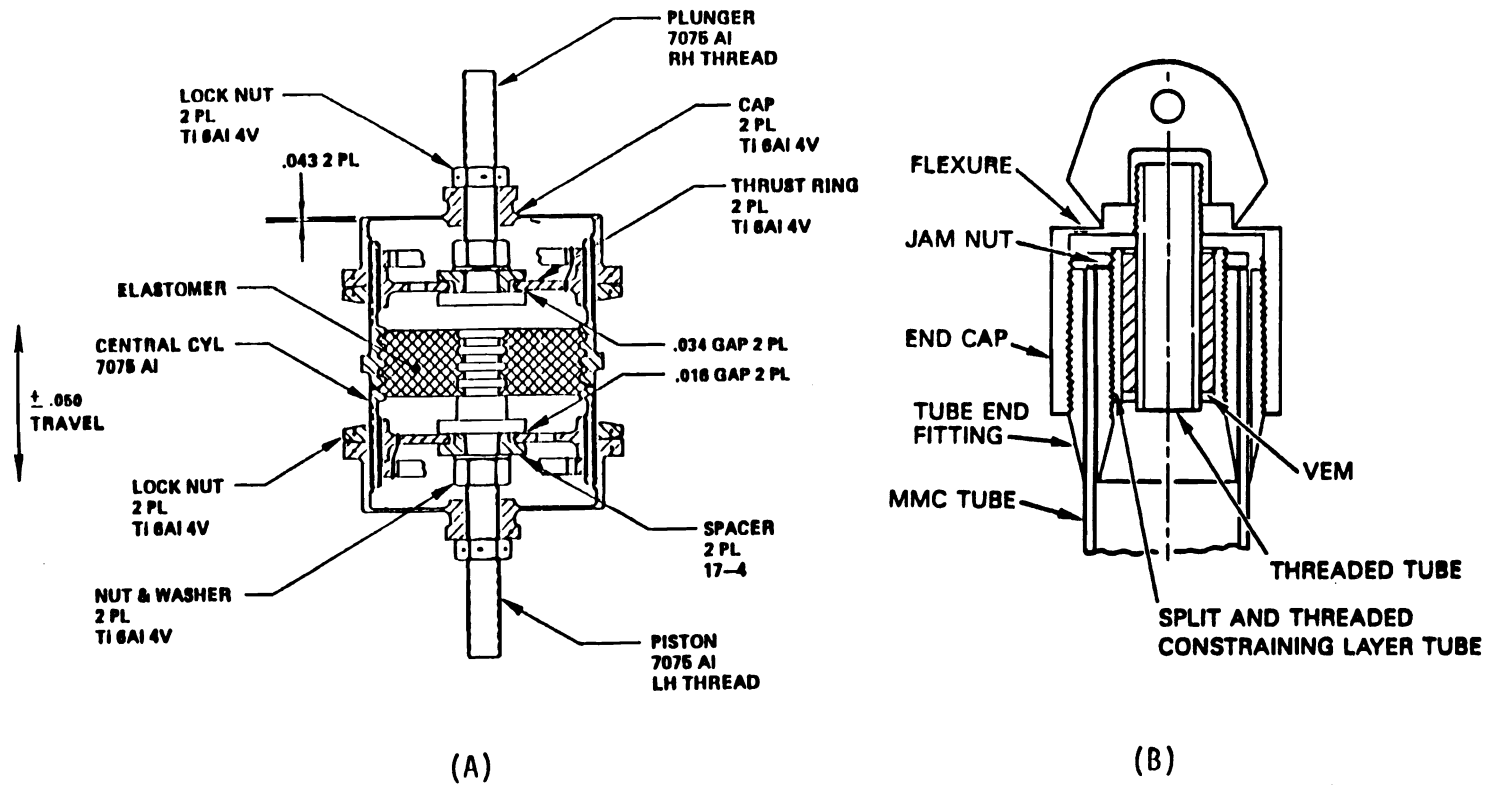
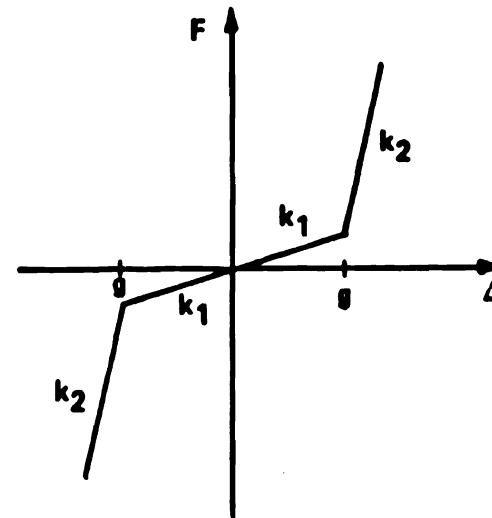
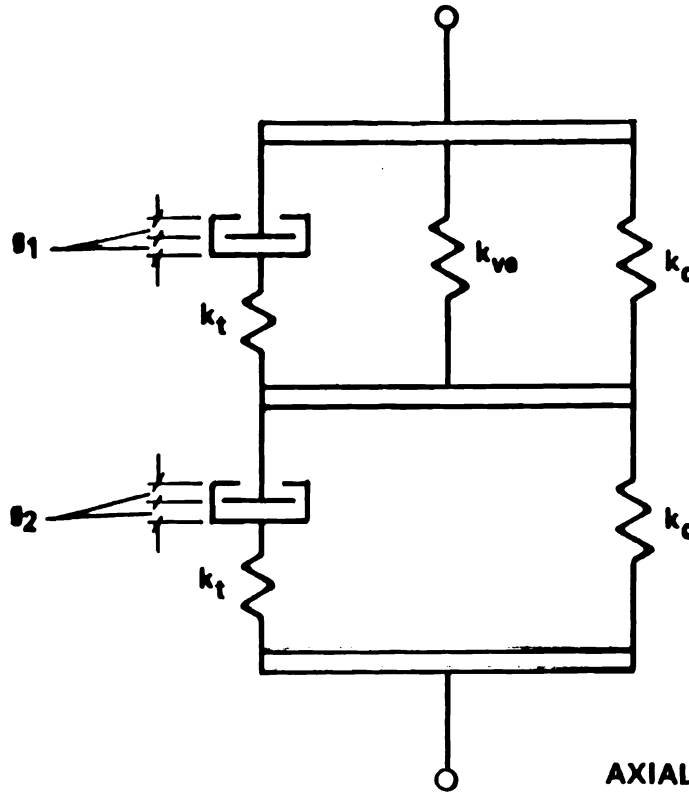
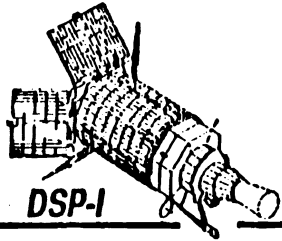


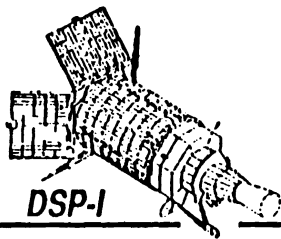
Figure 2: Comparison of A) DSP Proposed Isolator, and B) DAMPS JOINT Concept

Isolator Mechanical Model (Schematic)



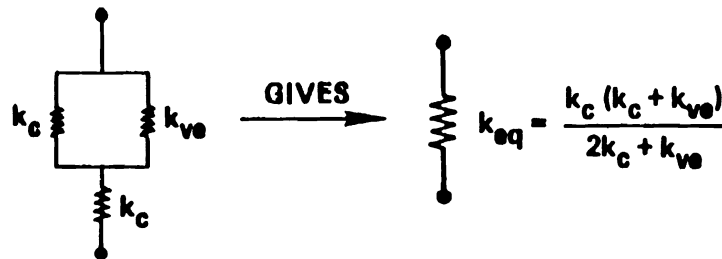
AXIAL ISOLATOR STIFFNESS MODEL:

- k_c = ISOLATOR CAP STIFFNESS
- k_{ve} = VISCOELASTIC SPRING STIFFNESS
- k_t = THRUST RING STIFFNESS
- g_1, g_2 = GAPS



Temperature Insensitive Design

- Performance of isolator is only slightly effected by extreme changes in temperature. Operating temperature is fairly constant at about 80°F.
- Isolator axial model:



k_c = Isolator End - Cap Stiffness

k_{ve} = Viscoelastic Material Stiffness (Acts Both as a Spring and Damper)

k_{eq} = Equivalent Spring Stiffness

- Robust Stiffness K_{eq} :

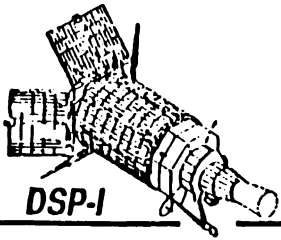
If $k_{ve} \rightarrow 0, k_{eq} \rightarrow \frac{k_c}{2}$

If $k_{ve} \rightarrow \infty, k_{eq} \rightarrow k_c$

$$\frac{k_c}{2} \leq k_{eq} \leq k_c$$

Extreme Bounds

- Variations due to manufacturing, radiation, and fatigue are also bounded by using this analytical method

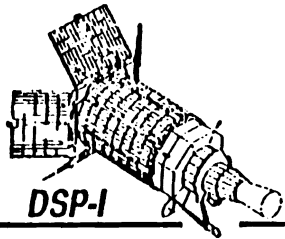


Isolator Stiffness



- Nominal 13 Hz Isolator
- Single isolator axial stiffness (total of 8 per module):

	Temp (°F)	K_c (lb/in)	K_{ve} (lb/in)	K_{eq} (lb/in)	Freq. (Hz)
Lower limit :	20	2000	135,000	1970	16
Operating :	80	2000	2000	1330	13.3
Upper limit :	185	2000	300	1070	11.8



Low Outgassing Viscoelastic Material

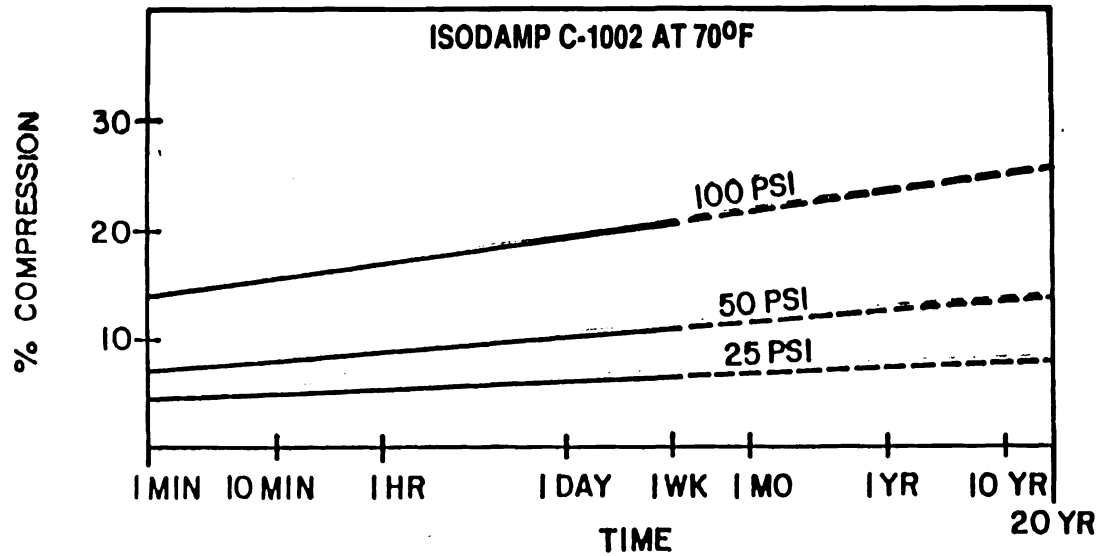
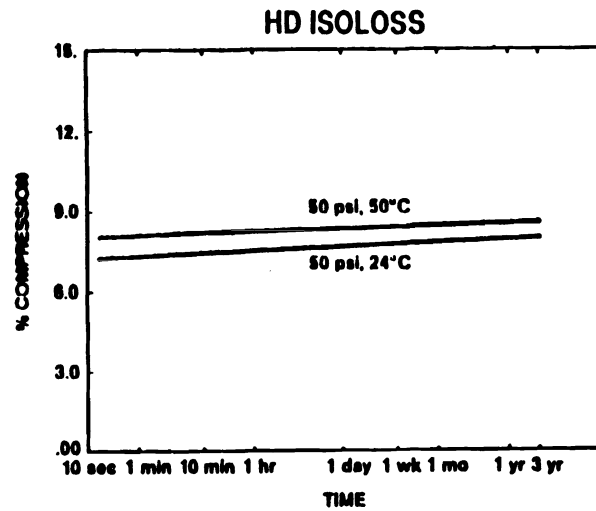
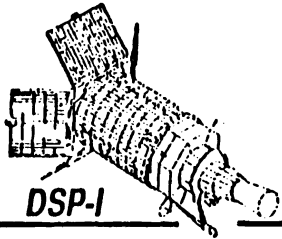


- Specification : NASA JSC SP - R - 0022

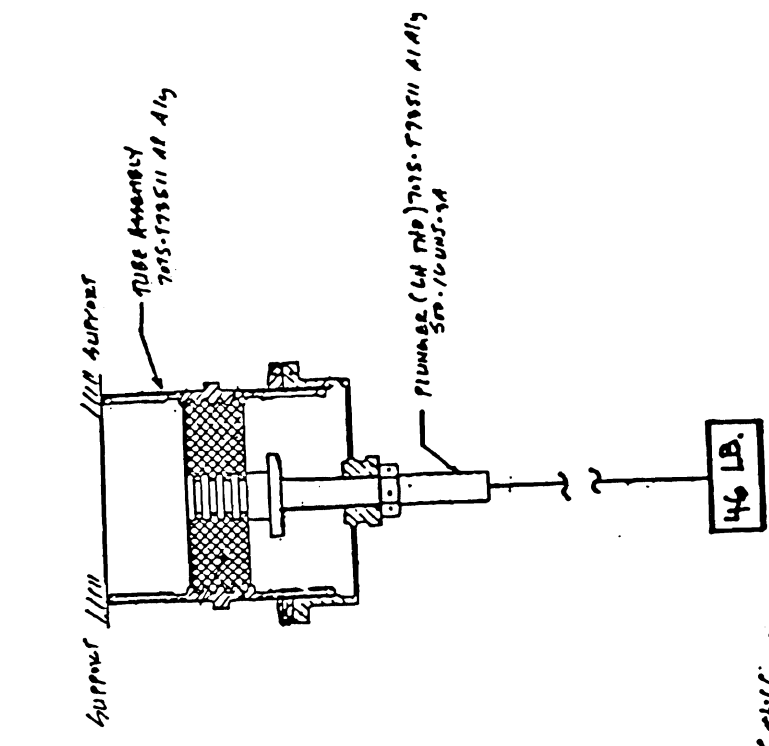
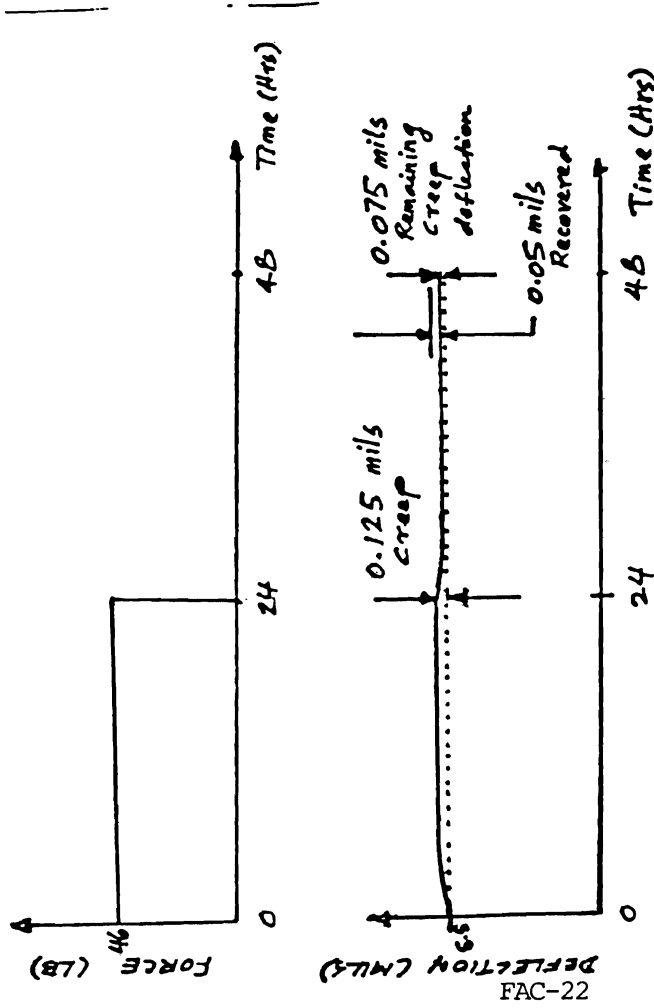
	<u>Requirement</u>
— Total mass loss (%) *	≤ 1.0
— Collected volatile condensable material (%) (CVCM)	≤ 0.1

* Vendor data indicates TML of .46% for E.A. R. 's HD Isoloss and .067% for Isodamp C1002 (Tested per ASTM-E-595 modified)

Compressive Creep



CREEP / RECOVERY TEST (DSP ISOLATOR STUDY)



• Total Deflection = Elastic Defl. + Creep Defl. (Stiffness ≈ 8360 lb/in.)
(24 Hrs) ≈ 0.0055 in. + 0.00125 in.

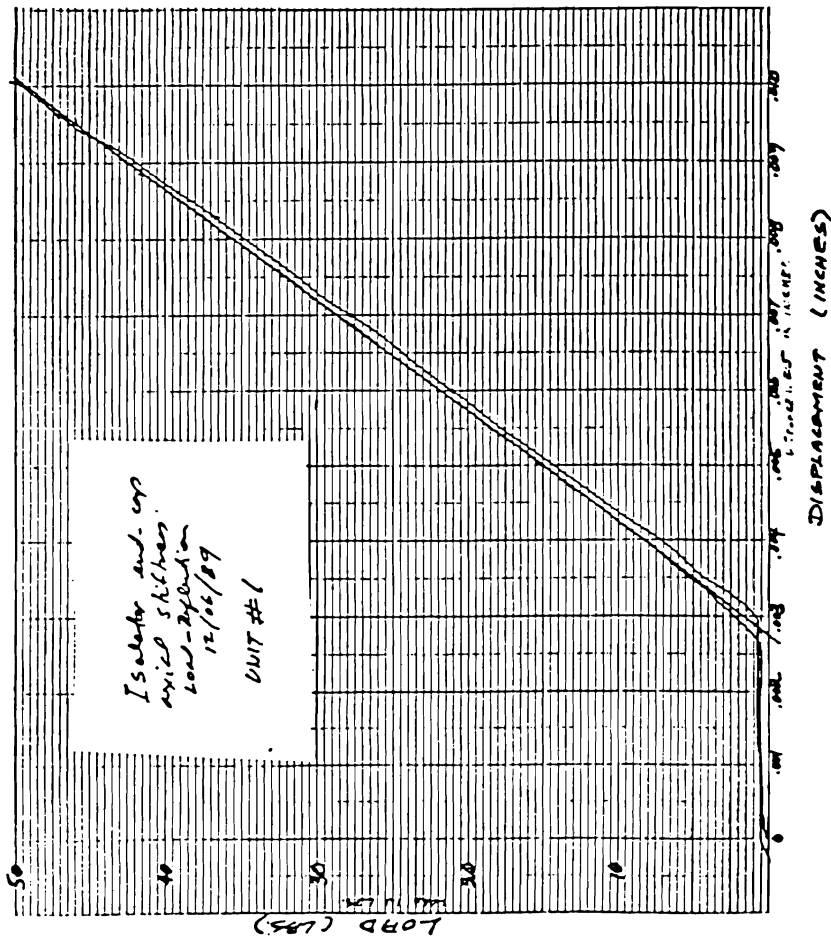
$$\delta_{\text{Total}} = 0.005625 \text{ in.}$$

• Recovered Deflection = 0.0005 in.
(Creep part after 24 Hrs)

• 40% of creep deflection recovered after 24 Hrs.

• COMPARISONS } COMPRESSIVE CREEP (24 Hrs) : $(\delta_{\text{Creep}} / \delta_{\text{Elastic}})_{\text{C}} = 0.056$
(Isolator HD) } SHEAR CREEP (24 Hrs) : $(\delta_{\text{Creep}} / \delta_{\text{Elastic}})_{\text{S}} = 0.0227$

CAP FLEXURE STIFFNESS TESTS (DSP ISOLATOR STUDY)



$$k = \frac{50 - 0.7}{.010 - .00275} = \frac{49.3}{.00725} = 6800 \text{ lb/in}$$

$$k = \frac{50}{.0101 - .00275} = 6803 \text{ 1/2 OK}$$

- UNIT NO. 1 STIFFNESS $\approx 6800 \text{ lb/in}$ } Difference within 5.4%
- UNIT NO. 2 STIFFNESS $\approx 6430 \text{ lb/in}$
- FLEXURE THICKNESS MEASUREMENTS : 0.043", 0.044", 0.044"
(9 POINT MEASUREMENTS) DIFFERENCE : 0.043" + 0.001" = 0.000"

