

PREDICTION OF SPACE VEHICLE THERMAL CHARACTERISTICS

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FOREWORD

The following report was prepared by TRW Systems Group, under USAF Contract No. AF 33(615)-1725 as part of Project 6146, Task 614617. The program was administered by the Air Force Flight Dynamics Laboratory, Research and Technology Division, Wright-Patterson Air Force Base. The Technical Monitor was Mr. C. J. Feldmanis.

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ABSTRACT

The work reported herein is the first phase of a program to improve the prediction of spacecraft thermal performance. The study has consisted of measuring actual joint thermal conductances, correlation of the measured joint conductances, programing an improved method of thermal radiation analysis, and performing an experimental comparison of predicted radiation exchange for a simple geometrical system.

Three types of structural and three sizes of component mounting joints were tested and the conductances measured. A successful method of correlation was developed for the unfilled component mounting joints. All joints were selected for their applicability to the next phase of the program, a thermal test of a spacecraft model.

A method of radiation analysis has been programed which uses directional thermal radiation properties and accounts for the specularity and/or diffuseness of these properties. The results of this program can be readily incorporated into most existing thermal analysis programs. The user has the choice of the specular, the diffuse, or the specular-diffuse assumption. The prediction of radiation exchange using these assumptions for simple geometrical arrangements has been compared to experiment. Although the results were within the overall experimental tolerances, further improvement in the predicted values is believed possible.

The study has developed several important technical areas which are worthy of further evaluation. The first is the extension of the correlation techniques to include filled component joints and filled or unfilled structural joints. Continuation of the general measurement of joints to develop a large knowledge of practical joint conductances is also indicated. The comparison of experimental and predicted radiation exchange has shown that a more extensive study is needed of thermal radiation properties to determine the division of these properties into specular and diffuse components. The non-gray error of radiation analysis has also been shown to be an important area for further study.



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SYMBOLS

Section 3	
A	Area - ft ²
h	Thermal conductance - Btu/hr ft P; h eff = effective h
q	Heat flow - Btu/hr
t	Temperature - ^o F
Section 4	_
A	Area of a surface -ft ²
В	Quantity introduced by Gebhart - Btu/hr ft ^{2 o} R ⁴ (Section 4.1)
C	Heat capacity - Btu/hr
D	Diffuse irradiation - Btu/hr ft ² ster. (Section 4.2)
F	Geometrical shape factor
8	"Script F"
J	Radiosity - Btu/hr ft ²
M	Number of surfaces within the enclosure
N	Number of time intervals
R	Thermal conduction resistance - hr F/Btu (Equation 4-3)
R	Hottel's radiant power leaving a surface - Btu/hr ft ^{2 o} R ⁴ (Section 4.1)
T	Absolute temperature - OR
a.	Coefficient (Section 4.2)
Ъ	Coefficient (Section 4.2)
С	Coefficient (Section 4.2)
d	Coefficient (Section 4.2)
i,j,k	Indices representing surfaces within the enclosure
q	Heat flow Btu/hr
x,y,z	Indices
a	Absorptance
ε	Emittance
η	Convergence factor (Equation 4-8)
π	3.1415927
ρ	Reflectance
σ	Stefan-Boltzmann constant - Btu/hr ft ^{2 o} R ⁴
8	Time



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SYMBOLS (Cont.)
[ ]
            Square matrix
[]-1
            Inverse square matrix
{ }
             Column matrix
Section 5
Symbols defined in the text.
Section 6
             Source heat flow - Btu/hr
Q
             Directional reflectance at angle 0
ρ(θ)
θ
            Angle between the normal to the surface and the
             incident or reflected radiation - degrees
Section 7
            Area, ft2
A
            Heat flux, Btu/hr ft2
Q
            Radius - in.
R
             Temperature, oF
            Bolt diameter, in.
a
             Twice the plate thickness, in.
þ
            Effective contact radius, in.
C
            Bolt major thread dia.
đ
             Thermal conductance - Btu/hr ft<sup>2</sup> oF
h
            Thermal conductivity - Btu/hr ft oF
k
            Radial position, in.
r
t
            Plate thickness - ft.
η
             Nondimensional radius ratio - r/R
\eta_{o}
            Nondimensional radius constant R /R
Appendix IV
Tp = "Receiver" temperature OR
T<sub>M</sub> = "Mirror" temperature CR
T = "Sink" (cold wall) temperature OR
T = "Source" temperature OR
                                       ix
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1. INTRODUCTION AND SUMMARY

The program, "Prediction of Space Vehicle Thermal Performance," was initiated on 1 July 1964, under Contract AF 33(615)-1725. The purpose of the study can be stated as: Given the necessary analytical methods and experimental data, how well can the thermal performance of a space vehicle be predicted? The subject program was the first step towards securing an answer to this question.

The problem provides two natural divisions. The first is the examination of the analytical procedures needed and the experimental information required for analysis. The second is the verification of the predictions of analysis by a thermal test of a model space vehicle. The present program was intended to satisfy the first need and to provide a transition to the second. Since a model is required to verify analysis. its design will dictate the nature and scope of the experimental studies performed to support analysis. In particular, the subsequent construction of a test model will require the selection of structural and component joints in anticipation of the design. Depending upon the type of joint selected and the degree of experimental measurements made, the thermal resistance of the joints can be critical to the experimental verification of any predictions made. Consequently, it was necessary at the start of the present program to select, in reasonable detail, the model configuration. The experimental measurements of joint thermal resistance were restricted to those joints to be used in the model. Only in this manner could the end purpose of the study, the test of prediction, be achieved within the allocated resources and time.

The specific tasks undertaken in the study were:

- (a) Selection of a model for determination of the experimental joint thermal conductance measurements
- (b) Experimental measurement of component and structural joint thermal conductance
- (c) Examination of the results of the joint thermal conductance results to ascertain if a correlation were possible
- (d) Comparison of the analytical techniques of Hottel (1), Gebhart (2), and Oppenheim (3).
- (e) Development of a computer program for a specular-diffuse analysis (4)
- (f) Experimental measurement of radiation exchange with real surfaces

The following report will consider the above tasks in the order shown. It should be re-emphasized that the purpose of the program and hence, the goal of each task, is to provide the necessary data for a comparison of thermal analysis and thermal test of a spacecraft model.



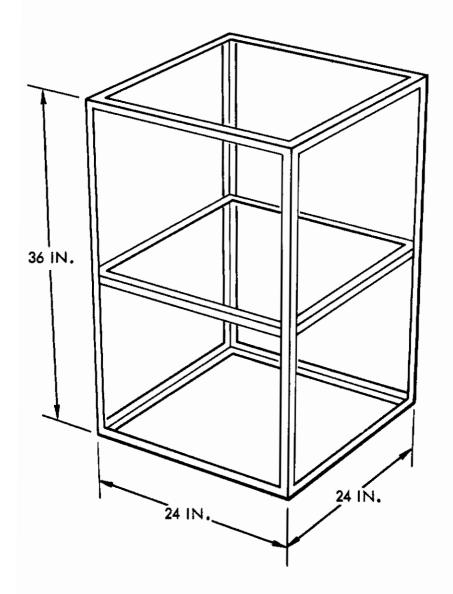
2. SPACECRAFT MODEL SELECTION

An important initial task was the conceptual design of the model of the space vehicle to be tested in the subsequent phase of the program. The size, method of construction and shape of the model greatly affects the type of fasteners, the physical dimensions and the shape of the joints.

The model which has been selected is shown in Figure 1. Alternative shapes, cylindrical and spherical, were considered but the rectangular parallelepiped was chosen for economy and ease of fabrication. Furthermore, the geometrical shape can not be a critical factor in a test of the prediction of thermal performance. The indicated dimensions, $24" \times 24" \times 36"$, are sufficiently large to demonstrate the effects of construction variations, thermal gradients, and internal dissipation. The model will conveniently fit into most environmental test chambers and available solar simulation facilities. Also, the size is representative of many present day space vehicles.

A welded framework is indicated. This method of construction was selected to reduce the number of structural joints that had to be tested. There are three structural joints with the frame: the side panels, the end panels, and the component mounting platform. The side and end panels are 1/16-inch aluminum; i.e., thin enough to sustain a thermal gradient. The mounting platform is 1/8-inch aluminum. In actual space vehicle construction, this mounting plate would probably be a honeycomb structure to reduce weight. Such materials are anisotropic and the thermal conductance in the x, y, and z directions are variable from sample to sample of the same material. The conductance also varies widely for different types of honeycomb. Thus, use of a honeycomb structure would introduce a major undetermined factor in the thermal analysis. This could easily obscure the validity of the comparison of prediction and experiment. The aluminum mounting plate avoids this without affecting the value of the test to be conducted. Thus, if the analysis can properly predict for the aluminum plate, it will be satisfactory for application to a honeycomb material (assuming the properties of the honeycomb are known).

The external panels can be changed to provide different external thermal radiation properties. This may not be important in the initial testing to be performed with the model but will be useful should further testing be desired or required. These panels can be coated to simulate solar cell thermal radiation properties, low α/ϵ properties or even be insulated without affecting the basic model physically. A louver system could be used in place of any panel to determine the effects of variable emission. Hence, the model will be of much more value than just for the program contemplated in Phase II.



ALUMINUM FRAME-HELI ARC CONSTRUCTION

Figure 1. Spacecraft Model - Size and Shape



3. THERMAL CONDUCTANCE OF JOINTS

Completely riveted joints were excluded from the study. In spacecraft practice, riveted systems are used in order to save weight. However, the thermal conductance of such joints is not considered reproducible and variations of 100 percent have been found in supposedly identical joints (5). Since the goal of the program is to test the ability to predict thermal performance with reliable input information, the introduction of such an uncontrolled thermal resistance is not desired. This would not test the prediction of thermal performance but only the uncertainty of knowledge. The effect of the variable thermal resistance can be demonstrated analytically, once the analysis has been verified.

Two general types of joints were studied: component and structural joints. The component joints are shown in Figure 2. The dimensions were chosen as representative of typical component base sizes. Simulation of the actual component box was not deemed necessary since this would only involve changes in the radiation shape factors used. The assumption was made that the base plates would have a uniform areal power dissipation. The experimental variables examined were bolt-torque, power dissipation level, filler material and reproducibility of the joints. A detailed description of the test method and the results will be given in Section 3.1.

The structural joints tested are presented in Figure 3 and all are bolted joints. The structural joints were selected to satisfy the requirements of the proposed space vehicle model (see Section 2). The first configuration corresponds to the joint between the side panels and the frame. The end panels are bolted to the frame by means of nut plates which are riveted in place (second joint). This joint can be considered to be a combination of a rivet and bolt fastener. The third joint shown represents the joint between the component mounting platform and the frame. As with the component joints, the variables of power dissipation level, filler material and reproducibility were examined. The experimental test method and results are given in Section 3.2.

These joints are "practical" ones; i.e., representing actual fabricated joints. As a result, variations in the thermal conductance must be expected from "identical" joints. An attempt was made to apply idealized theories to these joints to obtain a correlation of the test data. The results of this effort are given in Section 7.

3.1 COMPONENT JOINT EXPERIMENTAL TESTS

The component joints were simulated by bolting a plate 1/16 inch thick of the necessary dimensions to a base plate 1/8 inch thick. The component base plate dimensions used were 6 inches square, 6 inches by 12 inches, and 12 inches square. The plates upon which the base plates were mounted were 2 inches greater in each dimension than the component plate; e.g., 8 inches square for the 6-inch square component plate. The bolt size and placement for each joint are shown in Figure 2. A heater made of 40 gage constantan wire sandwiched between 1 mil Mylar was bonded to the upper surface of each component base plate. The mounting plate had 1/4 inch



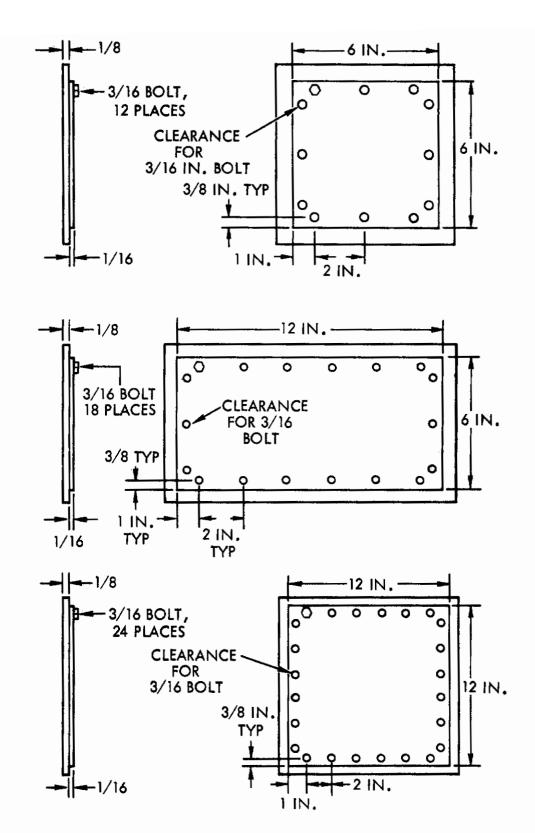


Figure 2. Component Joints

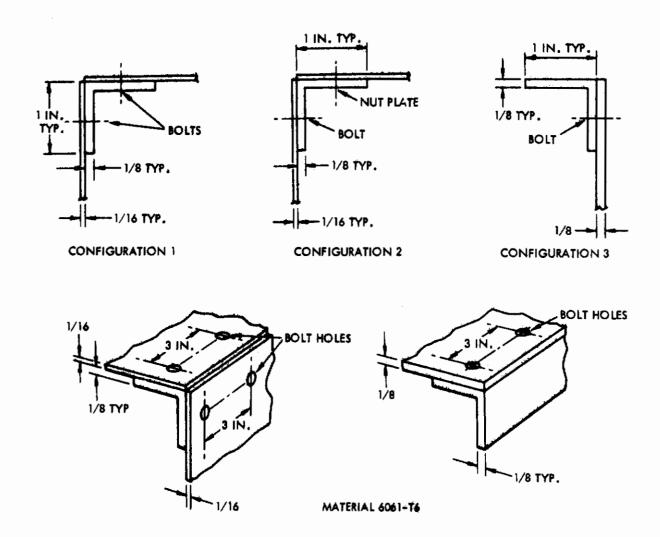


Figure 3. Structural Joints



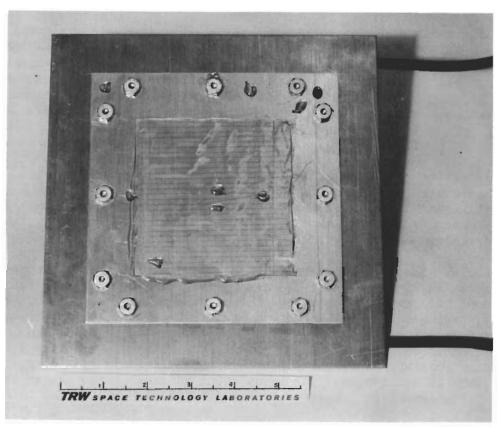
copper cooling coils attached to its underside. The whole assembly was wrapped in 20 layers of super insulation and suspended within a bell jar. This bell jar was evacuated to a pressure less than 10^{-5} torr. Figure 4 shows a component joint after testing; the final assembly and the vacuum system are illustrated in Figure 5. The thermocouples have been removed from this sample so that surface roughness measurements can be made.

The test procedure consisted of placing the insulated and instrumented joint within the bell jar, securing a vacuum on the system, and setting the initial heating rate. Equilibrium was determined by plotting the various temperatures as a function of time. Once these temperatures had stabilized to less than plus or minus 1°F.per hour, a set of data was taken. The observed temperature drift was caused by drift in the cooling water temperature.

The electrical circuit used to measure the power dissipated by the heater is shown in Figure 6. The power was determined by measuring the voltage across the heater terminals at the component joint and measuring the current flowing in the heater with a standard resistor. This procedure is commonly referred to as the four terminal resistor technique. The potentiometer used for these two measurements was a Leeds and Northrup Type K-3 Potentiometer. This instrument has three ranges: 1.6 volts, 0.16 volts, and 16 millivolts. The least count on these three ranges is 50, 5, and 0.5 microvolts, respectively.

Initially, temperatures were to be measured with nickel resistance temperature sensors. These sensors were obtained from the RdF Corp., Hudson, New Hampshire, and were calibrated by the vendor to within plus or minus 0.5°F. The first tests did not yield consistent results. This was traced to the resistance sensors. Deviations as large as 2°F were found between initial and final calibrations for a run. Since the temperature differences across a joint were generally smaller than 2°F, this initial data had to be discarded and the sensors replaced with differential copper-constantan thermocouples. The subsequent data was reproducible and consistent for a given test configuration.

Resistance thermometry has the inherent advantage of measuring an area rather than a point; i.e., a local average. When properly calibrated, it is also a more accurate sensor since the impurities in the metals used are less important in resistance than in thermoelectric effects. However, this accuracy can only be achieved at a significant increase in cost relative to thermocouples. The instrumentation method required for differential resistance thermometry is quite different than that used for resistance thermometry. The ratio of the resistances of two elements must be measured, the absolute value of one of these elements is needed, and two sets of lead resistance corrections are necessary. This involves two different bridge circuits (and/or instruments) and a means for electrical switching. The alternative use of thermocouples can provide a differential accuracy of approximately plus or minus 0.1°F if the thermocouples are cut from the same roll of wire and careful experimental procedures used. The cost is much less, both in construction and use. This is offset by the "point" measurement characteristics of a thermocouple. For this series of tests, the thermal conductivity of the aluminum joint material was sufficient to minimize this problem.



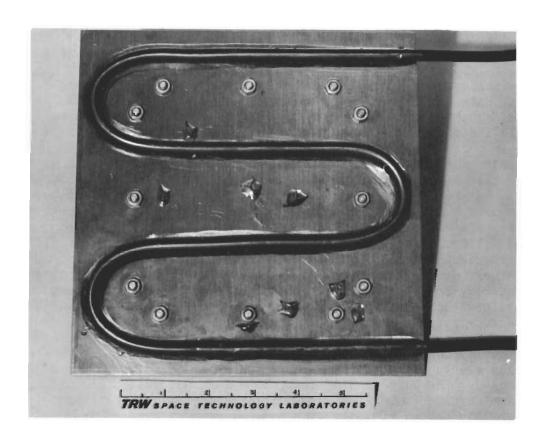


Figure 4. Typical Component Joint

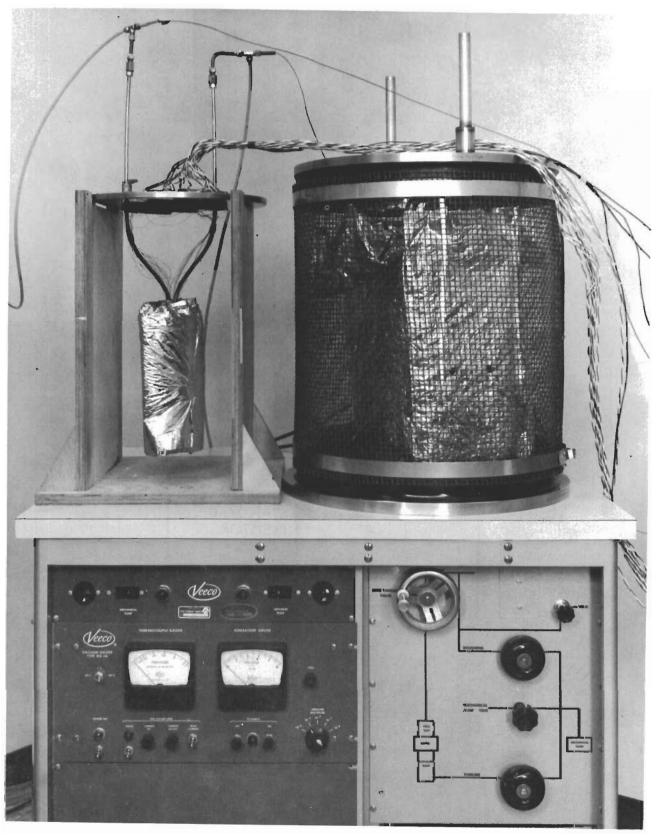


Figure 5. Component Joint Ready for Testing



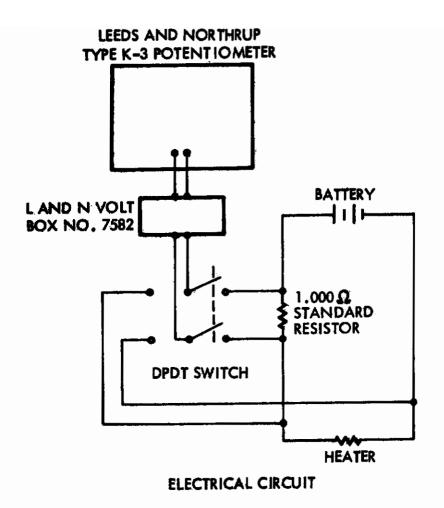


Figure 6. Power Circuit for Joint Testing



The emf of the test thermocouples was measured with a Leeds and Northrup Type K-3 Potentiometer. On the millivolt range, this instrument has a least count of 0.5 microvolts. Deutch No. 14657-37T vacuum feed throughs were used for the thermocouples to avoid a discontinuity in the thermocouple circuitry. When a filler material was used, it was applied by placing two 0.050 inch wires on the surface of the mounting plate, putting an ample quantity of the filler material between the wires and scraping the excess off with a straight edge resting on the wires. Before the material set, in the case of RTV-11 filler material, the component plate was placed on the mounting plate and bolted down. The bolt torques for all joints were set with a calibrated torque wrench. No special instructions were given to the person assembling the joint relative to the order of tightening the bolts. This was intentional since the randomness of a fabricated joint was desired.

The results are summarized in Tables 1, 2, and 3; the actual data and the techniques used in its reduction are given in Appendix I. Included in the Appendix are schematic diagrams showing the placement of the temperature sensors. Three specimens of each joint were run with the exception of the G 683 silicone grease filler. This material was found to be less suitable for use as filler than the silicone rubber. The primary difficulty with the grease was the contamination of the other areas around the joint; i.e., it was messy. Furthermore, it did not yield joint conductances as large as the RTV-11 material.

The results for the 6-inch square joint (Table 1) shows that the effect of heat flux level was small. This was a temperature gradient effect and for the small range involved in this test (from 2.5°F to 10°F for a typical case), it was not important. Similarly, the change in bolt torque from 12 to 30 inch-pounds was not significant. The effect of the RTV-11 was, however, quite significant. It increased the thermal conductance of the 6-inch square joints by a factor of 4 and the larger joints by a factor between 5 and 6.

The most obvious result of the tests was the inconsistency of the results for "identical" joints. Joint No. 2 of the 6-inch square joints is a good example. An examination of the second joint showed the component base plate to be bowed by 0.007 inches (concave upwards); Joint No. 1 was bowed 0.003 inches (concave downwards); and Joint No. 3 was bowed 0.003 inches (concave upwards). Thus a trend of increased conductance with upward concavity is indicated by these limited tests. In actual fabrication, a flatness tolerance can be imposed, e.g., plus or minus .003 inches, which would minimize this effect. Such a constraint is not unreasonable. The surface roughness of the test plates was measured using a diamond stylus profilometer. The results were consistent for all the plates and yielded $11~\mu$ in. rms across the roll marks and $4~\mu$ in. rms with the roll marks. The surfaces were randomly mated, that is the roll marks placed either parallel or perpendicular, but recorded. The results show no correlation between striation alignment and conductance values.

^{*}Manufactured by General Electric Company, Silicone Products Department



TABLE 1 COMPONENT JOINT THERMAL CONDUCTANCE EXPERIMENTAL RESULTS THERMAL CONDUCTANCE - BTU/HR FT^{2 O}F

6 inch by 6 inch plate, 1/16 inch thick, bolted to 8 inch by 8 inch plate, 1/8 inch thick, using 12 bolts

Filler	-		None	None	None	RTV-11	RTV-11	RTV-11	G-683	G-683	
	30 in-lb	10 Watts		- 30°0			142.0			57.0	
		18.4 Watts	23.1	30.0	26.6	83.2	130.0	95.4		67.1	49.5
Bolt Torque	24 in-lb	Power Dissipation Watts 13.4 Watts	22.9	30.1	26.2	82.5	129.0	8.46		66.1	48.8
Bolt	777	Power I 8.6 Watts	23.2	30.1	25.9	81.5	127.0	93.5		65.0	48.2
		4.9 Watts	22.8	29.1	22.1	76.9	128.1	91.0		63.0	47.3
	12 in-1b	10 Watts		28.5	24.8		123.0	84.1		55.5	0.74
Sample No.			H	2	8	*~	R	m	*~	8	80

*
Same samples as above, with filler added.



TABLE 2 COMPONENT JOINT THERMAL CONDUCTANCE EXPERIMENTAL RESULTS THERMAL CONDUCTANCE - BTU/HR FT^{2 o}F

6 inch by 12 inch plate, 1/16 inch thick, mounted to 8 inch by 14 inch plate, 1/8 inch thick using 18 bolts; bolt torque 24 in-1b

Power Dissipation

Sample No.	10 Watts	20 Watts	40 Watts	Filler Material
1	18.5	18.9	18.5	None
1	103	101.5	98	RTV-11
2	103	101	97	RTV-11
3	90	92	92	RTV-11

TABLE 3 COMPONENT JOINT THERMAL CONDUCTANCE EXPERIMENTAL RESULTS THERMAL CONDUCTANCE - BTU/HR FT^{2 o}F

12 inch by 12 inch plate, 1/16 inch thick, mounted to 14 inch by 14 inch plate, 1/8 inch thick using 24 bolts; bolt torque 24 in-1b

,		Power Dissipa	tion	
Sample No.	20 Watts	40 Watts	80 Watts	Filler Material
1	8.4	8.3	8.3	None
1	56.6	55.8	56.1	RTV-11
2	51.7	52.8	51	RTV-11
3	51.4	51.9	52.4	RTV-11



The value of the filler for component mounting boxes is apparent. For the proposed test of a spacecraft model, the component boxes will be simulated by resistances dissipating pre-determined values of power. This is very similar to an actual spacecraft system. The higher values of conductance will permit the same heat flow with 1/3 to 1/4 of the temperature difference or conversely, 3 to 4 times the heat flow for the same temperature difference. This should make this type of thermal resistance less critical in the thermal analysis and prediction.

The effect of using filled joints must be investigated for each specific application under consideration. While much higher conductance values were obtained, the scatter in the data was larger for filled than unfilled joints. Therefore, the selection of filled or unfilled joints depends upon whether joints of high conductance, not precisely defined or joints of low conductance, more accurately described, are desired.

The differences in conductance for different sized component mounting plates was also of interest. The filled conductance decreased by a factor of 2 when the dimensions of the square component base was increased from 6 to 12 inches. This decrease is expected since the number of bolts doubled while the total area increased four times. This effectively causes an increase in the conduction pathlength of the mounting plate. These factors will be considered in more detail in Section 7. "Correlation of Experimental Results."

The overall accuracy of the tests is difficult to assess properly. However, the experimental accuracy of the various tests quantities can be given:

Inaccuracy in temperature difference measurement: ± 0.1°F

Inaccuracy in temperature measurement: ± 0.5°F

Inaccuracy in power dissipation (including insulation loss): + .5%

Inaccuracy in area measurement: ± .050 in2

Inaccuracy in bolt torque: \pm 0.5 inch-pounds

These values may be combined in a linear error analysis to approximate the total measurement inaccuracy. That is, the error in measured conductance (h) of a typical unfilled joint is:

$$\frac{\Delta h}{h} = \frac{\Delta(\Delta t)}{\Delta t} + \frac{\Delta q}{q} + \frac{\Delta A}{A} = \frac{\cdot 1}{1} + \frac{\cdot 025}{5} + \frac{\cdot 05}{36}$$

or

$$\frac{\Delta h}{h} = 10.5\%$$

The significance of this inaccuracy must be appraised in terms of the application of the data. The error in the measurement of a single joint is less than the lack of reproducibility between joints. Hence, the more



important factor is the variation of the conductance of "identical" joints. As shown in Tables 1, 2, and 3, this is approximately plus or minus 25 percent. However the influence of such a variation upon a thermal analysis can be either large or small, depending upon the system examined. For example, if a spacecraft thermal control system is conduction controlled, this variation might be critical; conversely, if it were radiation dominated, the differences might be negligible. To determine the importance of these variations requires an error analysis of the specific configuration.

3.2 STRUCTURAL JOINT EXPERIMENTAL TESTS

The test procedures used for the structural joint measurements were identical to those used with the component joints. The structural joints tested are shown schematically in Figure 3; an actual test joint is shown in Figure 7. A 40 gage constantan and Mylar heater was bonded to one edge of the joint. On the opposite edge, a 1/4 inch copper cooling tube was bonded to provide the necessary heat sink. This whole assembly was wrapped in 20 layers of super insulation and suspended in a bell jar (similar to Figure 5). The remainder of the test procedure was identical to that used for the component joints, e.g., the electrical measurement circuit was that given in Figure 6. Based upon the experience with the component joints, only thermocouples were used as the temperature sensors. The Leeds and Northrup Type K-3 Potenticmeter was again used for measuring the thermocouple voltages.

The test results are given in Tables 4, 5, and 6; the actual data from which these results were reduced are given in Appendix II. The first joint tested, Configuration 1 of Figure 3, is representative of the trends indicated for all three joints. Within the range of power dissipations used, no dependency upon power level is indicated for the unfilled joint; i.e., for small temperature differences, the conductance is a constant. A much higher value of joint conductance was obtained with the use of a filler material along with an apparent heat flow dependency. Configuration 2 used nut plates on one side instead of bolts. This had little effect upon conductance for the unfilled case. However, opposite results were obtained for two different RTV-11 filled joints with this configuration; i.e., in one case the nut plate side had a higher conductance and in the other, it had a lower one. No difference between a bolted joint and a nut plate joint could be concluded from the results for Configuration I and 2 because of this conflicting data. A strong dependency with heat flow is also noted for the filled joint.

The results of the filled structural joint tests show wide variations in calculated conductance. The most probable reason for these variations is the temperature measurement error. The temperature difference across the interface was of the same order of magnitude as the expected temperature error. In ideal joint conductance tests appearing in the literature (see Section 3.3), the temperature profile of the mating parts is accurately plotted and the data projected to the interface to obtain the temperature difference. The heat flows are normally much higher than in the present study and much higher temperature differences result. In the

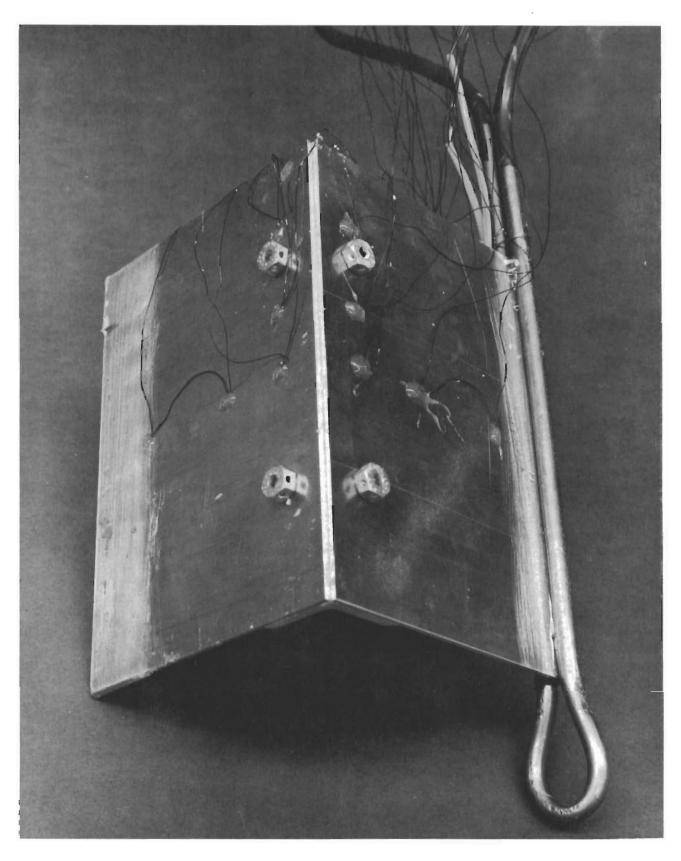


Figure 7. Typical Structural Joint



TABLE 4
STRUCTURAL JOINT CONDUCTANCE - BTU/HR FT² °F

6 inch joint, 2 bolts, 24 inch-pounds torque, Configuration 1

Joint No.*		Q - Heat Supplied					
	5 Watts	15 Watts	25 Watts				
la.	70.3	74.2	75.7	None			
lb	80.5	80.6	85.3	None			
2 a	103.5	100.1	100.9	None			
2 b	88.5	90	96.5	None			
3 a	78.5	79.4	77.0	Non e			
3b	77.5	79.8	81.8	None			
la	1042	906	715	RTV-11			
lb	1042	995	895	RTV-11			
la	602	595	542	G-683			
lb	681	652	645	G-683			

9 inch joint, 3 bolts, 24 inch-pounds torque, Configuration 1

Joint No.*				Filler
	7.5 Watts	22.5 Watts	37.5 Watts	
1a	116.0	98.5	100.8	None
lb	74.0	75.3	77.9	None

^{*}The notation a and b are used to distinguish the side of the joint next to the heater and the cooling coil, respectively.



TABLE 5 STRUCTURAL JOINT CONDUCTANCE, BTU HR FT² of

6 inch joint, 2 bolts, 24 inch-pounds torque, Configuration 2

	Joint No.				Filler	
		5 Watte	15 Watte	25 Watts		
14	(Bolt)	64.2	81.5	85.0	None	
16	(Nut Plate)	99.0	100.8	110.3	None	
28	(Bolt)	105.5	102	100.8	None	
2 b	(Nut Plate)	82.4	81.4	83.2	None	
34	(Bolt)	69.5	88.5	92.6	None	
3 b	(Nut Plate)	93.5	99.3	105.2	None	
la	(Bolt)	1427	1227	1050	RTV-11	
16	(Nut Plate)	520	514	490	RTV-11	
14	(Bolt)	438	425	420	G-683	
ĮЪ	(Nut Plate)	343	345	375	G-683	
24	(Bolt)	869	795	669	RTV-11	
2 b	(Nut Plate)	1892	1466	800	RTV-11	

9 inch joint, 3 bolts, 24 inch-pounds torque, Configuration 2

Joint No.				Filler
	7.5 Watts	22.5 Watte	37.5 Watts	
la (Bolt)	93.5	95.2	94.1	None
1b (Nut Plate)	84.1	87.8	97.6	None



TABLE 6 STRUCTURAL JOINT CONDUCTANCE, BTU HR FT² of

6 inch joint, 2 bolts, 24 inch-pounds torque, Configuration 3

Joint No.				Filler
	5 Watts	15 Watts	25 Watts	
1	147.0	144.2	142.0	None
2	194.0	180.0	174.0	None
3	112.2	108.5	106.5	None
1	1110	1273	1242	RTV-11
1	1328	1262	1231	G-683

9 inch joint, 3 bolts, 24 inch-pounds torque, Configuration 3

Joint No. Filler

7.5 Watts 22.5 Watts 27.5 Watts 1 142.2 139.0 135.5



present investigation, the real joints had two dimensional heat flows. It was not possible to project gradient measurements to the interface. Furthermore, the heat fluxes used were selected as representative of those to be encountered in an actual spacecraft, and the temperature gradients were correspondingly small.

Two values of joint conductance are given in Table 4 and 5 (Configurations 1 and 2) for each test joint. The experimental system was instrumented to obtain the conductance from either plate to the angle. The effective conductance from plate to plate is determined (by analogy to an electrical circuit) as:

$$h_{eff} = \frac{1}{\frac{1}{h_1} + \frac{1}{h_2}}$$

If this effective conductance is computed for "identical" joints and conditions, the variations between the measurements are reduced significantly for the unfilled joints. In the case of Configuration 1, the variations in total conductance are less than plus or minus 15 percent; for Configuration 2, it is less than plus or minus 7.5 percent. The filled joints have a much wider variation as is indicated by the measurements.

Two lengths of joint were tested for all three configurations. No significant differences in the measured conductances were observed. Hence, the end losses from the test joint are considered to have been negligible.

The third configuration tested was the one to be used for connecting the internal mounting plate to the frame. The measured results were similar to those obtained for the other two configurations.

The test results obtained indicate a filled structural joint to be more variable than an unfilled one. The conductance is significantly higher, of course. This variability may be nullified by the higher value obtained. As discussed in Section 3.1, this can only be assessed by performing an analysis of an actual spacecraft system using these opposing conditions. The choice will depend upon the relative importance of the two modes of heat transfer, radiation and conduction, for the joint analyzed and the particular system used. However, if filled joints are used, a formerly conduction dominated system may become radiation controlled. For example, the total effective conductance of an unfilled joint is of the order of 40 to 50 Btu/hr ft² of where as an RTV-ll filled joint has a conductance of over 500 Btu/hr ft² of.



4. DEVELOPMENT OF ANALYTICAL METHODS FOR THERMAL PERFORMANCE ANALYSIS

The transient energy equation which must be solved for each surface in space vehicle thermal analysis is:

$$C_{i} \frac{dT_{i}}{d\theta} = (q_{x})_{i} + (q_{r})_{i} + (q_{c})_{i}$$
 4-1

where q_x = net heat transfer from an external source or by internal dissipation

 q_r = net heat transfer by radiation

q = net heat transfer by conduction

The quantity q_x is generally a function of time. This is a result of orbital conditions and/or of mission imposed duty cycles. Solutions of Equation 4-1 are required for each surface of the spacecraft (internal and external) as a function of time in orbit.

For computer solution, the technique of finite differences is used. Equation 4-1 is written

$$T_{\mathbf{i}}(\theta + \Delta \theta) = T_{\mathbf{i}}(\theta) + \left[\frac{\Delta \theta}{C_{\mathbf{i}}}\right] \left\langle \left[q_{\mathbf{x}}(\theta)\right]_{\mathbf{i}} + \left[q_{\mathbf{c}}(\theta)\right]_{\mathbf{i}} + \left[q_{\mathbf{r}}(\theta)\right]_{\mathbf{i}} \right\rangle - 4-2$$

Thus, the temperature of surface i at time θ + $\Delta\theta$ is expressed in terms of the temperature and net energy transfers at time θ . The variation of q_χ with time is assumed to be known or imposed by external constraints upon the spacecraft. However, both conduction and radiation contain the temperature variable. The expression for q_χ is

$$(q_c)_i = \sum_{k=1}^{M} \frac{T_k - T_i}{R_{ki}}$$
 4-3

The expression for q_r can be given by either the network method or by Hottel's "script F." The equations which must be solved to obtain $(q_r)_i$ by the two methods is given in Section 4.1. They are

Hottel:
$$(q_r)_i = \sum_{k=1}^{M} A_i \tilde{a}_{ik} \sigma (T_k^4 - T_i^4)$$

$$4-4$$

^{*}The simple equivalence of Hottel (1) and Gebhart (2) methods (see Section 4.1) is such that for all practical purposes, they may be assumed to be identical.

Network:
$$(\mathbf{q_r})_{\mathbf{i}} = \mathbf{A_i} \left(\frac{\varepsilon_{\mathbf{i}}}{\rho_{\mathbf{i}}}\right) \left(\sigma \mathbf{T_i}^{\mu} - \mathbf{J_i}\right)$$
 4-5
$$\mathbf{J_i} = \varepsilon_{\mathbf{i}} \sigma \mathbf{T_i}^{\mu} + \rho_{\mathbf{i}} \sum_{\mathbf{k}=\mathbf{1}}^{\mathbf{F_{ik}}} \mathbf{J_k}$$
 4-6
or $(\mathbf{q_r})_{\mathbf{i}} = \mathbf{A_i} \varepsilon_{\mathbf{i}} \sigma \mathbf{T_i}^{\mu} - \mathbf{A_i} \varepsilon_{\mathbf{i}} \sum_{\mathbf{k}=\mathbf{1}}^{\mathbf{M}} \mathbf{F_{ik}} \mathbf{J_k}$ 4-7

The difference between the two methods for radiation calculations becomes apparent by examining the above equations. At each time interval, the network method requires a new solution of the radiation problem; the "script F" technique requires the radiation problem to be solved once to determine the values of \tilde{v}_{ik} . The determination of \tilde{v}_{ik} does not need to be repeated unless the properties are changed. It should be noted that if the problem is not transient and no conduction is involved, neither method has any computational advantage over the other.

The procedure for obtaining the "script F" values for a given enclosure can be that described by Hottel (1) or from the network method (6). In both methods of securing \tilde{n}_{ij} , one matrix inversion is required; if the two matrices are compared (see References 1 and 6), they differ only by the use of the areas of the surfaces in the diagonal of Hottel's matrix; i.e., no computational or accuracy advantage.

The inversion process and the time interval increments used in Equation 4-2 provides a quantitative means for determining the "cost" of solving Equation 4-2 by the radiosity method. A matrix of the coefficients of the various J's must be inverted once at the start of the entire problem and can be used again with the values of temperature obtained at subsequent times. Hottel's method for calculating "script F" requires a similar matrix inversion. In each case, after the matrix inversion, secondary calculations are required to determine the various 5, or the new radiosities. However, with "script F," this does not have to be repeated at each time interval. Hence, for N time intervals and M surface enclosure, the number of calculations using radiosities is:

The reciprocity relationship $A_{i}\bar{v}_{ij} = A_{j}\bar{v}_{ji}$ can be used in conjunction with the method given by Reference 6 to obtain \bar{v}_{ij} in a time corresponding to that given for the network method of:

Consequently, the "script F" method is significantly more economical than the network method.



The steady state case is also more readily solved by the "script F" method when radiation and conduction are both present. Equation 4-1 for the steady state case can be written with the aid of Equation 4-3 as:

$$T_{i} = T_{i} (1-\eta) + \eta \begin{cases} q_{x}^{1} + (q_{r}^{1})_{i} + \sum_{k=1}^{M} \frac{T_{k}}{R_{ki}} \\ \sum_{k=1}^{M} \frac{1}{R_{ki}} \end{cases}$$

$$4-8$$

where η represents the convergence factor; i.e., $\eta \Rightarrow 0$ with convergence. Equation 4-8 must be solved for all surfaces i, e.g., by iteration. If, for each iteration, a new solution for the values of $(q_r)_i$ is required, the number of calculations required is identical to the time interval problem. If however, $(q_r)_i$ is represented by Equation 4-4, the iteration process is independent of recalculation of the radiation problem.

This discussion of the relative merits of the network method and the "script F" method is not based upon the assumptions inherent in either procedure. Another technique based on less restrictive assumptions will be described in Section 4.2. It can be used in either a network or a "script F" form, and the same arguments will hold relative to the method of solution to be used.

The accuracy of any method can be separated into two parts. The first is that inherent in the assumptions; e.g., specular versus diffuse properties. The second part is the accuracy of computation. The assumptions of the analysis is the dominant factor in determining the degree to which a method approximates a real system.

4.1 COMPARISON OF THE ANALYTICAL METHODS OF HOTTEL (1), GEBHART (2), AND OPPENHEIM (3) FOR CALCULATION OF RADIATION HEAT TRANSFER

The calculation of radiation heat transfer is generally based upon several simplifying assumptions:

- (1) The thermal radiation properties of all surfaces involved in the heat transfer are diffuse (independent of angle), grey (independent of wavelength), not dependent upon temperature, and surfaces are opaque.
- (2) An "enclosure" can be constructed which contains and/or bounds all of the surfaces involved in the radiation exchange such that all radiation emitted and/or reflected from any one surface is reflected and/or absorbed by the other surfaces.
- (3) Any single surface used in the calculations is isothermal and uniformly irradiated; this may necessitate the subdivision of a large natural surface into several parts in order to approach this condition.
- (4) No effects occur as a result of polarization, diffraction or fluorescence.



Three different methods of viewing the solution of this radiation exchange problem are available. These are generally known as the "script F" method (Hottel), Gebhart's method, and the network (Oppenheim). Intuitively, these methods must be identical since they are based upon the same physical assumptions and the conservation of energy. However, it is important that this equivalence be demonstrated. Sparrow (7) has recently shown this by developing the methods of Hottel and Gebhart from the network method. Since the "script F" method has been advocated as a more useful approach in complex transient radiation exchange, the "script F" method will be used here as the method of comparison.

Hottel's method is based upon the superposition of the radiant exchange within an enclosure. To do this, he assumed all of the surfaces except one within the enclosure to be at zero temperature; the remaining surface has an emission rate of unity, i.e., $\sigma T_1^{\ 4}=1$. He then considers the quantity ${}_1^R$, the power per unit area leaving surface j as a result of the power emitted by surface i; for surface i, the radiation leaving is ϵ_i + ${}_1^R$. The exchange between surfaces i and j are expressed as

$$Q_{ij} = A_i \delta_{ij} \sigma (T_i^{4} - T_j^{4})$$

$$4-9$$

where the reciprocity relation has been used, i.e., $A_{i}^{5}_{ij} = A_{j}^{5}_{ji}$. The quantity i^{R}_{j} is related to b_{ij} by:

$$A_{\mathbf{i}} \mathbf{\tilde{s}}_{\mathbf{i}\mathbf{j}} = {}_{\mathbf{i}} \mathbf{R}_{\mathbf{j}} \mathbf{A}_{\mathbf{j}} \left(\frac{\varepsilon_{\mathbf{j}}}{\rho_{\mathbf{j}}} \right)$$
 4-10

Thus, the incident power per unit area $({}_{1}R_{1}/\rho_{1})$ is absorbed in the fraction ϵ_{1} . This absorbed power is a result of an emission from surface i of unity and must be increased by the factor σT_{1} . Correspondingly, the absorbed power of surface i from emission by surface j must be increased by σT_{1} . The "script F" is, therefore, a quantity which collects the interreflections within the enclosure and provides a measure of the radiant interchange between two surfaces by direct and reflected (from all surfaces) exchange.

The irradiation of surface j by surface i ($_{i}$ R $_{j}/\rho_{j}$) can be expressed for an M surface enclosure ($_{\sigma}$ T $_{i}$ ⁴ = 1) as:

$$\frac{i^{R}j}{\rho_{j}} = F_{ji}\varepsilon_{i} + \sum_{k=1}^{M} F_{jk} i^{R}k$$
4-11

Multiplying through by $\epsilon_j A_j / A_i$ gives

$$\frac{A_{\mathbf{j}}^{\varepsilon}_{\mathbf{j}} \mathbf{i}^{R}_{\mathbf{j}}}{A_{\mathbf{i}}^{\rho}_{\mathbf{j}}} = \frac{A_{\mathbf{j}}^{F}_{\mathbf{j}} \mathbf{i}^{\varepsilon}_{\mathbf{i}}^{\varepsilon}_{\mathbf{j}}}{A_{\mathbf{i}}} + \sum_{\mathbf{k}=1}^{M} \frac{\varepsilon_{\mathbf{j}}^{A}_{\mathbf{j}}^{F}_{\mathbf{j}}_{\mathbf{k}} \mathbf{i}^{R}_{\mathbf{k}}}{A_{\mathbf{i}}} \left(\frac{\rho_{\mathbf{k}}}{\rho_{\mathbf{k}}}\right) \left(\frac{\varepsilon_{\mathbf{k}}}{\varepsilon_{\mathbf{k}}}\right)$$

$$4-12$$

With Equation 4-10 and noting A_iF_{ij} = A_jF_{ji}, this gives

$$\mathfrak{F}_{ij} = \varepsilon_{i}\varepsilon_{j}F_{ij} + \sum_{k=1}^{M} (\varepsilon_{j}F_{kj}) \frac{\rho_{k}}{\varepsilon_{k}} \frac{A_{k}}{A_{i}} \frac{\varepsilon_{k}}{\rho_{k}} i^{R}_{k}$$

or

$$\mathbf{\tilde{s}}_{ij} = \varepsilon_{i} \varepsilon_{j} \mathbf{F}_{ij} + \sum_{k=1}^{M} \varepsilon_{j} \mathbf{F}_{kj} \frac{\rho_{k}}{\varepsilon_{k}} \mathbf{\tilde{s}}_{ik}$$

$$4-13$$

Equation 4-13 will be developed by the network method in order to indicate the equivalence of the two techniques.

The Gebhart method is a variation of the "script F" phrased in different language. Gebhart utilized a quantity B_i , to represent the effects of interreflections within the enclosure. $^{ij}B_{ij}$ is the fraction of radiation emitted by surface i which is absorbed by surface j. The heat loss of a surface was expressed by Gebhart as:

$$q_{j} = \varepsilon_{j} A_{j} \sigma T_{j}^{4} - \sum_{i=1}^{M} B_{ij} \varepsilon_{i} A_{i} \sigma T_{i}^{4}$$

$$4-14a$$

or

$$q_{j} = \varepsilon_{j} A_{j} \sigma T_{j}^{4} - \sum_{i=1}^{M} q_{i,j}$$
 4-14b

The corresponding expression for Hottel's method is:

$$\mathbf{q}_{\mathbf{j}} = \sum_{i \neq j}^{\mathbf{M}} \mathbf{A}_{\mathbf{j}} \mathbf{\tilde{g}}_{\mathbf{j}i} \sigma \mathbf{T}_{\mathbf{j}}^{\mathbf{L}} - \sum_{i \neq j}^{\mathbf{M}} \mathbf{A}_{\mathbf{i}} \mathbf{\tilde{g}}_{\mathbf{i}j} \sigma \mathbf{T}_{\mathbf{i}}^{\mathbf{L}}$$
 4-15

The first term of Equation 4-15 simplifies by noting the total radiation leaving surface j is $\epsilon_j \sigma^{T_j}^{4}$, i.e., $T_i = 0$

$$\sum_{i \neq j}^{M} \sigma T_{j}^{4} \delta_{ji} = \varepsilon_{j} \sigma T_{j}^{4} - S_{jj} \sigma T_{j}^{4}$$

or

$$\sum_{i=1}^{M} \mathfrak{J}_{ji} = \varepsilon_{j}$$
 4-16

Equations 4-14 and 4-15 must represent the same net heat loss by surface j. Equating these two relations gives:

$$\sum_{i=1}^{M} A_{i} \delta_{ij} \sigma_{i}^{4} = \sum_{i=1}^{M} B_{ij} \epsilon_{i}^{A} \sigma_{i}^{4}$$

This can only be true if:

$$\mathfrak{F}_{i,j} = \varepsilon_i B_{i,j}$$

Consequently, Gebhart's $B_{i,j}$ is equal to Hottel's $\pi_{i,j}$ divided by ϵ_i .

The equations representing the network method of solution utilize the radiosity of a surface. The radiosity of a surface can be expressed as:

$$J_{i} = \varepsilon_{i} \sigma T_{i}^{4} + \sum_{k=1}^{M} \rho_{i} F_{ik} J_{k}$$
 4-18

The net heat flux leaving a surface is:

$$q_{i} = A_{i} \frac{\varepsilon_{i}}{\rho_{i}} \left(\sigma T_{i}^{4} - J_{i} \right)$$
 4-19

This can also be written as (since $\varepsilon_i + \rho_i = 1$):

$$q_{i} = A_{i}J_{i} - A_{i}\sum_{k=1}^{M} F_{ik}J_{k}$$
 4-20

Now consider the case of an enclosure with all surfaces at zero temperature except surface i which has $\sigma T_i^{\ \ \mu} = 1$.

$$J_{j} = \rho_{j} \sum_{k=1}^{m} F_{jk} J_{k}$$
 4-21

$$q_{j} = q_{ij} = A_{j}J_{j} - A_{j} \sum_{k=1}^{M} F_{jk}J_{k}$$
 4-22

or

$$q_{ij} = A_{j}J_{j}(1 - \frac{1}{\rho_{j}}) = -\left(\frac{\varepsilon_{j}}{\rho_{j}}\right) A_{j}J_{j}$$
 4-23

^{*}Radiosity is the sum of the emitted and reflected radiant power from a surface.



But by Equation 4-9 for the assumed constraints on surface temperatures

$$q_{ij} = -A_i \delta_{ij} = -A_j \delta_{ji}$$

Hence

$$\mathfrak{F}_{\mathtt{ji}} = \left\langle \frac{\varepsilon_{\mathtt{j}}}{\rho_{\mathtt{j}}} \right/ J_{\mathtt{j}}$$
 4-24

Substitution of Equation 4-24 into Equation 4-20 yields

$$\mathfrak{F}_{ij} = \varepsilon_{i}\varepsilon_{j}F_{ij} + \sum_{k=1}^{M} \varepsilon_{j}F_{kj} \left(\frac{\rho_{k}}{\varepsilon_{k}}\right) \mathfrak{F}_{ik}$$

$$4-25$$

This is identical to Equation 4-13.

SUMMARY

The method of Gebhart has been shown to be directly convertible to the "script F" of Hottel by the use of Equation 4-17. Similarly the network method has been shown to yield an expression for $\mathfrak{F}_{i,j}$ identical to that obtained from Hottel's method (Equation 4-13 and 4-25). Therefore, there is no difference in the methods and by algebraic manipulation, one method can be expressed in the terms of either of the other two.

4.2 IMPROVED METHOD OF RADIATION ANALYSIS

The available methods for radiation heat transfer analysis have been restricted by the assumptions given in Section 4.1 Recently, a review of the problem has been made and a procedure is now available for eliminating the restriction to nondirectional diffuse properties (4). The use of nongrey thermal radiation properties can be used in the manner described by Bevans and Dunkle (8). Perfectly specular properties can be treated by the method of Eckert and Sparrow (9) but the properties must be considered to be nondirectional. The case of polarization can also be treated (10) but the practicality is limited to a few cases. The most practical new technique is believed to be that given by the second approximation described in Reference 4. The following discussion will describe the adaptation of this method to development of a "script F."

The second approximation of Reference 4 considers surfaces which have directionality and components of reflection which are diffuse and specular. The expression for the heat transfer to a surface within an enclosure under the assumptions of wavelength independent properties is:

^{*}This later restriction can be easily removed but is not pertinent to the ensuing discussion.

$$q_{\mathbf{k}} = A_{\mathbf{k}} \mathbf{E}_{\mathbf{k}} \sigma \mathbf{T}_{\mathbf{k}}^{4} - \sum_{\mathbf{j}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{j}} \mathbf{F}_{\mathbf{k}\mathbf{j}} \mathbf{E}_{\mathbf{j}\mathbf{k}} \sigma \mathbf{T}_{\mathbf{j}}^{4}$$

$$- \sum_{\mathbf{j}=1}^{\mathbf{M}} \sum_{\mathbf{i}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{j}} \mathbf{P}_{\mathbf{i}\mathbf{j}\mathbf{k}} \mathbf{E}_{\mathbf{i}\mathbf{j}} \mathbf{F}_{\mathbf{k}\mathbf{j}} \mathbf{F}_{\mathbf{j}\mathbf{i}} \sigma \mathbf{T}_{\mathbf{i}}^{4}$$

$$- \pi \sum_{\mathbf{j}=1}^{\mathbf{M}} \sum_{\mathbf{i}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{j}} \mathbf{P}_{\mathbf{i}\mathbf{j}\mathbf{k}} \mathbf{P}_{\mathbf{i}\mathbf{j}} \mathbf{F}_{\mathbf{k}\mathbf{j}} \mathbf{F}_{\mathbf{j}\mathbf{i}} \mathbf{D}_{\mathbf{i}}$$

$$- \frac{\mathbf{M}}{\mathbf{M}} \sum_{\mathbf{i}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{j}} \mathbf{P}_{\mathbf{i}\mathbf{j}\mathbf{k}} \mathbf{P}_{\mathbf{i}\mathbf{j}} \mathbf{F}_{\mathbf{k}\mathbf{j}} \mathbf{F}_{\mathbf{j}\mathbf{i}} \mathbf{D}_{\mathbf{i}}$$

This can be written as:

$$q_{\mathbf{k}} = A_{\mathbf{k}} \tilde{\epsilon}_{\mathbf{k}} \sigma T_{\mathbf{k}}^{4} - \sum_{\mathbf{i}=1}^{\mathbf{M}} \sum_{\mathbf{j}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{i}} (\epsilon_{\mathbf{i}\mathbf{k}} F_{\mathbf{k}\mathbf{i}} + \rho_{\mathbf{i}\mathbf{j}\mathbf{k}} \epsilon_{\mathbf{i}\mathbf{j}} F_{\mathbf{k}\mathbf{j}} F_{\mathbf{j}\mathbf{i}}) \sigma T_{\mathbf{i}}^{4}$$

$$- \pi \sum_{\mathbf{j}=1}^{\mathbf{M}} \sum_{\mathbf{j}=1}^{\mathbf{M}} A_{\mathbf{k}} \alpha_{\mathbf{k}\mathbf{j}} \rho_{\mathbf{i}\mathbf{j}\mathbf{k}} \rho_{\mathbf{i}\mathbf{j}} F_{\mathbf{k}\mathbf{j}} F_{\mathbf{j}\mathbf{i}} D_{\mathbf{i}}$$

$$4-27$$

In matrix notation this becomes:

$$\begin{bmatrix} \mathbf{q_1} \\ \mathbf{q_2} \\ \vdots \\ \mathbf{q_M} \end{bmatrix} \begin{bmatrix} \epsilon_1 \sigma \mathbf{T_1}^{4} \\ \epsilon_2 \sigma \mathbf{T_2}^{4} \\ \vdots \\ \epsilon_M \sigma \mathbf{T_M}^{4} \end{bmatrix} \begin{bmatrix} \mathbf{a_{11}} \ \mathbf{a_{12}} & \cdots \ \mathbf{a_{1M}} \\ \mathbf{a_{21}} \ \mathbf{a_{22}} & \cdots \ \mathbf{a_{2M}} \\ \vdots \\ \vdots \\ \mathbf{a_{M1}} \ \mathbf{a_{M1}} \ \mathbf{a_{M2}} \end{bmatrix} \begin{bmatrix} \sigma \mathbf{T_1}^{4} \\ \sigma \mathbf{T_2}^{4} \\ \vdots \\ \sigma \mathbf{T_M}^{4} \end{bmatrix}$$

where

$$\mathbf{a}_{\mathbf{x}\mathbf{y}} = -\left(\mathbf{A}_{\mathbf{x}}^{\alpha}\mathbf{x}\mathbf{y}^{\varepsilon}\mathbf{y}\mathbf{x}^{F}\mathbf{x}\mathbf{y}\right) + \sum_{\alpha=1}^{M} \mathbf{A}_{\mathbf{x}}^{\alpha}\mathbf{x}\mathbf{y}^{\alpha}\mathbf{y}\mathbf{z}\mathbf{x}^{\varepsilon}\mathbf{y}\mathbf{z}^{F}\mathbf{x}\mathbf{z}^{F}\mathbf{z}\mathbf{y}$$

$$4-29$$

$$b_{xy} = -\sum_{\alpha=1}^{\infty} A_{x}^{\alpha} c_{xz} c_{yz} F_{xz} F_{zy} c_{xz}$$
4-30

The quantity D_k is given by:

$$D_{\mathbf{k}} = \frac{1}{\pi} \sum_{\mathbf{j}=1}^{\mathbf{M}} \varepsilon_{\mathbf{j}\mathbf{k}} \sigma_{\mathbf{j}}^{\mathbf{j}} F_{\mathbf{k}\mathbf{j}} + \frac{1}{\pi} \sum_{\mathbf{j}=1}^{\mathbf{M}} \sum_{\mathbf{i}=1}^{\mathbf{M}} \rho_{\mathbf{i}\mathbf{j}\mathbf{k}} \varepsilon_{\mathbf{i}\mathbf{j}} F_{\mathbf{k}\mathbf{j}} F_{\mathbf{j}\mathbf{i}} \sigma_{\mathbf{i}}^{\mathbf{j}}$$

$$+ \sum_{\mathbf{j}=1}^{\mathbf{M}} \sum_{\mathbf{j}=1}^{\mathbf{M}} \rho_{\mathbf{i}\mathbf{j}\mathbf{k}} \rho_{\mathbf{i}\mathbf{j}} F_{\mathbf{k}\mathbf{j}} F_{\mathbf{j}\mathbf{i}} D_{\mathbf{i}}$$

$$4-31$$

In matrix notation, these equations can be written:

where

$$d_{xy} = \begin{pmatrix} M & \rho_{yzx} \rho_{yz} F_{xz} F_{zy} & (x \neq y) \\ \sum_{z=1}^{M} \rho_{xzx} \rho_{xz} F_{xz} F_{zx} & (x = y) \end{pmatrix}$$

$$d_{xy} = \begin{pmatrix} M & \rho_{xzx} \rho_{xz} F_{xz} F_{zx} & (x = y) \\ M & \rho_{xzx} \rho_{xz} F_{xz} F_{zx} & (x = y) \end{pmatrix}$$

$$c_{xy} = \frac{1}{\pi} \quad \epsilon_{yx} F_{xy} + \sum_{z=1}^{M} \quad \rho_{yzx} \epsilon_{yz} F_{xz} F_{zy}$$
 4-34

If Equation 4-32 is now solved for the quantities D, we have

$$\{D\} = [d] [c] \{\sigma T^{4}\}$$
 4-35*

The notation [] has been introduced to denote a square matrix, e.g., the d or c matrix of Equation 4-32; the { } denotes a column matrix such as the D or σ T⁴ matrix of Equation 4-32; and []⁻¹ is the inverse of the indicated matrix



Solution of Equation 4-35 yields the various D_k 's required in Equation 4-28. Equation 4-28 can then be expressed as:

$$\{q\} = \{\varepsilon\sigma T^{4}\} + [a] \{\sigma T^{4}\} + [b] \{D\}$$
 4-36

A directional diffuse-specular "script F" can be obtained with Equations 4-35 and 4-36. Using Hottel's concept of a "script F," i.e., set all temperatures except one within the enclosure equal to zero and the remaining one equal to unity (say surface k), the heat flows (q) are then $\mathbf{q}_{\mathbf{k}}$. With this condition:

$$\left\{q_{kj}\right\} = \left\{c_{k}\right\} + \left\{a_{jk}\right\} + \left[b\right] \left\{D_{jk}\right\}$$
 4-37*

and

$$\left\{D_{kj}\right\} = \left[d\right]^{-1} \left\{c_{jk}\right\}$$
 4-38*

The solution then proceeds as follows:

- An index k is selected and the pertinent coefficients ckj selected.
- (2) D is computed for all j by Equation 4-38.
- (3) The values of a are selected and the values of qkj for all j are computed with Equation 4-37.
- (4) $\mathfrak{I}_{k,j}$ is then computed with the definition:

$$\mathfrak{I}_{jk} = \frac{q_{k,j}}{A_{j}}$$
 4-39

- (5) The next value of k is selected, and the calculation continues until all M surfaces have been computed. The reciprocity relationship $A_j \tilde{J}_{jk} = A_k \tilde{J}_{kj}$ is used to reduce the number of computations.
- (6) is used in the same manner as with Hottel's method and the solution of Equation 4-2 or 4-8.

$$\left\{q_{kj}\right\} = \begin{bmatrix} q_{k1} \\ q_{k2} \\ \vdots \\ q_{kM} \end{bmatrix} ; \left\{ \begin{matrix} 0 \\ \varepsilon_k \end{matrix} \right\} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ \varepsilon_k \end{bmatrix} ; \left\{ a_{jk} \right\} = \begin{bmatrix} a_{1k} \\ a_{2k} \\ \vdots \\ a_{Mk} \end{bmatrix} ; \left\{ c_{jk} \right\} = \begin{bmatrix} c_{1k} \\ c_{2k} \\ \vdots \\ c_{Mk} \end{bmatrix}$$



The equations presented in this section may appear to be more complicated and hence, more difficult than with the diffuse property assumption. Mathematically, this is not the case. The computations are more time consuming and require added computer time and storage space. This is only the penalty paid for more exact computations.



5. COMPUTER PROGRAM FOR DIRECTIONAL SPECULAR-DIFFUSE METHOD

The procedural steps required to calculate a "script F" (5) from the equations for the directional specular-diffuse analysis have been described in Section 4.2 This method has been programmed for an IBM 7094 as a program separate from any general program for thermal analysis. The technical basis for selecting the 5 procedure rather than the network approach have been discussed in the first portion of Section 4. For the reasons given there, most computer programs for thermal analysis have been written in terms of 3. Thus, the existing analysis programs could incorporate a directional specular-diffuse 5 as an input quantity with a minimum of alteration. Furthermore, the direction specular-diffuse 3 requires a much larger working computer storage than a diffuse 3. If an attempt was made to assemble a single 3 and analysis program, the number of surfaces would have been seriously limited. It is for these technical and practical reasons that the 5 calculation was programmed as a separate entity. The flow chart of the program is shown in Figure 8 and a complete printout in Appendix III. The symbols used are those of Section 4.2.

5.1 REQUIRED INPUT DATA

The physical factors which are required for the directional specular-diffuse 3 are:

- (a) the areas of the surfaces involved $(A_1, i = 1, 2, 3...)$
- (b) the number of surfaces used to subdivide the enclosure $(N; N \le 20)$
- (c) the directional reflectance of surface i in the direction of surface j (ρ_{ij} of Reference 4; designated RHØ in machine language)
- (d) the geometrical bidirectional reflectance of surface j for radiation from surface i which is reflected to surface k by surface j (ρ_{ijk} of Reference 4; designated R_{ijk} in machine language)
- (e) the geometrical diffuse shape factors between surfaces (F i i)

The only quantities which are not used in conventional diffuse 5 analysis are $\rho_{i,j}$ (RHØ) and $\rho_{i,jk}$ (R_{i,jk}). The use of the usual diffuse shape factors (F_{i,j}) is made possible by assigning the deviations from diffuseness to the reflectances. This is described in greater detail in Reference 4 and leads to the concept of geometrical reflectances, i.e., a property which is weighted by the geometry and nondiffuseness of the surface. The directional emittance of a surface is incorporated in the program as: $1-\rho_{i,j}$. This introduces the gray radiation assumption, i.e., properties independent of wavelength. If desired, either a band energy or monochromatic analysis could be performed (see Reference 4).

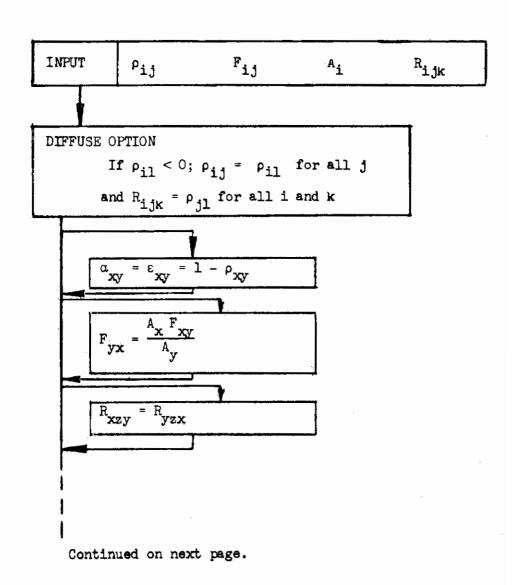


Figure 8. Computer Program Flow Chart

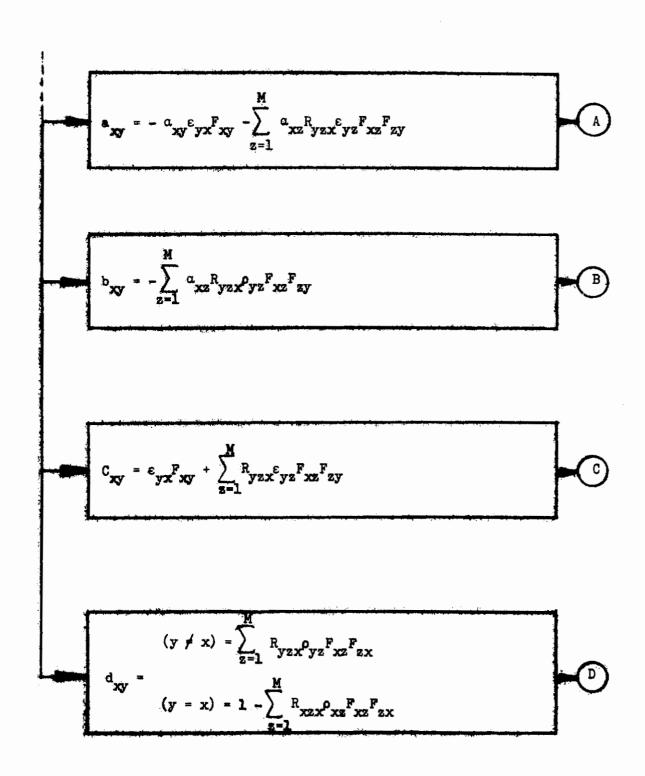


Figure 8. Computer Program Flow Chart (Cont.)

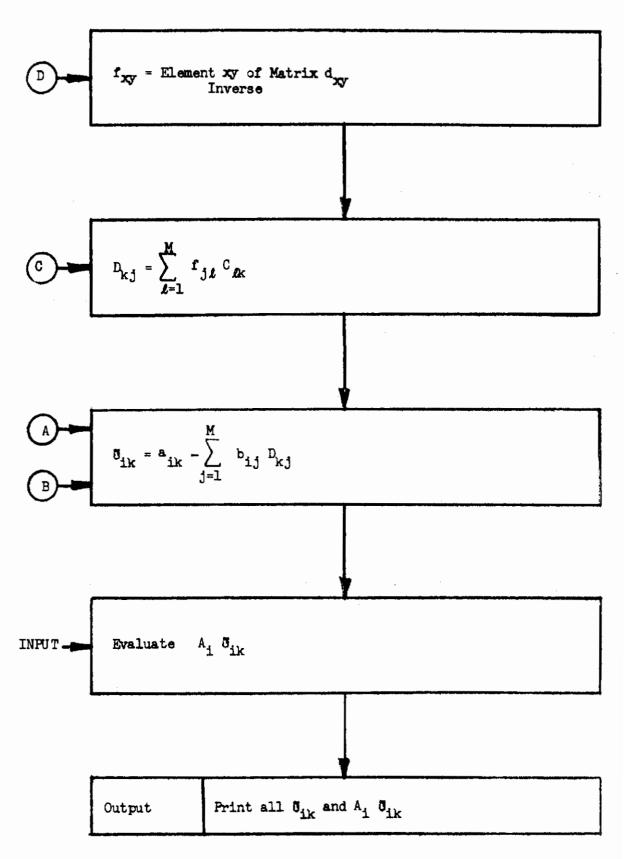


Figure 8. Computer Program Flow Chart (Cont.)



Values of ρ_{ij} and ρ_{ijk} (RHØ and R_{ijk}) can be approximated with data obtained in many Thermophysics Laboratories (4). The methods suggested for this approximation will be illustrated in Section 5.3 and 6.2

5.2 INPUT PROCEDURE

The input format is shown in Figure 9. The quantities indicated are as follows:

- N = the number of surfaces within the enclosure to be examined.

 The present program is storage limited to a maximum of 20 surfaces.
- CLR = a flag directing the program to clear itself of input information (CLR = 1), prior to proceeding to the next case, or instructing the program to retain input information (CLR = 0) for the following case. When CLR is set to zero, only those quantities that vary from case to case need be entered, all other information will be retained.
- L = a flag used in the column labeled "PRE" of the load sheet.

 The quantity L is used in conjunction with CLR = 0. An input matrix is not cleared of information if the quantity L is inserted in the column labeled "PRE."
- M = a flag used in the column labeled "PRE" of the load sheet. It instructs the program to clear the input matrix of information prior to storing data.
- $ho_{ij} = RH\emptyset = the directional reflectivity of surface i in the direction of surface j. For program convenience, <math>
 ho_{il}$ is set equal to the negative value of the hemispherical reflectance for a diffuse surface.
- F_{ij} = F = the shape factor of surface j as viewed by surface i. Only the lower triangular half of the shape factor matrix need be entered; that is: F₁₁, F₂₁, F₂₂, F₃₁, F₃₂, F₃₃, · · · F_{mn}.
- R_{ijk} = Geometrical bidirectional reflectance of surface j for incident energy from surface i and reflected to surface k. Bidirectional reflectivities are inputed in block form as indicated by the sample load sheet. The block number corresponds to the third subscript k, and the other two subscripts are contained within the k'th block. Only the upper triangular portion of the three dimensional R_{ijk} matrix need be entered. That is, R_{ljl} for j = 1 to n is entered for the first matrix, K = 1; R_{lj2} R_{2j2}, for j = 1 to n is entered for the second matrix, K = 2; R_{lj3}, R_{2j3}, R_{3j3} for j = 1 to n is entered for the third matrix,
- K = 3; and so on until the full matrix is entered for K = n. $A_{i} = A = surface$ area of node i.



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Figure 9. Program Input Format



An unlimited number of cases may be "stacked"; all that is required to run several cases together is an END card between cases. Output quantities 5 and 5-area products, are printed out in matrix form.

The following is a very simple problem which illustrates the input loading. Consider two infinite diffuse strips of unit width and separation, as shown below:

(2) surface (1) and (2) (3)
$$\ell$$
 surface (3) is space $\rho_1 = \rho_2 = 0.9; \ \rho_3 = 0$

Input information:

(a)
$$\rho_{12} = \rho_{13} = \rho_{21} = \rho_{23} = 0.9$$

 $\rho_{31} = \rho_{32} = \rho_{33} = 0$
(b) $F_{12} = F_{21} = F_{33} = 0.414214$
 $F_{13} = F_{23} = 0.585786$
(c) $R_{213} = R_{312} = R_{313} = R_{212} = \rho_1 = 0.9$
 $R_{123} = R_{321} = R_{323} = R_{121} = \rho_2 = 0.9$
(d) $A_1 = A_2 = 1.0$, $A_3 = 2.0$

The load sheet for the above problem with diffuse surfaces can be found in Figure 10. The result of this computation is 0.0933965, which can be compared to the value given by Reference 9 of 0.09340.

It should be noted that in addition to comparing very favorably with the 3 matrix evaluated by hand, using Hottel's techniques, the following holds

$$\bar{\mathbf{e}}_{\mathbf{k}} = \sum_{j=1}^{M} \bar{\mathbf{s}}_{\mathbf{k}j} = \text{hemispherical emittance}$$

as it should.

^{*}It should be noted that all quantities should be left justified within their respective fields.



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Figure 10. Load Sheet for Two Parallel Infinite
Diffuse Strips of Unit Width and Separation

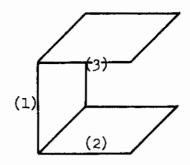


5.3 EXAMPLES OF INPUT FOR DIFFUSE, SPECULAR, AND SPECULAR-DIFFUSE

The following problem has been selected to illustrate the input required for the three cases of diffuse, specular and directional specular-diffuse. The $\overline{\imath}$ computer program given here can treat these cases by manipulation of the quantity R_{ijk} (ρ_{ijk}). As discussed in Reference 4, this factor is approximated by:

$$\rho_{ijk} = (\rho_D)_j + (\rho_S)_j \qquad \left\{ \frac{F_{jk(j)}}{F_{kj} F_{ji}} \right\}$$
 5-1

If the perfectly diffuse assumption is to be made, the specular reflectance of surface j (ρ_{S}) is set equal to zero; if the perfectly specular assumption is made, the diffuse reflectance (ρ_{D}) is set equal to zero. The configuration to be used to illustrate the input is shown below:



Surface 1: ρ_1 = 0.973 (vacuum deposited aluminum) Surface 2: ρ_2 = ρ_3 = 0.116 (3M black paint) and 3: Surface 4: ρ_4 = 0 (surrounding space) $F_{12} = F_{21} = F_{31} = F_{32} = F_{41} = F_{43} = 0.2$ $F_{44} = 0.4$ $A_1 = A_2 = A_3 = 1$ $A_4 = 3$

The diffuse assumption input sheet is shown in Figure 11.



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SYMBOL F	M	N CLR RHØ O1, O1 O2, O1 O3, O1 O4, O1 F	4 20, 20 -0.973 -0.116 -0.116	EXP.		SYMBOL	PR	LOC.		VALUE	
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Figure 11. Load Sheet for Sample Problem; Diffuse Assumption

The specular assumption utilizes the same data as above, but the reflection is assumed to be perfectly specular. For this condition,

$$R_{213} = \rho_{12} \left\{ \frac{F_{23(1)}}{F_{21}F_{13}} \right\}$$
$$= 2.0897$$

The quantity R_{412} is obtained by noting for R_{ijk}

$$\rho_{jk} = \sum_{i=1}^{n} R_{ijk} F_{ji}$$
 5-2

i.e., conservation of energy. Thus,

$$R_{412} = \frac{\rho_{12} - R_{312}F_{13}}{F_{14}} = 0.9323$$

Use is made of reciprocity to find $R_{312} = R_{213}$, $R_{214} = R_{412}$, and $R_{412} = R_{413}$. The load sheet for this problem is shown in Figure 12.

The directional specular-diffuse procedure requires a knowledge of the directional properties of the surfaces. The greatest angle subtended by surface 3 as viewed from surface 2 is less than 55 degrees. For the black surface, the directional reflectance and hence directional emittance is very nearly equal to the near normal value. Therefore, the near normal value was used for ρ_{23} and ρ_{32} . To obtain ρ_{21} , a heat balance was used, i.e., for the general case of surface i

$$\left(\rho_{H}\right)_{i} = \frac{1}{A_{i}} \sum_{i=1}^{n} \rho_{ij} A_{i} F_{ij}$$
5-3

where

 $(\rho_{H})_{i}$ = hemispherical reflectance of surface i.

The value of $\boldsymbol{\rho}_{\mbox{2l}}$ was obtained from:

$$\rho_{21} = \frac{(\rho_{\rm H})_2 - F_{23}\rho_{23}}{4 F_{21}}$$

or

$$\rho_{21} = 0.1275$$



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Figure 12. Load Sheet for Sample Problem; Specular Assumption



Reciprocity was utilized to obtain $\rho_{21}=\rho_{12}$, $\rho_{31}=\rho_{13}$, etc. Using the procedure described for ρ_{21} , the values of the other geometrical reflectances were:

$$\rho_{12} = \rho_{13} = 0.9716$$

$$\rho_{14} = 0.9744$$

$$\rho_{23} = \rho_{32} = 0.07$$

The load sheet for this problem is shown in Figure 13. The computer results for the above configuration will be found in Section 6.



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Figure 13. Load Sheet for Sample Problem; Directional Specular-Diffuse Assumption



6. EXPERIMENTAL COMPARISON OF SPECULAR, DIFFUSE AND DIRECTIONAL SPECULAR-DIFFUSE ANALYSES

The purpose of this task was to obtain an experimental evaluation of the different analytical methods. Such a comparison must utilize an experimental system that is simple conceptually and physically. Otherwise the effects of geometry, conduction, convections, extraneous heat losses, etc., will not be controlled. The experimental configurations chosen are shown in Figure 14. A test consisted of placing the experiment within a cold wall vacuum chamber (to eliminate convection), insulating the non-radiative surfaces, supplying a known quantity of power to one of the surfaces and measuring the equilibrium temperatures of the other surface(s). The experimental results were then compared to the predicted values using the directional specular-diffuse analysis (4), the specular property assumption and the diffuse property assumption.

The following discussion will be divided into three parts: (1) the experimental test method, (2) the analytical results, and (3) a discussion of the comparison of experiment and analysis.

6.1 EXPERIMENTAL METHOD AND PROCEDURE

The configuration selected for test are shown in Figure 14. The test surfaces were six such squares of 1100 aluminum 0.0625 inches thick. In each case the lower surface was selected as the heat source and the remaining surface(s) allowed to reach an equilibrium condition with the environment. The heated surface had a heater of approximately 200 ohms cemented to its underside (the non-radiative side). This heater consisted of 40 gage constantan wire sandwiched between two sheets of 1 mil Mylar. Voltage leads were attached at the heater boundary and the four terminal resistance method used (see Section 3.1) to calculate power dissipation. The electrical measuring circuit was the same as shown in Figure 6 of Section 3 with a Leeds and Northrup 8686 substituted for the Type K 3.

Originally, the back of each surface was insulated with 20 layers of super insulation. However, the edge heat leak was found to be too large relative to the heat absorbed by the unheated surfaces. A guard heat system was found to be necessary. This was obtained by placing a heated plate on the outside of the insulation and adjusting the dissipation until the temperature difference across the insulation was zero, i.e., no heat flow through the insulation. The edges of the insulation, guard heater, and test surface were covered with 1/4 mil thick aluminized Mylar, aluminum side out. These steps reduced the edge and back heat "leak," i.e., uncontrolled loss, to approximately 1 Btu/hr for a test surface temperature of 70°F. This was satisfactory for all test surfaces except the surface coated with vacuum deposited aluminum. The radiative heat loss or gain from such a surface was the same order of magnitude as the edge loss. Hence, this test surface had to be used as a passive surface, i.e., a reflector, and no heat balance could be performed for it.

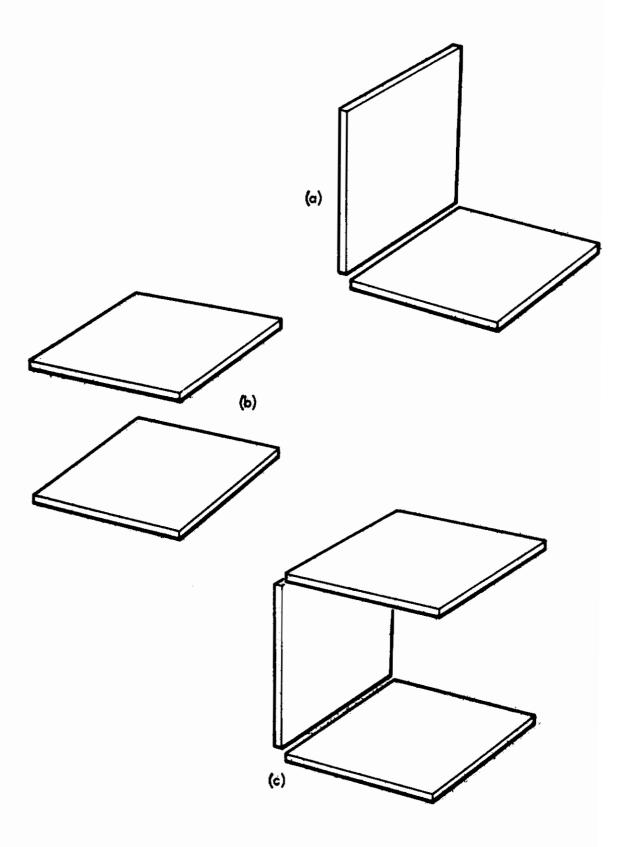


Figure 14. Configuration Used for Test of Radiation Analysis
47

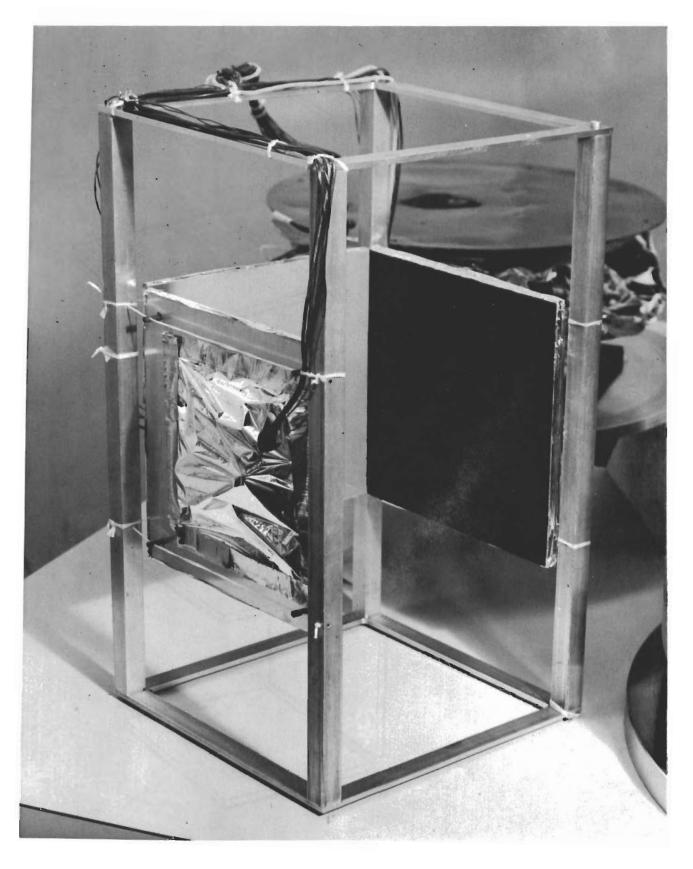


Figure 15. Test Configuration in Test Fixture

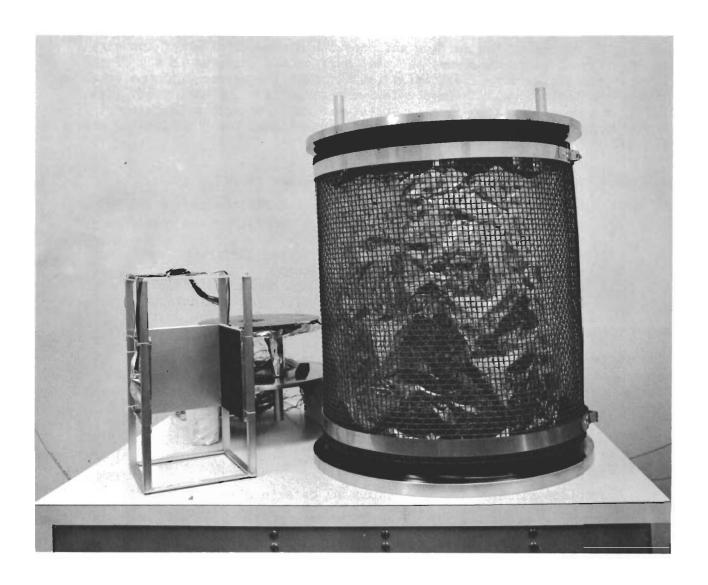


Figure 16. Test Configuration Ready for Testing



Each test surface was supported within a framework by dacron cords attached to phenolic stand-off attachments. In this manner the test surfaces were isolated from the framework but properly positioned and restrained (see Figure 15). This framework was mounted within a LN₂ cooled baffled and the assembly placed within a vacuum system. A pressure of 10^{-5} torr or lower was obtained during the testing. The system is illustrated in Figure 16.

Thermocouples were placed on at least two points of each test surface; one at the center of the surface and one within one-half inch of the edge. No significant gradient across the test surface was observed in any of the tests; i.e., the surfaces were essentially isothermal. The thermocouple material was copper-constantan. All thermocouples were taken from the same roll. The voltages generated by the thermocouples were measured with a Leeds and Northrup Type 8686 potentiometer using a conventional ice junction compensation system.

The test procedure consisted of the following steps:

- (1) setting the predicted power dissipation for the source surface
- (2) setting estimated guard heat dissipation(s) for the receiving surface(s)
- (3) observing the temperature of the receiver surface(s) and adjusting the guard power dissipation(s)
- (4) when the receiver surface(s) and guard heater(s) indicated a negligible temperature difference for thirty minutes, at least two sets of data were recorded within the next thirty minutes.

The latter step insured that the surfaces were in equilibrium for approximately one hour. The accuracy of the measurements are estimated to be:

Temperature difference	+ 0.1°F							
Temperature	- l ^o f							
Total power dissipated by	1.5%							
the heat source								

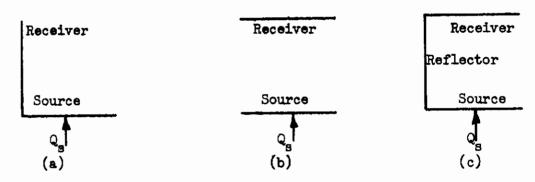
A complete summary of the experimental data is given in Appendix III.

6.2 ANALYTICAL PREDICTION

The radiative heat flow from the source surface and the temperature of the receiver surface were predicted by the analytical methods based upon the three different property assumptions: diffuse (1,2,3), specular (7), and the directional specular-diffuse (4). The prediction served to test the utility and practicality of the computer program developed for this study (Section 5) as well as provide a basis of comparison between theory and experiment.

The test configurations have been described in Section 6.1 and illustrated in Figure 14. These three configurations were combined with different surface coatings to give six different test systems. These systems are schematically represented in Figure 17. The directional





Test Surface Coatings

	Source	Receiver	Reflector	Configuration
1.	"3M" Flat Black Paint	"3M" Flat Black Paint		(a)
2.	"3M" Flat Black Paint	"3M" Flat Black Paint		(b)
3.	"3M" Flat Black Paint	"3M" Flat Black Paint	Vacuum Deposited Aluminum	(c)
4.	"3M" Flat Black Paint	"3M" Flat Black Paint	Rinshed-Mason Leafing Aluminum Paint	(c)
5.	"3M" Flat Black Paint	Rinshed-Mason Leafing Aluminum Paint	Vacuum Deposited Aluminum	(c)
6.	"3M" Flat Black Paint	Rinshed-Mason Leafing Aluminum Paint	Anodized Aluminu	m (c)

NOTE: The coating material descriptions are described in detail in Figures 18 through 21.

Figure 17. Experimental Matrix for Test of Radiation Analysis



reflectances of these coatings for a black body source at 540°R are shown in Figures 18 through 21. Included in these figures is the specular reflectance for the same radiation source. The specular reflectances were measured with a goniometric reflectancesr shown in Figure 22. The directional reflectances were measured with a heated cavity reflectometer similar to that described in Reference 11.

The method of determining the various quantities and establishing the input for the computer program has been described in Section 5.3. The results of the computer calculations are shown in Table 7.

6.3 COMPARISON OF EXPERIMENTAL AND ANALYTICAL RESULTS

An examination of the results presented in Table 7 will quickly show one consistent fact: In every case, the experimentally measured temperature exceeded the value predicted by any of the analytical methods. A hasty conclusion would be that the experiments were in error in some manner. After re-examining the experimental technique for major errors, nothing sufficiently significant could be found. Conversely, many questions can be raised relative to the analytical predictions. The following discussion will be concerned with the errors of prediction. However, the possibility of an unrealized source of error in the experiments is not ruled out.

The difficulties with the predictions are believed to be centered about the thermal radiation properties used. The analyses are based upon the gray radiation assumption, i.e., wavelength independent properties. The source surfaces was operated at approximately 585°R whereas the receiver surfaces ranged between 340 and 415°R, i.e., a difference of 170 to 245°F. All properties used in the analysis assumed a material and source temperature of 585°R for emittance and reflectance. This "non-gray" error would be particularly noticeable with anodized aluminum and aluminum paint surfaces. To correct for this, the analyses would have to be performed on at least the band energy basis (4).

A second error was in the measurement of the properties. The heated cavity reflectometer is known to have an error due to sample heating (11). This error could be of the order of .02-.04 in directional reflectance (or emittance) and would affect the predicted temperatures slightly. It would have a more direct effect upon the predicted heat loss by the source surface. In only one case (Test 5), was the measured heat loss lower than predicted. In this instance, it was within experimental accuracy for the nearest prediction. The predicted temperatures and heat fluxes are too interrelated to separate them except as a first approximation. Thus, no firm conclusion can be drawn from this one case. However, the problem of sample emission is not considered to have been a major source of the discrepancies as judged from the spectral data.

Polarization of the energy with the monochromator of the heated cavity can also cause an error. For very highly reflective materials, e.g., vacuum deposited aluminum, or smooth dielectrics, polarization may cause an error as large as 10 to 20 percent in the reflectance at high angles.



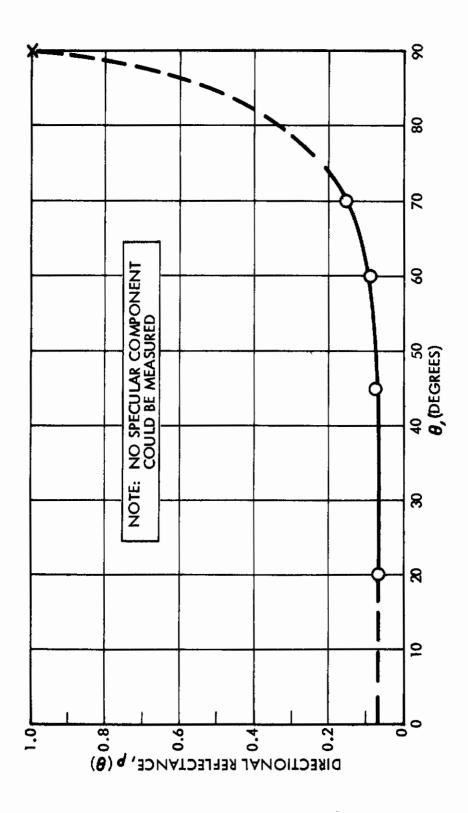


Figure 18. Directional Reflectance of 3M Flat Black Paint to a 540°R Black Body as a Function of Angle

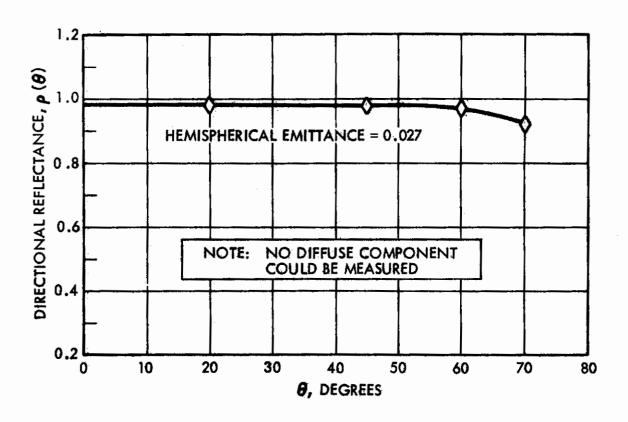


Figure 19. Directional Reflectance of Vacuum Deposited Aluminum to a 540 R Black Body as a Function of Angle

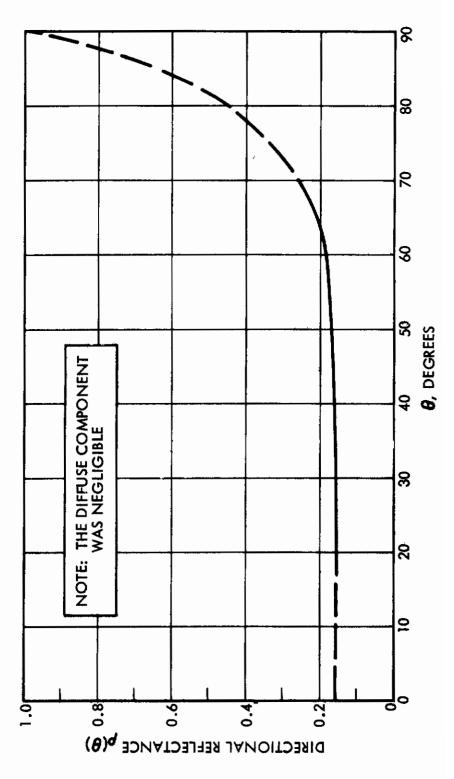


Figure 20. Directional Reflectance of Sulfuric Soft Anodized Aluminum (Type 1100), 0.0005 Inches Thick to a 540 R Black Body as a Function of Angle

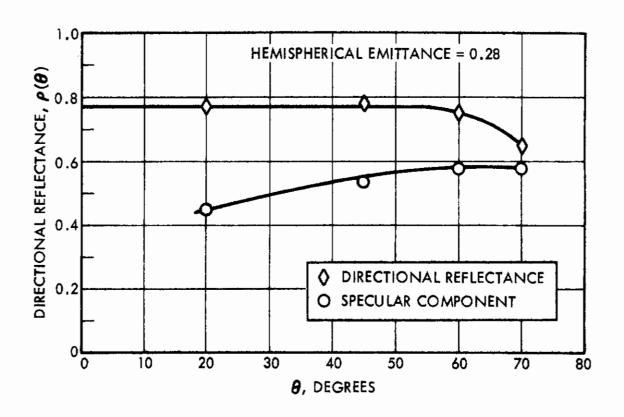


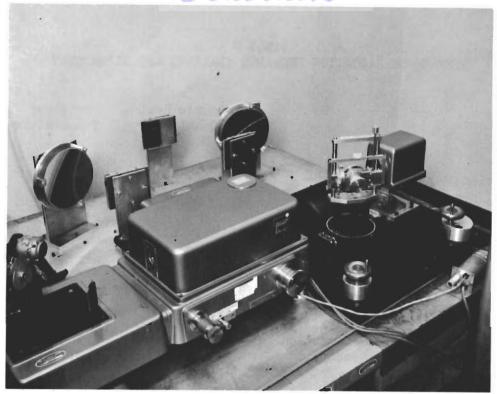
Figure 21. Directional Reflectance of Rinshed-Mason Leafing Aluminum Paint to a 540°R Black Body as a Function of Angle

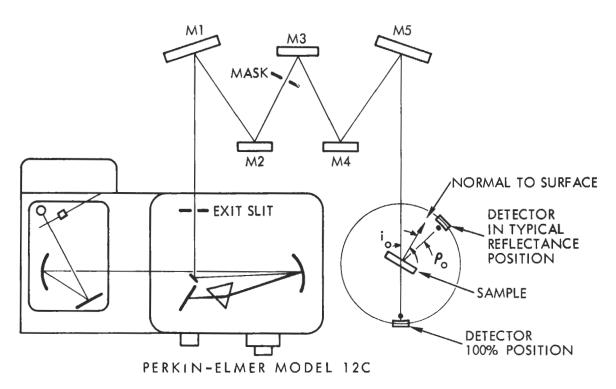


TABLE 7
SUMMARY OF RADIATION EXCHANGE ANALYSES AND EXPERIMENT

		Q _s	${ t T}_{ t R}$
		Source Heat Quantity Btu/hr	Receiver Temperature OR
Configuration*			
1	Experimental Directional Specular-	29.83	345.2
	Diffuse Analysis	29.41	340.4
	Specular-Assumption	29.17	342.2
	Diffuse Assumption	29.17	342.2
2	Experimental Directional Specular-	42.50	393.8
	Diffuse Analysis	42.06	38 6
	Specular-Assumption	41.2	386.4
	Diffuse Assumption	41.2	38 6.4
3	Experimental Directional Specular-	41.29	428.2
	Diffuse Analysis	40.68	419.4
	Specular-Assumption	40.93	412.0
	Diffuse Assumption	39.69	393.8
4	Experimental Directional Specular-	40.7	423.5
	Diffuse Analysis	40.33	415.5
	Specular-Assumption	40.25	408.8
	Diffuse Assumption	40.54	397.4
5	Experimental Directional Specular-	39.93	409.7
	Diffuse Analysis	40.0	391.6
	Specular-Assumption	40.3	402.5
	Diffuse Assumption	40.2	383.8
6	Experimental Directional Specular-	40.05	398.7
	Diffuse Analysis	39.21	382.3
	Specular-Assumption	39.56	391.1
	Diffuse Assumption	40.19	387.9

^{*}See Figures 14 and 17.





M1, M5 SPHERICAL MIRRORS 300 mm f.I. M2, M3, M4 FLAT MIRRORS

Figure 22. STL Goniometric Reflectometer



This source of error has also been recently recognized and the information required to assess this error is not yet available for the monochromator used. In the case of the tests described, only the 3M flat black paint will be free of this error.

A fourth source of error was the approximations used to obtain the geometrical reflectances; i.e., the interaction between spatial variation of reflectance and the shape factor integral. The methods used to approximate these properties have been described in Section 5.3. Until a spatial distribution of the reflectance property of a number of surfaces have been obtained and incorporated in the integration of a shape factor, the magnitude of this error will not be known. Simple analysis of an extreme case has shown this to be as large as 30 percent (4).

Considering all of these factors together, plus the probable experimental error, leads to the conclusion that the predicted temperatures should be re-examined. This would require the analyses to be performed on a band energy basis and with a more detailed evaluation of the properties.

The analytical results given in Table 7 also offer an opportunity to compare the different methods of analysis. The program described in Section 5 is based upon the method given in Reference 4. The technique is an admitted approximation to the integral equations describing the radiation exchange within an enclosure. The other two methods are also approximations in that an assumption is made relative to the radiation properties, i.e., nondirectional perfectly specular or perfectly diffuse. The approach programed to this study resulted in a set of equations which were very similar to those obtained in the diffuse approximation and could be solved with a slight increase in time. In contrast, an enclosure with perfectly specular surfaces can require extensive preliminary calculation to obtain the "specular interreflections."

The test configurations of Figure 17 are examples of very simple enclosures which are easily solved by any one of the three methods. They do not represent a complex enclosure and cannot adequately demonstrate the differences between the specular, diffuse and directional speculardiffuse methods. A trend can be inferred, however. For example, Test Configurations 1 and 2 should yield identical results for the specular and diffuse assumptions. The directional specular-diffuse analysis yields different results because the emission from source occurs at large angles from the normal. The predicted temperature of the receiver is higher for Test 1 and lower for Test 2 because of the angular effects of absorption. For Test 3, the specular analysis is suitable but does not account for the directional properties. The diffuse analysis does not account for specular reflection and radiation is "diffusely" reflected back to the source. directional specular-diffuse result is between these two. Similar arguments hold for Test Configurations 4, 5, and 6. These geometries are more complicated by the use of the aluminum paint and anodized aluminum which have directional and/or specular components of reflection. In more complicated enclosures, such a simple explanation of possible differences is not practical. The only comment that can be made is that the directional specular-diffuse analysis is a more realistic approximation to physical fact.



7. CORRELATION OF COMPONENT JOINT EXPERIMENTAL RESULTS

At the request of the Technical Monitor, C. J. Feldmanis, an effort was made to correlate the experimentally measured values of joint conduction. This work was a substitute for the completion of the preliminary design task originally scheduled for the last portion of the program. This correlation effort has resulted in a simplified approach based on the conduction flow pattern to a circular cavity (region of the bolts) in the mating parts. For the thin plates in the component mounting joints, the conduction at the bolts was very high and the apparent contact area small. This led to the conclusion that macroscopic effects were of the greatest significance.

A review of the technical literature revealed little information that would be useful in predicting interface conductance for the bolted joints of this study. A subsequent study of the pressure distribution indicated that the apparent contact area occupies only to a small region near the bolts. This suggested that the predominant thermal resistance lies in the mating plates themselves. This correlation effort has resulted in a simplified expression for the interface conductance based on the heat flow pattern in a large circular region to a circular sink at the center. These comments apply specifically to the mounting plate configuration investigated in this study.

7.1 REVIEW OF LITERATURE

A review of technical literature reveals that the study of vacuum thermal contact resistance is of recent vintage. Past emphasis has been upon joints in a conducting fluid; e.g., air. This is not surprising since the need for information on the behavior of heat flow through connecting elements in a vacuum was not great until the advent of satellites. An excellent review of technical literature is contained in Reference 12 and a bibliography on contact conductance is contained in Reference 13; Appendix V list references that are not reported in Reference 13.

As background to the correlation to be presented, two well known methods that have been proposed will be cited. The applicability (or lack of it) to the type of joints considered in the present study will be indicated.

Fenech and Rohsenow (14) developed an expression for the thermal conductance of a mathematical model with contacting surfaces idealized as cylindrical contacts equally spaced in a triangular array. The thermal conductance was expressed in terms of the thermal conductivity of the metals and of the fluids of filling the voids, the real area in contact, the number of contact points per unit area, and the volume average thickness of the void gaps. A method of obtaining these physical properties of a contact is contained in Reference 15. The need for the profiles of the contacting surfaces precluded the examination of this method.



While most investigators were concerned with microscopic areas of contacts (those due to surface finish), Clausing and Chao (12) concluded that macroscopic resistances (that due to large scale waviness or nonflatness) was predominant over the microscopic resistance for a majority of engineering surfaces. The interface conductance was expressed in terms of the mean thermal conductivity of the two contacting materials, the radius of the macroscopic constriction ratio, the contact pressure, the macroscopic constriction ratio, the harmonic mean of the moduli of the two-contacting materials, and the total equivalent flatness deviation. This method requires the measurement of flatness deviation and surface finish; the latter is readily obtained, but the former is more difficult to measure. This method was not applied since subsequent studies showed that the apparent contact area (the region adjacent to the bolts) represents only a small percent of the total joint area. However, the concept of constrictive heat flow is employed in the present study, except that it is applied in a much larger, gross scale. The method is discussed below.

The two methods discussed above considered a physical system without a disruptive element such as a bolt. Intuitively, the influence of fasteners should be great. An attempt at correlating joint conductance data is reported in Reference 16, and the resultant expression is semi-empirical. The method employed in the present study is semi-analytical and the close correlation with experimental results strongly suggests that the governing resistance is centered in the plate itself; at least for the type of joints considered here. The analytical method is discussed below.

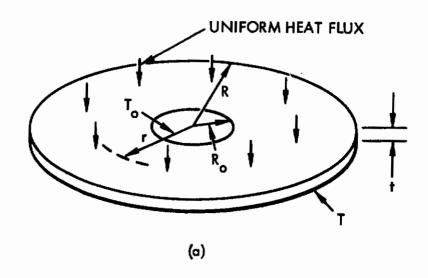
7.2 ANALYTICAL DEVELOPMENT

The correlation of joint conductance data was limited to the component joint configurations. An anlytical model was postulated based on the work done by previous workers, experimental data and engineering judgement. The basic concept of the proposed method is that the controlling thermal resistance is the plate. It is postulated that the points of contact which contribute to the conductance are in the small region under and around the bolts. The problem is then to describe the heat flow in the plate to the bolt area. Two mathematical models were employed for this purpose.

7.2.1 ANALYTICAL MODEL I

The first model is shown in Figure 23(a). It is a disc with uniform heat flux over its surface and conduction to a central area at a constant temperature. The outside surface (r = R) is assumed to be insulated. This model is used to describe heat flow in a joint with only a few bolts in relation to the total area.





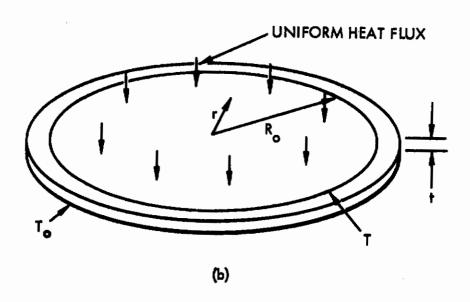
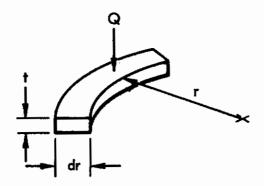


Figure 23. Analytical Models for Bolted Component Joint Correlation

For an incremental volume at radius r, a heat balance yields,



Q
$$2\pi r dr = -2\pi k t r \frac{dT}{dr} + 2\pi k t r \frac{dT}{dr}$$
 7-1

or

$$Q = -\frac{kt}{r} \frac{d}{dr} \left(r \frac{dT}{dr} \right)$$
 7-2

with boundary conditions:

at
$$r = R$$
, $\frac{dT}{dr} = 0$ (insulated) and

at
$$r = R_0$$
, $T = T_0$

Hence,
$$T_0 - T = \frac{Q}{Rt} + \frac{1}{4} (r^2 - R_0^2) + \frac{1}{2} R^2 \ln \frac{R_0}{r}$$
 7-3

Now let $\frac{\mathbf{r}}{R} = \eta$, $\frac{R_o}{R} = \eta_o$

...
$$T_0 - T = \frac{QR^2}{kt} + \frac{1}{4} (\eta^2 - \eta_0^2) + \frac{1}{2} \ln \frac{\eta_0}{\eta} = \Delta T$$
 7-4

The conductance of one plate is:

$$h = \frac{Q\pi R^2}{R}$$

$$\int_{R_0}^{R} (T-T_0)2\pi r dr$$
7-5

Substituting ΔT from Equation 7-4 and changing the limits of integration gives:

$$h = \frac{QnR^{2}}{1} \int_{\eta_{o}}^{QR^{2}} \frac{\left[\frac{1}{4} (\eta_{o}^{2} - \eta^{2}) + \frac{1}{2} \ln \frac{\eta}{\eta_{o}}\right] 2m\eta d\eta}{7-6}$$

Integrating and substituting the limits yields

$$h = \frac{2kt}{R^2} \qquad \left[\frac{1}{\eta_0^2 - \eta_0^4 /_4 - \ln \eta_0 - 3/4} \right]$$
 7-7

The bracketed term of Equation 7-7 is plotted in Figure 24 and the conductance versus radius for several effective contact radius values is shown in Figure 25.

7.2.2 ANALYTICAL MODEL II

The model which can be applied to a system having contact around the periphery is shown in Figure 23(b). The equation for this system is:

$$Q = -\frac{kt}{r} \frac{d}{dr} \left(r \frac{dt}{dr}\right)$$
 7-8

The boundary conditions are:

$$r = 0$$
, T is finite
 $r = R_0$, $T = T_0$

Solution of Equation 7-8 yields,

$$T - T_0 = \frac{Q}{4kt} \left[R_0^2 - r^2 \right]$$
 7-9

The conductance of one plate is:

$$h = \frac{Q\pi R^2_o}{R_o}$$

$$\int (T-T_o) 2\pi r dr$$
7-10

Substituting ΔT from Equation 7-9 and integrating gives:

$$h = \frac{8kt}{R_0} 2$$
 7-11

This equation is plotted in Figure 26.

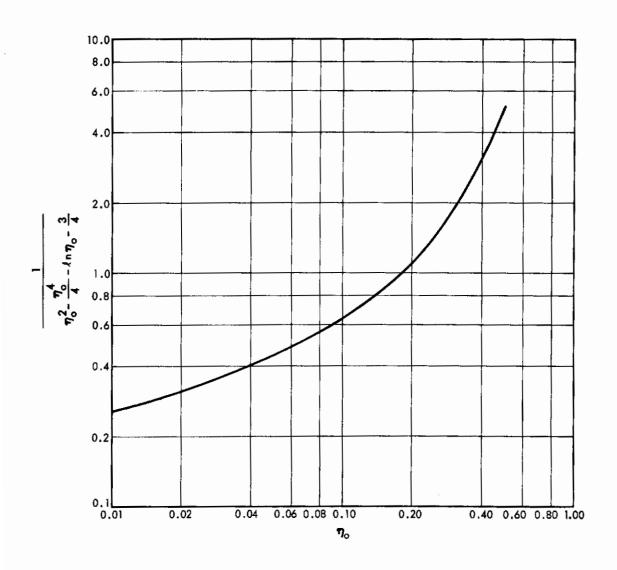


Figure 24. The Quantity $\left[\eta_o^2 - (\eta_o^4/4) - \ln \eta_o - 3/4\right]^{-1}$ as a Function of η_o

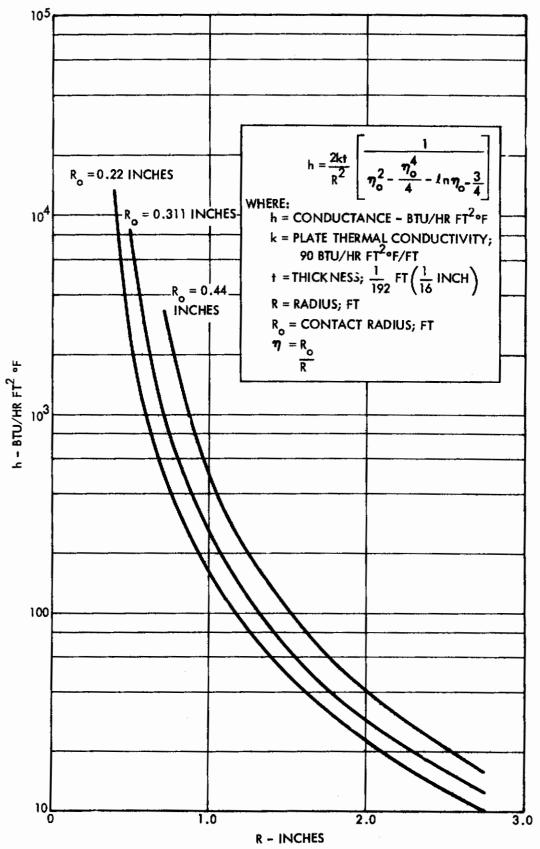


Figure 25. The Thermal Conductance of a Single Contact Junction as a Function of Contact Radius (R_o) for an Aluminum Plate 1/16th Inch Thick

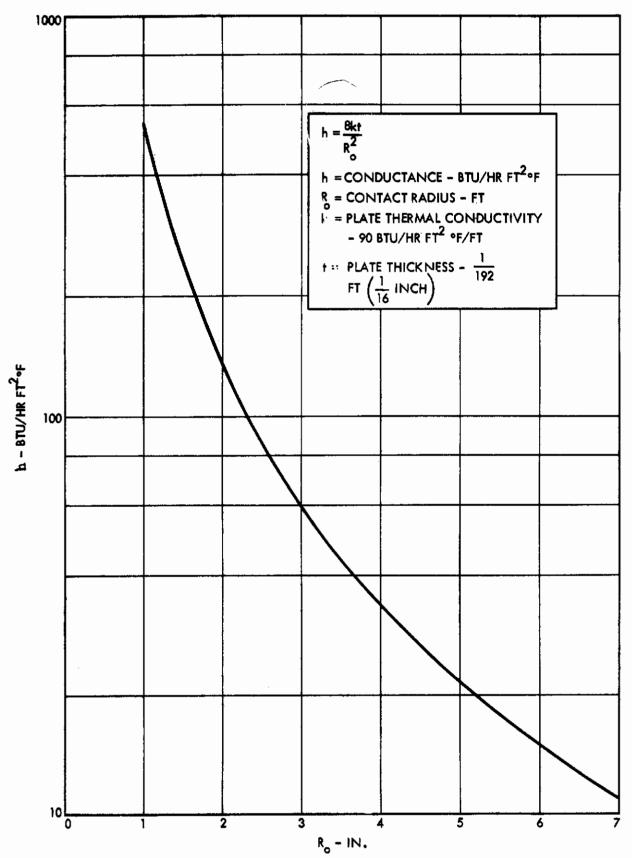


Figure 26. The Thermal Conductance of a Peripheral Contact Junction for an Aluminum Plate 1/16th Inch Thick



7.2.3 CONTACT REGION AROUND A BOLT

The contact area and conductance of a bolt is based on the deformation of the plates under bolt head. The method used to determine this quantity is that presented in reference (17). The analysis given by this reference assumes a uniform loading over the bolt area. The resultant stress distribution is shown in Figure 27 and can be expressed as (Equation 56, Reference 17):

$$\frac{\sigma_{z}}{\sigma_{p}} = 1 - \left(\frac{r}{c}\right)$$
7-12

The quantity c is dependent upon the bolt diameter, a, and the plate thickness, $\frac{b}{2}$. For a 1/16-inch plate in contact with a 1/8-inch plate, the effective contact radius, c, is given by Reference 17 as 1.35a.

The pressure under the bolt must be computed for use in the above expression. The tensile load in a bolt torqued to a preset value is determined from the approximate relation given in Reference 18.

$$T = 0.20 \text{ Fd.}$$
 7-13

where

T = bolt torque, 24 in.-lb.

F = tensile load, lb.

d = major thread dia. = .190 in.

or

F = 630 lb.

This value is conservative for the present application; that is, it yields a lower conductance than values given by other references. Aron and Colombo (16), for example, use a value of 800 lb. for 22 in.-lb. torque in the same size bolt.

The bolt (NAS 563) has a measured bearing diameter of 0.344 inches and the nut (NAS 671) has a measured bearing diameter of 0.312 inches. The area under the nut was used to obtain the pressure, assuming uniform loading ($\sigma_{\rm D}$ = P)

$$P = \frac{F}{A} = \frac{630 \text{ lb}}{.0468 \text{ in}} 2 = 13,450 \text{ lb/in}^2$$
 7-14

This result was used with Equation 7-12 to obtain the pressure distribution and conductance at the bolt. The solution of Equation 7-12 for σ_z , using the results of Equation 7-14, are plotted in Figure 28. The pressure distribution was used by dividing the area into annular zones and evaluating each zone to estimate its conductance. The numerical values were obtained from the conductance versus pressure plot given in



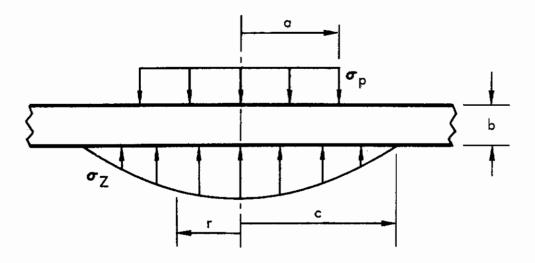


Figure 27. Stress Distribution in a Bolted Plate for Uniform Bolt Pressure

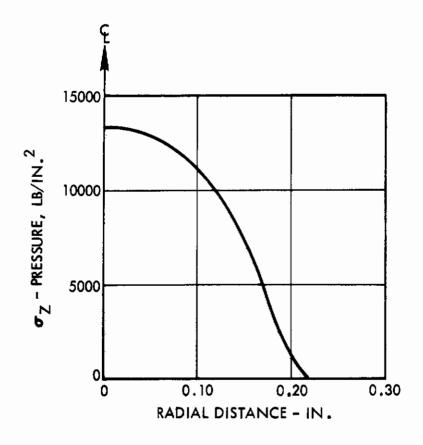


Figure 28. The Pressure Distribution Under the Nut of a Bolted Plate According to Equation 7-12

Figure 6-3 of Reference 19, labeled "Best line through most of the Aluminum (II) Data-Vacuum." The results of this calculation yield a conductance through the bolt of 21,000 Btu/hr ft F. This can be compared to the value of 10,000 Btu/hr ft F calculated in Reference 19 for a No. 10 bolt tightened to 22 in.-lb_torque. The area under the bolt in Reference 19 is given as 0.33 inches (a washer was used in Reference 19). The contact area under the bolt in the present study was 0.12 in.². Thus, the thermal resistance of the two bolts can be compared:

Present Study:

$$R = \frac{1}{hA} = .0575 \frac{o_{F hr}}{BTU}$$

Reference (3)

$$R = \frac{1}{hA} = .044 \frac{o_{F} hr}{BTU}$$

7.3 APPLICATION TO TEST CONFIGURATIONS

Three component test configurations were run with fewer than the normal 12 bolts to evaluate bolt spacing effectiveness. These tests were in addition to those reported in Section 3.1. These configurations are shown in Figure 29 (a, b, and c). The sample size was 6 inches by 6 inches, the upper plate thickness was 1/16 inch, and the mounting plate was 1/8 inch thick. The bolt torque was 24 in. 1b. for all cases.

Configuration 29-a was divided into four equal areas for purposes of analytical correlation. Each triangular section was assumed to be deformed into a semicircular shape of the same area and having a contact region at the center. The radius of the segment is then 2.38 in., and the bolt contact area, now semicircular, has an effective radius of 0.311 in. These dimensions were substituted in the equations described in Section 7.2.1. The resulting conductance of the upper plate was found to be: $h_1 = 18.3$ Btu/hr ft^{2 o}F.

The conductance of the lower plate will be computed using the same analytical procedure. Since the heat removal from the lower plate is not as uniform as heat supplied to the upper plate, the analytical model is now a poorer approximation of the real system. The results were used as an approximation since an analytical solution of the real heat flow in this plate would be a lengthy task. Applying this method to the lower plate, which has a thickness twice that of the upper plate, results in

h₂ = 36.6 Btu/hr ft^{2 o}F. These two plate thermal conductances must be combined with the bolt thermal conductance. The thermal circuit for this system is:

$$R_1 = \frac{1}{h_1 A_1}$$
 $R_2 = \frac{1}{h_2 A_2}$
 $R_3 = \frac{1}{h_B A_B}$

Figure 30. Thermal Circuit for Calculating Overall Thermal Conductance

The overall conductance is given by:

$$\frac{1}{hA} = \frac{1}{h_1A_1} + \frac{1}{h_BA_B} + \frac{1}{h_2A_2}$$

Substituting the values gives:

$$\frac{1}{hA} = \frac{1}{18.3} \frac{1}{(\frac{9}{144})} + \frac{1}{21,000} \frac{1}{(\frac{12}{144})} + \frac{1}{36.6} \frac{1}{(\frac{9}{144})}$$

$$\frac{1}{hA} = .874 + .057 + .437$$

or $h = \frac{1}{1.368(\frac{9}{1LL})} = 11.7 \text{ Btu/hr ft}^2 \text{ or}$

Applying this technique to Configuration 29-b, the corner bolts were close together and were lumped together to form a quarter circular area having an effective radius of 0.622 inches. The analytical method of Section 7.2.1 and thermal circuit substitutions yield an overall conductance of h=8.0 Btu/hr ft^{2 o}F.

Configuration 29-c was divided by allotting to each corner bolt a hemicircular area of 4 in. 2 and each center bolt a quarter circle of 5 in. 2. Using the same technique as above, the thermal circuit gave:

The twelve-bolt configuration was analysed in the same manner by dividing this area into eight equal area segments as shown in Figure 29-d. The result was:

$$h = 26.7 \text{ Btu/hr ft}^2 \circ_{F.}$$

The 6 inch by 12 inch component configuration can be approached using the same technique by dividing the area into eight hemicircular sectors and four quarter circular sectors each with an effective area of 6 inch². Similarly the 12 by 12 configuration was divided into twelve hemicircles and four quarter circles of equal area, 9 inch². The results for these six configurations are shown in Table 8.

The 6 inch by 6 inch, 12 bolt and 12 inch by 12 inch, 24 bolt configurations can also be predicted using the method described in Section 7.2.2. An effective radius based on the plate area was used in Equation 7-11. The results are also given in Table 8. The results of these correlation attempts are compared to the measured values in Table 8. The agreement is adequate in all cases except 29-b where the predicted value is a little more than half of the measured conductance. In spite of this, the success of the technique is quite satisfactory. Further exploitation should be made of the approach described here. The results have been restricted to a bolted thin plate without a filler material.



EXPERIMENTAL SYSTEMS AND ANALYTICAL APPROXIMATIONS

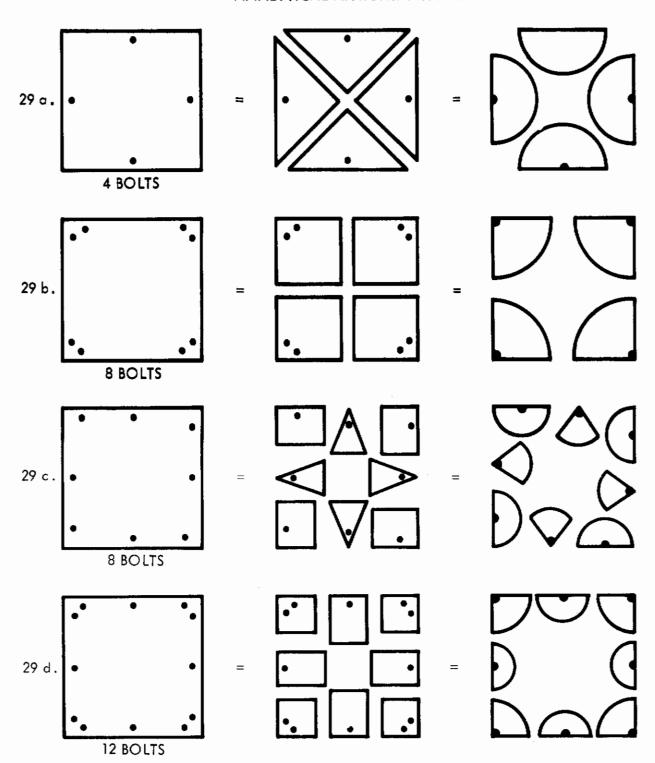


Figure 29. Method of Subdividing the Test Configurations to Predict Overall Thermal Conductance



TABLE 8
COMPARISON OF PREDICTED AND MEASURED COMPONENT JOINT CONDUCTANCES

Configuration	Experimental h, BTU/hr ft2 of	Method I (Sec. 7.2.1) h, BTU/hr ft ² F	Method II (Sec. 7.2.2) h, BTU/hr ft2 oF
29-a	13.4	11.7	
29-b	13.7	8.0	
29 - c	22.0	22.0	
29-d 6 x 6, 12 bolts	26.3	26.7	29
6 x 12, 18 bolts	18.5	18.1	
12 x 12, 24 bolts	8.3	10.5	7.8



An attempt should be made to extend this to thick plates with and without a filler and to thin plates with a filler.



8. CONCLUSIONS AND RECOMMENDATIONS

This report presents the results of the first phase of a program designed to improve the prediction of spacecraft thermal performance. The information necessary for the comparison of prediction and test of a spacecraft model has been gathered. The continuation of the program to this natural conclusion is the second phase of the study. There has been no decrease in the practical needs for this continuation and it is important to complete this program.

There have been several developments within this program which warrant further study. The first is the extension of the joint conductance testing to include a larger number of joint types. The techniques which have been developed in this program for experimentally measuring the conductance of practical joints have proven to be very simple and inexpensive. The accuracy which is obtained is adequate for such joints and is a satisfactory compromise with the cost of such experimentation. The joints for this additional work should not be chosen on the basis of a thermal test model but selected for the frequency with which they are used in actual practice, e.g., riveted joints, low conductance joints, etc.

The practical correlation of joint conductances should also be continued. The correlation for the thin plate unfilled component joints was obtained by assuming the primary resistance to heat flow was in the thin plates. This primary resistance was found to be adequately described by radial in the region surrounding each bolt fastener. The success with which the component joints were correlated by this procedure was very encouraging. The limitations of time and resources did not allow a similar attempt to be made to correlate filled joints or structural joints. However, such a correlation is believed to be feasible. This work could be included in the second phase of the program; correlation of other test joints would be performed as part of the experimental work described above or as a separate study. Regardless of the mechanism chosen for performing this correlation, this work should be continued and extended.

The application of the directional specular-diffuse method of analysis has indicated a major gap in our knowledge of thermal radiation properties. A critical part of this method is the separation of the thermal radiation properties into the diffuse and specular components. Additional experimental and analytical work is required to develop a basis for this separation from measurements of the directional and specular reflectances. Such a study should include an examination of the geometrical reflectances (and emittances) relative to the distribution of reflected (and emitted) radiation.

Although the comparisons of predicted and experimental radiation exchange in the simple geometries were close, further refinement of the predictions are desired. This problem is related in part to the separation of the diffuse and specular components discussed above. The effect of non-gray radiation properties is probably of equal or greater importance. Further study is needed for the improvement of the predicted temperatures and heat fluxes, e.g., a prediction using the band energy method.



In conclusion, the objectives of the first phase of the program have been satisfied; i.e., the data and methods required to compare the predicted and test thermal performance of a model spacecraft have been developed. Other areas for further study have also been found:

(1) practical joint conductance measurements

(2) correlation of measured joint conductances

- (3) the separation of radiation properties into diffuse and specular components for the directional specular-diffuse analysis
- (4) the importance of the non-gray property assumption

The development of additional problems is to be expected in a study of this nature. The second phase of the program should be expected to raise its own share of new problems.



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APPENDICES

- I. Experimental Data—Component Joints
- II. Structural Joint Tests
- III. Script F Computer Program Print Out
- IV. Experimental Data—Radiation Exchange Experiment V. Bibliography for Joint Thermal Conductance
- VI. Component Joint Test Data used for Correlation Task



APPENDIX I EXPERIMENTAL DATA—COMPONENT JOINTS

The experimental data for the 6 x 6 component joint is listed in Table 9 of this appendix. The thermocouple locations are shown on the full size drawing of Figure 31. In addition to these thermocouples, thermocouples were placed in the cooling water inlet and outlet lines. These are absolute thermocouples No. 3 and 4 respectively. The approximate cooling water flow rate was also recorded, but varied as the water pressure fluctuated. The heater voltage and current are also recorded.

Figure 31 also illustrates the zones which were used in computing the area weighted temperature difference. A sample calculation for run No. 1 is as follows:

$$\overline{\Delta T}_{\bigcirc} = \frac{1.02 + 1.04 + 0.80 + 0.77}{4} = 0.91^{\circ} F$$

$$\overline{\Delta T}_{\bigcirc} = 1.98^{\circ} F$$

$$\overline{\Delta T}_{\bigcirc} = \frac{2.50 + 4.11 + 2.57}{3} = 3.06^{\circ} F$$

$$\overline{\Delta T}_{\bigcirc} = \frac{6.29 + 6.53}{2} = 6.41^{\circ} F$$

These average ΔT 's are for each zone, obtained by averaging the differential thermocouple readings in each zone. The overall ΔT is now computed by area weighting these values.

$$\Delta T_{M} = \Delta T_{\bigcirc} \frac{A_{\bigcirc}}{A_{T}} + \Delta T_{\bigcirc} \frac{A_{\bigcirc}}{A_{T}} + \Delta T_{\bigcirc} \frac{A_{\bigcirc}}{A_{T}} + \Delta T_{\bigcirc} \frac{A_{\bigcirc}}{A_{T}}$$

$$\Delta T_{M} = \frac{9.05}{36} (0.91) + \frac{7.50}{36} (1.98) + \frac{13.2}{36} (3.06) + \frac{6.25}{36} (6.41)$$

$$\Delta T_{M} = 0.229 + 0.412 + 1.121 + 1.11$$

$$\Delta T_{M} = 2.872^{\circ} F$$

$$Q_{IN} = 3.702 (0.1314) = 4.864 \text{ watts}$$

$$= 16.6 \text{ Btu/hr}$$

$$h = \frac{Q}{A\Delta T_M}$$

$$= \frac{16.6 \text{ Btu/hr}}{1/4 \text{ ft}^2 2.872^{\circ} \text{F}}$$

$$h = 23.1$$
 Btu/hr ft² oF

The experimental data for the 6 inch \times 12 inch and 12 inch \times 12 inch component joints are given in Tables 10 and 11, respectively, of this appendix. The thermocouple locations and temperature weighting zones are shown in Figures 32 and 33 for these two experimental configurations.

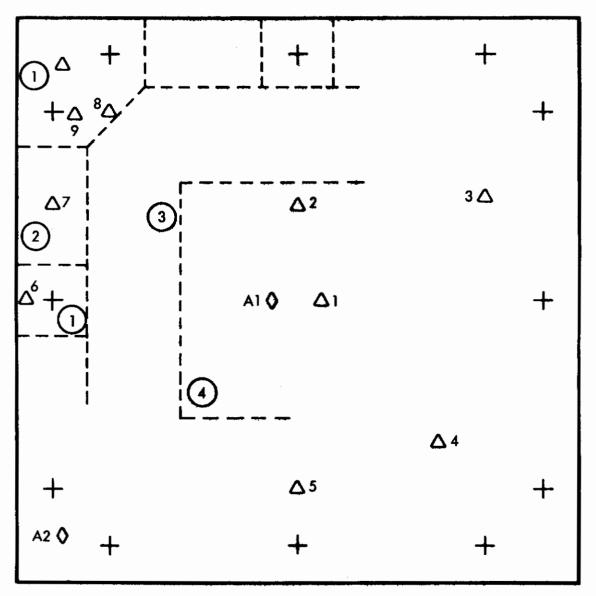
Differential thermocouples are located at the same (x, y) coordinates on the back of the mounting plate and the component plate at the locations shown on Figures 31, 32 and 33.

The conductance is calculated using the following equation:

$$h = \frac{Q}{A\Delta T}$$

The area used in this calculation is the contact area of the mating parts. For the structural joints, this was the overlap area between the angle bracket and the panel. The ΔT is an area weighted average which is determined by the method explained in above.

6" x 6" COMPONENT THERMOCOUPLE LOCATION

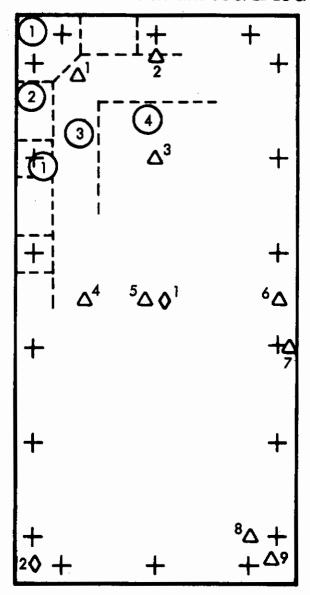


- (1) ZONE 1, AREA = 9.05 IN. 2
- (2) ZONE 2, AREA = 7.50 IN. 2
- (3) ZONE 3, AREA = $13.20 \, \text{IN.}^2$
- (4) ZONE 4, AREA = 6.25 IN. 2

- △ DIFFERENTIAL THERMOCOUPLES
- **♦** ABSOLUTE THERMOCOUPLES
- + BOLT LOCATION
- ZONE AREAS USED TO CALCULATE AVERAGE ΔT

Figure 31. 6" x 6" Component Joint Thermocouple Location

6" x 12" COMPONENT THERMOCOUPLE LOCATION

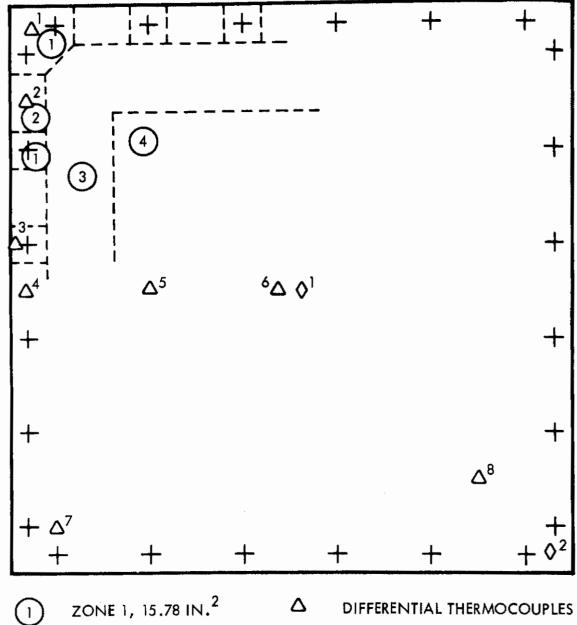


- (1) ZONE 1, 12.40 IN.²
 -) ZONE 2, 13.15 IN.²
- 3) ZONE 3, 25.20 IN.²
- (4) ZONE 4, 21.25 IN.²
- △ DIFFERENTIAL THERMOCOUPLES
- ♦ ABSOLUTE THERMOCOUPLES
- + BOLT LOCATION
- ZONE AREAS USED TO CALCULATE AVERAGE AT

Figure 32. 6" x 12" Component Joint Thermocouple Location



12" x 12" COMPONENT THERMOCOUPLE LOCATION



- 2) ZONE 2, 18.75 IN.²
- ♦ ABSOLUTE THERMOCOUPLES
- 3) ZONE 3, 53.22 IN.²
- + BOLT LOCATION
- (4) ZONE 4, 56.25 IN.²
- ZONE AREAS USED TO CALCULATE AVERAGE AT

Figure 33. 12" x 12" Component Joint Thermocouple Location



Table 9. Experimental Data - 6 by 6 Inch Component Joints						
Run No.	1	2	3	4	5	
Date	10/26/64	10/26/64	10/26/64	10/26/64	10/27/64	
Pressure, Torr	6×10^{-7}	6 x 10 ⁻⁷	6×10^{-7}	6×10^{-7}	5 x 10 ⁻⁷	
Absolute T.C.						
1 - °F	85.7	95.3	107.1	119.0	85.3	
2 - °F	80.2	85.6	91.6	97.8	79.8	
3 - ^o F	74.0	7 4. 5	74.5	74.3	73.8	
4 - ^o F	74.1	74.8	75.0	75.0	74.0	
Differential T.C.						
1 - ⁰ F	6.5 3	11.78	18.28	24.72	6.72	
2 - ^o F	6.29	11.38	17.60	23.78	6. 4 8	
3 - °F	2.50	4.56	7, 25	9.85	2,52	
4 - ^o F	4.11	7.06	10.95	14.90	4.05	
5 - °F	2.57	4.64	7.25	9.81	2.63	
6 - °F	1.02	1.81	2.81	3.81	1.02	
7 - °F	1.98	3.52	5 .4 6	7.40	2.00	
8 - ^o F	1.04	1.88	2.92	3.96	1.07	
9 - °F	0.80	1.41	2.19	2.97	0.81	
10 - °F	0.77	1.31	2.04	2.77	0.74	
Voltage, volts	37.02	49.31	61.54	72.04	36.99	
Current, amps	0.1314	0.1750	0.2185	0.2560	0.1313	
Water Flow, ml/min	72 5	650	650	650	575	
Bolt Torque, in-lb	24	24	24	24	24	
Filler	None	None	None	None	None	
Sample Number	1	1	1	1	1	
Number of Bolts	12	12	12	12	12	
h, Btu/hr ft ^{2 o} F	23.1	22.9	23.0	22.3	22.8	



Table 9. Experimental Data - 6 by 6 Inch Component Joints (Continued)

Run Number	6	7	8	9	10
Date	10/27/64	10/27/64	10/27/64	10/28/64	10/28/64
Pressure, Torr	5 x 10 ⁻⁷	5 x 10 ⁻⁷	5 x 10 ⁻⁷	6×10^{-7}	7×10^{-7}
Absolute T. C.					
1 - °F	95.1	107.5	118.5	105.5	117.5
2 - ^o F	85.2	92.3	97.3	89.9	102.3
3 - ⁰ F	74.1	74.3	73.3	73.2	74.7
4 - ^o F	74.5	75.0	74.1	73.6	89.1
Differential T.C.					
1 - ^o F	11.78	18.30	24.72	18.27	18.68
2 - °F	11.31	17.65	23.89	17.68	17.82
3 - ^o F	4.48	7.25	9.85	7.22	7.95
4 - °F	7.03	10.95	14.88	10.90	11.32
5 - ^o F	4.60	7.50	9. 79	7.19	7.44
6 - °F	1.78	2.77	3.77	2.78	2.53
7 - ^o F	3.50	5.45	7.37	5.50	5 .04
8 - ^o F	1.86	2.92	3.96	2.94	2.87
9 - ⁰ F	1.40	2.16	2.94	2.19	2.00
10 - ^o F	1.30	2.00	2.71	2.02	1.82
Voltage, volts	49.33	61.54	72.02	61.53	61.52
Current, amps	0.1751	0.2185	0.2559	0.2185	0.2185
Water Flow, ml/min	525	525	525	1175	21
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	None
Sample Number	1	1	1	1	-1
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	23.2	22.9	23, 1	2.3.0	22.8



Table 9. Experim	nental Data-	-6 by 6 Incl	h Component	Joints (Con	tinued)
Run Number	11	12	13	14	15
Date	10/29/64	10/29/64	10/29/64	10/29/64	10/30/64
Pressure, Torr	7×10^{-7}	7×10^{-7}	7×10^{-7}	7 x 10 ⁻⁷	5 x 10 ⁻⁷
Absolute T. C.					
1 - °F	85.0	94.2	105.7	117.8	84.8
2 - ^o F	79.8	84.9	91.9	97.5	79.5
3 - ^o f	73.8	73.9	73.7	73.6	73.6
4 - ⁰ F	74.0	74.3	74.3	74.4	73.6
Differential T.C.					
1 - ^o F	6.22	10.90	17.20	23.37	6.27
2 - ⁰ F	5.88	10.29	16.30	22.10	5.93
3 - ⁰ F	2.23	4.02	6.62	9.10	2.90
4 - °F	3.88	6.74	10.52	14.31	3.90
5 - °F	2.45	4.30	6.80	9.30	2.55
6 - °F	0.62	1.10	1.73	2.32	0.68
7 - °F	1.83	3.21	5.04	6.81	1.84
8 - ^o F	0.91	1.61	2.57	3.50	0.95
9 - °F	0.66	1.19	1.87	2.53	0.70
10 - °F	0.74	1.31	2.04	2.73	0.79
Voltage, volts	37.00	49.32	61.54	72.02	37.0
Current, amps	0.1313	0.1751	0.2185	0.2559	0.1313
Water Flow, ml/min	525	550	550	55 0	500
Bolt Torque, in-lb	30	30	30	30	18
Filler	None	None	None	None	None
Sample Number	1	1	1	1	1
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	25.0	25.2	24.8	25.0	23.9



Table 9. Experimental Data - 6 by 6 Inch Component Joints (Continued)

Run Number	16	17	18	1-9	20
Date	10/30/64	11/2/64	11/2/64	11/2/64	11/2/64
Pressure, Torr	5 x 10 ⁻⁷	6 x 10 ⁻⁷	6×10^{-7}	6 x 10 ⁻⁷	6 x 10 ⁻⁷
Absolute T.C.					
1 - ⁰ F	94.1	81.5	88.4	96.1	104.5
2 - °F	84.8	78.9	84.0	88.9	94.7
3 - ^o f	73.7	73.2	73.6	73.4	0.891
4 - °F	74.1	73.4	73.9	73.9	
Differential T.C.					
l - ^o F	10.99	2.20	3.76	5.76	7.83
2 - °F	10.34	2.25	3.87	5.94	8.05
3 - ^o F	4.10	0.50	0.83	1.27	1.73
4 - ^o F	6.76	1.49	2.50	3.90	5.27
5 - ^o f	4.46	0.43	0.72	1.11	1.52
6 - ⁰ F	1.19	0.27	0.47	0.71	0.98
7 - ^o f	3.21	0.52	0.83	1.26	1.71
8 - ^o F	1.67	0.15	0.25	0.38	0.53
9 - ⁰ F	1.24	0.28	0,44	0.67	0.91
10 - ⁰ F	1.38	0.45	0.73	1.11	1.49
Voltage, volts	49.30	37.00	49.34	61.50	72.04
Current, amps	0.1750	0.1313	0.1751	0.2183	0.2558
Water Flow, ml/min	525	600	600	600	600
Bolt Torque, in-1b	18	24	24	24	24
Filler	None	RTV 11	RTV 11	RTV 11	RTV 11
Sample Number	1	1	1	1	1
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	24.8	76.9	81.5	82.5	83.2



Table 9. Experimental Data — 6 by 6 Inch Component Joints (Continued)

Run Number	21	22	23	24	25
Date	11/6/64	11/6/64	11/9/64	11/9/64	11/9/64
Pressure, Torr.	8 x 10 ⁻⁷	8 x 10 ⁻⁷	9×10^{-7}	9×10^{-7}	9×10^{-7}
Absolute T. C.					
1 - ⁰ F	81.4	91.0	83.7	86.8	95.5
2 - ^o F	76.0	80.2	74.2	77.5	80.9
3 - °F	73.3	73.8	70.9	71.7	72.1
4 - ^o F	73.4	74.1	71.1	72.1	72.5
Differential T.C.					
1 - °F	5.76	11.60	5.69	9.82	15.25
2 - ^o F	5.11	10.29	5.06	8.71	13.56
3 - ^o F	2.88	5.85	2.87	4.92	7.65
4 - ⁰ F	2.29	4.62	2.23	3.82	5.96
5 - ⁰ F	0.65	1.32	0.45	0.76	1.18
6 - ⁰ F	1.36	2.76	1.26	2.17	3.38
7 - °F	0.95	1.97	0.91	1.55	2.44
8 - ^o f	0.48	1.02	0.44	0.74	1.17
9 - ^o f					
10 - °F					
Voltage, volts	37.03	53.01	37.01	49.33	61.53
Current, amps	0.1315	0.1883	0.1314	0.1752	0.2186
Water Flow, ml/min	1300	675	575	575	575
Bolt Torque, in-lb	12	12	24	24	24
Filler	None	None	None	None	None
Sample Number	2	2	2	2	2
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ² °F	24.7	28.5	29.1	30.1	30.1



Table 9. Experimental Data — 6 by 6 Inch Component Joints (Continued)

Run Number	26	27	28	29	30
Date	11/9/64	11/10/64	11/13/64	11/17/64	11/17/64
Pressure, Torr.	9×10^{-7}	1 x 10 ⁻⁶			
Absolute T.C.					
l - ^o F	104.7	88.2	81.2	71.6	75.7
2 - °F	84.5	77.4	75.4	69.0	70.9
3 - ^o F	72.1	70.8	69.9	66.0	70.9
4 - ^O F	73.0	71.3	70.4	66.4	66.5
Differential T.C.					
l - ^o F	20.93	11.30	3.78	1.80	3.08
2 - °F	18.57	10.09	3.38	1.61	2.76
3 - ^o F	10.51	5.74	1.38	0.63	1.11
4 ~ °F	8.19	4.50	0.72	0.31	0.58
5 - ^o F	1.63	0.84	0.29	0.21	0.36
6 - ^o f	4.62	2.54	0.20	0.091	0.20
7 - °F	3,34	1.78	0.26	0.095	0.20
8 - ⁰ F	1.63	0.89	0.26	0.091	0.27
9 - °F					
10 - °F					
Voltage, volts	72.03	53.01	53.03	37.02	49.31
Current, amps	0.2560	0.1883	0.1883	0.1314	0.1751
Water Flow, ml/min	5 7 5	575	575	6 2 5	600
Bolt Torque, in-lb	24	30	12	24	24
Filler	None	None	RTV 11	RTV 11	RTV 11
Sample Number	2	2	2	2	2
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	30.1	30.0	123.0	128.1	127.0



Table 9. Experimental Data—6 by 6 Inch Component Joints (Continued)

Run Number	31	32	33	34	35
Date	11/17/64	11/17/64	11/19/64	11/20/64	11/23/64
Pressure, Torr	1 x 10 ⁻⁶	1 x 10 ⁻⁶	7×10^{-7}	1×10^{-6}	1 x 10 ⁻⁶
Absolute T.C.					
1 - ⁰ F	81.7	87.0	78.8	80.6	72.1
2 - ^o F	74.2	76.5	73.4	72. 5	68.2
3 - ^o F	66.2	66.1	67.7	66.7	65.2
4 - ⁰ F	67.0	67.0	68.2	67.1	65.4
Differential T.C.					
1 - ° F	4.72	6.39	3.39	7.25	3.62
2 - ^o F	4.25	5.77	3.04	6.20	1.29
3 - ⁰ F	1,73	2,35	1.12	3, 12	1.57
4 - ⁰ F	0.89	1.24	0.54	2.22	1.07
5 - ^o F	0.51	0.67	0.31	0.37	0.19
6 - °F	0.30	0.41	0.17	0.93	0.45
7 - °F	0.29	0.37	0.17	0.53	0.23
8 - °F	0,44	0.65	0.30	0.42	0.15
9 - °F					
10 - ^O F					
Voltage, volts	61.51	72.05	53.01	52.99	37.00
Current Amps	0.2185	0,2560	0.1883	0.1879	0.1312
Water Flow, ml/min	600	600	600	600	460
Bolt Torque, in-lb	24	24	30	12	24
Filler	RTV 11	RTV 11	RTV 11	G 683	G 683
Sample Number	2	2	2	2	2
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	129.0	130.0	142.0	55.5	63.0



Table 9. Experimental Data - 6 by 6 Inch Component Joints (Continued)

Run Number	36	37	38	39	40
Date	11/23/64	11/23/64	11/23/64	11/23/64	11/24/64
Pressure, Torr	1 x 10 ⁻⁶	1×10^{-6}	1×10^{-6}	1 x 10 ⁻⁶	5 x 10 ⁻⁷
Absolute T.C.					
l - ^o F	78.3	85.7	92.4	79.9	88.1
2 - ^o F	71.4	74.7	77.4	71.7	73.9
3 - °F	66.0	66.7	66.5	65.9	66.7
4 - °F	66.5	67.4	67.5	66.4	67.1
Differential T.C.					
l - °F	6.20	9.46	12.83	7.15	13.58
2 - °F	2.07	3.11	4.15	6.15	13.37
3 - °F	2.72	4.17	5.63	2.99	6.59
4 - ⁰ F	1.86	2.88	3.89	2.37	4.72
5 - ^o F	0.33	0.52	0.67	0.33	1.07
6 - ^o f	0.77	1.17	1,56	0.72	3.35
7 - ^o F	0.42	0.66	0.87	0.44	2.22
8 - ^o F	0.34	0.56	0.77	0.34	1.18
9 - °F					
10 - ^O F					
Voltage, volts	49.31	61.53	72.04	52.96	52.96
Current, amps	0.1749	0.2183	0.2556	0.1878	0.1880
Water Flow, ml/min	460	460	460	475	560
Bolt Torque, in-lb	24	24	24	30	12
Filler	G 683	G 683	G 683	G 683	None
Sample Number	2	2	2	2	3
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	65.0	66.1	67.1	57.0	24.8



Table 9. Experimental Data — 6 by 6 Inch Component Joints (Continued)

Run Number	41	42	43	44	4 5
Date	11/24/64	11/25/64	11/25/64	11/25/64	11/25/64
Pressure, Torr	5 x 10 ⁻⁷	5 x 10 ⁻⁶	5 x 10 ⁻⁶	5 x 10 ⁻⁷	5 x 10 ⁻⁷
Absolute T.C.					
1 - °F	92.6	88.4	92.7	77.5	85.0
2 - °F	81.8	74.9	75.0	70.7	72.9
3 - ^o F	66.6	65.9	66.4	66.8	66.2
4 - ⁰ F	67.0	66.4	66.9	67.0	66.7
Differential T.C.					
1 - °F	17.64	14.32	18.42	6.70	11.50
2 - ^o F	17.70	13.93	18.45	6.65	11.44
3 - °F	11.94	7.36	10.19	3.17	5 .4 5
4 - °F	7.46	4.97	10.59	2.26	3.92
5 - ^o F	1.80	1.11	9.44	4.78	0.80
6 - ^o F	7.80	4.26	7.95	1.57	2.67
7 - ⁰ F	10.18	3.26	3.64	0.93	1.65
8 - ^o F	10.40	2.53	1.61	0.49	0.92
9 - ⁰ F					
10 - ^o F					
Voltage, volts	52.96	52.95	52.95	37.01	49.32
Current, amps	0.1880	0.1880	0.1880	0.1313	0.1751
Water Flow, ml/min	700	575	550	625	625
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	None
Sample Number	3	3	3	3	3
Number of Bolts	4*	8*	8*	12	12
h, Btu/hr ft ^{2 o} F	13.4	22.0	13.7	22.1	25.9

^{*}See Appendix VI.



Table 9. Experimental Data — 6 by 6 Inch Component Joints (Continued)

Run Number	46	47	48	49	50
Date	11/27/64	11/27/64	11/30/64	12/3/64	12/3/64
Pressure, Torr	5 x 10 ⁻⁷	5 x 10 ⁻⁷	6 x 10 ⁻⁷	4×10^{-7}	4×10^{-7}
Absolute T.C.					
1 - °F	94.6	105.5	81.8	73.0	79.1
2 - ^o F	75.7	79.6	72.7	68.8	71.5
3 - ^o F	65.4	65.5	66.0	65.3	65.8
4 - ⁰ F	66.0	66.4	66.5	65.6	66.3
Differential T.C.					
1 - ⁰ F	17.67	23.95	5.63	2.63	4.54
2 - ⁰ F	17.59	23.80	6.21	3.00	5.14
3 - ^o F	8.36	11.31	1.81	0.76	1.32
4 - ⁰ F	6.02	8.20	0.75	0.27	0.45
5 - ⁰ F	1.26	1.69	0.24	0.14	0.21
6 - ⁰ F	4.14	5.60	0.24	0.13	0.20
7 - ⁰ F	2.59	3.54	0.24	0.12	0.23
8 - ⁰ F	1.49	2.02	0.37	0.05	0.23
9 - ^o f					
10 - °F					
Voltage, volts	61.52	72.06	53.01	37.00	49.34
Current, amps	0.2184	0.2560	0.1881	0.1313	0.1751
Water Flow, ml/min	600	600	600	550	550
Bolt Torque, in-lb	24	24	12	24	24
Filler	None	None	RTV 11	RTV 11	RTV 11
Sample Number	3	3	3	3	3
Number of Bolts	12	12	12	12	12
h, Btu/hr ft ^{2 o} F	26.2	26.6	84.1	91.0	93.5



Table 9. Experimental Data—6 by 6 Inch Component Joints (Continued)

Run Number	51	52	53	54
Date	12/3/64	12/3/64	12/4/64	12/4/64
Pressure, Torr	4×10^{-7}	4×10^{-7}	5 x 10 ⁻⁷	2 x 10 ⁻⁶
Absolute T.C.				
1 - °F	86.8	94.9	83.5	75.6
2 - ^o F	74.8	78. 5	72.2	70.0
3 - ^o F	66.2	66.2	65.6	66.7
4 - ^o F	66.9	67.1	66.0	67.0
Differential T.C.				
1 - °F	6.95	9.44	8.95	4.52
2 - ^o F	7.86	10.62	9.19	4.48
3 - ^o F	2.03	2.77	3.22	1.59
4 - ^o F	0.70	0.96	2.25	1.09
5 - ^o F	0.30	0.40	0.26	0.12
6 - ^o F	0.29	0.40	0.92	0.42
7 - °F	0.37	0.52	0.70	0.28
8 - °F	0.44	0.67	0.42	0.11
9 - ^o f				
10 - ^o F				
Voltage, volts	61.54	72.05	53.01	37.05
Current, amps	0.2184	0.2558	0.1878	0.1312
Water Flow, ml/min	550	550	650	600
Bolt Torque, in-lb	24	24	12	24
Filler	RTV 11	RTV 11	G 683	G 683
Sample Number	3	3	3	3
Number of Bolts	12	12	12	12
h, Btu/hr ft ^{2 o} F	94.8	95.4	47.0	47.3



Table 9. Experimental Data — 6 by 6 Inch Component Joints (Continued)

		- 1		
Run Number	55	56	57	58
Date	12/4/64	12/7/64	12/7/64	12/8/64
Pressure, Torr	5 x 10 ⁻⁸	1 x 10 ⁻⁶	1 x 10 ⁻⁶	5 x 10 ⁻⁷
Absolute T.C.				
1 - ^o F	81.9	88.0	97.1	71.0
2 - ^o F	72.9	72.9	76 .4	66. 3
3 - ^O F	63.5	6 3. 5	63.8	63.1
4 - ⁰ F	64.3	63.4	64.7	63. 5
Differential T.C.				
1 - ⁰ F	7.70	11.80	15.93	3.12
2 - ^o F	7.74	11.88	16.05	3.25
3 - ^o F	2.76	4.25	5.74	0.85
4 - °F	1.91	2.98	4.02	0.48
5 - ^o F	0.22	0.36	0.48	0.15
6 - °F	0.74	1.09	1.48	0.18
7 - ^o f	0.54	0.81	1.10	0.73
8 - ^o F	0.33	0.51	0.76	0.
9 - °F				
10 - ^o F				
Voltage, volts	49.36	61.52	72.04	37.02
Current, amps	0.1748	0.2180	0.2554	0.1311
Water Flow, ml/min	600	500	500	525
Bolt Torque, in-lb	24	24	24	24
Filler	G 683	G 683	G 683	G 641
Sample Number	3	3	3	3
Number of Bolts	12	12	12	12
h, Btu/hr ft ^{2 o} F	48.2	48.8	49.5	77.5



Table 9. Experimental Data - 6 by 6 Inch Component Joints (Continued)

•			•	
Run Number	59	60	61	
Date	12/8/64	12/8/64	12/8/64	
Pressure, Torr	5 x 10 ⁻⁷	5 x 10 ⁻⁷	5 × 10 ⁻⁷	
Absolute T.C.				
1 - ⁰ F	77.8	85.8	93.8	
2 - ^o f	69.7	73,2	76.8	
3 - ^o F	63,9	64.5	64.8	
4 - ⁰ F	64.4	65.2	65.8	
Differential T.C.				
1 - ⁰ F	5.36	8.20	11.10	
2 - ⁰ F	5.58	8.56	11.56	
3 - ⁰ F	1,47	2.27	3.07	
4 - °F	0.85	1,34	1.81	
5 - ^o F	0.22	0.32	0.40	
6 - ^o F	0.33	0.51	0.70	
7 - °F	0,20	0.37	0.54	
8 - °F	0.19	0.45	0.69	
9 - ^o f				
10 - °F				
Voltage, volts	49.35	61.52	72.02	
Current, amps	0.1748	0,2180	0.2553	
Water Flow, ml/min	525	525	525	
Bolt Torque, in-lb	24	24	24	
Filler	G 641	G 641	G641	
Sample Number	3	3	3	
Number of Bolts	12	12	12	
h, Btu/hr ft ^{2 o} F	79.0	79.0	79.5	



Table 10. Experimental Data — 6 by 12 Inch Component Joints

Run Number	62	63	64	65	66
Date	12/9/64	12/9/64	12/9/64	12/10/64	12/10/64
Pressure, Torr	3×10^{-7}	3 x 10 ⁻⁷	3 x 10 ⁻⁷	5 x 10 ⁻⁷	5 x 10 ⁻⁷
Absolute T.C.					
1 - °F	74. 4	84. 9	106. 0	74.9	70.0
2 - ^o F	67.7	71.6	79. 0	68.1	66.7
3 - ^o F	63.8	63.9	63.5	64.0	64.5
4 - ^o F	64.3	64.8	65.2	64.6	64.9
Differential T.C.					
i - ^o F	2, 43	5. 93	8.94	3. 02	1, 35
2 - ^o F	1.94	3.87	7. 90	1.96	0. 98
3 - ^o F	5,83	11.57	23.50	5.87	2.94
4 - °F	5, 22	10.40	22.02	5.17	2.59
5 - ^o F	3.15	11.71	29.30	7. 22	3.64
6 - °F	2. 49	4.95	10.20	2. 47	1.24
7 - °F	0.73	1.43	2.85	0.75	0.39
8 - °F	1.33	2. 61	5.37	1.31	0.66
9 - ^o F	0.50	1.00	2. 09	0.51	0.25
Voltage, volts	35.48	50.00	70. 70	35. 47	25.00
Currents, amps	0.2837	0.4000	0.5667	0. 2840	0.2001
Water Flow, ml/min	575	600	600	550	550
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	None
Sample Number	1	1	i	1	1
Number of Bolts	18	18	18	18	18
h, Btu/hr ft ^{2 o} F	22.7	19.5	18.5	18.5	18.5



Table 10. Experimental Data - 6 by 12 Inch Component Joints

Run Number	67	68	69	70	71
Date	12/10/64	12/14/64	12/14/64	12/14/64	12/17/64
Pressure, Torr.	5 x 10 ⁻⁷	4×10^{-7}	4×10^{-7}	4×10^{-7}	6 x 10 ⁻⁷
Absolute T. C.					
1 - °F	86.5	70,4	76.0	88.3	68.6
2 - ⁰ F	73.3	67.9	70.8	77.6	65.2
3 - ^o f	65.2	64.6	65.0	66.5	62.0
4 - ^o f	66.2	65.1	65.9	67.7	62.6
Differential T.C.					
1 - °F	4.72	0.32	0.66	1.68	0.64
2 - ^o f	3.86	0.22	0.44	0.95	0.28
3 - ⁰ F	11.60	1.25	2,52	5.26	1.27
4 - °F	10.37	1.06	2.09	4,24	1.05
5 - ° F	14.36	1.55	3.06	6.15	1.42
6 - °F	4, 95	0.22	0.48	1.02	0.15
7 - °F	1.46	0.19	0.37	0.80	0.08
8 - °F	2.60	0.18	0.41	0.91	0.04
9 - ^o f	1.02	0.12	0.29	0.61	
Voltage, volts	50.00	35.47	50.00	70.73	35.49
Current, amps	0.4005	0.2839	0.4004	0.5669	0.2822
Water Flow, ml/min	550	625	625	625	575
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	RTV 11	RTV 11	RTV 11	RTV 11
Sample Number	1	1	1	1	2
Number of Bolts	18	18	18	18	18
h, Btr/hr ft ^{2 o} F	18.9	103.0	101.5	98.0	103.0



Table 10. Experimental Data - 6 by 12 Inch Component Joints (Continued)

Run Number	72	73	74	75	76
Date	12/17/64	12/17/64	12/21/64	12/21/64	12/21/64
Pressure, Torr.	6 x 10 ⁻⁷	6×10^{-7}	6 x 10 ⁻⁷	6 x 10 ⁻⁷	6 x 10 ⁻⁷
Absolute T.C.					
1 - ⁰ F	75.5	88.5	67.5	73.5	86.2
2 - ⁰ F	68.8	75.0	64.2	67.0	73.4
3 - ^o F	62.6	62.8	61.1	61.1	61.6
4 - ^o F	63.6	64.8	61.6	61.9	63.3
Differential T.C.					
l - °F	1.37	2.85	0.71	1.41	2.88
2 - °F	0.59	1.21	0.27	0.52	1.05
3 - °F	2.52	5.50	1.26	2.48	5.02
4 - ^o F	2.13	4.30	1.21	2.37	4.74
5 - °F	2.86	5.76	1.79	3.51	7.05
6 - ^o f	0.33	0.71	0.17	0.30	0.57
7 - ⁰ F	0.12	0.23	0.11	0.20	0.36
8 - ^o F	0.11	0.26	0.16	0.30	0.61
9 - °F		0	0.08	0.17	0.38
Voltage, volts	50.02	70.64	35.48	50.01	70.71
Current, amps	0.3980	0.5628	0.2834	0.3995	0.5651
Water Flow, ml/min	575	5 7 5	650	650	650
Bolt Torque, in-lb	24	24	24	24	24
Filler	RTV 11	RTV 11	RTV 11	RTV 11	RTV 11
Sample Number	2	2	3	3	3
Number of Bolts	18	18	18	18	18
h, Btu/hr ft ^{2 o} F	101.0	97.0	90.0	92.0	92.0



Table 11. Experimental Data - 12 by 12 Inch Component Joint

Run	77	78	79	80
Date	12/22/64	12/22/64	12/22/64	12/28/64
Pressure, Torr	4×10^{-7}	4×10^{-7}	4×10^{-7}	6×10^{-7}
Absolute T.C.				
i - °F	80.5	100.2	138.6	69. 9
2 - ^o f	66. 3	71.6	82.3	65.6
3 - ^o F	61.1	60.9	61.4	61.8
4 - °F	62. 0	62.8	65, 2	62.8
Differential T.C.				
1 - °F	0,58	0.92	1.64	0.51
2 - °F	1.89	3, 85	7. 73	0. 28
3 - °F	1.35	2. 75	5.19	0.18
4 - ^o F	3. 29	6. 75	13.40	0.10
5 - ^o F	12.10	24, 50	48.60	1.49
6 - °F	16. 42	33. 20	65.80	3.14
7 - °F	1.30	2.69	5.36	0.12
8 - °F	5.78	11.59	22. 90	0.70
Voltage, volts	29.60	41.90	59. 20	29.61
Current, amps	0.6753	0.9543	1.3437	0.6748
Water Flow, ml/min	550	550	550	600
Bolt Torque, in-lb	24	24	24	24
Filler	None	None	None	RTV 11
Sample Number	1	i	1	1
Number of Bolts	24	24	24	24
h, Btu/hr ft ^{2 o} F	8. 36	8.32	8.34	56.6



Table 11. Experimental Data - 12 by 12 Inch Component Joint (Continued)

Run	81	82	83	84
Date	12/28/64			
Date			• •	1/5/65
Pressure, Torr	6×10^{-7}	6×10^{-7}	8×10^{-8}	8×10^{-7}
Absolute T.C.				
1 - °F	77. 7	93.3	68; 7	77.3
2 - °F	69. 0	76.0	64 . 5	69.5
3 - ^O F	61.5	61.7	60.5	61.4
4 - °F	63.4	65, 3	61.7	63.5
Differential T.C.				
1 - °F	0.72	0. 98	0.31	0.53
2 - °F	0,53	1.04	0.20	0.37
3 - ^o F	0,37	0.68	0, 20	0.35
4 - ^o F	0.22	0.48	0.12	0.20
5 - ^O F	2.95	5.91	1.74	3, 39
6 - ^o f	6.25	12.41	2. 76	5.42
7 - ^o F	0.27	0.55	0.14	0.25
8 - °F	1.48	2.94	1.06	2.10
Voltage, volts	41.83	59. 22	29, 59	41.84
Current, amps	0.9527	1.3460	0,6747	0.9521
Water Flow, ml/min	600	600	550	550
Bolt Torque, in-1b	24	24	24	24
Filler	RTV 11	RTV 11	RTV 11	RTV 11
Sample Number	1	1	2	2
Number of Bolts	24	24	24	24
h, Btu/hr ft ^{2 o} F	55.8	56.1	51.7	52, 8



Table 11. Experimental Data - 12 by 12 Inch Component Joint (Continued)					
Run	85	86	87	88	
Date	1/5/65	1/7/65	1/7/65	1/8/65	
Pressure, Torr	8 x 10 ⁻⁷	8 x 10 ⁻⁷	8 x 10 ⁻⁷	5 x 10 ⁻⁷	
Absolute T.C.					
1 - ⁰ F	95.6	69.0	76. 9	92.7	
2 - ⁰ F	79. 2	64.8	68.3	75.7	
.3 - ^o F	63. 4	60.6	60.4	59.1	
4 - ⁰ F	67.1	61.6	62. 3	63.3	
Differential T.C.					
1 - ⁰ F	1.06	0. 42	0.57	0.87	
2 - °F	0. 77	0.17	0.32	0.66	
3 - ⁰ F	0.65	0. 13	0.28	0.60	
4 - ⁰ F	0.37	-	-	-	
5 - ^o F	6.80	1.89	3.76	7.54	
6 - °F	10.80	2. 91	5. 72	11.40	
7 - °F	0.63	0.14	0.30	0.64	
8 - ⁰ F	4.64	0.93	1.85	3,58	
Voltage, volts	59. 26	29.65	41.85	59.25	
Current, amps	1.3436	0.6750	0.9518	1.3440	
Water Flow, ml/min	550	550	550	500	
Bolt Torque, in-lb	24	24	24	24	
Filler	RTV 11	RTV 11	RTV 11	RTV 11	
Sample Number	2	3	3	3	
Number of Bolts	24	24	24	24	
h, Btu/hr ft ^{2 o} F	51,0	51, 4	51.9	52, 4	



APPENDIX II STRUCTURAL JOINT TESTS

The experimental data for structural joint configuration No. 1 (Figure 3 of main report) is given in Table 12 of this appendix. The location of thermocouples is shown in Figures 34 and 35. The average ΔT for each joint, called "a" and "b," was obtained by dividing the joint area into zones. Two zones were used, a one inch square zone at each bolt, with the bolt in the center, and the remaining area as the other zone. The water flow rate and temperatures were monitored as in the component joints, and absolute thermocouples 2 and 3 measure inlet and outlet temperatures respectively. For run number 1, the conductance calculation for joint "a" is as follows:

$$\overline{\Delta T}_{\underbrace{1}} = 3.56^{\circ} F$$

$$\overline{\Delta T}_{\underbrace{2}} = \frac{6.10 + 8.17}{2} = 7.13^{\circ} F$$

$$\overline{\Delta T}_{M} = \frac{A_{1}}{A_{T}} \overline{\Delta T}_{1} + \frac{A_{2}}{A_{T}} \overline{\Delta T}_{2}$$

$$\overline{\Delta T}_{M} = \frac{2}{6} (3.56) + \frac{4}{6} (7.13)$$

$$\overline{\Delta T}_{M} = 5.95^{\circ} F$$

$$Q_{IN} = 22.05(0.2310) = 5.099 \text{ watts}$$

$$= 17.4 \text{ Btu/hr}$$

$$h_{a} = \frac{Q}{A\overline{\Delta T}_{M}}$$

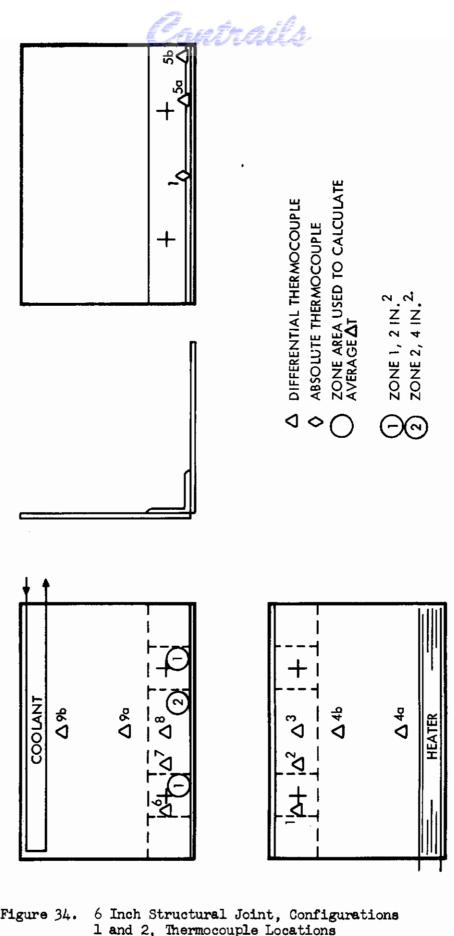
$$h_{a} = \frac{17.4}{\frac{6}{144} \times 5.95} = 70.3 \text{ Btu/hr ft}^{2 \circ} F$$

Thermocouples 1, 2, and 3 are used to calculate the conductance of joint "a," h_a, and thermocouples 6, 7, and 8 to calculate the conductance of joint "b," h_b.



Table 13 lists the experimental data for structural joint configuration 2. The thermocouple locations are shown in Figures 34 and 35. This configuration utilizes nut plates on one joint, called joint "b" in Table 13.

The results for configuration 3 are shown in Table 14, and the thermocouple locations in Figures 36 and 37. Differential thermocouples are located at the same (x, y) coordinates on the back of the angle brackets and panels at the locations shown on Figures 34, 35, 36, and 37.



6 Inch Structural Joint, Configurations 1 and 2, Thermocouple Locations Figure 34.

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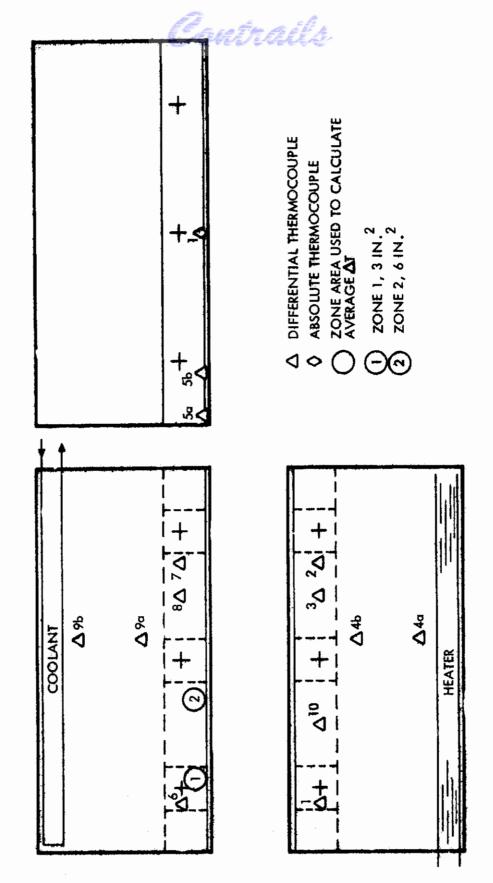


Figure 35. 9 Inch Structural Joint, Configurations 1 and 2, Thermocouple Locations

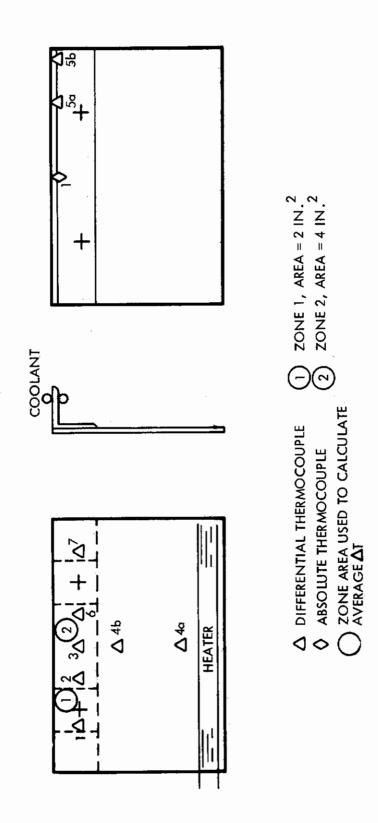


Figure 36. 6 Inch Structural Joint, Configuration 3, Thermocouple Locations

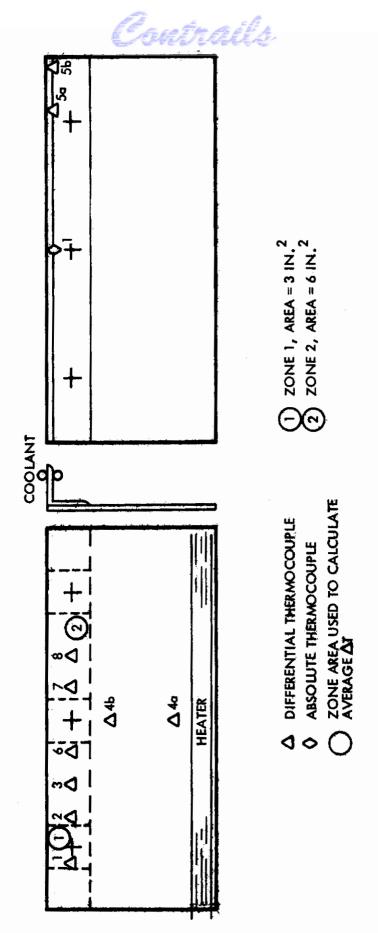


Figure 37. 9 Inch Structural Joint, Configuration 3, Thermocouple Locations



Table 12. Experimental Data - Structural Joint Configuration 1

Run Number	1	2	3	4	5
Date	2/16/65	2/16/65	2/16/65	2/17/65	3/1/65
Pressure, Torr	2×10^{-6}	2 x 10 ⁻⁶	2 x 10 ⁻⁶	1 x 10 ⁻⁶	1 x 10 ⁻⁶
Absolute T.C.					
1 - ⁰ F	93.0	126. 2	158. 4	196. 7	88.0
2 - °F	63.5	63.8	63.0	60.2	63.1
3 - ^o F	63.9	64. 4	63.9	61.4	63.5
Differential T. C.					
1 - °F	3. 56	7. 4 6	11.32	16.00	0.22
2 - ^o F	6.10	12.48	18.32	25.55	0.54
3 - ^o F	8.17	17, 05	26.55	37.70	0.45
4 - °F	7. 89	16.82	26.30	36.95	7. 95
5 - ⁰ F	0.50	0.97	1.51	2.13	0.06
6 - °F	3.30	7.00	10.72	14.90	0.20
7 - ⁰ F	5, 11	11, 47	17.60	23.93	0.33
8 - ^o F	7. 24	14.72	23. 28	31.60	0.65
9 - °F	6, 72	13.88	21.44	30.10	7.30
10 - ⁰ F					
Voltage, volts	22, 05	32. 21	40.17	48.17	22.00
Current, amps	0.2310	0.3376	0. 4 216	0.5061	0,2306
Water Flow, ml/min	750	750	750	550	700
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	RTV 11
Sample Number	1	1	1	1	1
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	70.3	72.0	74. 2	75.7	1042
h _b , Btu/hr ft ^{2 o} F	80,5	80.6	80.6	85.3	1042



Table 12. Experimental Data - Structural Joint Configuration 1 (Continued)

Run Number	6	7	8	9	10
Date	3/1/65	3/1/65	2/19/65	2/19/65	2/19/65
Pressure, Torr	1 x 10 ⁻⁶				
Absolute T. C.					
1 - ⁰ F	141.0	176.6	88. 4	149.8	184.9
2 - °F	62.8	62.6	61.1	62.3	61.3
3 - ⁰ F	63.6	63.7	61.6	63.1	62.5
Differential T.C.					
1 - ⁰ F	0.88	2.30	2, 58	8. 25	11.31
2 - ^o F	1.95	3.36	4.08	14.20	20,52
3 - ^o F	1.61	2.77	5. 44	18.88	27. 42
4 - ^o F	25.10	38.60	8.06	26, 22	37.95
5 - ⁰ F	0.33	2. 75	0	0.04	0.13
6 - °F	0.68	0.82	3,50	11.24	15.88
7 - ⁰ F	1, 08	2.05	4,50	14.80	19.80
8 - °F	2. 28	3.89	6.17	19.93	26.08
9 - ^o f	22.58	33.75	7, 82	24.17	34.85
10 - °F					
Voltage, volts	39.52	48.40	22.01	39.99	47.92
Current, amps	0.4149	0.5085	0.2319	0.4223	0.5067
Water Flow, ml/min	700	700	650	650	650
Bolt Torque, in-lb	24	24	24	24	24
Filler	RTV 11	RTV 11	None	None	None
Sample Number	1	1	2	2	2
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	906	715	103.5	100.1	100.9
h _b , Btu/hr ft ^{2 o} F	995	895	88.5	90	96.5



Table 12. Experimental Data - Structural Joint Configuration 1 (Continued)

Run Number	11	12	13	14	15
Date	3/5/ 65	3/5/65	3/8/65	3/9/65	3/9/65
Pressure, Torr	2 x 10 ⁻⁶	2 x 10 ⁻⁶	1 x 10 ⁻⁶	8 x 10 ⁻⁷	8×10^{-7}
Absolute T.C.					
1 - °F	90.5	142, 5	192.1	87.7	134.7
2 - ^o F	63,5	63. 4	62. 9	62.8	62.5
3 - ^o F	63.9	64.1	64.0	63.1	63.1
Differential T.C.					
1 - °F	7.12	21.30	35.8	0.50	1.50
2 - °F	5.98	18.07	30.82	0.75	2.44
3 - °F	2,61	7. 99	13.70	0.77	2.27
4 - ⁰ F	7. 21	21.42	36.0	7. 92	23.70
5 - ^o F	1.74	4. 96	7, 85	0.35	1.02
6 - °F	7. 21	21.05	32.65	0	0.07
7 - ⁰ F	5.87	17.37	28.5	0.65	2.08
8 - °F	2.84	8. 36	14.4	1.16	3, 53
9 - °F	6. 98	20.05	33, 15	6.98	20.47
10 - ^o F	1.37	3.84	5. 4 9		
Voltage, volts	21.58	37.50	48.22	21.83	37.83
Current, amps	0.2327	0.4050	0.5217	0. 2289	0.3972
Water Flow, ml/min	675	675	700	750	750
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	G 683	G 683
Sample Number	3	3	3	1	1
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	78.5	79. 4	77.0	602	595
h _b , Btu/hr ft ^{2 o} F	77.5	79.8	81.8	681	652



Table 12. Experimental Data - Structural Joint Configuration 1 (Continued)

Run Number	16	17	18	19
Date	3/9/65	3/15/65	3/16/65	3/16/65
Pressure, Torr	8 x 10 ⁻⁷	8 x 10 ⁻⁷	6 x 10 ⁻⁷	6 x 10 ⁻⁷
Absolute T.C.				
1 - ⁰ F	176.5	88.5	138.9	189.1
2 - ^o F	62.7	62.5	62. 2	62.6
3 - ^o F	63.8	63.0	63.3	64. 2
Differential T.C.				
1 - ⁰ F	2. 48	1.96	7.85	12.53
2 - ^o F	4. 59	4. 05	13, 85	22.80
3 - ^o F	3, 82	4. 59	15, 75	25.65
4 - ^o F	37.45	8.62	26.40	43.30
5 - °F	1.66	1. 21	4, 55	7.48
6 - °F	0. 21	3.64	11.28	18.70
7 - °F	3. 26	6. 02	18.05	28.85
8 - ⁰ F	5. 71	6. 57	19.58	31.45
9 - °F	31.90	7. 70	23. 25	37.20
10 - °F		3.86	13.80	21.77
Voltage, volts	47,80	19.44	33.73	43.55
Current, amps	0.5024	0.3841	0.6672	0.8623
Water Flow, ml/min	750	700	625	625
Bolt Torque, in-lb	24	24	24	24
Filler	G 683	None	None	None
Sample Number	1	1	1	1
Joint Length, in.	6	9	9	9
Number of Bolts	2	3	3	3
h _a , Btu/hr ft ^{2 o} F	542	116	98. 5	100.8
h _b , Btu/hr ft ^{2 o} F	645	74	75.3	77. 9



Table 13. Experimental Data - Structural Joint Configuration 2

Run Number	20	21	22	23	24
Date	3/23/65	3/23/65	3/23/65	3/25/65	3/25/65
Pressure, Torr	5 x 10 ⁻⁷	5 x 10 ⁻⁷	5 x 10 ⁻⁷	7 x 10 ⁻⁷	7 x 10 ⁻⁷
Absolute T.C.					
1 - ⁰ F	87.8	134. 5	178.8	89.3	140.4
2 - °F	63.7	64. 4	64.0	63.5	64. 2
3 - °F	64.0	65.0	65.0	63.9	6 4. 9
Differential T.C.					
1 - ⁰ F	2. 61	8, 02	12.75	2.14	6.53
2 - °F	5. 20	16.10	25.80	3. 93	12.42
3 - ^o F	6. 79	20.95	33.75	5.55	17. 25
4 - ^o F	8.03	24. 35	38.65	7.37	21.60
5 - ° F	-0.11	-0. 23	0. 05	0.35	0.94
6 - °F	3.32	9.70	15.35	3.53	10,44
7 - °F	3, 75	10,81	16.33	5.25	15, 20
8 - °F	5.35	15.91	24.62	6. 72	19.88
9 - °F	7. 24	21.40	34, 10	7.07	20, 22
10 - °F					
Voltage, volts	21.89	37, 85	48.97	21.88	37.99
Current, amps	0. 2284	0. 3956	0.5126	0.2279	0.3964
Water Flow, ml/min	775	775	775	625	625
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	None
Sample Number	1	1	1	2	2
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	84.2	81.5	85.0	105.5	102.0
h, Btu/hr ft ^{2 o} F	99.0	100.8	110, 3	82.4	81.4



Table 13. Experimental Data - Structural Joint Configuration 2 (Continued)

Run Number	25	26	27	28
Date	3/25/65	3/26/65	3/26/65	3/29/65
Pressure, Torr	7×10^{-7}	3 x 10 ⁻⁶	3 x 10 ⁻⁶	2 x 10 ⁻⁶
Absolute T.C.				
1 - °F	188.6	94.0	149.7	206, 2
2 - °F	63.8	64.7	64.5	64.8
3 - ^o F	65.1	65.0	65.2	65.8
Differential T.C.				
1 - °F	11.05	2. 54	8.00	12, 35
2 - ^o F	20.80	4.89	14, 73	23.78
3 - ^o F	29. 35	6. 41	19,12	31,00
4 - ^o F	34.70	7.35	21.92	37.80
5 - ^o F	1,53	1.02	2.50	3.65
6 - ^o F	17.48	3.69	10.81	17, 25
7 - ^o F	24. 20	4.31	11.94	18.55
8 - ^o F	32.45	5.24	14.55	23,10
9 - ^o F	32.80	6.91	19.87	32,10
10 - ^o F				
Voltage, volts	49.00	21.86	37.75	4 8.88
Current, amps	0.5121	0.2308	0.3993	0.5179
Water Flow, ml/min	550	700	700	650
Bolt Torque, in-lb	24	24	24	24
Filler	None	None	None	None
Sample Number	2	3	3	3
Joint Length, in.	6	6	6	6
Number of Bolts	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	100.8	89.5	88.5	92.6
h _b , Btu/hr ft ^{2 o} F	83.2	93.5	99.3	105.2



Table 13. Experimental Data—Structural Joint Configuration 2 (Continued)

			_	
Run Number	29	30	31	32
Date	3/31/65	3/31/65	3/31/65	4/1/65
Pressure, Torr	7×10^{-7}	7 x 10 ⁻⁷	7×10^{-7}	1 x 10 ⁻⁶
Absolute T.C.				
1 - °F	84.2	124. 7	165.0	84,0
2 - ^o F	63.3	63.5	63.5	62.7
3 - ^o F	63.6	64. 1	64.7	63.0
Differential T.C.				
1 - ⁰ F	0.70	2.51	4. 46	0.95
2 - ^o F	0.07	0.08	0.34	0.67
3 - ^o F	0.09	0.40	1.05	1.17
4 - ^o F	7. 73	22.85	37.85	7, 53
5 - ^o F	0.33	0.91	1.37	0.20
6 - °F	0, 48	1.50	2.19	0.54
7 - °F	0.64	1.96	3.70	0.80
8 - ^o F	1.24	3.72	6.65	2. 24
9 - °F	7, 42	21.50	34. 75	7. 4 9
10 - °F				
Voltage, volts	21.93	37.87	48. 93	21.83
Current, amps	0. 2289	0.3958	0.5120	0.2279
Water Flow, ml/min	650	650	650	575
Bolt Torque, in-lb	24	24	24	24
Filler	RTV 11	RTV 11	RTV 11	G 683
Sample Number	1	1	1	1
Joint Length, in.	6	6	6	6
Number of Bolts	2	2	2	2
h _a , Btu/hr ft ^{2 o} F	1427	1227	1050	438
h _b , Btu/hr ft ^{2 o} F	520	514	490	341
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Table 13. Experimental Data—Structural Joint Configuration 2 (Continued)

Run Number	33	34	35	36
Date	4/1/65	4/2/65	4/5/65	4/5/65
Pressure, Torr	1 x 10 ⁻⁶	7 x 10 ⁻⁷	1 x 10 ⁻⁶	1 x 10 ⁻⁶
Absolute T.C.				
1 - ⁰ F	126.0	167. 2	88.8	137.0
2 - ^o F	62.9	63.1	6 4 . 2	65.1
3 - ^o F	63.8	64. 5	64.6	66.0
Differential T.C.				
1 - ⁰ F	3.54	6.13	2.78	8.04
2 - °F	1.89	3.10	4.03	11.92
3 - ⁰ F	3.33	5, 44	6.31	18.92
4 - °F	22.40	36.95	8.51	26.80
5 - ⁰ F	0.50	0.91	0, 25	0.74
6 - ^o F	1.73	2.66	2.76	8.35
7 - ^o F	2,44	3.74	5.23	15.50
8 - ⁰ F	6.53	10.03	6.21	18,28
9 - ^o F	21.75	35, 15	7.97	23.00
10 - °F			5, 13	14.95
Voltage, volts	37.96	4 8. 96	19.43	33.66
Current, amps	0. 3967	0.5124	0.3865	0.6710
Water Flow, ml/min	575	550	600	600
Bolt Torque, in-lb	24	24	24	24
Filler	G 683	G 683	None	None
Sample Number	1	· 1	1	1
Joint Length, in.	6	6	9	9
Number of Bolts	2	2	3	3
h _a , Btu/hr ft ^{2 o} F	425	420	93.5	95.2
h, Btu/hr ft ^{2 o} F	345	375	84.1	87.8



Table 13. Experimental Data - Structural Joint Configuration 2 (Continued)

Run	37	38	39	40
Date	4/5/65	4/6/65	4/6/65	4/6/65
Pressure, Torr	1 x 10 ⁻⁶	8 x 10 ⁻⁷	8 x 10 ⁻⁷	8 x 10 ⁻⁷
Absolute T.C.				
i - °F	182. 2	85, 1	126. 0	162. 2
2 - °F	64.6	64. 0	64. 4	64.0
3 - ^o F	66.2	64.4	65.1	65.0
Differential T.C.				
1 - °F	12,58	0.16	0.60	1.26
2 - °F	20.59	0.39	1.44	2. 99
3 - °F	32.44	0.83	2. 61	4. 95
4 - °F	45.32	7. 33	22,00	36.10
5 - °F	1, 28	0.35	1.05	1,87
6 - °F	12.05	0.17	0.65	3, 43
7 - ⁰ F	23.56	0, 13	0.51	1.44
8 - ^o F	27.59	0.35	1.36	2.86
9 - °F	36. 90	7. 41	21.60	35.02
10 - °F	25. 22			
Voltage, volts	43.44	21.89	37. 99	48.99
Current, amps	0.8674	0. 2281	0. 3960	0.5119
Water Flow, ml/min	600	625	625	625
Bolt Torque, in-lb	24	24	24	24
Filler	None	RTV 11	RTV 11	RTV 11
Sample Number	1	2	2	2
Joint Length, in,	9	6	6	6
Number of Bolts	3	2	2	2
h _a , Btu/hr ft ^{2 o} F	94.1	889	795	669
h _b , Btu/hr ft ^{2 o} F	97.6	1892	1466	800



Table 14. Experimental Data — Structural Joint Configuration 3

Run Number	41	42	43	44	4 5
Date	5/8/65	5/8/65	5/8/65	5/9/65	5/9/65
Pressure, Torr	1 x 10 ⁻⁶				
Absolute T.C.					
1 - °F	70.3	84.5	98.1	69.6	80.0
2 - °F	62.7	62.6	62, 2	63,5	63.1
3 - ⁰ F	63.0	63.3	63.4	63.9	64.0
Differential T.C.					
1 - ^o F	1.42	4, 55	7.80	1.11	4.06
2 - ° F	3, 12	9.34	15.78	2.35	7.48
3 - ^o F	3, 83	11,61	19.67	2.84	8.90
4 - ^o F	3.62	10.91	18.90	3.64	11,20
5 - °F	-0.22	0.36	1.15	0. 43	1,55
6 - °F	2.66	8.30	14. 35	1.92	6.15
7 - °F	3.11	9.55	16.40	1.98	6. 41
8 - °F					
Voltage, volts	21.93	37,94	49.01	21.89	38.04
Current, amps	0. 2281	0.3949	0.5106	0. 2268	0.3943
Water Flow, ml/min	600	600	600	575	575
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	None
Sample Number	1	1	1	2	2
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h, Btu/hr ft ^{2 o} F	147	144, 2	142	194	180



Date Pressure, Torr Absolute T. C. 1 - °F 2 - °F 3 - °F Differential T. C. 1 - °F 2 - °F 3 - °F 4 - °F 5 - °F 6 - °F	5/9/65 1 x 10 ⁻⁶ 89. 7		5/13/65 6 x 10 ⁻⁷		
Absolute T. C. 1 - °F 2 - °F 3 - °F Differential T. C. 1 - °F 2 - °F 3 - °F 4 - °F 5 - °F		6 x 10 ⁻⁷	6 x 10 ⁻⁷	6×10^{-7}	_ 7
1 - °F 2 - °F 3 - °F Differential T.C. 1 - °F 2 - °F 3 - °F 4 - °F 5 - °F	89. 7			UAIV	5 x 10 ⁻⁷
2 - °F 3 - °F Differential T. C. 1 - °F 2 - °F 3 - °F 4 - °F 5 - °F	89. 7				
3 - °F Differential T. C. 1 - °F 2 - °F 3 - °F 4 - °F 5 - °F		72.2	86.8	98.3	70.7
Differential T.C. 1 - OF 2 - OF 3 - OF 4 - OF 5 - OF	62.5	65.0	66.0	64.1	62.4
1 - °F 2 - °F 3 - °F 4 - °F 5 - °F	63.7	65.3	66.9	65.4	62.8
2 - °F 3 - °F 4 - °F 5 - °F					
3 - °F 4 - °F 5 - °F	7.11	2. 69	7. 9 4	13.30	0.107
4 - °F 5 - °F	12.79	3.82	11.62	19.90	0.583
5 - °F	15,31	4. 91	14.60	24.80	0.414
	19.00	4.01	11.79	20,30	3.84
6 - ⁰ F	1.94	0.07	0.43	0.76	-0, 458
	10.50	3.71	11.08	18.82	0.307
7 - ⁰ F 8 - ⁰ F	10.81	3.66	10.52	17.78	0. 222
Voltage, volts	49.01	21.88	37.20	48.00	21.91
Current, amps	0.5084	0.2385	0.4059	0.5244	0, 2279
Water Flow, ml/min	575	575	575	575	425
Bolt Torque, in-lb	24	24	24	24	24
Filler	None	None	None	None	RTV 11
Sample Number	2	3	3	3	1
Joint Length, in.	6	6	6	6	6
Number of Bolts	2	2	2	2	2
h, Btu/hr ft ^{2 o} F	174.0	112.2	108.5	106.5	1110



Table 14. Experimental Data - Structural Joint Configuration 3 (Continued)

Run Number	51	52	53	54
Date	5/15/65	5/15/65	5/16/65	5/16/65
Pressure, Torr	5 x 10 ⁻⁷	5×10^{-7}	4×10^{-7}	4×10^{-7}
Absolute T. C.				
1 - °F	87, 7	102.5	74.3	91.8
2 - ^o F	63.7	63.4	66.0	68.0
3 - ^o F	64.8	65.0	66.3	68.9
Differential T.C.				
1 - °F	0.461	0.827	0. 222	0.723
2 - °F	1.560	2. 441	0.284	0.991
3 - ^o F	0.979	1,672	0.418	1,208
4 - ^o F	11,52	19.50	3.89	11.71
5 - °F	-0.282	-0.218	-0.515	0.491
6 - °F	0, 735	1.260	0.391	1.104
7 - ⁰ F	0.630	1.088	0.311	0.835
8 - °F				
Voltage, volts	38.00	48.99	21,90	38.00
Current, amps	0. 3956	0,5104	0.2278	0.3955
Water Flow, ml/min	375	450	450	575
Bolt Torque, in-lb	24	24	24	24
Filler	RTV 11	RTV 11	G 683	G 683
Sample Number	1	1	1	1
Joint Length, in.	6	6	6	6
Number of Bolts	2	2	2	2
h, Btu/hr ft ^{2 o} F	1273	1242	1328	1262



Table 14. Experimental Data - Structural Joint Configuration 3 (Continued)

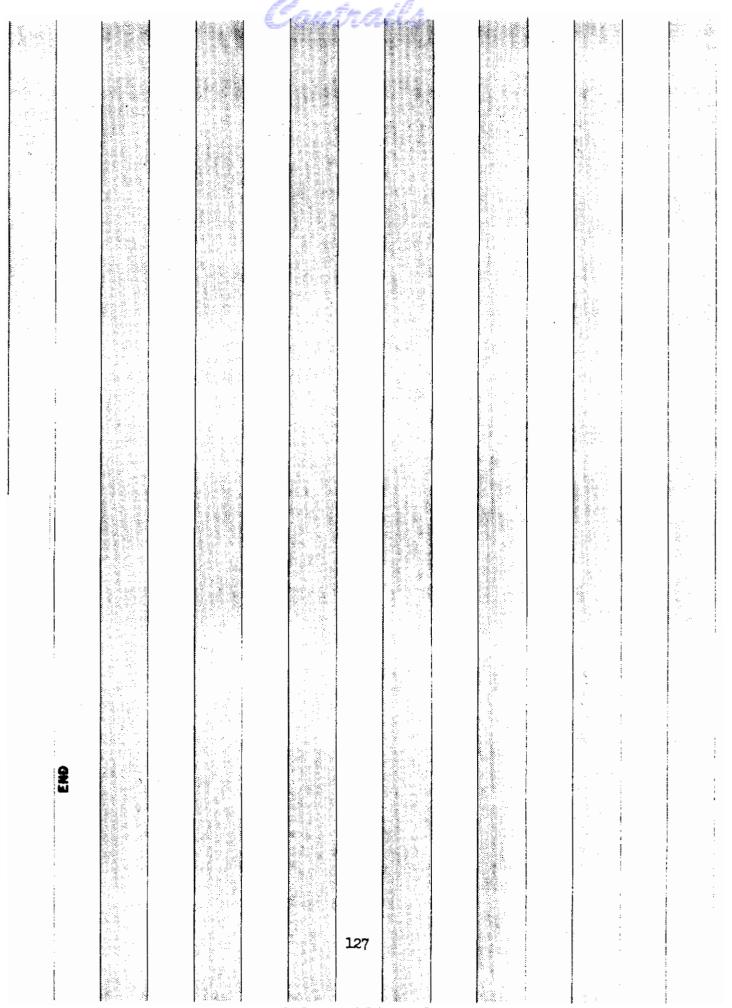
Run Number	55	56	57	58
Date	5/16/65	5/19/65	5/19/65	5/20/65
Pressure, Torr	4×10^{-7}	7×10^{-7}	7×10^{-7}	4×10^{-7}
Absolute T. C.				
1 - ⁰ F	103, 2	75, 0	87. 0	96.8
2 - ^o F	63.9	68.8	69. 2	67.2
3 - ^o F	65.1	69. 2	70. 2	68.9
Differential T.C.				
1 - °F	1.273	1.44	4. 41	7. 60
2 - ^o F	1.678	3.10	9. 4 6	16. 21
3 - ^o F	2.043	4.10	12.64	21.63
4 - ^o F	19.85	4.10	12.39	21.08
5 - ⁰ F	0.80	0.40	1.50	2, 78
6 - °F	1.905	4.64	14.00	23.78
7 - °F	1.440	3,84	11.61	19.60
8 - ^o F		3.00	9. 18	15.47
Voltage, volts	4 9. 01	18.98	32.84	42. 45
Current, amps	0,5105	0. 3958	0.6852	0.8860
Water Flow, ml/min	625	575	575	575
Bolt Torque, in-lb	24	24	24	24
Filler	G 683	None	None	None
Sample Number	1	1	1	1
Joint Length, in.	6	9	9	9
Number of Bolts	2	3	3	3
h, Btu/hr ft ^{2 o} F	1231	142. 2	139	135.5

APPENDIX III

SCRIPT F COMPUTER PROGRAM PRINT OUT

DINIVER FOR SPECULAR- DINIVERS FOR SPECULAR- DINIVERS FOR SPECULAR- DINIVERS FOR SPECULAR- DINIVERS FOR SPECULAR- 2

							L	F PROGRAM (AMDSZA).															
NN= N+N DO 2100 I=1.N IF(RHO(I.1))2020.2070.2070	(1+1)=-RMO(1+1) 2060 J=1+N	MHO(1:-J)=RMO(1:1) DO 2060 K=1:-J	R(K+1.04)=RMO(1+1) 50 2100 L=1.8	IF(Jattal)f(Jai)=AREA(I) #f(Ia)/AREA(J)	J. I. K.)	WRITE (991001) FORMAT (1H0.5x.12HFND OF IMPUT)	TE (3,1010) ID	FURNATIONAL SCRIPT IN 10/28/64 /(IMD-21X+11A6))	WRITE (3.)002)	H	CALL MPRT (RHOAN)	IAT "4 2	CALL MPRT (F.N.) MOTTE (A.1004) (ADEA([).Tml.N.)	F (1H1.5X.11HAREA	FORMAT CINISTANDED AND ARRAY	DO 150 K=1.N	HUL	CALL MPRT (R(1+1+K)+N)	CALL SCRF (NoMINEMOFOREROR, D.DI.SF.SFA.1ERR	WARREN (SOUTH STATE OF STATE O	L MPRT (SF.N.)	WRITE (301008) FORMAT (1H105Kel6HSCRIPT FA MATRIX)	MPRT (SFA-M) CLR) 300-100-300
2 000	2020		2060		2100	Ap			d f	12 12	26 ₽ü	5001		7001	ea		6001	04.			L	1008	



Approved for Public Release

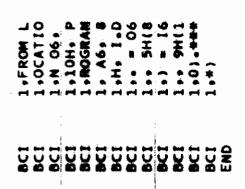
	ENTRY	ERRS			ERRS0001
ERRS	SAVE	4,2,1			ERR SOOO2
	SXA	EAst		man	ERRS0603
	LAC LAC	EA+2			ERR SOOO
	SXA	EA+2			ERRSODO
	TXI	#+1,4,0-2			ERRS000
	V U	7.7			ERRSOOD
	STA	I DENT2			ERRSOOD
	*	7.4			ERR 50009
	PAX	, 1			ERR 50010
	440	CODEDA			EKKSOOT
	Y.	2,4			ERRS001
	AXA	(PDT)			ERRS001
:	TNZ	ER23			ERRSOO
	CAL*	2,4			ERRSO0)
	TRA	ER24			ERRSOOL
ER23	ZF.	5,4			ERRSOO
R24	SLW	NAME			ERRS0018
	212	ER7			ERRSOOL
	3	3,4	-		ERR S0020
	YHY Y	(PDT)			ERRS00
	TAZ	ER31			ERRS0022
	ZYF	394	:		ERRS002
	STA	LEAV1			ERRS0024
	AXT	1,2			ERRSOO
İ	SXA	ER7 . 2			ERRS0026
	SXD	4+2+4			ERRS0027
	AXC	14,2			ERR 50028
	TXI	#+1 • Z • ##			ERRSOO
	SXA	BEG1 • 2			ERRS0030
	LAC	8EG1 • 2			ERRS0031
:	SXA	BEG1 , 2			ERRS0032
	SXA	BEG1+3,2			ERRS 603
	AXT	10.4			ERRS003
BEG1	S	4.44		:	ERRSOO3
	ANA	(PDT)			ERRS003
	TNZ	ER31			ERRS003
1	C.	***			ERRS003
	STA	٠			ENRSOO.
	×	DFG * . 4 . 1			

200		
66-	ntra	6 F 16
	ESTERS	REEL

ER31	CALL	*FWRD*(*UN03**A)	ERRS0041
	CLA	EA	ERRS0042
	TSX	* FCNV * * 4	ERRS0043
	4		ERRS0044
	TSK	*FCNV***	ERRS0045
	.	CODEO	ERRS0046
		•FCNV••4	ERRS0047
IDENT2		**	ERRS0048
	TSX	.FCNV4	ERRS0049
1	TSX.		ERRS0050
	ZET		ERRS0051
	TRA	LEAVI	ERRS0052
R I N	RETURN	FRRS	ERRS0053
	Z.		ERRS0054
	Z W	ATE CAL	ERRS0055
	X	UP TO 10 ARGUMENTS PERMITTED	ERRS0056
!			ERRS0057
LEAVI	TSX	************************************	ERRS0058
	TRA	XL C	ERRS0059
1	00		ERRS0060
ARG	37d		ERRS0061
	374		ERRS0062
	32d		ERRS6063
	PZE		ERRS0064
	PZE		ERRS0065
	PZE		ERR 50066
	PZE		ERRS0067
	PZE.		ERRS0068
	P2E		ERRS0069
,	PZE		ERRS0070
NAME	B O!		ERRS0071
¥ .	PZE		ERRS0072
ALIST	PZE		ERRS0073
CODEO	S 80		ERRS0074
(PDT)	t o	17777700000	ERRS0075
ER7	858		ERRS0076
≺	8CI	# () # (ERRS0077
	901	II T	ERR50078
	8 C I	I * * FIRES -	ERRS0079
			ERR 50080
		Is EXIT	ERR SOO 81



82	83	40	Š	96	6	88	60	90	5	35	93	46	95
868	500	200	590	88	568	500	500	3	88	500	500	500	88
ER.	ERR	ERR	EX	ERR	ERR	ERR	ER	ERR	ER	EXX	E	FR	ERR





FINP 0001 FINP 0001 FINP 0002	FINPODOS	F1NP0004	,	CALL	FINP0007	SCC CAN'T		A DOD LET L	0100414	FIRPOOII	FINPO012	FIMPOOLS	FINP0014	FINP0015	F1NP0016	FINPOOLT	FINPOLIA	FINP0019	FINP0020	FIMPOOZI	FINP0622			F1NP0025	F IMP0026	F1RP0027	F1xP0628	FINP0029	FINP0030	FINP 0031	F1NP0032	FIMPO033	FIRP0034	FINP0035	F1NP0036	FINPO037	FINPOG38	FINP0039
DECEMBER 1964				FLAG TO USE PREVIOUS									AL PHA+N			:	N OR O			-			_	RELATIVE ORIGIN					IMAGE FROM INPUT TAPE	•UN02••=H(14A6))						Z	Z	ON CUIPUT TAPE.
FINP LISTAREFADECK FINP-FORTRAN IV DECEM ENTRY TBLOO	(4.1.2)1	*+1,4,4-2		COMMON+28	IMPT2	FIMPT.4	77-071-3	4.0	ě	# # F	1835		TBL02	1,04	18100		COMMON+29	18		**1	#+I • 4 • 0	4.0	GINOO	O 7		COMMON+29	TBL01	_	80	0.(14,1	*FCNV 4	COMMON+14.1	A.1.1	•	COMMON+29		CARD INAGE ON
	SAVE	TXI	CLA	STO	12E	SXD	6) \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	X X 1	SBR	SUB	¥00	STA	3	STA	CLA *	STO	ALS	₹	STD	TXI	₹	STO	ST0	CLA	ğ	STA	STO	_	CALL	AXT	1.S.	STO	TIX	1SX	CLA	٦	WRITE
S I BMAP * TBL	FIRE						THDT-	7.																					*	GINA		∢						*
																		13	ı												•							

FINDOOAT	FINP 0042	FINDO043	FINP0044	FINP0045	FINP0046	FINP0047	FINPOO48	FINDO049	FINPOOSO	F14P0651	FINPO052	F1NP0053	FINP0054	F1NP0055	FINDOS6	FINP 0057	FINPOSS	FINP0059	FINP0060	FINP0061	FINP 0062	F1NP0063	F1MP0064	F1NP0065	FINPO066	F1MP0067	FINPODES	F1MP0069	FINP 0670	FINPOOT	FINP0072	FIMP 0073	F1900074	FINP0075	FINP0076	FINP0077	FINPOOTS	FINP0079	FINPOOSO	FINPOORI
																		INGORE BLANK CZRD		- !	SAVE PREFIX CODE				la.j	Q	SAVE LAST DIGIT OF ADDRESS			TEST FOR BLANK ADDRESS					BLANK	DETERMINE COMMA POSITION				
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บ	TSX	AXT	3	TSX	TIX		GINAI AXC	×	SXD	SX	AXC		GINB CA	TX.	TXI		GINC TXH	×	×Ψ	Ċ	GINOI PXD	3	ST	ST	SUB	121	3	¥	21	ST	STZ	CLA	3	TXI	TXL	001	רפר	X	OX.	5

TAX AXA TAX AX	#-5 * 4 * 1 * 4 MIXGO * 4 GINER GINZO * 4 5 * 4 0 * 1 6 IN 19 * 2 * 9 GIN 19 * 2 * 9 GIN 19 * 2 * 4 8 GIN 10 * 4 8 GIN 10 * 4 8	POSITION OF COMMA MATRIX OUTSIDE MATRIX SYMBOLIC	
STO TXL	MASK3 ADDIND 61NO7		
-	ADDIND MASK3 GINO4	TEST FOR OCTAL	
	5835+2 OCTAL+4	SET-UP OCTAL ADDRESS	
	5 * * * * * * * * * * * * * * * * * * *	SET UP DECIMAL ADDRESS	
TRA	DECIM.4 GINER 6.5**	ERROR	·

	INPOI	FINPO125 FINPO126	FINPO127	FINDOLAB	INP013		FINP0132	FINPOISS	F1MP0134	FINP0135	FINP0136	FINPOIST	FINDOLSE	FINDALSY	FINPO141	FINPO142	FIMP0143	FINPO144	FINPOI45	INPO	FINPOI47	FINPO148	FINPO149	FINPOISO	FINPOISI	FINPOISZ	FINP0153	FINPO154	FINPO155	F 1 100150		のないのよれてし	FINPOISS	FINPOLSO
SET-UP TRA TO SUB-PROGRAM 8.4.41 4.32 8.4.4-23 8.4.4-1												i					:			:														
200 SET-UP TRA 48 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 47 SUB-P 60 SUB-P		70	DGRAM													INDEX	J (ZERO	ONIT	ELLS		INTEGER	\sim				2	EXT	OCTAL	SYMBOL IC	MO CARD	Ş		CARD	CARD
		SET-UP TRA	SUB-PR											3 Q	. · ·	_	_	MATRI	SKIP					ia.		:	SAVE		244	AMK			TO NEXT	NEXT
	GINO7	CRDADO PREFIX•4	NER : 4 : 48	700+4+4/ 0835+4	60	÷	4	9,44	R.4.	GINER,4,16	NO9+1+1+-1	N10.4	RGINOO	GINER	GINER	NGINOO	MCD00	MCDOO	KGIMOO	CRDADO	IGINOO	HEINOO	GG I NOO	F61400	GINER	Delwoo	CGINOO	BG I NOO	ACDO	LeimO0+12		_	GINO1-1:1:** GINA	in CK R
	61NO6	1 NO 7				I NO 8					6 I NO 9						Ì			:										OTHIO CINIC	111		N12	GIN12 GIN13



CALL COMMON-29 CALL HIPE GINI2 CALL HIPE GINI3H(14A6) CLA HIPE GINI3H(14A6) CLA HIPE GINI3H(14A6) CLA HIPE GINI3H(14A6) CLA HIPE GINI3H(14A6) AXT HIPE GINI3H(14A6) AXT HIPE GINI3H(14A6) AXT HIPE GINI3H(14A6) CALL GINI3 ELAM AXI 10.1 CALL GINI3 ELAM BCT 1H(14A6) ELAM GINI3 GGINOO CLA ADDINO SUB HASK3 FIE GGINOI FIE GGINOI FIE GGINOI FIE GGINOI FIE GGINOI FIE GINI3 F
TPL GIN12 CALL FURB. (-UN03.,-H(14A6)) AXT 10.1 CLA -H TIX +-2.1.1 CALL FINC+4,1 TIX +-2.1.1 CALL FFIL. TXL GIN12 CAS FFIL. TXL GIN12 LDG CRDADD CAS MASK2 TXL H2 LLS 35 TXL H2 LLS 35 TXL TXL GIN12 LDG CRDADD AXT 11.9 LDG CRDADD AXT 11.1.1 LDG CRDADD AXT 11.1.1 LDG CRDADD AXT 11.1.1 LDG CRDADD AXT 11.1.1 LDG CRDADD AXT 11.1.1 LDG CRDADD AXT 11.1 LDG CRDADD AXT 11.1 LDG CRDADD AXT TXL GIN12 CCMMON+12.1 TXL GIN12 OCCLA MASK2 SGIN00,4 CLA MASK2 STO CRDADD TIX GIN12 TXL GIN12 FXC CRDADD TXL GIN12 TXL GIN12 FXC CRDADD TXL GIN12 FXC CR
CALL FINES. (-UM03., -H(14A6)) CLA -H TSX -FCNV., 4 TIX -2.1.1 CLA GINICA+,1 TSC -FIL. TSC -FIL. TSC -FIL. TSC -FIL. TSC -FIL. TSC -FIL. TSC -S.1.1 CAL -FIL. TXL GINIZ LDG CRABB MPY 11835 LLS 35 TXL GINIZ LDG CRABB MPY 11835 LLS 35 TXL SGINOO, 4 SGINOO, 7
CLA "H
CLA "H TSX "FCNV.** TIX "-2.1.1 CLA GINRC+4.1 TSU "FIL.* FFIL.* FFIL.* GINI2 EDG CLA GINI2 EDG CRABD CAS MASK2 TXL GINI2 LDG CRABD NPY 11835 LLS 35 LLS 35 LLS 35 LLS 35 CRABD NPY 11835 LLS 35 CRABD NPY 11835 LLS 35 LLS 4+2 SUB 10835 STO CRABD AXT 11.1 LDG CRABD AXT 11.1 LDG CRABD TXL GINI2 CRABD TXL GINI2 FXL GINI3
TSX
TIX
CLA CENV4 TIX CALL FEIL. TXL GINI2 TXL H+2 TXL H+2 TXL H+2 TXL H+2 STO CROADD AXT TI LDO CROADD AXT TI LDO CROADD TXL GINI2 TXL GINI3 TXL G
CLA GINRC+4,1 TIX +-2,1,1 CALL FIL. TXL FIL. IXL GIN12 ED CRDADE CAS MASK2 TXL H-2 TXL GIN12 TXL GIN12 TXL GIN12 LDG CRDADE MASK2 TXL H+2 TXL GIN12 LDG CRDADE MASK2 TXL GIN12 LDG CRDADE AXT 11,1 LDG CRDADE AXT X1,1 LDG CRDADE TXL GIN12 TXL GIN13
TSK -FCNV.,4 TIX #-2,1,1 CALL FFIL. TXL GIN12 EC BCI 1,00000E EC BCI
TIX #-2,1,1 CALL FFIL. TXL GINIZ ECI 4, ABOVE CAMO IN EMBO ECI 1,00000E M BCI 1,00000E M BCI 1,00000E M SK2 TXL H+2 TXL GINIZ LDG CROADD MPY 11835 LLS 35 TZE ++2 SUB 10835 STO COMPON+12,1 TXL GINIZ TXL GINIZ OCHOON+12,1 TXL GINIZ FIX #-4,1,1 TXL GINIZ FOC CLA ADDIND SUB MASK3 TZE GGINO1 PXD CROADD TIX #-4,1,1 TXL GINIZ FIX #-4,1,1 TXL GINIZ FIX #-4,1,1 TXL GINIZ FIX #-4,1,1
CALL .FFIL. TXL GINIZ IXL GINIZ ECI 1.00000E ECI 1.00000E ECI 1.00000E MASK2 TXL 4+2 TXL 61N1Z LDQ CRDABD MPY 11835 LLS 35 TZE ++2 SUB 10835 STO COMPON+12,1 TXL GINIZ TXL GINIZ TXL GINIZ TXL GINIZ TXL GINIZ TYL GINIZ
TXL GIN12 ABOVE CARD IN ERRO IN ERRO
C BC 4. ABOVE CARD IN ERRO BC 1.00000E 1.00000E CA CRDADO CA CRDADO CA CRDADO CA CRDADO CC CA CC CC CC CC CC C
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CLA CRDADD CAS MASK2 TXL #+2 TXL #+2 TXL G4N12 LDG CRDADD MPY 11835 LLS 35 TZE #+2 SUB 10835 STD CRDADD AXT 1181 LDG CRDADD AXT 1181 TXE #+2 SGINOO,4 CLA MASK2 SGINOO,4 STO CRDADD TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 FXL GIN12 TXL GIN13 TXL GIN12 TXL GIN13 TXL GYNNO TXL
CLA CRDADD CAS MASK2 TXL #+2 TXL GINIZ LDG CRDADD MPY 11835 LLS 35 TZE #+2 SUB 10835 STD CRDADD AXT 119,1 LDG CRDADD AXT 119,1 TXE GINIZ CLA MASK2 SUB MASK2 CLA ADDIND SUB MASK3 TZE GGINO1 TXE GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1 FXL GGINO1
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TXL #+2 LDG CRDABD MPY 11835 LLS 35 LLS 35 TZE #+2 SUB 10835 STO CRDABD AXT 11.1.1 LDG CROMMON+12.1 FSX SGINOO.4 CLA MASK2 STO CRDADD TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
TXL GINIZ LDG CROADD HPY 11835 LLS 35 LLS 35 TZE ++2 SUB 10835 STO CROADD AXT 11.1 LDG CROADD AXT 11.1 TSX SGINOO.4 CLA MASK2 STO CROADD TIX #-4.1.1 TXL GINIZ CLA ADDIND SUB MASK3 TZE GGINOI PXD PXD
LDG CRDABD MPY 11835 LLS 35 LLS 35 TZE ++2 SUB 10835 STØ CROABD AXT 11,1 LDG COMMON+12,1 TSX SGINOO,4 CLA MASK2 STØ CRDADD TIX #-4,1,1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD PXD
LLS 35 LLS 35 LLS 35 TZE #+2 SUB 10835 STO CROADD AXT 11,1 LDO COMPON+12,1 TSX SGINOO,4 CLA MASK2 STO CROADD TIX #-4,1,1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD PXD
LLS 35 TZE ++2 SUB 10835 SUB 10835 STD CROADD AXT 11,1 LDG CROADD TSX SGINOO,4 CLA MASK2 STD CRDADD TIX #-4,1,1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
SYMBOLI SUB 10835 ### 10835 ### 10835
SUB 10835 ST0 CROADD AXT 11.1 LD0 COMMON+12.1 TSX SGINOO.4 CLA MASK2 ST0 CRDADD TIX #-4.1.1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
\$10 CROADD AXT 11.1 LDG COMMON+12.1 TSX SGINOO.4 CLA MASK2 STO CRDADD TIX #-4.1.1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
AXT 11:1 LDG COMMON+12:1 TSX SGINOO:4 CLA MASK2 STO CRDADD TIX #-4:1:1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
LDG COMMON+12.1 TSX SGINOO.4 CLA MASK2 STO CRDADD TIX #-4.1.1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
TSX SGINOO.4 CLA MASK2 STO CRDADD TIX #-4.1.1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD
CLA MASK2 SET TO STO CRDADD TIX #-4.1.1 TXL GIN12 CLA ADDIND SUB MASK3 TZE GGINO1 PXD FT.
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GEINOI CAL GINDO

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	CLA C	0.1	
	STO	COMMON+33	
	CLA C	101	
	STO	COMMON+34	
	ALS	24	
	SLW	COMMON+20	
	ST2	SUM	
	ST2	1	
	KX (100835+2	
	CLS	100030	



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	TSX DECIM+4		-
		ERROR	FINPOZ
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TMI GINER STA FGINOI LDG COMMON+12 MPY FREF,2 FRINOI LRS ** TXL BGINOZ, ** TXL BGINOZ, ** TXL BGINOZ, ** TXL BGINOZ, ** TXL BGINOZ, ** TXL BGINOZ, ** TXL BGINOZ, ** APS 18 SSM ADD COMMON LRS 35 DVP 10835 SUB M9835 PAX *2 CLM LLS 35 ADD 5835 TMI GINER PAX *2 CLM CLLS 35 ADD 126835 TPL LGINOI+12 CLA XREF1,2 ADD XREF2,4 ADD 126835 TPL LGINOA STZ COMMON+12 LGINOA PAX 0*1 LLS 2 TZE LGINO2 LLS 2 TZE LGINO2 LRS 1 TXI LGINOI 11						PT.												1			ADD														
· · · · · · · · · · · · · · · · · · ·	-	LDQ COMMON+1	F F	TNZ	TXL BGINO2.	TSX	COMMON	DECN2,2				U	LRS 35	DVP 10835	SUB M9835	PAX .2	CLM	- 1			FGIN01+2			STZ COMMON+1	PAX	FREF1	FREF2	i				12E		TXI LGINO1.1	LLS PND

FINP0328	FINP0329	9	FIMPOSSI	F1MP0332	F1MP0333	FINP0334	FINP0335	FIMP0336	FINPOSST	FIMPOSSE	F1MP0339	FINP0340	FIMP0341	FINP0342	FIND343	•	FIRE0349	FIRP0346	FIMP0347	FINP0346	FINDONS	FINDESS	9	F 1MP0352	F1MP0353	F1MP0354	TIRDOUS.	FIRECOMP	F1MP0357	FINP0358	F1MP0359	F1NP0360	FIMP0361	FINP0362	FINP0363	FINP0364	FINPOSES	FINP0366	FIMP0368
									EXIT TO STORE	STORE ROUTINE	the make to the part of the pa							ONLY IF CRDADD HAS			RELATIVE LOCATION IN					ADD I TO OLD ADDRESS			The state of the s			•	NOW INTEGER						
27		- ·	1010144	-				GINER	BGIM02	CRDADD	MASK2	SGINOI	ADDIND	MASK3	SAA1	CRDADO	SGINO2	CRDADO	SGINOA	CRDADO	1835	CRDADD	GINOO	CRDADD	SGI NO2	SGINO3	1835	SGINOS	*	194		DECNO,4	GINER, 2,0		GINER	SGINO3	SGINO3	GINII	0.1
LRS	IZE	באין	- X	AX4	LLS	LRS	LGING3 LXD	TNZ		SGINOO CLA	SUB	TZE	CLA	·		3		SAA1 CLA	TZE	S	SUB		SGINOA CAL	V		SGINO1 CAL			SG1M03 570			KGINOO TSX	TXH	×	II I		STA		CGINOO CLA

356	~	FINP0371.	FINP0372	-	FINP0374	FINP0375	FINP0376	FINP0377	FINP0378	NPO	FINP0380	FINP0381	FINP0382		-	FINP0385	FIND0386	FINP0387	FINP0388	FINP0389	2	F1MP0391	I KP 03	FINP0393	MPO	INPO	-	FINP0397	FINP0398	FINP0399	F1NP0400	INPO	FINP0402	FINP0403	-	FINP0405	FINP0406	INPOA	F IMPO408	FINDO409
		:																					:																	
																																				i				
													EX													:														
						z							E INDEX													;												!		
						ABSOLUTE LOCATION					LOCATION		BLANK-RELATIVE							;														INTEGER						
						LUTE 1							3LANK-F																!					OCTAL						
						AND ABS			!		SYMLOL		NOT																					SET-UP (
!		1																														İ		S						
4	_				1.0-1	LOCATION		4	\$					-2				-	_							1-61		4				1 9-3								
18100	SGINO3	1835	***5	TBL02	GINI	ATIVE	0,1	TBLOO,	CGINO	*+1,29	TBLO1	BLANK	GINER	*+1,2	TBL02		NC INO	*+1,2	SGIN03	1835	TBL02	1835	RLOC	*+1	**	GINII	0,1	TBL 00,	RLOC		RLOC	GIN11					L 2			
				*		E REL					*										*			*										0,1			OCTA			S S
TSX	CAL			STA	TXI	SAV			L XA	TXI	CLA	SUB	TNZ	IXI	XEC	¥ V V	STA	TXI	CAL	ADD	STA	ADD	SUB	512		ı		TSX	212	V OX	STA	TXI		100		LGL	INZ	CAL	10 P	St.W
			CG 1NO1			*	NGINOO																:		NGINOI		RGINOO						•	CTAL	OCTAL 1					

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FINPO451	Z N		FINDO454	2		FIND0457	FIND0458	FIND0459	F. IND 0460	FINP0461	FINP0462	FINP0463	FINP0464	FINP0465	FIRDO466		FINDO468	FINP0469	FINP0470	FINPO471	2.0	F1MP0473	FIND0474	FINP0475	FINP0476	3		FINP0479	F.1 RP0480	FINPO461	FINP0482	1	FINDOVEA	FIRPO485	-	=	FINDO488	2	FIRPO491
		and the second s			:															ģ																			
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-								END ON DIGIT CO		ERROR EXIT																													
								END ON		ERR				:						; ; ; ; ;			٠												;				
		!	14		2,1	4.1	4	1,4,-1	IM2.4											961680	905380	357980	609280	ı	459280	763080	300280	787180				1							
SUM	10835	35	+1011100			DECIMI:	DECIM2.	DECIM8+	DEC					34																		20					4	-	m 40 1
100	Ϋ́DΥ	2	ADD	STO			LXD	TXI	١.	TRA		5	DEC	DEC		DEC	2	DEC	DEC	Ì	DEC	DEC	DEC	DEC	DEC	DEC	DEC.			DEC	DEC			DEC		DEC	DEC	DEC	DEC
						DECIM7			DECIMS			0083			835					REF 2						Ì			FREF2			-]-	7835		10835		4835	ZEF	M6835

83	<u></u>	- eA .
C O I	rie	ails

F I NP 0492	FINDOASS	1 1 NP 0496	F1800487	FINDO498	至	FINP0500	FIND 0501	F1100002	F110-0503	ŧ	F120005	FIN-0506	F1200567	F135-650s	£	ŧ	100	٤			9	1	FIMPOSTS		FIM-0520	FIRPOSEE	Š.	9	4 1 1 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	FINDOSSE	-	NP 05	OLK I	F1MP0530	F1800981
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																					The second secon										and the second s			TSX MTX00.4	NO CHAR I
	51.	ŧ	-26	-29	.931322574	. 745058059	.596046447880	.953674316	. 762939453	•610351562	-	7	•	-	-	•	•	٠,	•	•	.67108864B	•	N	126	000000000	60606060600	000000000	100000	3	8835	,	12		MTX10,4	
M9835 DEC	236	DEC	DE C	XREF1 DEC	DEC	DEC	DEC	0	DEC	DEC	DEC	DEC		TREF DEC	5	DEC	DEC			DEC	1		- 1	PZE	Š	DO!	000		3835 PZE	DEC				MTX00 SXA	STO

F1NP0533	FINP0534	FINPO535	F1MP0536	FINPOSST	FINPO538	F1NP0539	FINP0540	FINP0541	F1MP0542	FINP0543	FINPOSA	FINPOS45	FINP0546	FINP0547	FINP0546	FINP0549	FINP0550	FINPOSSI	FINPOS52	FINP0553	FINP0554	F1NP0555	FINP0556	FINP0557	FINP0558	FINP0559	F1NP0560	FINPOS61	FINP0562	FINPOS63	FINP0564	FINP0565	FINP0566	F1NP0567	FINP0568	FINP0569	FINPO570		FINP0572	FIMP0573
		⊃:	NORMAL RETURN							LES THAN N CHADS			7.1							The state of the s			LOC GTR MAX			1 · · · · · · · · · · · · · · · · · · ·	I ERROR	~~						DETERMINE COMMA POSITION	· · · · · · · · · · · · · · · · · · ·				COMMA	
5835	COMMON+36	2•4	XTX02+4	SIGN	SUM	100835,2	COMMON+37.4	DECIM.4	GINER	MTX11	GINER + 2 + 100	**	1+2,4	MTX01,44,1	***	7	1835		IMAX		H	7 I	1,4		2.4	MTX02.4	GINER.4.1	MTX02-1	IJ WORD	MCD02.4	GINOO	1835	SGINO3	0.1	9	2,4	0.0	9	MASK4	*+3
ADD	STO	AXT	SXA	212	512	LXA	CLA	TSX	TRA	TRA	TXL	AXT	STO	TIX	AXT	CLA	SUB	XCA	Υď	X V V	ADD	L00	760	XCA	TRA	LXA	TXH		SET UP	SXA	CAL	SUB	STA	007	LGL	AXT	PXO	1.6L	SUB	12E
			MIXOI						:			MTX02			MTX10											MTX11				MCD00										
																				444																		-		

FINP 0575	FINPO576	FIMPOST	FIMPOSTA	F1MP0579	FINPOS80	FINPOSEI	F1NP0582	F. IMPOSES	FIRPOSE	FIRECORIA	FINPOSE	FINP0587	FIMPOSES	F1MP0589	Ξ	360-21	=	FINDOS	FINP0594			2	F1MP0599	=	FIMPOGO	FINPOGO	F1 MP 0603	F1NP0604	FIMP0605	F1MP0606	F.1 HP 040	F1 MP 060	Š	FINPO610	FINPO613	FINPOGI
	POSITION OF COMMA									a depart of the second of the			ZERO MATRIX									BLANK		NULL AND BLANK			BLANK			BLANK	MOLT.					
GINER,44,3 *-5,4,1	**	MTX00,4	**	1	IMAX	7	7	MCD02,4	MCD04,4,12	4.0I	GINOO	71	*+*	**	#-1040]	GIN11+1+-1		CTR	PASS	P F	SYMOOAA	4.0	ACD6,2,1	ACD12,4,0	ACD6+1	70	ACD10,4,0	1.2	SYM00*4	4.0	ACD10,2,1		15	P	PF	PASS
X X X	PXA	TSX	d ON	607	STO	MPY	STO	LXA	TXL	LXA	Z V	ADM	STA	STZ	TIX	TXI		STZ	512	ST2	, V L	AXT	TXH	TXL	1XL	STQ	TXL	AXT	TSX	AXT	TXL	XCL	ALS	STT	100	CLS
			MCD02													#CDO#	*	ACD0		AC01						ACD6									ACD10	

FINP0615	FINDSI	9	FINP0620	FINP0621	FINPO622	F1MP0623	F1MP0624	F1MP0625	F1MP0626	FINP0627	400	FINFOGES	š	F INPOSAL	F120632	Š	ş	FINP0635	F140636	F120637	F18P0638	F1MP0639	FINDS+0	FIMP0641		FINFOGAS	443042 H	F1MP0645	FINDOGA	FINDOGET	ALMOST F	F120045	FINESS	-	A Z	FINPOESS	464062ML
NOT BLANK			BL ANK			-			:		LXA L(NO CHARACTERS),2	TSX SYMO0.4		MORMAL 1R2=1 IF MULL				7										BLANK		COMMA					NO CHARACTERS		LEFT JUSTIFY
WORD ACD19490	ACD14.4.6	*+1+1+1	*+3.4.1	WORD	SGIN00.4	GINII	18	WORD	ACD12		SYM02,2	SYM14,4	PSYM	1,52	CTR	1835	CTR	10835+1	*+2	#+1+1+1-1	0.1	PSYM	ø	PSYM	0•1	MASK1	MASK3	SYM20	11835	SYMZ1		SYM01,2,++	PSYM	*+1,2,-1	SYM06,2	MASK2	9
STQ TXT	TXH	TXI	TXL	60	TSX	TXL	ğ	SLO	TXL		SXD	SXA	STZ	AXT	CLA	ADD	STO	SUB	TNZ	IXI	20	Y.	101 101	SLW	sto	ANA	SUB	TZE	SUB	1		TXL	3	TXI	SXA	100	ا ا ا
	ACD12			ACD14			ACD15			_	SYM00				SYMO1																	SYM02	. !	SYMO3			SYMO4

F2		c B
Co.	nTu	ails

F 1 MP 0656 F 1 MP 0657 F 1 MP 0658	FINDSAS	F.1 NP 06-60	F1MP0661	F INPO662	F1NP0663	FINPOSS	F. INPO665	FIND0666	F1M0667	FINPO668	F1MP0649	F1NP0670	F1140671	F1M0472		F1NP0674	S	F1#P0676	Ĭ	Š		00000011		₽	3	FIRE COST	-	-	_	FINP0688	F.E. 1000.00	ì	F1890691		F180693	FINP0694	CASCALLA	F1MP0696
		SYMBOL IC	NO CHARACTERS				DECIMAL	OCTAL								ERROR					THE NAME OF THE PARTY OF THE PA			EXIT	BLAME					The second secon			3-X+000					AL PHA+N-(N-2)
SYMU4,2,5 SYMBL PSYM	BLANK	SYM10	***2	SYMBL	¥ns	SIGN	SYM08.2.4	OCTAL1.4	GINER	SYM14,2	0•1	0,1	SYMBL	*2	DECIM•4	GINER	GINER	SYMBL	0.1	SYM14.2	SYMBL	TBL.00.4	7. P. (294	Tete 7+#	SYM14*4	SYM14+1,2,1	PSYM	9	PSYM	SYMO3	***2	20**		TBL02,2,-2	TBL01,2,1	GINER + 0 1	***2
S L K	ANA	TMZ	AXT	LDQ	212	572	TXL	TSX	TXF	TSX	CLA	STO	STO	ΡXΑ	TSX	TRA	TXL	CLA	STO	TSX	7	SX	YX I	TRA		SXA	TXL	CAL	ARS	SLW	TXL	LXA	CAS	TXL	TXI	TIX	IXL	100
			SYM06						:		SYM08										SYM10		SYM14		SYNC		SYM21	SYM25				18100	TBLOI				TBL03	TBL02

TA ERROR. . . JOB DELETED

CGINO1,2 TBL03,2 1,4	+++	COMMON+21 COMMON+22 COMMON+22 COMMON+23 COMMON+24		40 E40MES**6 6,0FINP INPUT DA
SXA LXD TRA PZE	1		で	PZE PZE PZE BCI BSS END
I MAX	PF PASS CTR	PSYM CRDADD CRDADD SIGN SUM ADDIND	PREFIX WORD ERROR I GINOO RLOC	FINDT CODE40 ER40MS E40MES COMMON



ST.REF.DECK MAT9(A.X.*KR.*KC.*LC.*LA) (KR.*KC.).*X(KR.*LC.) 1.3) 1.3) 1.3) MM K) -R*A(J.*K) K) K) K) K() K) K() K) K() K) K

MAT90041 MAT9004+

RETURN



*		
20 ARI		
20X		
# 4		
MPRI LIST, REF, DECK MPRI PRINTS THE FIRST N ROWS AND COLUMNS OF A 20X20 ARRAY SUBROUTINE MPRI (A.N.) DIMENSION A(20,20) DO 100 I=1.N WRITE (3,1001) I,(A(1,J),J=1.N.) FORMAT (4HOROW,I4,5E20,8/(8X,5E20,8)) CONTINUE RETURN END		
SIBFTC MPRT PRIF SUBROUTIV SUBROUTIV DIMENSION DO 100 I: WRITE (3: 100 FORMAT (4: 100 CONTINUE RETURN		
	151	

```
SCRF LIST.REF.DECK
SCRF COMPUTES AN NXN SCRIPT F MATRIX (( SCRIPT F(I,J) ))
                                                                                              *ALPHA(20,20),A(20,20),B(20,20),C(20,20),DD(20,20)
                                           SUBROUTINE SCRF (N.NN.RHO.F.AREA.R.D.DI.SF.SFA.IERR)
                                                                             DIMENSION RHO(20,20), F(20,20), AREA(20), R(20,20)
                                                                                                                                                                                                                                                                                                                                                                                                   COMPUTE ABSORBITIVITIES AND EMISSITIVITIES.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       R[J+K+1]+F[1]+K]+F[K+J]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      COMPUTE MATRICES A, B, C, AND
                                                                                                                              , SF (20,20), SFA(20,20)
                                                                                                                                                                                                                                                                                                                                                                                                                                                  ALPHA(I)-1 1 -- RHO(I)
                                                                                                                                                                                                                                 STORAGE REGIONS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       #K(5)*RHO(J,K)
                                                                                                              (New) IO (NEW) O.
                                                                                                                                                                                                                                                DO 120 I=1,400
                                                                                                                                                                                                                                                                                                                                    DO 150 I=1,NN2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      DO 320 K=1.N
WK(5)= R(3.K)
                                                                                                                                                                                                                                                                                                                                                                                                                   DO 210 I=1.N
                                                                                                                                                                                                                                                                                                                                                                                                                                    DO 210 J=1.N
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      M4 [#1 066 00
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        JE JON
                                                                                                                                                                                                                                                                                                    SFA(1,1)= 0.
                                                                                                                                                                                                                                                                  00(1.1)= 0.
                                                                                                                                                                                                                                                                                                                                                    D(I + I) = 0.
                                                                                                                                             **K(10)
                                                                                                                                                                                               NN2= 2=N2
                                                                                                                                                                                                                                                                                                                   CONTINUE
                                                                                                                                                                                                                                                                                                                                                                   CONTINUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                    CONTINUE
                                                                                                                                                                                乙典之 サフド
                                                                                                                                                                                                                 IERR= 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        X(6)#
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      天(3)=
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        MK ( 1 ) =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       00 390
                                                                                                                                                                                                                                   CLEAR
 SIBFIC SCRF
                                                                                                                                                                               100
                                                                                                                                                                                                                                                                                                                                                                                                                    200
                                                                                                                                                                                                                                                                                                                                                                                                                                                                      210
                                                                                                                                                                                                                                                                                                                                                                    150
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      300
                                                                                                                                                                                                                                                                                                                   120
                                                                                                                                                                                                                                   Ú,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        Ų
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WK(7) = WK(5) + ALPHA(J.K)	WK(1)= WK(1) + ALPHA(I,K)+WK(7) WK(2)= WK(2) + ALPHA(I,K)+WK(6) WK(3)= WK(3) + WK(7) WK(4)= WK(4) + WK(6) CONTINUE	A(I,J)= -WK(1) B(I,J)= -WK(2) C(I,J)= WK(3) D(I,J)= -WK(4) IF (I-J) 390,330,390	I=J. DIAGONAL ELEMENTS D(I.J)= 1WK(4) IN PAR D(I.SIN)= 1 CONTINUE	COMPUTE SMALL P. PANNALA P. CALL. MATS (B.DI. M. M. M. LA.)	WRITE (3 FORMAT (ILEMENTS IERR*I CALL VMP		
	320		330	153	410	005 005 500	*****

```
C COMPUTE SCRIPT F MATRIX

600 D0 690 I=1:N

WK= A(1:5)

D0 620 K=1:N

WK= WK + B(1:K)*DD(J:K)

620 CONTINUE

SF(1:5) = -WK

SF(1:5) = -WK

SFA(1:5) = -WK
```

SIBFIC VMPRT LIST.REF.DECK
C VMPRT PRINTS AN MXN ARRAY
SUBROUTINE VMPRT (A.N.)
DIMENSION A(N.N.)
DO 100 1=1.N.
WRITE (3:1001) I:(A(I.J):J=1.N.)
1001 FORMAT (4HOROW:I4:5E20.8/(8X:5E20.8))
100 CONTINUE
RETURN
END

TE DEALN DEPEN	מצי		
4		MRH0 20,20	01,020,7075
01,030.7075	01,040,7283		02,010,1275
02,030.07	02.040.1275		03,010,1275
03,020.07	03,040,1275		1
MF 20,20	02,010.2	03,010.2	03,020.2
04.010.2	04,020.2	04,030.2	04.040.4
	AREA	1 0.25	2 0.25
3 0.25	4 0.75		
MR1 20,20	01,020.07	01,030.07	
	01,030,07	02,030,07	
	C1,020.07	02,011.519	C3 C20.07
			MR4 20,20
01,020.16583	C1+030-16583	02,010.692613	02,030,07
	03,010,692613	03,020.07	
04,010.752091	04,020.13368	04,030,13388	
			GNE

SPECULAR-DIRECTIONAL SCRIPT F PROGRAM (AND 52A), 10/28/64

DIRECTIONAL SPECULAR, ALUM, PAINT

BLACK, BLACK

	RHO(I,J	RHO(I, J) MATRIX			
MOX	-	٥.	0.70750GUDE CO	C. 707506CCE CO	0.72830000E CO
MO	2	Q.12750000E-60	•0	0.7000000 E-01	0.1275000E-00
MQ.	ĸ	0.12750060E-00	0.700C0C0nE-01	•0	0.12750000E-00
2	4	ů	0.	:	••

	F(1,J)	F(I,J) MATRIX			:
S	1	0.	0.20000CC0E-CO	C.2 GC000C0E-00	0.5999999E 00
30	2	0.20000000E-00	•0	0.20000000E-60	0.5999999E 00
ROM	m	0.20000000E-00	0-20000000E-00	0. 0.5999999E 00	0.5999999E 00
20	4	0.20000000E-U0	0.2000000E-00	0.2000000E-00	0.40000000E-00

0.75000000E 00

0.25GCCCCE-CO

0.25000000E-C0

AREA VECTOR 0.25000000E-00

160

		0.7000000000-01	C. 70000000E-01	
ä		0. 70000000E-01	•	3
ö		0-16582999E-00	G. 165829998-00	ó
BEBCK, MO.	:			The same of the sa
ö		•	0.700000000-01	
•		.0	C. 70000000E-01	•
3	0.151899998 01	• • •	•	•
3	0.69261300E 00	•0	0. 7000000E-01	•
BLBCN MG.	m	*		
ö		0.700000000-01	3	6
	0.15189999E 01	••	ċ	•
•		0.7000000000-01	4	
•	0.692613COE 00	0. 70000000E-01	8	•
	4			
ö		0.16582996-00	0.165829996-00	ò

R(I, J,K) ARRAY

ROM	7	0.69261390E UC	.0	C. 7000006E-01	0.
MON	9	0,69261300E 00	G.70000CC0E-01	• 0	•
ROM	4	0.75209160E U0	0.13388000E-00	0.133880C0E-C0	0.



			0.52C23C36E-01 0.43687483E-02 0.21963776E-00	0.52023036E-01	0.17548605E-00
P.O.	-	0.48790440E-03	i	0.21963776E-00	
8	7	0.52221070E-01	0-21963776E-00		0.60985991E 00
2	m	0.522210706-01		0.43687482E-02	0.60985991E 00
2	4	0.58681963E-01	0.20385623E-00	C. 20385623E-00	0.53362094E 00

	SCRIPT	SCRIPT FA MATRIX			
ROM	1	0.12197610E-03	0.13065759E-01	C.13005759E-01	0.43871512E-01
ROM	2	0.13055267E-01	0.10921870E-02	C. 54909441E-01	0.15246497E-00
MQ.	ю	0.13055267E-01	0.54909441E-01	C-10921870E-02	0.15246497E-00
R-ON	4	0.44011472E-01	0.15289217E-00	0.15289217E-00	0.40021570E-00



APPENDIX IV EXPERIMENTAL DATA— RADIATION EXCHANGE EXPERIMENT



The experimental data used in the verification of the analytical techniques described in Section 6 are shown in Table 15. The predicted receiver temperature was calculated from a heat balance between the surfaces of the experimental enclosure. The heat balance equation for the receiver is

$$A_{S} \tilde{S}_{S-R} \left(\sigma T_{S}^{4} - \sigma T_{R}^{4} \right) + A_{M} \tilde{S}_{M-R} \left(\sigma T_{M}^{4} - \sigma T_{R}^{4} \right) = A_{R} \tilde{S}_{R-O} \left(\sigma T_{R}^{4} - \sigma T_{O}^{4} \right) + Q_{LOSS}$$

$$\sigma T_{R}^{4} = \frac{A_{S} \tilde{S}_{S-R} \sigma T_{S}^{4} + A_{M} \tilde{S}_{M-R} \sigma T_{M}^{4} + A_{R} \tilde{S}_{R-O} \sigma T_{O}^{4} - Q_{LOSS}}{A_{S} \tilde{S}_{S-R} + A_{M} \tilde{S}_{M-R} + A_{R} \tilde{S}_{R-O}}$$

For Configuration 3, run number 7, using the directional analysis to obtain the $\ensuremath{\mathfrak{V}}'s$

$$\sigma T_{R}^{4} = \frac{0.0593(201.84) + 0.0013(62.85) + 0.159(1.0) - 0.57}{0.2196}$$

$$\sigma T_{R}^{4} = 53.0$$

$$T_{R} = 419.4^{\circ}R$$

This temperature can be compared to the experimentally measured value of 428.2°R.

The net heat lost by the source, $\mathbf{Q}_{\mathbf{S}}$, is computed by summing the heat leaving the source and received by each surrounding surface

$$Q_{S-M} = Q_{S-M} + Q_{S-R} + Q_{S-O} + Q_{LOSS}$$

$$Q_{S-M} = A_S \delta_{S-M} \left(\sigma T_S^4 - \sigma T_M^4 \right)$$

$$Q_{S-R} = A_S \delta_{R-S} \left(\sigma T_S^4 - \sigma T_R^4 \right)$$

$$Q_{S-O} = A_S \delta_{R-O} \left(\sigma T_S^4 - \sigma T_O^4 \right)$$



Using the data from Run 7, directional analysis

 $Q_S = 0.0013(201.84 - 62.85) + 0.0593(201.84 - 57.62) + 0.159(201.84 - 1.0)$

 $Q_S = 40.68 \text{ Btu/hr}$

This value compares to the experimental quantity of 41.29 Btu/hr.

As described in Section 6, a guard heater method was used to minimize the extraneous heat losses from each test surface. Figure 38 shows the measured heat losses from a vacuum deposited aluminum coated surface and a 3M black paint coated surface. These results were used to correct the experimentally measured source radiation and in the prediction of the temperature of the receiver temperature.



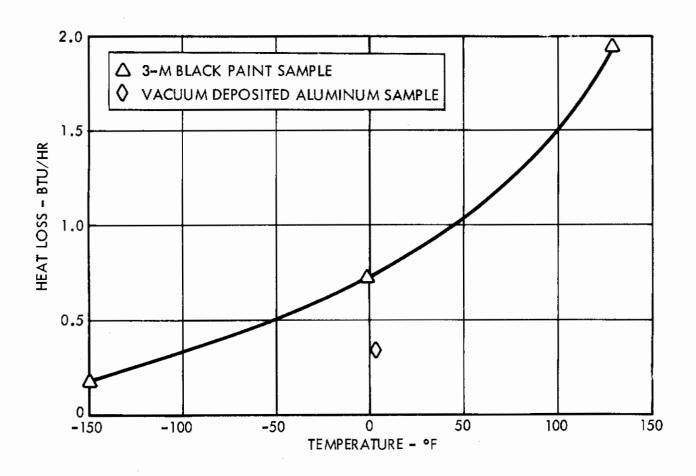


Figure 38. Measured Heat Loss from Test Surfaces of Radiation Experiment



Table 15. Summary of the Data Obtained in the Experimental Testing of the Analytical Prediction

Run Number	1	2	3	4	5
Date	3/18/65	3/19/65	3/19/65	3/23/65	3/4/65
Pressure	4 x 10 ⁻⁶	4×10^{-6}	3×10^{-6}	4 x 10 ⁻⁶	5 x 10 ⁻⁶
Configuration	*	*	*	**	1
Source					
Center T.C OF	129.9	-1,0	-150.9	+4.4	73.8
Corner T.C OF	129.1	-2.5	-151.7	+4. 1	72.2
Guard T.C OF	129.9	-0.3	-147.4	+1.0	73.1
Mirror					
Center T.C OF					
Corner T.C OF					
Guard T.C °F					
Receiver					
Center T.C °F					-114,5
Corner T.C OF					-115.0
Guard T.C OF					-114.8
Source Voltage, volts	50.5	30.4	13,5	6.86	41.11
Source Current, amps	0.276	0.167	0.0776	0.0373	0. 2266

^{*}Single black plate

^{**}Single vacuum deposited aluminum plate



Table 15. Summary of the Data Obtained in the Experimental Testing of the Analytical Prediction (Continued)

Run Number	6	7	8	9	10
Date	3/28/65	4/1/65	4/5/65	4/6/65	4/8/65
Pressure	2×10^{-6}	3 x 10 ⁻⁶	4×10^{-6}	5 x 10 ⁻⁶	7×10^{-6}
Configuration	2	3	4	5	6
Source					
Center T.C OF	124.6	125.8	124.7	125.0	124, 5
Corner T.C OF	124.5	125.8	124.3	124.6	124.1
Guard T.C OF	125.1	125.3	123.7	126.7	125.5
Mirror					
Center T.C OF		-22.4	-51.8	-74.7	-63.5
Corner T.C OF		-22.4	-51.7	-74. 7	-62.6
Guard T. C OF	a.	-23.7	-51.7	-73.5	-60, 3
Receiver					
Center T, C, - OF	-66. 1	-31,0	-36.5	-50.3	-61.3
Corner T.C OF	-66.4	-31.7	-37.0	-50.3	-61.3
Guard T. C OF	-65.4	-24. 4	-35,2	-52.4	-61.7
Source Voltage, volts	48.7	48.0	47.7	47.3	47.4
Source Current, amps	0, 267	0.2635	0.2615	0, 259	0. 2592



APPENDIX V BIBLIOGRAPHY FOR JOINT THERMAL CONDUCTANCE

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APPENDIX V

BIBLIOGRAPHY FOR JOINT THERMAL CONDUCTANCE

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APPENDIX VI COMPONENT JOINT TEST DATA USED FOR CORRELATION TASK



Three experimental tests were conducted to verify the results of the correlation task. The experimental measurements are given in Table 16. The thermocouple locations and data reduction technique are described in Appendix I. The bolt locations for these three tests are shown in Figure 39.



BOLT LOCATION-CORRELATION TASK

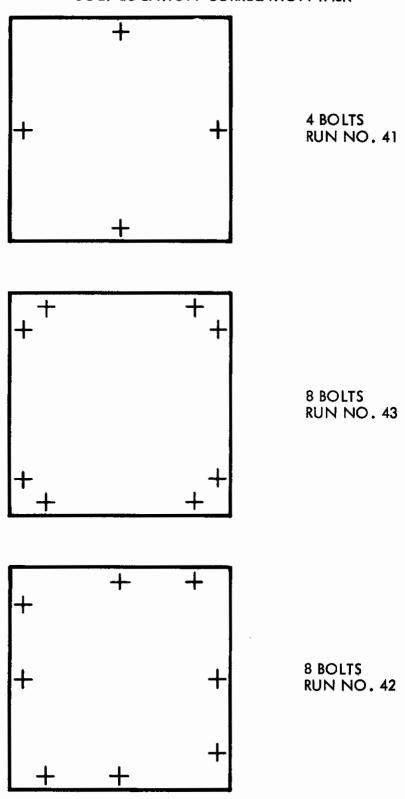


Figure 39. Bolt Locations for Correlation Task Experiments

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Table 16. Additional Component Joint Correlation Data

Run Number	41	42	43
Date	11/24/64	11/25/64	11/25/64
Pressure	5 x 10 ⁻⁷	5 x 10 ⁻⁶	5 x 10 ⁻⁶
Absolute T. C.			
1 - ⁰ F	92.6	88.4	92.7
2 - ^o F	81.8	7 4 . 9	75.0
3 - ^o F	66.6	65.9	66.4
4 - ^O F	67.0	66.4	66.9
Differential T.C.			
1 - °F	17.64	14. 32	18.42
2 - ^o F	17.70	13.93	18.45
3 - °F	11.94	7. 36	10.19
4 - ^o F	7. 46	4. 97	10.59
5 - ^o F	1.80	1.11	9. 44
6 - ^o F	7.80	4. 26	7. 95
7 - ^o F	10.18	3. 26	3.64
8 - ^o F	10.40	2.53	1.61
Voltage, volts	52.96	52. 95	52.95
Current, amps	0.1880	0.1880	0.1880
Water Flow, ml/min	700	575	550
Bolt Torque, in-lb	24	24	24
Filler	None	None	None
Sample Number	3	3	3
Number of Bolts	4	8	8
h, Btu/hr ft ^{2 o} F	13.4	22.0	13.7



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