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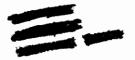
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FOREWORD



This report has been prepared for the United States Air Force by the Flight Research Laboratory, National Research Council of Canada, Ottawa, Ontario, under the sponsorship of the Air Force Flight Dynamics Laboratory, Air Force Systems Command, Wright-Patterson Air Force Base, Ohio. The research was conducted under Contract No. F33615-71-C-1722 to the United States Air Force and under Sub Contract No. S 72-3 to CALSPAN Corporation, Buffalo, New York during the period July 1972 to May 1974.

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The project engineers for each of the participating agencies were T. Neighbor (AFFDL/FGC), D. Key (CALSPAN) and K-H. Doetsch, Jr. (NRC). The assistant project engineer was D.W. Laurie-Lean (NRC). The evaluation pilots were W.S. Hindson (NRC), N.L. Infanti (CALSPAN), D.M. McGregor (NRC) and A.D. Wood (NRC). Digital computer programming was due to D.H. Carter (NRC) and the loan of the TALAR transmitter to G.D. Adams (FAA, NAFEC).

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The report has been reviewed and is approved.

EVARD H. FLINN, Acting Chief Control Criteria Branch Flight Control Division



ABSTRACT

A flight investigation was undertaken of the longitudinal handling qualities of the STOL class of aircraft controlled through the modulation of pitch and normal thrust, and flown on steep, instrument landing approaches at low airspeed. Pilots' assessments of the characteristics resulting from independent variations in both short and long term longitudinal dynamics were obtained.

It was found that the pitch control characteristics dominated the handling qualities. The more easily and precisely pitch could be controlled, the more adverse the control characteristics of the other degrees of freedom the pilot would accept. When precise long-term control of airspeed through pitch modulation was not difficult, the pilots were prepared to tolerate operation well along the backside of the power-required curve. For the typical unaugmented stability characteristics of this class of aircraft, exhibiting small modal separation, the handling qualities were governed by the overall responses to control and disturbance inputs rather than by the location of individual roots of the characteristic equation. This was true even for reasonable short-period characteristics when the stiffness and total damping of the short-term mode was derived to a large extent from the derivative, $Z_{\mathbf{W}}$. Atmospheric turbulence, wind and wind shear often affected the control task significantly during these steep, low-speed approaches.

This report documents comprehensively the configuration characteristics evaluated and the resulting pilots' comments and ratings. It also presents the statistical characteristics of the pilots' control usage during several landing approaches. Analytical considerations which emphasize those aspects of the handling qualities that proved to be of major concern to the pilots are developed.



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LIST OF SYMBOLS

The axis system used in the definition of many of the following symbols and that controlled by the autopilot of the simulator is the right-hand principal axis system of the simulator. The control moments and forces which respectively produce positive (clockwise) initial angular accelerations about and positive initial linear accelerations along these axes are positive.

Symbol	<u>Definition</u>	<u>Units</u>
A_x , A_y , A_z	Accelerations along X, Y, Z axes	ft/sec ²
a_x , a_y , a_z	Acceleration perturbations along X, Y, Z axes	ft/sec ²
В	Pitching moment of inertia of simulator	slug-ft ²
c _r	Lift Coefficient at operating point	
$^{\mathtt{C}}{}_{\mathtt{L}_{_{m{lpha}}}}$	Lift curve slope at operating point	
F	General forcing function (Eq. A-4)	
$F_q(s), F_w(s)$	Fi ter transfer functions for pitch and heave autopilot loops	
$H_u(s), H_v(s), H_w(s)$	Filter transfer functions applied to generate the artificial turbulence components	
H _{uVK} (s), H _{VVK} (s), H _{wVK} (s)	Von Karman filter characteristics to describe atmospheric turbulence components	
h _R	Negative of OZ coordinate of main rotor pivot point	ft



Symbol	<u>Definition</u>	<u>Units</u>
ĥ	Rate of change of height	ft/sec
IMC/VMC	Instrument/Visual meteorological conditions	
К	Gain of crosscoupling term from collective to pitch autopilot loop	
к ₃	Scale Length relating main rotor pitching moments and X-forces	ft
L	(i) Rolling Acceleration	rad/sec ² / unit subscript
	(ii) Integral scale length of	ft
	turbulence (iii) As suffix - pilot station effect	
m	Mass of simulator	slugs
ΔM	Pitching Moment perturbation	ft.1b
М	Pitching Acceleration	rad/sec ² / unit subscript
N	Yawing Acceleration	rad/sec ² / unit subscript
n	Load factor	g
P, Q, R	Rates of roll, pitch and yaw	rad/sec
p, q, r	Perturbations in rates of roll, pitch and yaw	rad/sec
r.m.s.	Root mean square	
S	Laplace's Transform Variable	l/sec
Т	Time interval of sample: Appendix E, Figures 30-35	sec
T ₂	Time to double amplitude	sec
t	Time	sec



Symbol	Definition	<u>Units</u>
U, V, W	Linear velocities along X , Y and Z axes	ft/sec
u, v, w	Perturbations in linear velocities along X, Y and Z axes	ft/sec
X, Y, Z	(i) Principal Axis system(ii) Linear acceleration along axes	ft/sec ² /unit subscript
α	Angle of attack	rad
β	Angle of sideslip	rad
Υ	Flight path angle - positive for climb	rad
Δ	Characteristic Equation of longitudinal equations of motion	
Δt _o	Average dwell time at zero displacement: Appendix E	sec
δa	Pilot's aileron control displacement	ins
δ c	Pilot's collective control displacement	ins
δe	Pilot's elevator control displacement	ins
δr	Pilot's rudder control displacement	ins
Тδ	Pilot's thrust control displacement	ins
ζ	Damping ratio of a second-order linear system	
2ζω	Total damping of a second-order linear system	1/sec
Θ	Pitch attitude	rad
θ	Pitch attitude perturbation	rad
λ_{R}	Roll subsidence root of the lateral-directional characteristic equation	1/sec



Symbol	<u>Definition</u>	Units
λ _S	Spiral root of the lateral-directional characteristic equation	l/sec
σ	Root mean square value	
Φ	Roll attitude	rad
ф	Roll attitude perturbation	rad
φ _{ii} (w)	Input power spectral density	(ft/sec ²)/rad/sec
φ ₀₀ (w)	Output power spectral density	(ft/sec ²)/rad/sec
$\begin{vmatrix} \phi \\ \beta \end{vmatrix}$ DR	Modulus of ratio of roll angle to sideslip angle in dutch roll mode	
ω	 (i) Frequency (ii) Undamped natural frequency of a second order mode specified by a subscript 	rad/sec
ω <mark>2</mark> a	Stiffness characterizing the initial pitch response to elevator	
ω' _{SP}	Equivalent short-period frequency obtained with the assumption $\theta_0 = 0$	rad/sec
Prefices		
A	Attitude Command Form	
R	Rate Command Form	
Subscripts		
AERO	From Aerodynamic sources	
DR	Dutch roll mode	
F	Total equivalent fuselage contribution	



Subscripts	
f	Component of fuselage contribution
g	Gust disturbance
Н	Basic helicopter
HF	High Frequency
LF	Low Frequency
R	Main Rotor
М	Model
MIX	Composite inertial-air data quantity
PH	Phugoid Mode
p	Pilot's control
s	Control surface
SAS	Contribution from stability augmentation system
SP	Short-period
ss	Steady state
ST	Short-term
0	Fixed operating point condition

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Contrails

Contrails

1.0 INTRODUCTION

The reduction in approach speeds and the increase in approach glide-slopes that became possible with the advent of the STOL class of aircraft through the use of 'powered' lift to supplement the aerodynamically generated lift, were not attained without accompanying changes in the handling qualities of the aircraft. Many of these changes were, moreover, for the worse and such specifications as those in MIL-F-83300 (Ref. 1) were established to limit the deterioration to levels that remained acceptable to the pilot. Unfortunately, many of the data used in the formulation of these requirements, described in Ref. 2, were, of necessity, derived from the extrapolation of data applicable to CTOL aircraft obtained under quite different operating conditions. This deficiency was recognized from the outset of the formulation of the requirements and, to remedy the resulting weaknesses, the present investigation was undertaken to provide new data of a general nature from in-flight evaluations of typical STOL configurations operating under conditions of instrument approaches at low airspeed and steep approach angle down to weather minimums.

Some of the differences in handling qualities are directly attributable to the change in airspeed. Trajectory control takes on added significance, not only because of changes in the inherent dynamic characteristics resulting from lower approach speeds, but also because the external



environment (wind, wind shear and turbulence) has greater influence on the aircraft's trajectory (Ref. 3). Furthermore, at low airspeeds, the separation between the short-period and phugoid modes for aircraft without stability augmentation is often diminished so that classical assumptions used in the calculation of the root locations of these modes may no longer remain valid. This is particularly true when the short-period mode, instead of exhibiting its customary complex form, is composed of widely separated aperiodic roots. The question is then raised of whether, in these circumstances, the characteristic modes of motion remain as sensitive indicators of the ensuing handling qualities.

In order to assess the relative importance of some of these factors experimentally, the various interacting parameters were first decoupled to the greatest extent possible so that pilots' evaluations of single parametric variations in longitudinal dynamic characteristics could be obtained. Interaction between parameters was then allowed so that its influence on the pilot's control task could be ascertained.

Specifically, the following were investigated:

- i Short-Period characteristics
- ii Speed and Flight Path control characteristics in the presence of good, augmented pitch characteristics
- iii Speed and Flight Path control characteristics



in the presence of typical unaugmented STOL pitch characteristics

iv Effect of the speed stability derivative M_{11}

v Effect of $Z_{\delta e}/M_{\delta e}$

vi Effect of $M_{\delta T}/Z_{\delta T}$.

All evaluations were undertaken with an airborne simulator flown at an airspeed of 60 knots under instrument conditions down an 8° glide path to 200 ft A.G.L. prior to visual acquisition of the touch down point. The pilot's instrument display was deliberately rudimentary in keeping with the aims of obtaining basic handling qualities data.

In the following chapters a complete documentation of the experiment and its constraints has been attempted to allow the widespread use of the data in analyses made from different points of view.



2.0 TEST EQUIPMENT AND EVALUATION TASK

2.1 Simulator

The simulator utilized, based on a Bell 47G-3Bl helicopter, is described in some detail in Ref. 4. Since that report was written, several changes of importance to the present investigation have been made, namely:

- i The removal of the horizontal stabilizer
- ii Changes in the control forms and improvements in the performance of the pitch and heave autopilot loops
- iii The incorporation of electro-hydraulic forcefeel systems for the evaluation pilot's elevator, aileron and rudder controls
 - iv The incorporation of a special-purpose onboard computer to allow the calculation with both high fidelity and high signal-to-noise ratio, of the linear motion of the simulator's centre of gravity relative to the long wavelength components of the airmass.

The influence of these changes is considered in detail in the appropriate portions of the text.

In concept, the simulator uses a model-following technique on four of the six degrees of freedom, the rotary motions in pitch, roll and yaw and the linear motion in heave.

The fore-and-aft and transverse linear motions cannot be



controlled independently and are governed by the inherent characteristics of the simulator as modified by the cross-coupling terms resulting from the closure of the four controlled loops.

Details of the simulation are presented in Appendix A with discussions of the simulator and model equations of motion and of the form of the autopilot loop closures.

2.1.1 Cockpit

The simulator is occupied by two pilots, the safety pilot who sets up the configurations and monitors the safety of the evaluation, and the evaluation pilot who assesses the configurations.

For the present investigation, the evaluation pilot's instrument display, illustrated in Figure 1, was conventional and rudimentary. Available to present him with aircraft state information were, from left to right in this figure:

Top row Thrust lever position indicator

Airspeed indicator

Combined attitude and flight-

path indicator

Altimeter

2nd row Engine Manifold pressure from

82% to 100%

Turn and Slip Indicator



Direction Indicator Vertical Speed Indicator.

A translucent white screen which could be rapidly raised or lowered by the evaluation pilot, served to obliterate all outside visual references when he was flying on instruments.

The evaluation pilot's controls consisted of a central stick and rudder pedals for controlling rotary motions and of a thrust lever, in a conventional left-hand throttle-quadrant format, to control the normal thrust of the configuration. The simulator's engine speed was governed to maintain constant rotor rpm. The evaluation pilot's controls, through an onboard computer, commanded the appropriate motion of the simulator for the configuration being evaluated.

Electro-hydraulic force-feel systems for the pilot's stick and rudder controls allowed desirable force-displacement characteristics to be presented to the pilot. The characteristics chosen are described in Appendix B and tabulated in Figure 2.

2.1.2 Motion Sensing System

To define the motion of the simulator, measurements were made of rotary rates, attitudes, linear accelerations and linear velocities, the latter relative to the airmass. All measurements were referred to the principal axes of the simulator. The linear velocities, which were required either as feedback in the model equations of motion or in the heave autopilot



loop, are normally subject to fluctuations arising from external turbulence or from wind shear. Both the pitotstatic system and the α and β -vanes used in the experiment as prime velocity sensors responded to these external disturbances and, in order that the effects of the latter's shorter wavelength components on the simulator's motion could be alleviated, a complementary filter arrangement which mixed inertial data with air data was utilized. The ensuing velocity data may be considered as aircraft inertial data washed out at low frequency to airmass reference frame data. The major advantage of the system was that the influence of short-wavelength external disturbances or position errors on the velocity data was filtered out, thereby allowing a much improved signal-to-noise ratio, whilst the aircraft still responded to the long wavelength changes in the airmass frame of reference relative to the ground. This latter condition is necessary when it is not possible, as in the present experiment, to control all the linear-motion degrees of freedom and when engine power limitations are such that complete alleviation of long wavelength components of large amplitude is not feasible along the controlled degree of freedom. Further details of the air data sensing system, as it affected the heave autopilot loop, are given in Appendix A.

The inertial data were sensed by a strap-down system of attitude and rate gyros and linear accelerometers.

Contrails

2.1.3 Parameters Recorded

Recorded continuously on magnetic tape during evaluations were the following quantities:

- i Pilot's comments
- ii Glide slope tracking error
- iii Localizer tracking error
- iv Longitudinal velocity, $U_{\rm H}$
- v Normal velocity, w_H
- vi Normal acceleration, a_{z_H}
- vii Pitch attitude, θ_H
- viii Pitch rate, q_H
 - ix Commanded normal velocity, $\mathbf{w}_{\mathbf{M}}$
 - x Commanded pitch rate, q_M
 - xi Evaluation pilot's elevator input, δe
- xii Evaluation pilot's thrust lever input, δT
- xiii Longitudinal component of artificial turbulence, u_g
- xiv Normal component of artificial turbulence, $\mathbf{w}_{\mathbf{g}}$.

2.1.4 Artificial Turbulence Generation

In efforts to define better the disturbing influences on the simulator, evaluations were made in conditions characterized by both low external turbulence and mean



winds. Typical turbulence disturbance levels were then artificially created through the excitation of the model equations of motion with the output of three independent, onboard turbulence generators producing gust components with the Von Karman spectral shape and a normal distribution.

The form of the implementation is discussed in Appendix C.

No artificial mean winds or wind shears were simulated.
2.1.5 Simulator Performance

A discussion of the ability of the autopilot loops in pitch and heave to ensure that the simulator followed the motions commanded by the model equations of motion is presented in Appendix A.

The remaining question to be resolved is whether the estimates of fuselage X-forces were adequate to obtain the predicted modal motion. An attempt to verify this point was made by exciting a ground-based simulation of the model with the pilot's inputs recorded in flight during the evaluation of the same configuration. This technique is not entirely satisfactory for the class of configurations evaluated, characterized as they are by low total stiffness, because very small biases or the pilot's inputs to counteract the influence of unrecorded external disturbances or lateral-directional inputs, can result in large long-term responses.

The comparisons are presented in Figures 4 to 7 for four configurations, the first with no longitudinal velocity feedback to the equations of motion and the others with



differing degrees of feedback. It is seen that, even with the above mentioned proviso, good motion following was obtained. Further discussion of these comparisons is presented in Appendix D.

2.2 Ground Guidance Aid

To provide guidance during the base and final legs of the approach phase a High-Angle TALAR Transmitter, Model IV, was utilized. Calibration against a theodolite indicated that when set to the 8° glide slope of the experiment, the narrow-beam width limits were given by

Glide Slope +3°, -2.5°

Localizer ±3°.

The full scale deflections of the aircraft's receiver corresponded to these angular deviations from the centre of the guidance beam.

The specifications for the transmitter indicate a localizer coverage at 2 n.m. of $\pm 55^{\circ}$ when on glide path.

2.3 The Pilots

Four pilots participated in the evaluations:

A D.M. McGregor NRC

B W.S. Hindson NRC

C A.D. Wood NRC

D N.L. Infanti CALSPAN

Each pilot has accumulated considerable experience relevant to evaluating the class of aircraft being investigated, both Contrails

in aircraft and airborne simulators.

The pilots were allowed as much preliminary flying as they felt necessary to familiarize themselves with the task and instrument crosscheck. About four hours (12 complete circuits) were opted for. In retrospect, it was felt that the learning process probably required longer than this period, a figure of 10 hours being suggested as appropriate by one pilot. It was also important for the pilots to remain current on the task, a refamiliarization flight being required after their not having flown the task for a period of about three weeks.

Three evaluations per flight hour could normally be undertaken and the workload was such that the pilots generally reached their saturation point after six evaluations in any one day.

2.4 Configuration Evaluation Task

The task, detailed in Figure 8, consisted essentially of a VMC circuit and an IMC approach down from 1900 feet using a TALAR, microwave approach-aid set up for a nominal approach angle of 8 degrees. The evaluation pilot "broke-out" to VMC conditions at a height of 200 feet and performed a transition manoeuvre into horizontal flight at 10 feet above a marked touchdown point and at an airspeed of 60 km. ts.

The touchdown point was situated 200 feet upwind of the TALAR transmitter.

The purpose of the VMC portion of the task was



primarily to position the simulator for the IMC approach task and to enable the evaluation pilot to learn something of the characteristics of the configuration being simulated.

The sequence of events in an evaluation flight was as follows:

VMC - Turbulence Out

- (1) The safety pilot adjusted the cockpit potentiometers and function switches that determined the magnitude
 and sign of the stability derivatives for the configuration
 being simulated.
- (2) With the aircraft still on the ground the safety pilot excited the simulation model with sequential, artifically produced, electrical elevator and thrust control doublets. The recorded model responses were later compared with ones obtained in a laboratory ground-simulation in order to determine whether the model had been set correctly.
- (3) The previous model of the flight was identified for the record on magnetic tape and on the evaluation pilot's comment sheet. This was the first time that the evaluation pilot was informed of the identity of the model he had previously evaluated.
- (4) The safety pilot flew the simulator to a height of 500 feet above the ground and established an airspeed of 60 knots in level flight. The autopilot was engaged and the analogue computer was switched to the "operate" mode. At this point, the evaluation pilot assumed full control of the

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aircraft under visual conditions with the artificial turbulence switched out.

- (5) The evaluation pilot flew the aircraft straight ahead at 50 knots up to an altitude of 2000 feet, made a left turn onto the crosswind leg and continued to climb to the downwind leg.
- (6) A left turn was made onto the downwind leg and, at 2300 feet, the aircraft was levelled off and its airspeed increased to 60 knots.
- (7) When steady conditions were established, a descent was made to 1900 feet at 500 fpm and at an airspeed of 60 knots. This manoeuvre enabled the evaluation pilot to assess the ease of establishing and maintaining desired vertical and longitudinal velocities.
- (8) Back in level flight at 1900 feet, the evaluation pilot undertook a series of linked turns through heading changes of 60 degrees, -120 degrees, 120 degrees and -60 degrees back onto the downwind leg. The bank angle in the turns was no greater than 20 degrees. The purpose of the turns was to permit the pilot to assess the thrust requirements of the configuration in turning flight.

IMC - Turbulence Out

(9) As he drew level with the TALAR transmitter, the evaluation pilot pulled up the screen on top of the instrument panel to remove all external visual cues, and commenced flight under instrument conditions. When he had stabilized



the aircraft, he increased the airspeed to 70 knots.

IMC - Turbulence In

- (10) The safety pilot provided information as to when to commence the turn onto the base-leg, which allowed a suitable 90° track to the approach to be followed. He also switched in the artificial turbulence at that point.
- (11) The turn onto the base-leg was made with a maximum bank angle of 20 degrees and the speed was reduced to 60 knots in the turn. Subsequent guidance to the breakout height of 200 feet was provided by the TALAR unit.

VMC - Turbulence In

- (12) At 200 feet, the evaluation pilot lowered the cockpit screen and returned to visual flight conditions. He then performed a transition manoeuvre from the glide-path to arrive at 10 feet over the marked touchdown point, at 60 knots in level flight.
- (13) The safety pilot took control and landed the simulator. While the safety pilot set up the next configuration, the evaluation pilot documented his comments concerning the configuration characteristics on the pilot's comment sheet, shown in Figure 9, and gave a subjective rating according to the Cooper-Harper scale shown in Figure 10.

In addition to the above mentioned ratings of handling qualities, Pilot B also gave a subjective rating of the influence of turbulence according to the scale presented in Figure 11 (source: CALSPAN). This rating follows his

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numerical rating of the configuration in Table III.



3.0 CONTROLLED AND UNCONTROLLED CONSTRAINTS ON THE SIMULATOR MOTION

The following chapter is concerned both with those aspects of simulator motion which could be directly controlled and with those which were uncontrollable because of either simulator limitations or influences of the external environment.

3.1 Equations of Motion

The equations governing the simulator motion and the implementation of the model equations of motion are described in detail in Appendix A.

3.1.1 Controlled Degrees of Freedom

Two of the three degrees of freedom of importance to the longitudinal dynamics (heave and pitch) could be controlled independently whereas that of the fore-and-aft motion was dependent on the motion in the other degrees of freedom and on external atmospheric conditions.

The desired variations in pitching motion were obtained through the response derivatives.

$$M_{u}$$
, M_{w} , M_{\bullet} , M_{q} , M_{θ} ,

and the pilot's control derivatives, $\text{M}_{\delta\,\text{e}}$ and $\text{M}_{\delta\,\text{T}}.$

In the heave equation of motion, variations were made through the response derivatives,

$$Z_u$$
, Z_w , Z_q and Z_θ ,

and the pilot's control derivatives, $\mathbf{Z}_{\delta T}$ and $\mathbf{Z}_{\delta e}$.

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No physically unrealistic values for derivatives were allowed and this resulted in the imposition of the following additional constraints:

$$M_{q} < 0$$

$$\frac{UM_{w}}{M_{q}} < 1.0$$

$$\frac{Z_{u}}{Z_{w}} \le 1.2$$

$$Z_{u} \le 0$$

$$Z_{\delta \theta} \ge 0.$$

The evaluation pilot's control sensitivities, $M_{\delta e}$ and $Z_{\delta T}$, were established initially on the basis of the magnitude of M_q + $M_{\dot{\alpha}}$ and Z_w respectively. The sensitivities so obtained were subsequently adjusted on the basis of pertinent pilots' comments made during the first few evaluations. If the ensuing preset levels still did not coincide with his desires, the pilot was free to alter the sensitivities at any time during an evaluation. The pilots made little use of this option as, quite often, if the response to controls was of concern, it was because the aircraft's dynamic characteristics were such that a compromise gearing between satisfactory initial and final responses to control inputs needed to be selected. The optimum sensitivity in these circumstances was not well defined.



The control sensitivities selected or accepted by the pilots are documented with their comments in Table III, along with any changes made by the pilot from the original setting.

3.1.2 The Dependent Fore-and-Aft Degree of Freedom

No means existed, in the simulator utilized, of varying the longitudinal force characteristics independently. The closed-loop response in this degree of freedom could, however, be formulated in terms of the demanded pitching motion and of the fuselage contributions to the longitudinal forces, as is shown in Appendix A.

With the modulation of the thrust vector by the autopilot in the longitudinal plane to produce the desired pitch and heave motions, the only suitable means available to the pilot of controlling long-term airspeed variations of the simulator was through pitch modulation. The geometric and inertial characteristics of the simulator were such that the force component at the rotor hub, required to produce the desired pitching accelerations, did not have a significant influence on the long-term variations in airspeed when compared with that due to the gravitational component mg0. The aerodynamic reaction forces significant to the long-term control of airspeed all originated from the fuselage longitudinal force and pitching moment derivatives and resulted in rather low closed-loop drag characteristics for the class of aircraft being simulated.



As far as the pilot was concerned, when he was flying configurations with reasonable flight-path control characteristics, the influence of the drag characteristics was most apparent in the sensitivity of trim speed to attitude changes and in the time constant associated with attaining these speed changes. For pitch modulation at constant angle of attack with the simulator in question, the steady state speed variation was about 8 knots per degree and the associated time constant was approximately 25 seconds.

Comments were made by the pilots about this high sensitivity of trim speed to pitch attitude, particularly when precise control of long-term pitch variations was difficult.

and attitude on the pilot's assessments of handling qualities will have to await further experimental investigation in simulators capable of producing more significant drag forces. However, it is to be noted that even with the existing harmony, many pilots' ratings of 3 were attained in this programme when easily controlled pitching characteristics prevailed and when the control task was not complicated by operation on the 'backside' of the power-required curve.

3.1.3 The Effect of the Steady-State Pitch Attitude of the Simulator

The steady-state pitch attitude of the principal axis system being controlled can have a significant influence on the longitudinal characteristic modes when the overall



stiffness becomes low. (For the loading condition of the simulator, the pitch attitude in straight and level flight at 60 knots was -7°.) Its influence is seen clearly in the root loci as $-M_{_{\!\!\!M}}$ is reduced. When the resulting stiffness thereby becomes low, the singularity at the origin for zero θ_{0} (and for $M_{11} = Z_{11} = 0$) moves away from the origin when θ_{0} is varied. Coupled with this movement one finds complementary movements in the short-period roots which indicate that variations in θ_0 primarily result in a redistribution of the damping between the modes. In these circumstances, and when the characteristic equation is composed of four aperiodic roots (one of these, associated with the phugoid mode, remains at X_u for M_u = Z_u = 0), it no longer remains obvious which combination of two of the remaining three aperiodic roots should be used to generate an equivalent overdamped second order pair to define the short-term mode. Possible ambiguity could thereby result in configuration classification.

Current requirements necessitate a separation of the modes into long and short-term pairs to establish conformity. Difficulty is foreseen in uniquely demonstrating compliance with the requirements in these circumstances.

To help assess the influence of non-zero θ_0 on handling qualities, it is noted that the movement from the origin of one characteristic root through θ_0 variations is complemented by movement in the opposite direction by another. The total damping of these roots remains much the same and



the effect on handling qualities is probably not significant for moderate values of $\theta_{_{0}}$. This premise is made on the basis of the effect of a similar and marked sensitivity of the root loci to $\mathbf{M}_{_{\mathbf{U}}}$ variations for these configurations with low short-term stiffness. In evaluations of such configurations differing only in their values of $\mathbf{M}_{_{\mathbf{U}}}$, the pilot was able to redistribute the damping between the modes without discernible effect on his assessments of the ensuing handling qualities.

3.1.4 Thrust Control Direction

The autopilot loops used for controlling the motion of the simulator ensure that the thrust vector over which the evaluation pilot has control, acts along the normal axis of the aircraft when neither pitching nor rolling accelerations are demanded. For the conditions of the experiment, this meant that the thrust vector remained essentially normal to the flight path of the aircraft.

STOL aircraft are typified by resultant thrust vector inclinations that lie somewhere between this direction and that along the flight path, and consideration thus needs to be given to the constraint imposed by the thrust inclination of this experiment.

The influence of thrust vector inclination depends primarily on three factors, namely on the velocity component (airspeed or rate of change of height) being controlled by thrust modulation, on the availability to the pilot of independent control over both thrust magnitude and inclination,



and on the ease and precision with which undesired velocity responses to thrust vector variations may be compensated for through pitch modulation. Details are presented in Ref. 3 of the pitch modulation necessary to constrain one velocity component to the desired constant level while the other is being changed by variations in the thrust vector. Under these conditions, it is shown that the time constant associated with attaining a change in the velocity component controlled by thrust is independent of the thrust inclination. However, the pitch compensation demanded is dependent on thrust inclination and, not surprisingly, a near normal thrust vector reduces the necessary pitch modulation when thrust controls rate of change of height, whereas a near longitudinal one does so when thrust controls longitudinal velocity.

If pitch attitude can be easily and precisely controlled, the modulation required to compensate for undesired changes in trim condition caused by thrust variations probably does not play an important role in the ensuing handling qualities. However, as control of pitch becomes more difficult, the need to compensate continually for thrust changes may add significantly to the pilot's workload and lead to a deterioration in his performance.

3.1.5 Pilot-Station Effects (Configurations denoted by L)

It is likely that the pilots of STOL aircraft will be seated further forward of the centre of gravity of the aircraft than in the simulator used in this experiment.

In order to assess the influence of motion cues resulting from a forward pilot's station, the effect of being 25 ft in front of the centre of gravity (designated by L in configuration identifiers) was simulated during many evaluations. In general, the differences in ratings and commentaries resulting for the same configuration with either the simulated station of 25 ft or the actual station of 3 ft ahead of the centre of gravity were insignificant.

The lateral forces arising from a forward pilot's station could not be simulated as no means of independently varying the side-force characteristics of the simulator existed.

3.1.6 Effect of Turning

The most significant long-term forcing function of the longitudinal equations of motion from the lateral-directional planes probably results during turning manoeuvres and, for this reason, deliberate turning manoeuvres were incorporated into the task. With airspeed maintained through control of pitch attitude, the additional thrust required in turns to maintain height is primarily a function of bank angle. If no thrust inputs are made, however, the steady rate of descent, for small $X_{\rm W}$ and a given bank angle, becomes inversely proportional to $-Z_{\rm W}$. Quite significant descent rates can result for small $-Z_{\rm W}$ and moderate bank angles if no compensating thrust is applied, for example, 500 fpm for a bank angle of 20° and $Z_{\rm W}$ of -0.25.



3.1.7 Lateral-Directional Characteristics

It was intended that the pilot be presented with lateral-directional characteristics which were representative of the class of aircraft being investigated but which were, in addition, unobtrusive in order that attention could be focussed on the longitudinal characteristics. For this reason, one of the better configurations of a previous investigation (LH 100+30+30, Ref. 5) was selected for the entire programme.

The characteristic roots were

$$\lambda_{R} = -4 \frac{1}{\text{sec}},$$

$$\lambda_{S} = 0,$$

$$\omega_{DR} = 1.0 \text{ rad/sec},$$

$$\zeta_{DR} = 0.3,$$

$$\left|\frac{\phi}{\beta}\right|_{DR} = 0.2.$$

The dutch roll mode was not excited by application of aileron control.

The non-zero derivatives used to obtain these characteristics were

$$\frac{N_{\delta a}}{L_{\delta a}} = 0.2$$
, $N_{r} = -.63$, $N_{p} = 1.06$, $N_{\beta} = 1.14$
 $L_{r} = .41$, $L_{p} = -3.9$, $L_{\beta} = -.75$
 $Y_{r} = .95$, $Y_{p} = -4.34$, $Y_{\beta} = -5.48$

Finally, the pilot's control sensitivities were

 $L_{\delta a} = 0.5$, $N_{\delta r} = 0.6$ to F1. No. 102 , = 0.4 after F1. No. 102 .

The change in rudder control sensitivity was made because
Pilot A felt that control harmony would thereby be improved.
The long-term responses were considered by him to be somewhat too great at the higher sensitivity level.

3.2 External Environment

As the simulator is flown in the real environment, the influence of atmospheric conditions on evaluations needs to be discussed.

3.2.1 Mean Winds and Wind Shear

The ground approach aid presents data to the pilot in an earth-fixed frame of reference whereas he is required to fly the aircraft at a prescribed airspeed. With the decreased approach speeds typifying STOL aircraft, the normal wind fluctuations encountered in the lower atmosphere take on added significance through their influence on the control of the final approach phase. The major effects are seen in the need to correct for airspeed changes and in the requirement to change the rate of descent and heading in order to maintain the earth-fixed trajectory whenever variations in wind that are a significant proportion of airspeed occur.

To limit these influences, evaluations were in general



not undertaken in surface winds greater than 10-15 knots. Even with this restriction, rates of descent over extended periods of between 400 fpm and 1500 fpm about a nominal zero-wind value of 850 fpm were reported by the pilots to result from wind and wind shear. In view of these variations, it was decided that the effect of limiting the maximum descent angle could not be investigated satisfactorily in this experiment.

The lateral wind shear encountered by the pilots was also cause for frequent comment and the attention required to counteract its effects on ground track could contribute significantly to the difficulty of controlling configurations with undesirable longitudinal handling qualities.

3.2.2 External Turbulence

In order to alleviate the influence of external turbulence on the motion of the simulator, velocity feedback signals to the autopilot or model equations of motion were composite mixed inertial-air data signals as described in Section 2.1. Despite the attributes of this system, engine power limitations did impose a constraint on evaluations whenever large scale convective instabilities predominated.

Estimates of the magnitude of surface wind, wind shear and external turbulence were made by the pilots for each evaluation and recorded with their comments.



4.0 CONFIGURATION MATRIX EVALUATED

For the purposes of classification, the evaluations undertaken have been grouped so as to illustrate the influence of certain parametric variations of known importance to longitudinal handling qualities. In general, the variations were made first to illustrate the influence of given parameters when the others of known significance were held to unobtrusive levels and then, in order to assess the influence of parametric interactions, these secondary parameters were allowed to take on added significance whilst variations in the primary parameters were made.

The configuration matrix which evolved is illustrated in Figure 12, the derivatives in Table I and the primary modal characteristics in Table II.

A brief discussion of the resulting grouping is given in the following section, and a more detailed appraisal is given in Section 5 prior to the assessment of the pilots' comments for each group of parametric variations.

GROUP I Short-Period Characteristics

The effect of varying the stiffness and total damping of the short-period mode for various levels of $\mathbf{Z}_{\mathbf{W}}$ was investigated. For this group the phugoid roots were maintained nearly constant through $\mathbf{Z}_{\mathbf{U}} = \mathbf{M}_{\mathbf{U}} = \mathbf{0}$ as may be seen from Table II. The configurations were all operated on the 'frontside' of the power-required curve.



GROUP II Variations of Flight-Path Characteristics in the Presence of Good Pitch Control Characteristics

Several of the configurations of Group I were stabilized through a simple pitch stability augmentation system to ease the pilot's pitch control task. Variations were made in the force characteristics through $\mathbf{Z}_{\mathbf{u}}$ and $\mathbf{Z}_{\mathbf{w}}$ in order to investigate operation on the 'backside' of the power-required curve. Both pitch attitude and rate command forms were investigated.

GROUP III Simultaneous Variations in Both Short and Long-Term Characteristics through $\mathbf{Z}_{\mathbf{u}}$

The pitch stability augmentation of Group II was removed and an investigation of configurations exhibiting both the resulting poor (low stiffness and/or damping) pitch characteristics and 'backside' operation was undertaken.

GROUP IV Simultaneous Variations in Both Short and Long-Term Characteristics through $\mathbf{M}_{\mathbf{u}}$

The influence of the speed stability derivative on the configurations of Group III was assessed.

GROUP V Effect of non-zero $Z_{\delta e}/M_{\delta e}$ on Selected Configurations

The effect of realistic changes in lift expected with pitching moment production was investigated on configurations both with and without pitch stability augmentation.

One basic configuration was chosen to investigate typical variations in the thrust offset effect on the pilot's

assessment of handling qualities.



5.0 ANALYTICAL CONSIDERATIONS AND PILOTS' ASSESSMENTS OF CONFIGURATION CHARACTERISTICS

Each of the groups of configurations detailed in the previous section is considered from an analytical point of view. The analytical results are then compared with the pilots' assessments of the appropriate handling qualities.

The pilot's elevator control usage during evaluations of representative configurations was also analyzed statistically to provide an indication of the sensitivity of the power spectral density and amplitude distributions to such changes in handling qualities that demanded different levels of compensation from the pilot. A discussion of this aspect is presented in Section 5.7 and Appendix E.

With regard to the terminology used in subsequent sections of the report, the short-term mode is, as in Ref. 2, considered to be the second-order mode that primarily determines the short-term response of angle of attack to an abrupt elevator input. The short-period approximation t this mode is the second-order solution which would result if the influence of longitudinal velocity perturbations on the short-term mode were negligible.

5.1 GROUP I Short-Period Characteristics

The short-term characteristics to be evaluated in this group were established by constraining the total damping of the characteristic modes to the desired level for different values of \mathbf{Z}_{w} and by then obtaining the appropriate short-

period stiffness through variations in $\mathbf{M}_{\mathbf{w}}$.

In order to achieve decoupling between the longitudinal velocity perturbations and the pitching moments and normal forces, M_u and Z_u were held at zero (this makes the short-period and short-term modes identical). The influence of the coupling derivatives M_u and Z_u was subsequently assessed to determine their effect on speed and flight path control, and is discussed in following sections of the report. The level of M_w , which can have an important effect on the aircraft responses, was fixed at realistic values of either $UM_w^* = 0.76 \ M_q$ or $UM_w^* = 0.5 \ M_q$.

The non-zero θ_0 which, in the simulator used, could not be independently varied, establishes a non-zero root in the characteristic equations for this group of configurations. For the configurations with low stiffness, this results in the possibility of multiple choices for the grouping of two of three aperiodic roots to be combined to define the short-term stiffness. In these circumstances the concept of short-term stiffness in itself is somewhat artificial and, in order to provide a consistent measure which merges smoothly into the unique values resulting in the presence of complex roots well separated from the phugoid roots, the value to be used for short-period stiffness is here further restricted through the definition

$$\omega_{\text{SP}}^{\text{r2}} = \omega_{\text{SP}}^{2} \Big|_{\theta_{\text{O}}} = 0$$
.



For Group I, the constraints $M_u=Z_u=\theta_o=0$ result in a real root at the origin and a real root at - .04 for all configurations. These two roots are identified as the phugoid or low frequency pair.

5.1.1 Analytical Considerations

It becomes apparent from a study of the pilots' comments that the prime concern of a pilot when faced with low short-term stiffness is the control of pitch attitude with elevator. The θ/δ_e (s) transfer function should thus provide a sensitive indication of the source of the pilot's difficulty. For $M_u = Z_u = M_\theta = Z_{\delta e} = 0$ and $\theta_o = 0$ (applied for consistency with the assumption used in the definition of the stiffness), one obtains the following well known short-period approximation:

$$\frac{q}{M_{\delta}e^{\delta e}} (s) = \frac{s - Z_{w}}{s^{2} - (M_{q} + UM_{w}^{\bullet} + Z_{w})s - (UM_{w} - M_{q}Z_{w})}$$
(1)

$$= \frac{s - Z_W}{s^2 + 2\zeta_{SP} \omega_{SP}^{i} s + \omega_{SP}^{i2}}$$
 (2)

In order to obtain a better understanding of the terms influencing the initial pitch response to elevator inputs, Equation 2 is expanded about the zero location to give (Ref. 3),

$$\frac{q}{M_{\delta e}^{\delta e}}(s) = \frac{1}{s^2 + 2\zeta_A \omega_A s + \omega_A^2} \left[s - \frac{Z_W \omega_A^2}{s^2 + 2\zeta_{SP} \omega_{SP}^! s + \omega_{SP}^{!2}} \right],$$
(3)

where
$$2\zeta_{A} \omega_{A} = 2\zeta_{SP} \omega_{SP}^{\dagger} + Z_{W}$$

$$= - (M_{q} + UM_{W}^{\bullet})$$
(4)

and
$$\omega_{A}^{2} = \omega_{SP}^{*2} + 2\zeta_{A} \omega_{A} Z_{W}$$

$$= -U(M_{W} + M_{W}^{*} Z_{W})$$
(5)

If the high-frequency pitch response is approximated by

$$\frac{q_{HF}}{M_{\delta e} \delta e} (s) = \frac{s}{s^2 + 2\zeta_A \omega_A s + \omega_A^2}, \qquad (6)$$

then the ratio between this approximate solution and the response due to the short-period approximation is

$$\frac{q_{HF}}{q_{SF}}(s) = \frac{s(s^2 + 2\zeta_{SP} \omega_{SP}^{\dagger} + \omega_{SP}^{\dagger 2})}{s(s^2 + 2\zeta_{SP} \omega_{SP}^{\dagger} + \omega_{SP}^{\dagger 2}) - Z_w \omega_A^2}$$
(7)

The short-term pitch response to elevator inputs is well represented by Equation 6 provided that $\left| Z_{W} \right. \omega_{A}^{2} \left| \right|$ remains small in comparison with the modulus of $s(s^{2}+2\zeta_{SP} \omega_{SP}^{i} s+\omega_{SP}^{i2})$ in the frequency range of interest to the pilot in his short-term control of pitch attitude. Reference 3 presents examples of comparisons between the pitch responses given by Equations 2 and 6 respectively to elevator inputs for a variety of configurations evaluated in Group I of this investigation. Little deviation between the solutions occurs in the first two or three seconds following a step elevator input.

The low frequency or long-term pitch response to elevator inputs is, in general, not adquately represented by Equation 6 and, for the low stiffness configurations being



considered in this group, this portion of the response is better represented by

$$\frac{q_{LF}}{M_{\delta e} \delta e} (s) \simeq \frac{-Z_W}{2\zeta_{SP} \omega_{SP}' s + \omega_{SP}'^2}.$$
 (8)

When formulated in terms of the unaugmented shortperiod approximation of Equation 1, Equation 6 becomes

$$\frac{q_{HF}}{M_{\delta e} \delta e} (s) \simeq \frac{s}{s^2 - (M_q + UM_w^{\bullet})s - U(M_w + M_w^{\bullet} Z_w)}$$
(9)

It is seen that the high frequency response is characterized by a second-order system with a total damping less than that given by $2\zeta_{\mathrm{SP}}$ $\omega_{\mathrm{SP}}^{\mathrm{i}}$ and a stiffness which becomes negative when $-M_{\mathrm{W}}$ $< M_{\mathrm{W}}^{\mathrm{o}}$ Z_{W} .

The special case of pole-zero cancellation for M $_W$ + M_W^{\bullet} Z $_W$ = 0 (or ω_A^2 = 0) is readily obtained from Equation 3 and the resulting response is given by

$$\frac{q}{M_{\delta e} \delta e} (s) = \frac{1}{s - (M_{q} + UM_{w}^{\bullet})}$$
 (10)

$$= \frac{1}{s + (2\zeta_{SP} \omega_{SP}^{i} + Z_{W})}$$
 (11)

This condition, quite apart from the first-order pitch response to elevator inputs (the form of this, in the time scales of interest, is essentially retained even for non-zero θ_0), also results in a first order pitch response to normal thrust inputs and in minimum pitch response to normal gusts. Because of these attributes this configuration will be designated as basic in the considerations of the effects of

 $\mathbf{M}_{\mathbf{W}}$ and $\mathbf{Z}_{\mathbf{W}}$ that follow.

5.1.1.1 Effect of $M_{\overline{W}}$

Variations in $\mathbf{M}_{\mathbf{W}}$ do not affect the total damping of the longitudinal modes of motion but they do have a significant effect on the total stiffness, that is, for complex roots, on the stiffness of the short-period mode and, for aperiodic modes, on the distribution of the total damping between the roots.

Attention is again directed at the short-period pitch response to elevator inputs. In order to emphasize the changes in harmony between the initial and final pitch responses to elevator inputs when the short-period characteristics are changed through $M_{_{\mathbf{W}}}$, the steady-state pitch rate response to step inputs is used for normalizing purposes. This implies that the elevator displacement appropriate to the attainment of a given change in the steady state pitch rate is applied by the pilot in one step. (This form of normalizing is only possible for stable short-term pitch responses to elevator.) When comparisons are then made between the pitch responses of the basic configuration with - $M_w = M_w^{\bullet} Z_w$ and those with - $M_w > M_w^{\bullet} Z_w$, it is found that the initial response of the latter group is quickened relative to the basic first-order response by the stiffness formulated in Equation 6 and, indeed, can appear to be underdamped for complex roots. However, when - $M_w < M_w^{\bullet} Z_w$, the response is



more sluggish than the first-order response and can, in the short term, create the impression of the existence of an aperiodic instability. The loci, due to variations in $\mathbf{M}_{\mathbf{W}}$, of both the short-period roots and the roots of the approximation to the high frequency pitch response to elevator inputs are presented in Figure 13a to illustrate these regions of operation.

Turning to other transfer functions relevant to the pitch response, it is found that moving — M_W from M_W^{\bullet} Z_W results in increasing response to both normal gusts and normal thrust inputs.

5.1.1.2 Effect of $Z_{\overline{W}}$

The level of $\mathbf{Z}_{\mathbf{W}}$ can affect significantly the pitch control characteristics even of configurations with identical short-period roots.

It is seen from Equations 1 and 9 and from the root loci plots in Figure 13b that, although the short-period stiffness and damping are both increased with increases in - Z_w , the short-term pitch stiffness to elevator inputs is decreased in the presence of the normally negative values of M_w^{\bullet} , whereas the short-term pitch damping remains unchanged. Thus, despite the movement away from the origin of the short-period roots which can be achieved through increases in - Z_w^{\bullet} , the short-term control of pitch through elevator is characterized by an apparently reduced high frequency stiffness

at constant damping as - $Z_{\rm W}$ is increased. When comparisons are made between configurations with the same short-period characteristic roots but with different values for $Z_{\rm W}$, it is generally true that both the apparent total damping and stiffness of the pitch response to elevator inputs at high frequencies are reduced at higher levels of - $Z_{\rm W}$. This can lead to sluggish pitch control characteristics and to poor control over the trim values of pitch attitude for configurations whose short-period stiffness and damping are derived to a large extent from the contribution of $Z_{\rm W}$.

Other effects of $Z_{_{W}}$ are seen in the normal acceleration response to vertical gusts which increases with increasing - $Z_{_{W}}$, and in the time constant associated with the control of normal-velocity related quantities which decreases with increasing - $Z_{_{W}}$. As - $Z_{_{W}}$ is increased, the height control task should thus be eased through the quickened response to normal thrust inputs, whereas the ride and control of pitch will be worsened at a given level of short-period stiffness and total damping.

5.1.2 Configuration Characteristics Evaluated

The significant characteristics are listed in Tables I and II and illustrated in Figure 12. Common to all configurations in this group were the steady-state flight path response to elevator given by

$$\frac{\dot{\mathbf{h}}}{\mathbf{u}}\Big|_{\delta e_{SS}} = -.23$$
,

and that $\mathbf{Z}_{\mathbf{u}}$ and $\mathbf{M}_{\mathbf{u}}$ were set to zero.

The short-period stiffness was varied through $\mathbf{M}_{\mathbf{W}}$ for the following values of total damping and $\mathbf{Z}_{\mathbf{W}}$:

CONFIGURATIONS	Z _w	2ζ _{SP} ω' _{SP}
1 - 5	5	1.75
6 – 9	25	1.75
10 - 15	- 1.0	1.75
16 - 17	 5	1.4
18 - 20	5	1.0

5.1.3 Pilots' Assessments of Handling Qualities

As a general observation to preface the discussion of pilots' comments and ratings, it should be noted that on occasion considerable variations in ratings were obtained for different evaluations of the same configurations. Only a study of the pilots' comments will indicate the actual cause for this spread but it can often be attributed to the difficulty that the pilot has in assigning an overall rating to a configuration exhibiting several mediocre to poor characteristics, any one of which may or may not be disturbed sufficiently to cause him anxiety during an evaluation.

Although all the comments have been studied in detail, the main concern in the text is to extract trends in the changes in handling qualities that result from parametric variations. The comments pertaining to individual evaluations are

presented in full in Table III to allow the reader to study the causes for anomalous behaviour.

For the first group in question, the influence on pilots' ratings of variations in M_w at different Z_w for $2\zeta_{\mathrm{SP}}\omega_{\mathrm{SP}}'=1.75$ is presented in Figure 14 whereas that at different damping levels for $Z_w=-0.5$ is presented in Figure 15.

and the precision attained in each flight phase are also presented in a statistical manner in Figures 26 and 27 for two of the parametric variations discussed in this group. Shown are the extreme and mean adjectives and their standard deviation as used by the pilots to describe the various flight phases in each of the evaluations of the configuration. To attain these statistical properties on the basis of the prescribed adjectives, it has been assumed that the pilots used the adjectives according to a linear scale. The aim of the presentation is to indicate the mean trends as well as the likely deviations which may occur.

5.1.3.1 Configurations 1-5, $Z_w = -.5$, $2\zeta_{SP} \omega_{SP}^i = 1.75$

The above mentioned statistical properties of the pilots' comments are summarized in Figure 27 and those of Pilot A's control usage for Configurations 1, 2 and 5 are presented in Figure 30.

The basic configuration of the group (#2) with $\frac{q}{M_{Ae}\delta e}$ (s) $\simeq \frac{1}{s+1.25}$ exhibited good pitch characteristics



with no oscillatory tendencies. Speed control (both longitudinal and normal) caused at worst only slight difficulty and the insensitivity to turbulence was favourably commented upon. Any slight difficulty during glideslope and localizer tracking was attributed to the wind shear encountered. In the flare, rate of descent could easily be arrested with fair to good precision.

As - M_W was increased, the crosscoupling effects from the heave motion to the pitching motion became nuisance factors but, at the level of M_W investigated, did not degrade the rating. Turbulence response and the effects of thrust changes on the pitching moment equation elicited some comment. Airspeed control became more difficult in the presence of turbulence and slight, closed-loop oscillatory tendencies were occasionally noted. In general, the comments, if not the ratings, indicated slightly less desirable characteristics than those exhibited by the basic configuration.

As - M_W was decreased from the basic level, the difficulty of controlling the pitch attitude and hence airspeed increased markedly. Complaints centred on apparent aperiodic pitch instabilities and high steady-state pitch responses to elevator inputs. The pitch control was classed as sluggish and, for the more unstable values of M_W , pilots indicated a propensity towards pilot induced oscillations. The minimum breakout height to which the pilots would be prepared to fly under instrument conditions showed a general



increase although the pilots' assessments of the difficulty encountered and the performance achieved in flight path control did not vary significantly with decreasing stiffness. The flare caused difficulty at the lowest stiffness level because of the P.I.O. tendency.

In general, the difficulty in controlling the airspeed increased first with the introduction of IMC and then further with the introduction of turbulence for all but the basic configuration. Height rate control showed a similar increase in difficulty with the introduction of IMC but was not significantly affected by the introduction of turbulence. The control of the rate of change of height was considered to be less difficult than that of airspeed.

Summarizing, the effects of decreasing the stiffness to levels below the basic value caused marked changes in the following:

· Pitch Characteristics

Pitch characteristics appeared to become sluggish.

Pitch appeared to become increasingly unstable.

Tendencies towards low frequency P.I.O.'s in pitch became increasingly significant. Interaction between thrust inputs and pitch response became noticeable.

· Airspeed Control

As airspeed was controlled essentially through the pitch control loop, deterioration in airspeed control was linked to that in pitch.

Rate of Change of Height Control
 As the primary task of controlling pitch demanded more attention, the control of height rate tended to become more difficult.

The small effect of decreasing stiffness on the remaining tasks, namely on glidepath and localizer control and on turning and flare manoeuvres, could be attributed to the lessened attention available for their control with increasing primary control task difficulty.

5.1.3.2 Configurations 6-9, $Z_w = -.25$, $2\zeta_{SP} \omega_{SP}^{i} = 1.75$

The basic configuration for the group (#7) with

$$\frac{q}{M_{\delta e} \cdot \delta e} \text{ (s)} \simeq \frac{1}{s + 1.5}$$

was rated to be slightly worse than the corresponding configuration with $Z_{\rm W}$ = -.5. The pitch was characterized by a tendency to wander at low frequencies and this resulted in airspeed control problems. On the whole, however, the configuration appeared to exhibit reasonable handling qualities.

Increasing the stiffness seemed to reduce the pitch looseness, probably because of the influence of $\theta_{_{0}},$ and thus

eased the airspeed control problem. However, because of the insidious character of low frequency height rate errors resulting from the long time constant in heave, difficulty could be experienced in recovering from the large errors in height or height rate that could arise prior to perception by the pilot in turning manoeuvres or glide slope control. The pitch response to thrust inputs also became objectionable.

Decreasing the stiffness resulted in the same deterioration in pitch characteristics as for the higher - Z_W configurations but, in addition, the undesirable influence of low - Z_W on the precision of maintaining control over height rate was more pronounced. On the credit side, however, was the apparently reduced influence of turbulence on both pitch and heave responses.

5.1.3.3 Configurations 10-15,
$$Z_W = -1.0$$
, $2\zeta_{SP} \omega_{SP}' = 1.75$

The basic configuration for the group (#11) was characterized by

$$\frac{q}{M_{\delta e} \cdot \delta e} \text{ (s)} \simeq \frac{1}{s + .75}$$

The assessment of this and all the other configurations of the group with different stiffnesses was dominated by the difficulty experienced in controlling pitch which was generally described as loose or sloppy. Strong propensities towards pilot induced oscillations existed. Turbulence effects, particularly on pitch and thus on airspeed, were much more pronounced than for the lower levels of $-Z_w$. Surprisingly,



even though the time constant associated with the control of heave was reduced, a factor which should allow greater precision in height and height-rate control, the pilots often reported getting high on the glidepath. Some comments were made to the effect that the maximum selectable control gearing $(Z_{\delta T} = 15.0 \text{ ft/sec}^2/\text{in})$ was perhaps a little low for these configurations. In general the configurations were considered to be unacceptable and the pilots would not be prepared to remain IMC to the desired breakout height of 200 ft A.G.L. 5.1.3.4 Summary of the Effect of Varying Z_w at $2\zeta_{SP}$ $\omega_{SP}^{!}$ = 1.75

The statistical properties of the pilots' comments for the basic configurations at the three levels of $\mathbf{Z}_{_{\mathbf{W}}}$ are presented in Figure 28 and those of Pilot A's control usage in Figure 31.

From the pilots' assessments of the configurations it is seen that, as shown in Section 5.1.1.2, increasing - Z_w at a constant $2\zeta_{\mathrm{SP}}~\omega_{\mathrm{SP}}^{\,\prime}$ increases the time constant associated with the control of pitch through elevator, and that this results in a very real deterioration in handling qualities when $2\zeta_{SP}$ ω_{SP}^{\prime} + Z_{W} becomes small. For example, all the configurations with $Z_{\rm W}$ = -1.0 and $2\zeta_{\rm SP}$ $\omega_{\rm SP}^{\star}$ = 1.75 were deemed unacceptable irrespective of the level of $\mathbf{M}_{\mathbf{w}}$.

At the other limit of very small $\mathbf{Z}_{\mathbf{w}}$ one finds that the control of normal velocity becomes less precise, even with a normal thrust vector, because of the need to make acceleration-like commands to achieve the desired responses.

It is thus seen that a requirement exists for $^{2\zeta_{\mathrm{SP}}\omega_{\mathrm{SP}}^{\prime}}+^{Z_{\mathrm{W}}}$ to be sufficiently large for pitch control to remain acceptable and for - $^{Z_{\mathrm{W}}}$ to be sufficiently large to allow precise control of normal velocity related quantities. Even for adequate levels of $^{2\zeta_{\mathrm{SP}}}\omega_{\mathrm{SP}}^{\prime}+^{Z_{\mathrm{W}}}$, however, an upper limit needs to be placed on - $^{Z_{\mathrm{W}}}$ to restrain the acceleration response to gusts in heave to acceptable levels.

5.1.3.5 Configurations 16-17,
$$Z_w = -.5$$
, $2\zeta_{SP} \omega_{SP}' = 1.4$

The intent of this and the next group of configurations was to investigate the influence of reducing the short period damping at a constant $\mathbf{Z}_{\mathbf{w}}$.

The basic configuration (#17) with

$$\frac{q}{M_{\delta e} \delta e} (s) \simeq \frac{1}{s + 0.9}$$

exhibited characteristics considerably worse than those of Configuration 2 at the higher damping level, with pitch and airspeed control being singled out for their poor low frequency characteristics. This, coupled with normal velocity control problems, caused difficulty in maintaining the desired glide slope.

Increasing the stiffness improved the low frequency pitch characteristics and resulted in a marked improvement in rating.

5.1.3.6 Configurations 18-20,
$$Z_{W} = -.5$$
, $2\zeta_{SP} \omega_{SP}^{t} = 1.0$

The basic configuration (#19) with

$$\frac{q}{M_{\delta e} \delta e}$$
 (s) $\simeq \frac{1}{s + .5}$

exhibited poor pitch characteristics and these were not improved noticeably by changing the stiffness. Again, the low frequency pitch wander or looseness was the source of most of the control problems encountered and resulted in the pilot's overdriving the aircraft into low frequency, pilot induced oscillations. Airspeed control, normal velocity control and glide slope control all suffered and proved to be difficult.

5.1.3.7 Summary of the Effect of Varying $2\zeta_{SP}$ ω_{SP}^{\prime} at $Z_{W} = -.5$

The effect of decreasing $2\zeta_{SP}$ ω_{SP}^{\prime} at constant Z_{W} led to a rapid deterioration in handling qualities when the basic pitch control time constant was increased to more than about one second. The deterioration could generally be traced to the more sluggish pitch response to elevator which resulted in a requirement for the pitch control form to become an acceleration rather than rate command type if sufficiently great initial responses were to be attained without very large steady state responses. Some alleviation of this sluggish character could be provided by increasing the stiffness through M_{W} for the intermediate damping level, but no stiffness level was found to compensate adequately for these characteristics at the lowest damping level.



5.2 GROUP II Variations of Flight-Path Characteristics in the Presence of Good Pitch Control Characteristics

Removing the constraint of zero Z_u applied to the Group I configurations is likely to affect the flight-path control significantly in that it tends to result in a non-minimum phase response of height rate to elevator inputs. Previous investigations have indicated that even slight non-minimum phase values can cause significant deterioration in handling qualities during the approach task. It was thus considered important to attempt to isolate this outer control loop from the inner pitch control loop as much as possible by augmenting the pitch stability to desirable levels.

To be effective, it is required that the authority of a stability augmentation system be sufficient to produce pitch characteristics which allow the pilot to change predictably and precisely from one attitude to another. Furthermore, it is necessary that the desired attitude not be disturbed either markedly by external disturbances or unpredictably by cross-coupling effects from his controls.

Many of the configurations of Group I exhibited unacceptable pitching characteristics and it thus appeared appropriate to investigate whether, with the simple pitch attitude and rate feedback augmentation system illustrated schematically in Figure 3, it was possible firstly to make the handling qualities associated with pitch control acceptable and secondly, to ascertain whether this system dominated these



ensuing handling qualities to the extent of reducing the influence of external disturbances and crosscoupling from the other controls to insignificant levels.

5.2.1 Assessment of the Effectiveness of the Pitch S.A.S.

Three configurations from Group I with $\mathbf{Z}_{\mathbf{W}} = -.5$ were chosen to assess the effectiveness of the pitch stability augmentation system:

Configuration	Basic Short-Term	Pitch Characteristics
1	Good Damping,	Good Stiffness
4	Good Damping,	Poor Stiffness
19	Poor Damping,	Good Stiffness

The pilots' ratings for these configurations may be seen from Figure 15 and their comments from Table III.

The augmented short-term modal characteristics of ω_{ST} = 1.5 r/s, ζ_{ST} = 0.7 were anticipated to produce desirable control characteristics. The aircraft states, θ and q, were fed back at appropriate gains to achieve these characteristics and the feed forward characteristics of the pilots' elevator control could be adjusted to result in either pitch rate or attitude command forms. No optimization of the augmentation systems was undertaken by the pilots, firstly because it was felt that once the pitching characteristics were easily controllable, minor variations in these characteristics would not affect the pilot's control task significantly, and secondly for the more mundane reason of keeping the experimental programme within manageable bounds.



It may be seen from the pilots' comments in Table III and their ratings in Figure 16 that the objective of the augmentation system was achieved. To within the scatter of ratings found in the evaluation of any specific model caused by, for example, external factors or pilot variability, the handling qualities of all three configurations were, by the rate command system, improved to the level exhibited by the unaugmented Configuration 1. Furthermore these handling qualities, because of the desirable pitch characteristics, allowed ready control of both longitudinal and normal velocities and also exhibited good gust and control-crosscoupling moment rejection.

The attitude command system allowed greater precision in the control of steady state values and thereby made the tracking task easier than when it was undertaken with the rate command system but, in favour of the latter system, one observes a more significant propensity towards pilot induced oscillations with the attitude command form.

Comparison of the pilots' comments about configurations R1, R4 and R19 and about their progenies with non zero Z_u does not show significant differences at a given level of Z_u , thus supporting further the contention that these augmented characteristics would override the basic pitching characteristics. The differences remaining in the open-loop modes of motion could be readily controlled by the pilot without altering his assessment of the overall handling qualities.



It is not the intention here to imply that the command forms of the augmented systems were near optimum for all conditions, only that for a given command form the pitch control task was essentially normalized for the pilot.

5.2.2 Analytical Considerations of Flight Path Control

In the presence of easily controlled pitching characteristics, many of the salient features of flight-path control through elevator may be expressed in terms of the pitching motion rather than the higher-order pilot's elevator motion, as was originally implied in Reference 6 and subsequently reiterated in different forms in several more recent publications. This remains true at least for those cases where the forces on the aircraft due to elevator movement are significant only in the production of pitching moments. In these circumstances, the characteristic equation and the transfer functions for height and speed control in terms of the pitch change generated through elevator become respectively

$$\Delta = s^{2} - (X_{u} + Z_{w})s - X_{w}Z_{u} + X_{u}Z_{w}, \qquad (12)$$

$$\frac{\dot{h}}{\theta}(s)\Big|_{\delta e} = -UZ_{w}\left[s - \frac{Z_{u}}{Z_{w}}\left(\frac{g}{U} - X_{w}\right) - X_{u} - \frac{g}{U}\theta_{o}\right] / \Delta, \qquad (13)$$

$$\frac{u}{\theta}(s)\Big|_{\delta e} = -\left[W_{o} s^{2} + \left(g - W_{o}Z_{w} - U_{o}X_{w}\right)s - g\left(Z_{w} - X_{w}\theta_{o}\right)\right] / \Delta. \qquad (14)$$

If
$$|Z_w| >> |X_w \theta_0|$$
 and $\frac{g}{U} >> |X_w|$, Equation 14 may be simplified to:
$$\frac{u}{\theta}(s) \Big|_{\delta e} = -\left[\left(s - Z_w\right)\left(W_0 s + g\right)\right] / \Delta . \tag{15}$$

[As an aside, it should be noted that, in the linear range, variations in both $X_w Z_u - X_u Z_w$ and $W_o Z_w + U_o X_w$ due to a small angular rotation θ_o are zero and that these groupings rather than the individual derivatives should be considered in handling qualities investigations of flight path control when either X_w or X_u deviate markedly from the values caused primarily by aerodynamic drag changes.]

The levels of W_0 typically attained in the landing approach phase are such that the lead produced by it in the speed response to pitch attitude variations is not significant in the long-term flight-path control mode. Equation 15 may thus be further approximated as:

$$\frac{\mathbf{u}}{\theta} (\mathbf{s}) \Big|_{\delta \mathbf{e}} = -\left[\mathbf{g} (\mathbf{s} - \mathbf{Z}_{\mathbf{w}}) \right] / \Delta . \tag{16}$$

For the situation which normally arises in practice, of $|X_u + Z_w|$ being considerably larger than $\left|X_w \frac{Z_u}{Z_w}\right|$, one may finally write:

$$\frac{\mathbf{u}}{\theta} (s) \Big|_{\delta e} = \frac{-g}{s - X_u + X_w \frac{Z_u}{Z_w}}$$
 (17)

During the landing approach task, a quantity of importance to the pilot is the relative response of the rate of change of height and longitudinal speed resulting from pitch attitude changes made by means of the elevator control.

This is given, for the above approximations, by

$$\frac{\dot{\mathbf{h}}}{\mathbf{u}} (\mathbf{s}) \Big|_{\delta e \to \theta} = \frac{\mathbf{u} \mathbf{z}_{\mathbf{w}}}{\mathbf{g}} \frac{\left[\mathbf{s} - \frac{\mathbf{g}}{\mathbf{u}} \left(\frac{\mathbf{z}_{\mathbf{u}}}{\mathbf{z}_{\mathbf{w}}} + \theta_{o} \right) - \mathbf{x}_{\mathbf{u}} \right]}{\mathbf{s} - \mathbf{z}_{\mathbf{w}}}. \tag{18}$$

The well known result of speed-instability occurs when a non-minimum phase value is attained in this expression and the height-rate loop is closed with pitch attitude. Even for the situation of a zero in the left half of the root locus plane, one finds that the initial relative response of height-rate to velocity decreases with decreasing - UZ_w , thereby making the short-term control of height rate with elevator less effective than that to which pilots have become accustomed in more conventional aircraft exhibiting higher

values of
$$\frac{c_{L_{\alpha}}}{c_{L_{o}}}$$
 in the landing approach phase $\left[\frac{\underline{U}}{\underline{g}} \ \underline{Z}_{w_{AERO}}^{} \simeq -\frac{c_{L_{\alpha}}}{c_{L_{o}}}\right]$.

5.2.3 Configuration Characteristics Evaluated

The parameter chosen as possibly being the most appropriate open-loop measure of the long-term flight path control problems likely to be encountered is the steady state ratio, $\frac{\dot{h}}{u}\Big|_{\delta e}$, between the rate of change of height and

velocity for a change in pitch attitude through elevator.

This velocity ratio is obtained approximately from Equation 18 as:

$$\frac{\dot{h}}{u}\Big|_{\delta e \to \theta_{gg}} \simeq \frac{Z_{u}}{Z_{w}} + \frac{U}{g} X_{u} + \theta_{o} . \tag{19}$$

It is related to the change in flight path angle caused by speed changes, used for this same purpose in Reference 7, through

$$\frac{\dot{\mathbf{h}}}{\mathbf{u}} = \mathbf{U} \, \frac{\mathbf{y}}{\mathbf{u}} \, . \tag{20}$$

Rate of change of height rather than flight-path angle is chosen here for use in the identifying parameter both because of the ensuing non-dimensional nature of the parameter and because h and U are the two predominant state variables which the pilot modulates in his long-term control of trajectory.

As well as giving the long-term relative velocity changes obtained through pitch modulation, the parameter gives an indication of the compensatory thrust that would be required to maintain or achieve the desired speed and trajectory when the inner pitch loop is closed by the pilot on one or other of the velocity components in the longitudinal plane.

It is seen from Equation 19 that changes in the parameter can arise from changes in both the X and Z force derivatives. Lack of an independent means of controlling longitudinal forces of the simulator in question, however, restricted the investigation to one of assessing the effect of variations in the dominant normal force derivatives, $\mathbf{Z}_{\mathbf{u}}$ and $\mathbf{Z}_{\mathbf{w}}$.

The three levels of $\mathbf{Z}_{_{\mathbf{W}}}$ investigated in Group I were



evaluated with non-zero $\mathbf{Z}_{\mathbf{u}}$, the latter being limited to values less than the 'pure' aerodynamic value of

$$Z_{II} = -2g/U_{O} = -0.635$$
.

In addition, the ratio Z_u/Z_w was not allowed to exceed a value of 1.2. [For aerodynamically generated forces, $Z_u/Z_w \simeq 2 \ C_{L_o}/C_{L_\alpha}$.]

5.2.3.1 Characteristics of Pitch Stability Augmentation System

The control surface movement for the attitude command system utilized was related to the pilot's control displacement and the aircraft pitch states by

$$M_{\delta e} \delta e_{s} = M_{\delta e} \delta e_{p} + M_{\theta_{SAS}} \cdot \theta + M_{q_{SAS}} \cdot q , \qquad (21)$$

whilst that for the rate command system was related by

$$M_{\delta e} \delta e_{s} = M_{\delta e} \left[\frac{s^{2} - (M_{q} + M_{\alpha}^{\bullet})s - M_{\theta}}{s(s - M_{q} - M_{\alpha}^{\bullet})} \right] \delta e_{p} + M_{\theta} \delta e_{sAS} \delta + M_{qSAS} \epsilon q \quad (22)$$

The pre-filtering applied to the pilot's elevator control diplacements for the rate command form was chosen to provide, with a minimum of adjustable components, an approximate polezero cancellation of the second-order short-term characteristic mode, and to replace this mode with a pair of roots, one of which was located at the origin.

The introduction of pitch attitude feedback to the moment equation alters the short-term pitch response to elevator inputs obtained from the expansion of the transfer function about the zero location, given in Equation 3, to the

following:

$$\frac{\theta}{M_{\delta e}^{\delta e}}(s) = \frac{1}{s^2 + 2\zeta_{A} \omega_{A} + \omega_{A}^{2}} \left[\frac{s^3 + 2\zeta_{SP} \omega_{SP} s^2 + \omega_{SP}^{2} s - Z_{W} \omega_{A}^{2}}{s^3 + 2\zeta_{SP} \omega_{SP} s^2 + \omega_{SP}^{2} s - Z_{W} M_{\theta}} \right],$$
(23)

where
$$2\zeta_A \omega_A = 2\zeta_{SP} \omega_{SP} + Z_W$$

 $= - (M_Q + UM_W^{\bullet})$,
 $\omega_A^2 = \omega_{SP}^2 + 2\zeta_A \omega_A Z_W$
 $= - (UM_W + UM_W^{\bullet} Z_W + M_{\theta})$

If the stabilization authority is high in comparison to the basic moment characteristics, that is, if $|M_{\theta}| >> |U(M_W + M_W^* Z_W)|$, one may write $\omega_A^2 \simeq -M_{\theta}$. In this case the high frequency pitch response for the attitude command form, A, is well approximated by

$$\frac{\theta_{\rm HF}}{M_{\delta \rm e}^{\delta \rm e}} \, (\rm s) \simeq \frac{1}{\rm s^2 + 2\zeta_A \, \omega_A \, s + \omega_A^2} \,, \tag{24}$$

whereas that for the rate command form, R, with the control law shaping of Equation 22 becomes

$$\frac{\theta_{\text{HF}}}{M_{\delta e} \delta e} \text{ (s)} \simeq \frac{1}{s(s - M_{q} - UM_{w}^{\bullet})}. \tag{25}$$

The steady state error of these approximations is readily obtained from Equation 23.

The non-zero values of $\mathbf{Z}_{\mathbf{u}}$ for this group of configurations also mean that one of the phugoid or long-term roots is no longer precisely cancelled by the low frequency



zero in the $\frac{\theta}{\delta e}$ (s) transfer function (see Table II). At low frequencies, this causes a further deviation between the predicted responses of Equations 24 and 25 and the actual responses. However, this deviation should not prove to be significant in the bandwidth of concern to the pilot for the short-term control of the pitch attitude loop.

5.2.3.2 Configuration Matrix

The following configurations were evaluated:

Basic Config'n	Z_{W}	z _u	0	05	1	2	6
1	 5	h/u 6e ss EVALUATED	24 R		_	.20 R	1.07 A, R
4	 5	h/u δe _{ss} EVALUATED	24 R		02 A	.20 A, R	1.07 A, R
19	 5	h/u _{δess}	24 R		02 R	.20 R	1.07 A, R
8	25	h/u _{δess}	23 A, R	01 A, R		.64 A, R	
14	-1.0	h/u δe ss EVALUATED	24 A, R			.02 A, R	.41 A, R

where R signifies evaluations with the rate command system A signifies evaluations with the attitude command system All configurations were stabilized to possess the same short-period characteristics, $\omega_{\rm SP}$ = 1.5, $\zeta_{\rm SP}$ = 0.7.

The relationship between this group of configurations and the

others evaluated is illustrated in Figure 12.

5.2.4 Pilots' Assessments of Handling Qualities

5.2.4.1 Configurations Based on No's 1, 4 and 19 with $Z_{\rm W}$ = -0.5

These configurations have already been referred to in Section 5.2.1 with regard to the pitch stabilization system and it was therein indicated that the system essentially normalized the pitch response for the pilot. It thus becomes possible to treat the configurations at a given level of $\mathbf{Z}_{\mathbf{u}}$ as a group.

(a) Rate Command System

The pilots' comments about these configurations are presented in Table III and their ratings are plotted in Figure 16. The comments for conglomerates of configurations with the same Z_u regarding the difficulty experienced and the precision attained in each flight phase are also presented in a statistical manner in Figure 29. The statistical properties of the pilots' control usage are given in Figures 32-35.

It is noteworthy that, for this group, the average difficulty experienced and precision attained in all flight phases, including the localizer tracking, followed the same trend with variation in $\mathbf{Z}_{\mathbf{u}}$ and that this trend repeats the one found in the overall average of the pilots' ratings of Figure 16.

As the detailed aspects of the configuration control characteristics are presented in Figure 29, only what are considered to be the causal parameters will be considered here.

Movement away from the optimum region, defined approximately by $\left|\frac{\dot{h}}{u}\right|_{\delta e_{_{SS}}}$ < 0.3 - 0.5, is characterized

chiefly by a deterioration in speed control and its ensuing influence on height rate control.

The speed control, for the constant pitching characteristics of this group, may be affected firstly by the control technique employed by the pilot and secondly by the speed response to attitude changes or, in more detail, by the following factors.

- (i) When $\frac{\dot{h}}{u}\Big|_{\delta e_{_{SS}}}$ > 0, speed instability may result if the pilot attempts to close on height rate errors with pitch attitude. Any such tendency would be destabilizing.
- (ii) The open-loop speed response to pitch attitude is governed to good approximation by Equation 17 and it is seen from this equation that both the time constant and the magnitude of the steady state response increase as $-\left(X_u-X_w\frac{Z_u}{Z_w}\right)$ tends towards zero. Increases in $-Z_u$ for the X_w of the simulator thus tend to make pitch attitude a rate control for speed throughout the time scales of interest to the pilot.

Either of the above two factors, or a combination thereof, could explain the worsening speed control but, in view of the improvement afforded to the configurations with introduction of the attitude command system described in the next section, it is suspected that the factor (ii) was the more important.



In summary, when - Z_u is increased to values beyond the optimum region, the configurations with the rate-command pitch control system are characterized by a deterioration in all control phases except that of the inner pitch loop. This deterioration is attributed to a worsening in the control over airspeed and the increased coupling between airspeed and vertical speed. The latter factor results in a greater heave response to longitudinal gusts, wind shear and speed perturbations arising from the pilot's control inputs.

Perturbations from these sources, which could remain undetected until they became quite large because of the low level of acceleration cues typifying the configurations, could cause wide variations in control difficulty during any portion of the task.

(b) Attitude Command System

The pilots' comments about these configurations are presented in Table III and their ratings are plotted in Figure 15.

Comparison of the comments with those on the rate command system at any level of Z_u shows a decrease in difficulty and an increase in precision for all task phases except the flare for the zero Z_u case. For this configuration, a greater propensity towards pilot induced oscillations resulted in difficulty because of the higher control gains that pilots tend to use when close to the ground. The pilots' ratings were degraded correspondingly.

The improvement in the control of other task phases, in particular that at the highest level of - Z_u , was without doubt due to the greater precision with which steady state airspeed could be controlled. When the longitudinal speed response to pitch attitude is governed by a long time constant because of a small value of - $\left(X_u - X_w \frac{Z_u}{Z_w}\right)$, direct control over pitch attitude becomes an advantage to the pilot as an aid to the precise long-term control of speed. The pilots' estimates of their greatest undesired speed fluctuations did not show a noticeable improvement with the attitude command form until the highest level of - Z_u was reached. However, frequent comments were made about the good pitch and speed hold characteristics.

The turbulence response in heave emerged as one of the worse features whereas height rate, airspeed and pitch control were classed amongst the better features of all the configurations.

The requirement to trim the elevator forces during steady manoeuvres such as turns did not elicit unfavourable comments.

5.2.4.2 Configurations Based on No. 8 with $Z_{\rm W}$ = -0.25

The pilots' comments about and their ratings of these configurations are presented in Table III and Figure 17 respectively.



(a) Rate Command System

For zero Z_u , airspeed and vertical velocity control in general and height control during turns proved to be more difficult than for the configurations with $Z_w = -0.5$. It is apparent that the long time constant associated with the low value of Z_w resulted in a lack of precision in the control of the normal velocities and that this concerned the pilots. When - Z_u was increased to make $\frac{\dot{h}}{u} \Big|_{\delta e_{SS}}$ zero, airspeed control

improved somewhat but the height rate control problem remained. A further increase in - Z_u caused a deterioration in most flight phases in a manner similar to that experienced for the configurations with Z_w = -.5 and for the same reasons.

The trends are thus similar to those for $Z_{\rm W}$ = -0.5, but the added difficulty of controlling the long-term height rate results in a general degradation in pilots' ratings by as much as two rating points.

(b) Attitude Command System

The attitude command system, in comparison with the rate command system, again improved the general precision of speed control. The ensuing rating was more favourable, particularly for the highest - Z_u level. At the zero Z_u level, however, neither system improved upon the stiffest unaugmented configuration for this Z_w level, indicating that the origin of the difficulty experienced lay in the heave rather than the pitch control loop.



5.2.4.3 Configurations Based on No. 14 with $Z_{\rm W}$ = -1.0

The pilots' comments about and their ratings of these configurations are presented in Table III and Figure 17 respectively.

The premise that most of the control problems associated with the unaugmented configurations 10-15 lay with the long effective time constant associated with the pitch control loop was supported by the improvements obtained with both the rate and attitude command pitch stability augmentation systems.

Pitch control and hence speed control improved markedly. The general level of ratings was still somewhat worse than for the configurations with $Z_{_{\!\!W}}=-.5$ and much of this difference can be attributed to the sharper responses to turbulence in heave which resulted in an unsteady feeling. The differences in control task difficulty arising between the attitude and rate command forms were not as great as for the configurations with smaller $Z_{_{\!\!\!W}}$.

The crosscoupling between longitudinal and vertical velocities became noticeable at the highest - $\mathbf{Z}_{\mathbf{u}}$ level, but did not achieve the magnitude needed to dominate all other characteristics.

5.2.5 Summary of the Effect of Varying Flight Path Characteristics

The influence on handling qualities of varying flight path characteristics through \mathbf{Z}_{ij} was quite dependent



on the pitch characteristics of the configuration - on both the numerators and the denominator of the various pitch response transfer functions.

A general observation that may be made is that the pilots showed a preference for a near zero level of steady state rate of change of height with the elevator inputs - at least for these configurations evaluated with thrust vectors that were almost normal to the flight path and thereby encouraged the control of height rate through thrust modulation. When the level of Z_u was varied away from the rather flat optimum level centred on zero, the deterioration in handling qualities was dependent on how well the low frequency airspeed perturbations could be controlled. The attitude command, pitch stabilized system proved advantageous in this respect as it allowed a somewhat more precise control of the long-term pitch attitude variations which governed airspeed.

Positive $\frac{\dot{h}}{u}\Big|_{\delta e_{_{\mathbf{SS}}}}$ did not appear to cause dominant

speed instability problems and this factor is indicative that the pilots recognized the need to control airspeed with elevator rather than thrust. However, the need to closely constrain airspeed as an inner loop for satisfactory height control added considerably to the pilot's workload, particularly as the acceleration cues indicating deviations in airspeed were generally small.

When $\mathbf{Z}_{_{\boldsymbol{W}}}$ was varied, it was found that a value of



 $\mathbf{Z_W}$ = -.5 exhibited the best compromise between precise control of height rate, which deteriorates with decreasing - $\mathbf{Z_W}$, and excessive accelerations in heave due to turbulence which arises with increasing - $\mathbf{Z_W}$.

5.3 GROUP III <u>Simultaneous Variations in Both Short and Long-Term Characteristics Through Z</u>u

Removing the pitch stability augmentation system returns the pitch characteristics of the configurations to their often poor original state. The purpose of evaluating the resulting group was to assess the influence of changing the long-term characteristics through variations in $\mathbf{Z}_{\mathbf{u}}$ in the presence of typical unaugmented short-term characteristics of STOL alreraft.

5.3.1 Analytical Considerations

The analytical considerations for the previous two groups remain in effect but, in addition, the pilot is faced with the control of the long-term or phugoid mode which may be strongly excited by his elevator inputs. Group I configurations were characterized by a pole-zero cancellation in this mode, whereas the pitch stabilization of the Group II configurations resulted in the mode being well damped. In this group neither condition prevails for non-zero $\mathbf{Z}_{\mathbf{u}}$. As the modulus of this derivative is increased, the pilot needs to concern himself not only with the problems associated with $\frac{\mathbf{h}}{\mathbf{u}}$ (s) but also with the additional task of precisely controlling pitch attitude in the presence of more significant



disturbing influences.

The total damping is unaffected by variations in $\mathbf{Z}_{\mathbf{u}}$. Its effect, just as that of $\mathbf{M}_{\mathbf{w}}$, lies with the distribution of the damping and stiffness between the modes. However, whereas the influence of $\mathbf{M}_{\mathbf{w}}$ was apparent mainly in the short-term mode, that of $\mathbf{Z}_{\mathbf{u}}$ makes itself felt more in the long-term mode.

As the time constants associated with each of these modes converge, the classical separation between the modes can no longer always be assumed valid. It is found that Z, may transfer some of the damping traditionally associated with the short-period mode to the phugoid mode and vice versa depending on whether M_{w} Z_{ij} is positive or negative. The less the modes are separated in stiffness, the more pronounced the effect. To the pilot concerned principally with closing a tight loop on attitude, this redistribution is apparent mainly in the phasing of his moment cues. When M_{w} and Z_{ij} are negative, a poorly damped, complex long-term mode tends to result, and the initial swing back of attitude, due to this mode, following an elevator input may lull the pilot into a false sense of security and cause him to lag behind the aircraft. For positive M_{w} and negative Z_{11} , the long-term mode is well damped at the expense of an aperiodic instability in the 'short' term mode. The pilot is thereby made aware earlier of a need to compensate for the ensuing error. One example of this latter phenomenon is obtained amongst the configurations of this group.



5.3.2 Configuration Characteristics Evaluated

The characteristics of certain configurations of Group I were varied through changes in $\mathbf{Z}_{_{11}}$ as indicated below.

Config.	Zw	Z _u	0	2	6
1	-0.5		24	.20	1.07
2(Basic)	-0.5		24	.20	1.07
4	-0.5		24	.20	1.07
19(Basic)	-0.5	u sess	24	.20	1.07
7(Basic)	-0.25	88	23	.64	-
8	-0.25		23	.64	-
11(Basic)	-1.0		24	_	.41
14	-1.0		24	.02	.41

The designation 'basic', as before, indicates a short-term pole-zero cancellation in the $\frac{q}{\delta e}$ (s) transfer function. This particular pole-zero cancellation was virtually unaffected for the range of Z_u evaluated.

The configuration characteristics may be obtained from Tables I and II whereas the relationship between this group of configurations and the others may be seen from Figure 12.

5.3.3 Pilots' Assessments of Handling Qualities

Only those characteristics altered by non-zero $\mathbf{Z}_{\mathbf{u}}$ will be considered in detail in this section. For consistency with the Group II presentation, the ratings are again plotted against

 $\left.\frac{\dot{h}}{u}\right|_{\delta e_{_{SS}}}$ although it is recognized that the characteristic modes take on added significance.

5.3.3.1 Configurations with $Z_W = -0.5$: No's 1, 1-2, 1-3; $\frac{2}{2}$, 2-2, 2-3; 4, 4-2, 4-3; 19, 19-2, 19-3

The pilots' comments and ratings are presented in Table III and Figure 18 respectively. It is seen that there is a trend indicating a monotonic worsening in handling qualities with increasing – Z_u for all configurations except No. 4. This is the only configuration with positive M_w . It is thus characterized by an unstable aperiodic mode $(T_2 \cong 6 \text{ secs})$ and a well damped, low frequency complex pair. This combination resulted in ratings that were slightly more favourable (but perhaps insignificantly so) than those of Configuration 4 with $Z_u = 0$.

The difference in ratings between the configurations with $2\zeta\omega$ = 1.75 and Z_u = 0 noted when the short-period stiffness was changed, was no longer apparent with Z_u = -.2 despite the significant difference in root locations between the configurations.

All configurations exhibited unacceptable handling qualities at the highest level of - Z_{ij} .

Perusal of the pilots' comments indicates that the pilots were concerned first and foremost with the pitch characteristics and their effect on the control of airspeed and height rate. At the highest level of - $Z_{\rm u}$, the coupling



between airspeed and vertical speed achieved the 'Most Objection-able Features' category. Even for Z_u = -0.2, the level of difficulty experienced in controlling vertical velocity approached moderate from the slight category typical for the better configurations at Z_u = 0. It is this increase in difficulty and its effect on flight path control to which the worsening in rating is attributed even though the coupling did not attain a 'Most Objectionable Feature' designation.

Finally, the influence of turbulence in disturbing both pitch and heave increased to objectionable levels for $Z_{11} = -0.6$.

5.3.3.2 Configurations with $Z_W = -0.25$: No's 7, 7-2; 8, 8-2

The general level of ratings is seen from Figure 19 to worsen to the same unacceptable level for both configurations with $\rm Z_u$ = -.2.

Lack of pitch stiffness was held to be mainly responsible and the coupling between airspeed and vertical speed was considered to be an important contributing factor.

5.3.3.3 Configurations with $Z_W = -1.0$: No's 11, 11-2; 14, 14-1, 14-2

Again, as seen from the pilot's comments and Figure 19, the introduction of Z_u only worsened the already poor control over pitch and resulted in unacceptable configurations. Positive M_w did not result in the slight improvement in handling qualities noted with the introduction of moderate Z_u at $Z_w = -.5$.



5.3.4 Summary of the Effects of Varying \boldsymbol{z}_u

The handling qualities of all configurations with negative M_w worsened progressively with the introduction of Z_u . The only and slight improvement obtained in ratings for non-zero Z_u was with $Z_u = -.2$ at $Z_w = -0.5$ and positive M_w .

The deterioration in handling qualities was apparent mainly in the increased difficulty experienced in precisely controlling pitch caused by the additional excitation of the phugoid or long-term mode with elevator inputs. The coupling between airspeed and vertical speed added to the general difficulty in controlling either parameter. Turbulence response in both pitch and heave also added noticeably to the pilot's workload.

The evaluations indicate that the handling qualities of Group I, with Z_u = 0, are likely to be as good as can be obtained for these configurations with poor short-period characteristics and low inherent speed-damping. It is suggested that this is both because of the minimal excitation through elevator of the long-term modes that occurs with Z_u = 0 and because of the reasonable level of $\frac{\dot{h}}{u} \Big|_{\delta e_{_{SS}}}$ for Group I.

Group 1.

5.4 GROUP IV Simultaneous Variations in Both Short and Long-Term Characteristics Through Mu

For this group, the final major constraint of $M_{\rm m}$ = 0, imposed in the previous groups, was removed.



Evaluations for non-zero M_{u} were only undertaken for configurations without pitch stability augmentation as the latter tends to alleviate the effects of variations in M_{u} too much to warrant an investigation.

5.4.1 Analytical Considerations

Whereas the major effect of non-zero Z_u u occurs in the equation governing normal velocity and affects the pitching moment equation only through the ensuing feedback terms $M_{\hat{\mathbf{w}}}^{\bullet}$ and $M_{\hat{\mathbf{w}}}$, that of M_u is fed back directly to the pitching moment equation through M_u u and can thus be expected to affect the short-term mode more than did Z_u for the levels of $M_{\hat{\mathbf{w}}}$ prevailing.

Just as for variations in $\mathbf{Z}_{\mathbf{u}}$, the total damping of all the characteristic modes remains insensitive to variations in $\mathbf{M}_{\mathbf{u}}$. However, $\mathbf{M}_{\mathbf{u}}$ does affect the stiffness of both modes, that of the short-term being decreased and that of the long-term increased as $\mathbf{M}_{\mathbf{u}}$ is made more positive. Providing that the modes are well separated, only a very slight redistribution of total damping between the two modes occurs. As the separation between the modes decreases, however, the distribution of damping between them may also be affected noticeably by $\mathbf{M}_{\mathbf{u}}$. A short and long term aperiodic root may combine into a complex pair exhibiting levels of total damping and stiffness lying somewhere between the 'pure' short and long term modes. The damping of this pair is derived at the expense of the remaining aperiodic root near the origin and can result in an



aperiodic instability. The distribution of the damping between the complex pair and aperiodic root depends critically on the value of M_u - positive values of which lead to oscillatory instabilities and negative values to aperiodic instabilities. However, the total damping of these three roots near the origin does not vary significantly.

Root locus plots illustrating three forms of the effect of $M_{\rm u}$ on the short and long term modes are presented in Figure 26. They are representative of configurations whose 'pure' modes exhibit differing degrees of separation.

The intermediate configuration (19-2) is of interest in that whilst the short and long term modes remain separated, a significant exchange of total damping between them occurs.

A situation of some concern arises when attempts are made to categorize configurations with least separation. If, as usual, requirements are to be based on the separate application of short and long term criteria, it is seen that very small variations in Mu can turn an acceptable into an unacceptable configuration. Some means needs to be devised to take into account the exchange of damping between the roots close to the origin which can easily be reversed by the pilot through closing an airspeed to elevator loop without his having to provide lead.

Apart from its effect on the characteristic modes, \mathbf{M}_{u} also affects the control task through its effect on the pitch response to turbulence. The appropriate numerator is

given by

$$N_{ug}^{\theta}(s) = s[(M_u + Z_u M_w^{\bullet})s + Z_u M_w - Z_w M_u].$$

For small θ_o and no attitude stabilization, the low frequency asymptote remains at the same gain level. The turbulence response is thus minimized when M $_u$ + Z $_u$ M $_w^{\bullet}$ = 0.

5.4.2 Configuration Characteristics Evaluated

Representative configurations of Group III were chosen for Mu variations. In general, the level of Mu required to obtain either an aperiodic divergence represented by λ = 0.1, or an unstable oscillatory mode with $\zeta\omega$ = -0.1, was chosen. In addition Mu was not allowed to exceed a value of $|M_{\rm u}|$ = 0.005.

The following configuration groups, encompassing a wide range of short-term characteristics (shown in Table II and Figure 12) were evaluated.

Conf	Z _w	z _u	0	2	6
1	 5		+, -	+, -	+, -
2	 5			+	
4	 5			+	
19	 5	М _и	+, -	+, -	+, -
8	 25		+	+, -	
11	-1.0			+	
14	-1.0		+	-	+



5.4.3 Pilots' Assessments of Handling Qualities

5.4.3.1 Configurations with $Z_{\rm W}$ = -0.5 Based on No. 1

The pilots' comments and their ratings are presented in Table III and Figure 20 respectively.

The basic configuration exhibited good short-period stiffness and damping. The effects of varying $\mathbf{Z}_{\mathbf{u}}$ have already been assessed in Section 5.3.3.1, and the additional ones due to changes in $\mathbf{M}_{\mathbf{u}}$ at each level of $\mathbf{Z}_{\mathbf{u}}$ are now considered.

Because of the good separation between the short and long term responses, $\mathbf{M}_{\mathbf{u}}$ does not significantly affect the total damping of either mode but does change the stiffness of each mode.

(i)
$$Z_{11} = 0$$

The pilots' main concern remained correlated with the changes in the long-term characteristics as $\rm M_u$ was varied. For negative $\rm M_u$, the complaints were about the lack of pitch stiffness associated with the aperiodic instability of λ = 0.1, whereas for positive $\rm M_u$, the resulting long-term complex mode of relatively short period and low damping led to a tendency towards pilot induced oscillations. The one evaluation made with negative $\rm M_u$ returned a surprisingly good rating in view of the rapidity of the aperiodic divergence (time to double amplitude \simeq 7 secs) but, as the rate of divergence is very sensitive to small changes in $\rm M_u$, its control should not cause too much difficulty providing that the pilot is able to devote

sufficient attention to this aspect of the task.

The configurations with non-zero $M_{\rm u}$ were disturbed noticeably more in pitch by the effects of turbulence and also made the pilot more aware of the pronounced response in pitch to thrust modulation arising from the large value of $M_{\rm w}$.

(ii)
$$Z_{11} = -0.2$$

The characteristics exhibited at Z_u = 0 with changing M_u again came to the fore but this time were even more apparent. The value of M_u required to generate the aperiodic instability was considerably greater than before and led to comments about the requirement for reversed force trim with steady state velocity changes. Positive M_u did not result in a significant deterioration in handling qualities, but even the best configurations of this group were barely acceptable.

(iii)
$$Z_{11} = -0.6$$

The characteristic modes remained complex with $M_u = -.005$. All configurations were rated as unacceptable because the poor pitch characteristics, coupled with the strong interaction between the airspeed and normal velocity, proved to make the control task too difficult.

5.4.3.2 Configurations with $Z_W = -0.5$ Based on No's 2-2 and 4-2

In this group, the basic short period damping remained high but the stiffness was reduced.

(1) Configuration 2-2, $Z_u = -0.2$



The pilots' comments and ratings are presented in Table III and Figure 20 respectively.

Configuration 2-2 exhibited a complex long-term mode and a short-term pole-zero cancellation in the $\theta/\delta e$ (s) transfer function. Some damping of the long-term mode was transferred to the short-term mode with increasing M_{U} but the pole-zero cancellation essentially remained unaltered.

The increase in M_u made the pilot more aware of the oscillatory long-term mode, because of the resulting decreased damping and increased frequency of this mode. The deterioration in oscillatory character and the increased response to turbulence rendered the configuration unacceptable for two of the three pilots who evaluated it.

The configuration with negative M_{ij} was not evaluated.

(ii) Configuration 4-2, $Z_u = -0.2$

The pilots' comments and ratings are presented in Table III and Figure 21 respectively.

The short-term stiffness was reduced further and, in Configuration 4-2, resulted in the combining of a short and long term root into a complex pair of moderate frequency and damping, and an unstable aperiodic root.

The aperiodic instability did not cause undue concern. When $\mathbf{M}_{\mathbf{U}}$ was increased, however, this and the other short-term root were stabilized at the expense of the complex pair. The ensuing oscillation, which was easily excited, became difficult to suppress and resulted in the configuration

being rated as unacceptable.

5.4.3.3 Configurations with $Z_{\rm W} = -0.5$ Based on No. 19

The pilots' ratings and comments are presented in Figure 21 and Table III respectively.

This group of configurations had a lower basic short-period damping of $2\zeta\omega_{\mathrm{SP}}=1.0$ than the previous three groups and a short-period pole-zero cancellation in the $\frac{\theta}{\delta e}$ (s) transfer function. Because the total damping was decreased while the stiffness was held at the same level as in Configuration 4, the short-term aperiodic roots tended to be closer together and neither was as close to the origin as in Configuration 4. The short and long-term roots tended to remain more separated as a result but positive Mu did transfer significant total damping from the long-term to the short-term mode.

(1)
$$Z_{11} = 0$$

The unstable long-term oscillation dominated the unacceptable handling qualities for the configuration with positive $\mathbf{M}_{\mathbf{U}}$, whereas that with zero $\mathbf{M}_{\mathbf{U}}$ was marred by the general sloppiness of the pitch characteristics which resulted in overcontrol by the pilot.

(ii)
$$Z_{11} = -0.2$$

The characteristics which dominated were much the same as at Z_u = 0. The configuration evaluated with an unstable aperiodic root in this group again did not cause a

noticeable deterioration in rating, which seems to indicate that no significant difficulty was added by the need to control it. This configuration with negative $\mathbf{M}_{\mathbf{u}}$ is marked by minimum pitch response to $\mathbf{u}_{\mathbf{g}}$.

(iii)
$$Z_{11} = -0.6$$

All configurations proved to be unacceptable because of both the pitch characteristics and the coupling between airspeed and normal velocity. The aperiodic instability caused considerable difficulty for these configurations already characterized by other pronounced deficiencies in handling qualities.

5.4.3.4 Configurations with $Z_W = -0.25$ Based on No. 8

The pilots' comments and their ratings are presented in Table III and Figure 22.

Marked redistribution of the total damping between the short and long-term roots occurs just as for the higher $\mathbf{Z}_{\mathbf{w}}$ level for the same basic stiffness.

The mean ratings at both levels of $\mathbf{Z}_{\mathbf{u}}$ were insensitive to the $\mathbf{M}_{\mathbf{u}}$ variations undertaken and remained at the acceptable-unacceptable borderline. The general looseness of the control, particularly in pitch, was the chief source of difficulty at zero $\mathbf{Z}_{\mathbf{u}}$, whereas, at the higher $\mathbf{Z}_{\mathbf{u}}$ level, the coupling between longitudinal and vertical velocities compounded the difficulties.

The aperiodic instability with negative \mathbf{M}_{u} again was not cause for undue concern.



5.4.3.5 Configurations with $Z_{\rm W}$ = -1.0 Based on No. 14

The pilots' ratings and their comments are presented in Figure 23 and Table III respectively.

The redistribution of total damping between short and long term modes through $\mathbf{M}_{i,j}$ was marked.

 $\rm M_{u}$ variations had the same general effect as at $\rm Z_{w}$ = -0.5, but in a more pronounced manner. The already poor pitching characteristics, in particular their oscillatory nature and their response to turbulence, deteriorated even further and no acceptable configurations were found.

5.4.3.6 Summary of the Effect of Varying M_{11}

Perhaps the most important outcome of this portion of the investigation was the confirmation, seen also from the evaluations of Group III, that when the short and long term modes were no longer well separated and the influence of longitudinal velocity perturbations in the short-term mode was not negligible, then the combination of a phugoid and short period root into a reasonably damped long period oscillatory pair and a corresponding unstable aperiodic root of quite divergent characteristics did not necessarily result in unacceptable handling qualities. The sensitivity of these three roots to small Mu variations indicates that the pilot would have no difficulty in redistributing the total damping of the three roots near the origin by closing a low gain airspeed to elevator loop and thereby stabilizing the

unstable aperiodic root.

In general, the variations in Mu did not improve the handling qualities of any configurations that were initially acceptable. The added response to turbulence, the establishment of easily excited long-term oscillatory characteristics and the redistribution of the already meagre damping of the long term mode to the short term mode when it would have been more beneficial to the former, all added to the control difficulty.

The effects of these changes were most pronounced in those configurations already exhibiting poor pitching characteristics.

5.5 GROUP V Effect of Non-Zero $\frac{Z_{\text{Se}}}{M_{\text{Se}}}$ on Selected Configurations

Many aircraft in the STOL class experience a change in lift force when the motivater providing pitching moment control is activated. The intent of this somewhat limited investigation was to ascertain whether significant handling qualities problems would ensue when realistic coupling levels were introduced.

It appeared to be appropriate to consider the effect of this crosscoupling term firstly on a basic configuration exhibiting some undesirable pitching characteristics to ensure that the elevator was moved significantly by the pilot, and secondly on a stabilized configuration in which the pilot was no longer linked directly through his control column to

the motivater movement.

The basic configuration chosen was No. 1-2 in both its unstabilized form and its stabilized form with rate command.

Typical values of tail-arm coupling for this class of aircraft led to the choice of

$$\frac{Z_{\delta e}}{M_{\delta e}} = 7.5 , 15$$

as being suitable for investigation.

5.5.1 Pilots' Assessments of Handling Qualities

The pilots' comments and ratings are presented in Table III and Figure 24 respectively.

(a) Stabilized Configuration

The pilots' ratings were not affected significantly by factors which could be attributed directly to this control crosscoupling. However, uncertainty about the height-rate control characteristics were commented upon by Pilot B.

(b) Unstabilized Configuration

For the unstabilized configuration, Pilot A became more aware of the increased difficulty in controlling height

rate as $\frac{Z_{\delta e}}{M_{\delta e}}$ was increased, mainly as a secondary effect.

Pilot B's major concern did not change from that over the pitch characteristics.

5.5.2 Summary of the Effect of Varying $\frac{Z_{\delta e}}{M_{\delta e}}$

The influence of $Z_{\delta e}/M_{\delta e}$ on the general handling

qualities remained secondary to the pilot throughout the range evaluated. It did, however, affect the background difficulty level experienced by the pilot in his control task.

5.6 GROUP VI Effect of Non-Zero
$$\frac{M_{\delta T}}{Z_{\delta T}}$$
 on Configuration 2-2

The control crosscoupling effect complementing that investigated in the previous group, is that due to thrust modulation on the aircraft's pitching moment.

Configuration 2-2 was chosen as the basic configuration for these tests because of its inherent coupling between speed and rate of change of height, which encourages some thrust modulation, and because of its relatively pure pitch response to elevator inputs. It was thereby hoped to focus attention on the effects of $M_{\xi m}$.

The variations made were as follows:

$$\frac{M_{\delta T}}{Z_{\delta T}} = -0.0064, + 0.0064, + 0.0128.$$

The most pronounced effect of $M_{\delta T} \delta T$ occurs in the $\theta/\delta T$ (s) transfer function and it is found that the initial pitch response is minimized when

$$\frac{M_{\delta T}}{Z_{\delta T}} = -M_{\tilde{W}} = .00412$$

for this configuration.

5.6.1 Pilots' Assessments of Handling Qualities

The pilots' comments and ratings are presented in Table III and Figure 25 respectively.



A study of these comments indicates that the pilots were quite aware of the control crosscoupling for the extreme values of $\rm M_{\delta T}/\rm Z_{\delta T}$ and were concerned that situations might arise where this coupling could be dangerous. Pilot B classified the crosscoupling under 'Most Objectional Features'. At the intermediate level of $\rm M_{\delta T}/\rm Z_{\delta T}$, the crosscoupling, rather than standing in isolation as a dominant parameter, appeared to contribute to the general background level of difficulty.

Thus, the effects of $M_{\delta T}/Z_{\delta T}$, although not producing a monotonic variation in overall pilots' ratings, were more directly apparent to the pilot than were the effects of $Z_{\delta e}/M_{\delta e}$ and were recognized as being potentially hazardous. This added awareness of the coupling was probably due to the fact that the pitch disturbances caused by thrust changes are readily noticed by the pilot who is trying to maintain tight control over pitch in order to suppress his speed variations.

5.7 Statistical Analysis of the Pilots' Control Inputs

Few data were available, for the class of aircraft evaluated, of the pilot's control usage during the approach to landing. To supplement these data and to obtain insight into the sensitivity of the form of the pilot's control application to changing longitudinal handling qualities, several representative approaches were chosen for analysis. The statistical analysis was restricted to that of obtaining the power spectral density and amplitude distributions of the



pilot's elevator control movement. The same analysis is not presented for the thrust lever movement because, in the quasistationary portion of the approach selected for analysis (approximately 50 seconds on the approach), only a few discrete adjustments to thrust were in general made and, quite often, a significant linear trend in the thrust modulation existed during this time period. Such a time history does not lend itself well to statistical categorization by means of frequency and amplitude distributions.

Details of the analysis and its results are presented in Appendix E and in Figures 30 to 35.

The form of the power spectral density distributions of each pilot's elevator control movements for the group of configurations analyzed was, in general, relatively insensitive to the configuration characteristics being evaluated. If the open-loop configuration characteristics were known, one could discern trends in the pilot's control movements which supported closed-loop expectations, particularly when the power spectral density distributions were viewed in conjunction with the amplitude distributions and time histories. For example, in the group of configurations evaluated by Pilot A in which the short-term stiffness was reduced by variations in M_W (Figure 30), there was a tendency on the pilot's part to hunt, at low frequency, for the appropriate pitch trim position when the short-term pitch stiffness became negative, (Conf. 5L; see also Section 5.1.1.1). The change in the



statistical distributions of the elevator movement with $\mathbf{M}_{\mathbf{W}}$ is nonetheless small when viewed in the light of the very pronounced change in the pilot's rating due predominantly to the changing pitch control characteristics.

Similar observations may be made about the effect of variations in $\mathbf{Z}_{\mathbf{w}}.$

In the group of configurations for which Z_u was the variable, it may again be seen that the statistical distributions of the elevator control movement were relatively insensitive to configuration changes. This, however, is not surprising in view of the essentially constant pitch control characteristics of these configurations. Of interest is the pilots' use of thrust modulation. It is seen from the time histories that even when operating on the extreme backside of the power required curve, the pilots did not significantly vary the form of their thrust-control usage. Thrust modulation was used only for long term control and this remained true for all the configurations evaluated.

Some correlation between the root mean square (r.m.s.) of the elevator control movements and the pilot's workload existed but, as the r.m.s. can be noticeably affected by changes in parameters that need not affect the workload significantly, for example, changes in the turbulence level or increases in the pitch stiffness through M_W , it can only be used as a relative rather than absolute indication of the pilot's workload.

In summary, statistical analysis of the pilots' elevator movements showed weak correlation between control activity and workload, but this correlation was not sufficiently unique or pronounced to allow the use of the statistical analysis for more than a substantiating role to other forms of analysis.

5.8 Comparison with MIL-F-83300

The portions of the MIL-F-83300 specifications relevant to the group of configurations evaluated are those dealing with the longitudinal characteristics in Sections 3.3.1 and 3.3.2 of those specifications.

Underlying the current limits and parameters therein utilized is the attempt to specify desirable pitch responses to elevator inputs. The total flight path control problem, however, has not yet been addressed in a quantitative manner.

Longitudinal equilibrium is established through the device of pitch-controller force and position gradients with respect to both attitude and speed changes, whereas the dynamics are specified in terms of the characteristic modes of motion of the configuration. The characteristic modes are separated into conglomerates of two pairs of roots, each pair having to satisfy certain requirements.

With regard to the longitudinal equilibrium, no

Level 1 configuration which contravened the appropriate

requirements was found. This factor could, however, equally

well be a reflection of the simultaneously poor dynamic



characteristics as of the contravention of the equilibrium conditions per se.

The dynamic requirements are expressed in terms of a short term mode, characterized by ω_n , $2\zeta_n\omega_n$, ζ_n and the short-term response to elevator parameter, $\frac{\omega_n^2}{\alpha}$, and by a low frequency, phugoid-type mode characterized

by ω_{ph} , ζ_{ph} , T_2 .

The previous analysis in this report has indicated that the implementation of the appropriate separation of the roots into two pairs can give rise to ambiguity. Moreover, whether or not the requirements are satisfied, is sensitive to the choice of pairs made, a situation which leaves much to be desired.

It is suggested that when the separation between the short and long term modes is small, some other means of categorizing the handling qualities which does not require modal separation into pairs of roots be established.

Included should be a more direct measure of all the responses to elevator of concern to the pilot than is given by

$$\omega_n^2/\frac{n}{\alpha}$$
 or, its equivalent, $\frac{g}{U} \frac{\theta_{\text{initial}}}{\dot{\theta}_{\text{final}}}$, for those configurations

exhibiting small modal separation and low pitch stiffness.

Some of the analysis presented in previous sections, which attempts to highlight the responses to controls in the time scales of interest to the pilot, is appropriate to such

considerations.

It was found, when establishing minimum acceptable short-term stiffness and damping levels, that the pilots' major concern was not with $\boldsymbol{\omega}_n$ and $2\boldsymbol{\zeta}_n\boldsymbol{\omega}_n$ per se but rather with the apparent initial (high frequency) pitch stiffness and damping in response to elevator inputs. As is shown in Section 5.1, the pitch response depends not only on the shortterm characteristic mode, but also on the short-term zero in the $\frac{\theta}{\delta e}$ (s) transfer function, the location of which is essentially established by the magnitude of the damping in heave derivative $\mathbf{Z}_{\mathbf{w}}$. The present requirements address the limit for minimum stiffness through the parameter, $\omega_n^2/\frac{n}{\alpha}\Big|_{\alpha=0}$, which, in terms of the pitch responses to rapid elevator inputs, relates the initial pitch acceleration to the final pitc! rate that would be achieved if speed were to remain constant. During evaluations, it was found that the intermediate pitch response was also of importance to the pilot when flying low stiffness configurations, and this factor would suggest that the minimum stiffness requirement should be a function not only of $\mathbf{Z}_{_{\mathbf{W}}}$ but also of short-period damping, much as is the high frequency pitch stiffness $\omega_{\Delta}^{\,2}$ calculated in Section 5.1.

Similarly, flight evaluations demonstrated that the lower limit on total damping would be more appropriately related to $(2\zeta_n \ \omega_n + Z_w)$ rather than to $2\zeta_n \ \omega_n$ as in the present requirements.



Of the parameters not restricted explicitly in the requirements, flight path control would appear to be the most important remaining. This investigation indicates that

 $\begin{array}{c|c} \dot{\underline{h}} & \text{may well be the parameter to be considered for this} \\ \delta e_{ss} & \\ \text{definitive role.} & \text{It should be noted, however, that a marked} \\ \text{interaction exists between the quality of pitch control and} \\ \text{the ease of controlling the flight path.} \end{array}$

5.9 Preliminary Summary of Handling Qualities Investigated

The foregoing investigation of a wide range of longitudinal handling qualities and their effect on a steep, low-speed instrument approach was intended to distinguish those characteristics which most critically affected the successful completion of this flight task.

The intent of this summary is to place the detailed investigations into perspective.

The dominant feature, whatever the other characteristics, was the control of pitch attitude. The more easily, predictably and precisely this could be controlled the less the significance of other undesirable characteristics.

In the first group investigated, in which the pitching characteristics were altered whilst those of the long-term speed and flight path control were maintained at favourable levels, it was found that the short-term characteristic mode no longer provided a unique parametric reference for the ensuing handling qualities when either the stiffness



or the total damping of the mode became small. Under these circumstances the pitch response to elevator becomes particularly sensitive to the location of the high frequency zero of the $\frac{\theta}{\delta e}$ (s) transfer function relative to the roots comprising the short-term mode. It is this pole-zero conglomerate rather than the poles alone which critically determines the short-term handling qualities of the configuration. The pilot was sensitive to reductions in the high frequency pitch stiffness and damping characteristics for which second order approximations are developed in Section 5.1.1. With Mu and Zu constrained to zero, no configuration was found which remained acceptable to the pilots for positive values of Mu, let alone for negative values of the short-period stiffness, (- UMu + Ma Zu).

For low short-period stiffness arising from positive $M_{\rm w}$, and when the influence of longitudinal velocity perturbations on the short-term mode is pronounced because of nonzero $Z_{\rm u}$, it is found that the three roots near the origin can combine into a different configuration of a well damped complex pair and an unstable aperiodic root. (For example, compare configurations 4 and 4-2.) Flight evaluations of such configurations resulted in essentially the same ratings as those for the configurations with $Z_{\rm u}=0$ which had the same total damping derived from three stable or neutral roots near the origin. The new complex pair does not have the same character as the classical phugoid in that it has high residue



in all three degrees of freedom. A redistribution of the damping between the roots can be caused by closing the elevator loop on airspeed with low gain - a technique which would not be successful in the control of the classical phugoid. Only limited stabilization governed by the inherent damping of the three roots near the origin is, however, possible with this technique.

The question raised is one of the definition of longterm and short-term modes to be used in these circumstances if compliance with requirements based on these separate modes needs to be demonstrated.

The derivative Z_W is of significance in many aspects of the control task. It critically affects the pitch response to elevator inputs and establishes the time constant of all motions in the normal plane. The turbulence response increased with increasing - Z_W . Moreover, for a given set of short term characteristics exhibiting low total damping, pitch control was worse at the higher levels of - Z_W . When - Z_W became too small, although the turbulence response decreased, the imprecision of the long-term control of the vertical motion caused much concern. In the present investigation, a value of Z_W = -0.5 led to a better compromise of these conflicting characteristics than did values of Z_W = -0.25 and -1.0.

When the pitch stability is well augmented, it is found that larger positive steady state values of \dot{h}/u for

elevator inputs can be tolerated than in the absence of augmentation. The more positive the value of $\frac{\dot{h}}{u}\Big|_{\delta e_{SS}}$, the more advantageous the attitude command control form becomes because of its capabilities in allowing precise control of the steady state pitch attitude. The levels of $\dot{h}/u\Big|_{\delta e_{SS}}$ that could be accommodated by the pilot were considerably higher, with the good attitude command form and the normal thrust control vector of the experiment, than has previously been reported.

The effects of control crosscoupling could be disturbing in the overall task. That of thrust modulation on the aircraft's pitching moment was more readily isolated by the pilot as a causal factor than was the effect on lift of elevator displacements.

The statistical analysis of the pilot's elevator control movements during representative evaluations indicated that the shape of the power spectral density and amplitude distributions was only weakly and not very consistently correlated with the pilot's workload and rating. The thrust magnitude modulation by the pilot was of such frequency content as to indicate that he used thrust only as a long-term control.

The influence of simulating a pilot's station 25 feet ahead of the centre of gravity instead of the inherent 3 feet did not affect assessments noticeably.



Finally, the surprisingly large proportion of approaches during which the pilot complained of pronounced wind shear and the ensuing requirements for very large changes in steady state descent rates or large heading changes to compensate for the significant errors that built up before being detected, needs to be singled out. The sensitivity of the configurations in heave, in particular through the derivative $\mathbf{Z}_{\mathbf{u}}$, played a significant role in the frequency of comments about this aspect.



6.0 CONCLUSIONS

An in-flight investigation of a variety of longitudinal handling qualities during steep, low-speed instrument approaches resulted in the following general observations:

- The pitch control characteristics dominated the handling qualities. Pilots were sensitive to variations in both the short and long term pitch control characteristics.
- Pilots were prepared to accept operation well along the backside of the power-required curve providing that the long-term control of airspeed through pitch modulation was not difficult.
- well separated, longitudinal handling qualities criteria could no longer be uniquely established on the basis of separating out two pairs of second order characteristic modes. The location of the zeros relative to the roots, particularly in the pitch response transfer functions, played a significant role in establishing the handling qualities.
- The magnitude of the derivative, Z_w, proved to be of importance as a handling qualities parameter because of its pronounced effect on the responses in and the control of both the pitch and heave degrees of freedom.



- The statistical characteristics of the pilots'
 elevator control movements could, at best, only be
 correlated weakly with the pilots' assessments of
 the handling qualities. Thrust modulation was used
 primarily as a long-term control.
- Atmospheric turbulence, wind and wind shear could have a significant effect on the control task during steep, low-speed, instrument approaches.



FIG I EVALUATION PILOT'S COCKPIT LAYOUT

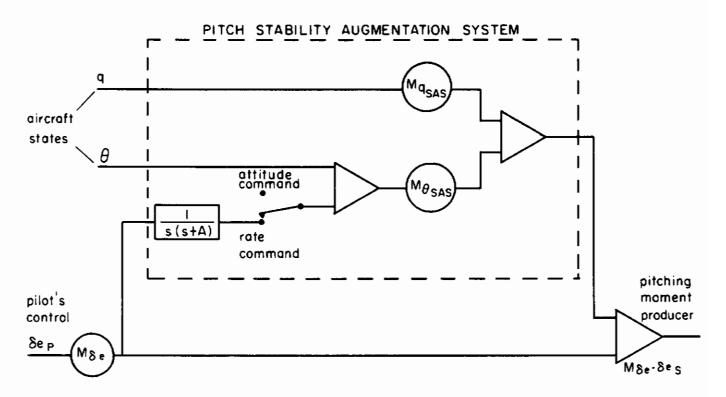


PARAMETER	ELEVATOR	AILERON	RUDDER	THRUST LEVER
Static Characteristics				
Spring Gradient (lb/in)	2.2	1.3	10.5	0
Preload Force (1b)	0.8	0.4	6.5	0
Dry Friction (1b)	0.7	0.3	6	Adjustable
Travel (ins)	± ¼	±3	±3	-1.5, +4.0
Linear* Dynamic Characteristics				
Trim Rate (ins/sec)	±0.75	±0.55	Manual	N/A
ω_{o} (rad/sec)	8.2	7.7	8.2	N/A
ζ ₀	0.3	0.4	0.3	N/A
		1	1	1

FIG. 2 EVALUATION PILOT'S CONTROL CHARACTERISTICS

^{*} The dynamic characteristics due only to the spring gradient, viscous damping and inertia of the control system.





$$A = -(Mq + M\dot{\alpha}) = TOTAL DAMPING + Xu + Zw$$

RATE COMMAND:

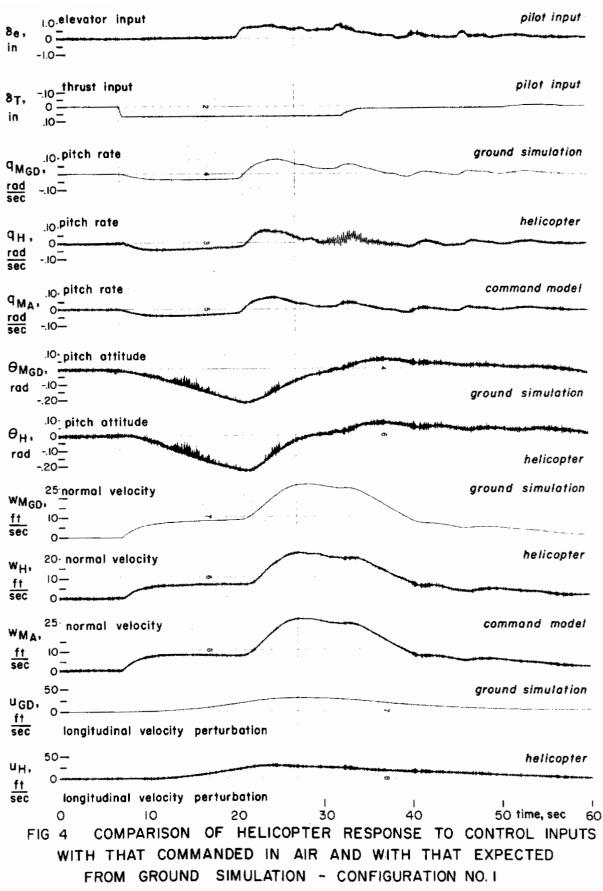
$$M_{\delta e} \delta e_{S} = M_{\delta e} \left[\frac{S^{2} - (Mq + M\dot{q})S - M\theta_{SAS}}{S(S - Mq - M\dot{q})} \right] \delta_{eP} + M\theta_{SAS} \cdot \theta + Mq_{SAS} \cdot q$$

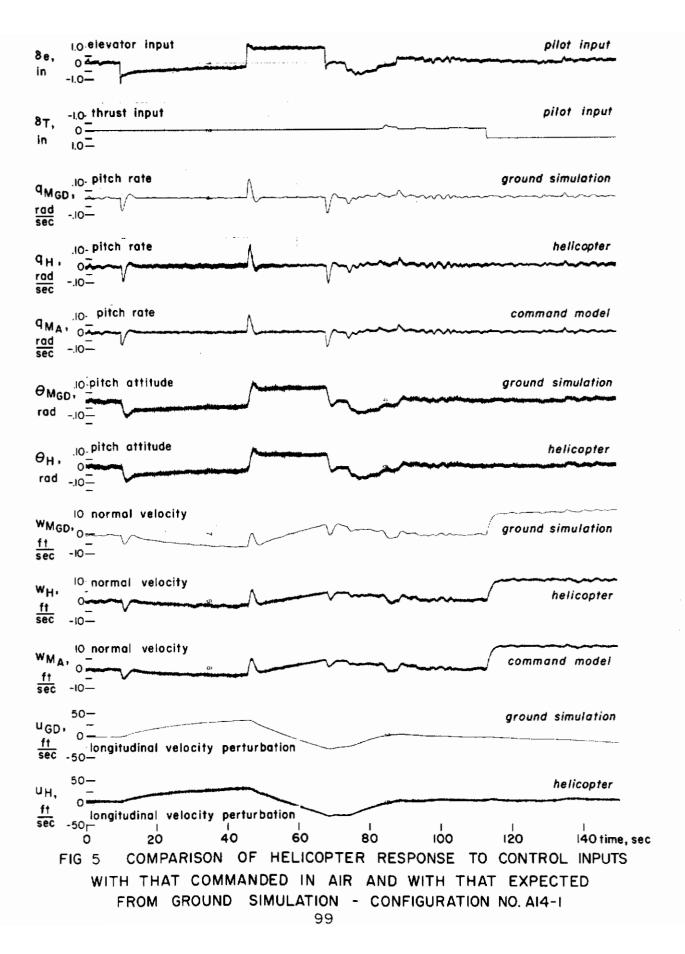
ATTITUDE COMMAND:

$$M_{\delta e} \cdot \delta e_s = M_{\delta e} \delta e_P + M_{\theta_{SAS}} \cdot \theta + M_{q_{SAS}} \cdot q$$

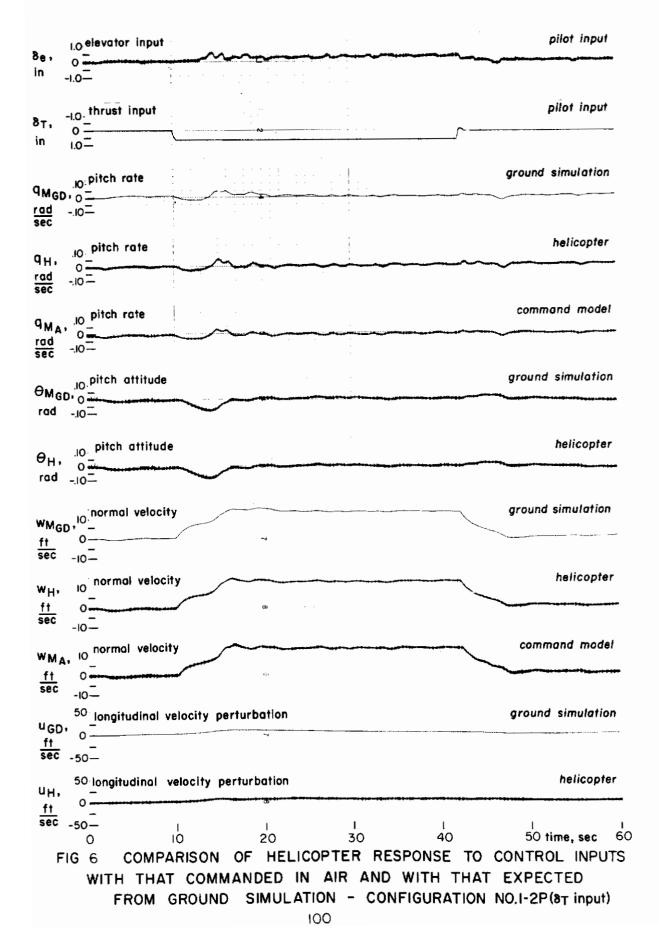
FIG 3 SCHEMATIC OF STABILITY AUGMENTATION SYSTEM



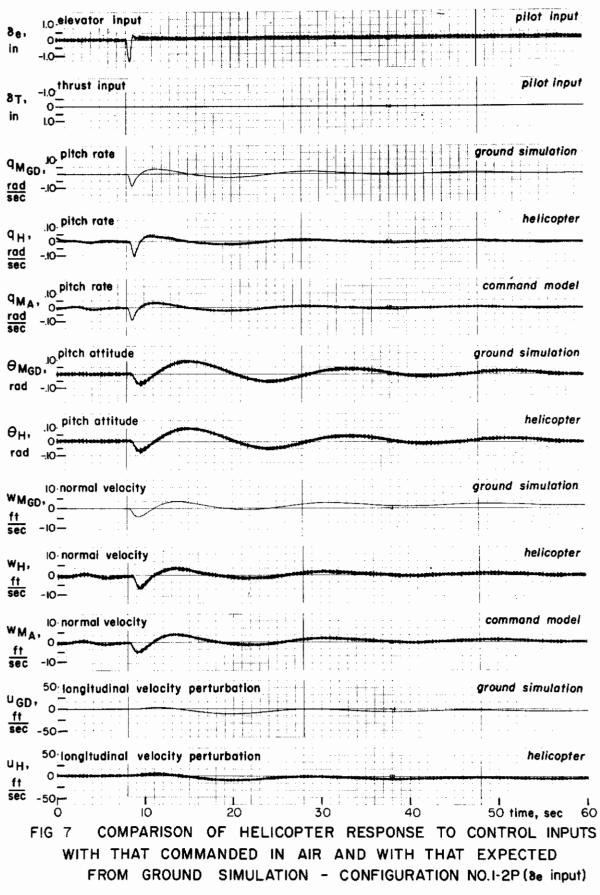














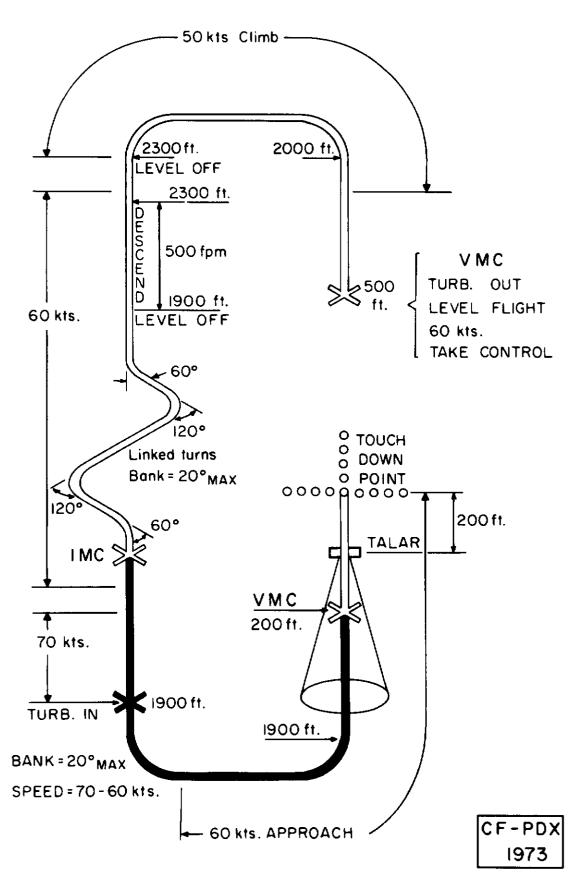


FIG 8 TASK FOR LONGITUDINAL DYNAMICS INVESTIGATION 102



EVALUATION DATA SHEET Page of 4										
CANCOLLOW DAIL STEEL										
Pilgi	6 FLIGHT PATH	CONTROL								
Ools Temperature Esternol Wind	Difficulty experi		cision attained	in the Jollow	ing approach i	phoses				
Time Pressure Turbulence Shear Flight No Negligible						Final	Leagh			
Configuration Light/Small		Glide path	Localiser	intermeda Glide goth	Localiser	Glide path	Localser			
Roring	Difficulty									
I CONTROL FEEL CHARACTERISTICS	Great	ļ		ļ						
Forces Displacements Term Rate	Moderate Slight	+	 							
$\delta_{\rm E}$ $\delta_{\rm E}\delta_{\rm I}$ $\delta_{\rm E}$	No	+								
High Too lorge Too fast	Precision									
Satisfactory Satisfactory Satisfactory Law Too small Too slow	Vary poor		<u> </u>	<u> </u>			_			
100 41101	Poor	ļ——				-				
2. AIRCRAFT RESPONSE TO CONTROL INPUTS REQUIRED TO PERFORM TASK	Good	1				<u> </u>				
In-lial rasponse to Control Sensitivities	<u></u>									
δ _E δ _T δ _E δ _T (Face values)	Min-mum occep	ptable br ec koul	altitude If gr	epter than 20	DO II					
Tao great Tao great	Reason for difficulty									
Satisfactory Satisfactory Set POTG										
Not ossessable										
3 EASE OF MAINTAINING DESIRED VELOCITIES	7. BREAKOUT	AND FLARE								
Langitudina Vertical Reason for difficulty	Ease of arr	esting rate of	desceni							
Velocity Velocity	Opening to the start									
Turbulence OUT IN OUT IN OUT WAS IMC IMC IMC IMC	Great difficulty Reason for difficulty:									
Great Difficulty	Slight		_							
Modera le	No	نــــــــــــــــــــــــــــــــــــــ	_							
Slight	_									
No "	Precision t	il allaining lav	ch down point							
MAXIMUM UNDESIRED VELOCITY FLUCTUATIONS -Longitudinal (knots) Vertical (fam)	Very paar									
<u></u>	Poer									
	Fair Good									
	1.555									
4 RESIDUAL OSCILLATORY CHARACTERISTICS	8. CONTROL	FECHNIQUE								
	<u> </u>									
Amphilude Period Comping Prich Heave Prich Heave Prich Heave	if control lec	thrique used d	iflered from	longitudinal v	elacity contro	il with elevato	· and			
Lorge Short High	vertical velo	city confroi w	ith thrust lev	er, camment						
Moderate Medium Moderate										
Zero Long Lon										
Negotive Negotive										
L										
How controlled?	9 LATERAL	DIRECTIONA	L CHARACTE	RISTICS						
εξ ογ Turb Sources δε δε δη Both Easi γ Not attempted	Ellect on	final assessm	ent							
Moderately Effective		_								
Hordly Ineffective	Lorge Moderate	_	ffeos	on						
Aggravating	Small	\dashv	_							
Comments	None									
										
	O. LEAST	OBJECTIONAB	LE FEATURI	<u> </u>						
5 THRUST REQUIREMENTS IN TURNS										
Thrust demanded to maintain vertical velocity in a 20° banked (ven										
Excessive'	MOST OB	JECTIONABLE	FEATURES							
Large										
Moderate										
Sino /	12 MISCELL	ANEOUS								
Neg i g Die										
Ease of compensating for thrust demands whilst changing bank angle										
Great difficulty Reason for difficulty:	3 RATING		7							
Moderate										
Sigh: "		•								

FIG 9 PILOT'S COMMENT AND RATING SHEET



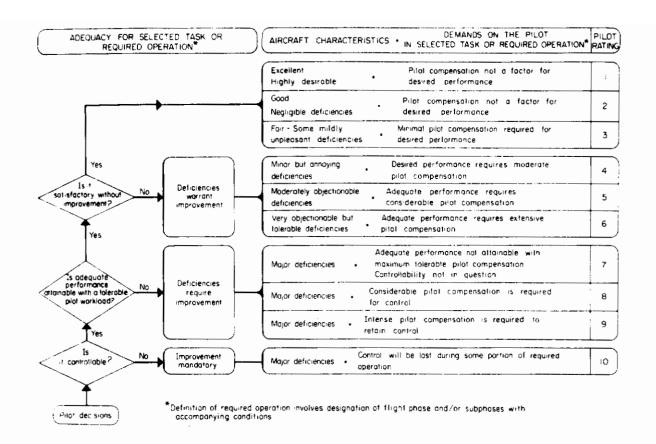


FIG IO COOPER-HARPER PILOT'S RATING SCALE

INCREASE OF PILOT EFFORT WITH TURBULENCE	DETERIORATION OF TASK PERFORMANCE WITH TURBULENCE	RATING
NO SIGNIFICANT INCREASE	NO SIGNIFICANT DETERIORATION	Α
	NO SIGNIFICANT DETERIORATION	8
MORE EFFORT REQUIRED	MINOR	С
	MODERATE	D
	MODERATE	E
BEST EFFORTS	MAJOR (BUT EVALUATION TASKS CAN STILL BE ACCOMPLISHED)	F
REQUIRED	LARGE (SOME TASKS CANNOT BE PERFORMED)	G
UNABLE TO	PERFORM TASKS	н

FIG II TURBULENCE EFFECT RATING SCALE



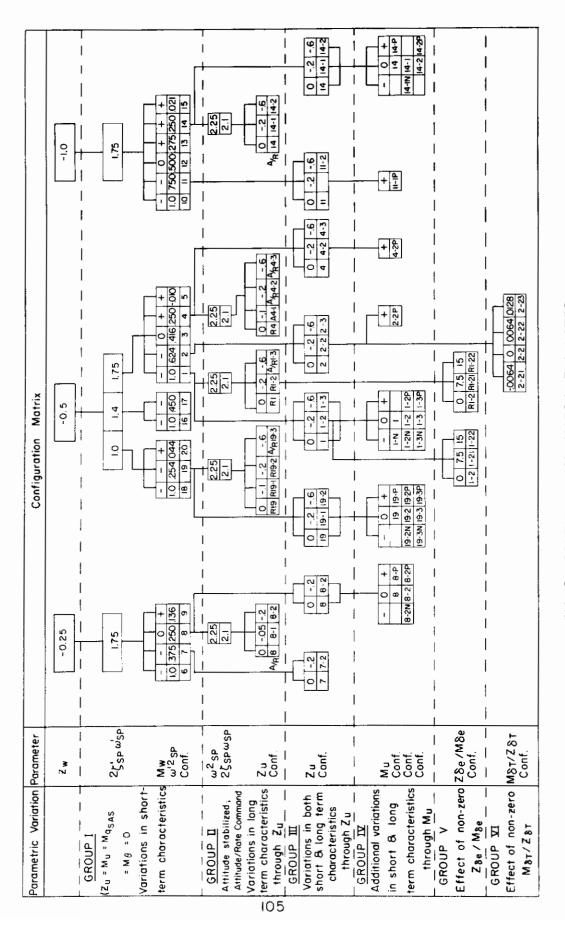
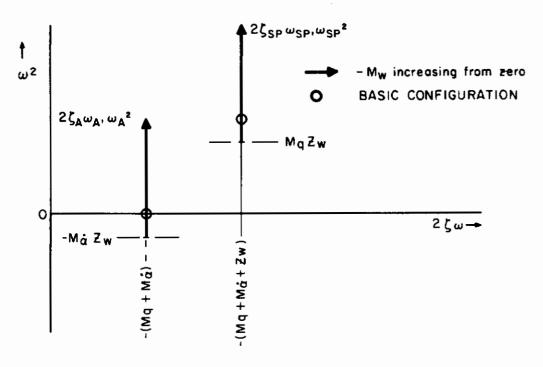


FIG 12 CONFIGURATION MATRIX EVALUATED



(a) LOCI FOR MW VARIATIONS

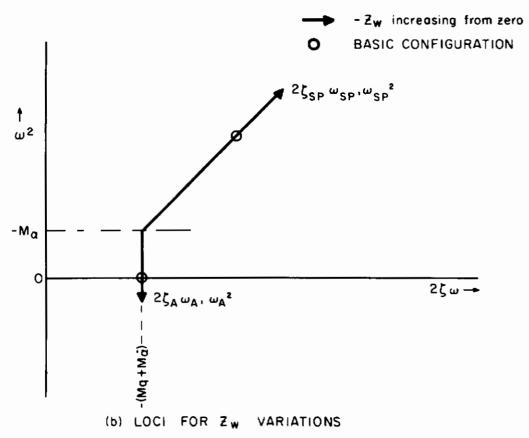
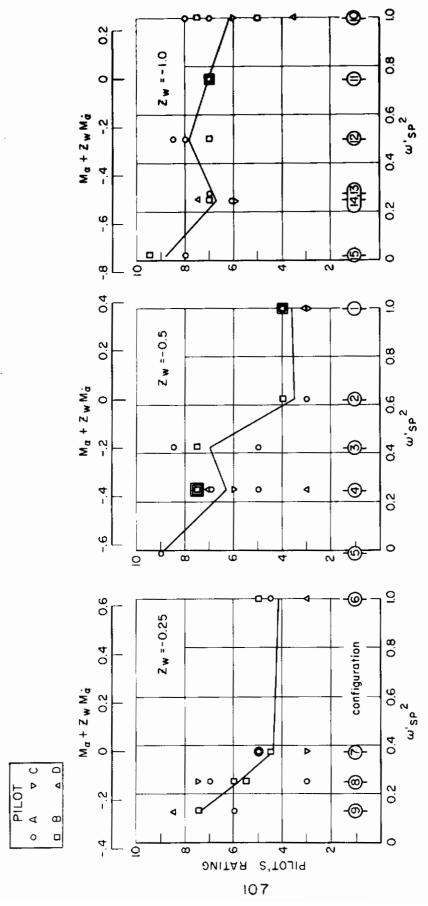
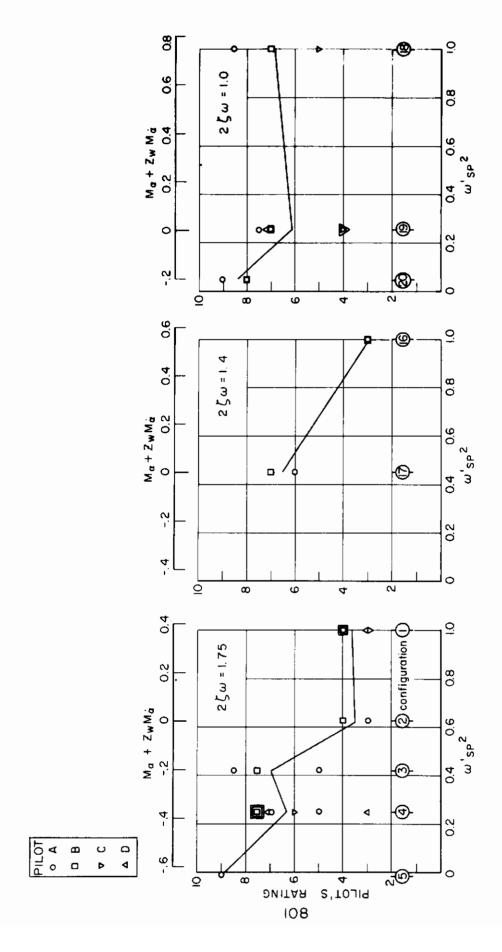


FIG 13 LOCI OF SHORT PERIOD ROOTS AND OF ROOTS CHARACTERIZING THE HIGH FREQUENCY PITCH RESPONSE TO ELEVATOR 106

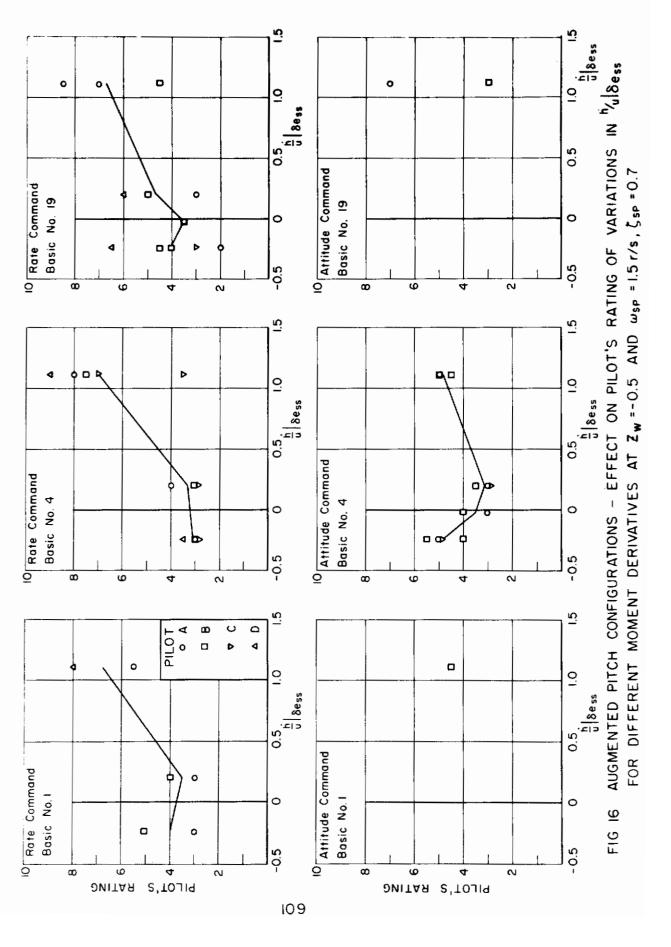


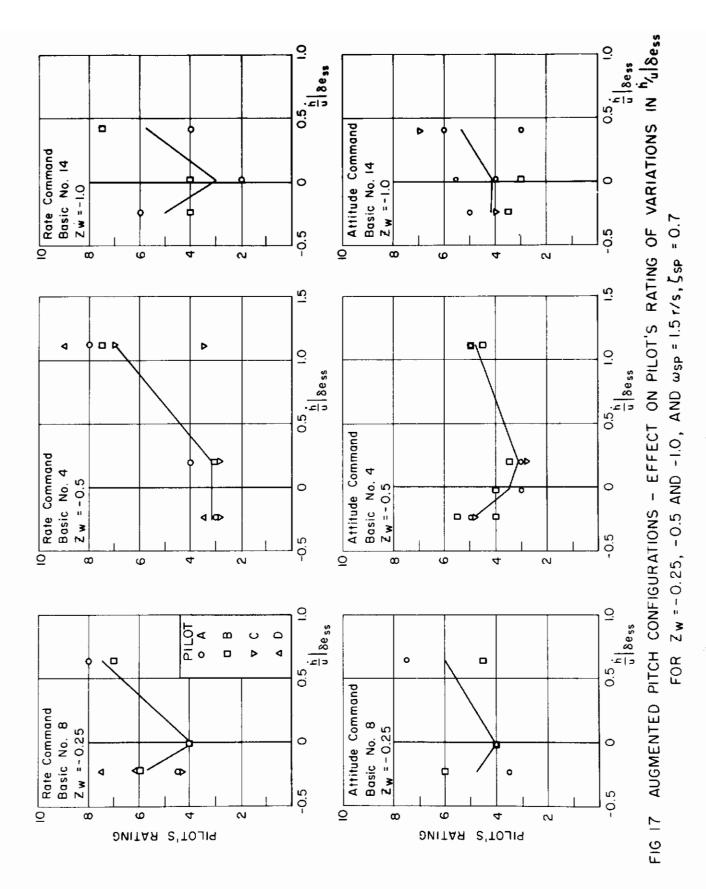


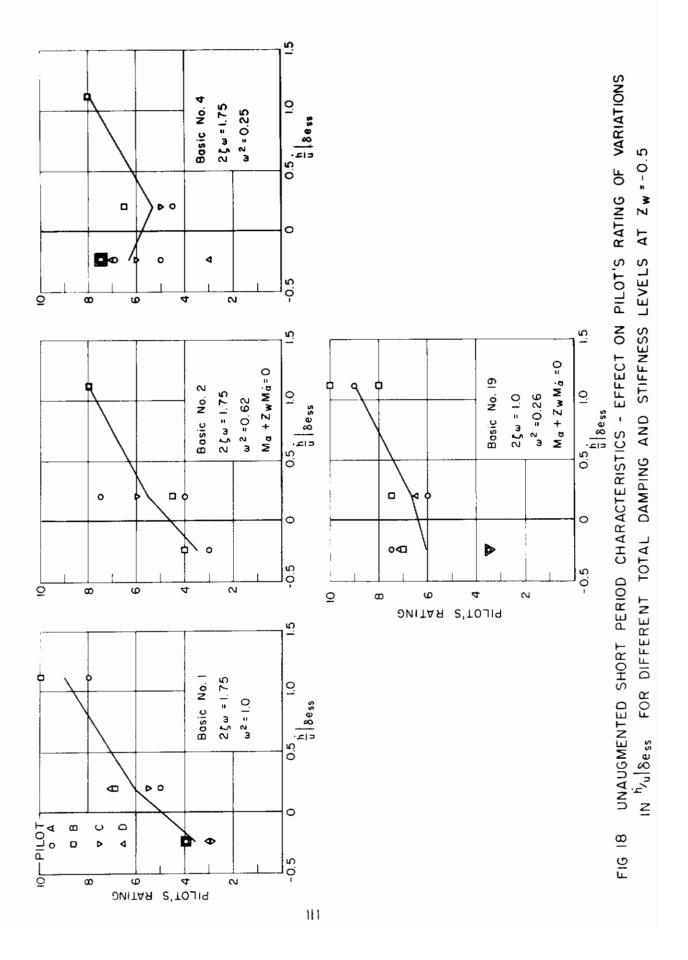
UNAUGMENTED SHORT PERIOD CHARACTERISTICS - EFFECT ON PILOT'S RATING OF VARIATIONS IN MA FOR 25 wsp = 1.75 AT DIFFERENT ZW F1G 14

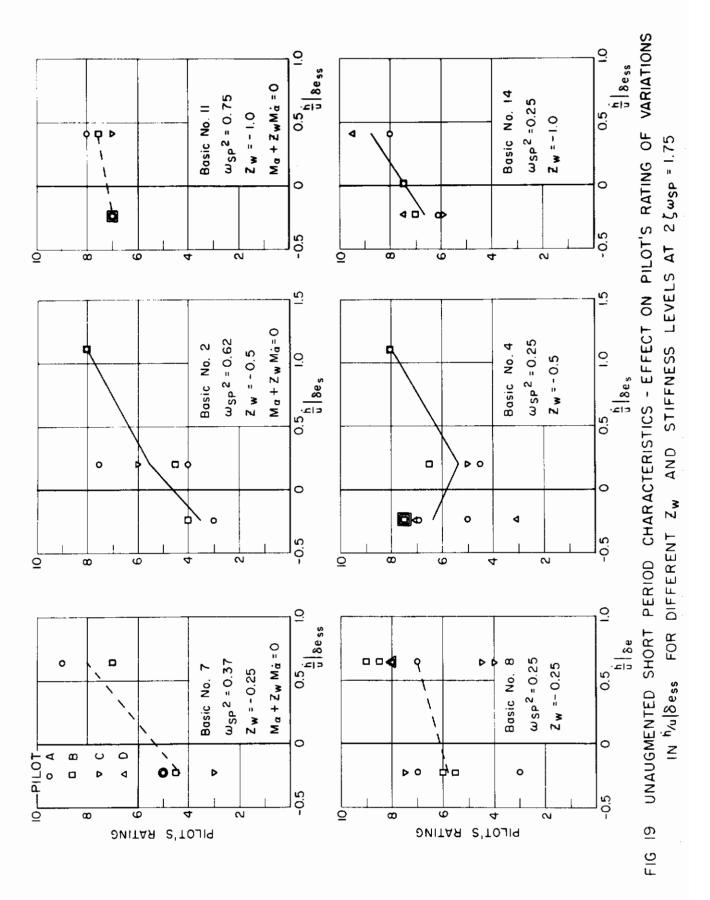


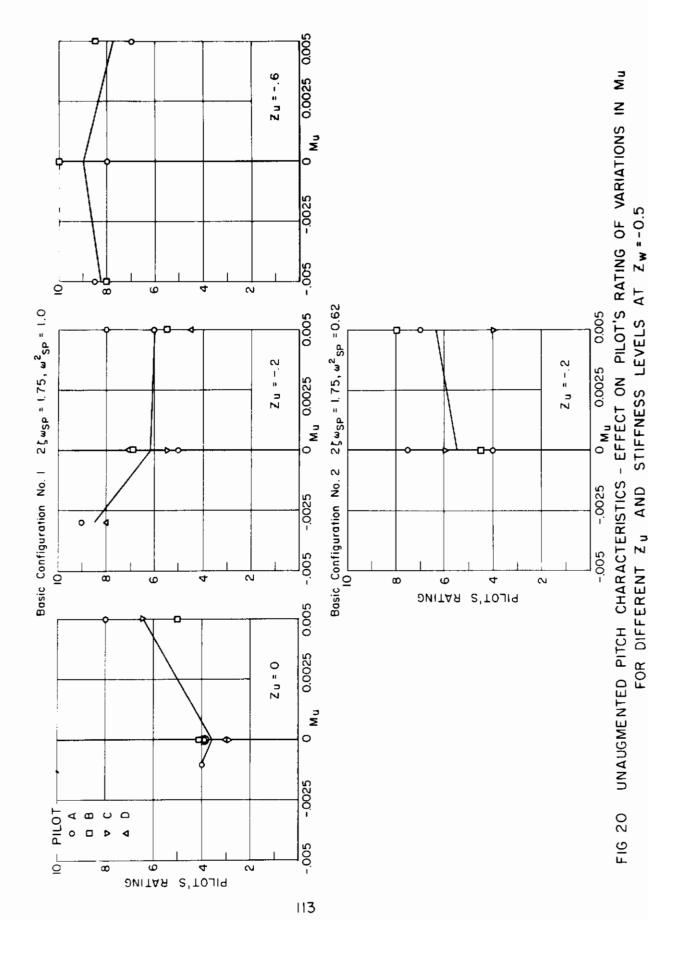
UNAUGMENTED SHORT PERIOD CHARACTERISTICS - EFFECT ON PILOT'S RATING OF VARIATIONS IN Ma Zw=-.5 AT DIFFERENT DAMPING LEVELS FOR F1G 15

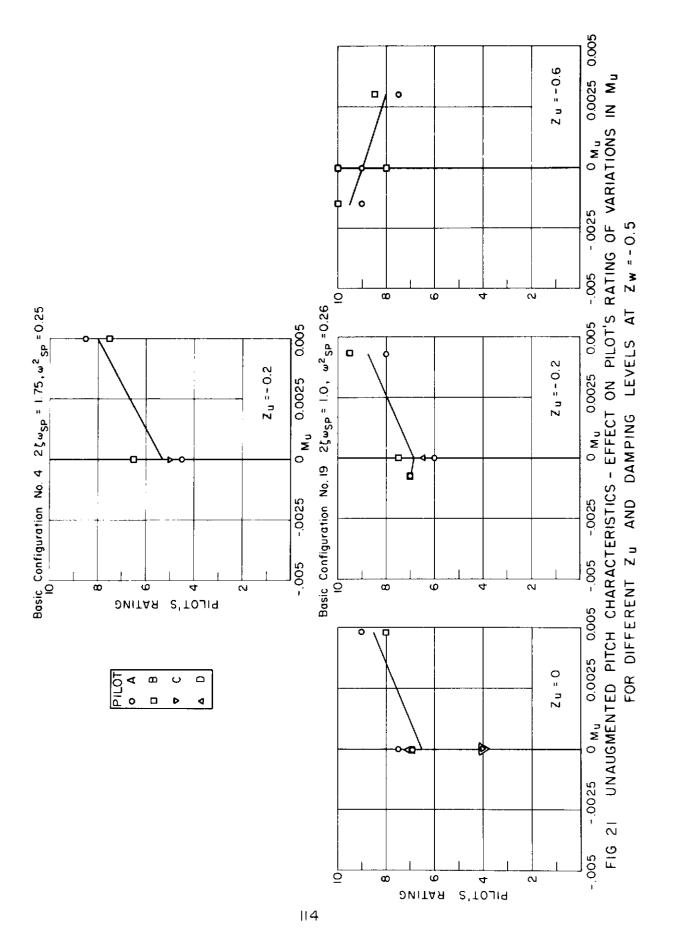


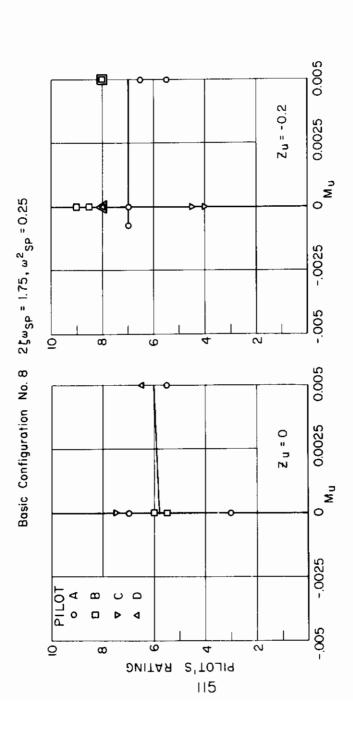




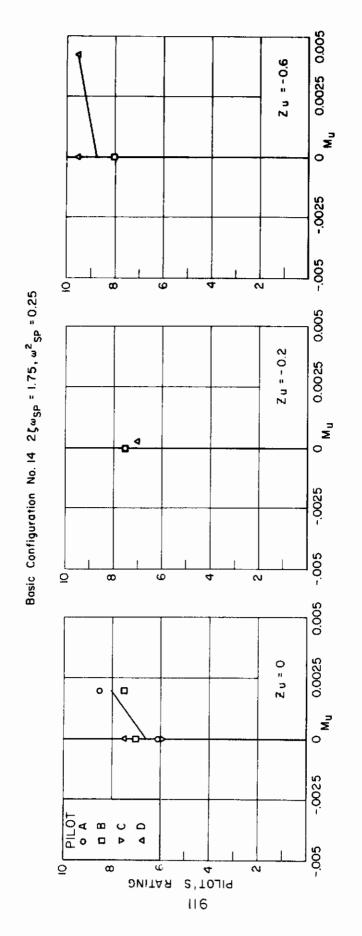




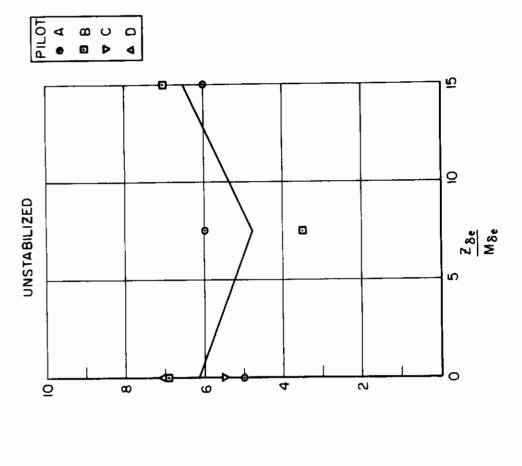


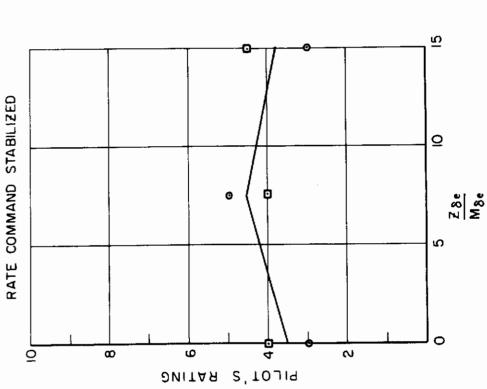


UNAUGMENTED PITCH CHARACTERISTICS - EFFECT ON PILOT'S RATING OF VARIATIONS IN Mu FOR DIFFERENT Z u AT Z w = -0.25 FIG 22



UNAUGMENTED PITCH CHARACTERISTICS - EFFECT ON PILOT'S RATING OF VARIATIONS IN Mu FOR DIFFERENT Zu AT Zw = -1.0 FIG 23





ON BOTH STABILIZED AND UNSTABILIZED CONFIGURATIONS BASED ON NO 1-2 FIG 24 EFFECT ON PILOT'S RATING OF VARIATIONS IN \$28.



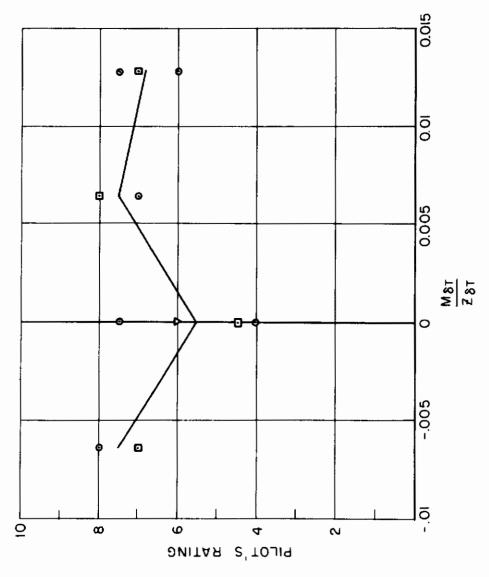


FIG 25 EFFECT ON PILOT'S RATING OF VARIATIONS IN M8T NO 2-2 ON CONFIGURATIONS BASED ON

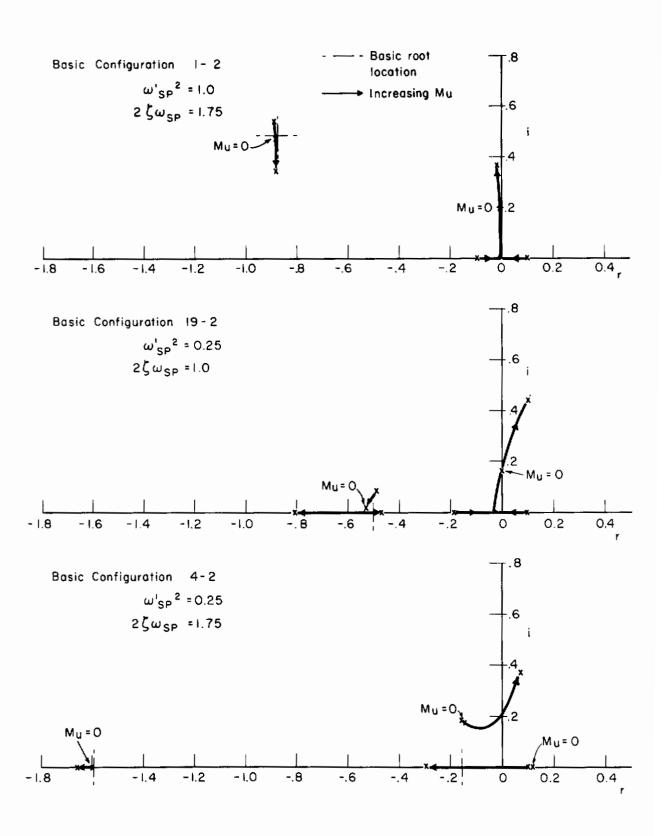


FIG 26 EFFECT ON ROOT LOCI OF VARYING Mu
FOR CONFIGURATIONS WITH DIFFERENT LEVELS OF SHORT-TERM STIFFNESS
AND TOTAL DAMPING

119



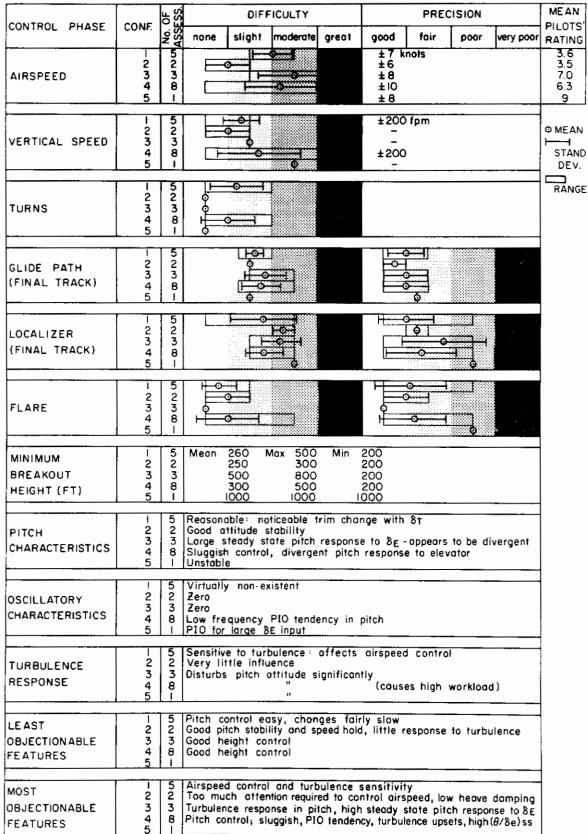


FIG 27 GROUP I : EFFECT ON PILOT'S ASSESSMENT OF TASK DIFFICULTY AND PRECISION; Ma VARIATIONS FOR Zw=-0.5 AND 2ζω'Sp=1.75



		DIFFICULTY			PRE	CISION		MEA
CONTROL PHASE	CONF.	No. OF ASSESS.	none slight moderate great	good	fair	poor	very poor	
	7	4		±91	inots			4.4
AIRSPEED	2	2		±6				3.5
AINS! EED	11	3		±ΙΟ				7
	7	4	<u> </u>	±250) fpm			Ì
VERTICAL SPEED	2	3	1 6 3	±200)			о мед
	["	"						STA
		1	1 2 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4					DE
	7	2						RAN
TURNS	<u>ī</u>	3	H 					
	7	4	6		ø		88 3.1	
GLIDE PATH	2	2	φ	-0-	∃			
(FINAL TRACK)	11	3	1-0-1		7. 6	·		
	<u> </u>				<u> </u>		88	
	7	4	 ©	<u> </u>	O	d		
LOCALIZER	2	2 3			-0-1		806	
(FINAL TRACK)	''							
	7 2	4 2			<u>~</u>	1]		
FLARE	ាំ	3	101		0 →			
	7	T	Man 250 No. 500 Nie	200				Į .
MINIMUM	7 2	4 2	Mean 350 Max 500 Mir 250 300	200 200				
BREAKOUT	В	3	450 500	300				
HEIGHT (FT)								1
	7	4	Good stability and damping, b	ut some	wander			1
PITCH	2	2	Good attitude stability					
CHARACTERISTICS	11	3	Poor, high $(\theta/\delta e)_{SS}$, needs	close atte	ntion			ļ
								1
	7		Zero					1
OSCILLATORY	2	3	Zero Slight PIO tendency in pitch	- long se	riod			
CHARACTERISTICS	"		onghi i to rendency in phon	long pe	1100			Į
								1
TURBULENCE	7	4 2	Very little influence					
RESPONSE	2	3	Disturbs pitch					
								-
LEAST	7	4	Good pitch stability and speed	hold, litt	le respo	inse to t	urbulence	ļ
OBJECTIONABLE	2 	2	None					
FEATURES								
	7	4	Thrust modulation; nose wan	der				-
MOST	2	2	Too much attention required to		irspeed:	low heav	e dampina	
OBJECTIONABLE	П	3	Pitch control, turbulence and	E offect	pitch ar	nd speed		
FEATURES						und	esirably	

FIG 28 GROUP I: EFFECT ON PILOT'S ASSESSMENT OF TASK DIFFICULTY AND PRECISION; BASIC CONFIGURATIONS WITH Z_{w} VARIATIONS AT $2\zeta\omega^{'}_{SP}$ =1.75



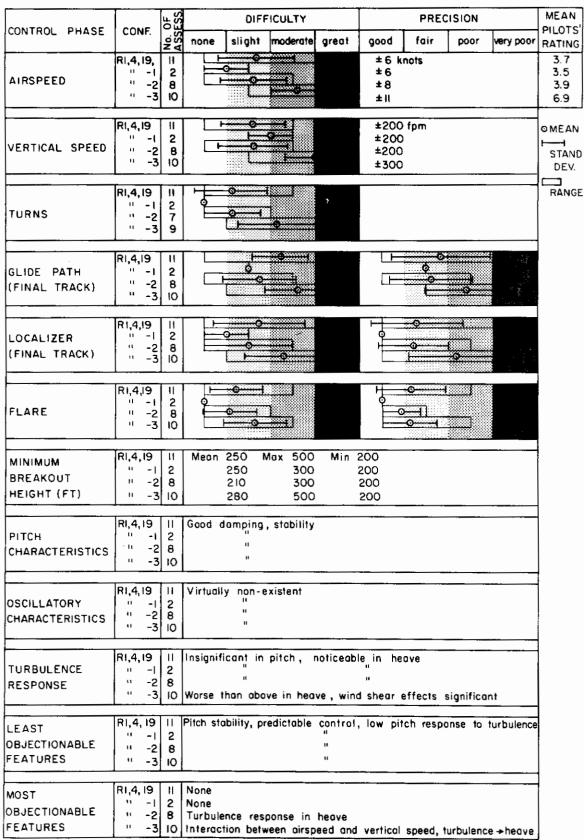
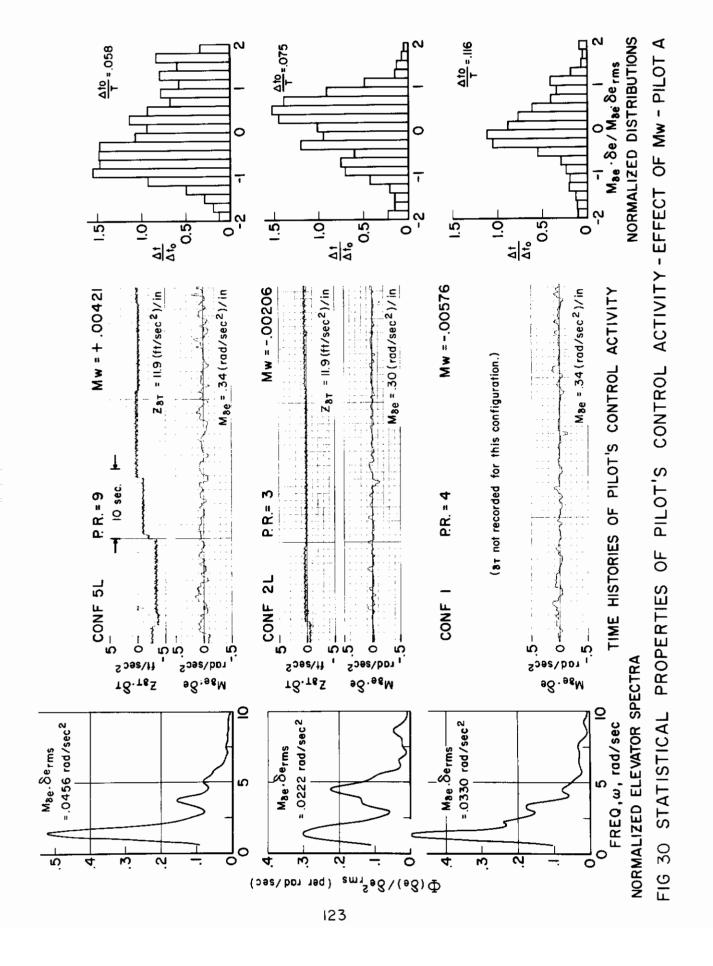
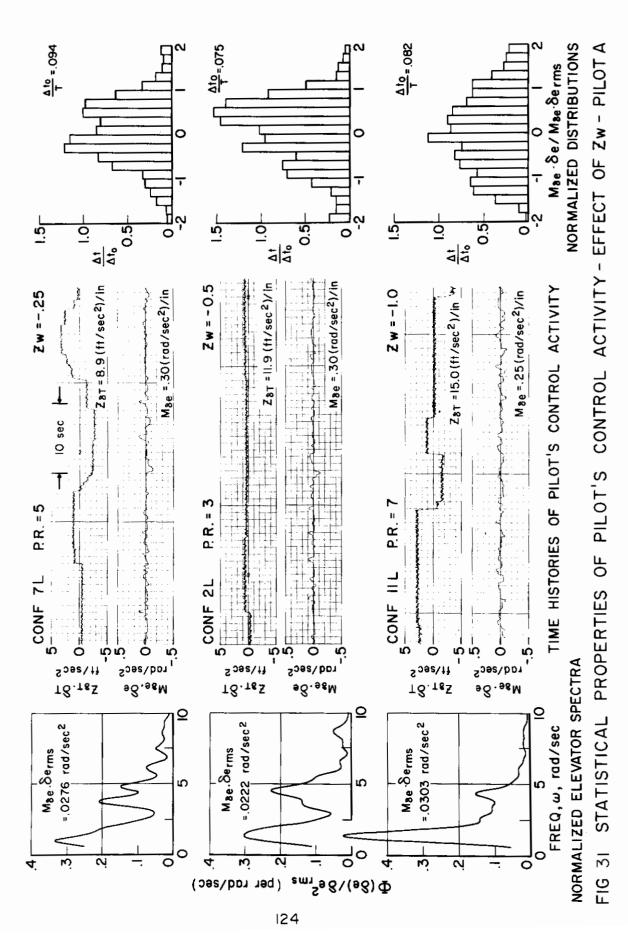


FIG 29 RATE COMMAND SYSTEM : EFFECT ON PILOTS' ASSESSMENT OF TASK DIFFICULTY AND PRECISION: Zu VARIATIONS AT Zw =-0.5







4 Zu=O not analysed for pilot

Zu = -. 2 not analysed for pilot A

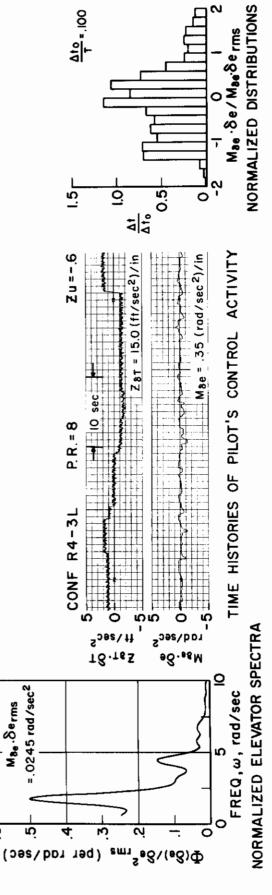
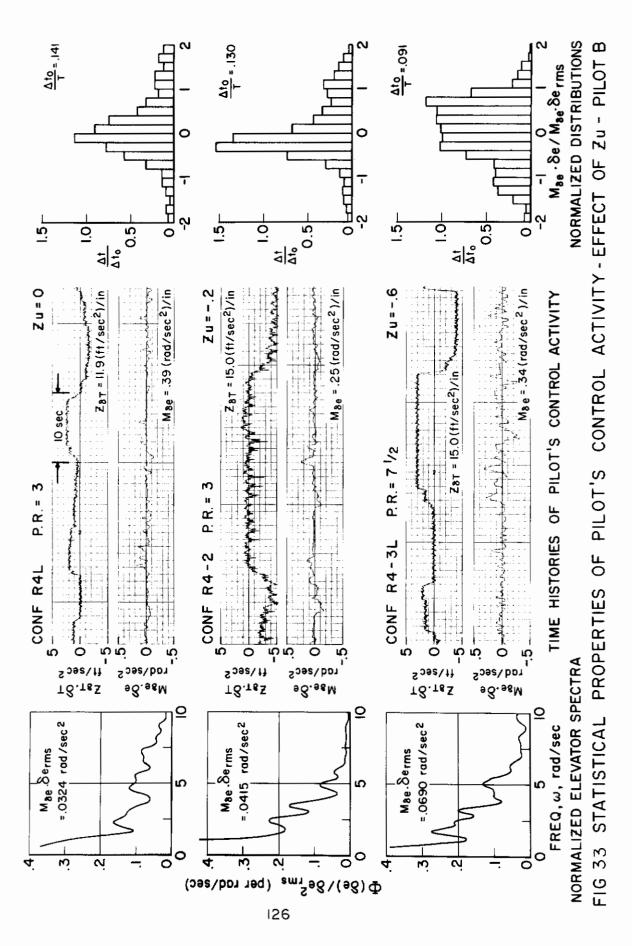
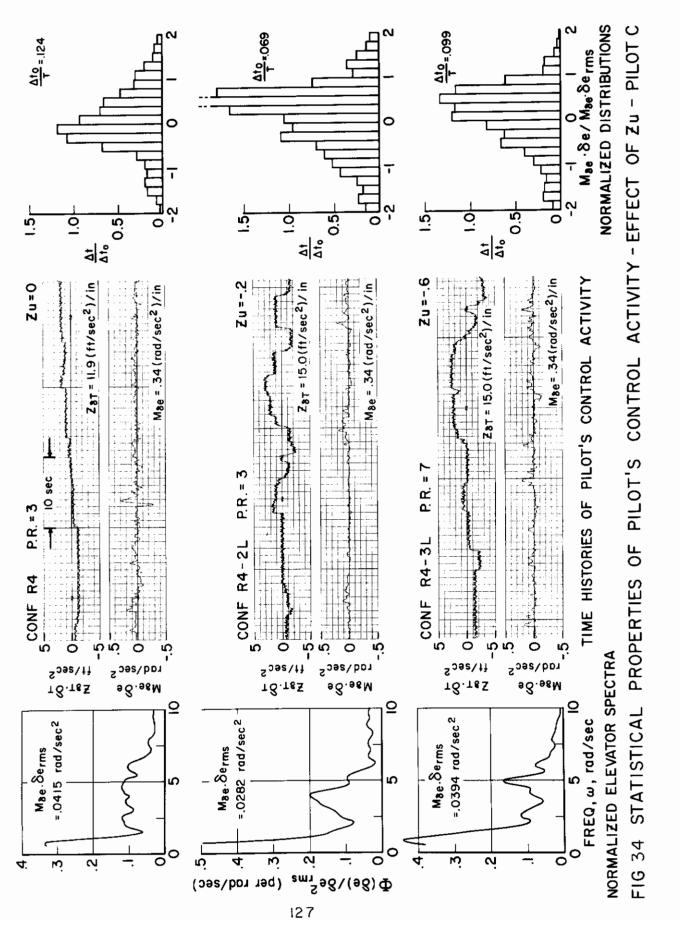


FIG 32 STATISTICAL PROPERTIES OF PILOT'S CONTROL ACTIVITY - EFFECT OF Zu - PILOT A

Mae Serms





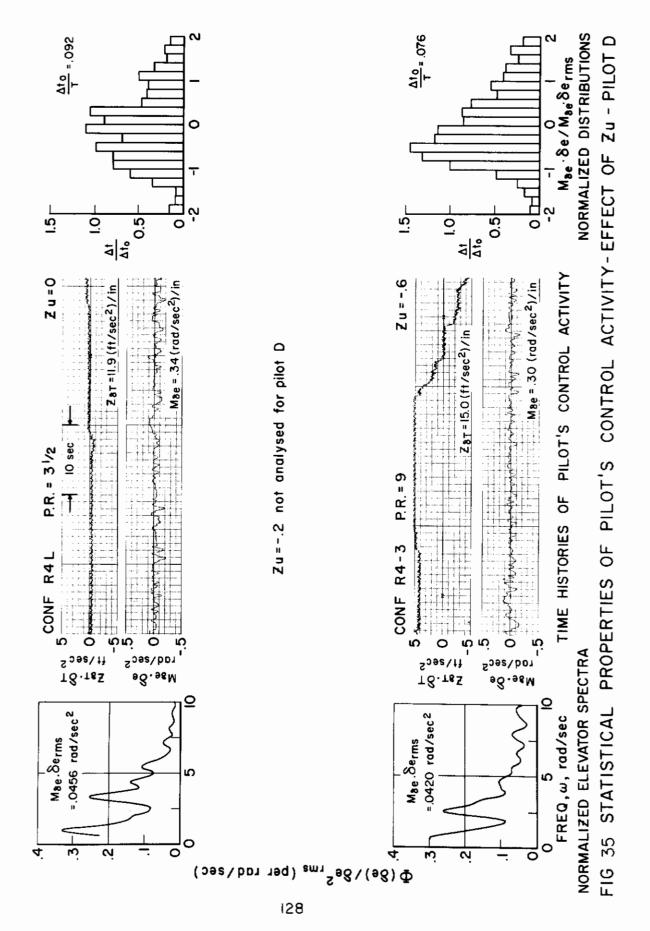


TABLE I LONGITUDINAL DERIVATIVES OF CONFIGURATIONS EVALUATED

	T										 						 				
ZSE /MSE		0		-		→	 0			-	 0	_					0	→	0		-
ΥZ		7:	_			→	25				-1.0	_	····				 5:	→	5		-
Zu		0	_			→	0			→	0	_				→	0	→	0		→
M61/Z61		0				→	0			>	0				_	→	0	->	0		→
Ψθ		0				→	0				0						0	-	0		→
M		00412				-	00493				00247					>	00296	-	00220		→
M _w		00576	00206	0	+.00165	+.00421	00740	00123	0	+.00118	00493	00247	0	+.00222	+.00247	+.00473	 00692	00148	0087 ⁴	41100	+.00102
M,		0				-	0			-	0					>	0	→	0		>
Mq	RISTICS	833		•		-	 -1.0				50	_				>	09:-	→	295		→
	PERIOD CHARACTERISTICS									, III								. "	••		
Conf.		ч	c _V	m	†	2	9	7	ω	6	10	11	12	13	14	15	 16	17	18	19	20
Group	I SHORT		,,																		

Group	Conf.		Mq	Mu	Mw	Μ∵	M_{Θ}	$M_{\delta_T}/Z_{\delta_T}$	$\mathbf{z_u}$	$Z_{\mathbf{W}}$	$z_{\delta_{\epsilon}}/M_{\delta_{\epsilon}}$
VA.	VARIATIONS OF FLIGHT PATH CHARACTERISTICS IN	F FLIGHT	PATH CHAR	ACTERISTI	CS IN THE	PRESENCE	OF GOOD	THE PRESENCE OF GOOD PITCH CONTROL CHARACTERISTICS.	TROL CHAR	ACTERISTI	cs.
린 _	(PITCH SAS with ATTITUDE (PRE 	rith ATTI 	rude (pref 	FIX A) and 	RATE	(PREFIX R) CC	COMMAND FORMS)	RMS)			
	R 1		-1.57	0	00576	00412	-1.65	0	0	5	0
	R 1-2		-1.57				-1.64		2.5		
	R/A 1-3		-1.58				-1.64		9	-	
	B/A 4		-1.82	C	+.00165	-,00412	α, α	c	c	ر. ا	C
	A 4-1		-1.82	. —	<u> </u>		-2.8	, —	, ;	· —	
	R/A 4-2		-1.85				-2.8		5		
	R/A 4-3		-1.93	>	-	>	-2.93	>	9	→	>
	סר		-1 87	c	(1100)	00000	C C	c	c	ע	c
	R 19-1		-1.87	,		-	: -	, -	· .	· -	, –
	R 19-2		-1.89						2		
	R/A 19-3		-1.89			->			9		-
	R/A 8		-1.62	0	0	€6400	-2.37	0	0	25	0
	R/A 8-1	·			_	_	_		05	_	_
	R/A 8-2		>			→			5.5	-	→
	R/A 14		6.	c	9¶200°+	74500°=	ر در ا	C	c	0,	c
	R/A 14-1		<u> </u>	, -		-	; –	· —	. 2.	-	, –
	R/A 14-2			>	>	-		→	9		→



 $Z_{\delta_{\epsilon}}/M_{\delta_{\epsilon}}$ -1.0 **-.**25 $Z_{\mathbf{W}}$ 9: -.2 9.-٠. د 9.--.2 9.-9.-**-**.2 9.- $Z_{\mathbf{u}}$ SIMULTANEOUS VARIATIONS IN BOTH SHORT AND LONG TERM CHARACTERISTICS THROUGH $\mathbf{z_u}$. $M_{\delta_1}/Z_{\delta_1}$ ¥Ρ -.00412 -.00247 -.00220 -.00493 Σ -.00247 -.00576 -.00874 -.00206 -.00123 -.00576 -.00206 +.00165 +.00165 +.00247 +.00247 ¥ χ -.833 -.295 Σ Conf. 1-3 2-5 2-3 4-3 7-2 8-2 19-2 19-3 11-2 14-1 14-2 Group III

TABLE I (III) (cont'd)

	$Z_{\delta_E}/M_{\delta_E}$	0					→	0	0	0						0		-	0	0		_
	Z																			 		
	Z	5				,	-	.5	3.5	.5	_					25		-	-1.0	-1.0	_	-•
	$\mathbf{z}_{\mathbf{u}}$	Mu. 0	0	+.2	2	9	9	5.5	5.	0	0	2	2	9	9	0	5.5	2	5.5	0	2	6
	M6, /Z6,	AND LONG TERM CHARACTERISTICS THROUGH	_				-	0	0	0					-	0	_	-	0	٥		-
	Мθ	CTERISTI(0					-	0	0	0						0	_	-	0	0		-
	M.	ERM CHARA						7.00412	00412	-,0022					→	00493		→	00247	00247		
	M	ND LONG T00576					-	00206	+.00165	00114	_				-	0		→	00247	0		•
	Mu	BOTH SHORT A	001	+.005	003	+.005	005	+.005	+.005	+.00¼8	0003	+.0043	00075	+.003	0015	+.005	+.005	00075	+.0029	+.002	+.00025	+.00h25
(cont'd)	Mq							833	833	295						-1.0	<u></u>	→	5	5		-
LE I (IV)		US VARIATIONS IN																				
TABLE	Conf.	SIMULTANEOUS	1-N	1-2P	1-2N	1-3P	1-3N	2-2P	4-2P	19-P	19-N	19-2P	19-2N	19-3F	19-3N	8-P	8-2P	8-2N	11-11	14-P	תנ−קנ	14-2P
	Group	us vi	•														"		##. 3 .41	 		

TABLE I (V) (cont'd)

Group	conf.	Mq	Mu	Mw	M.	Mβ	$M_{\delta_T}/Z_{\delta_T}$	Zq	zθ	Zu	Zw	$z_{\delta_E}/M_{\delta_E}$
V EF	FECT OF NO	ON-ZERO Z&	E /MSE ON E	EFFECT OF NON-ZERO Zof /Mor ON SELECTED CONFIGURATIONS	NFIGURATI	SNO						
<u> </u>	CONFIGURAL	ION 1-2 WI	TH AND WIT	(CONFIGURATION 1-2 WITH AND WITHOUT PITCH SAS)	(SAS)							
	1-21	833	0	00576	00412	0	0	0	0	1.2	5	7.5
	1-22	=	=	Ξ	=	=	=	0	0	=	=	15.0
	R1-21	-1.57	0	00576	00412	-1.64	0	-11.8	-12.3	5.5	5	7.5
	R1-22	:	ε	=	=	:		-23.6	-2 ⁴ .6	:	=	15.0
VI I	SFECT OF 1	NON-ZERO N	461 /Z61 ON	VI EFFECT OF NON-ZERO M ₆₁ /Z ₆₁ ON CONFIGURATION 2-2	rion 2-2							
	2-21	833	0	00206	00412	0	±,0064	0	0	5.5	5	0
133	2-22		-				+.0064		-	-		

For all the above configurations, the X-force derivatives are given by:

$$x_u = -3M_u - .04$$

$$X_W = -3M_W - .03$$

$$X_{\bf q} = -3M_{\bf q} - .022$$

 $X_{\bf \theta} = -3M_{\bf \theta}$

$$X_{\delta_E} = -3M_{\delta_E}$$

$$X_{\delta_1} = -3M_{\delta_1}$$

 $U_o = 60 \text{ knots}$, $\theta_o = -7 \text{ degrees}$, $W_O = U_O (\theta_o - \gamma_O)$ The operating point conditions were



Table II Predominant molal parameters of configurations evaluated : $U_o = 101.3$, $W_o = 1.77$, $\theta_o = -.1222$

• না	u Če ss		238				→	227			-	242	_				-	 238	± .	238		→
₹ (S)	λ2		039	_				039	_		-	039	_		******			039	:	039		-
> \ ×	λ1		040	_			→	040			-	040	_					040	;	040		
N h (S)	γ1		075				→	073			-	077					-	075	=	075	_	→
N 3 (S)	λ1.		460				→	232				92					→	-,460	:	460	_	-
(8)	λ2		50				→	25				-1.0	_			-	-	50	:	50		
N & (S)	λ1		040					040			→	±0						040	:	070		
	λt		1,4801	-1.24	-1.45	-1.58	-1.74	1674.	-1.49	-1.58	-1.66	.4761	-1.00	-1.38	-1.57	-1.58	-1.73	.7101	188	.8751	.0581	959
	λ3		-,864±	499	298	192	102	860±	250	171	116	865±	733	369	212	199	116	685±	500	492±	500₹	101
	γ5		040	040	0,00-	0 [†] 0	040	040	040	040	070	010	040	040	040	040	0,00-	040	040	040	040	040
	γ1	RISTICS	023	013	0	.021	.093	030	013	0	,024	020	•.013	0	920.	.031	.093	028	013	034	018	.042
		CHARACTERISTICS								•		-	-					·				
	Conf.	SHORT PERIOD	п	a	m	<i>a</i>	~	9	۲	80	٥,	10	п	12	13	17	15	16	17	18	19	50
	Group	ions i																			74	



TABLE II (II) (CONT'D)

	7	۵		N (S)	s)	$\frac{u}{\delta}$ (s)	$\frac{h}{\delta}$ (S)	$\frac{W}{\delta}(S)$	(S)	
1	λ2	λ3	γη	λ_1	λ2	λ1	λ1	λ_1	λ2	uloess
			PRESENCE O	F GOOD PI	PRESENCE OF GOOD PITCH CONTROL CHARACTERISTICS	OL CHARAC	TERISTICS	(PITCH	SAS WITH	
Η.	COCCAND FORM).	FLEVATOR	ON TROP	I TOJI	CONTROL OUTPUT IS ROBIFIED AS SHOWN IN FIG. 5	L MANORE O	7 .514	LON THE R	3.TH	
.379	040	-1.05±	1,061	040	500	-,460	075	040	039	238
.336	082	-1.06±	1.051	027	513	_	.063	041+	.2511	197
.208±	.0981	-1.07±	1.03i	100°-	536	→	.350	-,044	.4321	1.07
	040	-1.06±	1.061	040	500	460	075	040	039	238
	029	-1.05±	1,061	U34	905		900	040	.178i	019
	019	-1.06±	1.041	027	513		.063	041+	.2511	761.
	.015	-1.08±	1.05i	+000-	536	•	.350	044±	4321	1.07
	040	-1.05±	1.081	070	500	-,460	075	0,00-	039	238
	037	-1.05#	1.081	034	905		900 -	040-	.1781	019
	034	-1.05	1.071	027	513		.063	041∓	.2511	761.
	022	-1.05±	1,06i	100°-	536	-•	.350	- ,0¼¼±	,4321	1.07
	0,00-	-1.05±	1,061	040	250	232	072	070	039	227
	033	-1.05±	1.06i	033	257		004	040-	.1261	1110
.312	01h	-10°t-	1.061	015	276		.206	041±	.2511	.635
	040	-1.06±	1.051	040	-1.00	919	077	040	039	545.
	028	-1.05±	1.06i	034	-1.01		008	041±	.2511	420
	007	-1.03±	1.071	022	-1.02	→	.133	0¼¼±	,432i	.413



u o ess .197 1.07 .197 1.07 •635 .413 .197 1.07 1.197 .635 ,024 .413 1.07 .2511 2511 2511 2511 .2511 4321 4321 4321 .2511 4321 N V (S) -,044--.041± -.04h+ -.041± -.044± -.041+ -.041+ -.044± -.041± -.011± -.044± ÷440.--.041+ $\left(\frac{n}{s}, \frac{h}{\delta}, \left(s\right)\right)$.063 .063 .350 .063 .350 .206 .133 -.008 .133 .350 .206 $\frac{1}{5}$ (S) -.919 -,460 -.232 - .513 - .276 SIMULTANEOUS VARIATIONS IN BOTH SHORT AND LONG TERM CHARACTERISTICS THROUGH - .536 .513 .513 - .276 .513 - .536 .536 .536 -1.02 -1.01 -1.02 $\frac{\theta}{\delta}$ (S) -.004 -.015 -.015 -.022 -.022 †00 --.027 -.004 -.027 100. -.034 -.027 -.027 ٧, ,476i .4711 .0201 649. --1.26 -1.60 -1.30 -1.60 -1.04 -1.60 -1.63 -1.51 -.886± -.530± -.926± -.492 -.510 -.504 .175 -.783 .119 -.261 .152 .227 ◁ .1941 .3211 2451 1811 ,1431 .145i .2891 1631 2601 2421 .1151 .1931 3021 -.010± 0 ± .040± -.027± -.013± .016± -.015± .006± -,157± -.098± -.169± -.173± -,196+ Conf. 1-2 1-3 2-3 4-2 4-3 19-2 7-2 8-2 11-2 14-2 14-1 Group H

TABLE II (III) (CONT'D)

.242 n ess - .238 238 .238 - .227 .635 .635 •02₫ .024 .413 - .238 197 .197 .197 .197 .197 .197 1.07 1.07 .2511 .2511 2511 ,432i .2511 .2511 .2511 .25li .25li 2511 ,432i 4321 .432i .251 4321 -.039 -.039 -.039 -.039 ¢ (S) -.041± -.04 -.041± - 041± **-**.0¼4∓ -,044± -.041± -.041± -.041± -.041# -.0h+± -,044± -.0⁴1± **-**,0¼± -.041± 040 -.040 -.040 -.040 ĭ ћ (S) -.075 .063 .063 .350 .350 -.075 -.075 .063 .063 .350 -.072 .206 .206 -.008 -.008 .133 .063 .063 .350 -.077 71 Z رع ه (ع) -.160 -.460 -,160 -.232 -.919 -,460 --919 γ, z SHORT AND LONG TERM CHARACTERISTICS THROUGH M .500 - .500 - .250 .500 .500 .513 .513 .536 .513 .513 .513 .513 -..536 .276 .276 .536 - .536 -i-00 -1.01 -1.02 -1.01 $\frac{7}{2}$ & (S) -.040 070.--.040 -.015 -.040 -.040 ±.00 -.015 -.027 -.027 -.034 -.040 -.022 -.004 -.027 -.027 -.027 <u>-</u>.004 -.034 100°--.027 7 .5041 3381 .3461 .5411 .3581 .0781 .5681 .0851 .0851 - .809 - .808 - .801 -1.66 -1.37 -1.65 -1.06 -1.67 -1.59 -1.60 -1.60 -1.66 **-.857**± -.867± -.465 -.478± -,885± -,894± -.930± -,489± -,514= -.931± -.467 -,472 -.218 -.297 .196 .099 -.827 -.398 .106 -.349 -.48 ◁ .38 1 **T**††† .3701 .3361 .3531 302i .3081 .3631 ,4411 .1571 ,4401 .4211 1251 3521 .1621 .3801 -.153 -.200 -.183 -.106 -.097 SIMULTANEOUS VARIATIONS IN BOTH 10 + .024± 040∓ ,021± ±470. 101± 101 .10 ± -.019± 102± .032± .028± .152± .043± -.149= 100 104 .077 1-2P 1-3P 2-2P Conf. 1-2N 1-3N 4-2P 19-2P 19-3P 19-2N 19-3N 8-2P 8-2N 11-1P 14-1N 19-P 1-P 1-N 19-N 14-P Group 2

TABLE II (IV) (CONT'D)



TABLE II (V) (CONT'D)

				₫			и 8 (s)	s)	$\frac{u}{\delta}$ (S)	N h (S)	N \$ (S)	(8)	•.वाः
Group	Conf.		γ1	γ2	γ3	η,	λ_1	γ5	γ,	γ1	λ1	λ2	aloess
V EF	EFFECT OF	(NON-ZERO	Z ₆₋ /M ₆₋ ON SELECTED CONFIGURATIONS	N SELECTED	CONFIGURA	TIONS					-		
၁)	ONFIGURAT	TION 1-2 W	(CONFIGURATION 1-2 WITH AND WITHOUT PITCH SAS)	THOUT PITC	H SAS)						•••		
	1-51		-010·-	.1941.	886±	.4761	026	-,485	432	620.	038±	.2441	.239
	1-22		010±	.194i.	886±	.4761	025	0.456	402	.100	035±	.2381	.290
	R1-21		088	308	-1.04+	1.031	026	485	η£η	.078	039±	.252i	.239
	R1-22		960	276	-1.03±	1.01i	025	954	904	960*	036±	.2531	.290
NB		ANSFER FUN	6 TRANSFER FUNCTIONS FOR R1-21	-	NI NWORS ACCEPTATER SHAFF AS SHOWN IN	S FURTHER	SHAFTD AS	SHOWN IN	FIG. 3.				
±a I∧	FECT OF 1	NON-ZERO M	EFFECT OF NON-ZERO M _{&T} /Z _{&T} ON CONFIGURATIONS 2-2	CONFIGURAT	TONS 2-2								
	2-51		015±	.1451		-1.26	027	513	460	.063	041±	.2511	191.
	2-55					_							
	2-23		-	•	-	•	>	•		-		-•	-
vi (c	(CONT'D)		θ										
			$^{ m Z}_{ m o_{ m T}}{}^{ m o_{ m T}}_{ m ss}$										
	2-21		0127										
	2-5		-,0061										
	2-55		9000*										
	2-23		.0072										



TABLE III Pilots' Comments

The pilots' comments are arranged in the sequence of Tables I and II.



CONFIGURATION 1 FLIGHT NUMBER 60-I PILOT A PILOT-RATING 4

CHARACTERISTIC ROOTS

(atona)ONIW WIND SHEAR SMAIL EXTERNAL TURBULENCE LIGHT

-,02 -.04 -.86± .481

CONFIGURATION 1
FLIGHT NUMBER 129-1
PILOT A
PILOT-RATING 4

WIND(knots) 8
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTER:STIC ROOTS -.02 -.04 -.86 ± .481

I AIRCRAFT RESPONSE TO CONTROL INPUTS

ELE	VATOR	THRUS	T LEVER
M&E = 0.34	(rad/sec ²)/in	Z81= 11.9	(ft/sec ² /n
Initial	Fingl	Initial	Finol
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FOUCTUATIONS

Longila	d-nal veloci	ly ([AS]	Vert	cal velocity	(fi) ~ ·
VMC.	[MC	: NF C	VMC	IMC	INC
OUT	OUT	IN	OUT	OUT	IN
51.1GH T	SLIGHT	MUDERATE	\$1.IGHT	SLIGHT	SLIGHT
+1(i, -s	Knafs	1 200		f.pm.

COMMENTS

THE STRONG DEPENDENCE OF ALKSPEED ON PLTGA ATTITUDE MAKES ARE A DIFFICULT ALKSPEED HOLDING TASK EVEN WITH THIS FAIRLY GOOD MODEL.

ELE1	ATOR	THRUS	LEVER
Mae: 0.25	(rad/sec2)/in	Z ₈₇ : 11.9	(fi/sec²)/·n
Initial	Final	Initial	Final
SATISFACTURY	TOO GREAT	SATISFACTORY	SATISFACTORY

Longitu	idinal veloci	ity ([AS)	Vert	ical velocity	(6)
V.M.C	LMC.	LMC	VMC	1.M.C.	LMC
ōu-	QUT	il.	CUT	OUT	1N
NONE	SLIGHT	MODERATE	NONE	SLIGHT	SLICHT
+	105	Kno's	0 K		1p

PITCH ATTITUDE VARIED CONTINUOUSLY WITH SHALL OUT-OF-TRIM ON BLEVATCH AND WITH TURBULENCE. MIDBEATE PITCH TRIM SEQUENCED TO COMPENSATE FOR CHANCES OF DESCENT BATE. INCREASING AIRSPEPEN APPEARED TO PITCH THE MOSE DOWN, ALL THE ABOVE FACTORS CONTRIBUTED TO AIRSPEED PROBLEMS.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPL TUDE	PERIOD	DAMP NG
ZERO		
25k0		

EXCITATION CONTROL

SOURCE DEGREE	SOURCE DEGREE		
		SOURCE	DEGREE

AMPLITUDE PERIOD DAMPING SOURCE

COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

SMALL	
SLIGHT	DIFFICULTY

VEGLICIBILE VO DIFFICU_TY

SLIGHT

FAIR

5 F. IGHT PATH CONTROL

DIESICULTY PRECISION

COMMENTS:

	of & initial track Intermediate track Final track				
Glide poth	Localizer	Glide polh	Localiter	Gude path	Local-zer
SLIGST	SLIGHT	MODERATE	SLIGET	SLIGHT	SLUME
GMD	G005	PA] ₹	3000	(1000)	COOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

THE AIRSPEED CONTROL CAUSED ENOUGH PROBLEMS TO ROQUER A GREATER CONCENTRATION THAN DESIRED. HAD TO DESCEND AT 1200 F.M.M. FOR A WILLE DURING THE HIDDLE FORTION OF THE APPROACH AND THUS FELT UNCOMPONEDABLE.

NONE

GOOD

DIFFLOURTY PROBABLY DUE TO BEING SLIGHTLY RUSTY ON GROSS-CHECK.

Intercept B initial track intermediate track. Final track Glide path Localizer Glide path Localizer Glide path Localizer

SLEGST

RIAR

SLIGHT

FAIR

MODERATE

POOR

SLIGHT

FAIR

6 BREAKOUT AND FLARE

EASE OF ARRESTING MATE OF DESCENT PRECISION OF ATTAINING TOUCHOOWN POINT

SL13ET	DIFFICULT
FA1R	

GOOD DIFFICULTY

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM ...AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECT-ONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST CBJECT:ONABLE FEATURES

VLL CHANGES TAKE PLACE SLOWLY AND WITH MODERATE CONCENTRATION CAN BE CONTAINED WELL ENOUGH.

IO. WOST OBJECTIONABLE FEATURES

SEE SECTION #2.

I: V.SCELLANEOUS



CONFIGURATION [FLIGHT NUMBER 30-2 PILOT C PILOT-RATING) CONFIGURATION 1 FLIGHT NUMBER 21-2 PILOT D WIND (knois) CALK
WIND SHEAR REGLIGIBLE
EXTERNAL TURBULENCE LIGHT 10 W:NO(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT PLOT-RATING 3 CHARACTERISTIC ROOTS -.02 -.04 -.86± .481 CHARACTERISTIC ROOTS __.02 __.04 __.86± __.481 LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = 0.39 (rod/sec2)/n Zag = 11.9 (ft/ (ft/sec2)/in CONTROL SENSITIVITY: Includ Final Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (IAS)
VMC IMC IMC Vertical velocity (h) VM C OUT NONE OUT IN SLIGHT SLIGHT COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERICO AMPL TUDE AMPLITUDE SMALL - ZERO ZERD CEGREE SOURCE EXCITATION COMMENTS GENERALLY REASONABLE CONFIGURATION, SLIGHT P. 1.O. TENDENCIES, SOME OVERGENTROL BUT NOT MUCH. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED
EASE OF COMPENSATION NEGLIGIBLE SLIGHT NODERATE SLIGHT MODERATE DIFFICULTY DFFICULTY COMMENTS GAINED MEIGHT AND LOST UP TO 10 AMOTS AIRSPEED ON TURBS. SMALL AMOUNT OF FOMER ADDED IN TURBS. CONTROL OF AIRSPEED IS MAJOR PREOCCUPATION. DIFFICULTY DUE TO LAG IN SENSING NEED FOR POWER. 5 FLIGHT PATH CONTROL Intercept & miliot track | Intermediale track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Intercept 8 introl track | rtermediate track | Final Irack Glide path | Localizer | Glide path | Localizer | Glide path | Localizer DIFFICULTY NONE SLIGHT SLIGHT SLIGHT MODERATE NONE NONE SLIGHT SLIGHT >SLIGHT >SLIGHT PRECISION F GREATER THAN 200 FEET COMMENTS. BEHIND THE AIRCRAFT NEAR MINIMUM AUTITUDE - OK UNTIL LAST 00) FT. OR SO. 6 BREAKOUT AND FLARE EASE OF ARRESTING 9ATE OF DESCENT 80 DIFFICULTY PRECISON OF ATTAINING TOUCHDOWN POINT 6000 DIFFICULTY PCOR COMMENTS 7 CONTROL TECHNIQUE COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE

SEEMS MASY TO CONTROL ATTITUDE, AND POWER REQUIREMENTS WERE RELATIVELY MINOR. REASONABLE PRECISION OF CONTROL WITH MODERATE PLICT EFFORT.

LAG BEHIND TALAR WHEN ATTEMPTING CLOSE CONTROL NEAR MINIMUM ALTITUDE.

MAYHE I AM STILL OVERODNING LLING WEEN TALAR SENSITIVITY IS HIGH MEAR TOUCHDOWN,

CONSTANT ATTENTION REQUIRED TO CONTRO! ACKEPSED, PARTICULARLY IF VARIATIONS ECCED 5 CNOTS.

9 LEAST DBJECTIONABLE FEAT.. PES

ID MOST OBJECTIONABLE FEATURES

.! MISCE_LANEOUS



	CONFIGURATION I WINDIANOTY 5 FLIGHT NUMBER 35-1 WIND SHEAR NEGLIGIBLE FILOT FATTING 48:0 CXTERNAL TURBULENCE NEGLIGIBLE FILOTIFATING 48:0	CONFIGURATION WIND (knots) FLIGHT NUMBER WIND SHEAR PILOT EXTERNAL TURBULENCE PILOT-RATING
	CHARACTER STIC ROOTS010486± .+81	CHARACTERIST C ROO'S
LA RORAFT RESPONSE TO CONTI		
CONTROL SENSITIVITY RESPONSE:	Mat 1, 50 If \$2/\$ec^2 \rangle Art TIRUST	
2 EASE OF MAINTAINING DESIRE	D VELOCITIES	
FLIGHT CONDITION TOBBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATION COMMENTS	Longitudinal velocity (LES)	Langrusmal velocity (1.15) VMC MC (IMC VM2 IMC IMC SUI St. IN OUT OUT IV Knots Langrusmal velocity (1.15) Knots Langrusmal velocity (1.15) Verical velocity (1.15)
3 RESIDUAL I OSCILLATORY CHARA	ACTER-STICS	
	AMPLITUCE PERIOD DAMPING	AMPLITUDE PERIOD DAMPING
PITCH HEAVE	SMALL GONG	
EXCITATION CONTROL	SOURCE DEGREE (NEWHOR) (NEWHOR	SOURCE DEGREE
COMMENTS	ONLY SENSED THIS A COUPLE OF TIMES \times USUALLY NOT SECN.	
	2 SOU 200 HANGE TURK	
4. CHANGE IN THRUST REQUIRE(CHANGE REQUIRED	D FOR 20° BANKED TURNS	
EASE OF COMPENSATION	Ne) CIFFICULTY	DIFFICULTY
COMMENTS	OK - 1800b.	
5 FLIGHT PATH CONTROL		
	Intercept & initial track Intermediate track Final track Glide path Localizer Glide poth Localizer Glide soth Localizer	Intercept 8 initia Track Intermediate track Final track Gride path Cocalizer Gride path Cocalizer Gride path Cocalizer
DIFFICULTY	NONE NONE STREAM NONE STREAM NONE.	Section 1
PREC SION	COOK, GOOD STATE GOOD, ADVOADATE COOK GOOD	
MINIMUM ACCEPTABLE BREAKOU IF GREATER THAN 200 FEET	f Aut füßt	PROF. 11.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.
COMMENTS	SPRED INTERACTION WITH RATE OF CLIMB CAUSED SILLOST ANNUAUS.	l
	HERICOLIY - SAC SECTION / .	
6 BREAKOUT AND FLARE		
EASE OF APRESTING MATE OF DE		DIFFCULTY
PRECISION OF ATTAINING TOUCHDO	OWN PONT CAND	
COMM EN ES -	OK - SAFI.	
7 CONTROL TECHNIQUE		
COMMENTS IF DIFFERENT IROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER	WHEN SPEED IS JUDES THAN TO KNOTS, MAYA TO PRIVE OF THAN THIS APPRATE EXISTING DESCRIPT AND SERVEN WITH HER PER TO THE TAITER WERE SPEED IS CORRECTED TO BUSINESS.	
6 LATERA, DIRECTIONAL CHAR	ACTERISTICS	
EFFECT ON FINAL ASSESSMENT	No. No.	
9 LEAST OBJECTIONABLE FEAT	URES	
IO MOST COLECTIONABLE FEAT.	PES PAIRE SONCTIVE TO PROCEED A ME LEAD, BUT NOT NOT NOT NOT NOT NOT NOT NOT NOT NO	
MEGEN AND S		
I MISCELLIANEOUS	BARD TO THEM ATT TUDES A SUSPECT THAT A THE K CLEWALCE SUBSTITUTE OF THEM WATER TO A THEM. SERVING TO BARTHER AND STEPS (ADD. ALINE AND STEPS (ADD. ADD. ALINE AND STEPS (ADD. ALINE AND STEPS (ADD. ADD. ALINE AND STEPS (



CONFIGURATION 2L FLIGHT NUMBER 74-2 PILOT B CONFIGURATION 2).
FLIGHT NUMBER 69-1
PILOT A WINDERHOES 5
WIND SHEAR > SMALL
EXTERNAL TURBULENCE NEGLIGIBLE WIND (KNOIS) CALM WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE PILOT-RATING 4B PILOT- RATING CHARACTERIST C ROCTS -.01 -.04 -.5 -1.24 CHARACTERISTIC ROOTS -.01 -.04 -.5 I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR 11-RUST LEVER

Mag 0.3 (mg/sec2)/m Zaj: 11.9 (f//sec5)/m

English English English Sec CONTROL SENS TIVITY SATISFACTORY SATISFACTORY SLIGHTLY SMALL SATISFACTORY RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (IAS) UMC IMC IMC CUT CUT IN NONE NONE SUIGHT Vertical velocity (h)
V M C I M C
CUT OUT
SORE NONE N Vertical velocity (h)
C INC I IMC FLIGHT CONDITION TURBULENCE
DIFFICULTY
WAX MUM UNDES RED FLUCTUATIONS STIGHT STIGHT APPARENT LOW HEIGHT MATE DAMPING - NEED TO WAIT FOR ANGLE OF ATTACK AND MATE OF CLIMB TO SETTLE DOWN. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERICO AMPLITUDE FERIOD CAMPING AMPLITUDE DAMP YG DEGREE SOURCE SCURCE COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGT SEE CHANGE REQUIRED EASE OF COMPENSATION DIFF CULTY DIFFICULTY COMMENTS 5 FLIGHT PATH CONTROL Intercept 6 portal track | Intermediate track | Final track | Gide path | Local zer | Gide path | Local zer | Gide path | Local zer | Gide path | Calizer | Gide path | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer | Calizer Intercept 8 indial track Intermediate track
Glide path Localizer Glide path Localizer
Glide path Localizer SLIGHT: -SU/GIT NONE DIFFICUIT* S .108: PODERATE NONE SLIGHT - SLIGHT FAIR PACK MINIMUM ACCEPTABLE BREAKOUT ALT TUDE IF SREATER THAN 200 FCET - THEFT LIMIT RECAIRS OF POOR OVERSHOOT CAPABILITY IN SISTEMSE TO THRUST.

BY PROGRAY OUR TO: 1) TAYAR - TIDE SERSITIVITY

BY BEING RACLY IN MORNING DIFFIGURY D.E. TO THIS BEING THE FIRST EVALUATION OF THE DAY MITH THE SINCE SHEAR AND DIRECTION NOT GALLEN BURN PRODUCT WE NUMBER OF SINCE 6 BREAKOUT AND FLAR(SLISHT DIFFICULTY
FAIR EASE OF ARRESTING RATE OF DESCENT NR PRECISION OF ATTA NING TOUCHDOWN POINT (1990) SPEED DROPPED TO 45 KNOTS MERIND TRANSITION FROM THE TO THE OFFICER TO TREASITION AND FLARE NOT THE GOOD RECARS: OF RUSTINESS AND FARLY MORNING CONSTITUTION. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND NEWL SPEED WITH THRUST CEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS NOTION OF STANDARD STANDARD SOUND WELL AND CHARM FROM SEVEN SINGLA DARK STORES OF PARAMETERS AND A CARE STORES OF PARAMETERS AND SOUND SOUND SAND A SMALL PURPLANDARD STANDARD OF STANDARD STAND EFFECT ON FINAL ASSESSMENT 9 LEAS' OBJECTIONABLE FEATURES DUBSTONG MEDS! INSCHOOMED. $_{\rm COS}$ -FIGUS ASSIGNMENTS TO TURBULENCE. GOOD ATTITUDE STABLISTY AND SPREED BOLD, IC MOST COLECTIONABLE FEATURES act and the Figs attraction after the polynomial that the tensor appears τ THE HARGET MATE DANGING APPEARED TO BE LOWER THAN LOWAR, WIT THE NEED MARRY COAD OF, ID BE WEARNED MASTEY. II MISCELL ANEOUS GRATUR PARCES SERNED HOR FOR ME TODAY (FIRST FUIGHT OF $\sim 3.683\%$.



CONFIGURATION 31, FLIGHT NUMBER 118-2 PILOT A PILOT-PATING 5

WIND(knots) 5
WIND SHEAR SMALL
EXTERNAL TURBULENCE REGLIGIBLE

CHARACTERISTIC ROOTS 0 -.04 -.30 -1.45

CONFIGURATION 3L F_IGHT NUMBER 88-3 PILOT A P_OT-RATING 85

WINC (knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE LIGHT

10-15

CHARACTERISTIC ROOTS 0

-.34 -.1 -1.45

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSIT VITY

ELEV	ATOR	[THRUST	LEVER
Mag: 0.3	(rad/sec2)/ n	ZsT=11.9	(f1/sec ² i/in
In t-ol	F rol	ritial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MANTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

	Longitudinal velocity (IAS)			Vertical velocity (h)		
	VMC.	IMC	LMIC	V M C	: M C	! M C
	OUT	Qu*	IN.	QUT	110	IN
	NONE	SLIGHT	MODERATE	NONE	NONE	SLIGHT
S	F5	-10	knots	u K	-	/pm

COMMENTS

RESPONSE -

TURBULENCE RESPONSE IN PITCH ATTITUDE WAS MAIN PROBLEM, TOO MUCH CONCENTRATION REQUIRED TO HOLD AIRSPEED ON APPROACH.

	ELE	VATOR	THRUS	T LEVER
$M_{\delta E}$	= 0.34	(rod/sec2)/in	ZBT = 11,9	(*1/sec2)/in
	initial	F ₁ nal	In ha!	Final
SAT	IS FACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

V M C OL T SLTCRT CUT OUT IN MODERATE GREAT GREAT SLIGHT SLIGHT

ENURMOUS CHANGES IN FITCH ATTITUDE WITH SMALL ELEVATOR

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE EXCITATION

CONTRO: COMMENTS.

AMP_11U0E 2ER0 2ER0	PERIOD	DAMPING	
SOURCE		DEGREE	i

AMPLITUDE . SOURCE DEGREE

FELT LIKE A STRAIGHT DIVERGENCE WHICH COULD BE DISASTROUS AFTER A MUMENT OF DIVERSION FROM THE TASK.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

NEGLIGIBLE	
NO ON	DIFF'CLLTY

DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

COMMENTS

ntercept &	in tial Trock	Intermedi	ore track	Final	trock
G de poth	Localizer	Glide path	Lacolizer	Glide path	Localizer
SLIGHT	SLIGHT	SLIGHT	SLIGHT	MODERATE	MODERATE
FAIR	ZATR	FAIR	ZALR		POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

THE EXPECTED WIND SHEAR DID NOT MATERIALIZE AND WE ENDED BY TO ONE SIDE OF THE LOCALIZER.

		Intermediate track		Final track	
Glide path	Localizer	Giide path	Localizer	Glide poth	Localizer
SLIGHT	MODERATE	SLIGHT	MODERATE	SLIGHT	MODERATE
FAIR	FA LR/GOOD	FAIR	POOR	FAIR	POOR

800

HAD TO BREAK FIRST APPROACH OFF AT 500 FT. DUE TO CONFLICTING TRAPPIC. SECOND STARTED FROM 800' AND WAS QUITE RUSHED.

XO DIFFICULTY

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO CIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT WOLLD

COMMENTS

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFEC" ON FINAL ASSESSMENT

NONE

SMALL

9 LEAST OBJECTIONABLE FEATURES

RETURN CONTROL GOOD.

SEE SECTIONS#?, 3.

O MOST DBUECTIONABLE FEATURES

TURBULENCE RESPONSE IN PITC+.

MISCELLANEOUS



	CONFIGURATION 3L WIND(kno's:) FLIGHT NUMBER 56-1 WIND SHEAR SHALL PILO" B EXTERNAL "URBULENCE	CONFIGURATION WIND (knots) FLIGHT NUMBER WIND SHEAR PILOT EXTERNAL TURBULENCE PILOT-RATING
	PILOT-RATING 73D CHARACTERISTIC ROOTS 0 -044 - 3 -145	CHARACTERISTIC ROOTS
I AIRCRAFT RESPONSE TO CONT	RCL INPUTS	
CONTROL SENSITIVITY RESPONSE:	Mag= 0.34 trad/sec*//m Zat= 11.9 (tr/sec*//m initial Final Initial Final SLIGHTLY GREAT TOO GREAT SLIGHTLY SMALE SMALE SMALE SMALE SMALE SMALE SMALE SMALE SMALE SMALE SMAL	ELEVATOR
2 EASE OF MAINTAINING DESIRE		
FLIGHT CONDITION. TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATION COMMENTS	DIFFICULTY IN ALESPEED CONTROL DUE TO PITCH INSTABILITY.	Longitud-nal velocity ([AS] Vertical velocity (h]
	AND IN VERTICAL VELOCITY CONTROL TO WIND SHEAR.	
3 RESIGUAL OSCILLATORY CHARA	octrais t ics	
	AMPL TUDE PERIOD DAMPING	AMPLITUDE PERIOD DAMPING
PITCH HEAVE	ZERO ZERO	
EXCITATION - CONTROL -	SOURCE DEGREE	SOURCE DEGREE
COMMENTS		
4 CHANGE IN THRUST REQUIRE	C FOR 20° BANKED TURNS	
CHANGE REQUIRED:	NEGLIGIBLE	
EASE OF COMPENSATION COMMENTS	NO DIFF:CJ_TY	DIFF CULTY)
5. FLIGHT PATH CONTROL		
	Intercept & initial track Intermediate track Final track	Intercept 8 initial track Intermediate track Final track
D FFICULTY	Slide poth Local zer Glide path Localizer G-ide path Localizer MONE MONE NONE NONE SLIGHT SLIGHT	Glide path Localizer Glide path Localizer Glide path Localizer
PRECISION	0000 0000 0000 0000 0000	
MINIMUM ACCEPTABLE BREAKOUT	· · · · · · · · · · · · · · · · · · ·	
F GREATER THAN 200 FEET COMMENTS	TRACKED INC TO 100'.	·
COMMENTS	LOCKED TO 100 C	
6 BREAKOUT AND FLARE		
EASE OF ARRESTING RATE OF DEP PRECISION OF ATTAINING TOUCHDO	SCENT NO DIFF CULTY	
PRECISION OF ATTRINING TOUCHDO	Wh POINT GOOD	OFFICULTY.
COMMENTS	WA POINT GOOD *MIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUGHDOWN EXCEPT THAT SPEED WAS LOST IN PLANE BYGAUSE OF THE GREATER STRETCH REQUIRED FROM LOG FT.	OFFICULTY.
	"RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUCHDOWN ENCEPT THAT SPEED WAS LOST IN FLARE BYCACSE OF THE GREATER)FFICULTY.
CONTROL TECHNIQUE	"RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUCHDOWN ENCEPT THAT SPEED WAS LOST IN FLARE BYCACSE OF THE GREATER) FF(CULTY
COMMENTS	"RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUCHDOWN ENCEPT THAT SPEED WAS LOST IN FLARE BYCACSE OF THE GREATER) FF(CULTY
COMMENTS 7 CONTROL "ECHNIQUE COMMENTS IF DIFFEREN" FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST	*RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUGHDOWN RECEPT THAT SPEED WAS LOST IN FLARE BUGAINE OF THE GREATER STRETCH REQUIRED FROM 100 PT.) FF(CULTY
COMMENTS 7 CONTROL "ECHNIQUE COMMENTS IF DIFFEREN" FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER	*RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUGHDOWN RECEPT THAT SPEED WAS LOST IN FLARE BUGAINE OF THE GREATER STRETCH REQUIRED FROM 100 PT.)FF(CULTY
COMMENTS 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARA FFFECT ON FINAL ASSESSMENT	*RIGHT IN THE SLOT" - GOOD POSITIONING BUR TOUGHOOMN RECEPT THAT SPERD WAS LOST IN FLARE BUGAINE OF THE GREATER STRETCH REQUIRED FROM 100 FT. ACTERISTICS NUME) FF(CULTY
COMMENTS 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERIAL DIRECTIONAL CHARZ	*RIGHT IN THE SLOT" - GOOD POSITIONING BUR TOUGHOOMN RECEPT THAT SPERD WAS LOST IN FLARE BUGAINE OF THE GREATER STRETCH REQUIRED FROM 100 FT. ACTERISTICS NUME) FF(CULTY
COMMENTS 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARA FFFECT ON FINAL ASSESSMENT	*RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUGHDOWN RECEPT THAT SPEED WAS LOST IN FLARE BECAUSE OF THE GREATER STRETCH REQUIRED FROM 100 PT. ACTERISTICS NOME LRES SELICHT CONTROL NOT TWO BAD IN PRESENCE OF)FFICULTY.
COMMENTS 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARA FFFECT ON FINAL ASSESSMENT	*RIGHT IN THE SLOT" - GOOD POSITIONING FOR TOUGHDOWN RECEPT THAT SPEND WAS LOST IN FLARE BUCAUSE OF THE GREATER STRETCH REQUIRED FROM 106 FT. ACCERISTICS NONE REGION CONCROL NOT THO BAD IN PRESENCE OF T. ABCLENCE AND REAL NING SACAR.)FFCUITY



CONFIGURATION 4 FLIGHT NUMBER 18-3 PILOT A PILOT-RATING 5

WIND(kopts) WIND SHEAR MODERATE
EXTERNAL TURBULENCE LIGHT

CONFIGURATION 4
FEIGHT NUMBER 16-2
PILOT B
PILOT-RATING 74

WIND (Hnots) 8
WIND SHEAR >SMALL
EXTERNAL TURBULENCE >LIGHT

CHARACTERISTIC ROOTS +.02 -.04 -.19 -1.58

DAMPING

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

	VATOR		T LEVER
M8E = 0.39	(rod/sec ² 1/in	Z8T=11,9	(ft/sec ² l/ii
Initio	Fina'	Initial	Final
SATIS FACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

CHARACTERISTIC ROOTS +.02 -.04 -.19 -1.58

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

Longit	udinal veloc	ty (IAS)	Verti	cal velocity	(h)
VM.C	TM.C	T M C	VMC	1 M C	IMC
OUT	700	IN	QUT	TLO	IN
SLIGHT	MODERATE	MODERATE	SLIGHT	SLIGHT	SLIGHT
	± 3	knots	0 K		f p.m.

A GENERAL PROBLEM OF NOT BEING ABLE TO SELECT AND HOLD THE PITCH ATTITUDE TO MAINTAIN A DESIRED AIRSPEED.

ELEVATOR		THRUST LEVER		
MBE = 0.39	(rad/sec2 1/in	Z8T: 11.9	(ft/sec²)/in	
Initial	F-nal	Initial	Final	
TOO GREAT	NOT ASSESSABLE	SATISFACTORY	SATISPACTORY	
_ 100 011				

Vertical velocity

DISFIGURTY IN SPEED CONTROL DUE TO TURBULENCE AND LEARNING

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH

EXC TATION CONTROL COMMENTS

COMMENTS

AMPLITUDE	PE RIOD	DAMPING
ZERO		
ZERO		
		DEGREE
SOURCE		

AMPLITUDE SMALL PERIOD MEDIUM CEGREE

OSCILLATION APPARENT ON INITIAL TAKE-OVER BUT WAS NOT NOTICED AFTER FIRST 5 MINUTES.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

MODERATE	
ST.LGHT	DIFFICULTY

COMMENTS

DURING THE TURN TO THE LOCALIZER ABOUT THE SIGHT AMOUNT OF THRUST MAS APPLIED IN ANTICIPATION OF MISS OF ACTITION, ON HOLLING OUT, HOWEVER, THE OFFREETION MAS REMOVED TOO HATE, AFTER THE ALERGAT HAD CLIMBED HOD IT.

SMALL	1
80	 D FFICULTY

5. FLIGHT PATH CONTROL

D-FFICULTY PRECISION

Intercept &					track
G de palh	Localizer	Gilde porh	_ocalizer	Glide path	Localizer
NONE	SLIGHT	SLIGHT	SLIGHT	SLIGIT	S1. (GH)
0000	FAIR	G005	AIR	3000	PALS

MINIMUM ACCEPTABLE BREAKOUT ALTTUDE

COMMENTS

THE WIND SHEAR REQUIRED MIGH ATTENTION TO IDCALIZER TRACKING. PEADING WAS AFFECTED MUCH MORE THAN NORMAL BY TIRBULENCE.

	inital track			Final Irock	
Glige path	Localizer	Glide path	Local-zer	Glide path	Local ter
NONE	NONE	SLIGHT	SLIGHT	SLIGHT	SLIGHT
COOD	COOD	GOOD	GOOD	G00 D	ເດດກ

CARSS-GRECK MEAK ON PITCH ATTITUDE: TURBULENCE AND/OR CONTROL OFF-CENTRES RESULTED IN DIFFICULTY IN MAINTAINING DENIRG ATTITUDE, STEED CONTROL CENERALLY POOR ON THIS APPROACH (SPEED LOW 45-55 KTS) PRIMARY TASK WAS GLIDE SLOPE TRACKING.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NO NO	DIFFICU_*Y
(-QOD	

COMMENTS

DIFFICULTY

7 CONTROL *ECHNIQUE

COMMENTS :F DIFFERENT FROM I.A.S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTER STICS

FFFECT ON FINAL ASSESSMENT

90 MRAPS/SMATE, SEE SECTION 1.

9 LEAST OBJECTIONABLE FRATURES

ID MOST OBJECTIONABLE FEATURES

NOTIAL PICC: FIG. GEOLIFIED LOW GAIN ON PITCH ATTITUDE CONTROL - INCE DIOR SPEED CONTROL.

IL MISCELLANEOUS

ONE WEEDS TO WEILER EPROPS WILLS THEY ARE SMALL AND TO MAKE SMALL CORRECTIONS. THIS RESULTS IN GOOD TRACKING.



CONFIGURATION 1
FLIGHT NUMBER 10-3
PLOT F
PRECT-RATING 7 WINDIKROIS) 1.0 WIND SHEAR SMALL EXTERNAL TURBULEACE SHOTT CONFIGURATION 4
FLIGHT NUMBER 23-?
PROT 3
PROT-RATING 7' WIND (knots) CAT.M
WIND SHEAR > SMALT.
EXTERNAL TURBLEENCE LIGHT CHARACTERISTIC ROOTS F.OZ -.04 -.19 -1.58 LARCRAFT RESPONSE TO CONTROL NPUTS CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION
TURBULENCE
DIFFICULTY
WAX MUM UNDES RED FLUCTUATIONS POTCH ATELLIES APPEARS TO DIVERSE WITH ELEVATOR INPUT, BUT NOT AS HADLY AS CHIEFCURATION 4. DISPLAY MUST BE MONITORED CLASSES, AND BLEVATOR KEPT CENTRED, 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD AMPLITUDE PERIOD DAMPING (6.9) SOURCE DEGREE SOURCE DEGREE EXC TATION CONTROL COMMENIS OF INTO A THE AT 500 FT. THERE IS ROTENTIAL FOR LOSS OF CHURCH, BUTCH INDOMESTELY THAT TRACKING. SUBSEM ELEVATO DEPUTS I V. PARE MISCONSE AS CIPACIT DURANTO OFF. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS SOURCE SHALL DIFF CULTY CHANGE REQUIRED EASE OF COMPENSATION MODERATE SMALL
SLIS IT DIFF COLTY COMME VTS CRUBATUS HASY TO LEARN - NOT A FACTOR FOR PLANE AND 5. F. IGHT PATH CONTROL olercept 9 out at track Intermediate frack find track Glide path Localizer Glide path Localizer Glide path Local intercept 6 in tial trock | Intermediate track | Final track | Slide path | Lacalizer | G de path | Lacalizer | G ioe path | Localizer | DIEFICL. TY 81.16.17 NJOP. 8-1697 808 S1.0 C 31.1% 1 SLEG T NONE SLIGHT SLIGHT PRECISION COOR A FR (COOR N NINUM ACCEPTABLE BREAKOUT ALTITUDE

IF GREATER THAN 200 FEET THE 501 CINO STACE 400-600 FFY DESCENT BEHTS LAWORD DESCRIPTION OF THE STATE BEHTS SERVED TO STATE AND ADDRESS OF THE STATE OF THE STATE STATES. COMMENTS FOR PT CONTROL REGISTED AND USED BELOW 500 FT (NOMICED MODEL INSTABILITY PROBLEMS, 6 BREAKOUT AND FLARE PRECISION OF ATTAINING TOUCHDOWN POINT | STITUTE | FALCOHOLD DIFF CJLTY COMMENTS DESCRIPTION OF THE BOUNT FROM NO STANSFORT, WAS ADDRESS OF THE SEASON OF I.A. AT BRIASE, T. - MOTTO A SLIGHTLY LIMBER THAN DESIRABLE WHITEAU, SHEED RESPONSE TO THRUST EXPERTS, SERBED POSSIBILITY OF CHILD THRUST FLUVATOR PIO WHILE ADJUSTING PATE OF DESCRIPTIONS TO THE DESCRIPTIONS. 7 CONTROL IFOHNIQUE COMMENTS IF DIFFEREN' FROM LAS WITH ELEVATOR AND SERTICAL SPEED WITH THPUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS. EFFECT ON FINAL ASSESSMENT NAME. 9 LEAST OBJECTIONABLE FEATURES ID MOST OBJECTIONABLE FEATURES $\begin{array}{lll} P(T) & ATT(TP) e^{-i t} (V_{t}, \epsilon, is, s^{\prime}Te^{-i t} I_{t}, \delta ATe^{-i} TSe^{\prime}TS) \\ T(T) & A(t) P(S) & ONS(SN) & ATT(TP) & ATT(TP) e. \end{array}$

MISCELLANEOUS SONT OF DATE: THE WAY MOVED DATE OF MISSELPHY.

GMTING BECKER OF PICE POTENTIAL, CTERMINE WOULD BE FIBERA SELS PITES HESPONSE TO SIEVADOR.

O INCLEMENT PICCOLINSTABLITY AT 500 FT, O PICCO SESSONS: TO CLEVATOR.



CONFIGURATION 4
FLIGHT NUMBER 23-L
PILOT 0 CONFIGURATION 4
FLIGHT NUMBER 23-3
PALOT D
PILOT-RATING 3 WIND!knate! CALM WIND (knots: CALM WIND SHEAR MODERATE EXTERNAL TURBULENCE LIGHT WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE PILOT-RATING 7+ CH4RACTERISTIC ROOTS +.02 -.04 -.19 ,-1.58 CHARACTERISTIC ROOTS | 1.02 | -.04 | -.19 | -1.58 I AIRCRAFT RESPONSE TO CONTROL INPUTS Hat O. 19 (100/sec²)/m 28T = 11.9 (11/sec²)/m 11.00 Fro I Intol Fro I Intol Find SLIGHTLY SMALL SATISFACTORY SATISFACTORY CONTROL SENSITIVITY Initial Fina Initia Final
TOO SMAIL TOO GREAT SATISFACTURY SATISFACTORY RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES COMMENTS VERY SUBGUISH PUTCH RESPONSE. NOT POSSIBLE TO ASSESS PINAL ATTITUDE TO A GUARN INPUT. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD DAMPING
(A60)
(280) AMPLITUDE DAMP: NG SOURCE SOURCE EXCITATION CONTROL COMMENTS NODERATE FITCH RESPONSE - NO PARTICULAR P.1.0. TENDENCY, SEEMS STIGHTLY SLUDGISH. THIS CONFIGURATION APPEARS TO HAVE LOW FREQUENCY SHORT-PRICED GRAMACTERISTICS; HENCE PLOT TEXOS TO CVENDRIVE IT TO SET INTHAL RESPONSE AND, AS A CONSCIUPRICE DYPERSHORTS, (e) LIM PREQUENCY PIO. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS VERY SMAL . EIFFICULTY VERY SMALL DIFFICULTY CHANGE REQUIRED EASE OF COMPENSATION COMMENTS 5. FLIGHT PATH CONTROL Intercept & initial track | Interrediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide p Intercept B in tial track Intermediate track Find track
Glide poin Lagai zer Glide poth Localizer Glide poth Lacalizer DIFFICULTY: NONE SLIGHT SLIGHT SHIGHT MODERATE NONE >SLIC-T NONE NONE SLICHT > SLIGHT PRECISION GOOD GOOD GOOD GOOD FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
F GREATER THAN 200 FEET COMMENTS SPENT TOO MODE THE CONTRIBUTED FIRST TO MAINTAIN AIRSPEED AND CONSEQUENTLY GOT STUTED THE CHEARLYEE TRACKING TASK, LARGE BIDESTED NAMED AND ELVE UP WITH SURVAY. 6 BREAKOUT AND FLARE FAIR GOOD EASE OF ARRESTING RATE OF DESCENT BS: DIFFICULTY:
PRECISION OF ATTAINING TOUCHDOWN POINT PORT COMMENTS: 7. CONTROL TECHNIQUE COMMENTS OF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NUME 9 LEAST OBJECTIONABLE FEATURES DEBUT CONTROL. 1000 SEIGHT CONTROL - NITTLE POWER ACTIVITY, IO MOST OBJECTIONABLE FEATURES TTGTUDE OUR BOLL - SERVIES - 18 TIAC F-SPONSE AND OVERCORT OF TENDERCY. TABLE PIT F ATTITUDE PLECTEALIONS BOLL ACCORDANCE. STIGSTELY STARREDS: PITCE RESPONSE - FALKLY LARGE PITCE ATTITUDE EXCURSIONS IN TURBULENCE.

JENDHABLY GOOD PERFORMANCE IN ALL FLASES OF TASK ENCEPT ROME ERBORS IN LUGALIZER DIJACKIDE RIGHT NEAR

STREET, ME.

BE FIGURE FOR , with DAMPLES OF THE TELL TO ATTAIN CLASSINABLE RESIDIANCE.

H MISCELLANEOUS



CONFIGURATION 41. FUIGHT NUMBER 119-1: PILOT A WIND SHEAR SMAIL EXTERNAL TURBULENCE FIRST CONFISURATION ALL FLIGHT NUMBER 131-1 PILOT C PILOT RATING 6 WIND (knots) 1.0 WIND SHEAR SMAIL EXTERNAL TURBULENCE (199T PLOT-RATING 7 CHARACTERIS* C ROO*S -.02 -.04 -.19 -1.58 CHARACTERISTIC ROOTS -.01 -.04 -.19 -1.58 LAIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY: RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES TURBULENCE DIFFICULTY MAX.MUM UNDES RED FLUCTUATIONS COMMENTS LIST 400 FT HEIGHT TURNING ONTO BASE GEG DUE TO LONGITUDINAL VELOCITY CHANGES. DIFFICULTY DUE TO OSCILLATORY CHARACTERESTICS WHEN LIMIC. 3 RESIDUAL OSCILLATORY CHARACTERISTICS DAM PING AMPLITUDE AMPLITUDE PERIOD DAMPING M. Ditter (6.83) 7E90 MODERATE SOURCE SOURCE DEGREE DEGREE EXCITATION: CONTROL COMMENTS NO INDUCTION SHORT PERIOD PUTCH OR RELATE MOTION DETICABLE. INDECTING CONDUCTIONS THERE SCHEED TO BE A PROBLEMATE SERVICING LIGHTLY DAMPED MOTION THAT SEMITITHE NOSE BUSYNTHE TURB. LENGT CONTRIBUTED TO THIS ACTIVITY, NOT RESENT 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION MEGLIGIBLE
MO DIFFICULTY OFFICULTY] MEDICO BEE CHANGE REQUIRED IF VELOCITY TELD CONSTANT. OF PERMITS FOR CHANGES REQUIRED TO COMPENSATE FOR THIS MORTION OF THE PARK MICHINER CHICKEN DAMELL DOWNSED. WITH CHIC PART THAT COLLEGED, COMMENTS AT (SPEED CHANGES) 5 FLIGHT PATH CONTROL Intercept & nitial track | Termediate track | Fino trock | Glide path | Spoalizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path ntercept B. init all track. Intermed are track Glide path Localizer Glide poth Localizer Glide path Localizer DIFFICULTY -MIDDRATE SELECT MODERATE MODIFICATE MODERATE MOSERATE SLIGHT 51.10017 MODERATE SLIGHT NONE -A1: POG. 2008 2016 2007 701R FA18 **WATE** FATR COOD NOR INITIAL PERFORMANCE DUS TO RETGET LOSS ON BASE LEG.
MAGESSARY TO MAKE LARGE ATTITUDE CORRECTIONS TO OFFSET
SPEED VARIATIONS PLAS LARGE THROTTLE MOVEMENTS. SPEED FELL
TO 50 KNOTS ON FINAL. DISTIBUTED A VIND STEAD OF THE NOTIFICIAL SECTION OF THE ANTICIPATING A VIND STEAD OF THE NOTIFICAL SECTION OF MATERIAL SECTION. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DISCENT NO. OFFICULTY
PRECISION OF ATTAINING TOLICHOOMY FOINT (200) MODERATE DIFFICULTY
FAIR COMMENTS REPRESENTABLE TO RECESSITY FOR MAKING EVEN LARGER CONSECUTIONS WHEN VMC TO SECOVER SPEED. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST AIRSPEED CONTROLLED WIT: ELEVATOR, BUT TOROTTLE USED TO COMPENSATE FOR SPEED CHARGES AS WELL AS TO CONTROL VERTICAL SPEED. LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES NO DISPURASANT DISCULLATORY CHARACTERISTICS DETECTABLE IO MOST OBJECTIONABLE FEATURES. MARGE THE ST CORRECTIONS WITH SPEED VARIATION. DIFFICULTY IN ATTAINING PRECISE SPEED CONTROL. SUCH ATOMS CHARAGES HETTICS. SCHOOL EXTERMAL TURBULENCE BELOW 1000 PT. CHANGE OF SPEED, i.e. bit of 70 km/ds, difficult to accomplish with drecision and takes too loss. A MISCELLANFOUS



	CONFIGURATION 5L WIND(N-ois) IN FLIGHT NUMBER 90-1 WIND SHEAR SMAIL PILOT A EXTERNAL TURBULENCE MEDITOIDUR PILOT-RATING 9	CONFIGURATION FIGHT NUMBER PILOT PLOT-RATING	WIND (knots) WIND SHEAR EXTERNAL TURBULENCE
LAIRCRAFT RESPONSE TO CONTR	CHARACTERISTIC ROOTS 1.090410 -1.74	CHARACTERISTIC ROOTS	
CONTROL SENSIT VITY		MSE: (add	THRUST LEVER
2 EASE OF MAINTAINING DESIRE FLIGHT CONDITION TURBULENCE DIFFICULTY MAX MUM UNDESIRED FLUCTUATION		Longitudinal velocity of VMC I M C OUT OUT	
COMMENTS	THE MUSIC VAS IN CONSTANT MOTION DUE TO AN ENGRHOUS STEADY STATE DESPONSE TO COMPAND. INFURS AND TO THE TURBURNOE. THE VERTICAL RESPONSE TO SLEVATOR SPUTS ACCENTRATED THE MOTION. A MOMENT'S DIVERSION COULD BE CATASTROPHIC.		
3 RESIDUAL OSCILLATORY CHARA	CTER STICS		
P TCH HEAVE	AMPERILOE PERICO DAMPING SERO SOURCE T DEGREE	AMPLITUCE SOURCE	PER OD CAMPING DEGREE
EXCITATION CONTROL			
COMMENTS	STRATEGT DIVERSENCE,		
4 CHANGE IN THRUST REQUIRES CHANGE REQUIRED EASE OF COMPENSATION: COMMENTS:	NSGLIGIBLE OFFICULTY	Ois	FIGULTY
5 FL GHT PATH CONTROL DIFFICULTY PRECISION	Intercept B mit of track Intermediate track Final track	Intercept 6 introl track Gide path Localizer Gi	ofermediate track Final track de path Lacditer Gide path cool zer
MINIMUM ACCEPTABLE GREAKOUT	COOD COOD PAIR FAIR FAIR POOR ALTITUDE		
IF GREATER THAN 200 FEET COMMENTS	SHE SECTION W2. I WAS WORKING SO HARD ON AIRSPEED CONTROL THAT HEADING VENT FOR A CHOP, WAS COT OFF TO THE WIGHT AND REQUERED COTTE A STRENGUS 'S' TORN.	<u> </u>	
6 BREAKOUT AND FLARE			
EASE OF ARRESTING RATE OF DES PRECISION OF ATTAINING TOUCHDO	SCENT GREAT DIFFICULTY WN POINT 2008		DIFFICULTY
COMMENTS	A PITCH PIO OCCUPRAD AS THE ALBCRAFT WAS LEGELLED.		
7 CONTROL TECHNIQUE			
COMMENTS IF DIFFERENT FROW LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER			
8 LATERAL DIRECTIONAL CHARA	CTERISTICS		
EFFECT ON FINAL ASSESSMENT			·
9 LEAST OBJECTIONABLE FEAT	JRES		
O MOST DBJECTIONABLE FEATUR	RES		
H MISCELLANFOUS			



CONFIGURATION 6
FLIGHT NUMBER 14-3
PILOT A
PILOT-RATING 45 WWND(knets) 10
WWND SHEAR SMALL
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION 6
F, IGHT NUMBER 45-1
PILOT 8
PILOT-RATING 5C W ND (knots) 5-10
WING SHEAR VERY SMALL
EXTERNAL TURBULENCE >CIGHT CH4RACTERISTIC ROOTS -.03 -.34 -.86± .481 CHARACTERISTIC ROO"S -.03 -.04 -.86 ± 0.481 I AIRCRAFT RESPONSE TO CONTROL INPUTS V E : 0.3 (rad/sec²)/m Z51 : 11.9 (r//sec²)/m Intal Final Intal Final Intal Final SATISFACTORY SATISFACTORY SATISFACTORY CONTROL SENSITIVITY RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES inal velocity (:AS) Vertical velocity (h) Longitudinal velocity ([AS)
VMC | IMC | IMC
OUT OUT IN
SUIGHT SUIGHT FLIGHT CONDITION:
TURBULENCE
DIFFICULTY
MAX MUM UNDESIRED F_UCTUATIONS STIGHT STEER V.STIGHT V.SLIGHT V.SLIGHT COMMENTS: DIFFICULTY DUE TO PITCH TRIM CHANGES WITH THRUST CHANGES. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE PE 9100 AMPLITUDE DAMPING PiTCH YEAVE SMAL. MODERATE ZERO ZERO DEGREE SOURCE SOURCE DEGREE EXCITATION SLEVATO CONTROL EFFECTIVE COMMENTS A SWORT PERIOD MOSTLE RESULTS FROM ELEVATOR INPUTS WRICH GOES THROUGH ABOUT 2-3 CYCLES BEFORE STOPPING 4 CHANGE IN THRUST REQUIRED FOR 20" BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY SLIGHT DIFFICULTY COMMENTS. 5 FLIGHT PATH CONTROL Infercept & milial track Intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer Intercept 8 initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Gli DIFFICULTY: SLIGHT NONE SLIGHT NONE NONE NONE MONE NONE NONE FALR COOD FALS 300 D 3000 :418 G00 D 6000 600 B FAIR/GOOD FAIR/GOOD N NIMUM ACCEPTABLE BREAKOUT 4LTITUDE IF GREATER THAN 200 FEET 200 0 K STAYED SLIGHTLY BELOW GLIDE PATH ON THIS APPROACH AND HAD NO DIFFICULTY IN REPING THE GLIDE PATH MEEDLE ON SCALE AND RECOVERING THE GLIDE PATH JUST BEFORE REACHING 200 FT A.G.C. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT STIGHT DIFFCULTY
PRECISION OF ATTA. NING TOUCHDOWN POINT FATR NO 0000 DIFF CULTY THE ALMSPEED FILL OFF SOMEWHAT PASTER THAN 1 HAD PLANNED - PROBABLY DUE TO A LITTLE CVERCUNTROS, AND DUE TO THE OVERSHOOT CHARACTERISTICS. NICE STEADY STATE DESCENT RATE SET UP FOR TOUCH-DOWN, BUT NOT REALLY CESTAIN THAT I HAD PRECISE CONTROL OVER RATE OF DESCENT AT TOUCHDOWN. ? CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES GOOD (SATISFACTORY) PITCH ATTITUDE STABILITY. IO. VOST OBJECTIONABLE FEATURES RESEA TO SECTION #3 INTERACTION BETWEEN THRUST AND PITCH - EVERY SIGNIFICANT POWER CHANGE REQUIRES NEW PITCH ATTITUDE TRIM - NOTICEABLE EVEN FOR RELATIVELY RAPLO POWER CHANGES ON AFFROACH. I MISCELLANEOUS Mag CHANGED FROM 0.59 to 0.39 OCCASIONAL LARGE PLTCH UPSETS - TURBULENCE?

151



CONFIGURATION 6
FLIGHT NUMBER 40-3
PILOT D
PILOT-RATING 3

WIND(knots) L5-20 WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE

CONFIGURATION
FLIGHT NUMBER
PILOT
PILOT-RATING

W:ND (knots) WIND SHEAR EXTERNAL TURBULENCE

CHARACTERISTIC ROOTS -.03 -.04 -.86 ± .481

CONTROL SENSITIVITY

	POTAV		T LEVER
M8E - 0.30	(rad/sec21/ r	Z8T = 7.4	(fl/sec ²)/in
Initial	Final	ritial	Final
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

CHARACTERISTIC ROOTS

(rad/sec2 1/in 281 = THRUST LEVER ELEVATOR Mag = In-tiol

2 EASE OF MAINTAINING DESIRED VELOCITIES

LAIRCRAFT RESPONSE TO CONTROL INPUTS

FLIGHT CONDITION TURBULENCE:
DIFFECULTY
MAXIMUM UNDESIRED FLUCTUATIONS

LD	Longitudinal velocity ([AS)			Vertical ve acity (file		
V.M	ig IMC	: M C	VMC	INC	TMC	
30		IN	QLT	100	'N	
NON	E SLICE	HT S1.IGHT	NONE	SLIGHT	SUIGHT	
	±5	<nots< th=""><th># 2</th><th>00</th><th>!pm</th></nots<>	# 2	00	!pm	

Longitu	dinat velocit	ly (IAS)	Ver'	cc: velocity	(*)
VMC	1 M C	EMC	VMC	IMC "	IMC
OUT	OL T	MI	OUT	OUT	LN
		Kno's			lp m

COMMENTS

RESPONSE :

TROUBLE DNLY NEAR GROUND - PROBABLY DUE TO WIND SHEAR.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS

COMMENTS

AMPLITUDE	PERIOD	DAMPING
SMALL	MEDITUM	MCDERATE
ZE30		,
SOURCE		DESREE
30350		DESREE

AMPLITUDE	PE RIOD	DAMFING
		<u> </u>
SOURCE		DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

PIC DERATE DIFF,CULTY

PILOT IS BEHIND THE AIRPLANE - AIRSPEED AND VERTICAL SPEED BUILDS UP SEPORE ACTION IS TAKEN - THEN OVERCONTROLS.

DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept &	instro *rack	Intermedi		Final track	
Glide path	Lacolizer	Glde path	Locolieer	Glide parh	_ocal-zer
NONE	NONE	SLIGHT	STIGHT	MODERATE	MODERATE
GODII	COOD	FAIR	FAIR	POOR	POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET

DIFFICULTY PROBABLY DUE TO WIND SHEAR

ntercept 8 initial track Intermediate track
Glide path Localizer Glide path Localizer Final track Glide path Localizer

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO. DIFFCULTY COOD

DIFFICULTY

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES GOOD DAMPING IN SITCH & DAY STABLE.

ID MOST OBJECTIONABLE FEATURES - QUITE A BIT OF THROTTLE MAXIPPLATION DO MAINTAIN CLIDE PATH.

I MISCELLANEOUS



CONFIGURATION 71_ FLIGHT NUMBER 74-1 PILOT A PILOT A
PILOT-RATING 5

CHARACTERISTIC ROOTS

WIND[knots] WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

-.013 -.04 -.25 **-1**.49

CONFIGERATION 7L FLIGHT NUMBER 87-1 PILOT A PILOT 5

WIND (knots) 10
WIND SHEAR REGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELE	VATOR	THRJ\$	
Mag = 0.3	(rob/sec ²)/in	Z87: 8.9	(11/sec ²)/in
Initial	F ina1	ritial	r na!
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISTACTORY

Mag = 0.3 (rad/sec)/m Za = 8.9 (tr/sec)/m satisfactory too great Satisfactory Satisfactory

CHARACTERISTIC ROOTS -.013 -.04 -.25 -1.49

2 EASE OF MAINTAINING DESIRED VELOCITIES

FL:GHT CONDITION TURBULENCE DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATION

	Long-tudinal velocity (IAS)		Vertical velocity (h)			
	y.M.C.	1MC	IMC	VMC	1.M C	IMC
- 1	OLT	OUT	IN	OUT	DUT	IN_
	SLIGHT	MODERATE	MODERATE	SLIGHT	SLICHT	SLIGHT
NS		10	knc*s	±3	300	f pm.

DURING VMC FLIGHT THE SPEED CONTROL MAS RELATIVELY EASY, BUT ON GOING UNDER THE HODD THE MOSE SEEMED TO MANDER. THIS BEGAME MORE OF A PROBLEM WITH TURBULENCE - HENGE THE ATREFEED CONTROL BECAME DIFFICULT.

THE NOSE WOULD NOT STAY WHERE IT WAS PUT AND VERY SMALL ELEVATOR DISPLACEMENTS CAUSED CONSTANT CREEP.

3 RES'DUAL OSCILLATORY CHARACTERISTICS

EXC-TATION CONTROL COMMENTS

COMMENTS

AMPLITUDE	PER	OC	DAMP NG
ZERO	, 		
ZEMO			
SOURCE			DEGREE

PERIOD DAMPING

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MODERATE DIFFICULTY

COMMENTS:

A PAIR AMOUNT OF POWER WAS REQUIRED DURING THE TURNS BUT THIS WOULD PROBABLE RECOME EASY TO ANTICIPATE WITH EXPERIENCE.

SMALL NO DIFFICULTY

5 FLIGHT PATH CONTROL

CIFFICULTY

Intercept &	in tial track	*1ermed:	ate track	track Final track	
G de palh	Localizer	Gude path	Lacalizer	Glide path	Localger
SI.[GHT	SLIGHT	MODERATE	SLIGHT	SLIGHT	MODERATE
PAIR	FAIR	FAIR	FAIR	PAIR	POOR

MINIMUM ACCEPTABLE BREAKOUT ALT TUDE
F GREATER THAN 200 FEET 500

COMMENTS

HE WENT RICH ON THE CLIDE PATH AT ABOUT 1000' ACL. - PROBABLY BECAUSE OF THE GREAT CONCENTRATION REQUIRED FOR ALREFEED CONTROL. THE MAJORITY OF THE APPROACH PRESENTED A VIGH REPRESENTED A VIGH REPRESENTED A VIGH REPRESENTED A VIGH REPRESENTED OF THE APPROACH PRESENTED A VIGH REPRESENTED A VIGHT REPRESENTED A VIGH REPRESENTED A VIGH REPRESENTED A VIGH RE

6 BREAKOUT AND FLARE

EASE OF ARRESTING MATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NO	 D FFICULTY
G0C3	

COMMENTS

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I 4'S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL 'DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

ID. MOST OBJECTIONABLE FEATURES

1 MISCELLANEOUS

Intercept B miliol track Intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer MODERATE MODERATE SLIGHT MODERATE

500

DIFFICULTY DUE TO ANTIGIPATING A REQUIREMENT TO CHANGE HEADING TO COUNTERACT A WIND SHEAR WHICH DID NOT MATERIALIZE LITTLE THE LAST 400-500 PT. AIRSPEED CONTROL REQUIRED TOO MUCH ATTENTION.

SLIGHT DIFFICULTY
POOR

ADDED TOO MUCH POWER AND STARTED TO CLIMS.



CONFIGURATION 7L FLIGHT NUMBER 74-4 PLO' B WIND (knots) ES
WIND SHEAR SMALL
EXTERNAL TURBULEACE MODERATE
BELOW 1:00* WIND:khots: CONFIGURATION 7L WIND SHEAR NOTICESTIBLE EXTERNAL TURHULENCE NEGLIGIBLE FLIGHT NUMBER 46-2 PLOT RATING 4.8 PILOT-RATING 3 CHARACTERISTIC RC015 -.013 -.05 -.25 -1.49 CHARACTERISTIC ROOTS [-.01] -.04 [-.05] -1.49 I AIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES | 10-gridded velocity (1AS) | Vertical velocity (17) | Vertical velocit FLIGHT CONDITION TURBULENCE DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS F8,-5 Kno*s THE CENTROLS OF THE PROPERTY O AN OWNARTS HE FROM DESIRED SPEED NOT TAMEDIACELY APPARENT. COMMENTS AND BENCE VARIATIONS INDICATED ABove. MORGES. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE P ___ PER_00 PERIOC DAMPING AMPLITUDE SNATT _______ HEAVE - -----HARDEN SOURCE SLEVAPOR MCT ATT MPT-0 SOURCE DEGREE EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED "URNS SMATE. A REJUDINE DIFF COUTY CHANGE REQUIRED LASE OF COMPENSATION Diff CULTY INJUST HE DS INDISTINUELS ABL. FROM THOSE OF LEVEL FLIGHT. COMMENTS 5 FLIGHT PATH CONTROL stercept & r 'se trock Interrediate rack f not 6 de parh Localizer State parh coolirer 6 de parh ntercept & initial track Finat track Localizer Gilde path Localizer - poolirer Glide path Localizer Glide par-5 .10801 - S.16 SLIGHT 0.1000 SOME SULUHT DIFFICULTY NUNE NON : 41.156.7 SONE NON-NONE canty 7A13 COOL 33510 door FAIR COOD PRECISION MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET GEST UP TREFINAL TURBULENCE VAS MARKED BELDW 1300° AGL. FARE MARKET IN TRACETRE RESALIKED GOOD BELAUSE OF COORSIDER CHECKLITH RESERVES. DIFFICURE OF TO WIND IL FOLD AND HER FILE CONTROL OF COMMENTS STEDESTARE. 6 BREAKOUT AND FLARE No DIFFCULTY FASE OF APPRESTING RATE OF DESCENT NOT PRECISION OF ATTAINING TOUCHDOWN POINT FAIR (400-0) DIFFERENCES IN NATURALS BY SIZE OF THE ASIA FOR ON OF GILBERTA WE ARM THROUGH HARM - GOT THE TIME ON SPELD. MADE A CORRUCTION OF TRUSH OF COMPANY OF THE SPECIAL PROPERTY OF T COMMENTS 7 CONTROL TECHNIQUE COMMEN'S IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LÉVER 8 LATERAL DIRECTIONAL CHARACTERISTICS FEFEC" ON FINAL ASSESSMENT NON NONE: ATERAL STICK ALGES COMPATIBLE VIT-PAGULISINAL ONES: 9 LEAST OBJECTIONABLE FEATURES (Growth To MORNAL, RESSOURCE ATTEMPTE STANCES). NO INEXPICTED LONGIT DINA, OR DEAVE RESPONSES. IO MOST OBJECTIONABLE FEATURES SCHE WIND SPEZITS METHO AND ELEMANO SUBSECTION HOW HERE, SPECIAL AND EXAMPLE AND AND STREAM SPECIAL CONTRACTOR OF A CARD AND AND ADDRESS OF A CARD AND AND ADDRESS OF A CARD ADDRESS OF A CARD ADDRESS OF A CARD ADDRESS OF A CARD AND ADDRESS OF A CARD ADDRESS OF A CA GROS MODEL WITE GLASSA DA PLEASANT GRARACTERISTICS. SLEWET STATIONITY OF MAINTAINING PRECISE SPEED ON CHROLIT, BUT STAKE CONTROL BETTER DURING APPROACH. : I MISCELLANEOUS



	CONFIGURATION 8 WHALL (MICHORS) 5 FLIGHT NUMBER 92- WHAL SHEAR FLIOT A EXTERNAL TURBULENCE PILOT-RAT NG 3	CONFIGURATION 8 WINCHMOTS) 5 FI GHT NUMBER TEST WAND SHEAR LIGHT PLOT A EXTERNAL TURBULENCE NEGLICIBLE PLOT-RATING 7
LAIRCRAFT RESPONSE TO CONT	CHARACTERISTIC ROOTS (CHARACTERISTIC ROOTS 00417 -1.58
CONTROL SENSITIVITY: RESPONSE 2 EASE OF MAINTAINING DESIRE		Mag: 0.3 (rad/sec ²)/m Za: 8.9 (rad/sec ²)/m Za: 8.9 (rad/sec ²)/m Satisfactory Too Great Satisfactory Satisfactory
FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATOR COMMENTS	Long tradinal velocity (TAS) Vertical velocity (h)	Longitudical velocity (1AS) VMC IMC IMC VMC IMC IMC OUT OUT OUT SIGNIT PEDERATE GREAT SITCHT PEDERATE GREAT +15,-10 k-ots +300 fg m TH: PITCH ATTITUDE CHANGE OF APTOLY NITH SHALL CONTROL IN- PUTS. A PODERATE CHANGE IN LIFT ACCOMPANIED AIRSPEED CHANGES MAKING FOR NOTH AN AIRSPEED AND VERTICAL SPEED CONTROL PROBLEM. TURBULENCE BOUNCED THE MOSE AROUND MODERATELY.
3 RESIDUAL OSCILLATORY CHARA	ACTERISTICS	
PITCH HEAVE EXCITATION	AMP_ITUJE PÉRIOD DAMFING	AMPLITUDE PERIOD DAMPING ZERO ZERO SCURCE DEGREE
CONTROL COMMENTS		
4 CHANGE IN THRUST REQUIRE	D FOR 20° BANKEC TURNS	
CHANGE REQUIRED EASE OF COMPENSATION	NECLICIBLE NO DIFFICULTY	SSACI. N° DIFFICULTY
COMMENTS		
5 FUIGHT PATH CONTROL		
	Intercept & initial track intermediate track Final track	Intercept 8 initial track Intermediate track Final track
DIFF GUUTY	Stide path Localizer Glide path Localizer Glide path Localizer NONE SLIGHT SCHOOL SLIGHT MADERATE SLIGHT	Glide path Localizer Glide path Localizer Glide path Localizer MODERATE SLIGHT CREAT MODERATE GREAT SLIGHT
PRECISION	FAIR PAIR FAIR PAIR PAIR FAIR	POUR FAIR VERY POOR FAIR POOR FAIR
MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET	4LTIT UDE 500	BCO
COMMENTS	TO STAY ON THE GLIDE PATH, THE MATE OF DESCENT FROM APPROXIMATED 700° TO 100 PT 18-2 TO BE INCREASED TO AS DUCH AS 14-02 F.P.M. THIS REQUIREMENT MAS ANTICIPATED FROM THE PREVIOUS APPROACH AND MAS COPED ATTH ADT-QUARTEY, MICHOUT THIS FROM REMONACOR, APPROACH WOULD	SEE SECTION #2. WIND SHEAR ALSO CAUSED SOME DIFFICULTY IN DIRECTION.
6 BREAKOUT AND FLARE	WAVE HAD TO HAVE HEEN ABORTED.	
EASE OF ARRESTING RATE OF DE PRECISION OF ATTA NING TOUCHDO COMMENTS:	SCENT NO DIFF CULTY SOOD STATE OF THE SOOD STATE	MC DIFFICU_TY
7 CONTROL TECHNIQLE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARGE	ACTERISTICS	
EFFECT ON FINAL ASSESSMENT	NOME	SMALL
9 LEAST OBJECTIONABLE FEAT	URES THE TURBULENC: DID NOT SEEN TO HAVE BEEN A PACTOR - IT WAS NOT REALLY NOTICEABLE.	
IO. MOST OBJECTIONABLE FEATU	RES	SEE SECTION #2
I MISCELLANEOUS	NBE WAS CHANGED FROM .59 TO .3 AND ZBT FROM 4.5 TO 2.9. NUMBER PAR FIGH OPTIMUM.	



CONFIGURATION 8
FEIGHT NUMBER 25-2
PILOT 8
PILOT-RATING 5½

WINDIknotsk 10 WIND SHEAR SMALL
EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROOTS 0 -.17 -1.58 -.04

WIND (knots)

CONFIGURATION 8
FLIGHT NUMBER 49-1
P_OT B
PLOT-RATING 6C

WIND SHEAR EXTERNAL TURBULENCE

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

RESPONSE

COMMENTS

ELE VATOR	THRUST LEVER		
Mag = 0.39 (rod/sec ²)/in 2	Z8T = 7.4	(ft/sec²Vini	
Initial Final	In-feat	Finel	
SATISFACTORY SATISFACTORY	SATISFACTURY	SATISFACTORY	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TURBULENCE:
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATION

- 1	Longitue	linat velac	'y (IAS)	Vertical velocity (h)		
	VMC.	TMC	IMC	VMC	:MC	IMC
- [OUT	QU*	IN	OUT	TLO	IN
1	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
NS	-12	+5	knots			1 pm

DIFFICULTY DUE TO CROSS-CHECK AND LEARNING.

	/ATOR	THRUST LEVER		
MaE: 0.59	(rad/sec2)/in	Zar: 4.5	[ft/sec2]/in	
Initial	F⊪nal	In:1:al	Final	
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY	

CHARACTER:STIC ROOTS 0 -.04 -.17 -1.58

Long tuding: velocity [IAS]			Vertica: ve acity (h)		
VMC	IMC	LMC	VMC	J.M.C	LM C
OUT	001	IN	QUT	OUT	IN
SLICHT	SLIGHT	SLIGHT	MODERATE	MODERATE	
t	В	knots			fp m

STRANGE HEAVE CHARACTERISTICS NOT APPRECIATED UNTIL FINAL APPROACH WHEN IT APPEARED THAT PROBLEM WAS DUE TO AN APPARENT LOW HEIGHT RATE DAMPHING. I JUST COULD NOT GET THE PRECISE DESCENT RATE NEEDED.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE EXCITATION

COMMENTS

AMPLITUDE	PERIOD	DAMPING
ZERO ZERO		
Zaro		
SOURCE		DEGREE

DAMPING SOURCE DEGREE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

MODERATE DIFFICULTY

COMMENTS:

LEARNING

SOME	
SLIGHT	DIFFICULTY

I was unable to attribute the thrust requirement directly to a bank angle effect.

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermed		Final track	
Glide path	Locolizer	Glide path	Localizer	Gide path	Localiter
SLIGHT	SLIGHT	\$1,1GHT	SLICHT	SLIGHT	SLIGHT
GOOD	GOOD	GOOD	GOOD	COOD	G00 P

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 0.K.

COMMENTS

Intercept & initial track Glide path Localizer Glide path Localizer Glide poth Localizer SLIGHT SLIGHT > SLIGHT SILIGHT MODERATE > SLIGHT FAIR FALR POOR FAIR FAIR FAIR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SLIGHT PRECISION OF ATTAINING TOUCHDOWN POINT FAIR/GOOD.

DIFFICULTY

COMMENTS:

NEEDBD L TO 2 SECONDS TO FIND THE LANDING AREA AFTER RREAKDUT - BRIGHT SUN AND RED MARKERS AGAINST SNOW.

500

I HAD NOT LEARNED THE CONTROL OF DESCENT RATE - WENT HIGH, THEN HIGHER EVEN THOUGH THRUST WAS STILL BEING REDUCED. FINALLY ORSECTED WITH A DESCENT RATE OF 1500 F.P.M. RECOVERED CLIDESCOPE AT END WITH LOTS OF THRUST LEAD BUT ON NOT LEKE LAGGE DESCENT RATE AND THRUST REQUIREMENTS NEAR GRUUND.

SLIGHT/MODERATE DIFFICULTY

DIFFICULTY POSSIBLY DUE TO THRUST LAG.

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

NONE

9 LEAST OBJECTIONABLE FEATURES LIKE A HELICOPTER - NEED MORE ATTENTION TO PITCH ATTITUDE THAN I GAVE IT.

TURBULENCE NOT A FACTOR, PITCH ATTITUDE STABILITY REASONABLE.

10. MOST CBJECTICNABLE FEATURES PATCH ATTITUDE MONITORING IS TOO MUCH OF A REQUIREMENT. IF CROSS-CHECK IS LOST MOMENTARILY to TO 15 KNOTS ATRSPEZO CHANGE RESULTS.

I MISCELLANEOUS

PILOT ASKED TO ASSESS THE EFFECT OF SIMULATION OF PILOT STATION REMOVED FROM CENTER OF GRAVITY.

COMPONIT: FEELS BETTER THAN MICHOUT THIS TERM, BUT OSCILLATORY MOSS OF CONTROL POSSIBLE EQUALLY WITH EITHER.



CONFIGURATION 8
FLIGHT NUMBER L22-3
PLOT G
PILOT-RATING 75 CONFIGURATION 9
FLIGHT NUMBER 41-2
PILOT D
FILOT-RATING 85 W NOTKHOOTS: 5
SMALL
ROTE STATE OF THE STATE #IND (nnots) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT (SOME THERMALS) CHARACTERISTIC FOOTS 0 -.04 -.17 -1.58 CHARACTERISTIC ROOTS -.024 -.04 -.116 -1.66 I AIRCHAFT RESPONSE TO CONTROL INPUTS $\frac{\text{ELEVATOR}}{\text{Mag}} = \frac{0.16}{1.000} \frac{\text{Cec}^2 1/n}{\text{Find}^2} \frac{\text{THRUS}}{\text{11.9}} \frac{\text{LEVER}}{\text{(11/sec}^2)^2/n} \frac{11.9}{\text{End}^2} \frac{(11/sec^2)^2/n}{\text{Find}^2}$ (1·/sec²//in CONTROL SENSITIVITY TOO CREAT TOO SMALL TOO CREAT TOO SMALL TOO GREAT TOU SMALL RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES origitudinal ve ocity (TAS) Vertical velacity (h)

VMC IMC :MC
OL OUT IN

SLICHT MCDERATE CREAT | Verlical velocity (h) | VMC | IMC | IMC | IMC | IMC | OUT | N | MODERATE | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | GREAT | G VMC OUT SIJICHT FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS 300 VERY CLOSE ATTENTION REQUIRED INC TO MAINTAIN GIVEN AIR-SPEED. AS A RESULT CONTROL OF VERTICAL SPEED SUPPERED, PARTICULARLY ON DOWNLISH AND HASE LEG. DIFFICULTY DUE TO OVERCONTROL OF PITCH ATTITUDE AND THRUST. TIT APPEARS THAT THE CONFIGURATION HAS NEGATIVE STATIC
MAGINA AND GOUPLING BETWEEN THRUST AND PITCH ATTITUDE.
PILLOT TENDS TO OVERDRIVE THE AIRCRAPT AND OVERCONTROLS TO
THE POINT OF A P.1.0. 3 RESIDUAL OSCILLATORY CHARACTER STICS AMPLITUDE MODERATE MODERATE AMPL TUDE DAMPING PERIOD DAMFING PERIOD HEAVE DEGREE SOURCE DEGREE **EXCITATION** CONTROL RESPONSE CLOSED LOOP - SOME TENDENCY TO P.I.O. BUT MOSTLY PILOT NOTICES LARGE AMPLITUDE OVERSHOOTS OF PITCH ATTITUDE OSCILLATION UNNOTICEABLE UNLESS OBSCURED BY LIGHT COMMENTS EXTERNAL TURBULENCE AND THRUST. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS DIFF CULTY DIFF CULTY COMMENTS THROTTLE USED TO MAINTAIN CONSTANT ALTITUDE IN PRESENCE OF SPEED VARIATIONS. DIFFICULTY PROBABLY DUE TO COUPLING BETWEEN IAS AND PITCH ATTITUDE. WHEN PILOT MAKES AN INPUT, HE CANNOT TELL PHAT THE FINAL RESPONSE WILL BE. 5 FLIGHT PATH CONTROL Final Irack intercept & initial track Intermediale track Intercept & initia track Intermediate track Glide path Lacolizer Glide path Localizer DIFFICULTY SLISHT SUIGHT CREAT SLIGHT SLIGHT MODERATE GREAT GREAT GREAT CREAT GREAT GOOD VERY POOR VERY POOR VERY POOR VERY POOR VERY POOR VERY POOR PRECISION VERY POOR FAIR 6000 FAIR FAIR MIN-MUM ACCEPTABLE BREAKOUT F GREATER THAN 200 FEET ALT TUDE LOST REIGHT TO 1500 PT ON BASE LEG. COULD NOT REDAIN 1900 FT DUE TO MANIFOLD PRESSURE PLUCTUATIONS IN PRESENCE OF TURBULENCE. TOO MICH ATTENTION REQUIRED TO CONTROL ALESPEED THROUGH-OUT APPROACH - CONTINUOUS OVERCONTROL. ALSO HAD FOOR VISIBILITY AND TRAFFIC PROBLEMS WHICH DISTRACTED ME FROM COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT DEFICULTY
PRECISION OF ATTAINING TOJCHDOWN POINT GOOD SLIGHT/MODERATE CHFF CULTY 900R VERY POSITIVE EFFORT REQUIRED TO KEEP SPEED OF COMMENTS INDICATED AIRSPEED WAS TOO LOW. WITH STICK AND TO REDUCE RATE OF DESCENT WITH THROTTLE 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST DURING THE INTERMEDIATE TRACK, USED THROTTLE TO LEAD, IN CHECKING SPEED DEPARTURES. COUPLING BETWEEN PITCH ATTITUDE AND RATE OF DESCENT SEEMED TO BE PRESENT. I MAD SO MICH TROUBLE MAINTAINING ATREPED THAT IT WAS NOT POSSIBLE TO BE POSITIVE ABOUT THE EFFECTS OF THRUST CHANGES. LEVER B LATERAL DIRECTIONAL CHARACTERISTICS SMALL: IT SEEMED THAT MAKING HEADING CHANGES WAS DIFFICULT BECAUSE OF THE GREAT DIFFICULTY IN CONTROLLING PYTCH DURING TURNING MANDEUVRES. EFFECT ON FINAL ASSESSMENT 9 LEAST COLECTIONABLE FEATURES IC. MOST OBJECT ONABLE FEATURES PETCH ATTITUDE CONTROL, IAS CONTROL, POOR RATE OF DESCENT CONTROL. II MISCELLANEOUS V.M.C. FUIGHT RELATIVELY EASY COMPARED WITH L.M.C. SOME PROBLEM PSYCHOLOGICACLY DUE TO WEATHER AND TRAFFIC REAL DIFFICULTY FIRST EXPERIENCED IN GRANCING AIRSPEED UNDER I.M.C.



CONFIGURATION 9
FLIGHT NUMBER 87-2
PILOT A PILOT A
PILOT-RATING 6

10 W ND(knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.024 -.040 -.116 -1.66

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION MAX MUM UNDESIRED FLUCTJATIONS

	Longitudinal velocity ([AS)			Vertical ve acity (fi)			
	V.M.C.	IMC	2 M 1	VMC	1.M.C	2 M I	
	OUT	OUT	IN	OUT	DUT	4N	
	MODERATE	GREAT	GREAT	SLIGHT	SLIGHT	SLIGHT	
S	±10		knots	OK		f.pm.	

COMMENTS

DIFFICULTY DUE TO THE PITCH ATTITUDE NOT SETTLING DOWN IN RESPONSE TO A VERY SMALL IMPUT BUT, INSTEAD, WANDERING IN THE DIRECTION OF THE IMPUT.

SATISFACTORY

CHARACTERIST.C ROOTS +.024 -.04 -.116 -1.66

WIND [knots]

WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

10-15

DAMPING

CONFIGURATION 9
FLIGHT NUMBER 38-2
PILCT B

PILOT-RATING 750

4MPLITUDE

Langitudinal velocity (1AS)			Vertical velocity (h)		
VMC	IM C.	I.M.C	VMC	I.M.C	_ IMC
Out	0r.	IN	OUT	QUT	IN
SLICHT	>5 LIGHT	>SLICHT	SLICHT	SCIGHT	SLIGHT
L5	-15	knots			l.p

DIFFIGURTY DUE TO TURBULENCE UPSETTING FITCH ATTITUDE AND TO PITCH ATTITUDE INSTABILITY.

PERIOD

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE SOURCE

SOURCE DEGREE

COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

DIFFICUL**T**Y

COMMENTS

DIFFICULTY

SOME THRUST COMPENSATION IS REQUIRED, BUT 1 AM NOT SURE OF THE CAUSE.

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermediale track		Final track	
Glide path	Lacalizer	Glde path	Localizer	Glide pair	Localizer
NONE	NONE	SLIGHT	SLIGHT	SLIGHT	SLIGHT
6000	CODD	FAIR	FAIR	FAIR	FA1R

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
F GREATER THAN 200 FEET

COMMEN*S:

COMMENTS:

Intercept & milia Irack | Intermediate track Glide path | Localizer | Glide path | Localize Final track Lacalizer Gude path Localizer SLIGHT SLIGHT SLIGHT FAIR/GOOD FAIR/GOOD

GREATER ATTENTION IS REQUIRED TO CONTROL PITCH ATTITUDE - THIS DEGRADES BOTH VERTICAL AND LATERAL TRACKING.

EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT COOD

6 BREAKOUT AND FLARE

SLIGHT DIFFICULTY

NOT STREE OF THRUST RESPONSE TO BE EXPECTED, RATE OF DESCRIPT AT TOUCHDOWN WAS SATISFACTORY, BUT WAS NOT POSITIVELY AND PRECISELY UNDER CONTROL.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECT ONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

NONE

300

9 LEAST OBJECTIONABLE FEATURES

O. MOST OBJECTIONABLE FEATURES AIRSPEED CONTROL QUITE DIFFICULT

PITCH ATTITUDE INSTABILITY - NOT ACCEPTABLE IN TURBULENCE. HEAVE CHARACTERISTICS A LITTLE CONFUSING FOR SOME UNKNOWN REASON.

II MISCELLANEOUS

CONTROLLABILITY COULD BE IN QUESTION BECAUSE OF PITCH ATTITUDE DIVERGENCE - MOTION DISCRIENTATION ETC.



CONFIGURATION 10 F_GHT NUMBER 14-2 PLOT A PILOT-RATING 8

10-15 WIND(snots! WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION LO F_IGHT NUMBER 61-1 PILOT A PILOT A
PI_OT-RATING 7

ELEVATOR

SATISPACTORY TOO GREAT

W-ND (knots) WIND SHEAR EXTERNAL TURBULENCE

CHARACTERISTIC ROOTS -,02 -,04 -.855± .476i

Mag = 0.25

CHARACTERISTIC ROOTS -.02 -.04 -.865 ± .4761

THRUST LEVER

SATISFACTORY SATISFACTORY

(11/sec²)/in

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE -

ELEV	ATOR	THRUST LEVER			
M&E : 0.3	(rad/sec ² l/in	Z8T= 15.0	(ft/sec ² l/in		
Initio	Fire	Initial	Final		
SLIGHTLY GREAT	TOO CREAT	SATISFACTORY	TOO SMALL		

2 EASE OF MAINTAINING DESIRED VELOCITIES

F_:GHT CONDITION	
TURBULENCE	
DIFFICULTY	
MAXIMUM UNCESIRED	FLACTUATION

	Longitudinal velocity (TAS)			Vertical veracity (h)		
	VMC.	IMC	IMC	VMC.	INC	: M.C
	CUT	OUT	IN	Q u1	DUT	IN
	MODERATE	GREAT	GREAT	SLIGHT	SUIGHT	GREAT
4S	+15	.0	anots	+20	0.0	fpm

Langitudinal velocity (IAS)
VMC IMC IMC
OUT OUT IN OUT OUT IN
SLIGHT MODERATE MODERATE
± 200 Fp.m.

(rad/sec2)/n ZaT = 15.0

THE FINAL RESPONSE TO SLEWATOR IMPUTS WAS TOO GREAT AND TOO MUCH ATTENTION WAS REQUIRED TO BOLD PITCH ATTITUDE. THE THREELENGS ALSO DISTURBED PITCH ATTITUDE TWO MICH. COMMENTS

DIFFICULTY DUE TO FITCH OSCILLATION WHICH REQUIRED MUCH TOO MUCH CONCENTRATION ON PITCH ATTITUDE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMP, ITUDE	PERIOD	DAMPING
LARGE	MEDIUM	, the
ZERO		

MODERATE ELEVATOR, TORBULENCE EASILY ELEVATOR

EXC TATION ELEVATOR, TURBULENCE ELEVATOR COMMENTS

THIS DID NOT SEEM TO BE AN OPEN IDOP OSCILLATION BUT RATHER

EASILY INEFFECTIVE

OSCILLATION CONTINUOUSLY BEING EXCLIED.

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION:

SMACL NO DIFFICULTY

SMALL SLIGHT DIFFICULTY

.

SLIGHT FAIR

AMPLITUDE

5. E. IGHT PATH CONTROL

DIFFICULTY PRECISION

COMMENTS:

		Intermediate trock Final trace			
Glide path	Losquize	Glide path	Localizer	Gi de path	Localizer
MODERATE	NONE	MODERATE	MODERATE	GREAT	MODERATE
POOR	COOD	PODR	FAIR	VERY POOR	P004

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET

COMMENTS

THE THRUST LEVER HAD TO BE PULLED SACK CONTINUOUSLY ON APPROACH TO THY TO KEEP THE AIRCRAFT COING DOWN. THERE HAS A PAIR WIND SHEAR CAUSING MOVEMENT TO THE RIGHT OF LOCALIZER AT LOW ALTITUDE.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT VERY POOR

DIFF CULTY

COMMENTS:

TOO HIGH ON GLIDE PATH AT BREAKDIFT

ntercept 8 initial trock | Intermediate Irack | Final t Glide paln | Localizer | Glide path | Localizer | Glide paln | Lacalizer NONE SLIGHT NONE SLIGHT NONE PAIR FAIR GOOD FAIR 0000

Final track

7. CONTROL TECHNIQUE

COMMENTS IF OFFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IC. MOST OBJECTIONABLE FEATURES

I. MISCELLANEOUS

TRAUST LEVER DISPLACEMENTS TOO LARGE.

THIS PORTION WENT SURPRISINGLY WELL IN LIGHT OF UNDESTRABLE PITCH CHARACTERISTICS.

DIFFICULTY

MADE TWO ATTEMPTS WITH TALAR LOCALIZER AT 090° AND ENDED UP MICH 100 HIGH ON EACH. - CHANCED TALAR TO 220° AND A THIRD APPROACH HAS MADE SUCCESSFULLY. THIS ILLUSTRATES THE PROTANCE OF GOOD WIND IMPORMATION FOR AIRCRAFT OF THIS TYPE. 1400 P.P.M. DOWN ESQUIRED WITH TAIL WIND AND STILL NOT RECOVERING CLIDESLOPE.



CONFIGURATION 1D FUIGHT NUMBER 52-1 PILOT H

CAILM ? WIND(knots)

WIND SHEAR EXTERNAL TURBULENCE

CONFIGURATION 10
FLIGHT NUMBER 55-1
PILOT B
PI_OT-RATING 5C

WIND (knots) WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE

PILOT-RATING 750

CHARACTERISTIC ROOTS -.02 -.04 -.865 ± 1.4761

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELE	VATOR		T LÉVÉR
Mag = D. 25	trod/sec21/in	Z8T - 15.0	(1 /sec ² //in
Initial	Fina:	Init-al	Final
SAT LS PACTORY	SATISFACTORY	SATIS FACTORY	NCT ASSESSABLE

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION MAXIMUM UNDESIRED FLUCTUATIONS

	Longitu	dina) velac	ity (TAS)	Vert	ico velocity	(h)
	V.M.C	IMC	IMC	VMC	MC	LW C
	OUT	CUT	IN .	OUT	110	IN
	SLIGHT	SLIGHT	MODERATE	SLICHT	SLIGHT	GREAT
5	-20	5	knots	-3	GD	f.pm,

DIFFICULTY MAINLY ON APPROACH FOR SUME UNKNOWN REASON

CHARACTERISTIC ROCTS -.02 -.04 -.865± .4761

	dinat velocit	y (IAS)	. Ver	tical ve ocity	(h)
VMC	I.M.C	IMC	V M C	TIME	TMC
OUT	CUT	IN	OUT	OUT	IN
SLIGHT	> SLIGHT	MODERATE	SLIGHT	MUDERATE	MODERATE
+1	5,-10	knols	+3	800	(pm

DIFFICULTY IN VERTICAL SPEED CONTROL DUE TO SON THRUST LEVER SENSITIVITY. IT TAXES A LUNG TIME TO SETTLE DOWN TO WHAT IS TOO SMALL A VALUE

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS

AMPLITUDE	PERICO	DAMPING
ZERO		
ZERO		
SCURCE		DEGREE

EXCITATION CONTROL

ZERO ZERO	O DAMPING
SOJRÇE	DEGREE

Intercept 8 initial track | Intermediate track | Final track |
Slide path | Localizer | Glide path | Localizer | Glide path | Localizer |

NONE

COOD

DIFFICULTY

MODERATE

VERY POOR

NONE

FAIR

FAIR

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMA1,L NO DIFFICULTY

COMMENTS

NEGLIGIBLE NO DIFFIGULTY

NONE

GCOD

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermediate trock		Final track	
Glide path	Localizer	Glide path	Lacolizer	Glide path Localiz	
NONE	NONE	SLICHT	HONE	GREAT	SLIGHT
GDGD	FAIR	FAIR		VERY POOR	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 600

COMMENTS

GLIDESCOPE OK TO 800 FT, THEN COT HIGHER AND RIGHER SUDDENLY — REDUCING POWER HAD NO EFFECT

3000

3404

DIFFICULTY COULD BE DUE TO WIND SHEAR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT GOOD

DIFF-CU_TY

COMMENTS:

ENCERTAIN OF THRUST LEVER CHARACTERISTICS

MODERATE POOR DIFFICULTY DUE TO GETTING HIGH ON APPROACH

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I.A S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT NONE

9 LEAST OBJECTIONABLE FEATURES

TURBULENCE RESPONSE NOT BAD - BETTER IN PITCH THAN IN

SPEED UNINTENTIONALLY HIGH ON APPROACH. PROBABLY DUE TO PUTTING MOSE DOWN WHEN THRUST LEVER DOES NOT PRODUCE DESIRED RATE OF DESCENT.

IO MOST OBJECT ONABLE FEATURES SOME PITCH ATTITUDE UPSETS IN TURBULENCE PITCH ATTITUDE LOSSE - NILDLY INSTABLE, VERICAL SPEED CONTROL VERY POOR (INVABLE TO GET DOWN)

PITCH ATTITUDE DIVERGENCE

II. MISCELLANEOUS

DID TWO APPROACHES AND UNINTENTIONALLY GOT HIGH ON BOTH OF THEM

POSSIBLE WIND SHEAR ON APPROACH. RATING ASSUMES THAT A COMBINATION OF WIND SHEAR AND LEARNING DEFICIENCY HAS RESPONSIBLE FOR NOT BEING ABLE TO GET DOWN ON GLIDESLOPE



CONFIGURATION 10
FLIGHT NUMBER 48-3
PILOT C
PILOT-RATING 6

WIND(knots) WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE

CONFIGURATION 10 FLIGHT NUMBER 20-1 P:LOT D P:LOT D PLOT-RATING 3 TO 4

WIND (knots) CALM
WIND SHEAR HEGLIGIBLE
EXTERNAL TURBULENCE HEGLIGIBLE

CHARACTERISTIC ROOTS -.02 -.04 -.865 ± .4751

CHARACTERISTIC ROOTS -.02 -.04 -.865± .4761

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELEV	ATOR		T LEVER
MBE = 0.25	(rad/sec ²)/in	Zat = 15.0	(f1/sec ²)/in
Initial	Final	Initial	Final
SATISFACTORY	SATISFACTORY	TOG SMALL	TOO SMALL

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION MAXIMUM UNDESIRED FLUCTUATIONS

| Longitudinal velocity (TAS) | VMC | IMC | IMC | IMC | OUT | IN | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | Ver'ica velacity (h)

VMC IMC IMC
OUT OUT N

SLIGHT MODERATE MODERATE | Longitudinal velocity (TAS) | VMC | 1MC | 1MC | VMC | UMC

COMMENTS

DIFFICULTY ONLY NOTICEABLE ON FINAL APPROACH WHEN UNABLE TO STAY DOWN ON GLIDESLUPE, SPEED FLUCTUATIONS OCCURRED DURING THIS PHASE

CONSTANT ATTENTION TO PITCH ATTITUDE REQUIRED BOTH WITH AND WITHOUT TURBULENCE, WITHOUT TURBULENCE SPEED FLUCTUATIONS ±3 KNOTS.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE	PERI	00	DAMPING	
SMALL	MEDIUM		MODERATE	
ZERO				
SCURC	f [DEGREE	

HARDLY

DAMPING MODERATE HLGR PERIOD SMALL SMALL SOURCE DEGREE

NOT OSCILLATORY BUT, WHEN MAKING RAPID, MODERATE TO LARCE PITCH INPUTS, SOME TERMENCY TO OVERCONTROL DEVELOPED. THIS CREATED A SLIGHT PIO WHICH COULD BE ELIMINATED BY THE PILOT SEDUCING HIS GAIN

intercept 8 initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer |

MOST IF NOT ALL DIFFICULTY PROBABLY DUE TO LACK OF PILOT'S PROFICIENCY. OVERCONTROLLED AS TALAR SENSITIVITY INCREASED NEAR END OF APPROACH.

POOR

MODERATE MODERATE MODERATE

VERY POOR VERY POOR

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

ELEVATOR ELEVATOR

CHANGE REQUIRED. EASE OF COMPENSATION

NEGLIGIBLE	 	
NO		DIFFICULTY

COMMENTS

DIFFICULTY

SLIGHT

COOD

NONE

GOOD

5. FLIGHT PATH CONTROL

DIFFICULTY:
PREC SION

		Intermedia		Final track	
Glide path	Localize	Glide poth	Localizer	Glide path	Localizer
SUIGHT	NONE	MODERATE	SLIGHT	GREAT	MODERATE
FAIR	coon	6000	GOOD	VERY POOR	POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS:

UNABLE TO GET DOWN ON TO GLIDESLOPE ON PINAL APPROACH.

(MB. MODERATE VERTICAL WIND SHEAR.) TO STEEPEN DESCENT,
ALLOHEN DOSE TO DORD AND SPEED INCREASE TO 70 RONTS.
RELUCTANT TO PULL THRUST LEVER PAR ENOUGH WHEN RATE OF
DESCENT ALERADY 1000 FT/MIN.

6 BREAKOUT AND FLARE

EASE OF ARRESTING MATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

MODERATE	DIFFICULTY
----------	------------

COMMENTS:

OVERSHOT. WOULD HAVE HAD GREATER DIFFICULTY AT 200 FT DUE TO HIGH RATE OF DESCENT

NO _ POOR DIFFICULTY

POOR

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT MONE: NOT CONSCIOUS OF ANY DISHARMONY IF PRESENT.

NONE

9 LEAST OBJECTIONABLE FEATURES. INTIL MINAL PART OF APPROACH, WOULD HAVE RATED MODEL AS QUITE GOOD

POWER MANIPULATION IS A MENOR REQUIREMENT

IO MOST OBJECT: ONABLE FEATURES

DIFFICULTY IN FOLLOWING FINAL GLIDZSLOPE OVER-RIDING IN AURIVING AT RATING

NEED TO PAY CLOSE ATTENTION TO ATTITUDE. NOT POSSIBLE TO TRIM PRECISELY AND TO FLY HANDS OFF

I: MISCELLANEOUS

THRUST LEVER DISPLACEMENTS TOO LARGE. UNCERTAIN WHETHER PRESENCE OF WIND SHEAR AGGRAVATED ABOVE PROBLEM

TURBULENCE CAUSES SUBSTANTIAL INCREASE IN PILOT'S MORELOAD. I AM NOT SURE MY PROPICIENCY IS YET UP SUPFICIENTLY FOR EVALUATIONS. RATING IS TENTATIVE. NOTE: THIS WAS THE PILOT'S FIRST EVALUATION.



CONFIGURATION 11L FLIGHT NUMBER 69-2 PILOT

WIND(knots)

CHARACTERIST C ROOTS -.013 -.04 -.733 -1.0

WIND SHEAR SMALL/MODER EXTERNAL TURBULENCE NEGLIGIBLE SMALL/MODERATE

PILOT A PILOT-RATING 7

CONFIGURATION E1L FLIGHT NUMBER 95-3 PILOT B PILOT B PILOT-RATING 7C

WIND (knots) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERIST C ROOTS -.013 -.04 -.733 -1.0

DAMPING

Final track Glide path Localizer

SLICHT

FAIR

SLIGHT

FAIR

ZERO

DÉGRÉE

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

FLIGHT CONDITION

TURBULENCE: DIFFICULTY

Initial Final Initial Final SATISFACTORY TOO GREAT SATISFACTORY TOO SMALL

Mag = 0.2 (ro TOR THRUST _EVER (roa/sec2)/in ZBT = 15.0 (ft/sec2/in SATISFACTORY SATISFACTORY SLIGHTLY SHALL SLIGHTLY SHALL

2.EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (h)
VMC IMC
OUT OUT IMC VMC IMC OUT OUT

MAXIMUM UNDESIRED FLUCTUATIONS

IMC NONE : GREAT knots ŞLIGHT

Langitudinal velocity (IAS)
VMC LMC IMC IMC
OUT OUT IN Vertical velocity (f)
VMC (MC)
OUT OUT OUT OUT IN SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT

PITCH CHARACTERISTICS REQUIRE CLOSE ATTENTION TO PITCH ATTITUDE

COMMENTS:

THE TURBULENCE AND LARGE PITCH ATTITUDE RESPONSE TO BLEVATOR CAUSED MUCH TOO MUCH PITCH ATTITUDE ACTIVITY AND HENCE A REAL AIRSPEED CONTROL PROBLEM. TOO MUCH CONCENTRATION ON THIS ASPECT WAS REQUIRED AND HEADING CONTROL SECAME

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

PERIOD	DAMPING	
	DEGREE	

50URCE

AMFL TUDE PERIOD
I LONG (=12 SEC.)

EXCITATION CONTROL COMMENTS

BOTHERSOME DURING TIGHT PITCH AND AIRSPEED TRACKING EXERCISES

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

SMALI. OIFFICUL*Y

COMMENTS

SMALL SLIGHT DIFFICULTY

intercept & initial track | Intermed Glide path | Lacalizer | Glide path

NONE

GOOD

DIFFICULTY DUE TO PITCH CHARACTERISTICS BEING EITHER UNSTABLE OR BARELY OSCILLATORY WITH ZERO DAMPING.

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept & mitto-track Intermediale track Fino track
Glide path Localizer Glide path Localizer Glide path Localizer MODERATE MODERATE SLIGHT SUIGHT SLIGHT GREAT FAIR FAIR POOR VERY POOR

MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET

ALTITUDE 500

COMMENTS

SEE SECTION 92. I STARTED TO GET WELL ABOVE THE GLIDEPATH DURING THE INTERMEDIATE PORTION AND RAD TO SELECT ABOUT 1300 F.P.M. DOWN WHICH WAS UNCOMPORTABLE. AT AND JUST BEFORE BREAKDUT THE LOCALIZER WAS HARD RIGHT AND THE GLIDEPATH SLIGHTLY LOW. HIGH WORKLOAD ON BOTH G.P. AND LOC.

6 BREAKOUT AND FLARE

NO	DIFFICULTY
COOD	

300

NONE

G000

SMALI.

PITCH CHARACTERISTICS DEMAND MOST ATTENTION - LOCALIZER TRACKING SUPPERS. ALWAYS SEEM TO GO HIGH AT BREAKOUT WHEN BLIND LOWERED.

diate trock

5 LIGHT

FAIR

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NO	CIFFICULT
CGOD	

COMMENTS

SLIGHT FAIR DIFFICULTY

SLIGHT

GOOD

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8. LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL: THE WEATHERCOCK STABILITY SEEMS WEAK MEEN A SMALL RUDDER INPUT IS MADE.

VERY SMALL

9 LEAST OBJECTIONABLE FEATURES

10 MOST OBJECTIONABLE FEATURES

FITCH CHARACTERISTICS - APPARENT OSCILLATION SOMETIMES ADDS TO YOUR CORRECTING CONTROL INPUT TO GIVE TOO LARGE A CORRECTION. THE LOW PERIOD OF THE OSCILLATION IS SUCH AS TO NOT ALLOW ANTICIPATION OF THIS EFFECT AND THEREBY TO GET GAUGHT.

II MISCELLANEOUS

NOTE: NO ARTIFICIAL TURBULENCE WAS INTRODUCED DURING THIS EVALUATION.



	CONFIGURATION 11 WIND(Mods) 10 FLIGHT NUMBER 37-2 WIND SHEAR ? PILOT B EXTERNAL TURBULENCE REGITCIBLE PILOT-RATING 7	CONFIGURATION FLIGHT NUMBER FILOT PILOT-RATING	WIND (KODIS) WIND SHEAR EXTERNAL TURBULENCE
LARGRAFI AFCRONCE TO CONT	CHARACTERISTIC ROOTS [-,01]04733 -1.0	CHARACTER STIC ROOTS	
I AIRCRAFT RESPONSE TO CONT CONTROL SENSITIVITY RESPONSE: 2 EASE OF MAINTAINING DESIRE			ECTIVE ZST: FINAL Final
FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATION	Longitus nail velocity (11AS) Vertical velocity (h)		AS1
COMMENTS	DIFFICULTY DUE TO PITCH ATTITUDE SPEETS BY TURBULENCE, POUR DESCENT-RATE CONTROL ON APPROACH - POSSIBLY DUE TO WIND SHEAR.		
	AIMD DUCKE		
3.750.5			
3 RESIDUAL OSCILLATORY CHARA	AMPLITUDE PERIOD DAMPING	AMPL TUDE	PERIOD DAMPING
P TCH HEAVE	ZERO ZERO		
EXCITATION	SOURCE DEGREE	SOURCE	DEGREE
CONTROL			
COMMENTS			
4. CHANGE IN THRUST REQUIRED	D FOR 20° BANKED TURNS		
CHANGE REQUIRED. EASE OF COMPENSATION	DIFF CULTY	DIFF!	CULTY
COMMENTS	NOT SURE OF REQUIREMENTS. THRUST CHARGES APPEAR TO AFFECT PITCH ACTITUE - NO PROBLEM.		
S FLIGHT PATH CONTROL			
DIES CHUTH	Intercept & initial Irack Intermediate Irack Final track Glide path Localizer Glide path Localizer Glide path Localizer	Intercept 8 mittal track Int Glide path Lacatizer Glide	lermediate track Final track path Localizer Glide path Localizer
PRECISION	NORE NONE NONE NONE MODERATE SLIGHT		
MINIMUM ACCEPTABLE BREAKOUT			
IF GREATER THAN 200 FEET	500		
COMMENTS.	NOT SURE OF CALSE OF DIFFICULTY POSSIBLY SIDEAR		
6 BREAKOUT AND FLARE			
EASE OF ARRESTING RATE OF DEP PRECISION OF ATTAINING TOUCHDO	SCENT SLICET DIFFICULTY WN POINT FAIR		DIFFICULTY
COMMEN "S	SOT BURE O CAUTE OF DOTFICHARY		
7 CONTROL TECHNIQUE			
COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND			
VERTICAL SPEED WITH THRUST LEVER			
B LATERAL DIRECTIONAL CHARA	ACTERISTICS		
EFFECT ON FINAL ASSESSMENT			
9 LEAST OBJECTIONABLE FEAT	URES		
O MOST OBJECT ONABLE FEATUR	TO PITCH ATTITUDE. RATHER RAPID RESPONSE TO		
	ELEVATOR.		
I MISCELLANGO A			
I. MISCELLANEOUS	LARGE RESPONSE TO REFUNDED FOR SOMEY NOTICEABLE WHEN ELEVATOR STEPS APPLIED PORPOSERY. DISARCTERISTICS LIKE A HELICOPTER. TURBULENCE ACTING D TO C.		
	TOTAL TOTAL		



CONFIGURATION 121. FLIGHT NUMBER 85-7 PILOT A P-LOT-RATING 81. WIND(knots) NEGLIAI BLE WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE PILOT A PILOT-RATING 8 CHARAC*ERISTIC ROOTS 0 -- 04 -- 369 -1.38 CHARACTERISTIC R001S 0 -.04 -.369 -1.38 I AIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY SATISFACTORY TOO GREAT SATISFACTORY TOO SMALL RESPONSE. SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES. Congitudinal velocity (CAS)
VMC IMC IMC
OUT OUT IN Vertical velocity (h)
VMC IMC IMC IMC
OUT OUT IN SIJCHT PITCH ATTITUDE CONTROL WAS MUCH TOO SENSITIVE WHEN TURBULENCE WAS HE MENTING THE MOSE AROUND. ON FIRST APPROACH 1300FF, P.M. WAS REQUIRED TO HOLD CLIDE PATH ON SECOND APPROACH POWER MAD TO BE BLED OFF TO 48%. COMMENTS FARTASTIC ATTITUDE CHANGES TAKE PLACE QUITE RAPIDLY WITH FARLASTIC ATTIONS CONNECTS TAKE PROPERTY OF THE MEDITAL TO SEE TO MAINTAIN AIRSPESS. THE TURBULENCE ALSO SUMPS THE MOSE AND SERVES THE AIRCRAST INACCEPTABLY. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD DAMPI MCDERATE MEDIUM MODERATE ZERO AMPLITUDE ____ PERIOD DAMPING 1.ONG ZERO/YECATIVE SQUAGE DEGREE

ELEVATOR, TURBULENCE EASILY
ELEVATOR INEPFECTIVE SOURCE DEGREE EASILY EFFECTIVE EXCITATION: SLEVATOR, TURBULENCE ELEVATOR IT APPEARED, BY A SPECIFIC TEST THAT THERE WAS A ZERO OR NEGATIVELY DAMPED OSCILLATION, BUT THIS SHOWED UP IN PRACTICE AS A STRAIGHT PITCH DIVERGENCE. COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGIBLE NO CHANGE REQUIRED EASE OF COMPENSATION SMALL NO DIFFICULTY DIFFICU_TY COMMENTS 5. FL:GHT PATH CONTROL Intercept & in-trait track | htermediate track | Fino: track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide pat Intercept 8 initial track intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY: MODERATE SLIGHT MODERATE SLIGHT GREAT FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 800 800° ALL PHASES OF TRACKING WERE CK, BUT I WAS WORKING MUCH TOO ASSESSMENT FOR SECOND APPROACH. APPROXIMATELY 1000 F.P.M. WERE REQUIRED TO MAINTAIN GLIDEPATH. THE AIRSPEED CONTROL WAS POOR AND THIS ADDED TO THE VERTICAL SPEED PROBLEMS. LITTLE TIME HAS LEFT FOR LOCALIZER MONITORING AND HEADING WANDERED. COMMENTS: HARD ON AIRSPED CONTROL. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO OFFICELTY PRECISION OF ATTAINING TOUCHDOWN POINT 12000 NO DIFFICULTY
GOOD COMMENTS: 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM : A S WITH ELEVATOR AND VEATICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS FFFFCT ON FINAL ASSESSMENT SMALL: AS ON ALL MODELS, THE HEADING CHANGE WITH SMALL OUT-OF-TRIF ON RUDGER WAS TOO LARGE 9 LEAST OBJECTIONABLE FEATURES IO. MOST CRUECTIONABLE FEATURES THE UNSTRADINESS IN PITCH BECAME QUITE INTOLERABLE WHEN THE TURNIQUECK WAS ENTRODUCED. TURBULENCE AND PITCH ATTITUDE CONTROL. POWER CHANGES WITH DESCENT RATE. II. MISCELLANEOUS APPROACH PHASE WAS REPEATED WITH TALAR LOCALIZER REGRIENTED 80° LNTG WIND.



WIND(knots) 5
wind Shear SMALL
EXTERNAL TURBULENCE MODERATE
X(SLIGHT TAIL WIND) CONFIGURATION 13), FLIGHT NUMBER 62-1 PILOT A FILOT-RATING 7 CONFIGURATION 12L FLIGHT NUMBER 55-3 PLOT B PILOT-RATING 70 WIND (knots) 5
WIND SHEAR MODERN
EXTERNAL TURBULENCE LIGHT MODERATE CHAR4CTERISTIC ROOTS 0 -.04 -.369 -1.38 CHARACTER STIC ROOTS +.026 -.04 -.212 -1.57 : AIRCRAFT RESPONSE TO CONTROL INPUTS (11/sec²)/in CONTROL SENSIT VITY Initial Final Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY

SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES DIFFIGURTY DUE TO: LOW THRUST LEVER SENSITIVITY: DUITE RESPONSIVE TO TURBULENCE, SLOW TO SETTLE DOWN TO PINAL RATE OF DESCENT AFTER THRUST INPUTS: 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD AMPLITUDE DAMPING SMAL /MODERATE ZERO LONG MODERATE REAVE DEGRE É DEGREE EXC TATION EASILY EFFECTIVE EASILY LEVATOR, TURBULENCE CONTROL THE LIGHTLY DAMPED OSCILLATION IN PITCH HAS THE MOST OUTSTANDING FEATURE OF THIS MODEL. CONTINUOUS ATTENTION HAS REQUERED TO MAINTAIN PITCH ATTITUDE BUT, AFTER A WHILE THE AIRSPEED CONTROL SEMEDO TO BE RELATIVELY EASY. — I CANNOT BE POSITIVE THAT THE OSCILLATION IS THERE! - COULD COMMENTS BE LOW PITCH DAMPING, HIGH ELEVATOR SENSITIVITY PRODUCTS. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NO DEFICULTY NEGLIGIBLE NO DIFFICU_TY COMMENTS 5 FLIGHT PATH CONTROL Intercept & nihol track | Intermediate track | Final track Glide path | Localizer | Glide path | Localizer | Glide path | Localizer Intercept & Initial track | Intermed ate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | SLICHT NONE SLICHT SLIGHT MODERATE SLIGHT GOOD FAIR COOD FAIR FAIR MININUM ACCEPTABLE BREAKOUT ALT-TUDE
IF GREATER THAN 200 FEET 500 EVERYTEING WAS SORTED OUT WITH 800F.P.M. RATE OF DESCENT IN INTERMEDIATE PORTION. THEN, TO MAINTAIN GLIDERATH 1000 F.P.M. BECAME INADEQUATE AND WE EMDED UP MUCH TOO RIGH TO COMPLETE THE APPROACH. THE WIND SOCK SHOWED ABOUT 5 KNOTS CROSSWIND. ON FINAL TRACK, PROBLEM WAS DIE TO WIND SHEAR 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT 1300B. CREAT VERY POOR DIFFICULTY NOT POSITIVE OF THRUST CONTROL OVER RATE OF DESCENT. AT TOUCHDOWN, RATE OF DESCENT WAS CERTAINLY OK. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED W:TH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT MONE. MODERATE REAL TURBULENCE, HAD TO TRIM RUDDER THICE. LATERAL DIRECTIONAL CHARACTERISTICS OF STAINLY NOTICEABLE. 9 LEAST OBJECTIONABLE FEATURES O MCST OBJECT:ONABLE FEATURES FITCH INSTABILITY. RESPONSIVE IN PITCH AND REAVE TO TURBULENCE. ELEVATOR CONTROL SENSITIVITY REDUCED FROM 0.25 TO 0.15 BECAUSE CONTROL WOULD BE IN DOUBT FOR STEP INPUTS AT HIGHER LEVEL (VERY LARGE PITCH RATE RESPONSE). I: MISCELLANEOUS



CONFIGURATION 14 FLIGHT NUMBER 18-1 PILOT A PILOT-RATING 6

WIND(knots) L0-15
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MEGLIGIBLE

CONFIGURATION 14 FLIGHT NUMBER 40-3 FLO[†] D PILOT-RATING 7's

W:ND (knots) WIND SHEAR EXTERNAL TURBLLENCE

CHARACTERISTIC ROOTS +.031 -.04 -.20 -1.58

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE:

	ATOR	ThRUST	LEVÉR
M8E = 0.3	(-od/sec ²)/in	Za+- 15.0	(ft/sec ²)/in
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATIS FACTORY	SAT IS FACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION FLIGHT CONDITION
TURBULENCE:
DIFFICULTY
MAX MUM UNDESIRED FLUCTUATIONS

į	Longitu	dinal veloc	ity ([AS]	Ver	tical ve acty	(6)
	VMC.	1MC	I.M.C	VMC	1 M C	IMC
	OUT	out	IN	out	DUT	IN
	SLIGHT	SLICHT	MODERATE	SLIGHT	SLIGHT	SLIGHT
i	3	TO 5	knots	Ü	К	Ipm

THE FINAL ESPONSE TO ELEVATOR IS TOO GREAT. THE FITCH ATTITUDE CONTINUOUSLY JOSTLES AS A RESULT OF ELEVATOR AND TURBULENCE MAKING FOR A HIGH FITCH WORKLOAD.

CHARACTERISTIC ROOTS +.031 -.04 -.20 -1.58

Longitu	idinal veloci	ly (IAS)	Ver	tical velocity	(H)
VMC	IMC.	IMC	VM C	I.M.C	IMC
Ou*	100	IN	1LQ	OUT	IN
SLIGHT	MODERATE	>MODERATE	SLIGHT	MODERATE	MODERATE
	10	knots	4	200	lp m

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS

AMPLITUDE	PÉRIO0	DAMPING
MODERATE	HEDLUM	::::::::::::::::::::::::::::::::::::::
COURCE		necet e
SOURCE ELEVATOR, TURBULER	NGE HASILY	DEGREE

EXCITATION CONTROL

COMMENTS

AMPL TUDE	PERIOD	DAMPING
MODERATE	MEDIUM	NEGAT I VE
SHALL	LONG	MODERATE

SOURCE	DEGREE
ELEVATOR, TURBULENCE	EASILY
ELEVATOR	EFFECTIVE

THE OSCILLATORY CHARACTERISTICS ARE ALL CLOSED LOOP-PIO.
OPEN LOOP THE RESONSE WAS TYPICAL OF NEGATIVE STATIC MARGIN
CHARACTERISTICS.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

NEGLIGIBLE DIFFICULTY

DIFFICULTY

NONE

coop

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

COMMENTS :

			ntermed			track
	Grde path	Lacaliter	Gude poth	Localize-	Gride path	Locaheer
	NONE	NONE	NONE	S'_1GIIT	NONE	MODERATE
i	3A1R	COOR	FAIR	FAIR COOD	FAIR	VERY POOR

M-NIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 500

DIFFICULTY DUE TO UNCOMPORTABLE PITCHING THAT IS DIFFICULT TO RESTRAIN.

SLIGHT

COUD

MAD TO WORK VERY HARD - CONSTANT PILOT CONTROL IMPUTS REQUIRED. SURPRISED AT THE PERFORMANCE.

Intercept 8 initial track | Intermed are track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glid

MODERATE MODERATE GREAT

FAIR

GREAT

VERY POOR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT HODERATE DIFF CULTY
PRECISION OF ATTAINING TOUCHDOWN POINT VERY FOOR

SEE SECTIONS 42 AND 5. THE PITCH ATTITUDE COULD NOT BE SELECTED ACCURATELY EMOUGH BEFORE THE TOUCHDOWN FOIRT TO ENSURE A LANDING. HOWEVER, WITHOUT ACTUALLY TOUCHING DOWN THIS IS DIFFICULT TO ASSESS.

DIFFICULTY VERY POOR

FA1R

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1 AS WITH ELEVATOR AND VEHTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT NONE

NONE

9 LEAST OBJECTIONABLE FEATURES

RATE OF CLIMB CONTROL AND HEADING CONTROL OK.

O. MOST OBJECTIONABLE FEATURES SEE SECTIONS #2, 5 AND 6.

ATTITUDE CONTROL — REQUIRED CONSTANT ATTENTION AND STADING TENDENCY TO OVERCONTROL AND PIO.

II MISCELLANEOUS

PERFORMANCE CAN BE ACHIEVED is. REASONABLY GOOD PRECISION, BUT MUST WORK TOO HARD.



CONF.GURATION 141.
FILIGHY NUMBER 125-1
PILOT 3
PILOT-RATING 7K WIND(KHOIS) WIND SHEAR EXTERNAL TURBULENCE CONFIGURATION 141, FLIGHT NUMBER 58-1 PILCT C FILCT-RATINS 6 WIND (xno's) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT (THERMAL ACTIVITY) CHARACTERISTIC ROOTS +.031 -.04 -.20 -1.58 CHARACTERISTIC ROOTS +.03L -.04 -.20 -1.58 AIRCRAFT RESPONSE TO CONTROL INPLTS | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | Hrust Lever | SATISFACTORY TOO GREAT SATISFACTORY NOT ASSESSABLE 2 EASE OF MAINTAINING DESIRED VELOCITIES | Corg | Tudino| | Velocity | (AS) | Velocity | VMC | TMC | VMC | Vertical velocity (h)

V M C
OUT
OUT
SLIGHT HODERATE HODERATE LARGE MINAL RESPONSE TO LONGITUDINAL CONTROL INPUTS SIFFICULTY DUE TO WEAK PITCHING OSCILLATION 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE LUNG HEAVE 50URCE DEGREE EXCITATION. EASILY EFFECTIVE CONTROL EFFECT IS TENDENCY TO DEPART FROM REQUIRED AIRSPEED BY TOO LARGE A MARGIN TO BE ACCEPTABLE. CLOSE AIRSPEED CONTROL COMMENTS OSCILLATION ITSELF IS NOT VERY LARGE, BUT TERBULENCE EXCITES DIFFICULT. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION SMALL SLIGHT NO CIFFICULTY DIFFICULTY MAINTENANCE OF VERTICAL VELOCITY MO MORE DIFFICULT IN TURNS THAN IN LEVEL FLICHT, ALTITUDE VARIATION IN VMC TASKS LDG FT. COMMENTS MUST MONITOR PITCH DURING TURNS 5 FLIGHT PATH CONTROL Interces? & initial track | Intermediate track Slide path | Localizer | Slide path | Localizer Intercept B initia track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Gide path Localizer MODERATE NONE NONE ENGR NONE NONE NONE SUIGHT SLICHT MODERATE MODERATE GREAT 6000 COOD G00D 0000MINIMUM ACCEPTABLE BREAKOLT ALTITUDE IF GREATER THAN 200 FEFT $\begin{array}{c|c} \text{OK} & \text{OK} \end{array}$ (IF IN POSITION) 400 ATTITUDE AND SPEED CONTROL MOST DIFFICULT. DRAWS ATTENTION AWAY FROM LOCALIZER TASK RESILTING IN SLICHT 'S' TURNING. WENT VMC AT 400 PT. SINCE HIGH ON GLIDEPATH AND WANTED TO ATTEMPT FLARE. 6 BREAKOUT AND FLARE EASE OF AFRESTING RATE OF DESCENT VERY SLIGHT DIFF CULTY PRECISION OF ATTA NING TOLCHDOWN POINT 1200P THERE WAS A BINT OF HEAVE PRO TENDENCY NEAR GROUND WHILE TRYEN: TO STABILIZE PITCH. FAILED TO CORRECT COMPLETELY FOR HIGH APPROACH. 7 CONTROL TECHNIQUE COMMENTS PORFERENT FROM SPEED CONTROL TECHNIQUE IS TO MAKE LARGE PITCH ATTITUDE LAS WITH ELEVATOR AND CORRECTIONS FOR A SHORT TIME. LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS SMALL RELATIVELY HIGH LATERAL PORCES, LONGITUDINAL PURCES LOWER, LACK OF HARMONY NOTICEABLE. EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES

> UNSTABLE PETGEING MOMENT FROM HEAVI, INPUTS APPEARED GO TO EXIST.

POOR CONTROL OF AIRSPEED AND POSSIBLY ALSO RATE OF

IO. MOST OBJECTIONABLE FEATURES PIPCE OSCILLATION, PIPCE DIVERGENCE (RATHER RAPIO), VERG RESTORTIVE TO ARTIFICIAL TURBULENCE.

P MISCELLANEOUS



CONFIGURATION 15L FLIGHT NUMBER 52-3 PILOT B PLOT-RATING 95 8-F WIND (knots) 3 WIND SHEAR SMALL HODERATE EXTERNAL TURBULENCE LIGHT WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT CONFIGURATION LS1. FLIGHT NUMBER 105-1 PILOT A PILOT-RATING 8 MODERATE CHARACTERISTIC ROOTS +.093 -.04 -.116 -1.73 CHARACTERISTIC RCOTS F.093 -.04 -.116 -1.73 LAIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (TAS)
VMC IMC IMC
OUT OUT IN Vertical velocity (h)
VMC IMC IMC
OUT SUT IN
SLIGHT WIDERATE MODERATE FLIGHT CONDITION TURBULENCE MODERATE MODERATE GREAT MAXIMUM UNDESIRED FLUCTUATIONS PITCH ATTITUDE CONTROL SLOPPY - STATICALLY DIVERGENT THE TURBULENCE CONTROLLY DISTURBS THE PITCH ATTITUDE AND THE VERTICAL VELOCITY DIFFIGURITY DUE TO PITCH SPERCTS ON AIRSPEED AND WIND SHEAR SPEECTS ON RATE OF DESCENT COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE AMPLITUDE PERIOD DAMPING ZERO NEGATIVE PITCH MODERATE LONG (IO-15 SECS) DEGREE EXCITATION CONTRO: EASILY EFFECTIVE THE OSCILLATORY CHARACTERISTICS WERE VERY BOTHERSOME, DISORIENTATING AND DAWDEROUS — 10. IF THE PHASING IS SUCH THAT OSCILLATION ADOS TO AN ELEVATOR INPUT, A VERY MAPID RESPONSE MESULTS. COMMENTS 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION VERY SMALL VERY SLIGHT NECLECTIBLE, NO DIFFICULTY ÖIFF:CÚLTY COMMENTS 5 FLIGHT PATH CONTROL Intercept B Initial Irack | Intermedials Irack | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glid Intercept 8 initial track Intermediate track Final track Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY SLIGHT SLICHT MODERATE SLIGHT MODERATE SLIGHT SLIGHT SLEGAT SLICHT SLIGHT SLIGHT SLIGHT PRECISION EALS. FAIR FAIR/GOOD FAIR/GOOD FAIR/GOOD FAIR MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET ALTITUDE 500 NO IMO PERMITTEN. COMMENTS SO MUCH ATTENTION WAS REQUIRED FOR PITCH ATTITUDE CONTROL THAT HEADING AND AIRSPEED MAINTENANCE WENT FOR A CHOP DISPICULT DUE TO UNSTABLE PITCH OSCILLATION AND TO THE GREAT SUSCEPTIBILITY TO TURBULENCE 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHOOWN POINT (CHOD) DIFFICULTY GREAT VERY POOR SPASON FOR DIFFICULTY NOT KNOWN — THRUST APPLIED WITHOUT SPEECT. SIRST SHORT TOUGHOUN TO DATE, PRECISION AT BREAKOUT NOT BAD — A BUT LOW - BUT UNABLE TO ARREST HIGH RATE OF DESCENT NEEDED IN WIND SHEAR. COMMENTS: 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SMALL

9 LEAST OBJECTIONABLE FEATURES

IO MOST OBJECTIONABLE FEATURES SLOPPY PITCH ATTITUDE CONTROL, TURBULENCE DISTURBANCE IN PITCH.

I MISCELLANEOUS

PITCH CHARACTERISTICS. INABILITY TO ARREST RATE OF DESCENT AT TOUCHDOWN. TURBULENCE UPSETS IN HEAVE AND PITCH

NONE

TERIST LEVER SENSITIVITY WAS OK IN AIR BUT TOO LOW NEAR CHOUND. INCLCIENT DISORIENTATION AS TALAR SENSITIVITY INCREASES AND CONTROL IMPUT FREQUENCY INCREASES IN PARSTNER OF PITCH CHARACTERISTICS. HEAD WIND BECAME TALLMIND ON APPROACH.



CONFIGURATION 166, FUGHT NUMBER 117-1 PLOT A PILOT-RATING 3 CONFIGURATION 16L FLIGHT NUMBER 127-1 PILOT B PILOT-RATING 38 WIND(knots) CALM
WIND SHEAR SMALL
EXTERNAL TURBULENCE NIGHTED BLK WIND (knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE CHARACTERISTIC ROOTS __028 __04 __.69 ± __.711 AIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSIT-VITY SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY RESPONSE SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES | Longitud not | Velocity (LAS) | VMC | IMC | IMC | IMC | OUT | IN | NONE | ST.ICIT | MODERATE | FS.-10 | knots | Vertical velocity (h
V M C I.M C
OUT OUT
NONE NOWE FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS SOMEWHAT TOO MICH ATTENTION REQUIRED TO KEEP THE MOSE IN POSITION TO RETAIN THE AIRSPEED. ATRIFECED, IN MANY CASE FALLS OPP ARROTT IN KNOTS AT AROUT 400-500 FT AGE, + 2KORABLY DUE TO DECREASING WIND. COMMENTS AMPLITUDE ZBRO ZBRO 3 RESIDUAL OSCILLATORY CHARACTER STICS AMPLITUDE PERIOD DAMPING PERIOD DAMP NG HEAVE SOURCE SOURCE CONTROL : COMMENTS 4 CHANGE IN "HRUST REQUIRED FOR 20" BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NEGLIGIBLE
NO DIFFICULTY SMALL NO OFF CULTY COMMENTS 5 FLIGHT PATH CONTROL Intercept & initial frack | Intermediale track | Final Itaak Glide path | Cocalizer | Glide path | Lacalizer | Glide path | Localizer Intercept & iniliai Irack Glide path Localizer Intermediate track Final track
Glide path Localizer Glide path Localizer DIFFICULTY NONE SLICHT NONE SLIGHT SLIGHT S'.IGHT KONE NONE MONE NONE NONE NONE FALR G000 FAIR FAIR FAIR GOOD coon GOOD coon COOD GOOD MINIMUM ACCEPTABLE BREAKOU" ALTITUDE
IF GREATER THAN 200 FEET 0.K. THE ONLY PROBLEM WAS THE WIND SHEAR WEIGH REQUIRED ABOUT 200 OF HEADING CHANGE STARTING AT ABOUT 600 TO 700 PT AGL. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT MID DEFICULTY
PRECISION OF ATTAINING TOJCHDOWN POINT COOD DIFF CULTY NO FAIR/SOOD 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEEC WITH THRUST B LATERAL DIRECTIONAL CHARACTERISTICS NONE EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECT:ONABLE FEATURES COOR AMOUNT OF ATTITUDE STABILITY - MASY TO CONTROL YET ADEQUATELY STABLE. NOT VERY SENSITIVE TO TURBULENCE.

I MISCELLANEOUS

IC MOST COLECTIONABLE FEATURES

NOTICEABLE AFFECT OF POWER, CHANGES ON PITCH TRIM — BUT IS ACCEPTABLE. HAJIN EFFECT IS HAVING TO RETRIM ON ALIUS SLOPE INTESCRET. THEREAFTER MINOR POWER CHANGES OF MET NOFESSACILY REQUIRE RETRIM, ALTHOUGH EFFECT MUST RE ANTICEPTORY



CONFIGURATION 17. FLIGHT NUMBER 117-2 PILOT A PILOT-RATING 6

W ND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.013 -.04 -.50 -.89

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE :

ELE	VATOR	THRUS"	LEVER
V8E = U.25	(rad/sec ²)/in	Z8T = 11.9	(*1/sec ²)/in
Initial	Final	In. fiel	Final
SAT LSFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TORBULENCE:
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

	Longitu	idina) yelaçı	ty (IAS)	Ver	fical velocity	(h)
	VMC	1MC	JMC	VMC	- TMC	: W C
	CUT	100	- N	OUT.	OUT	IN
	SLIGHT	MODERATE	UREAT	NONE	S16H"	MODERATE
5	F12	-8	unots		₹ 300	(pm.

COMMENTS:

DIFFIGURTY DUE TO PITCH ATTITUDE WANDRY WAICH KEPT THE AIRSPEED CHANGING (SEE SECTION 3).

Initial Final Initial Final SATISFACTORY SATISFACTORY SATISFACTORY

CHARACTERISTIC ROOTS __.013 __.04 __.50 ___.89

WIND(knors) 5-10 WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE

CONFIGURATION 17L FLIGHT NUMBER 116-1 PRECT D

PILOT D
PILOT-RATING 7D

Longitud	inal veloci:	ty (IAS)	Verti	cal velocity	(h)
VMC	IMC	IMC	VMC	LWC	1 M C
OUT	OUT	IN	OUT.	Out	·N
SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
±5		knots	+400	-200	fp.m

ACRUSVED ASOU F. 2.M. RATE OF DESCENT UNINTENTIONALLY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPL TUDE	PF	RIDD DAMPING
SMACL	LONG	10%
ZERO		
80	URCE	DEGREE
ELEVATOR		EASILY
ELEVATOR		EFFECTIVE

EXCITATION CONTROL COMMENTS

COMMENTS:

A LOW PREQUENCY WANDER IN PITCH PELT AS IF IT WOLLD DIVERSE IF LEFT ALONE. THIS KEPT THE NOSE ACTIVE AND PRODUCED A VERY HIGH MORKIDAD IN PITCH.

DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION:

NEGLIGIBLE:	
NO	DIFFICULTY

DIFFICULTY

5. FLIGHT PATH CONTROL

SIFFICULTY

Intercept B.	initial track	Intermedia	ale frack	Fnal	track
Glide poth	Cocalizer	Glide path	Laculizer	Glide parh	Localizer
NONE	NONE	MODERATE	SLIGHT	MODERATE	SLIGHT
מספר	COOD	FALK ;	FAIR	FAIR	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE F GREATER THAN 200 FEET 500

COMMENTS:

THE LACK OF GOOD ALRSPEED CONTROL RESULTED IN A CHANGING REQUIREMENT FOR MATE OF DESCRIT, THE WIND SHEAR OF APPROXIMATELY 20° CAUSED A SLIGHT PROBLEM.

FAIR

ntercept & initial track		intermediate track		Fino: track	
Gide path	Localizer	Glide parh	Localizer	Glide path	Localizer
SLIGHT	MODERATE	SLICHT	SLIGHT	MODERATE	MODERATE
FAIR	POOR	FAIR	FAIR	POO R	POOR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

30	DIFFICULTY
COOD	

400

PERFORMANCE NOT GOOD ENOUGH FOR LOWER BREAROUT HEIGHT, OVERSHOT ON LOCALIZER INTERCEPT, DIFFICULTY DUE TO HEIGHT CONTROL, TURBULENCE, ENGINE POWER SURGES.

SLIGHT DIFFICULTY

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT NONE

9 LEAST OBJECTIONABLE FEATURES

10 VOST OBJECTIONABLE FEATURES

(L) HRIGHT CONTROL DIFFICULT IN THE PRESENCE OF SIMULATOR ENGINE POWER LIMITATIONS.

(2) PITCH DIVERGENCE.

1. MISCELLANEOUS



CONFIGURATION L8 FLIGHT NUMBER 15-3 PILOT A PILOT-RATING 85

WIND(knots) 5-10 NEGLIGIBLE WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS

-.034 -.04 -.49± .8751

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELE	VATOR	THRUST LEVER		
MBE20	(rad/sec ²)/in	Z _{8T} = 11.9	(f1/sec ² i/in	
In-t-al	Final	Initial	Final	
SATISFACTORY	NUT ASSESSABLE	SATISFACTORY	SAT 15 FACTORY	
SKIIBENCIONI	NOT ADDECDARDED	SALISTAÇICA	JACE I STRUCTURE	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

	Lorgitu	dinol velo	cily (LAS)	Ver	fical velocity	[6]
	VMC.	LMC	: M C	V M C	J.M.C	: M C
	OUT	QUT	IN.	OUT	DUT	IN
	MODERATE	GREAT	GREAT	SLICHT		MODERATE
S	-10	,+5	knots		Ŧ.500	(mg)

COMMENTS

A CONSTANT MODERATE PREQUENCY PITCH OSCILLATION, WHICH IS PROBABLY PILOT INDUCED, KEEPS THE PITCH ATTITUDE MOVING. THE TUBBLINGCE EXCITES THIS AND THE HEAVING DUE TO TURBULINGS IS LARGER THAN HITH ANY OFFER MODEL TO DATE. THE MESET PART OF THE TUBBLICHOS MODEWER, LIES HITH THE DIRECTHONAL DISTURNANCES CAUSED BURING LOCALIZER TRACKING.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMP, TUDE	PERIOD	DAMPING
MODERATE	MEDIUM	Wal

EXCITATION CONTROL

SCURCE	DEGREE
ELEVATOR AND TURBULENCE	BASILY
ELEVATOR	INSFERTIVE

COMMENTS

SEE #2

CONFIGURATION 18
FLIGHT NUMBER 37-1
PLOT B
PILOT-RATING 7

WIND (knots) WIND SHEAR ? EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS

	·		,
034	04	49 ±	.8751

	VATOR		T LEVER
M8E: .2	(rad/sec2)/in	Zar= 11.9	(ft/sec²)/in
Initial	Final	Initial	Fingl
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

Longit.	idinal veloc	ity ((AS)	Ver	tical velacit	y (n)
v. vi C	LM C.	IMC	V M.C	I.M.C	I.M.C
OUT	CUT	IN.	OUT	QUT	IN
NONE	SLIGHT	SLIGHT	NONE	SLICHT	SLIGHT
	±10	knots	±	:300	I n

NOT SURE OF REASON FOR DIFFICULTY. MAY BE THAT WITH RATE OF DESCENT CONTROL ON CLIDE PATH NEAR BOTTON WAS DUE TO A WIND SHEAR PROBLEM. 500F.P.M. TO HOLD AT TOP BUT, ALTHOUGH CONTINUOUSLY REDUCING PRINTS TAT BOTTOM (800 PT.), CORRECTION WAS NOT LARGE ENOUGH TO MAINTAIN CLIDE SLOPE.

AMP_ITUDE	PERIOD	DAMPING
SOURCE		DEGREE

THERE WAS A TRACE OF A PITCH/HEAVE OSCILLATION - PERHAPS PARTLY PILOT INDUCED WITH THRUST LEVER AND ELEVATOR.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

SFALL NO DIFF CULTY

DIFFICULTY

NOT A FACTOR IN RATING.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Glide poin	Localizer	Glide poth	Localizer	Gide path	Localize:
SLIGHT	SLIGHT	MODERATE	MC DERATE	GREAT	GREAT

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 300

COMMENTS

SEE SECTION #2

Intercept 8 int of track intermediate track Final track Glide path Localizer Glide path Localizer Glide path, Localizer NONE NONE MODERATE SLIGHT aca FAIR/GOOD COOD

THE REASON FOR DIFFICULTY IS NOT CLEAR BUT MAY HAVE BEEN DUE TO WIND SHEAR OR FOWER/PITCH ATTITUDE INTERACTION, WE WENT HIGH TOWARDS THE END.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

	 	DIFFICULTY
LCOOR		

COMMENTS

SLIGHT DIFFICULTY
PAIR/GOOD

CLIDE SLOPE INJICATION WAS FULL DEFLECTION HIGH AT BREAK-OUT - I CAME OUT AT 300 FT. TO ACCOMPLISH TRANSITION. EVEN SO I WAS ABLE TO PREITY WELL CONTROL THE TOUCHDOWN BUINT AND MATE OF DESCRIT.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1.4.5 WITH ELEVATOR AND VEHT-CAL SPEEC WITH THRUST _EVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT MODERATE, SHE #2. THE YAMING MAY LAWE BEEN DUE TO POWER CHANGES HATHER THAN TO THRULENCE.

9 LEAST OBJECTIONABLE FEATURES

TURBULENCE RATING B

TO MOST OBJECTIONABLE FEATURES

(1) LARGE INTERACTION BETWEEN TERUST LEVER AND PITCH

ATTITUE.

(2) RELATIVELY LOOSE IN PITCH - ONE NEEDS TO MONITOR PITCH ATTITUEE, ESPECIALLY IS THROST LEVER CHANGES ARE COING ON SIMULTANEOUSLY.

1- MISCELLANEOUS

THE RATING COULD HAVE BREN 5 IF IT HAD NOT BEEN POR GOING HIGH ON CLIDS SIGNE, THE REASON FOR WHICH I AM NOT CERTAIN.



CONFIGURATION LB FLIGHT NUMBER L25-2 PILOT C PILOT-RATING 5

WIND(knots)

WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLEGIBLE

CONFIGURATION FLIGHT NUMBER PILOT-RATING

W ND (knots)
WIND SHEAR
EXTERNAL TURBULENCE

CHARACTERISTIC ROOTS

-.034 -.04 -.49± .8751

CHARACTER STIC ROOTS

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY: RESPONSE

ÉLE!	ATOR	THRUS	T LEVER
Mag: 0.2	(rad/sec ²)/in	Z ₈₁ = 11.9	(ft/seç²)/₁n
Initial	Final	Initial	Finol
TOO SMALL	TOO GREAT	SATISFACTORY	SATISPACTORY

	VATOR	IHRUS	T LEVER	
MBE :	[rad/sec2]/in	1 Zar = (+t/sec2)/i		
Initial	Final	Initial	Final	
			T	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION: TURBULENCE
DIFFICULTY
MAX MUM UNDESIRED FLUCTUATIONS

	Langitudinal velocity ([AS)			ical velocity	(÷)
VMC.	i imc	I M C	VMC	IMC	1.M C
OUT	Out	IN	Ou†	DUT	IN
SLIGHT	MODERATE	MODERATE	SLIGHT	MODERATE	MODERATE
1	0	knots			(pm

Vertical velocity (h
VMC IMC

COMMENTS

CHANGES OF SPEED DIFFICULT TO ACCOMPLISH WITH PRECISION.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION CONTROL COMMENTS

AMPLITUCE	PERIOD	DAMPING	
ZERO .			
ZERO			
SOURCE		DEGREE	

AMPLITACE	PERIOD	DAMPING
		1
SOURCE		DEGREE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION:

SHALL
MODERATE DIFFICULTY

COMMENTS :

THRUST DEMANDS OBSCURED. BY EFFECT OF SPEED VARIATIONS.

DIFFICULTY

5 F_IGHT PATH CONTROL

DIFFICULTY:

Intercept & initial track		Intermediate track		Final track	
Glide path	Lacalizer	Glide path	Lacal-rer	Glide poth	Loconger '
MODERATE	SLIGHT	MODERATE	SLIGHT	MODERATE	SLLGHT .
POOR	G OOD	POOR	SCOD	FAIR	COOD

Intercept & initial track | Intermediale track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer |

D.FFICULTY

MINIMUM ACCEPTABLE BREAKOUT ALT TUDE IF GREATER THAN 200 FEET

COMMENTS:

TRACKING ON INTERMEDIATE PORTION QUITE GOOD, BUT SPEED WAS HIGH (70 KNOTS). DIFFICULT TO GRT ESTABLISHED ON GLIDE PATH WITH CORRECT SPEED.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT GOOD

D FFICULTY

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VEHTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES NO NOTICEABLE OSCILLATORY TEMPENCIES.

IC. MOST OBJECTIONABLE FEATURES DIPPROUDT TO CHANGE SPRED WITH PRECISION, BUT SPEED CHANGES HAVE CONSIDERABLE EFFECT ON THRUST REQUIREMENTS. MORE OF A PROBLEM INC. THAN TWO.

H MISCELLANEOUS

THRUST LEVER DISPLACEMENTS POSSIBLY A BIT LARGER THAN NECESSARY. ELEVATOR TRIM NATE TOO SLOW.



CONFIGURATION 19 FUIGHT NUMBER 6-2 PILOT A PILOT A PILOT-RATING 7

WIND(xopts)

WIND SHEAR EXTERNAL TURBULENCE ZERO

CHARACTERISTIC ROOTS -.018 -.04 -.50± .0581

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION

MAXIMUM UNDESIRED FLUCTUATIONS

	Long tud	inal veloc	ity (TAS)	Vertical velocity (h)		
	VMC	1MC	IMC	VMC	IMC	IMC
	TLO	OUT	IN	CUT	DUT	IN
	SLIGHT	-	GREAT	SLIGHT	SLIGHT	SLIGHT
١S	±8	ļ.	knots			f pm,

COMMENTS

THE PITCH CONTROL IS VERY POSITIVE AND CAUSED OVERCONTROLLING IN PITCH ATTITUDE, TURBULENCE HAS A MODERATE EFFECT ON BOTH PITCH AND HEAVE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE	PER OD	DAMPING
ZERO	L	
Z230		
SOURCE		DEGREE
	1	

EXCITATION CONTROL

COMMENTS

AMPLITUDE	PER OD	DAMPING
ZERO		
2330		

4 CHANGE N THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DIFFICULTY

COMMENTS

DIFFICULTY

SOURCE 85, 87, TURBULENCE ELEVATOR

SEE SECTION #2.

CONFIGURATION 19
FLISH: NUMBER 14-1
PILOT A
PILOT-RATING 75

Long tud not velocity (1A5)

VMC IMC LMC

OUT OUT IN

MODERATE GREAT GREAT

WIND(knots) 10-15 WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.018 -.04 -.50± .0581

SATISFACTORY SATISFACTORY SATISFACTORY

THE PITCH ATTITUDE HAD A WAY OF MANDERING RATHER UNPREDICT-ASLY — ALTHOUGH THERE WAS A PERIODIC CHARACTERISTIC, IT WAS DEFFICULT TO PREDICT WHEN FACED WITH OTHER PARTS OF THE

AMPLITUDE PERIOD DAMPING
LARGE MEDIUM LOW
ZERO

EASILY

INEFFECTIVE

5. FLIGHT PATH CONTROL

D-FF-CULTY:

PRECISION

		Intermediate track		Final	
Glice path	Loca izer	Glide path Localizer		Gli de poth	Localizer
		MODERATE	MODERATE		
		РОЭК	200R		

MINIMUM ACCEPTABLE BREAKOUT A_TITJDE
IF GREATER THAN 200 FEET

PITCH ATTITUDE DIFFICULT TO SETTLE ON AND HENCE THE AIRSPERH AND REQUIRED RATE OF DESCENT WARY.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO GOOD.

WE WERE LOW ON THE CLIDE PATH AND BREAKOUT AND HENCE HAD LOTS OF TIME TO DRAG IT IN TO THE LANDING TOUGHDOUS POINT.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VEGITAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL

9 LEAST OBJECTIONABLE FEATURES

IO MOST CBUECTIONABLE FEATURES

STE SECTION #2

NONE

I MISCELLANEOUS

THE EURVATUR CONTROL POSCES WERE UTOH AND THOSE OF THE RUBDER $\mathbb{I}_{\mathcal{A}(N)}$

Intercept 8 initial Irack | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | SLIGHT NONE GREAT MODERATE GREAT MODERATE FALE COOD POOR COOD VERY POOR FAIR

500

THE GLIDE PATH GOT AWAY AT ABOUT 500 PT. A.G.L., PROBABLY DUE TO THE HIGH WORKLOAD IN TRYING TO KEEP AIRSPEED.

GREAT VERY POOR DIFF CULTY

BROKE OUT WELL ABOVE GLIDE PATH EVEN THOUGH THE RATE OF DESCENT HAD BEEN AT OR CLOSE TO 1000 F.P.M. FROM 500 FT. A.G.L. TOO MUCK ATTENTION HAS REQUIRED TO DIVE-OFF STRICHT AND THE OSCILLATORY PITCH ATTITUDE MADE FOR A VERY INSECURE FEELING IN PITCH.



	CONFIGURATION 17 WIND (KIDTS) 2 FLIGHT NUMBER 175-1 WIND SHEAR NAVOLUCIELE PLOT 8 EXTERNAL TURBULFACE NEUTROBUR PLOT-RATING 7.	CONFIGURATION (4) FLIGHT NUMBER 30-1 PLOT C PLOT-RATING 4	WIND (knots) L5 WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE
	CHARACTER STIC ROOTS0180350± .05±1	CHARACTERISTIC ROOTS	0180450± .058i
AIRCRAFT RESPONSE TO CONT	ROL NPUTS		
CONTROL SENSITIVITY:	Mag -2 (od/sec ²)/n Z5 -1 1 1 1 2 2 2 2 2 2	In fig1 F	$\frac{7 \text{HQUST LEVER}}{28 \text{T}^2 \text{ Ling}} = \frac{7 \text{HQUST LEVER}}{(11/3 \text{es}^2)/\omega}$ and $\frac{7 \text{HQUST LEVER}}{(11/3 \text{es}^2)/\omega} = \frac{7 \text{HQUST LEVER}}{(11/3 \text{es}^2)/\omega}$
2 EASE OF MAINTAINING DESIRE		SAFISSACTORY SYFISS	ACTORY SATISFACTORY ;
FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM INDESIRED FLUCTUATOR	Longitudinal velocity (TAS)	Long-tudinal velocity VMC LM C OUT OUT SHOTE WINDENTS WO	
COMMENTS	DIFF CULTY D. 4 D. C'SDER MING PERGENCESCOL ATTEM WHICH CITES		1979
	CORT-NUCLES ATTITUDE PROOFS.		
3 RESIDUAL OSCILLATORY CHARA	ACTERISTICS		
S ALSO DATE OSCILLATION CHAIN	AMPLITUCE PERIOD DAMPING	AMPL TUDE	PER OD CAMPING
PifCH HEAVÉ	> SMALLDN (■ 10 <u>\$10\$</u>)		
ENCITATION	SOURCE DEGREE	SOURCE	DEGREC DEGREC
EXCITATION : CONTROL	TAKK#0905		
COMMENTS	SIGNLAS TO CONFIGURACION SOU EXEMPLICAÇÃO ACADES ON PRECINE EXOMERTS OF THE TRANSPORT OF AN EUG. ATTACE, TEX.		
	OSCIPLIATION CONTROL OF SOME OF 1885 IN BLAVE AS NOTE.		
4 CHANGE IN THRUST REQUIRE	D FOR 20% RANKED THREE		
CHANGE REQUIRED	TON 20 BARRES TONKS	AMARI.	
EASE OF COMPENSATION	DIFFICULTY	S Tell" Dis	FICULTY
COMMENTS	THE PURINCESS PROCESS OF HER SET TO A SCHOOL CONTAINING FIRST THE OBSEL ATTORS IS THE MANNER IN WHISE THE COCKLIA- TION RAYGRAIS BROWNINGTO A COURT OF COMMENCE FROM BLOW TOS INVESTIGATION OF THE SECOND OF THE CONTRIBUTE		
	SEVITAL SELONDS AFFER THE CONTRAL SPITE THIS DESARDS CLOSE MONITORING OF ATTENDIT PROPOSITE WAS AND OTHER		
5 FLIGHT PATH CONTROL	20 DESAT LES ACCRUSS VS NAME 1278 CB :		
	Intercept & instal track Intermediate fraux that track	Intercept 8 initio track	ntermed are track Fing track
D FFICULTY	SONE Stehn No. No. 1000 June 1000 Ju	Gide poin Localizer GI	de poth Localizer Glide path Localizer UNIT SLIGHT SLIGHT SLIGHT
PREC:SION	COD AND COD COD		
MIN MUM ACCEPTABLE BREAKOU	T ALTITUDE		
IF GHEATER THAN 200 FFET	(S.N. Alayor and the adaptive costs A. Naviga S. 2000)	1	
COMMENTS	A TETUDIA. TA 28 GASCAPA S. BODA, 18 CLA V. DOCETA		
6 BREAKOUT AND FLARE			
EASE OF ARRESTING RATE OF OR PRECISION OF ATTAINING TOUGHD	Auto Cont. T	<u> </u>	CIFT CULTY
COMMENTS	OWN POIN LARD	(F <u>MLS</u> (ms) 10 (80) (S 18 A1)(SF)	£ED
7 CONTROL TECHNIQUE			
COMMENTS FORFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST			
LEVER 8 LATERAL DIRECTIONAL CHAR	RACTERISTICS.		
EFFECT ON FINAL ASSESSMENT			
3 LEAST OBJECTIONABLE FEA	TURFS		
IC. VOST OBJECTIONAB, E FEAT	DRES (II TROBONTY & DRUNG OSC GANTON CONTRACTOR OTTAGE OF STAGE O	SCYL O PROBURY IN MAIN SEAT: ON IRST OWNERT TA	NEATH NG SPEED CONTROL WITHIN ±10 SKG
I MISCELL AMEDES			



CONFIGURATION 19 FLIGHT NUMBER 122-L PLOT C PILOT-RATING 4 WIND(Anots) 5
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT (LONGISH
PERICO THERMAL ACTIVITY NOTICEABLE)

CHARACTERISTIC ROOTS -.016 -.04 -.50± .0581

CONFIGURATION 19 FLIGHT NUMBER 21-3 PLOT D PLOT D PLOT-RATING 7

WIND (knots) CALM NEGLIGIBLE WIND SHEAR NEGLICE EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS -.018 -.04 -.50 ± .0581

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

RESPONSE:

ELEV	ATOR	THRUS	T LEVER
V.8F = 0.2 (rad/sec2)/in		ZgT: 11.9	(ft/sec ²)/n
Initial	Final	Initial	Final
TOO SMALL	TOU GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION

FLIGHT CONDITION
TURBULENCE:
DIFFCULTY
MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS:

Longitu	anal veloc	ity [1AS]	Ver	tical velocity	(fi)
V.M.C.	1.M.C	TM C	VMC	I.M.C	TMC
OUT	OJT	IN]	207	OU!	IN
SLIGHT	SLIGHT	SLIGHT	SULCHT	SLIGHT	SUICRE
±5 knots					l p.m.

OUITE GOOD PERFORMANCE ONTAINED, BUT REQUIRES CLOSE ATTENTION TO PAINTAIN REQUIRED SPEED.

M8E = ,2 tro VIOR THRUST EVER (rad/set2)/in Z_{BT} = 11.9 (II/ (11/sec²)/in TOO SMALL TOO GREAT TOO GREAT TOO SMALL

Longitudinal velocity ([AS]			Vertico- velacity (h)		
VMC	IMC	IMC	VMC	1 M C	[MC
OUT	001	1N	OUT	CU⊤	IN
SLIGST	MUDERATE	MODERATE	SLIGHT	SLIGHT	>MODERATE
ŧ	10	k r.ots	± (300	fpr

USCILLATORY IN PITCH AND TENDENCY TO OVERCONTROL. THE INITIAL RESPONSE SEEMS TO BE SLOW SO THAT PILOT OVERDRIVES INITIALLY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

ZERO SOURCE

EXCITATION COMMENTS AMPLITUDE
> MCDERATE
ZERO/SMALL DAMPING LOW MODERATE HIGH

EASILY MODERATELY TURBULENCE ELEVATOR ELEVATOR

CLOSED LOOP FIG - HEIGHT CONTROL SEEMS OK, PITCH RESPONSE RATHER SLOW BUT NOT EXTREMELY SO.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

NEGLIGIBLE SLIGHT DIFFICUL[†] Ÿ

COMMENTS

SPEED WARRATIONS REQUIRE THROTTLE COMPUNSATION TO MAINTAIN

SYALL.
NO DIFFICULTY

5 FLIGHT PATH CONTROL

D-FFIGURTY PRECISION

		intermedi			rack
Slide path	Localizer	Stide path	L'ogalizer	€ ide path	Localizer
SUIGHT	SUICHE	NONE	NONE	SLIGHT	SLIGHT
300D	(400.5	G0011	ссар	FA1R/(G00	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

COMMENTS

CLOSE ATTENVIOR REQUIRED TO PROVENT SPEED VARIATIONS.

8. init al track | Intermediate track Gira pota _ccalizer _aca'+≥er NO NE SLIGHT SLIGHT GREAT GREAT NONE

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SULGIF. CORD DIFFICULTY

COMMENTS

DIFFICULTY OUT TO NEED TO YAINTAIN SEEKS WITE MANGETTS NAT. CONTROL WHILE ARRESTENC RATE OF DESCENT WITH THROTTLE.

VERY POOR OFFICULTY

GYERCONTROL AS SENSITIVITY OF TALAR ENGREASED.

7 CONTROL TECHNIQUE

LEVER

COMMENTS FIDEFFERST FROM ON INTERMEDIATE TRACK SOME ATTEMPT WAS MADE TO POSITION THE ALBURANT SOME ATTEMPT WAS MADE TO POSITION OF A STATE OF STATE

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINA ASSESSMENT NONE

NONE

9 LEAST CAUECT ONABLE FEATURES

YOVER MEQUIREMENTS SMALL

IO MOST OBJECTIONABLE FEATURES

SATHER TOO CLOSE ATTENTION RECULARD TO AVOID SPEND VARIATIONS AND TRUES CONSCIONANT AS TOO ON MERTICAL SPEND

VERY POOR PRECISION FROM 200 FT. A.H. TO TOUGHDOWN STRONG TENDENCY TO OVERLONTROUGHT. TOTAL

IL M SCELLANEOUS

CUST FORSTBOAT THAT EXTERNAL TURBULENCE AFFROTED RATING ADVERSELY BY A SMAL AMOUNT

MUST OF THE TASK WAS RATED ENSATISFACTORY - ACCEPTABLE BUT, OF FINAL APPROACH WAL, I WOULD MESSITATE TO TRY AND LAND BECAUSE OF MOOR ATTITUDE CONTROL



CONFIGURATION 20 FLIGHT NUMBER 3-3 PILOT A PILOT-RATING 9

WINDERNOTS: CALM
WIND SHEAR
EXTERNAL TURBULENCE ZERO

CHARACTERISTIC ROCTS | +.041 | -.04 | -.101 | -.953

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

Initial GDOD TOO GREAT

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED PLUCTUATIONS

Longitudinal velocity (CAS)

VMC SMC IMC IMC

OU OUT N

MODERATE MODERATE GREAT

-10 to +6 km MODERATE MODERATE GREAT

COMMENTS

DIFFICULTY DUE TO VERY SLOPPY PITCH ATTITUDE CONTROL. TURBULENCE HAD LARGE EFFECT ON PITCH AND A MUDERATE EFFECT ON HEAVE

{f1/sec²}/in F nal SATISFACTORY TOO GREAT SATISFACTORY

WIND (knots)

CHARACTERISTIC ROOTS +.041 -.04 -.101 -.959

WIND SHEAR HODERATE
EXTERNAL TURBULENCE NECLIGIBLE HIGH
LIGHT LOW

CONFIGURATION 20 FLIGHT NUMBER 83-2 PILOT A PILOT-RATING 8

VMC MODERATE GREAT SLIGHT SLIGHT SLIGHT GREAT

A SLIGHT OUT OF TRIM ON ELEVATOR RESULTED IN ENGRHOUS PITCH ATTITUDE CLANGES. THE MOSE WAS IN CONSTANT MOTION AND VERY INTERISE CONCENTRATION WAS REQUIRED TO MAINTAIN AIRSPEED ON APPROACE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPL-TUDE DAMPING PER OD LARGE MEDIUM DEGREE ____EASILY 1 INKAPÉCTI VE

EXCITATION CONTROL COMMENTS

AMPLITUDE ___ PERICO DAMPING SOURCE DEGREE _____ ______

SIMPLE DIVERGENCE, A VERY SHORT PERIOD OF INATTENTION COULD RESULT IN ALARMINGLY LARGE PITCH ATTITUDE CHANGES.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMALL DIFFICULTY SMALL DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

COMMENTS:

		Intermediate track		Final Irack	
Glide path	Localizer	Glide poth	Localizer	Gide path	Localizer .
		GREAT	MODERATE		
		VERY POOR	POOR		

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

COMMENTS

Intercept & mittal track - nermediate track - Final track
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | MODERATE SLIGHT SLIGHT SLIGHT SLIGHT MODERATE 2003 FALR ∂A1R FAIR FAIR POOR.

700-800

SORTING OUT THE WIND AS A FUNCTION OF HEIGHT WAS A PROBLEM. APPROXIMATELY 20° OF HEADING CHANGE WAS REQUIRED FROM START

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT
VERY PLOR

COMMENTS

IT WAS IMPOSSIBLE TO SELECT THE DESIRED PITCH ATTITUDE FOR THE SLAWE SINCE THE OSCILLATORY GRARACTERISTICS WERE WERY BOTHERSOME.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

6 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT MODERATE, BECAUSE OF THE LIGHT BREAKOUT MORCE ON CUIDER

9 LEAST OBJECTIONABLE FEATURES

ID MOST OBJECTIONABLE FEATURES

I. MISCELLANEOUS

CLEVATOR AND RUDDER PARCES IGHT.

NO G000 DIFFICULTY

WHEN THE RATE OF DESCENT INCREASED, THE MOSE SEEMED TO COME UP, INDICATING AN UNSTABLE FITCHING MOMENT WITH ANGLE OF ATTACK. THIS IN ITSELF WAS NOT OVERLY BUTHERSOME BUT PRESCRIED A MINOR TRIM ANNOYANCE.



CONFIGURATION 20 FLIGHT NUMBER 124-2 PILOT B PILOT-RATING 8D

W ND(knols) 5
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS F.041 -.04 -.101 -.959

CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING

M8E: Initial

AMPLITUDE

WIND (knots) WIND SHEAR EXTERNAL TURBULENCE

Initial

THRUST LEVER (ft/sec²//in

DAMPING

ELEVATOR (rad/sec²)/in Z_{8T} =

CHARACTERISTIC ROOTS

ı	AIRCRAFT	RESPONSE	TO	CONTROL	INPUTS

CONTROL	SENSITIVITY
RESPONSE	

ELE	VATOR		T LEVER
VISE : 0.2	(rad/sec ²)/m	Z87= 11.9	(41/sec ² Min
Initial	Final	Initial	Final
TIO GREAT	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION	
TURBLLENCE	
D: FFICULTY	
ALEXANDER HARCESTEE	FUNCTUATIONS

Lorgitu	d nat veloc	ity ([AS]	Ver	lico' velocity	(6)
V.M.C.	INC	IMC	VMC	IMC	1 M C
OUT	OLT	IN	OUT	OUT	N
MODERATE	MODERATE	MODERATE	SLIGHT	MUDERATE	MODERATE
\$ 	8	krots		OΚ	í pm

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH	
HEAVE	

EXCITATION CONTROL

AMPLITUDE	PEI	100	DAMPING
MODERATE	LONG		NEGATIVE OR ZERO
?	,		
Source	CE	J	DEGREE
NKNOWN		EASILY	
SLEVATOR		REFECTI	JE.

SOUPCE DEGREE

DIFF CULTY

Intercept 8 initial track | Intermediate track | Final track | Glide path | Lacalizer | Glide path | Lacalizer | Glide path | Lacalizer | Glide path | Lacalizer |

DIFF CULTY

PERIOD

COMMENTS THERE IS A PIECH ATTITUDE INSTABILITY AS WELL.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DIFFICULTY

COMMENTS

THE MORE SIGNIFICANT FACTOR IS THAT PITCH INPUTS ARE REQUIRED IN THE TURN. THESE CAN LEAD TO A PID TYPE OF THEM RECAUSE OF THE SUPERPOSITION OF THE OSCILLATORY CHARACTERISTICS AND THE RESPONSE TO CONTROL INPUTS.

SIMILOR EFFECTS RESULT FROM THRUST INPUTS.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermediate track		Final track	
Glide path	Localizer	Ghde path	Local-zer	G de poth	Localize -
SLIGHT	SLIGHT	NONE	MONE	S'.IGHT	SLIGHT
COCD	GOUD	GOOD	G00 D	PAIR	GOOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
F GREATER THAN 200 FEET OR MECAUSE GOOD TRACKING WAS ACHIEVED

COMMENTS

GITDE PATH AND LOCALIZER CONTROL OK. SPEED CONTROL GAVE MODERATY DIFFICULTY INITIALLY.

6 BREAKOUT AND FLARE

PRECISION OF ATTAIN NO TOUCHDOWN POINT COOD

COMMENTS .

NEEDED TO PAY MORE THAN USUAL ATTENTION TO PITCH ATTITUDE IN ORDER TO MAINTAIN SPEED AFTER BREAKOUT

7. CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IQ MOST OBJECTIONABLE FEATURES AND CAN ADDITED A PRIORITINE FROM OSCILLATION - APPROXIMATELY 10 SEC. PIGGO, PITCLOW AND CAN ADD TO OR SUPERACT FROM OSCILLATION.

I. MISCELLANEOUS

TARGE PITCH CHANCES CAN RESULT INC UNLESS ATTITUDE CLOSELY MONITORED. RESPONSE TO ELEVATOR INFUTS TOO LARGE SECAUSE OF APPARENT PITCH ATTITUDE DIVERGENCE



CONFIGURATION R1f. FLIGHT NUMBER 89-3 FILCT A PILOT-RATING 3

AMP IT IDE

WIND(knots) ta WIND SHEAR SMALL.
EXTERNAL TURBLIENCE NEGLIGIBLE

CH4RACTERIST.C ROOTS -.04 -.18 -1.05± 1.061

DAMPING

CONF-GURATION RIL FLIGHT NUMBER 76-L PILOT B PILOT-RATING 5C

WIND (knals)

5 NEGLIGIBLE WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE VERY LIGHT

CHARACTERISTIC ROOTS -.04 -.38 -1.05± 1.061

OL INPUTS
Ç

CONTROL SENSITIVITY:	CONTROL	SENSITIVITY:
----------------------	---------	--------------

	VATOR	THRUS	
Mag 0.34	(rad/sec ²)/in	Z8T= 15.0	(fr/sec ² :/n
1 ~ 1 1 1 0 1	Fina	Init of	Finol
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION:	
TURBULENCE	
DIFFICULTY	
MAXIMUM UNDESIRED	FE ICTUATION

-	Long-tuginal velocity [[AS]			Ver	lical velocity	(h)
	VMC	IMC.	I M C	VVC	IMC	IMC
	TUQ	OUT	II.	TLO	OUT	2
- 6	NONE	5 L 1 GHT	SLIGHT	NONE	SLIGHT	SLICHT
45 [+5	, -B	krots	0 K		l.pm

Longitu	dinal velaci	ty ([AS]	Verl	icol velocity	(6)
V.M.C	LMC	: M C	VMC	I M C	IMC
DUT	OJT	LN	CUT	001	IN
SLIGHT	SLICHT	S.IGHT	SLIGHT	SLIGHT	SLIGHT
SLIGHT	SLICHT	S:. (GHT knols	SLIGHT	SLIGHT	SLIG

In tig1 Fing1 Initial Circle
SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY

ON FLARE, DID S'AW DOWN TO 50 KNOTS.

RESPONSE -

GOOD MODEL. - AIRSPEED GOT A LITTLE FOR DURING LATTER PART OF APPROACH, BUT 1 FRUT THAT THIS WAS A GROSS-CHECK PROBLEM, NOT A HANDLING QUALITIES PROBLEM.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH HEAVE	
EXCITATION -	

2.5	80	 	
	SOURCE	 DEGREE	

AMPL TUDE	COIRISS	DAMPING
ZERO .		
∂ERO		-l
SOURCE		DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

NEGLIGIBLE NO DIFFICULTY

COMMENTS

COMMENTS

VERY SMALL	
. N O	DIFFICULTY

5 FLIGHT PATH CONTROL

			Intermed		Final	
	Gude path	Localifer	Glide pota	Localizer	Gide path	Localiza
DIFFICULTY	NONE	NONE	NON:	NO VE	RONE	SONE
PRECISION	GUOD	coop	6000	u2008	1900	(a)OD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF SREATER THAN 200 FEET

COMMENTS

intercept & nitial track		intermediate track		Final track	
Glide sath	Localizer	Glide path	Localizer	Glide poth	Localizer
NONE	NONE	NUNE	NONE	V. SLIGHT	V. SLIGHT
∪0Ω β	coop	0000	3000	6000	GOOD

0 K

HAD TO WORK HARDER BUT PERFORMANCE WAS GOOD. LCTS OF CONTROL ACTIVITY.

SLIGHT MODERATE DEFICULTY
FAIR-GOOD

SPEED AN DURING TRANSITION (50 GNOTS) - HAD TO PITCH SISE DOWN AND REDUCE SATE OF DESCENT AT SAME TIME. I DID NOT HAVE PRECISE CONTROL OF MATE OF DESCENT AT TOUGHDUNG, SUSPECTED A SLIGHT TENDENCY TOWARDS A PITCH/HEAVE PIO AT CHICHEDEN.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT (2000) COMMENTS.

DIFFICULTY	

7 CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM I A S WITH ELEVATOR AND VERTICA. SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

NORE

9 LEAST OBJECT: ONABLE FEATURES

NG RESPONSE TO TURBULING... ALASPHED CONTSOL COOD SVEN TROUGH THE PITCH RESOURSE WAS NOT OF ATTITUDE COMMAND TYPE.

REASONABLE ATTITUDE AND SPEED STABILITY. LOW RESPONSE TO TURBULENCE.

O MOST OBUECT-ONABLE FEATURES

SOME PITCH UPSETS, PROBABLY DUE TO UNCONSCIOUS CONTROL

H MISCELLANEOUS

VIBRATION ENVIRONMENT WITH SUN BEHIND CAUSED A HIGHER DIVEL OF PHYSIOLOGICAL CONCERN AND ACTIVITY. - ODED LAND DO A DESCRIPTION TENDENCY IN SOME CIRCUMSTRUCES FOR, IN MY CASE, LIST NAME HE HANT DO LET TASK OVER WITH DESPITE OFFS, TRACKING PERFORMANCE WAS QUITE COURT.



CONFIGURATION R1-2L F_IGHT NUMBER 91-1 PILOT B CONFIGURATION R1-2L FLIGHT NUMBER 71-3 PLOT A PILOT-RATING 3 WIND(knots) WIND (knots) 10-15 WIND SHEAR EXTERNAL TURBULENCE WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT PLOT-RATING 4R CHARACTERISTIC ROOTS -.08 -.34 -1.06 ± 1.051 CHARACTERISTIC ROOTS -.05 -.34 -1.06± 1.051 I AIRCRAFT RESPONSE TO CONTROL INPUTS E E VATOR 1 HRUST LEVER 4 (rad/sec²)/in 28--15.0 [f1/ THRUST OF VER

(ft/sec²// n (11/sec²)/in Mag: 0.34 CONTROL SENSITIVITY: TOO GREAT SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (F VMC FMC OUT OU Vertical velocity (fr) FLIGHT CONDITION TURBJEENCE: DIFFICULTY MAXIMUM UNDES RED FLUCTUATIONS SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT COMMENTS DIFFICULTY DUE TO: (1) CROSS-CHECK, (2) THERE APPEARED TO BE A LONG PERIOD SPEED OSCILLATION, BUT IT WAS PROBABLY PILOT INDUCED, (3) HEIGHT CONTROL, PROBABLY DUE TO WIND THE PITCH ACTITUDE HOLDING COULD MAVE BEEN MORE FORM TO ALLEVIATE THIS ASPECT OF THE WORKLOAD. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE AMPLITUDE PERIO0 CAMPING PER CO DAMPING ZERO ZERG ZERO DEGREE SOURCE EXC TATION -COMMENTS THESE APPEARED TO BE A LONG PERIOD SPEED OSCILLATION -PROBABLY PILOT INDUCED. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS MODERATE NO CHANGE REQUIRED. EASE OF COMPENSATION VERY SMALL SLIGHT DEFICULTY O FFICULTY COMMENTS 5 FLIGHT PATH CONTROL ntercept & initio track intermediate frack Glide path localizer Glide path Localizer ntercept & r 'al track intermedate track Fina track inde path Localizer Clide path accuser. Since path occilier Fino track Glide path Localizer NONE NONE SCIENT SCIENT SLIGHT SUIGHT NONE NONE SELECT NONE SLIGHT SLIGHT -A13/0000 FATR/0000 MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET THIS WAS THE BEST APPROACH OF THE THRSE FOREIS (8-22L, 7-2L) FLOWN ON THIS FLOOT, THE TURBLENCE BID NOT LISET THE FITCH ATTITLE AND HENCE AIRSPER WAS OUTE COUD. DIFFICULTY DUE TO REING THE FIRST MODEL FLOWN IN A STRONG WIND GRADIENT, 6 BREAKOUT AND FLARE EASE OF ARRESTING PATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT GOOD _DIFFICL_TY 6000 COMMENTS HAD TO SET RATE OF DESCENT AND HILD IT TO TOTCHDOWN - -FELT F COULD GET A SLIGHT HEAVE PIO IF I ESED COLLECTIVE TO ARREST PRECISELY. 7 CONTROL TECHNIQUE COMMENTS IF OFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SMA.J.

9 LEAST OBJECTIONABLE FEATURES

O VOST OBJECTIONABLE FEATURES

I MISCELLANEOUS

NONA, GARANTER'S' TERRITOR BELOW 700 FT.

UNCO POTO: STABILITY, BUT INITIAL RESPONSE TOD WAST (e. TIME CONSTANT IN PITCH A MITTLE TOO SHORT - COULD MEA OF TO LIKE IT THOUGH,

RATE OF DESCRIPT TRACKING NEEDS SOME PRACTICE - APPARENT TO A HEIGHT RATE DAMPING?

NO STONIFICANT TURBULENCE EFFECTS.



CONFIGURATION R1-3L FLIGHT NUMBER 52-L PILOT A PILOT A
PILOT-RAT NG 55

WIND(knats) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS -.21 ± .11 -1.06 ± 1.031

CONFIGURATION R1-3L FLIGHT NUMBER 51-1 PILOT D PILOT-RATING 8

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.21± .11 -1.06± 1.031

· AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELEV	ATOR	THRUST LEVER		
M8E = 0.34 (rad/sec2)/ic		Z81 - 15.0	(ft/sec2)/n	
'rilia-	E no.	Initio	Final	
SAT1SFACTORY	SAT IS FACTORY	SATISFACTORY	SATISFACTORY	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION-TORBULENCE DIFFICULTY MAXIMUM UNDES'RED FLUCTUATIONS

	Lang tudinal velocity (IAS)			Vertical velocity (h)		
	V.M.C	1 M C	IMC	VMC	INC	INC
	OUT	ÇUT	IN	CUT	QUT	IN:
i	SLICHT	SLIGHT	MODERATE	SLIGHT	SLIGHT	MODERATE
1		± B	knots	± 300		f.p.m.

COMMENTS

AS THE AIRSPEED DECREASES, A RATE OF DESCENT BUILDS BUT THERE IS NOT THE IMMEDIATE 'NOTION FALLING OUT' FEELING OF SOME MODELS.

ELEV	ATOR	THAUS" LEVER		
M8E = 0.25	(rad/sec2 l/in	Z8T = 15.0	(It/sec2)/in	
Initial	EID3	Initial	Final	
SATISFACTORY	TOO GREAT	TOO SMALL	TOO GREAT	

Γ.	Longitudinal velocity (IAS)			Vertical velocity (h)		
	VMC	1 M C	_ ï w c	VMC	MIC	TMC
Г	01;	OUT	!N	CUT	CUT	IN
	SLIGHT	SLICHT	MODERATE		MODERATE	GREAT
		± 10	knots	± 300-5	90	form

DIFFICULTY DUE TO BEING ON BACKSIDE OF POWER REQUIRED CURVE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION CONTROL COMMENTS

COMMENTS

AMPLITUDE	PER OD	DAMPINS]
ZERO		
4E80		
SOJRCÉ		DEGREE
L		

ZERO ZERO HIGH DÉGREE

PITCH DYNAMICS WERE GOOD.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

SMAUL SLIGHT DIFFICULTY OK AS LONG AS ALRSPEED IS RELD. DIFF CULTY

ATRSPEED CONTROL WAS REASONABLY GOOD IN TURNS BECAUSE

5 FUIGHT PATH CONTROL

D:FFICULTY

Intercept 8	initial track			Final Irack	
Glide path	Loco izer	Glide poin	Localizer	Glide path	Localizer
NONE	NONE	SUIGHT	NONE	MODERATE	SLICHT
0000	COOD	FAIR	асов	POOR	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET [300-400]

COMMENTS

DUSING THE FINAL STAGES (APPRIX, 500 PT.) OF THE APPROACH, THE ARBERT INCREASED TO AROUND 68 NACTS AND THE BATE OF DESCENT DEGRASED LEAVING US HIGH ON THE CLUDE PATE.

Intercept &				Final		
Gl de poth	Localizer	Glide poth	Localizer	Glide path	Locai zer	
- SCICHT	>SLIGHT	MODERATE	MODERATE	GREAT	GREAT	
FAIR	FAIR	P003	POOR	VERY POOR	VERY POOR	

AS PILDT'S GAIN INCREASES NEAR FLNAL PORTION OF APPROACH, HE OVERCONTROLS AND HENCE I.A.S. AND VERTICAL VELOCITY EXCURSIONS INCREASE. THIS LEADS TO LARGE AND FREQUENT PORES INPUTS.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO HOUR POINT HOUR HOUR POINT

COMMENTS

DIFFICULTY

AIRSPEED, HOWEVER, WAS LOW.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM ! 4 \$ WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

COUPLED AIRSPEED AND POWER BUT NOT TOO SUCCESSFULLY.

COOD SITTER DYNAMICS.

IO MOST CBUECTIONABLE FEATURES

TOO MUCH COUPLING BRITATEN AIRSPRID AND VORTICAL SPEED.

PRICISM CONTROL OF AIRSPEED AND VERTICAL SPEED NOT POSSIBLION FINAL APPROACH - LARGE THRUST INPUTS REQUIRED.

MISCEL . ANEOUS



CONFIGURATION A1-3L FLIGHT NUMBER 101-3 PILOT B PILOT-RATING 45C CONF-GURATION FLIGHT NUMBER PILOT PILOT RATING WIND (knots) WIND SHEAR EXTERNAL TURBULENCE WINDExnots LO
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT CHARACTER STIC ROOTS CHARACTERISTIC ROOTS -.21 ± .14 -1.06 ± 1.031 I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR (11/sec²)/in Final CONTROL SENSITIV-TY: N_{SE} 2 EASE OF MAINTAINING DESIRED VELOCITIES IMC IMC VN C FLIGHT CONDITION 1N MAXIMUM UNDESIRED FLUCTUATIONS DIFFICULTY DUE TO MEIGHT RESPONSE TO CONTROL INPUTS BEING A LITTLE SLOW, ALSO SOME NORMAL FORCE DUE TO AIRSPEED CHANGES. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD DAMP NO AMPL TUDE PERIOD DAMPING ZERO ZERO HEAVE DEGREE EXCITATION COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY DIFFICULTY SLIGHT COMMENTS 5 FLIGHT PATH CONTROL Intercept & nitro track Intermediate track Glide path Localizer Glide path Localizer Intercept 8 instal track | Intermediate track | Final track | Glide path | Lacaizer | Glide path | Lacaizer | Glide path | Lacaizer | Glide path | Lacaizer | DIFFICULTY SLIGHT SLICHT SLIGHT SLIGHT SLIGHT SLIGHT PRECISION FAIR FALR FAIR FAIR FAIR FAIR A_TITUDE OK MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET COMMENTS BROKE DUT AT 150 FT. REASON FOR DIFFICULTY UNKNOWN. SPEED CONTROL NOT AS GOOD AS MIGHT HAVE REEN EXPECTED WITH THIS LARGE AVOINT OF ATTITUDE STABILITY. PERHAPS SPEED CHANGES WERE DUE TO THRUST INPUTS. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLEGET DIFFCULTY
PRECISION OF ATTAINING TOUCHDOWN POINT FATR/GOOD COMMENTS. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT GOOD PITCH STABLLTY BUT TOO GOOD (TIME CONSTANT TOO SHORT AND GEARING OF STICK TO PITCH ATTITUDE FOO HIGE), 9 LEAST OBJECTIONABLE FEATURES NOTICEABLE PITCHING MOMENT DUE TO THRUST CHANGES (I THINK THAT AFTER SEEING MODEL ADI-1 THAT THE SPEED AND REIGHT CONTROL PROBLEMS ON DESCENT WERE LARGELY DUE TO IO MOST OBJECT-ONABLE FEATURES II MISCELLANEOUS ELGVATOR CONTROL FORCES HIGH FOR THIS LEVEL OF PITCH STABILITY - DIFFIGURE TO CHANGE PITCH ATTITUDE AND HENCE SPEED



CONFIGURATION 34
FLIGHT NUMBER 61-2
PILOT A WIND(knots) 5
WIND SMEAR NECLICIBLE
EXTERNAL *URBULENCE LIGHT CONFIGURATION 84
FLIGHT NUMBER 48-1
PILOT C
PILOT-RATING 3 WIND (knots) 15
WIND SHEAR
EXTERNAL TURBULENCE MODERATE PILOT-RATING 3 CHARACTERISTIC ROOTS -.04 -.62 -1.06± 1.061 I.A.RCRAFT RESPONSE TO CONTROL INPUTS | SLEVATOR | THRUST LEVER | | Mag = 0.34 | (-ad/sec²)/n | Z81 - 11.9 | (tt/sec²)/n | | Initial | Final | Final | | CONTROL SENSITIVITY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2.EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (IAS)
VMC LMC IMC.
OUT IN Longitudinal velocity (IAS)
VMC IMC IMC
CUT OUT N Vertical velocity (h) Vertical velocity

VM C | IMC FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM ENDESIRED FLUCTUATIONS CUT OUT N
SLIGHT SLIGHT SLIGHT
KDC'S SLIGHT SLIGHT DEVELOPED SINK RATE ON TURNING ON TO LOCALIZER - RATHER SLOW TO CORRECT WHILE MAINTAINING AIRSPEED COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMP_ TUDE AMPLITUDE PERIOD DAMPING PERICO DEGREE. SOURCE CEGREE EXCITATION CONTROL NO NOTICEABLE LONGITUDINAL OSCILLATORY BEHAVIOUR COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGIBLE D FFICULTY CHANGE REQUIRED EASE OF COMPENSATION MODERATE SLIGHT DIFFICULTY COMMENTS DIFFICULTY TO DETECT EARLY ANY SINK TENDENCY 5 FLIGHT PATH CONTROL Entercept B in fall track intermediate track Finn frack G de path Localizer G ide path Localizer Stide path Localizer ntercept & initial track | Intermediate track Glide path | .oca izer | Glide path | Local zer Glide path Localize DIFF.SULTY: SLIGHT SLIGHT SLIGHT SLIGHT MODERATE SLIGHT PREC SION FAIR FAIR 6000 G000 FAIR GOOD MINIMUM ACCEPTABLE BREAKOUT ALTITUDE. I THINK THAT I BECAME OVER CONFIDENT SINCE THE MODEL HAD BEEN SO PLEASANT AND, AT AKOUND 500 ft., I LOST THE GLIDE PATU AND JETH TOO HIGH FOR A COMPORTABLE APPROACH TO THE TOUGH DOWN PLINT COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT RODERATE PRECISION OF ATTAINING TOUCHDOWN POINT POUR DIFFICULTY OFF.CULTY NONE COMMENTS: SEE SECTION # 5 7 CONTROL TECHNIQUE MORE IMPRESENCE STARMMOD DAM ROTAVELE MINE & A.C. NEURAL HINE CEERS LADITREY LEVER. 8 LAFERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE SMALL: DIFFICULT TO ASSESS, BUT TENDENCY TO UNDERBANK JEEN MAKING LARGE HEADING CHANGES. 9 LEAST OBJECTIONABLE FEATURES IO MOST OBJECTIONABLE FEATURES PROBABLY CONSIDERABLE GACK OF HARMONY BETWEEN DONGSTUDINAL AND LATERAL DIRECTIONAL CONTROLS II MISCELLANFOUS THIS IS THE FIRST MODEL THAT I MAVE FROM AS THOUGH I REALLY COULD REARN TO FRY AND LIKE. ELEVATOR PORCES WERE TOO HIGH AND DISPLACEMENTS TOO SMALL, COMPARATIVELY PLEASANT HODEL BUT STILL REQUIRES CONSIDERABLE CONCENTRATION TO FRY TASK WITH PRECISION.



CONFIGURATION R4L FLIGHT NUMBER 38-L PILCT B

W ND(knets) 10-15 WIND SHEAR EXTERNAL TURBULENCE

CONFIGURATION R4L FLIGHT NUMBER 40-1 PILOT D FILCT-RATING 35

WIND (knors) 15-20 WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE

PILOT-RATING 30

CHARACTERISTIC ROOTS -.04 -.52 1.36± 1.061

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

ſ	ÉLEV	4108	THRUS	LEVER
1	MEE 0.39	(rad/sec ² 1/in	Zer = 11.9	(tt/sec ² //
	Indial	Final	In-tip-	Fina
Γ	SLIGHTLY GREAT	SATISFACTORY	SATISFACTORY	SATISFACTORY

MgE = 0.34 trcd/sec2 //m Zg = 11.9 (H/sec2 // m total First

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBILENCE

RESPONSE -

COMMENTS:

MAXIMUM UNDESIRED FLUCTUATIONS

	Longitu	dinal velo	city (1AS)	Ver	tical velocity	(h)
	VMC.	:MC	IMC	VMC	I.M.C	1 M C
	Out	OUT	IN	OUT	CUT	N _
	NONE	NONE	NONE	NONE	NO NE	SUIGHT
;		±5	*nats		£200	_ 1 pm.

Longifudinal velocity (TAS) Vertical velocity (h)

VMC TMC TMC TMC TMC TMC

OUT OUT N OUT OUT N

SLIGHT MODERATE MODERATE SLIGHT SHIGHT OUT OUT
SLIGHT > SLIGHT MODERATE
±100 fpm MODERATE MODERATE SLIGHT +8, -10

NOTICEABLE RESPONSE IN REAVE TO TURBULENCE - DID NOT ACTEMPT TO CONTROL MATE OF DESCENT FOR TURBULENCE UPSETS. THE \$200 fpm FIGURE IS NOT MEANINGPOL.

ATTITUDE CONTROL FOOR DUE TO LACK OF PILOT PROFECIENCY OVER-CONTROL IN POWER

3 RESIDUAL OSCILLATORY CHARACTERISTICS

DAMPING AMPL TUDE PERIOD ZERO SOURCE DEGREE

AMPCITUDE PERIOD
SMALL MEDIUM
ZERO PERIOD MODERATE DEGREE SOURCE

EXCITATION

COMMENTS

NO PTO TEMBENCY

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

NEGGIGIBLE NONE DIFFICULTY

MODERATE MODERATE

DISPICULTY DUE TO OVERCONTROL

DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

riercept B. initia track Intermedi lige path Localizer Glide poth te trock Find frack Localizer Glide path Localizer NONE NONE NONE NONE SLIGHT SI. LUHT GOOD GOOD ссор

MINIMUM ACCEPTABLE BREAKOUT ALTIUDE F GREATER THAN 200 FEET OK

FIRST NODEL OF DAY - POSSIBLE JIND SHEAR BUT THIS WAS NOT A FACTOR IN THE RATING

GOOD

NONE

Glide poth _ocalizer

COOD

DISPIGULTY PROBABLY DUE TO PILIT'S LOW PROFICTIONS COUPLED WITH HIGH WIND AND WIND SHEAR

SLIGHT

FAIR

NO DIFF-CULTY

Intermediale track Final track
Glide path Localizer Glide path Localizer

GREAT

POOR

GREAT

200R

SLIGHT

FAIR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT FALCOOD

D FFICULTY

SEEMED TO PIC A B T IN THE FLARE WITH DESPECT TO TURBEL LEVER AND HEIGHT.

7 CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

STATIGALLY STABLE - NOT AS MECH ATTENTION (69) IRED TO PITCH ATTENDED

GOOD DAMPING ALL AXES.

O MOST OBJECTIONABLE FEATURES

MODIFACE TORBULANCE RESPONSE BUT NOT DAD.
SIME SITES ATTRITUDE UNSITE NOTICES ATTRI
THREFLENCE BUT NOT DISPIDITION CONTROL. DAYUSBETS SKON THE TESETERNES WERE, FOR THE MIST
PART, LIDOUR CIT WITH LITTLE, BUT SAME ATTEMPT,
TO CONTROL WITH IMPOST 1892A.

OVERODYTHOL TENDENCY BELOW 500 Ft. PROBABLY FILOT PROFESIENCY IS STILL LOW.

11 V SCELLANEOUS

S EVATOR TRIM RATE TOO PAST.

OVERALL IT WAS NOT A BAD CONFIGURATION. I COMMS MUST OF THE POOT PERFORMANCE CAN BE BLAMED ON PILOT PROFICIENCY. (NOTE, THE PILOT HAD NOT PLOYIN ON THIS PROJECT FOR 17 DAYS.)



CONFIGURATION A4L FLIGHT NUMBER 79-1 PILOT A PILOT-RATING 5

WIND[knats] CALM WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION A4L FLIGHT NUMBER 80-2 PILOT B PLOT-RATING 558

WIND (knots) WIND SHEAR EXTERNAL TURBULENCE

CHARACTERISTIC ROOTS -.04 -.62 1.061 1.061

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELE	VATOR	THRU:	
MaE: 0.34	(rad/sec2)/in	Z ₈₁ 15.0	(tt/sec ²)/in
Initial	Final	In tigi	Final
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

CHARACTERISTIC ROOTS -.04 -.62 1.06 ± 1.061

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE
DIFFICULTY
MAXIM.IM UNDESIRED FLUCTUATIONS

Longri	udinal vero	city (TAS)	Ver	t-cal velocity	(K)	
V.M.C.	1MC	I M C	VMC	1MC	IMC	
OU *	OUT	. iN	OUT	, QUT	IN	
ONE	SLIGHT	MODERATE	NONE	NONE	NONE	
+8.	-5	krats	DК		f.g	'n

COMMENTS

ON THE THIRD APPROACH. THE TURBULENCE SEEMED TO BE MORE OF A PROBLEM, AND THIS RESULTED IN AIRSPEED EXCURSIONS.

	VATOR		LEVER
M8E = 0.34	(rad/sec2)/in	Zar=15.0	(ft/sec2)/in
Initial	F-nal	Init al	F-nal
		SATISFACTORY	

Longitu	dinal veloci	ly (IAS)	Vert	cal velocity	y (n)
VMC.	IMC	LMC	VMC	(M C	IMC
OUT	Out	IN	OUT	TLO	iN
NONE	NONE	NONE	NONE	HONE	NONE
	5	knois	COOD		7 p.m.

PERIOD

COULD BE EXCITED IN THE LANDING AND FLARE MANDEUVRE.

DAMPING

DEGREE

AGGRAVATING

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE CAMPING SMA_L SHORT SOURCE CEGREE HODERATELY ELEVATOR, TURBULENCE

EXC-TATION

COMMENTS

THE TIRBULENCE GAVE BUNYS THAT SERMED TO START A PEM CYCLES OF THE OSCILLATION GOING, BUT THE MOST SEVERE EXCITATION OCCURRED WHEN LEVELLING OFF AY THE END OF THE APPROACH.

THIS IS A FEATURE THAT MAY BE LEARNABLE BUT IT WAS THE DECIDING FACTOR IN DE-RATING THE MODEL

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

SMALL NO

NEGLIGIBLE DIFFICULTY

AMPLITUDE

ELEVATOR, THRUST LEVER ELEVATOR, THRUST LEVER

SMALL, MODERATE

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

	initial track			Final	
31.de poth	Localizer	Glide path	Lacalizer	Glide parh	Localize.
NONE	NONE	SLIGHT	NONE	STATEMENT	St. [GHT
6000	G00D	FAIR	GOOD	FA13	G000

MINIMUM ACCEPTABLE BREAKOUT ALT TUDE
IF GREATER THAN 200 FEET

COMMENTS

ASSESSMENT ABOVE IS FOR LAST APPROACE.

Intercept & initial track | Intermediate track | Final track | Gige poth | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path > SCICHT NONE NONE NONE NONE NONE GOOD GOOD 6000 COOD GOCD COOD

DIFFICULTY ON LOCALIZER DUB TO WIND SHEAR BUT, ONCE RECOGNIZED, IT CAUSED NO BRAL PROBLEM - IT DID NOT AFFECT RATING. THE BREAROUT FEIGHT WAS CHOSEN TO ERABLE COOD STEADY STATE CONDITIONS TO BE ESTABLISHED FOR TOUCHOUM.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT MODERATE PRECISION OF ATTAINING TOUCHDOWN POINT VERY POOL

COMMENTS -SEE SECTION #3 MODERATE FAIR DIFFICULTY

P.I.O. TENDENCY DURING FLARE - HAD TO ESTABLISH A GLIDE PATH UNLIGH HAD A REASONABLE RATE OF DESCENT WHICH COULD THEN 85 CARREDA RIGHT ON TO TOUCH DOWN. ATTEMPTS TO ARREST SATE OF DESCENT SHOULD NOT BE MADE.

7. CONTROL TECHNIQUE

COMMENTS IF O.FFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFEC" ON FINAL ASSESSMENT

SMALL

NONE

300

9 LEAST OBJECTIONABLE FEATURES

THE PITCH ATTITUDE CONTROL WAS A GREAT HELP IN MAINTAINING AIMSPEED BUT IT MAS DEGRADED BY (1) THE OSCILLATORY PROBLEMS, (2) THE ROUMERMENT OF THIS HAS NOT A REAL PROBLEM SINCE IT WAS BITCE TRIMMING AIRSPEED.

MORKLOAD ON DESCENT VERY LOW - COOD PITCH ATTITUDE AND ANGLE OF ATTACK STABILITY EVEN IN TURBULENCE, BUT, I SUSPECT THAT LOOP IS TOO TIGHT ON ANGLE OF ATTACK.

IO MOST OBJECT-ONABLE FEATURES

DEFINITE PIO TENDENCY NEAR GROUND AND SOME IN AIR FOR MUDERATE SIZED, FAST INPUTS.

H. VISCELLANFOUS

MODEL WAS FLOWN TWICE WITH APPROACH HEADING OF 290. AND THEN WITH 040°.

SENSITIVITY ON ELEVATOR COULD BE REDUCED - 20%. GOOD MODEL ON GLIDE PATH TESTS - GLIDE PATH RATING 3B BUT PIO TENDENCY NOT GOOD AS IT CAUSES AN ABNORMAL (BUT PEASIBLE) LANDING TECHNIQUE



CONFIGURATION A4L FLIGHT NUMBER 83-L PILOT B WIND(kno's) 10 WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT CONF-GURATION A4L
FLIGHT NUMBER 98-1
PILOT C
PILOT-RATING 5 WIND (knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE LOT-RATING 4C CHARACTERISTIC ROOTS -.04 -.62 1.06 1 1.061 CHARACTERISTIC ROOTS -.04 -.62 1.06 ± 1.061 LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = 0.34 (100/sec2)/m Zag = 15.0 (11/ VATUR (40d/sec²)/m Z8T=15.0 (11/sec²)/in
Final In-tial Final Final SATISFACTORY SATISFACTORY SATISFACTORY CONTROL SENSITIVITY Initial Final SATISFACTORY SATISFACTORY SATISFACTORY TOO GREAT RESPONSE 2 EASE OF MAINTAINING CESIRED VELOCITIES I.M.C FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAX MUM UNDESIRED FLUCTUATIONS I.M.C VMC SUICRI SLIGHT SLIGHT SLIGHT VERY GOOD FOR HOLDING VELOCITIES - SO GOOD THAT THE CROSSCHECK ON IAS WAS ALLOWED TO BECOME DEFICIENT AND IAS COMMENTS SOME VELOCITY AND HEIGHT CHANGES DURING TURNS, OTHERWISE HOLDING ON GLIDE PATH WAS NOT AS GOOD AS EXPECTED. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLI UDE PERICO SMALL ZERO DAMPING ZERO SOURCE DEGREE EXCITATION EASILY COMMENTS SMALL, LIGHTLY DAMPED PITCH OSCILLATION PREVENTS RAPID AND 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION DIFFICULTY MODERATE DIFF CULTY COMMENTS GAINED HEIGHT IN TURNS AND LOST & 10 KNOTS. 5 FLIGHT PATH CONTROL intercept B mittal track Intermediale trock Final track Glide path Localizer Glide path Localizer Glide path Localizer Intercept & initial track | Intermediate track | Glide path | Localizer | Glide path | Localizer Glide pol Localizer DIFFICULTY SUIGHT SLIGHT NONE SLIGHT PRECISION GOOD GOOD COOR MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEE! A_TIT_JOE IF YOU CAN STAY ON COURSE. 1900 FT, OF DESCRIT AT A MEAN RATE OF 600 f.p.m. DUE TO MODERATE HEADNING. - THREE MINITE TRACKING TASK WHICH IS TOO LONG A PERIOD OF SISTAINFO HIGH WORKLOAD. COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT
FAIR (GOOD MODERATE FAIR DIFFICULTY, COMMENTS DIFFICULTY DUE TO LEARNING GOORDINATION OF ELGVATOR AND THRUST LEVER. PITCH OSCILLATION UNPLEASANT CLOSE TO GROUND DURING PLARE. IT INHIBITS FIRM ACTION. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I 4 S W:"H ELEVATOR AND VERT CAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST QBUECTIONABLE FEATURES GOOD U. V. 6 HOLD (STABLLITY) GOOD SEPARATION RELATIVELY LITTLE ATTENTION REQUIRED TO MAINTAIN SPEED OF CONTROLS (RESPONSE TURBULANCE SENSITIVITY MINIMAL. AND RATE OF DESCENT (TURNS EXCEPTED). IC. MOST OBJECTIONABLE FEATURES. COCKPIT DISPLAYS FOR TASK ACCOMPLISHMENT. LIGHTLY DAMPED PITCH OSCILLATION. # MISCELLANEOUS BIOGEST RESERVATION HER: IS NOT WITH RESPECT TO ELEVATOR FORCES WERE TOO HIGH AND DISPLACEMENTS TOO HANDLING QUALITIES, BUT THE INSTRUMENT APPROACH AND DISPLAY SYSTEM, BREAKOFT REIGHT STC. MOULD BE RATER 3 TO 35 WITH A 350'-400' RESAKOLT REIGHT. SMALL.



CONFIGURATION A4-IL FLIGHT NUMBER 131-4 FILOT A PILOT-RATING 3

ta WIND(knots) WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.03 -.65 -1.05 ± 1.061

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RÉSPONSE :

ELE	VATOR	THRUS	T LEVER
M8E = 0.3	(rad/sec²)/in	ZBT = 15.0	(11/sec ²)/in
Initial	Final	lected	Final
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION MAXIMUM UNDESIRED FLUCTUATION

ſ	Long, u	dinal veloci	y (IAS)	Verl	ical velocity	(h)
Т	V.M.C	IMC	IMC.	VMC	: MC	IMC
Γ	CUT	TUD	IN	aut	TLO	IN
ı	NONE	SLIGHT	SLIGHT	NONE	SUIGHT	SLIGHT
t	İ	5	knols	± 200		f.pm

COMMENTS:

THE ATTITUDE COMMAND SYSTEM SEEMED TO WORK WELL IN GIVING THE DESIRED AIRSPEED, BUT SOMEWHAT TOO MUCH ATTENTION IS STILL REQUIRED.

WIND (knots)

CHARACTERISTIC ROOTS -.03 -.65 -1.05 ± 1.061

WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIBIBLE

CONFIGURATION A4--L

FLIGHT NUMBER 129-1

PLOT-RATING 40

Long tu	dina velaci:	y (:AS:	Vert	co ve acity	(h)
VMC	1 M C	LMC	V.M.C	1 M C	I M C
OUT	OUT	11/1	OLT	OUT	IN
NONE	NONE	SLIGHT	SLIGHT	SLICHT	SLIGHT
94	, -7	knots			fρπ

GOOD ATTITUDE AND SPEED TRIM IN CRUISE, SPEED CONTROL NOT SO GOOD ON APPHOACH (SLIGHT TO MODERATE DIFFICULTY DURING THIS PHASE).

3 RESIDUAL OSCILLATORY CHARACTER STICS

EXCITATION CONTROL COMMENTS

AMPLITUDE	PERIOD	DAMPING
ZERO		
ZERO		
SOURCE		DEGREE
		`

SOURCE DÉGRÉE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION:

DIFFICULTY

COMMENTS :

NECLICIBLE DIFFICULTY

5. FLIGHT PATH CONTROL

DIFF CULTY PRECIS ON

Intercept & initial track				Final track	
Glige path	Lacalizer	Glide path	-acairter	Glide path	Laconter
SLIGHT	SLIGHT	SLIGHT	S1.IGHT	SLIGHT	SLIGHT
FAIR	FAIR	POUR	FAIR	RIAG	FAIR

A FOLLOWING WIND REQUIRED HIGH (UP TO 1500 f.p.m.) RATES OF DESCENT BUT THESE WERE FAIRLY SASILY SELECTED.

ntercept 8 initial track Intermediate track Fino track Gilde path Localizer Glide path Localizer Stide path Localizer NONE (OOD GOOD

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT BO DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT GOOD

COMMENTS

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAIS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SMALL

9 LEAST OBJECTIONABLE FEATURES

GOOD ATTITUDE HOLD

SPEED CONTROL ON APPROACH NOT AS GOOD AS MIGHT BE EXPECTED IN LIGHT OF HIGH PITCH ATTITUDE STABILITY, PERHAPS DUE TO THING TO MAKE GLIDE SLOPE CORRECTIONS WITH ATTITUDE, HENCE SPEED, SPEED BERGES OPTEN OCCURRED (PERSISTED) AND WERE DIFFICULT TO CORRECT.

MODERATE DIFFICULTY
POOR

DIFFICULTY DUE TO INEXPECTEDLY GOING HIGH AT BREACOUT, PULLED OFF POURS TO GET DOWN AND FOUND I NEEDED LOTS TO ARREST THE RESULTING HIGH SINK RATE - BALLOOMED, AND LANDED LOWN.

ID. MOST OBJECTIONABLE FEATURES

I MISCELLANEOUS

TURBULENCE UPSETS NOT BAD PITCH ATTITUDE VERY STABLE - GOOD FOR CRUISE AND EASY TO TRIM BLT, DURING MANUELYRES IT IS DIFFICULT TO CHANGE

EXCEPT FOR PROBLEM AFTER BREAKOUT WHERE AN UNEXPECTED ANOUNT OF POWER WAS NEEDED, THRUST LEVER CHARACTERISTICS SEEMED QUITE WOOD.



CONFIGURATION R4-2 FLIGHT NUMBER 45-3 PILOT B CONFIGURATION R4-2 FLIGHT NUMBER 66-2 P'LOT A PILOT-RATING 4 WIND (knots) WIND[knots] CALM WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE WIND SHEAR EXTERNAL TURBULENCE PILOT B PILOT-RATING 3C CHARACTERISTIC ROOTS -.02 -.67 -1.06 -1.045 CHARACTERISTIC ROOTS -.02 -.67 -1.06 11.041 LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag: 0.25 (rod/sec²)/m Za₁:15.0 (ftt/sec²)/n India Final Satisfactory Satisfactory Satisfactory Satisfactory CONTROL SENSITIVITY: RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS UNTIL DOING UNDER THE HOOD THE PITCH ATTITUDE SEEMED TO BE OFFER SOLID BUT, WITH THE ADDITION OF LIFT, AND TURBULENCE THE MANDER BECAME BOTHERSOME TO A FOINT AT WHICH I WAS BOTHER TOO HARD FOR MY LIKING. IF SPEED WAS OTHER THAN 60 KNOTS, IT WAS DUE TO COMPLACENCY COMMENTS AND BEING ABLE TO RELAX. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE ZERO ZERO COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGETELE OFFICULTY CHANGE REQUIRED. EASE OF COMPENSATION SMAIL SLIGHT D.FFICULTY COMMENTS 5 FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Fina track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | intercept & initial track | Intermediate track | Glide path | Localizer | Glide path | Localizer | Final Irack Glide path Localizer DIFFICULTY SLIGHT SLIGHT MODE RATE SLIGHT MODERATE MONE NONE NONE NONE NONE PATR 2000 PATE CODD 3000 GOOD COOD MINIMUM ACCEP"ABLE BREAKOUT ALT TUDE F GREATER THAN 200 FEE" ő ĸ COMMENTS CONTINUED DESCENT TO 150 FT BEFORE BREAKOUT. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT DIFFICULTY
PRECISION OF ATTAINING FOUCHDOWN POINT FAIR - NO GOOD DIFFICULTY THERE SEEMED TO BE A TENDENCY TO START INTO A SLICHT CLIMB AS THE ALBORAPT WAS LEVELLED BUT THIS PORTION WAS ALL OVER SO PAST THAT NOT TOO MUCH IMPORTANCE CAN BE ATTREBUTED TO 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT MONE 9 LEAST OBJECTIONABLE FEATURES GOOD PITCH ATTITUDE STABILITY CORD RESISTANCE TO TURBULENCE. IO MOST OBJECT!ONABLE FEATURES TOO NICH 'S' TERNING DOWN LOCALIZER - A DISPLAY DEFICIENCY RATHER THAN ANYTHING SISE BUT ACCURACY GOOD. I' MISCELLANEOUS THE ALRCKAPT SECRED TO SITCH MOSE-UP WHEN DESCENDING FROM 2300 PT TO 1900 PT, BUT THIS DID NOT CAUSE PROFILERS ON THE FINAL APPROAGE NEED BETTE: PREDICTOR DISPLAY FOR LOCALIZER DEVIATIONS.



CONFIGURATION: R4-2L FLIGHT NUMBER 126-3 P:LOT C CONFIGURATION FLIGHT NUMBER PILOT WIND (knots) W:ND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT WIND SHEAR EXTERNAL TURBULENCE P-LOT C
P-LOT-RATING 3 PILOT-RATING CHARACTERISTIC ROOTS -.02 -.67 -1.06 1.041 CHARACTERISTIC ROOTS LAPRORAFT RESPONSE TO CONTROL INPUTS ELEVATOR 1-RUST LEVER

Mag = 0.34 (roo/sec²)/in Zaj = 15.0 (ft/sec²)/in (rod/sec²)/in Z_{BT} = Final (f1/sec²)/in Final CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES Long todinal velocity (FAS)
VMC LMC TMC
OUT OUT IN
NONE SLIGHT SLIGHT Vertical velocity (h)
VMC LMC LMC FLIGHT CONDITION TURBULENCE.
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS OJT OUT IN SLIGHT SLIGHT MODERATE COMMENTS THE ONLY REAL DIFFIGULTY IN ACCELERATION TO AND HOLDING 70 KNOTS, HAD TO FAIL BACK TO 60 KNOTS TO STABILIZE IN LEVEL FLICHT, EXTERNAL TURBULENCE PROBABLY HAVING SOME EFFECT. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD DAMPING AMPL TUDE PERICO DAMP NG ZERO DEGREE SOURCE DEGREE EXCITATION COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY DIFFICULTY SLIGHT COMMENTS NECESSARY TO COMPENSATE FOR SPEED VARIATIONS USING POWER 5. FLIGHT PATH CONTROL Intercept A nital track Intermediate track Final track Glide path Localizer Glide path Localizer Glide path Localizer Intercept 6 initial track intermediate tracx Final track
Glide path Localizer Glide path Localizer Glide path Localizer DIFF.CULTY: NONE SUIGRI NONE PRECISION 6000 FALR GOOD GCOD FAIR MINIMUM ACCEPTABLE GREAKOUT IF GREATER THAN 200 FEET ALTITUDE SLIGHTLY HIGH ON GLIDE PATH AT BREAKOUT (2001) PICKED UP SPEED TO 65 KNOTS WHEN VMC. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT COOD DIFFICULTY DIFFICULTY SPEED SLIGHTLY HIGH 7 CONTROL TECHNIQUE COMMEN'S IF DIFFERENT FROM ON INTERMEDIATE TRACK, USED POWER LEVEK AS LEAD CONTROL I AS WITH ELEVEKTOR AND IN POSITIONING PORMAD OR AFT OF CLIDE PATH. LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES ABILITY TO HOLD SPEED WAS QUITE GOOD BUT PERMAPS COULD BE FURTHER IMPROVED? ID. MOST OBJECTIONABLE FEATURES II. MISCELLANEOUS EXTERNAL TURBULENCE BECOMING NOTICEABLE -PARTICULARLY AT HIGH POWER SETTINGS - EG, 70 KNOTS TURNING TO BASE LRG. THIS WAS THE LAST HODEL OF THE DAY.



WIND (knots) WIND SHEAR EXTERNAL TURBULENCE CONFIGURATION A4-2L FLIGHT NUMBER 95-1 PLOT B PLOT-RATING 3% CONFIGURATION A4-2L FLIGHT NUMBER 108-2 PLOT A # NOtknots1 SMALI. WIND SHEAR SMALL.
EXTERNAL TURBULENCE MEGLIGIBLE PILOT A
PILOT-RATING 3 CHARACTER STIC ROOTS -.02 -.67 |-1.06 | ±1.041 LAIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY STIGHTLY GREAT SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION OUT OUT IN SLIGHT SLIGHT SLIGHT S O C ... MAXIMUM UNDESIRED FLUCTUATIONS DISPICULTY DUE TO CHOSS-CHECK, THE MODEL IS OK. TURBULENCE WAS EVIDENT IN MEAVE AND YAW BUT DID NOT CAUSE COMMENTS CONCERN IN PITCH BECAUSE OF STRONG ATTITUDE STIFFNESS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE AMPLIT JDE P£RICO .2<u>€40</u> .2€80 SOURCE SOURCE CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED NEGLIGIBLE
NO CIFFICULTY DIFFICULTY DO NEED TO PAY ATTENTION. HOWEVER, ONE CAN ACTUALLY TRIM A STEADY STATE 20° BANKED TURN. LONGITUDINAL CONTROL FORCES IN STEADY TURNS SOMEWHAT COMMENTS: 5 FLIGHT PATH CONTROL Intercept & mit at track | Intermediate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Intercept & initial track | Intermediate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Gli SLIGHT SLIGHT SLIGHT SLIGHT S1,IGHT NONE NONE SLIGHT NONE SLIGHT SLIGHT NIMUM ACCEPTABLE BREAKOUT ALTITUDE
GREATER THAN 200 FEET 0 K DIFFICULTY DUE TO FACT THAT EVEN WITH THE COOD PITCH STABLUTTY, SPEED ERRORS DEVELOPEN, PROBABLY BY CHOUNCIOUSLY PUTTING MISS DOWN TO GET DOWN ON GLIDE PATH. SOME MORAL FORCE DRIVELOPS WITH SPEED CHANCES. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO DIFFICULTY
PRECISION OF ATTAINING TOJCHDOWN POINT COOD DIFFICULTY COMMENTS BROKE OUT A LITTLE LOW AT 150 FT. POSITIONING OK 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTER STICS EFFECT ON FINAL ASSESSMENT SOME TURBULENCE EFFECTS, BUT NOT A NONE. SACTOR IN BATING. 9 LEAST OBJECTIONABLE FEATURES GOOD ATTITUDE STABILITY, CONTROL SENSITIVITY.

IO MOST OBJECTIONABLE FEATURES

I MISCELLANEOUS

MB NO ARTIFICIAL TURBULENCE DURIN; THIS EVALUATION.

TIME CONSTANT FOR FITCH BESPONSE TO ELEVATOR COULD

BE HIGH A LITTLE LONGER. NEEDS SOME DISPLAY

IMPROVEMENT. COMPARISON WITH MODEL 19:2VL SHOWS

IMPROVED LOCALIZER TRACKING WITH IMPROVED LONGITUDINAL

DYNAMICS.

A LITTLE SENSITIVE TO TURBULENCE, BUT NOT BAD AT ALL.

189

HIGH CONTROL PORCES IN PITCH DURING SUSTAINED

TURNS. TURBULENCE IN MEAVO.

ELEVATOR TRIM RATE 100 SIGW.



CONFIGURATION A4-2L FLIGHT NUMBER 99-1 PLOT C PILOT-RATING 1 W·ND(knots) 3 RABHR CNIW FXTERNAL TURBULENCE CONFIGURATION WIND (knots) FL GHT NUMBER WIND SHEAR EXTERNAL TURBULENCE PILOT-RATING CHARACTERISTIC ROOTS __.02 __.67 __1.06 __±1.041 CHARACTERISTIC ROOTS AIRCRAFT RESPONSE TO CONTROL INPUTS THRUST LEVER

(f1/sec²//n
F nal ELEVATOR (roa/sec2)/n 787 = CONTROL SENSITIVITY Initial SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (h) COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE ZERO DAMPING HEAVE DEGREE DEGREE EXCITATION COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NECLIGIBLE
SLIGHT CHEF COLTY DIFFICULTY COMMENTS: SPEED CONTROL NOT BETTER TRAN \pm 5 KNCTS. 5 FLIGHT PATH CONTROL Intercept & initial track Intermediate track
Glide path Localizer Glide path Localizer Intercept 8 initial track intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer Final track Glide path _ocalizer SLIGHT MINIMUM ACCEPTABLE BREAKOUT ALT TUDE
IF GREATER THAN 200 FEET COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT 2000 DIFFICU.TY COMMENTS: DESCENT ARRESTED, BUT ALLOWED SPEND TO FALL TO 50 KNOTS. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES IO MOST OBJECTIONABLE FEATURES II. MISCELLANEOUS BEST MODEL THIS DAY, (cf. A4L, 4-2L,2-2L) WOULD PREFER SLIGHTLY BETTER SPEED CONTROL DURING MANDEUVERS.



CONFIGURATION R4-3G FLIGHT NUMBER72-3 PILCT A PILOT-RATING 8

 WIND (knots)
 CONFIGURATION
 44-3L

 WIND SHEAR
 HODERATE
 FLIGHT NUMBER
 97-2

 EXTERNAL TURBULENCE
 NEGLIGIBLE < 1100 / PILOT - P

WIND (knots)

Mag : .34 (rod/sec2)/n ZBT = 15.0 (tf/sec2)/in

| In tall | Fina | Install | Fina |
| SATISFACTORY | SATISFACTORY | SATISFACTORY | SATISFACTORY |

ARGE EFFECT OF AIRSPEED ON NORMAL FORCES POOR ATTITUDE

WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS

+.02 -.76 -1.08 + 1.051

CHARACTERISTIC HOOTS +.02 -.76 -1.08 1 1.051

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY.

RESPONSE:

COMMENTS

ELE:	ATOR		I LEVER
V8E = .35	(rad/sec2)/in	Z8T = 15	(ft/sec ² l/ir
Initial	Finol	Initial	Final
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATIS FACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

TUP DIF: MA)

" DOFF	NCE	
FICULT	Υ	
KIMUM	UNDESIRED	FLUCTUATIONS

	Long.tu	dina veloci	ty (!AS)	Vertical velocity (h)			
	y.M.C.	1MC	IM C	VMC	1 M C	IM C	
	Ou *	OUT	(N	OUT '	OLT	IN	
	MODERATE	GREAT	CREAT	MODERATE	GREAT	GREAT	
NS	± 5 -	LO	knois	± 300		tpm.	

THE INTERACTION BETWEEN AIRSPEED AND VERTICAL SPEED IS MOST

IRE INITIALITY REPRESENTATION FOR THE PROPERTY OF THE TRUST FARST BESONCESTING. AS THE AIRSPEED FALLS OFF, THE RATE OF DESCENT INCREASES, THE AIRSPEED FALLS OFF MERE, ETC. CONSTANT ATTENTION IS REQUIRED TO BOTH PITCH ATTITUDE AND VERTICAL SPEED TO PREVENT THIS INSTABLE SITUATION FROM GETTING AWAY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION CONTROL

COMMENTS

AMPLITUDE	PERIOD	DAMPING		
ZEKO				
ZERO				
SOURCE		DEGREE		

PER OD DAMPING

SOURCE DEGREE

COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DIFF CULTY

IT WAS EXTREMELY DIMPICULT TO RETAIN AIRSPEED AND ALTITUDE IN THE TURNS FOR THE REASONS GIVEN UNDER #2.

DIFFICULTY

MODERATE POOR

MUST ENSURE THAT SPEED IS HELD

5 FLIGHT PAIH CONTROL

	intercept 8 in rial frock intermediate frack			Fina frack		
	Glide poth	Localizer	Glide path	Lacalize [*]	Shae path	Localizer
DIFFICULTY:	SUICHT	SL1GHT	MODERATE	MODERATE	MODERATE	MODERATE
PRECISION	FAIR	FAIR	Pook	POOR	200 R	POOP

MINIMUM ACCEPTABLE BREAKOJT ALT TUDE F GREATER THAN 200 FEET 500

SEE SECTION 92. EVERY TIME THE AIRSPEED PELL OFF, THE BOTTOM FELL OUT AND THE RATE OF DESCENT WHISTLED UP

ntercept B in hal rack Intermediate track Finol track Glide path Localizer Glide path Localizer Glide path Loc NO/SLIGHT NO/SLIGHT SLIGHT SLIGHT MODERATE SLIGHT GOOD GOOD GOOD FAIR FAIR

(1) TENDENCY TO TRACK CLIDE PATH ERRORS WITH PITCH RESULTED IN (2) SPEED ERRORS WHICH RESULTED IN (3) HEIGHT CONTROL PROBLEMS. i.e., SPEED AND THEREFORE 4EIGHT CUNTROL IS DIFFICULT.

CIFFICULTY

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SLIGHT CIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT 2000

7 CONTROL TECHNIQUE

COWMENTS

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

TOO DIFFICULT TO BO OTHER THAN TO AIM TO HOLD SPEED AT 60 KNOTS AND TO CONTROL RATE OF DESCENT WITH THRUST LEVER

UNCONSCIOUSLY FLARED ON BREAKOUT WHICH GAVE SPEED LOSS AND LARGE UNANTED DESCENT RATE - DIFFICULT, BUT ABLE TO CORRECT.

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

TOO MUCH SEADING CHANGE WITH SMALL REDDER

1NPUTS

NONE

300

9 LEAST DBJECTICNABLE FEATURES

IC MOST COLECTIONABLE FEATURES

H MISCELLANEOUS

LACK OF ATTITUDE STABILITY GAVE SPEED ERRORS.
 SPEED ERRORS CAUSED CLIDK SLOPE TRACKING ERRORS.

 \mathbb{R}_0 EFFECT COULD CAUSE PROBLEMS NEAR TOUCHDOWN AND IN PLARE. REQUIRED 1100 fpm on descent twice.



CONFIGURATION R4-3L FLIGHT NUMBER 103-2 PILOT C PILOT-RATING 35 WMD(knois) 5
WIND SHEAR MEGLIGIBLE
EXTERNAL TURBULENCE MEGLIGIBLE CONFIGURATION R4-3L FLIGHT NUMBER 121-3 PILOT C PILOT-RATING 7 WIND (knots) WIND SHEAR EXTERNAL TURBULENCE CHARACTER STIC ROO'S +.02 -.75 -1.08 1 1.051 CHARACTERISTIC HOOTS +.02 | -.75 | -1.08 1 1.051 I. AIRCRAFT RESPONSE TO CONTROL INPUTS | ELEVATOR | THRUST LEVER | Misc = 0.34 | trod/sec2 | /in | Z t = 15 | (fil/s | Initial | Final f1/sec²l/n CONTROL SENSITIVITY: NOT ASSESSABLE SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY TOO SMALL RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (fill INC IMC VMC IMC IMC
OUT IN
SLIGHT SLIGHT TURBULENCE DIFFICULTY MAX:MUM UNDESIRED FLUCTUATIONS NONE SLICHT MODERATE MODERATE MODERATE MODERATE GREAT RELATIVELY SMALL SPEED DEPARTURES REQUIRED COMPENSATION BY THROTTLE TO AVOID EXCESSIVE MANIFOLD PRESSURE OR HEIGHT DIFFICULTY DUE TO LARGE THRUST CORRECTIONS REQUIRED TO RESPOND TO SPEED DEPARTURES. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PF RIOD DAMPING AMPLITUDE PER-00 AMPLITUDE DAMPING HEAVE SOURCE DEGREE SQL RCE EXCITATION CONTROL NO DISCERNIBLE DSCILLATORY CHARACTERISTICS, BUT SOME EXTERNAL TURBULENCE WAS PRESENT AND THIS COULD HAVE GBSCURED THEM. COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED: EASE OF COMPENSATION MODERATE DIFFICULTY DIFFICULTY OVERCOMPENSATED WITH THRUST LEVER WHEN EXECUTING TURNS. THRUST USED TO CORRECT FOR SPEED RATHER THAN BANK. THRUST COMPENSATION REQUIRED FOR SPEED CHANGES WAS DVERRIDING. 5. FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer Intercept & milia Irack Glide path Localizer Intermediate track Final track Glide path Localizer Glide path Localizer DIFFICULTY: SLIGHT NONE NONE MONE MODERATE SLIGHT MO DE RATE SLIGHT SLIGHT MODERATE MODERATE PRECISION GOOD COOD POOR FAIR GOOD GOOD FAIR FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET DIFFICULTY DUE TO CONSIDERABLE HEIGHT LOSS TURNING ON TO BASE LEG AND FURTHER LOSS BEFORE GLIDE PATH WAS ATTAINED. COMMENTS: SOME LOSS OF SPEED (ABOUT 10 KNOTS) ON FINAL - RECOVERED 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT SODD SLIGHT/MODERATE DIFF CULTY COMMENTS: DIFFICULTY DUE TO NEED TO CORRECT FOR LO KNOT LOSS OF LARGE STECK AND THEOTTLE INPUTS REQUIRED. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES NO NOTICEABLE OSCILLATIONS, SMAIL SPEED DEPARTURES REQUIRED RATHER LARGE POWER LEVEL CORRECTIONS. IF THESE WERE NOT MADE HEIGHT WOULD BE LOST OR GAINED. IC. MOST DRUECTIONABLE FEATURES VERY DIFFIGULT TO HOLD A PARTICULAR SPEED OR TO SELECT AND WOLD A DIFFERENT SPEED REASONABLE CONFIGURATION TO FLY, BUT CONSTANT ATTENTION TO RINGE LEVER TO PREVENT HEIGHT CHANGES WHEN CORRECTING FOR SPEED DEPARTURES A NUISANCE. II MISCELLANEOUS



WIND (knots)
WIND SHEAR
EXTERNAL TURBULENCE CONFIGURATION R4-3 Fulght NUMBER 47-1 PILOT D PILOT-RATING 9 WINDERHOIS 10-15
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE CONFIGURATION FLIGHT NUMBER PILOT PILOT- RATING CHARACTERISTIC ROOTS +.02 -.76 -1.08 + 1.051 CHARACTERISTIC ROOTS 1 AIRCRAFT RESPONSE TO CONTROL INPUTS (rag/sec²)/in ²8T = 15 /I. Final M&E : 30 (ro (rad/sec2)/in Z8T= (††/sec²)/in Final ST LEVER

(H/sec²Vin)

F nal

TOO GREAT N_{BE} = CONTROL SENSITIVITY TOO GREAT TOO GREAT TOO SMALL RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES
 Longitudinal velocity (1AS)
 Vertical velocity (F)

 VMC
 1MC
 1 M C
 1 M C
 1 M C

 OUT
 OUT
 1M
 OJT
 QUT
 1K

 ODERATE
 HDD/GREAT
 GREAT
 HDDFGREAT
 GREAT
 S00° GREAT
 1pm
 FLIGHT CONDITION MAXIMUM UNDESINED FLUCTUATIONS OBVIOUSLY ON BACKSION OF POWER-REQUIRED CURVE. UNLESS AIRSPEED WAS MAINTAINED VERY CLOSE TO THE TRIM POINT, PILOT WAS IN TROUBLE. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS DEGREÉ SOURCE DEGREE EXCITATION CONTROL NO PARTICULAR OSCILLATORY PROBLEMS BUT DUE TO DIFFICULTY IN CONTROLLING AIRSPEED, THERE APPEARED TO BE PITCH AND HEIGHT COMMENTS DYNAMICS PROBLEMS. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS EXCESSIVE
GREAT D FFICULTY CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY IF SPEED WAS KEPT CONSTANT MO PROBLEMS AROSE BUT, ONCE THE FILDT STARTED USING POWER TO COUNTERACT EFFECTS OF AIRSPEED CHANGES, HE WAS IN THOUSHE AND LARGE THRUST INPUTS WERE REQUIRED. COMMENTS 5 FLIGHT PATH CONTROL Intercept 8 initial track | Intermediate track | Final track | Gode path | Local zer | Glide path | Local zer | Glide path | Local zer | Glide path | Local zer | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path | Clide path Intercept & initial track | rtermediate track | Final track |
Glide path Localizer | Glide path Localizer | Glide path Localizer | Glide path Localizer | DIFFICULTY MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET ALASPEED CONTROL REQUIRED MOST OF PILOT'S TIME AND HENCE OTHER VARIABLES SUFFERED. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT FAIR DEFICULTY DIFFICULTY AIRSPEED CONTROL WAS MAIN CAUSE OF DIFFICULTY, INITIALLY SPEED WAS SLIGHTLY LOW. THIS SET UP AN INCREASING MATE OF DESCENT AND CONSECURATILY A LARGER POWER INPUT WAS REQUIRED TO ARREST HATE OF DESCENT. 7. CONTROL TECHNIQUE COMMENTS IF OFFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAS* OBJECTIONABLE FEATURES FAIR PITCH RESPONSE CHARACTERISTICS. :0 MOST OBJECT ONABLE FEATURES THE LARGE POWER CHANGES REQUIRED AND THE NEED FOR YERY PRECISE AIRSPEED CONTROL OVERBURDENED THE PILOT.

I DO NOT LIKE IT AT ALL,

I: MISCEL_ANEOUS



CONFIGURATION 44-3L FLIGHT NUMBER 80-3 PILOT A PILOT-RATING 5 CONFIGURATION A4-3L FLIGHT NUMBER 96-4 PILOT B P.OT-RATING 58 **₩IND**(knots) LIGHT WIND (knots) 10 WIND SHEAR SHALL EXTERNAL TURBULENCE LIGHT WIND SHEAR SMAGE EXTERNAL TURBULENCE NEGLIGIBLE CHARACTER.STIC ROOTS +.02 -.76 -1.08 1 1.051 CHARACTERISTIC ROOTS +.32 -.76 -1.38 - 1.051 I AIRCRAFT RESPONSE TO CONTROL INPUTS | THRUST LEVER | M8E = 13.0 | THRUST LEVER | M8E = 13.0 | THRUST LEVER | M8E = 15.0 | THRUST LEVER | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M8E | M CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES IMC _ FLIGHT CONDITION TURBULENCE MODERATE MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS THE TURBULENCE PRODUCED A "RIDING THE SWELLS" EFFECT WHICE HAD TO PAY CLOSER ATTENTION TO SPEED BECAUSE OF AIRSPEED CHANGED THE VERTICAL VEHICLTY SIGNIFICANTLY AND WAS THE EFFECTS ON NORMAL FORCES. UNLY OBJECTIONABLE PART OF THIS MODEL. 3 RESIDUAL OSCIULATORY CHARACTERISTICS PER CD CAMPING PERIOD DEGREE SOURCE DEGREE
THROUGH EASILY
THRUST LEVER EFFECTIVE EXCITATION CONTROL COMMENTS SEE PART 2. 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS SYALI DEFICULTY CHANGE REQUIRED. EASE OF COMPENSATION MCDERATE SILIST DIFFICULTY COMMENTS NEED TO HOLD SPEAD PRECISELY IN ORDER TO BEST HOLD HEIGHT. 5 FLIGHT PATH CONTROL Intercept & mittel track | Final track | G de path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Intercept 8 in hai track intermediate track Final track Giide path Local zer Glize path Local izer Glide path Localizer DIFFICULTY MODERATE STEERS SLIGHT MODERATE SLIGHT SLIGHT PRECISION COOR PERY POOK GOCO POOR FAIR (4000) GOOD FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 300 " 200 PT; JUST NOT ENOUGH TIME TO ASSESS GLIDE PATH AND SITUATION AT BREAKOUT. DIFFICULTY DUE MAINLY TO NORMAL PURCES GENERATED BY AIRSPEED CHANGES. COMMENTS THE WIND CHANGE IN THE CAST 600 +700 FT REPORTED ABOUT 70* OF HEADING CHARGE. THIS WAS NOT CAUGHT IN TIRE AND THE LOCALIZER REEDLE WAS HAND OVER TO LEFT AT HEADING. THIS ASS NOT TWO DISCONCERTING SINCE THE HANDLING CHALLIES MEHI-CHITE COACH ENUMBER OF THE SIDESTLY NAMEDING. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT GOOD SLIGHT/MODESATE DIFF.CULTY NEED TO CLOSELY MONITOR SPEED DUKING LAST 200 FT, WENT HIGH AT HERAK OUT, USED A HIGHER THAN WANTED DESCENT RATE AND NEEDED MORE THRUST THAN EXPECTED TO ARREST IT, MUST NOT LUSE SPEED! 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST IF ERRIR WAS SUCH THAT A CHANGE IN SPEED GAVE AN APPROPRIATE CHANGE IN RATE OF DESCRIPT, I USBD THIS, BUT REVEN INLESS <u>BOTH</u> SPEED AND HEIGHT ERRORS WERE IN CORRECT SENSE. 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES THE AIRSPEAD CONTROL THROUGH THE ATTITUDE CONTROL SYSTEM WAS VERY FINE. IO. MOST OBJECTIONABLE FEATURES THE BEAVE RESPONSE TO TERRULENCE. THE EFFECT OF NORMAL MONGE VARIATIONS WITH SPEED ON GLIDE PATH TRACKING TASK - PITCH STABILITY DID NOT HELP THAT LICALIZER TASK STILL SOMEWHAT DEGRADED. II MISCELLANEOUS PHIOT MATING OF 5B BECAUSE OF NEED TO HOLD SPEED PRECISELY MIR GOOD GLIDE PATH PERFORMANCE, NB - NO ARTIFICIAL TURBULENCE DURING THIS EVALUATION.



CONFIGURATION A4-3L FLIGHT NUMBER £14-2 PILOT B PILOT-RATING 4½D WIND(krots) 8
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT CONFIGURATION WIND (knots) FL-GHT NUMBER WIND SHEAR EXTERNAL TURBULENCE PILOT-PAT NG CHARACTER STIC ROOTS +.02 -.76 -1.08 1 1.051 CHARACTERISTIC ROOTS LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = (-od/sec2)/a Zar = Initial Final (tt/sec²i/in THRUST LEVER (ft/sec²)/in Final CONTROL SENSITIVITY Initial RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Long tuck hall velocity (145)
VMC 1MC LMC
OUT OUT IN FLIGHT CONDITION: TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS: 3 RESIDUAL OSCILLATORY CHARACTERISTICS HEAVE DEGREE SOURCE DEGREE EXCITATION CONTROL COMMENTS 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION SMAEL
SLIGHT DIFFICULTY DIFFICULTY COMMENTS ELST MAINTAIN SPEED DURING MANDEUVARS OR A HEIGHT LOSS WILL ENSUE. 5 FLIGHT PATH CONTROL Intercept & miliot track Intermed Intercept & india track - rermediate track
Glide path Localizer Glide path Localizer ate track Final track Gl-de path Laco-zer lide porh Local zer Glae path Localizer Gide path Localizer DFFICJLTY SLIGHT SLIGHT GOOD FAIR FAIR FAIR MIN MUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FLET 300 SPEED CHANGES DIFFICULT - HAD TO USE LARGE AMOUNTS OF CONTROL TO ADJUST SPEED, EVEN 5 KNOTS, AT A FAST EROUGH RATE. LOW ON CLIDE SLOPE AT BREAKOUT - RECAINED AT MINIMUMS NOT THEN SENT MICH. COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING HATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT FATE DIFFICULTY COMMENTS GOOD HEIGHT CONTROL. 7 CONTROL TECHNIQUE COMMENTS IF CIFFEREN' FROM IAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES GOOD HEIGHT CONTROL. IC. MCS* OBJECTIONABLE FEATURES TOO STABLE - DIFFIGULT TO CONTROL CHANGES THE HICH APOINT OF STABLLITY RECURS ANY CONTROL DRAWS TO HAVE TO BE CLOSELY MONITORED TO ENSURE THEIR STREET, SENSITIVE TO TURBULENCE ESPECIALLY IN HEAVE, CAUSING MOTERSOME ENGINE SUBCES. I MISCELLANEOUS



CONFIGURATION R19L FLIGHT NUMBER 52-2 PILOT R WIND(knots) CAUM
WIND SHEAR MODERATE
EXTERNAL TURBULENCE LIGHT/MODERATE CONFIGURATION R19L FLIGHT NUMBER 64-1 WIND(knots) WIND SHEAR MODERATE
EXTERNAL TURBULENCE NEGLIGIBLE PILOT A
PILOT-PATING 2 PILOT B PILOT-RATING 450 CHARACTERISTIC ROOTS -.04 -.50 -1.05# 1.081 CHARACTERIST C ROOTS -.04 -.5 -1.05 ± 1.081 LAIRCRAFT RESPONSE TO CONTROL INPUTS (rad/sec2)/in 281: 11.9 Mag : 0.34 (rad Mag = 0.34 (ro ATOR THRUST LEVER (rad/sec²)/ir Z_{BT} = 15.0 (11/sec²)/n (11/sec2)/in CONTROL SENSITIVITY SATISFACTORY SATISFACTORY SATISFACTORY SATIS PACTORY TOO SKALL SATISPACTORY TOO SHALL 2 EASE OF MAINTAINING DESIRED VELOCITIES VMC | MC | IMC | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | OUT | O velocity [TAS] VMC FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM JNDESIRED FLUCTUATIONS ONLY DIFFICULTY IS THAT DUE TO AIRSPEED CONTROL ON INSTRUMENTS BRING SOMEWHAT OF A PROBLEM. MODERATE DIFFICULTY WAS EXPERIENCED IN CONTROLLING RATE OF DESCRIPT ON APPROACH BECAUSE OF WIND SHEAR. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS ZERO PERIOD ZERO EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQLIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION SMAT.I.
NO DIFFICULTY D FFICULTY COMMENTS 5. FLIGHT PATH CONTROL Intercept 8 initial track | Intermed ate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | intercept & in tial track intermediate track Gilde path Localizer Glide path Localize Localizer Glide path Localizer DIFFICULTY NONE SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT NONE NONE NONE NONE MODERATE SLIGHT PRECISION FA1R/GOOD GOOD FAIR CATR FAIR FAIR GOOD GOOD ALT TUDE 400 SOME PROBLEMS WERE ENCOUNTERED DUE TO THE WIND SHEAR WHICH REQUIRED A READING CHANGE OF ABOUT 40° ON THE APPROACH. DIFFICULTY DUE TO WIND SREAR - HEADWIND CHANGING TO A TAIL WIND DOWN LOW, 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT PRECISION OF ATTA NING TOUCHDOWN POINT FAIR DIFFICULTY UNCERTAIN ABOUT THRUST LEVER CHARACTERISTICS BUT THERE PROBABLY WAS NOT A VALID CAUSE FOR THIS, OTHER PROBLEMS DUE TO WIND SHEAR, 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT MONE 9 LEAS' OBJECTIONABLE FEATURES REASONABLE BUT A STRANGE KIND OF PITCH ATTITUDE IO. MOST OBJECTIONABLE FEATURES HEIGHT CONTROL NOT VERY EFFECTIVE FOR SHEAR SITUATION ENCOUNTERED. II MISCELLANEOUS



CONFIGURATION REST. F_GHT NUMBER 55-2 PILOT B CONFIGURATION R19L FLIGHT NUMBER 86-1 PILOT C PILOT-RATING 3 WIND (knots) 10-L5 WIND SHEAR SHALL EX*ERNAL TURBULENCE LIGHT WINDExects CALM
WIND SHEAR SHALL
EXTERNAL TURBULENCE MODERATE PILOT B PILOT-RATING 4D CHARACTER STIC ROOTS -.04 -.50 -1.05 ± 1.081 CHARACTERISTIC ROOTS -.04 -.50 -1.05 ± 1.081 ILAIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES | Vertical velocity (h) | | VMC | IMC | IMC | IMC | OUT | IN | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLI VMC SLIGHT COMMENTS DIFFICULTY DUE TO CROSS-CHECK AND TURBULENCE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERIOD AMPL:TUDE PE RIOD DAMPING AMPLITUDE HEAVE DEGREE EXCITATION CONTROL COMMENTS NO NOTICEABLE OSCILLATION. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGIBLE
NO DIFF CULTY DIFFICULTY DIPPICULTY DUE TO NEED FOR THRUST CHANGE NOT BEING IMMEDIATELY EVIDENT. 5. FLIGHT PATH CONTROL G de path | Localizer G ide path | Localizer Gide path | Localizer | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Colde path | Col intercept 8 initial track | Intermediate track Glide path | Localizer | Glide path | Localizer Final track Glide path Localizer DIFFICULTY NONE SLIGHT SLIGHT NONE SLIGHT NONE MODERATE SLIGHT PRECISION FAIR/GOOD SALS PAIR GOOD FAIR GOOD POOR PATR MINIMEM ACCEPTABLE BREAKOUT ALTITUDE
OF GREATER THAN 200 FEET COMMENTS DIFFICUATIES DUE TO: (1) CROSS-CHECK, (2) SOME WIND SHEAR, (J) QUITE SENSITIVE TO TURBULENCE. SPEED CONTROL WAS NOT BAD BUT 1 DID GET TO 70 KNOTS ONCE. SOME WIND SHEAR APPECTING GLIDE SLOPE ADHERENCE. SOME SMALL LATERAL AND DIRECTIONAL OUT-OF-TRIM REDUCED LOCALIZER PRECISION. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT
PRECISION OF ATTAINING TOUCHDOWN POINT FATR/GOOD DIFF CULTY DIFFICULTY NO COMMENTS SUICHTLY LOW AT BREAKOUT. FAIRLY REASONABLE CONTROL OVER MATE OF DESCENT WITH THRUST LEVER. SPEED WAS 70 KNOTS AT START OF FLARE TO CORRECT POR HIGH POSITION ON GLIDE PATH. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 _ATERA_ DIRECTIONA_ CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE, MODERATE EXTERNAL TURBULENCE; LOOSE DIRECTIONS LEY, MODERATE: LATERAL FORCES THOUGHT TO BE RATHER HIGH AND LATERAL TRIM RATE A BIT FAST. 9 LEAST OBJECTIONABLE FEATURES CONTROL OF RATE OF DESCENT WITH THRUST LEVER WAS PRETTY COOD. SOME FITCH ATTITUDE STABILITY WAS PRESENT, NO UNEXPECTED LONGITUDINAL OR SHAVE RESPONSES.

SLIGHT TAIL WING AT SURFACE.

MODERATELY SUSCEPTIBLE TO VERTICAL TURBULENCE

IC MOST CBUECTIONABLE FEATURES

I. MISCELLANFOUS

ONE OF THE BETTER MODELS. BELIEVE FINAL APPROACH PERFORMANCE MOULD IMPROVE WITH PRACTICE ON THIS MODEL SATE-ANAL TURBULENCE PRESENT BUT EFFECTS THOUGHT TO BE MINGS OF THIS MODEL.

SEE NOTE ON LATERAL/DIRECTIONAL CHARACTERISTICS ASOVE.



CONFIGURATION R19
FLIGHT NUMBER 41-1
PILOT D
PILOT-RATING 65 CONF.GURATION FEIGHT NUMBER PILOT PILOT-RATING WIND(krois) 15-20 WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT WIND (knots) WIND SHEAR EXTERNAL TURBULENCE CHARACTERISTIC ROCTS __.04 __.50 __-1.05 ± __1.081 Characteristic RCOTS (AIRCRAFT RESPONSE TO CONTROL INPUTS E Cod/sec2)/in Zet Initial Final Final THRUST LEVER (11/sec²)/in Final CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity [[AS V.MC | IMC | IMC OUT OUT IN TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS THERE SEEMS 10 BE A COUPLING BETWEEN THRUST LEVER AND PITCH ATTITUDE AND I.A.S. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE PERIOD AMPLITUDE DAMPING DEGREE DEGREE EXCITATION CONTRO. COMMENTS HAD DIFFIGULTY MAINTAINING DESIRED PITCH ATTITUDE WHEN MANDEUVRING AND APPLYING THRUST. NO PARTICULAR TENDENCY TO 4 CHANGE N THRUS' REQUIRED FOR 20° BANKED TURNS NODERATE/LARGE DIFFICULTY CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY COMMENTS DIFFICULTY DUE TO COUPLING SETWEEN PITCH ATTITUDE AND THRUST 5 FLIGHT PATH CONTROL latercept & initial track Intermediate track Final Irack Glide path Local zer Glide path Local zer Glide path Loca zer Intercept 6 iniho track Intermediale track Final track Glide path Loca zer G de path Localizer Glide path Localizer DIFFICULTY MODERATE MODERATE MODERATE CREAT PRECISION FAIR POOR MIN'MUM ACCEPTABLE BREAKOUT ACTITUDE F GREATER THAN 200 FEET COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT DIFFICULTY
PRECISION OF ATTAINING TOLCHOWN FOINT FOOR DIFF:CULTY 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM HAND TO COORDINATE THRUST CONTROL AND PITCH ATTITUDE CHECK MAKING LARGE CORRECTIONS, I HAD TROUBLE CONTROLLING VERTICAL SPEED WITH THRUST (AS AND PITCH ATTITUDE). LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES GOOD DAMPING IN PITCH - NO PID TENDENCY, IO. MOST OBJECTIONABLE FEATURES. DIFFIGURTY IN CONTROLLING L.A.S. AND GLIDG PATH. II MISCELLANEOUS



CONFIGURATION R19-LL WIND(knots) 5
FLIGHT NUMBER 128-2 WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION R19-1L WIND(knots)
FLIGHT NUMBER 131-2 WIND SHEAR
PILOT A EXTERNAL T WIND SHEAR MODERATE EXTERNAL TURBULENCE NECLIGIBLE PILOT B
PILOT-RATING 35C PILOT A
PILOT-RATING 31/2 CHARACTERISTIC ROOTS -.04 -.51 -1.05± 1.081 CHARACTERISTIC ROOTS -.04 -.51 -1.05 ± 1.061 I. AIRCRAFT RESPONSE TO CONTROL INPUTS Mag: 0.3 Indd/sec2\/n ZaTis Factory

SATIS FACTORY

THRUST LEVER (1/5 xc2\/n) ZaT: 15.0 (1/5 xc2\/n) [Intid F.nd]

SATIS FACTORY SATIS FACTORY SATIS FACTORY MSE D. S. EVATOR THRUST LEVER (1//sec²)/n Z81 LS.0 (1//sec²)/n Intel Find for Online SATISFACTORY SATISFACTORY SATISFACTORY CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES | Vert cal velocity (N) | VMC | 1MC | 1MC | 1MC | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0 | Description | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color | Color Langitudinal velocity (: AS)
VMC MC IN C
OU' OUT IN
NONE SLIGHT SLIGHT
\$7 - 8 Knots FLIGHT CONDITION MAXIMUM UNDESIRED FLUCTUATIONS SOME TURBULENCE UPSETS IN PITCH AND HEAVE, BUT NOT A STEADY ELEVATOR IMPUT RESULTED IN A PITCH RATE BUT THIS PRESENTED LITTLE DIPPICULTY IN A RESPECT CONTROL. TURBULENCE PRODUCED A NOTICEABLE BUT NOT A BOTHERSOME EFFECT - ESPECIALLY NOTICEABLE IN YAW. COMMENTS: SIGNIFICANT. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMP_ITUDE PERIOD PERIOD DAMPING ZERO ...<u>i</u>__ SOURCE SOURCE DEGREE EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. SMALL DIFFICULTY NEGLIGIBLE
NO DIFFICULTY COMMENTS 5. FLIGHT PATH CONTROL intercept 8 nitroi track Intermediate track Final track Glide path Localizer Glide path Localizer 6 ide path Localizer Intercept 8 initial track | Intermediate track | Final track | Gide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | DIFFICULTY NONE MODERATE NONE SLIGHT NONE NONE SLIGHT SLIGHT PRECISION 0000 POOR (2000) POOR GCOD ZAIR WINIMUM ACCEPTABLE BREAKOUT ALT TUDE
F GREATER THAN 200 FEET 300 ÓΚ ON INITIAL GLIDE PATH INTERCEPTION ME MENT HIGH AND A SCRPRISINGLY LOW THREST HAD TO BE SELECTED (APPROX. 672) DO CHT THE AIRCRAFT DESCRIPTION AT ABOUT 1000 F.P.E. APPROX. 1300 F.P.M. WAS USED AND A MEAN OF AROUT 1000 F.P.M. WAS NECESSARY. GLIDE FATH DIFFICULTY DUE TO BEING LATE, LOCALIZER TO TENDERCY TO 'S' TURN SLIGHTLY.ONE DOES NOT HAVE MUCH TIME TO 'DECIDE' TO LAND FROM A BREAKOUT HEIGHT OF 200 FT. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT RD DISFIGULTY
PRECISION OF ATTAINING TOUCHDOWN POINT GOOD NO DEFICU: TY 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS. EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FLATURES PITCH AND SPEED CONTROL QUITE SATISFACTORY THRUST LEVER SENSITIVITY SATISFACTORY, GOOD. IO. MOST IGBUECTIONABLE FEATURES # MISCELLANEOUS THUR MAY HAVE BEEN A SIMORT REGLOWING WEND. 1900 FUPLY, ON DESCENT. THRUST LEVER SENSITIVITY MUCH LOWER THAN ASI, AND WAS OK! PITCH RESPONSE TO ELEVATUR APPEARED TO BE A WEAK TO MUTERATE POTCH ATTITUDE STABILITY WITH AN UNDERLYING WEAK DIVERGENCESS QUITE REASONABLE ANYHOW, MOTIVATED TO DRIVE AIRCRAFT IN SAME WAY AS R61.



CONFIGURATION 819-2L WIND KNOTS) CALM
FLIGHT NUMBER 93-2 WIND SHEAR SMALL
PILOT 8 EXTERNAL TURBULENCE MEGLIGINGS
PILOT-RATING SD CONFIGURATION R19-2L W.ND(knots) ALMOST CALM FLIGHT NUMBER 55-1 WIND SHEAR NODERATE PILOT RATING 3 EXTERNAL TURBULENCE NEGLIGIBLE ALMOST CALM CHARACTERISTIC ROOTS -.03 -.51 -1.05± 1.071 CHARACTER-STIC ROOTS -.03 -.51 -1.05 ± 1.071 I AIRCRAFT RESPONSE TO CONTROL INPUTS Wag = 0.36 (rod/sec²)/in 281 = 15.0 (H/sec²)/-CONTROL SENSITIVITY RESPONSE : SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MA:NTAINING DESIRED VELOCITIES TURBULENCE DIFFICULTY MAX:MUM UNDESIRED FLUCTUATIONS DIFFIGURTY DUE TO THRUST EFFECTS ON FITCH ATTITUDE, ALTHOUGH NOT AS MUCH AS CONFIGURATION $1\!-\!2L$. THERE WAS A HINT OF SINK WITH DECREASING AIRSPEED AND VICE VERSA, BUT THIS WAS NOT SERIOUS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUCE AMPLITUDE PERICO JAMP NG EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED: EASE OF COMPENSATION NEGLIGIBLE NEGLIGIBLE NO DIFFICULTY DFFICULTY COMMENTS 5 FLIGHT PATH CONTROL Intercept & in-tial track intermediate track Final track
Gide path Lacalizer Glide path Localizer Glide path Localizer intercept 8 initial track | Intermediate track | Final track Guide path | Localizer | Glide path | Localizer | Glide path | Localizer DIFFICULTY SLICHT SLIGHT MODERATE | ST. ICHT SI.IGHT SLIGHT MODERATE SLIGHT PREC SIGN FAIR FAIR PAIR 3000 FAIR FAIR FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 100 I SUMK PAIRLY LOW ON THE CLIDE PATH AT THE VERY END BUT 300 PT AGE APPEARED TO ALLOW PLEXITY OF GLEARANCE TO EFFECT THE MANGEUVRES REQUIRED TO GET TO THE LANDING SPOT. DIFFIGURY DUE TO: (1) FOWER CHANGES AFFECT PITCH AND SPEED, (2) SOME TAIL WIND ON APPROACH THIS RESULTED IN A DESCENT RATE OF 1200 F.P.M. ONCE FROM AN AVERAGE OF 900 COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLIGHT
PRECISION OF ATTAINING TOUCHDOWN POINT FAIR ST.LGIT /NODERATE CIFFICULTY
FATR/GOOD DIFF CULTY THE ATRORAPT SEEMED TO BALLDON SOMEWHAT AS THE TOUGHDOWN SPOT WAS APPROACHED. (THE ATRORAPT WAS BEING ACCELERATED AT THAT TIME,) COMMENTS. DIFFICULTY DUE TO MATE OF DESCENT NOT RESPONDING AS QUICKLY TO FOWER INCREASE AS ANTICIPATED. HOMEVER, TOUGHDOWN AND PLARE WERE OK. 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I A S W TH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES ATTITUDE STABILITY PELPS. 10 MOST OBJECTIONABLE FEATURES NEED TO RETRIM EVERY TIME THE POWER CHANGES SIGNIFICANTLY. I MISCEL_ANEOUS SENSITIVE TO TURBULENCE IN REAVE AND PITCH, TAIL, BIND DID NOT AFFECT NATING. TRIM RATE TOO FAST (MRED TO TAIM A LIST DUE TO THRUST EFFECT ON PITCH - TRIM RATE SLIGHTLY TOO PAST FOR THIS CONFIGURATION AND 1-21).



CONFIGURATION RE9-2 FLIGHT NUMBER 44-3 PLOT D PILOT-RATING 6 CONFIGURATION
FLIGHT NUMBER
PLOT
PLOT-RATING WIND (KNOTE) WIND SHEAR EXTERNAL TURBULENCE WIND(knots) 5-L0
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE CHARACTERISTIC ROOTS CHARACTERISTIC ROOTS -.93 -.51 -1.05* 1.071 AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

Mag = 0.34 (rod/sec²)/in Zat = 15.0 (ft/sec²)/in Initial Final Initial Final SLIGHTLY LARGE SLICKTLY SMALL SLIGHTLY LARGE ELEVATOR THRUST LEVER (rad/sec²)/in Z₈₁ : Final (ft/sec²)/in Final CONTROL SENSITIVITY Mag = initial RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Engitudinal velocity (TAS)
VMC TMC TMC
OUT OUT IN Vertical velocity (h)
C IMC I I M C COMMENTS: DIFFICULTY DUE TO LACS IN INITIAL RESPONSE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE DAMPING AMPLITUDE EXC TATION CONTROL COMMENTS AIRCRAFT FELT SLIGHTLY SLUGGISH IN PITCH AND IN HEIGHT CONTROL. 4 CHANGE N THRUST REQUIRED FOR 20° BANKED TURNS SMALL/MODERATE
SLIGHT/MODERATE D.FFICULTY CHANGE REQUIRED EASE OF COMPENSATION D FFICULTY COMMENTS 5. FLIGHT PATH CONTROL Intercept & miliol track Intermediate track Final track Glide path Localizer Glide path Localizer Glide path Localize intercept 8 initial track infermed ate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY > SLIGHT | > SLIGHT | MODERATE | MODERATE SLIGHT NONE FAIR FAIR FAIR FAIR 2008 P00 R MINIMUM ACCEPTABLE BREAKOUT ALTITUDE DIFFIGURTY DUE TO OVERCONTROL WITH TERRST LEVER. ALSO I BELIEVE PILOT PATIGUE IS A FACTOR. GUESS I AM SATURATED. COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT S.TONT DEFICULTY PRECISION OF ATTAINING TOUCHDOWN POIN FAIR DIFFICULTY COMMENTS 7. CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM I.A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUS' 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES ATTITUDE CONTROL WAS FAIR, C. MOST CRUECT CHARLE FEATURES POWER MANTEDLATION WAS SOMEWHAT EXCESSIVE - POSSIBLY A DENDERCY TO OVERGONIZOL EXISTED. I MISCELLANEOUS ALRO-APT IS DOWNGRADED MAINLY BUE TO POOR TRACKING NAME TOUGHOUGH (MMS FORTHORY). UP AND ANY THE PILOT PERFORMANCE AS ADE HATE. CATTER CAUGE POSSIBLY BE 6.



CONFIGURATION RL9-3L FLIGHT NUMBER 108-3 PILOT A PILOT-RATING 85

WIND(NOTS) L0-15
WIND SHEAR MODERATE
EXTÉRNAL TURBULENCE LIGHT

CONFIGURATION 819-31, WIND (knots) CALM
FLIGHT NUMBER 100-3 WIND SHEAR SMALL
PILOT-RATING 458

WIND SHEAR HEGLIGIBLE
EXTERNAL TURBULENCE HEGLIGIBLE

CHARACTERISTIC ROOTS -.02 -.54 -1.05 ± 1.061

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

ELEV		THRUST LEVER		
M8E: 0.34	(rad/sec2)/m	78T - 15.0	(11/sec ²)/in	
Initia	Fino!	Initial	Final	
SATISFACTORY	TOO GREAT	SAT15FACTORY	TOO GREAT	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT	CONDITION:	
TURBUL	ENCE:	
DIFFICU	_TY	
*** ****	I INCCORE	CLUCTUATIONS

1	Longitus	dinal veloc	ity (1AS)	Verli	car velocity	(fis
	y.vc	I.M.C	I.M.C	VMC	MC	T M.C
	OUT	OUT	IN	QUT	Out	IN
	MODERATE	GREAT	CREAT	MODERATE	GREAT	GREAT
5 !		=12	krats	± 300		f.pm

RESPONSE

AIRSPEED EFFECTS ON NORMAL FORCES VERY BOTHERSONE. MORMAL FORCE INCREASES WITH AIRSPEED CAUSING INSTABLLITY AND UNPREDICTABLE RATES OF CLIME. TURBULENCS IN REAVE ALSO VERY 30THERSOME.

Initial Final Initia Final
SATISFACTORY SATISFACTORY SATISFACTORY

CHARACTERISTIC ROCTS -.02 -.54 -1.05 ± 1.061

Long tud not velocity ([AS]			Ver	ico velocity	(h)
V M C	ÍMIC	IMC	V.M.C	TMC	I M C
CUT	001	IN	007	DJT	IN
SLIGHT	SLIGHT	SLICHT	SLIGHT	SLIGHT	SLIGHT
+14	, -5	knots	±200		fp m

DIFFICULTY GAUSED BY TENDENCY TO PUT NOSE DOWN IF HIGH ON GLIDE SLOPE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH HEAVE

AMPLITUDE	PER-CD	DAMPING	
SMALL	SHORT	HIGH	
ZERO			
SOURCE		DEGREE	

AMPLITUDE DAMPING SOURCE DEGREE

EXCITATION COMMENTS

ON UCCASION PITCH ATTITUDE COMMAND APPEARED TO BE PRESENT BUT IT WAS RATHER SLOPPY AND TENDED TO BOUNCE BACK. FELT SPONGY THROUGHOUT,

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

MODERATE	
MODERATE	OIFF IÇULT Y

COMMENTS

AIRSPEED CONTROL WAS NOT GOOD AND THIS REQUIRED POWER CHANGES WRICH NEEDED TOO MUCH ATTENTION TO REIGHT CONTROL.

SMALL	
SLIGHT	CIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY.

Intercept B.	mitral track	Intermediate track		Final track	
Glide path	Local-zer	Glide path	Local ger	Slide poth	Loca zer
MODERATE	MODERATE	GREAT	MODERATE	MODERATE	GREAT
POOR	POOR	POO R	POOR	VERY POOR	VERY POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 700

DIFFIGULTY CAUSED BY WIND SHEAR, TURBULENCE AND AIRSPEED - VERTICAL SPEED INTERACTION.

	in tial track			Final track	
Slide path	~0€0-156L	G de path	Lacolete-	Glide path	Locouzer
SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
FAIR	FAIR	FAIR	FAIR	FATR	FAIR

300

WIND CONDITION REQUIRES HIGH RATES OF DESCENT, GENERALLY HIGH ON THE GLIDESLOPE, SPEED CONTROL POOR BECAUSE OF TENDENCY TO PUT MOSE DOWN TO CORRECT GLIDESLOPE ERROR,

MODERATE DIFFICULTY

HENGE RECOMMENDED BREAKOUT HEIGHT.

HIGH RATES OF DESCENT NOT PLEASANT NEAR THE GROUND -

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

	NO	DIFFICULTY
ı	FAIR/GOOD	

COMMENTS:

7 CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SMALL

9 LEAST OBJECTIONABLE FEATURES SATISFACTORY ATTITUDE STABILITY.

IC MOST CBUECT CNABLE FEATURES

THRUST LEVER SENSITIVITY WAS POSSIBLY A LITTLE HIGH AND MAY HAVE CONTRIBUTED TO AN OSCILLATION DOWN CLIDC.

I MISCELLANEOUS

TURBULENCE NOT NOTICED.



CONFIGURATION R19-3L FLIGHT NUMBER 123-1 PILOT C CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING WIND(knois) 5 WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT WIND (knots) WIND SHEAR EXTERNAL TURBULENCE PILOT C PLOT-RATING 7 CHARACTERISTIC ROOTS CHARACTERISTIC ROOTS -.02 -.54 -1.05 ± 1.061 AIRCRAFT RESPONSE TO CONTROL INPUTS (rod/sec²)/m Z8T = 15.0 ELEVATOR SE = (rod/sec2)/in ZaT = | SE E VATOR | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | THR. | T THRUST FVER (#/sec²)/in Final CONTROL SENSITIV TY: 2.EASE OF MAINTAINING DESIRED VELOCITIES VMC FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS DIFFICULTY DUE TO EFFECT OF AIRSPEED ON CLIMB OR SINK IF THROTTLE LEFT ALONE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PITCH DEGREE SOURCE DEGREE EXCITATION CONTROL COMMEN'S NO NOTICEABLE OSCILLATORY CHARACTERISTICS, AUTHOUGH THEY COULD HAVE BEEN MASKED BY THE EFFECTS OF THE MARGINAL EXTERNAL TURBULENCE LEVEL. 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION SMALL
MODERATE OFFICULTY DIFFICULTY COMMENTS EFFECT OF BANK ANGLE INSIGNIFICANT IN COMPARISON WITH EFFECT OF ATREPED VARIATIONS. 5 FLIGHT PATH CONTROL Intercept B mitol track Intermediate track Final track
Slide poth Localizer Glide poth Localizer Intercept 8 initial track Intermediate track Final track
Gide path Localizer Glide path Localizer Glide path DIFFICULTY GREAT SLIGHT SLIGHT SLIGHT MODERATE SLIGHT PRECISION VERY POOR SAIR COOD 6035 PAIR MINIMUM ACCEPTABLE BREAKOLT ALTITUDE IF GREATER THAN 200 FEET COMMENTS INITIAL DIFFICULTY IN MAINTAINING BEIGHT PRIOR TO ACQUISITION OF GLIDE FATH, CONSIDERABLE HEIGHT LOSS ON TURNING TO BASK LEG DUE TO DEFINONTROLLING WITH THROTTLE IN COMPRESATING FOR ALBSPEED CHARGES. CAPTURED CLIDE PATH AT 1100 FEST. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF OCSCENT SLIGHT DIFFICULTY
PRECISION OF ATTAINING TOLCHDOWN POINT GOOD DIFFGULTY USE OF PORMARD STICK TO MAINTAIN AIRSPEED AND THROTTLE TO ARREST RATE OF DESCENT RELATIVELY EASY UNDER $\nu_{\rm A}$, C. CONDITIONS. COMMENTS -7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFEECT ON FINAL ASSESSMENT 9 LEAST OBJECT ONABLE FEATURES VMC OPERATION CONSIDERABLY LESS DIFFICULT THAN LMC. LARCE MANIFOLD PRESSURT FLUCTUATIONS WITH AIRSTREED GLARGES CARSING LARGE CORRECTIONS WITH TRUSTILL OR STYREAL ORDANIONS TO AVOID DV-R BOOSTING ENGINE, RESULTING IN HEIGHT LOSS. IC MOST CBUECT CNABLE FEATURES II MISCELLANEOUS *FFECT OF EXTERNAL TURBULENCE APPROACHING LIMITS OF TOLERANCE (NO FORTHER EVAL ATIONS). PIGHT HAVE OVER A ARTEN OF 6 17 LESS CONCERNED WITH OVER SCOTTING EXCITAT



CONFIGURATION A19-3L FLIGHT NUMBER 109-2 PILCT A PILOT-RATING 7

WIND(knats) WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION A19-3L WIND (knots)
FLIGHT NUMBER 102-1 WIND SHEAR
PILOT B EXTERNAL TU
PILOT-RATING 3C

WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROCTS __.02 __.54 __1.05 ± __1.061

AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE.

ÉLE	VATOR	THRUS	T_LEVER
Mag = 0.34	(rad/sec2)/in	Z8T= 15.0	(ft/sec ²)/in
Init-al	Final	Initial	Finel
SATISFACTORY	SAT IS FACTORY	SAT LS FACTORY	SAT IS FACTORY

2 FASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT C	ONDITION	
TURBULE	NCE.	
DIFFICULT	Y	
MUM:XAM	UNDESIRED	F_UCTUA*IONS

ſ	Langitudinal velocity (IAS)			Verl	ico velocity	(ĥ)
- [VMC.	DMI	LMIC	VMC	I.M.C	TM C
- [QUT	OUT	IN	OUT	OJT	IN
1	SLIGHT	MODERATE	MODERATE	SLICKT	MODERATE	GREAT
s l		+10	knols	± 300		f.pn

AIRSPECD SPECT ON POWER CAUSED DIFFICULTIES IN CONTROLLING BOTH AIRSPEED AND WESTICAL SPEED, ON THE APPROACH THE AIRSPEED BUILT UP CAUSING AN INCREASE IN LIFT WHICH ARRESTED THE BATE OF DESCENT,

ELEVATOR

MBE = 0.34 (rod/sec²)/in ZBT = 15.0 (ft/sec²)/in lot in tid Final (n.1) Final SATISFACTORY SATISFACTORY SATISFACTORY

CHARACTERISTIC ROOTS -.02 -.54 -1.05 ± 1.061

Longi*u	dinal veloci	ity (IAS)	Vert	ical velocity	(h)
V M.C	LMC	I'MC	VMC	EMC	INC
OUT	OUT	IN	OUT	TLO	IN
SLICHT	SILIGHT	SLIGHT	SILIGHT	SLIGHT	SLIGHT
	± 5	knots	ок		'pır

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXC. TATION

COMMENTS

COMMENTS

COMMENTS:

AMPLITUDE	PER OD	DAMPING
ZERO		
ZERO		J
20.055		- DECONE
SOURCE		DEGREE
SOURCE		DEGREE

AMPLITUDE	PERIOD	DAMP NG
ZERÓ		
Z.E.RO		
SOURCE		DEGREE
k		

Intercept 6 initial track intermediate track Final track
Gilde path Localizer Glide path Localizer Glide path Localizer

FAIR/GOOD FAIR/GOOD FAIR/GOOD FAIR/GOOD FAIR/GOOD FAIR/GOOD

DIFFICULTY

SLIGHT

SLIGHT

SLIGHT SLIGHT SLIGHT

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION:

MODERATE DIFFICULTY

NO PROBLEM IF AIRSPEED IS MAINTAINED IN TURNS, BUT AIRSPEED ERRORS INDUCE LARGE LIFT CHANGES.

VERY SMALL SLIGHT D-FFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermed.		Final	track
Slide poth	Localizer	Glide parh	Localizer	Grde path	Localizer
SLIGHT		MODERATE	SLIGHT	GREAT	MODERATE
		200 R	FAIR	VERY POOR	POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 700

COMMENTS:

COMMENTS

SEE SECTION 2. ALSO WIND SHEAR CAUNED LOCALIZER PROBLEM. AIRSPEED INCREASED TO 70 KNOTS AT ABOUT 500 FEET, CAUSING THE HATE OF DESCENT TO DEGREASE, AND THE AIRCRAFT TO GO HIGE ON THE GILDE PATH.

6 BREAKOUT AND FLARE

EASE OF AFRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT FATR/CODB

SLIGHT FAIR/GOOD

SLIGHT

0.%.

7. CONTROL TECHNIQUE

COMMEN'S IF DIFFERENT FROM I AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

NONE

9 LEAST OBJECTIONABLE FEATURES

ATTITUDE STABILITY GOOD FOR THIS TASK. EASY TO MAINTAIN SPEED AND TO MAKE SPEED CHANGES.

O MOST OBJECTIONABLE FEATURES

ONLY A SLIGHTLY NOTICEABLE BUT ACCEPTABLE COUPLING EFFECT BETWEEN AIRSPEED AND VERTICAL SPEED CHANNELS.

II MISCELLANEOUS

THE TURBULENCE WAS CAUSING THE MANIFOLD PRESSURE NEIGHT TO MHIP ABOUT VISCIOUSLY AND THIS WAS BOTHERSOME.

GOOD RELAXED APPROACH WITH LOW LEVELS OF CONTROL ACTIVITY.



CONFIGURATION R8L FLIGHT NUMBER 78-1 PLOT A PILOT-RATING 4½

LIGHT WIND SHEAR NECLIGIBLE EXTERNAL TURBULENCE LIGHT

CHARACTERIST C ROOTS -.04 -.26 -1.05 ± 1.061

CONFIGURATION R8L
FLIGHT NUMBER 38-3
PHOT B
PILOT-RATING 6C

WIND (knots) LO-L5 WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS -.04 -.26 -1.05 ± 1.061

LAPRORAFT RESPONSE TO CONTROL INPUTS

CONTROL SENS-TIVITY RESPONSE

ELEV	ATOR	THRUS	T LEVER
Mag = 0.34	(rad/sec ²)/in	Z _{δT} = 15	(tt/sec ² i/in
Initial	Fing'	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIO

	Long-tu	Long-tudinal velocity (TAS)			Vertical velocity (h)		
	_V.M.C.	IMC	I.M.C	VMC	I.M.C	1.M C	
	Ou†	OUT	IN	OUT	OUT	iN i	
	SLIGHT	MODERATE	MODERATE	SLIGHT	SLIGHT	SILIGHT	
ONS		± 5	knats	0 K		(pm	

COMMENTS

THE PITCH ATTITUDE STIFFNESS COULD HAVE BEEN MUCH STRUNGER TO CLAMP THE ATTITUDE WHERE IT IS PUT. AIRSPSED CONTROL REQUIRES TOO MUCH ATTENTION.

	VATOR	I THRUST LEVER		
M8E: .39	(rad/sec2)/in	Z87: 11.9	[ft/sec2]/in	
Initial	Final	Initial	Final	
SATISFACTORY	SATISFACTORY	SATISFACTORY	NOT ASSESSABLE	

Γ	Longitudinal velocity (JAS)			Vertical velocity (h)		
	VMC	TMC	IMC	V.M.C	IN C	LMC
	OLT	OUT	ΙN	700	100	IN
-	MONE	NONE	SLIGHT	SLIGHT	SLIGHT	SLIGHT
Г	+1	0, -5	knois			fp m

REASON FOR HEAVE DIFFICULTY WAS THAT THE FINAL RESPONSE TO THRUST LEVER WAS UNKNOWN.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION

CONTROL COMMENTS

AMPLITUDE ZERO	FERIO	C	CAMP:NG
ZERO			
SOURCE		DE	GREE
t			

 AMPL TUDE	PERIOD	DAMPING
 ZERO		
 ZERÓ		
	<u></u>	
 SOURCE	· · · · · · · · · · · · · · · · · · ·	DEGREE.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMALI.
SILIGHT DIFFICULTY

POWER WAS REQUIRED BUT IT WAS NATURAL AND EASILY LEARNED.

SOME
SLIGHT/MODERATE DIFFICULTY

NOT ENOUGH TIME TO THOROUGHLY INVESTIGATE THE SOURCE OF THE PROBLEM. THERE APPEARS TO BE A MORMAL FORCE DUE TO ROLL RATE BUT IT IS PROBABLY DUE TO ANGLE OF ATTACK.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept & initial track				Final trask	
Glide path	Loca'izer	Glide palh	l.ocol.zer	Glide path	Lacalizer
SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
6000	COOD	GOUD	G00D	COOD	GOOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

COMMENTS

Intercept & initial track interme Glide path Localizer Glide path Final track Localizer Glide path Localizer NONE NONE NONE NONE SLIGHT 3000 GOOD FAIR/GOOD FAIR/GOOD FAIR/GOOD PAIR/GOOD

THE LOCALIZER MENT TO FULL DEPLECTION BRIDW 300 FF. THE TALAK SENSITIVITY IS TOO RIGH BRIDW 300 FT IN THE PRESENCE OF MORE EXTENSIVE CROSS-CHECK REQUIREMENTS ON GLIDE SLOPE.

6 BREAKCUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT	NO DEFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT	COOD

COMMENTS

SLIGHT DEFICULTY
FAIR/000D

RESPONSE TO THRUST LEVER UNCERTAIN AGAIN, AS FOR MODEL # 9 . MATE OF SINK AT TOUCH DOWN WAS OK BUT WAS NOT PRECISELY UNDER CONTROL.

7. CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST CEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

FIXED-WING TECHNIQUE SUBCONCIOUSLY USED TO RETAIN GLIDE PATH IN THE PRESENCE OF POOR THRUST LEVER CHARACTERISTICS. THIS RESULTED IN SOME PROBLEM WITH SPEED.

NONE

309

GOOD PITCH ATTITUDE STABILITY.

IO MOST OBJECTIONABLE FEATURES

9 LEAST OBJECTIONABLE FEATURES

UNCERTAIN REAVE CHARACTERISTICS ESPECIALLY INTURBULENCE.

II MISCELLANEOUS

ELEVATOR TRIM RATE TOO FAST.
MENTAL ASSESSMENT REQUIRED OF WHAT TO DO TO KEEP THE
SAME CLIDE SLOPE WHILST ABJUSTING TO A NEW, CORRECT



CONFIGURATION R8L FLIGHT NUMBER 43-1 PILOT D PILOT-RATING 6 W-ND(knots) 5
WIND SHEAR SHALL
EXTERNAL TURBULENCE LIGHT/MODERATE WIND(snots) 0
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION REL FLIGHT NUMBER 99-3 PILOT C PILOT-RATING 48 CHARACTERIST C ROOTS -.04 -.26 -1.05 1 L.061 CHARACTERISTIC ROOTS __.04 __.26 __-1.05 ± ___1.061 I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

Mag: 0.3 (rad/sec²)/m Za++7.4 (11/sec²)/m CONTROL SENSITIVITY Fing India TOO CREAT TOO SMALL SATISFACTORY SATISFACTORY TOO SMALL TOO SMALL TOO GREAT TOO GREAT RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS SPEED AND ALTITUDE OFTEN CONSTANT FOR CONSIDERABLE FERIODS, BUT SOME DIFFICULTY WAS EXPERIENCED IN CHANGING FROM ONE CONDITION TO ANOTHER. DIFFIGULTY DUE TO LAG IN RESPONSE TO PILOT'S IMPUTS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERICO MEDIUM MEDIUM AMPLITUDE DAMPING AMP, ITUDE ZE30 DAMPING PERIOD HEAVE DEGREE SOURCE DE GHEE SOURCE EXC:TATION MODERATELY EFFECTIVE COMMENTS UNCERTAIN OF HEAVE OSCILLATION, BUT 1 MAD THE IMPRESSION THAT THERE WAS SOME NEGATIVE RESPONSE IN HEAVE WHEN THE IT SEEMED SLIGHTLY STATEGALLY UNSTABLE - AT LEAST IT WAS DIFFICULT TO PIND THE TRIM POINT. AIRCHAFT WAS PITCHED. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION MODERATE OFF CULTY DIFFICU_TY DIFFICULTY DUE TO LAG IN NOTICEABLE RESPONSE. COMMENTS 5. FLIGHT PATH CONTROL Intercept & initia: track | Intermedia Glide path | Locolizer Glide path ofe track Final track
Localizer Glide path _2001 zer Intercept & initial track | Intermediate track | Final track | Slide path | Localizer | Glide path | Localizer | Glide path | Localizer | DIFFICULTY SLIGAT SLIGHT MODERATE SUIGHT MODERATE SLIGHT SUIGHT > SLIGHT > SLIGHT | > MODERATE > MODERATE PRECISION FAIR G00D ₹**A** LR FAIR GOOD GOOD FAIR G000 FAIR FAIR POOR POOR MINIMUM ACCEPTABLE BREAKOU" ALTITUDE COMMENTS DIFFICULTY DUE TO PLLOT BEING BEHIND THE AIRPLANE. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SLECHT DIFFICULTY PRECIS ON OF ATTAINING TOUCHDOWN POINT FAIR DIFFICULTY MADE A TWO STEP LEVEL OFF, ie. AIRSPEED WAS TOO LOW AND I ANTIGIPATED. THE THRUST APPLICATION TOO MUCH. COMMENTS 7 CONTROL TECHNIQUE COMMENTS F CIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST THERE DEPINITELY SEEMED TO BE A COUPLING BETWEEN PITCH ATTITUDE AND THRUST LEVER IN CONTROLLING ATREPEED AND VERTICAL VERDILLY. LEVER 8 . AFERA: DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SMALL: CHARACTERISTICS WERE NOTICEABLE IN TURN COORDINATION, 9 LEAST OBJECTIONABLE FEATURES ASILITY TO COMPLETE APPROACH, BUT WITH CONSIDERABLE CONCENTRATION. NO PITCH OSCILLATION. IO MOST OBJECTIONABLE FEATURES MODEL RESPONSE TO SHARPER PITCH INPUTS WAS UNPLEASANT DUE TO UNEXPECTED STAVE BEHAVIOUR. MORE PRECISION OF AIRSPEED AND VERTICAL VELOCITY, OVERCONTROL DUE TO LAG IN NOTICEABLE RESPONSE TO PILOT INPUTS.

MODEL MIGHT BE IMPROVED BY SMALL BREAKOUT FORCE,

I MISCEL_ANEOUS



CONFIGURATION R8
FLIGHT NUMBER 42-2
PILOT D
PILOT-RATING 74 WIND(xnots) 0
WIND SHEAR VERY SMAIL
EXTERNAL *URBULENCE MODERATE CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING WIND (knots)
WIND SHEAR
EXTERNAL TURBULENCE 0 VERY SMALL CHARACTERISTIC ROOTS -.04 -.26 -L.05 - 1.061 CHARACTERISTIC ROOTS LAIRCRAFT RESPONSE TO CONTROL INPUTS THRUST LEVER

(1//sec2/in
of Final
NALL TOO GREAT ELEVATOR THRUST LEVER (ft/sec²)/in Final (rad/sec2)/in MBE: CONTROL SENSITIVITY: 781: hortial TOO SHALL RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION-TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS IN DIFFIGULTY DUE TO SUBSTANTIAL LAG BETHEEN CONTROL APPLICATION AND NOTICEABLE RESPONSE IN AIRSPEED AND VERTICAL VELOCITY. THIS WAS COMPLICATED BY LARGE LATERAL MANDEUVRES. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS DAMPING MODERATE CEGREE DESREE SOURCE EXCITATION CONTROL COMMENTS HAD TROUBLE IN ACHIEVING STEADY STATE VERTICAL VELOCITIES BUT I CANNOT CALL IT USCILLATORY. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED BASE OF COMPENSATION MODERATE/LARGE DIFFICULTY D-FFIGULLY COMMENTS 1 AM BEHIND THE AIRPLANE. VERTICA' VEHICLEY CHANGES SHOWLY INSTRALLY AND IT DAKES TIME TO NOTHER IT. 5. FLIGHT PATH CONTROL. Intercept & milial track | Intermediate track | Final track Glide path | Loca izer | Glide path | Loca izer | Clide path | Localizer Final track e poth Laca Fer Intercept & initial track intermediate truck Fina Glide path Localizer Glide path Localizer Glide pat SLIGHT SLIGHT > SLIGHT | SHIGHT | > HODERATE | > MODERATE FAIR/FOOR FAIR 2008 W NIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 HLET DIFFIGURITY PROBABLY DUE TO OVERCONTROL OF ELEVATOR AND PRIBUSE CONTROL AND TO THE PILOT BEING BEHIND THE AIRP AND. 6 BREAKOUT AND FLARE EASE OF ANNESTING MATE OF DESCEN.

SELENT/MODERATE OFFICELTY
PRESSOR OF ATTAINING TOJOHDOWN FOINT

PALE

SELENT/MODERATE OFFICELTY DIFF CLLTY DIFFICULTY DIE TO WORKYING ABOUT 1.0% 1.4.S. - THE.E. SEEMED TO BE A 1.4G IN THRUST LEVER RESPONSE. 7 CONTROL TECHNIQUE COMMENTS OF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTERISTICS 9 LEAST OBJECTIONABLE FEATURES GOOD PITCH DAYPING. C. MOST CBUECTIONABLE FEATURES THE MECH CONTROL MANAPERATION WAS REQUIRED AND STILL THE PERMERANCE WAS NOT CONSTITUED WHILE THE PERMERANCE WAS NOT CONSTITUED. ii ▼ SCELLANECUS POWER AND TAS GOTT OUT OF HAND ON FINAL. I TO NOT SEED MAY, BUT THE SAFETY PITCH THICK OMER. MAYBE I WINE BEYOND LIDITS OF MODIL ON THE ST. LEVER.



CONFIGURATION ABL FLIGHT NUMBER BO-L PILOT A PILOT-RATING 35

WIND(knots: 10
WIND SHEAR
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS -.04 -.26 1.05 ± 1.061

CHARACTERISTIC 4001\$

CONFIGURATION ABL FLIGHT NUMBER 85-1 PILO" 3 PILOT B PILOT: RATING 60

WIND(knofs) WIND SHEAR BEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

-.04 -.26 1.05 ± 1.061

I AIRCRAFT RESPONSE TO CONTROL IMPUTS

CONTROL SENSITIVITY:

ELE	VATOR	THRUŞ	
MBE = 0.34	[rad/sec ²]/in	Zat - 11.9	(ft/sec2)/in
Instial	Final	Initia	Final
SATISFACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

*URBULENCE: DIFFICULTY MAXIMUM UNDES RED FLUCTUATIONS

Longilus	dino velocii	y (1AS)	Vert	ecal velocity	(h)
V.M.C.	1M°C	[M-C	VMC	TAC	I M C
DUT	OUT	IN	OU.	OUT	IN
NONE	SLIGHT	SLIGHT	NONE	NONE	NONE
+5	0	knols	C K		f pm.

RESPONSE

ELEV	FOTA		LEVER
MaE: 0.25	(rod/sec2)/in	ZaT: 11.9	(ft/sec ²)/in
Initial	F⊹nal	Initial	Final
SATISFACTORY		SATISFACTORY	TOO GREAT

Longitu	dinal veloci	ty (IAS)	Vert	cal velocity	(e)
V.M.C	LMC	IMC	VVC	IMC	1 M C
OUT	CUT	IN	QLT	QLT	IN.
NONE	NONE	NONE	SLIGHT	SLIGHT	SLIGHT
	+36	knois	+300		f c m

DIFFICULTY DUE TO APPARENTLY HIGHER THAN NORMAL THRUST LEVER SENSITIVITY AND LOWER THAN NORMAL HEIGHT RATE DAMPING.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE	PERICO	DAMP, NG
SMALL	SHORT	MODERATE
SMALL	SHORT	MODERATE
SOURCE		DEGREE
ELEVATOR		MODERATELY
NOT ATTEMPTED		

EXCITATION COMMENTS

A SLIGHT NIBBLE OF AN OSCILLATION WAS EVIDENT WHEN THE FITCH CONTROL WAS MOVED RAPIDLY, BUT THIS SEEMED TO BE MORE OF A REAVING MOTION.

AMPL TUDE	PERIOD DAMPING
ZERO	
ELNO	
SOURCE	CEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MODERATE SUIGHT DIFFICULTY

COMMENTS

IF AIRSPEED IS GOOD, THE ALTITUDE STICKS ON THE DESIRED VALUE. HURING THE FIRST TURN THE AIRSPEED DECREASED TO 55 KNOTS AND THE VERTICAL SPEED WENT TO 300 F.P.M. DOWN.

DIFFICULTY DIFFICULTY DUE SIMPLY TO COORDINATION.

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

		Intermediale track		rmediale track Final tro	
Glide path	Lacalizer	Gide path	Localizer	Glide col	Locolizer
NONE	SLIGHT	NONE	SLICHT	NONE	NONE
COOD	FAIR	SOOD	FAIR	GOOD	GOOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

COMMENTS

Intercept & initial track | Intermediate track | Final Glide path | Localizer | Glide path | Localizer | Glide path | lrack Localizer SLIGHT HONE SLIGHT SLIGHT NONE 6000 GOOD GOOD

ALTHOUGH TURBULENCE BOTHERED ENGINE POWER SETTINGS QUITE SIGNIFICANTLY, IT DID NOT UPSET PITCH ATTITUDE OR VERTICAL VELOCITY VERY MUCH - EASILY ABLE TO FIND AND MAINTAIN GOOD VERTICAL VELOCITY.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF ATTAINING TOUCHDOWN POINT GOOD

COMMENTS:

FROM EXPERIENCE WITH A PREVIOUS SIMILAR MODEL AND THE HIST OF AN OSCILLATION, CARE WAS TAKEN NOT TO PITCH THE AIRCRAPT DURING THE LEVELLING OFF PROCESS.

MODERATE DIFFICULTY

MAD HIGHER THAN NORMAL OR WANTED RATE OF DESCENT AT TOUCHDOWN - DUE TO IMPROPERLY COMPENSATING FOR APPARENT LOW HEIGHT BATE DAMPING.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LA.S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

NONE

300

9 LEAST OBJECTIONABLE FEATURES

AIRSPEED CONTROL WAS QUITE EASY.

VERY GOOD AND STIFF PITCH ATTITUDE HOLD.

IC. MCST_OBJECT:ONABLE_FEATURES

THE PITCH ATTITUDE DOES NOT CHANGE THE AUTITUDE AT ALL, BUT JUST THE ALRSPEED, THERE IS A STRANGE SERSATION WHEN, FOR INSTANCE, THE MOSE IS PUBLIC UP AND THE ACCELERATION IS DOMMARDS.

APPARENT LOW HEIGHT RATE DAMPING. ARTIFICIAL TURBULENCE CAUSED SIGNIFICANT, BOTHERSOME ENGINE TRANSIENTS.

.I MISCELLANEOUS

SLEVATOR CONTROL FORCES ARE TOO RICH FOR THIS LEVEL OF STABILITY.



CONFIGURATION R8-IL FLIGHT NUMBER 131-3 PILOT A PILOT-RATING 4 WIND(knois) 10
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MEGLIGIBLE CHARACTERIST C ROOTS -.03 -.28 1.05 1.061 LAIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

MBE = 0.3 [rad/sec²]/n ZBT = 11.9 (fr/sec²/n Institut Final CONTROL SENSITIVITY RESPONSE. SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (TAS)
VMC IMC IM C
OUT OUT :N
NONE SLIGHT SLIGH FLIGHT CONDITION-TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS MAIN REASON FOR VERTICAL SPEED PROBLEM WAS THAT THERE MUST HAVE SEER A POLLOVING WIND WHICH MEGESSITATED A DESCENT RATE GREATER FRAN 1000 F.P.M. TO HOLD THE CLIDE PATH. ALRSPEED HOLD WAS QUITE GOOD BUT DID REQUIRE MUCH CONCENTRATION. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD HEAVE

CHARACTERISTIC ROOTS -.03 -.28 1.05 ± 1.061

CONFIGURATION RB-IL FLIGHT NUMBER L28-3 PILOT B

PILOT B PILOT-RATING 40

Longilui	dinal velaci	y ((45)	Vert	ical velacity	(h)
VMC	LMC	: MC	V.M.C	LMC	J M.C
OUT	QUT	N	OUT	OLT	:N
V. SLIGHT	V. SLIGHT	V. SLIGHT	V. SLIGHT	V. SLIGHT	V. SLIGHT
	± 6	knots	DK		fρm

WIND (knots) 5
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE

AMPLITUDE DAMPING DAMPING SOURCE DEGREE SOURCE DEGREE ELEVATOR ELEVATOR EASILY INEFFECTIVE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

5 FLIGHT PATH CONTROL

NEGLIGIBLE

DIFFICULTY

THE OSCILLATION ONLY OCCURRED AT TOUCHDOWN (SEE SECTION #6)

COMMENTS

EXCITAT ON

CONTROL COMMENTS

Intercept 8 in tial track intermediate track. Final track Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY PRECISION FAIR FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 300 TO 400

200 FT WOULD PROBABLY BE OK WITHOUT A FOLLOWING WIND (SURFACE WIND WAS IN CURRECT DIRECTION). COMMENTS

Intercept & initial track				Final track	
Glide path	Local-zer	Glide path	Localizer	Glide palh	Localizer
NONE	NONE	NONE	NONE	SLIGHT	NONE
GOOD	0000	G00D	GOOD	FAIR	GOOD

DIFFICULTY

0 K

NONE

NO GOOD

NEGLIG1 BLE

ONLY DIFFICULTY DUE TO TALAK SENSITIVITY ON FINAL TRACK - 'S' TURN TENDENCY ON LOCALIZER.

DIFFICULTY!

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT MODERATE
PRECISION OF ATTAINING TOUCHDOWN POINT POOR.

COMMENTS

GOT INTO A PIO IN PUTCH. THE ATTITUDE CHARGES RAPIDLY IMMEDIATELY POLLOWING AN ELEVATOR IMPUT AND THEN RATE SLOWS DOWN. WITHOUT THIS OSCILLATION WOULD PROBABLY BE RATED 3.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERT CAL SPEED WITH THRUST

LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IC MOST OBJECTIONABLE FEATURES

I. MISCELLANEOUS

WITHOUT CRCILLATION (SECTION #6) WOULD PROBABLY HE RATED 3.

SHE SECTION OF.

COOD HEIGHT CONTROL - MINIMAL THRUST CONTROL ACTIVITY ON DESCENT (APPROX. 850 F.P.M.) RESPONSE TO TURBULENCE ROT SIGNIFICANT.

PITCH RESPONSE - INITIALLY SATISFACTORILY RAPID, DECAYING TO WEAK DIVERGENCE - REASONABLE TO TRIM. THIS AND BODELENGHLE TO SERVE LANCE AGGRESSIVE ELEVATOR CONTROL THRUTS TO ADJUST SPEED, WANT TO "BANNER" IT AROUND DURING MANUSUVES.

209

MODERATE



CONFIGURATION A8-IL FLIGHT NUMBER 131-1

PILOT-RATING

WIND(knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION A8-IL FLIGHT NUMBER 128-1 PILOT B PILOT-RATING AD

TOD GREAT

WIND (knots)

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS

-,28 1.05 ± 1.061 -,03

CH4RACTERISTIC ROOTS -.03 -.28 1.05 ± 1.061

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELE	VATOR	THRUS	T LEVER
V8E = 0.3	(rad/sec ²)/in	Zar= 11.9	(11/sec ²)/ n
Initial	Final	Initial	Final
SATIS FACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

COMMENTS

TURBULENCE DIFFRUITY MAXIMUM UNDESIRED FLUCTUATIONS

	Longitu		ity (1AS)	Vert	cal velocity	(h)
Е	v.m.c	MC	IMC	VMC	IMC	[MC
Е	OUT	OUT	IN	CUT	Out	IN
	NONE	SLIGHT	MODERATE	NONE	NONE	SLIGHT
Г	+1	.0, -5	knats	200	•	'pm

Longitudino velocity ((AS) ± 250 to m

TOO GREAT SATISFACTORY TOO GREAT

THE ALRSPEED GOT UP TO 70 KNOTS AND THE BATE OF DESCENT FELL OFF ON APPROACH CAUSING FAIRLY LARGE DEVIATIONS FROM GLIDE PATH. AIRSPEED CONTROL WAS MAIN PROBLEM - ATTITUDE HOLD FELT GOOD BUT DID NOT PRODUCE A GOOD AIRSPEED HOLD.

DIFFICULTY DUE TO: (1) HIGH THRUST LEVER SENSITIVITY (2) LARGE AMOUNT OF PITCH STABILITY MAKES IT DIFFIGULT TO ADJUST SPEED AND YET SPEED STILL VARIED ON DESCENT.

3. RES-DUAL OSCILLATORY CHARACTERISTICS

PITCH

EXCITATION. CONTROL COMMENTS

AMPLITUDE	PERIOD DAMP	ING
2ERO		
ZERO		
SOURCE	DEGREE	
~		

AMPLITUDE	PERI	00	DAMPING
ZERO			
ZERO			
SOURCE			DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

NEGLIGIBLE	
NO .	D-FFICULTY

NECLICIBLE	
NO.	DIFF CULTY

5 FLIGHT PATH CONTROL

DEFICULTY

PRECISION

	initial Track			Fina	
G de palh	Locolizer	Glide path	Localizer	Glide path	Localizer
SLIGHT	SLIGHT	MODERATE	MODERATE	SLIGHT	SLIGHT
FAIR	FAIR	POOR	POOR	FAJR	FAIR

MINIMUM ACCEPTABLE GREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

THE AIRSPEED INCREASED AND WE FLEW AWAY FROM THE CLIDE PATH, UP TO 1300 F.P.M., DOWN WAS REQUIRED TO GET BACK ON. HAD DIFFICULTY HOLDING HEADING PRECISELY ENOUGH TO TRACK LOCALIZED CONTENTALIT.

6 BREAKOUT AND FLARE

COMMENTS:

	initial track			Final	Irack
Glide paln	Localizer	Glide path	Local zer	Glide poth	Localizer
SLIGHT	NO	SLIGHT	NO	SLIGHT	NO
MAIR/COOD	FAIR/GOOD	FAIR/GOOD	FALR /GOOD	FAIR/GOOD	FAIR/COOD

HIGH THRUST LEVER SENSITIVITY CAUSED HUNTING ON GLIDE PATH, I AM NOT SURE MITH, BLT HAD GREATER SPEED VARIATIONS THAN ANTICIPATED - PERHAPS DUE TO UNCONCIOUSLY PUSHING MOSE DOWN IF HIGH OR PULLING UP IF LOW.

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NO.	DIFFICULTY
COOD	

DIFFICULTY IN ADJUSTING SPEED TO 50 KNOTS (AT BREAKOUT SPEED WAS 52 KNOTS) - PERRAPS DUE TO HIGH FITCH ATTITUDE STABILITY.

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SMALL, SEE SECTION 5.

9 LEAST OBJECTIONABLE FEATURES

NO EFFECTS OF TURBULENCE.

NONE

IO. MOST CBJECTIONABLE FEATURES

SENSITIVITY TO TURBULENCE (LONG PERIOD) IN HEAVE. RIGH PLTOH STABL'LITY EASY TO TRIM BUT DISPICULT TO CHANGE SPERD. HICH THRUST LEVER SENSITIVITY AND POSSIBLY LOW DAMPING.

II M SCELLANEOUS

N.B. HAD TO USE 1300 P.P.M. RATE OF DESCENT TO RECOVER GLIDE PATE.

SLEVATOR STICK FORCES HIGH FOR THIS LEVEL OF STABILITY.

THRUST LEVER DISPLACEMENTS TOO SMALL.



CONFIGURATION R8-2L FLIGHT NUMBER IOO-1 FILOT B CONFIGURATION R8-2L FLIGHT NUMBER 112-1 WIND(knots) 0-5 WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT PILOT A
PILOT-RATING 8 PILOT B PILOT-RATING 7G CHARACTERIST C ROOTS CHARACTERISTIC RCOTS -.01 -.31 -1.04 ± 1.061 -.01 -.31 -1.04 ± 1.061 I. AIRCRAFT RESPONSE TO CONTROL INPUTS MBE = 0.34 (re E_EVATOR THRUST LEVER

VBE - 0.34 (rod/sec2)/in Z8T : 11.9 (11/sec2)/in THRUST LEVER (11/sec²)/in (rad/sec²)/m Z8T>15 CONTROL SENSITIVITY TOO GREAT RESPONSE : SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESTRED VELOCITIES Longitudinal velocity (TAS)
VMC TMC TM C
OU OUT IN Vertical velocity (h) FLIGHT CONDITION TURBULENCE OUT IN SLIGHT MODERATE OUT OUT IN
SLIGHT SLIGHT HODERATE SLIGHT DIFF-CULTY
MAX-MUM UNDESIRED FLUCTUATIONS COMMENTS IF I GET HIGH ON GLIDE SLOPE I TEND TO PUSH NOSE DOWN WHICH INCREASING AIRSPEED CAUSED AN INCREASE IN NURMAL PORCE WHICH CAUSED PROBLEMS IN HOLDING AIRSPRED AND VERTICAL SPEED. THE INCREASES SPEED UNDESTRABLY. I WAS HIGH ON GLIDE SLOPE AND PITCH ATTITUDE WAS DIFFICULT TO SETTLE ON. THE HEAVE RESPONSE TO POWER CHANGES TOOK A LONG TIME TO SETTLE. HIGH ON SPEED GENERALLY. I WAS UP TO - 1300 fpm ONCE ON 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE PERIOD DAMPING AMPLITUDE PERIOD DAMP-NG EXCITATION CONTROL COMMENTS ١ 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED -EASE OF COMPENSATION SMALL DIFFICULTY DIFFICULTY THE AIRSPEED VARIED AND THIS CAUSED LARGE VARIATIONS IN THE POWER REQUIRED - NEVER DID GET IT SOUTED OUT AT DESIRED CONDITIONS. 5. FLIGHT PATH CONTROL ntercept & initial track - fermediate track - Final track olde path | Localizer | Gilde path | Localizer | Gilde path | Localizer nitial track - r termedi .ocalizer Glide path Glide poth Final frack
Glide path Localizer Localizer DIFFICULTY MODERATE MODERATE MODERATE MODERATE SLIGHT SLIGHT SLIGHT MODERATE SLEGHT MODERATE MODERATE PRECISION FA1R **POOR** POOR POOR POOR GOOD GOOD FAIR POOR | FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 800 400 DIFFIGURTY DUE TO WIND SHEAR, IN TAIL WIND I SUSPECT, WHICH, RECAUSE OF POOR CONTROL TECHNIQUE, CAUSED ME TO HAVE HEIGHT CONTROL DIFFICULTIES. I USED MOSE DOWN TO CORRECT MEM HIGHO NO GLUDE SLOPE WHICH CAUSED HIGH SPEED AND CHANGING RATES OF DESCRIPT, MAYBE HIGH THRUST-LEVER SENSITIVITY WAS DIFFICULTY DUE TO QUITE LARGE WIND SHEAR - AS AIRSPEED INCREASED THE RATE OF DESCENT DECREASED, CACSING THE AIRCRAFT TO GO HIGH ON THE GILDE PATH. COMMENTS A CONTRIBUTING PACTOR. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SUIGHT OFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT POOR SLIGHT/MODERATE DIFF CULTY COMMENTS A PITCH OSCILLATION DEVELOPED WHILE TRYING TO GET TO THE LANDING ATTITUDE. DIFFIGURTY DUE TO FOOR POSITIONING AT BREAKOUT ON BOTH GLIDE SLUPE AND LOCALIZER. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM 1 A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE: BUT PROBLEMS WITH HEIGHT TASK CAUSED A DEGRADATION OF LOCALIZER TRACKING. 9 LEAST OBJECTIONABLE FEATURES ATTITUDE INSTABILITY NOT BAD AND IS, BY ITSELF, TOLERABLE, IC. VOST OBJECTIONABLE FEATURES ALRSPEED REFECT ON NORMAL PORCE BEIGHT CONTROL: SOME DUE TO AIRSPEED EFFECT ON NORMAL PORCE AND SOME TO HIGH THRUST LEVER SENSITIVITY, WEAK ATTITUDE STABILLTY. II. MISCELLANEOUS FALAR WAS SET ON 250° BUT WIND AT ATTITUDE ℓ_8 WAS REDUCED FROM 15 TO 11.9 BUT WAS STILL SLIGHTLY WAS APPROX. 160°. TALAR WAS REORIENTATED APTER THIS EVALUATION. TOO SENSITIVE.



 WIND (knots)
 5
 CONF GURATION
 AB-2L

 WIND SHEAR
 MDDERATE (300°+230°)FLIGHT NUMBER
 95-1

 EXTERNAL TURBULENCE
 NEGLIGIBLE
 PLOT
 48
 WIND (knots) 10
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT CONFIGURATION A8-2L FLIGHT NUMBER 112-3 PILOT A
PILOT-RATING 75 CHARACTERISTIC RCOTS -.01 -.31 -1.04 + 1.064 CHARACTERISTIC ROOTS -.31 -1.04 ± 1.061 -.01 I AIRCRAFT RESPONSE TO CONTROL INPUTS THRUST LEVER

(ft/sec2)/in (It/sec²)/in CONTROL SENSITIVITY TOO CREAT RESPONSE SATISFACTORY SATISFACTORY SATISFACTORY TOO GREAT TOO GREAT 2 EASE OF MAINTAINING DESIRED VELOCITIES C IMC I.M.C OT OU N E MODERATE GREAT +15, -10 knots Vertical velocity (h) Long tudina velocity (145)
VMC INC IMC
OUT CUT IN
SLIGHT SLIGHT SLIGHT VMC VMC IMC IMC FLIGHT CONDITION TURBULENCE: DIFFICULTY SLIGHT SLIGHT NONE MAXIMUM UNDESIRED FLUCTUATIONS DIFFICULTY DUE TO SPEED APPECTING RATE OF DESCENT AND TO THE POWER SEEMED TO HAVE A MIND OF ITS DWN AND CONTINUOUSLY VARIED. THE VARIATION DID NOT APPRAR TO BE PERIODIC. I KEPT ON LOSING BEIGHT ON DOWNIND LEG AND COULD NOT GET IT HIGH THRUST-LEVER SENSITIVITY. BACK BECAUSE OF POWER LIMITING ON EXCURSIONS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE FER 00 AMPLITUDE DAMPING CAMPING PERIOD P-TCH HEAVE DEGREE DEGREE EXCITATION CONTROL COMMENTS MUCH DIFFICULTY IN HEAVE, BUT I COULD NOT TELL IF IT WAS OSC. LATORY. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NEGLIGIBLE NONE D-FFICULTY OK AS LONG AS SPEED IS HELD. 5 FLIGHT PATH CONTROL intercept & in-tial track | Intermediate track | Fina track | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide ntercept & mittal track | Intermediate track Gride path | Localizer | Glide path | Localize Glide path Localizer Localizer DIFFICULTY: MODERATE MODERATE GREAT SLIGHT SLICHT MODERATE SLIGHT NONE SLIGHT SLIGHT SLICHT SLIGHT PRECISION FAIR FAIR POOR POOK VERY POOR VERY POOR GOOD COOR FAIR GOOD FAIR GOOD FAIR EALR MINIMUM ACCEPTABLE BREAKOJT ALTITJOE IF GREATER THAN 200 FEET 800 300 SEE SECTION #2. WIND SHEAR QUITE CONFUSING: 1 ANTICIPATED TOO MUCH SHEAR AND ENDED UP ON THE UPWIND SIDE OF LOCALIZER AT BREAKDUT DESCENDING TOO RAPIDLY. COMMENTS. DIFFICULT DUE TO: (1) SOME WIND SHEAR (2) EFFECT OF SPEED ON RATE OF DESCENT NOTICEABLE (3) MICHER THAN DESIRABLE THRUST-LEVER SENSITIVITY 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT MODERATE PRECISION OF ATTAINING TOUCHDOWN POINT WERY FOUR ______ CIFFICULTY SLIGHT FAIR/POOR DIFF CULTY COMMENTS POWER WAS APPLIED TO ARREST RATE OF DESCRIPT AND JUST AS I THOUGHT ALL WAS SORTED OUT, THE AIRCRAFT STARTED TO CLIMB AND JUSTLE IN FUTCH. NOT SURE OF HEIGHT CONTROL NEAR GROUND - PERFORMED A VERY ASYMPTOTIC TOUCHDOWN, ON GUIDE SLOPE AT BREAKGUT. 7 CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST SPEED WAS EFFECTIVE IN CONTROLLING RATE OF DESCENT - THIS TECHNIQUE HAS USED AS IANG AS BOTH SPEED AND GUIDE SLOPE HELE. IN CORRECT SENSE, 14. IF HIGH ON GLIDE PATH AND HIGH ON SPEED, THEN REULICE SPEED. LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES PITCH CONTROL VERY PERASANT. GOOD ATTITUDE STABILITY. IO MOST CBUECTIONABLE FEATURES HEIGHT CONTROL, PARTICULARLY CLOSE TRACKING OF HEIGHT THRUST LEVER DISPLACEMENTS THE SMALL - SENSITIVITY A LETTLE TOO HIGH ALTHOUGH IT DID NOT AFFECT RATING. I MISCELLANFOUS



CONFIGURATION R14L FLIGHT NUMBER 106-2 PILOT A PILOT-RATING 6 W-ND(knois)
WIND SHEAR MODERA
EXTERNAL TURBULENCE LIGHT CONFIGURATION 3141, FLIGHT NUMBER 96-3 PILOT 8 PILOT-RATING 40 WIND (knots) 5
WIND SHEAR SHALL
EXTERNAL TURBULENCE LIGHT MODERATE CHARACTERISTIC ROOTS -.04 | -1.43 -1.06 + 1.051 LAIRCRAFT RESPONSE TO CONTROL :NPUTS Mag: 0.34 trad/sec2 //m Z8T: 15.0 (II//sec2)/m Z8T: 15.0 (II//sec2)/m Z8T: 15.0 trad/sec2//m Z8T: 15.0 trad/sec2//m Z8T: 54.0 sradial Final SATISFACTORY SATISFACTORY SATISFACTORY CONTROL SENSITIVITY Initial Final Initial Final
SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES VM C FLIGHT CONDITION TURBULENCE DIFFICULTY SLIGHT SLICHT NONE SLIGHT SLIGHT MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS DIFFICULTY DUE TO TURBULENCE CONTINUALEY DISTURBING THE PITCH ATTITUDE AND CAUSING THE AIRSPEED TO CHANGE 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE AMPLITUDE DAMPING PERIOD SOURCE DEGREE EXC-TATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NEGLĮC; BLR NO NEGLIGIBLE NO DIFFICULTY DIFFICULTY COMMENTS 5 FLIGHT PATH CONTROL ntercept & initial track | Intermediate track | Final track | Gode path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Intercept & initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | DIEFICULTY MODERATE | SLIGHT MODERATE SLIGHT MODERATE NONE NONE NONE NONE SLIGHT SLIGHT PRECISION FAIR FAIR VERY POOR FAIR FAIR/COOD FAIR/COOD FAIR/COOD FAIR MINIMUM ACCEPTABLE BREAKOUT F GREATER THAN 200 FEET ALT TUDE 300 COMMENTS THE WIND SHEAR REQUIRED QUITE CARGE HEADING ACTEMATIONS UNCERTAIN OF REASON FOR DIFFICULTY, SOME LOCALIZER 'S' TURNING BECAUSE HEIGHT CONTROL WAS MODERATELY DIFFICULT 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT VERY FOOK DIFFICULTY DIFFICULTY DUS TO A FITCH OSCILLATION WHICH WENT TEROUGH ABOUT 2 CYCLES BEFORE STOPPING. IT COULD HAVE STARTED AGAIN IF THE PINAL TOUCHDOWN PHASE HAD BEEN COMPLETED. 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM 1.4 \$ WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES GOOD ATTITUDE STABILITY O. MOST OBJECTIONABLE FEATURES TURBULANCE RESPONSE, PIO AT PLARE. TEAVE SENSITIVE TO TURBULENCE (BUMPY) SOME LOCALIZER 'S' TURNING BECAUSE HEIGHT CONTROL MODERATELY DIFFICULT THE RATING WAS DEGRADED FROM 5 TO 5 BECAUSE OF THE PITCH USCILLATION DURING FLARE, ITS TRANSFERT NATURE MAKES IT DIFFICULT TO ASSESS. IF MISCELLANEOUS MUDEL DID N'T APPEAR TO BE VERY DIFFERENT FROM MODEL ALG-LL, BUT WELGHT CONTROL TASK ON APPROACH WAS APPRECIABLY HORE DIFFICULT FUR SOME UNDETERMINED REASON - POSSIBLY CROSS CHECK AND BAC LUCK.



CONFIGURATION A14L FLIGHT NUMBER 109-1 PILOT A WIND(knots) 10
WIND SHEAR MODERATE
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION A14L FLIGHT NUMBER 91-2 PILOT B PILOT-RATING 3\C WIND (knots)
WIND SHEAR
EXTERNAL TURBULENCE PILOT A
PILOT-RATING 5 CHARACTERISTIC ROOTS -.04 -1.43 -1.06 + 1.051 CHARACTERISTIC ROOTS -.04 -1.43 -.106 ± 1.051 LARCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR

MBE 0.34 (rod/sec²)/n Z8T 15.0 (ft/sec²/n

Ioniol Final

SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY E_EVATOR THRUS* LEVER

Mag = 0.34 (rad/sec^2 l/m 281 = 15.0 (tt/sec^2 l/m 281 = 15.0) Final CONTROL SENSITIVITY Initial SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES | Longitudino velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocity (18.5) | Vertical velocit TURBJENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS SLIGHT MODERATE DIFFIGULTY DUE TO THRUST LEVER SENSITIVITY OR DAMPING BEING A LITTLE LAW. SPEED DROPPED 9 KNOTS AT BREAKOUT AND FLARE DUE, I THINK, TO SHEAR 3 RESIGNAL OSCILLATORY CHARACTERISTICS AMPLITUDE ZERC HEAVE DEGREE DEGREE SOURCE EXCITATION CONTRO. COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NEGLIGIBLE DIFFICULTY COMMENTS NEED TO ADVANCE SOME POWER IN TURNS 5 FLIGHT PATH CONTROL Intercept & nitial track Intermediate track Final track
Glide path Localizer Glide path Lacolizer
Glide path Localizer Glide path Localizer DIFFIGULTY MODERATE MODERATE MODERATE MODERATE MODERATE SLIGHT SLIGHT SCIGHT SLIGHT PRECISION FATS /ALR 3000 COOD GOOD GOOD 300D MINIMUM ACCEPTABLE BREAKOUT ALTITUDE :F GREATER THAN 200 FEET 500 DIFFURILTY DUE TO TURBULENCE WHICH DISTURBS BUTH HEAVE AND FIRCH AND TO JIND SHEAR. COMMENTS: DIFFICULTY DUE TO WIND SHEAR. THERE APPEARED TO BE SOME LAG IN HEIGHT CONTROL, BUT COULD NOT BE CERTAIN OF THIS IN PRESENCE OF THIS WIND 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SO DIFFICULTY
PRECISION OF ATTA NING TOUGHDOWY POINT PALS SILCHT DEFICULTY SERSED THE POSSIBILITY OF A SLIGHT HEAVE PIO NEAR TOUCHTOWN, SET A REASONABLE MATE OF DESCENT AND HELD IT - THIS WAS SATISFACTORY. COMMENIS: 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM (4.5 WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LAFERAL DIRECTIONAL CHARACTER STICS SFFECT ON FINAL ASSESSMENT

NONE, SOME EDUCALIZER IS TURNING BREOW 1000 PT.

GOOD FITCH STIFFNESS. SPEED AND EXIGHT TRIMMABILITY GOOD.

NOTICEABLY SENSITIVE TO TURBULENCE IN BEAVE, NOT PITCH.

REVERSE GRADIENT IS WIND SHEAR I THINK. LIGHT WIND AT AUTIT DE, STRONG AT SURFACE.

9 LEAST OBJECTIONABLE FEATURES

I MISCELLANEOUS

10 MOST OBJECTIONABLE FEATURES A DENERAL INSCRIBINGUS MAIN, IT WILL INCOMPORTABLE



CONFIGURATION A14L FLIGHT NUMBER 104-L PILOT C CONFIGURATION WIND(knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE FLIGHT NUMBER PILOT WIND SHEAR EXTERNAL TURBULENCE PILOT C PILOT-RATING 4 PILOT - RATING CHARACTERISTIC ROOTS LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = ELEVATOR (rad/sec²)/in Z_{8T} = F:nol CONTROL SENSITIVITY: TOO SMALL RESPONSE: SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES | Longitudinal velocity (LAS) | V | VMC | IMC | M C | VMC | VMC | OUT | OUT | OUT | MODERATE | NONE | STORY | MODERATE | NONE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | NOTE | STORY | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODERATE | MODE Vertico velocity (h)
C I.M.C ;
T OUT SLIGHT SL FLIGHT CONDITION: MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS: SOME DIFFIGURTY IN PREVENTING MODERATE SPEED DEPARTURES IN IMC TASK. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD SQURCE DEGREE EXCITATION CONTROL SUEVATOR SLIGHT PITCH OSCILLATION JUST DETECTABLE WITH SHARPER ELEVATOR INPUTS. VERY SMALL AND POSSIBLY DUE TO AUTOPILCT. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION: NEGLIGIBLE CIFFICULTY DIFF CULTY 5. FLIGHT PATH CONTROL Intercept & miliot track | Intermediate track Ghide path | Localizer Glide path | Localizer Intercept & initio Irack Intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer Gide poth Localizer DIFFICULTY: NONE MONE SLIGHT NUNE MODERATE SLIGHT PRECISION GOOD FAIR ALTITUDE MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET CAINED LC KNOTS IN TRYING TO KEEP DOWN ON GLIDE PATH DURING INTERMEDIATE TRACK. COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT FAIR DIFF CULTY COMMENTS 7 CONTROL TECHNIQUE COMMENTS OF DIFFERENT FROM I AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LÉVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAS! DEJECTIONABLE FEATURES IO. WOST OBJECTIONABLE FEATURES CONTACT OF SPEED LACKS CRISPNESS. TOO RASY TO ALLOW RATHER LARGE DEPARTURES. ELEVATOR TRIM HATE NOTICEABLY SLOWER THAN SOME PREVIOUS MODELS. SPEED HOLDING RATHER POCKER THAN 'N PRRVIOUS TWO MODELS (6-21, 84-31) BUT LESS NEED EXISTS PON POWER LEVER ADJUSTMENTS. II WISCEL_ANEOUS



CONFIGURATION R14-LL WIND(knots)
FLIGHT NUMBER 110-L WIND SHEAR
PILOT A EXTERNAL TURBULENCE
PILOT-RATING 2

CONFIGURATION R14-1L WIND (knots) 10 FLIGHT NUMBER 101-1 WIND SHEAR VERY SPILOT B EXTERNAL TURBULENCE LIGHT FILCT-RATING 4C

VERY SMALL

CHARACTERISTIC ROOTS .03 -1.45 - .05 ± 1.06t

CHARACTERISTIC ROOTS -.03 -1.46 -1.06 ± 1.061

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELE	/ATOR		T LÉVÉR
Mag = 0.34	(rad/sec ²)/in	ZBT: 15.0	(It/sec ²)/ _{in}
(cilia)	Fest	Initial	- 00
SATISFACTORY	SATISFACTORY	SATIS FACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

Longitu	dinal yeloi	aly ([AS)	Ver	lical velocity	(h)
V M C.	:MC	IMC	VMC	IMC	IMC
OUT	TUO	- IN	OUT	1 00*	I IN
NONE	SLIGHT	ISLIGHT	NONE	SLIGHT	SLIGHT
	5	knafs	C	IK.	! pm

TURBULANCE RESPONSE IN HEAVE TENDS TO KEEP ONE HONEST, BUT NO GREAT PROBLEMS - THE AIRSPEED DID MANDER SOMEWHAT, BUT THIS MODEL FELT BETTER THAN THE ATTITUDE COMMAND TYPE SINCE THE CONTROL FORCES DID NOT HAVE TO BE HELD TO MAINTAIN A NEW AIRSPEED,

Longitu	dinal veloc	ty (IAS)	Vert	ical velocity	(h)
VAIC	TMC	I M C	VMC	LMC	LMC
007	QUIT	- 11	OJT	OUT	IN
SLIGHT	>SLIGHT	> SLIGHT	SLIGHT	SLIGHT	SLICHT

| The state of the

DIFFICULTY MAY HAVE BEEN DUE TO OFFSET ELEVATOR TRIM.

3 RESIGNAL OSCILLATORY CHARACTERISTICS

EXCITATION

COMMENTS

AMPLITUDE	COIRIG	DAMPING
ZERO		
ZEMO		1
5550 I		
SOJRCE		DEGREE

AMPLITUDE	PER OD	DAMPING
ZERO		
ZERO		i
SOURCE		DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

NEGISTRUS NO CIFF CULTY, NO PROBLEM - STEERS LIKE A KIDDIE CAR NEGLIGIBLE VERY SLIGHT DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept 8	initial track	Intermediate track		Final track	
Glide pall.	Localizer	Gliae patn	Localizer	Glide path	Localizer
NONE	NONE	NONE	NONE	NONE	NONE
GOOD	COOD	GDOD	GOOD	G00D	GUOD

IF GREATER THAN 200 FEET

COMMENTS

COMMENTS

Intercept 6 artial track offermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer NONE SLECHT SLIGHT SLIGHT SLICHT FAIR/GOOD FAIR FAIR/GOOD FAIR/GOOD FAIR

6 BREAKOUT AND FLARE

EASE OF ARRESTING MATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NC	5 FICULTY
3000	

OVERSHOT INITIALLY ON LOCALIZER. CLIDESLOPE: PERHAPS A WIND SHEAR CAUSED NE TO GO LON IN CLUSE - PERHAPS CROSSCHECK - 2 DOTS LOW AT BREAKOUT AT 200 FT.

VERY SLIGFT DIFFICULTY
FAIR/GOOD

7 CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SHAUL

9 LEAST OBJECTIONABLE FEATURES - SITCH CONTROL WAS POSITIVE AND VERY STABLE

NONE

ID MOST OBJECTIONABLE FEATURES - HEAVE RESPONSE TO TURBULENCE

HEIGHT CONTROL SREMED GOOD ATTITUDE STABILITY, ALTHOUGH WEAK, MAS SATISFACTORY AND DID MAKE MOR GOOD TRIMMABILITY AND SPEED CONTROL.

II MISCELLANEOUS

SENSITIVE TO TURBULENCE IN HEAVE (BUMPY RIDE).



CONFIGURATION A14-1L WIND (knois)
FLIGHT NUMBER 96-2 WIND SHEAR
PILOT B EXTERNAL TILL CONFIGURATION A14-1L WIND(Nnots)
FLIGHT NUMBER 115-3 WIND SHEAR NEGLIGIBLE
PILOT PLOTRATING 4

WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE LIGHT WIND SHEAR EXTERNAL TURBULENCE LIGHT PLOT-RATING JC CHARACTERISTIC ROOTS -.03 -1.46 -L.05 ± 1.061 CHARACTERISTIC ROOTS -.03 -1.46 -1.05 + 1.061 LARCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENS TIVITY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION MAXIMUM UNDESIRED FLUCTUATIONS RESPONSE TO TURBULENCE GAVE SOME DIFFICULTY - THERE SEEM $^{\circ}\mathrm{D}$ TO BE A BOUNCINESS FOLLOWING A MODERATE TO LARGE TURBULENCE COMMENTS DISTURBANCE. 3 RESIDUAL CSCILLATORY CHARACTERISTICS DAMPING MODERATE AMPLITUDE DAMPING PER OD SHALI. SHURT LEGREE SOURCE DEGREE EXCITATION CONTROL EASILY EFFECTIVE TURBULENCE YLEVATOR SEE SECTION x2 COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION: NEGLIGIBLE VERY SLICHT DISFICULTY NEGLIGIBLE NO DEFICULTY COMMENTS 5 FLIGHT PATH CONTROL ntercept & initial track intermediate track indicate frack Gide path Local zer Glide path Localizer Glide path Localizer Intercept & mitigal track - Hermediate track
Glide path Localizer Glide path Localizer Glide path Lacal-zer DIF F ICULTY SLIGHT MODERATE SLIGHT SL1GHT V.SLIGHT V.SLIGHT SLIGHT SLIGHT РООК FAIR FAIR FAIR FAIR FAIR/GOOD FAIR/GOOD GOOD MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET [500] OK ... 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO PRECISION OF AT AINING TOUCHDOWN POINT GOOD SLIGHT DIFFICULTY
FAIR/S000 COMMENTS BEING A LITTLE NOW AT BREAKOUT REQUIRED A SLIGHTLY DIFFERENT FLARE TECHNIQUE 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE. IDICALIZER TRACKING EASY BECAUSE HEIGHT CONTROL PAST. 9 LEAST OBJECTIONABLE FEATURES COOR ATTITUDE STABILITY FLAW PIRST PART OF CLECTIT, 900 PT TO DOWNWIND HANDS OFF! O MOST OBJECTIONABLE FEATURES RESPONSE TO FURBILLENCE CALSEL A VERY UNSTRAIN PERCENCE. A DITTLE SENSITIVE TO TURBULENCE II MISCELLANEOUS ELEVATOR CONTROL PURCES HIGH ELEVATOR TRIM HATE SOMEWHAT TOU SLOW



CONFIGURATION A14-1 FLIGHT NUMBER 130-2 PILOT A CONFIGURATION
FLIGHT NUMBER
PHOT
PLOT-RATING WIND (knots)
WIND SHEAR
EXTERNAL TURBULENCE WIND(knats) 10-15 WIND SHEAR HODERATE
EXTERNAL TURBULENCE RECLIGIBLE
(LIGHT BELOW
1200 FT) PILOT A
PILOT-RATING 5% CHARACTERISTIC ROOTS -.03 -1.46 -1.05 - 1.061 CHARACTERISTIC ROOTS I AIRCRAFT RESPONSE TO CONTROL INPUTS (rad/sec²)/in Z_{8T} = F-nal CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudina: velocity (IAS)
VMC INC IMC
OUT OUT IN FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS OUT IN I HAD MUCH HORE DISPICULTY ON THE APPROACH THAN WAS ANTICIPATED FROM Y.F.H.FLYING. THE TURBULENCE BOUNCED THE AIRCRAFT AROUND SUFFICIENTLY TO DISTURB THE AIRSPEED AND VERTICAL SPEED CONTROL UNSATISFACTURILY. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUÉE PER OC DAMPING PER OD AMPLITUDE DAMPING BEAVE SOURCE DEGREE SOURCE **EXCITATION** CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION: SMALL. NO O FFICULTY DIFF CULTY COMMENTS 5 FL-GHT PATH CONTROL nlercept 8 initial track | Intermed ate track | Final track | G de path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SLIGHT | SUBJECT | MODERATE | OREAT intercept 6 oital track intermediate track Final track
Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY MODERATE GREAT PRECISION FALR FATR VERY POOR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE F GREATER THAN 200 FEET 500 COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT MEDERATE DOOD COORD DIFFICULTY THE DESCENT MATE WAS HIGH AND THE APPLICATION OF POWER LEVER DID NOT SEEM TO BUT AS QUICKLY AS EXPECTED. COMMENTS 7 CONTROL TECHNIQUE COMMENTS A DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS SALL TO MODERATE. THE WIND SHEAR GCC PILD FORE ATTENTION THAN MAS AVAILABLE FOR LATERAL DIRECTIONAL GLARACTERISTICS ATTENDED SACREFICERS COSCITEDINAL CONTROL POSITION. BEADING CHANGES ON APPROACE TO MAINTAIN LOCALIZER BREE UNCAPERATION. LASSE. IO VOST CBUECTIONABLE FEATURES I MISCEL_ANEOUS



 CONFIGURATION
 R14-2L
 W-ND (knots)
 10

 FL GHT_NUMBER
 102-3
 WIND_SHEAR
 SMALL

 PILOT
 B
 EXTERNAL_TURBULENCE
 MODERATE
 CONFIGURATION R14-2L WIND(knois) FLIGHT NUMBER 89-2 PILOT A WIND SHEAR SMALL EXTERNAL TURBULENCE NECLIGIBLE PILOT RATING 4 PILOT B FILOT-RATING 75C CHARACTERISTIC ROOTS -.01 -1.52 -1.03 1.071 AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEYER

Mag = 0.35 [rod/sec²]/m Z31 = 15.0 [tr/sec²]/m

onto F rod In ito Find

SATISFACTORY SATISFACTORY SATISFACTORY CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES ong tudino! velocity (IAS)
MC IMC IMC
OUT 'N
OUT OUT 'N
CONT SLIGHT GREAT ! Vertical velocity (fi)
VMC i MC :
OUT OUT Vertical velocity (A)

VMC I.MC FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS SLIGHT SLIGHT SLIGHT E SLIGHT SLIGHT DIFFICULTY IN CONTROLLING SPEED ON APPROACH, WHICH REQUIRED BIG ELEVATOR AND FITCH ATTITUDE CHANGES TO CONTROL, WAS POSSIBLY DUE TO ATTITUDE INSTABILITY, CROSSCHECK OR TURBULENCE. THIS MODEL OBVIOUSLY HAD DECREASING VERTICAL PORCE WITH DEGRASSING LONGITUDINAL VELOCITY, BIT THIS WAS NOT BOTHERSOME. THE LACK OF ATTITUDE COMPAND OR STABLILIZATION AS FVIDENCED BY RESPONSE TO ELEVATOR HADE ALBSPEED CONTROL SOMEWHAT DEFICULT. THE TURBULENCE PRODUCED MORE MOTION IN HEAVE THAN NORMAL - NOT A PROBLEM. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE PERIOD DAMPING AMPLIT JOE PERIOD DAMP NG ZERO HEAVE SOURCE DEGREE DEGREE EXCITATION CONTROL COMMENTS. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION NEGLIGIBLE NO DIFF CULTY DIFFICULTY COMMENTS MUST BE CAREFUL TO COORDINATE AND MONITOR SPEED - LARGE NORMAL PORCES RESULT FROM AIRSPEED CHANGES. 5 FLIGHT PATH CONTROL Intercept 8 nitro track Intermediate track Final track
Glide path __cca _zer Glide path Localizer Glide path __ccalizer intercept 6 initial track | Intermediate track | Final track | Gide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | DIFFICULTY NONE NONE SI.IGHT SLICHT NONE NUNE SLIGHT NONE SLIGHT SLIGHT MODERATE MODERATE PRECISION COOD GOOD FALR PAIR ₹A1R SALAS FALR FATR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET SPEED CONTROL VERY POOR - OSCILLATING 5 KNOTS REGULARLY, SOMETIMES 10 - LARGE AGGRESSIVE CONTROL IMPUTS TO CORRECT - OVERCORRECTED OFFEN. COMMENTS 6 BREAKOUT AND FLARE FASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT GOOD DIFFICULTY ALTHOUGH SPEED HELD WELL AT 60 KNOTS, A VERY HIGH RATE OF DESCRIT DEVELOPED AT ABOUT 100 FT. A.G.Y. JUST ENOUGH (LARGE) THRUST APPLIED TO ARREST TO REASONABLE DESCRIT RATE AT TOUCHDOWN. GOULD HAVE BEEN CAUSED BY WIND SHEAR. COMMENTS 7 CONTROL TECHNIQUE COMMENTS & DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES THE TURBULENCE RESPONSE CERTAINLY ADDED AT LEAST ONE RATING POINT TO THIS MODEL. (1) WEAK ATTITUDE STABILITY BOT NOT TOO DIVERGENT - STILL SPEED CONTROL DIFFICULT.
(2) LANGE NORMAL PORCES WITH ARRSPEED CHANGES.
(3) THRUST CONTROL OF BATE OF DESCENT SLOW. IO MOST OBJECTIONABLE FEATURES WIND STRUNG AT SURPACE - WEAKER ABOVE. LARGE AGGRESSIVE CONTHOL INPITS ON APPROACH - BECAUSE OF PILOT PATIGUE AND HYPERACTIVITY 1 THINK - THIS WAS THE SEVENTH CONSECUTIVE APPROACH WITHOUT BEEAKS. II MISCELLANEOUS



CONFIGURATION A14-2L WIND(knois)
FLIGHT NUMBER 90-2 WIND SHEAR
PILOT A EXTERNAL TO
PILOT-RATING J

WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS -.01 -1.52 -1.03 L.071

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE :

ELE	POTAV	T ⊢R J\$	LEVER
M 8E = D.34	(rad/sec2)/in	Zar = 15.0	(ft/sec²)/in
Initial	F-nal	ln/fra*	Final
SATISFACTORY	SATISFACTORY	SATIS FACTORY	SAT 1S FACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

- 1	Langitua nai Velocity (145)		VEFFICAL VEIGENY (II.)			
- 1	V.M.C.	IMC	TMC	VMC	I.M.C	IMC
ı	QUT	DUT	IN	OUT	OUT	IN
- 1	NONE	NONE	NONE	NONE	SLIGHT	SLIGHT
ş [<u>+</u>	5	knots	1	200	fpr.
		_				

THE ATTITUDE COMMAND SYSTEM HORKED FILL IN HOLDING ALRSFEED, THE VERTICAL VELOCITY WAS INFLUENCED BY CUSTS AND BY AIR-SPEED BUT MEITHER WERE SERIOUS.

Longit.	dinal veloci	ly (IAS)	Verl	ical velocit	y (h)
VMC	IMC	IMC	VMC	IMC	1 M C
OUT	OL"	IN	0JT	OUT	IN
SLIGHT	MUDERATE	MODERATE	> SLIGHT	> SLICHT	MODERATE
t	4	kna*s			Ірп

SATISFACTORY SATISFACTORY SATISFACTORY

CHARACTERISTIC ROCTS -.01 -1.52 -1.03 ± | 1.071

WIND SHEAR SHALL EXTERNAL TURBULENCE LIGHT

(f1/sec²)/in

CONFIGURATION AL4-2L WIND (knots)
FLISHT NUMBER 93-3 WIND SHEAR
PILOT B EXTERNAL T

PILOT-RATING 6D

DIFFICULTY DUE TO LARGE NORMAL FORCES CAUSED BY AIRSPEED CHANGES, NEED TO HOLD SPEED PRECISELY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE EXCITATION

COMMENTS

AMPLITUDE	PERIOD	DAMPING
2.E.A.O 2.E.A.O		
SOURCE		DEGREE
SOUNCE		

AMPLITUDE	PERIOD	DAMPING	
ZERU			
ZERO			
SOL RCE		DEGREE	

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

NEGLIGIBLE	
NO	D.FFICULTY

COMMENTS:

NECLICIBLE NO DIFFICULTY

AS LONG AS SPEED IS HELD PRECISELY.

Intercept & initial track Gl de path Localizer

FAIR/GOOD FAIR/GOOD

400

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept & initial track				Final track	
Glide pa+h	Localizer	Glide poth	Localizer	Glide path	Localizer
NONE	NONE	SLICHT	NONE	SLIGHT	NONE
000 D	6000	FA13	0000	FAIR	ÇOOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE

COMMENTS

THE THRUST CONTROL DID NOT SEEN TO SETTLE US INTO A STEADY DESCENT FOR QUITE A WHILE AND THE LEVER HAD TO BE INCHED WELL BACK TO GET THE DESIRED EFFECT.

6 BREAKOUT AND FLARE

FASE OF ARRESTING RATE OF DESCENT	NO	D FFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT	6000	

COMMENTS:

DEFICULTY SLIGHT FAIR/GOOD

SLIGHT

FAIR

DIFFICULTY DUE TO NEED TO HOLD SPEED PRECISELY AND THEN THE RATE OF DESCENT IS CONTROLLED ONLY BY THRUST LEVER. IF SPEED WERE TO SE CHANGING, IT WOULD SE VERY DIFFICULT TO COGGUNATE THRUST "LEVER POSITION WITH AIRSPEED TO GIVE PROPER HATE OF DESCENT AT TOUCHOUGH."

DIFFICULTY ON LOCALIZER DUE TO CROSS CHECK. AT ONE POINT, ABOUT 700 FT., FORCOT TO NOTICE LOCALIZER AT ALL AND, WHEN NOTICED, IT HAD GONE FULL DEPLECTION RIGHT - CORRECTED OK.

Glide path Localizer Glide path Localizer

POOR

MODERATE MODERATE

FAIR

SLICHT

POOR

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SMALL

9 LEAST OBJECTIONABLE FEATURES

IO. MOST OBJECTIONABLE FEATURES

NONE

VERY STIFF ATTITUDE STABILITY, BUT IT DOES NOT SIGNIFICANTLY ALLEVIATE THE PROBLEMS CAUSED BY THE LARGE NORMAL FORCES GENERATED WITH ALRSPSED CHANGES.

NOTICEABLY SENSITIVE TO TURBULENCE IN HEAVE AND PITCH.

I: MISCELLANEOUS SOME TAILMIND WHICH DID NOT AFFECT RATING. RATING 6
BECAUSE, EVEN WITH GOOD ATTITUDE STIFTNESS THERE IS A
STRONG REQUIREMENT FOR THE FILLT DE MONITOR AIRSPEED TO
KEEP RATE OF DESCENT INDER CONTROL.



WIND (knots)
WIND SHEAR
EXTERNAL TURBULENCE CONFIGURATION A14-2L WIND(knots) io CONFIGURATION FLIGHT NUMBER 120-1 WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE FLIGHT NUMBER PILOT-RATING PILOT-RATING 7 CHARACTER-STIC ROOTS CHARACTERISTIC ROOTS -.01 -1.52 -1.03 1.071 I A-RCRAFT RESPONSE TO CONTROL INPUTS | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | HRUST LEVER | (roa/sec²)/in ZsT= THRUST LEVER
(ft/sec²)/in MaE: CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM INDESIRED FLUCTUATIONS LONGITUDINAL AND WERTIGAL VELOCITY DIFFICULT TO MOLD ON FINAL STACE OF APPROACE, V.M.C. SPEED TO 40 KNOTS DERING FLARK. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS C4MPING PE PIOD AMP_ITUDE CAMPING AMPL TUDE PE RIOC E PERIOD SHORT SHORY SMALL SPALL SCURCE DEGREE

ELEVATOR, TURBULENCE EASILY

NOT ATTEMPTED DEGREE SCURCE EXCITATION CONTROL SMALL BUT SHARP OSCILLATION, DIFFERENT TO TELL MACTHER FIRST OR SHAVE OR BOTH. COMMEN*S 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED
ACITE STATEMENT OF COMPENSATION MODERATE DIFFICULTY DIFFICULTY COMMENTS AFFECTED BY SMALL SPEED CHANGES. MOST HEIGHT (AND \mathcal{P}_{L}) ON TURNING BASE 5 FLIGHT PATH CONTROL Intercept 8 in hall track intermediate track in hall track.
Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Localizer | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide poth | Glide Intercept 6 initial track intermediale track Final track
Glide path Localizer Glide path Localizer Glide path Localizer DIFF CULTY V (2Y 2003 | 0000 FALR POOR JS1OR CALC WINIMUM ACCEPTABLE BREAKOUT ALT.TUDE IF GREATER THAN 200 FEET 250 COMMENTS GREATEST DIFFICULTY IN COMPLETENC FLARCE 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT VLRY ZOOR DIFFICULTY D FF.CULTY COMMENTS ALTOWER SPEED TO FALL TO 46 MOOTS OPENS PLAKE - EMABLE TO GLOCKER SPEED EFFECTIVELY PRIOR TO TOUGHDENN. 7 CONTROL TECHNIQUE COMMENTS OF DIFFERENT FROM 145 MORNAL TAGINIONE, BUT INAPPEDITIVE IN PLANE AND TIRES LEVER CAL SPEED WITH THRUST LEVER. 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NOV 9 LEAST CBJECTIONABLE FEATURES (6:149, W/LY 145) To translate smalles by Model and SPEED OR DESCRIPTION (4:10). IO MOST OBJECTIONABLE FEATURES — ALIMICIPATI IN VARIOUS PIPE (FLAME) CONTROL CONTROL CONTROL CONTROL (FIRE CONTROL CON CLEVATOR MORDIS (10 FAND TITH TAYTH TWO SIAM THE STILLWING DISPHACEMENTS THO LACT. TOWNER INCHESES ROUTHED WHED STILD ALLOWED TO DROW, ART THE CARRY. I MISCELLANEOUS



WIND(knots) 1.-15 (003.
WIND SHEAR SECRETE
EXTERNAL TURBULENCE SECLIGEBLE CONFIGURATION 1-20. FLIGHT NUMBER 93-1 PILOT B PILOT-RATING 20 1:-15 (003.14) WIND SHEAR EXTERNAL TURBULENCE NEGLIGIBLE PILOT-RATING 3 CHARACTERISTIC ROSTS -.01± .19; -.53± .481 CHARACTER STIC ROOTS -.01 ± .191 -.69# .481 LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = .25 CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (h)
VMC (MC I I M C F_GHT CONDIT ON-TURBULENCE . MAXIMUM CNOESIRED FLUCTUATIONS STIGHT STIGHT 0,8, DIPPLOCATE DUE TO PITCHING HOMENT ARISING FROM FOMER CHANGES RECAUSE NOSE DROPS SIGNIFICANTLY WHEN POWER IS REDUCED, AND CONVERSELY MHEN POWER IS INCREASED. NEED TO THEF INCLUDINGLY AS RESILTING FORCES ARE REASONABLY MIGH. A CEMERAL PITCH ATTITUE PROBLEM, NAMEDY IT MAS TOO DIM-FORDET TO FIND AND MAINTAIN THE COLSCEN PITCH ATTITUD-TO CIVE THE DESIRED AIRSPECT. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUCE PERIOD AMPLITUDE 4E(8) ZERO DEGREE SOURCE DEGREE EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION MEGILICILIC SUSPICE DIFFICULTY SEA_L DIFF CULTY COMMENTS 5 FLIGHT PATH CONTROL Intercept 8 in hal track | Intermediate track | Final track | Glide path | Local ser | Glide path | Local ser | SLIGHT/ | SLIGHT nitial track n'ermedia ntermediate track Final track ide path Localizer Glide path Loca zer MODERATE : SEIGHT MODERATE MODERATE NON 6 MODIC CATE 20 00201 (FODU ATA NONE PRECISION (2)0') GOOD | FAIR FAIR FAIR. MINIMUM ACCEPTABLE BREAKOUT ALTITUDE DIFFIGURY BUT TO SHURNING TO STAY ON LOCALISER. DISPLAY IN COROSS-CHECK MEAK ON HOADING. COMMENTS PITCH ACCURAGE PROSES AS IN SECTION - MERCY. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT VERY SLIGHT DIFFICULTY DIFFIGURAY DUE TO MEED TO KEEP CONTROL OF ATTITUDE WHILE CASING SPACE POWER CONNERS. 945 SCREETSE AT BELANDET TO FIND GOST (1/2,90) SCREET AS SOME OFFICE OPEROD, Fig. 18, 94, 61, July 175418. To GREET TO THE PROCESSES SOLET, 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM : A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NOME: NONE 9 LEAST CBJECTIONABLE FEATURES NO ATTITUDE STABILITY. COUPLING OF POWER CHANGES TO SITCH ATTITUTE NOTESISONE ON GLIDE SLEEP CAUSING POOR SPEED CAUSING, SOME TURBULENCS UPSETS IN FITCH. IO MOST OBJECTIONABLE FEATURES OP TO 1400 M.P.M. DESCENT WATE WERE REQUIRED TO CORRECT AND MAINTAIN SLIDE SLOPE. NOTE: THREST GIVEN USEGET, ALTS IT VM-R () FOR \mathbb{R}^2 NO \mathbb{R}^2 NOTE: The Formation \mathbb{R}^2 II MISCELLANEOUS



CONFIGURATION 1-21 CONFIGURATION 1-2 WIND(knots) FLIGHT NUMBER 57-2 WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLICIBLE FLIGHT NUMBER 42-1 PILCT D WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT/ PILOT D
PILOT-RATING 7 PILOT-RATING 51/2 MODERATE CHARACTERISTIC ROOTS -.01± ,19i -,89± ,48i I AIRCRAFT RESPONSE TO CONTROL INPUTS (rad/sec²)/in Z_{BT} = II. 9 IMRUST LEVER F noi MSE = .30 (rac (ATOR THRUST LÉVER (roa/sec²)/in Z8==15.0 (ff/sec²)/in Final Initial Final (ft/sec²)/in CONTROL SENSITIVITY: SATISFACTORY SATISFACTORY SLIGHTLY SMALL TOO GREAT RESPONSE : 2 EASE OF MAINTAINING DESIRED VELOCITIES TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS DIFFICULTY DUE TO OVERCONTROL IN HEADING AND HENCE LARGE HARK ANGLES. ATASPEED IS AFFECTED BY LARGE BANK ANGLES WEIGH THEN REQUITE POWER CHANGES SINCE VERTICAL VELOCITY 3 RESIDUAL OSCILLATORY CHARACTERISTICS ZERG SOURCE SCURCE !LARDLY/MCDERATELY EPPECTIVE EXC:TATION ELEVATOR TURBULENCE CONTROL COMMENTS PROBLEM SEEMS TO BE A COUPLING BETWEEN PLTCH ATTITUDE AND ROVER LEVER. HEIGHT DAMPING IS PROBABLY LOW, 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REGURED EASE OF COMPENSATION NE C.F.(13),
SCIONT DIFFICULTY O FFICULTY FIN ADDITIONAL TERRST WAS APPLIED, (APPL) ALTITUD. IN THEMS, OWNE-COMPENSATION AND IMPOST DEPARTMENT. SHAME TO BE A LAG IN POWER LEVER RESPONSE. 5 FL-GHT PATH CONTROL Intercept & initial track Intermedia G.de path Local zer Gide path le rack Final Irack Localizer Glide poth Localizer Fina: Irack Gi-de path Loca izer Glide path | Localizer | Glide path | Localizer | MNDERATE | DIFFICULTY 30 i j. 11T MODERATE MODERATE GREAT GREAT GREAT GREAT PRECISION PAIR VEHY POOR VERY POOR VERY POOR VERY POOR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FFET 200 .390 NAME TWO STRA, APPROACHES. THE FIRST ONE VERY POOR PER-BIRCHARDS. WIRE WICE HATE OF DESCENT AND STILL COULD NOT CATCH BY THIT THE CLIDE SLIPE, CONSEQUENTLY WERE POOR LUCALIZE TRACKING ALSO, SHOOMD APPROACH SETTER FROM 1800 FIRST BIT STILL DUCK PSILORMANCE DIE MAINLY TO OVER-CONTROL. INADJUNE CON ON OF PERCENT BARE DEBAGE TO DE APPROACH SENDERD IN CONTROL BE AT SPECID OF HALLOW, ALBERTAL FURNASED TO BE TOO SO WORST AT OVER POINT AND ACCUMENTED AT BOURSEL TO BE TOO SE AND TO ASSESS TAKE. COMMENTS: 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT DEPORTER DEFICULTY
PRECISION OF ATTA NING TOUCHDOWN POINT FALLS. SUID IT DIFFICULTY
VERY POOR DIFFERENCE FOR TO BE ID TO CORRECT AT SPIED FROM 50 KNOTS TO 90 KNOTS AFTER BRIGADIT. COMMENTS TRYING TO KARP SPEED OF WELCOURSPOURED NOSE-DOWN, SEEMED INCOMPATIBLE WITH GLOB WITES OF SINK. 7 CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 6 LATERAL DIRECTIONAL CHARACTERISTICS EFFECTION FAMAL ASSESSMENT SHOULD INDUSTRIES THAT DATE TO MALE AGAIN AND CHARGE THE TAX DATE OF THE SHOULD NOTE SHALL 9 LEAST OBJECTIONABLE FEATURES NO WORKS, NO. 2010 A COMPANY OF CROD PETCH OMETNO. SIPPLICATED IN ACCOUNTS AND MAINTAINING AIRSPEED AND PROTOCHE, PRODUCTY, IO MOST OBJECTIONABLE FEATURES - Judging Profession of the America. I MISCELLANEOUS YAY AS ABOUT PLACE TECONIOUS, FIRST BOT VICE ACCOMPLISHED OF THIS SATENG, /ERST PLIGHT OF THE DAY.



CONFIGURATION 1-3L FLIGHT NUMBER 75-1 PILOT A PILOT-RATING 8

WIND(knots)
WIND SHEAR SMALL
EXTERNAL FURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS .027# .3211 -.926# .4711

CONFIGURATION 1-3
FLIGHT NUMBER 34-2
PILOT B
PILOT-RATING 10

WIND (knots) 10
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROSTS .027 : .3211 -.926 : .4711

I AIRCRAFT RESPONSE TO CONTROL NPUTS

CONTROL SENSITIVITY Initial Final ritial Final
SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY RESPONSE

2 FASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

Longilu	dinai veloc	ity (IAS)	Ver	ical velocity	(ñ)
VMC.	LMC	INC	VMC	IMC	IMC
ou-	OJT	IN.	DUT	OUT	1N
MODERATE	CREAT	GREAT	MODERATE	GREAT	CREAT
5	± 10	knots		± 300	fpm.

COUPLING BETWEEN AIRSPEED AND VERTICAL SPEID IS STRONG AND IN ABDIRAL SENSE, MOSE DOWN INCREASES ATBEFRED AND ALTITUDE. THIS MAKES PRECISE AIRSPEED CONTROL DIFFICULT, SINCE THRUST CHANGES VARY THE AIRSPEED THROUGH THE ATTITUDE.

	VÁTOR	THRUST	
M&E = 0.40	trod/sec2 1/in		(f1/sec2)/in
Initial	Fingl	Initial	Final
TOO GREAT	CONFUSING	NOT ASSESSABLE	NOT ASSESSABLE

Longitudinal velocit	ly (TAS)	Verl	ical velocity	(h)
VMC IMC	LMC	VMC	IMC	1 M.C
TLO TUO	1N	CUT	OUT	IN
MODERATE MODERATE	GREAT	MODERATE	GREAT	GREAT
	knols			f p m

LARGE APPARENT AIRSPEED - VERTICAL VELOCITY COUPLING EFFECT.

3 RESIGNAL OSCILLATORY CHARACTERISTICS

PER-00 4MPLITUDE DAMPING HEAVE CEGREE EXCITATION CONTROL COMMENTS

AMPLITUDE	PERIOU_	LAMPING	ш
SNAU.	LONG	¿ERO]
MODERATE (LARGE)	LONG	CERO	1
			_
SOURCE		DEGREE	1
ELEVATOR, THRUST, 11		EASTLY	1
ELEVATOR		AGGRAVATING	J

HEAVE DECIDEATION COULD NOT BE CONTROLLED.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMALL,
DIFFICULTY

NO GREAT PROJUMN ENGRENCES ATTORN IS OBJUSTED MAIN-TAIN AIRSTEED VERY PROGUSELY DURING MASORITARS IN GIDER TO REEP THE VERTICAL SPEED UNDER CONTROL.

_	NEGL, G; NLE	
	MO	DIFF-CULTY!

MODERATE

PA1R 100000

5 F_IGHT PATH CONTROL

Intercept & milial track Intermediate track Final track Glide path | Local zer | Ghide path | Local zer | Glide path | Local zer DIFFICULTY: COBERATE ADDERATE UREAT SOBERATE NOBERATE PRECISION POOR POOR | POOR | YERY POOR POOR

MINIMUM ACCEPTABLE BREAKOUT IS GREATER THAN 200 FEET ALTITUDE 500

COMMENTS

THE CHARGER VERTICAL SPEED BITT THE CHARGEN (LESPING IN ROUTHOUT THE PROBLEM OF FIRSTED THE PROSES SEARCH: TARRET THE DESIRED TRACE (MEN VIET CHARGE) FROM VIETAGE THE CHARGE OF THE VIETAGE THE PROPERTY OF T

I.M.C. WOLLD NOT BE ALLAWED WITH THIS MODEL. POOR CROSS-CHECK ON BETRY AND CAPTURE. VERY DIFFICULT TO THAN DURING INTERPREDIETS PHASE OF APROCACE DUE TO HIGH LONGITUDINAL AND GLIDE STAPPE TRACKING MODE LOAD.

SLIGHT

GOOD

Intercept B. in-tigl track | Intermediate track | Final tiglide path | Localizer | G. ide path | Localizer | G. ide path |

JAIR

Final track _ocalizer

MODERATE

6 BREAKOUT AND FLARE

FASE OF ARRESTING RATE, OF DESCENT NO OFFICULTY PRECISION OF ATTAINING TOUCHDOWN POINT SEED COMMENTS

LEVER

7 CONTROL TECHNIQUE

MADERATE DIFF CULTY
PALE/COOD

JICH ON BREAKOUT. ATTEMPTED TO SLOWLY BLEED OF SPEED LO SLOW DESCREE MERTICAL MEDICITY AT TOUGHDWAN. MAD DECIDED TIVE DESIRED WRITTON, WIDDOTT AT TOURHOUN. FAD DECIDED TO STRIPTESE, SK DE POWER LEVER CONTROL IN THICHDWAN BECAUSE OF DOSCILLATION CHARACTERISTICS, INSUCCESSEU, RECAUSE RATE OF DESIGNATION HIGH AT TOUCH 2004.

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECTION FINAL ASSESSMENT SEVERAL SEVERAL SHAPE MENT TO GRANGE REGISTERED.

USEC ALGRESO - VERTICAL VELOCITY COURTING AFFECT TO AFFECT TO CONTROL VERTICAL VELOCITY. MODERATELY EFFECTIVE OFF LIMBS TO A VERY BIG! WORK LOAD.

9 LEAST OBJECTIONABLE FEATURES

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

5-13

ID MOST DBJECTIONABLE FEATURES

CSCILLATION, CONFISING AND DISCRIENTATING INTERACTION NUMBER BLOWNING MAD POLER LEVER CONTROLS, COURLING RETWEEN MAD NO. 57 (1944), P.C. STAFF DISORCENTATION OF USE OF STAFF OF STAFF OF STAFF OF STAFF OF STAFF OF STAFF.

II MISCELLANEOUS

THE COMPANY WAS IMPROVED AS CAMBAILEY CONTROLS DESCRIPTION. TWO INCL.



CONFIGURATION 2-2L FLIGHT NUMBER 71-2 PILOT A PILOT-RATING 71/2

WIND(knots)
WIND SHEAR MODERATE
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTER-STIC ROOTS -.015# .1451 -.50 -1.26

ARCHAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY Initial SAT15 FACTORY RESPONSE -

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

PIGGRATTITUDE WAS IN A CONSTANT STATE OF CHANGE ESPECIALLY WITH TURROLENCE ON. AIRSPERD GOT AS HIGH AS 80 KNOTS JUST BEFORE BREAKDUT AS I WAS PREOCCUPIED WITH VERTICAL VELOCITY

CHARACTER:STIC ROOTS -.015 + .1451 -.50 -1.26

CONFIGURATION 2-2L FLIGHT NUMBER 75-3 PILOT A

PILOT A
PILOT RATING 4

SATISFACTORY SATISFACTORY SATISFACTORY

WIND (knots)

WIND SHEAR SMALL FXTERNAL TURBULENCE LIGHT

LMC. IMC Verrical veracity (A)
VMC IMC
OUT OUT MODERATE MODERATE SLICHT SLIGHT | SLIGHT

THE PITCH ATTITUDE DID NOT STAY WHERE DESIRED FOR VERY LONG AND MADE AIRSPEED CONTROL DIFFICULT. GOMEVER, THIS WAS ONLY MODERATELY ROTHERSOME AND, ON APPROACH, AIRSPEED HAS HILD RELATIVELY WELL.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE PERIOD DAMPING M. DI UM MODERATE SCURCE DEGREE

EXCITATION. CONTROL COMMENTS

THE MOSE SEEMS TO ROUNCE BACK AFTER BEING DISTURBED AND ONE HAS GREAT DISFIGURTY IN SETTING A PITCH ATTITUDE.

AMPLITUDE	PERII	00	DAMPING
ZERO	[<u> </u>		
ZERO			
SOURCE			DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MODERATE SUIGHT DIFF:CULTY

COMMENTS

SMALL	
NO.	DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

intercept &				Final	
Gi de path	-cco izer	Glide polh	Localizer	Gide path	Localize:
SLIGHT	SLEGHT	SLIGHT	SLIGHT	MIDERATE	HODERATE
FAIR	FA13	FAIR	FALS	Pecak	PODR

MIN MUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

AAN ON THE GLIDE PATH AT 5-700 FEET ALOLL, AND A TARGE POWER INGREASE WAS MADE. THIS ARRESTED THE TATH OF STAK TOO NICH AND CAUSED PROBLEMS ALL ADHED WITH ATRISPED, HEALTHY, AND VERTICAL PRODUCTLY ARE AWAY FEW DESIGNO VALUES.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT

COMMENTS

	init all frack			Final	track
Gide poth	Localize.	Glide path	Locaitzer	Glide path	Locolizer
	1				
SUIGHT	N/A	SLIGHT	N/A	SLIGHT	N/A
		;			
	^			·	

THE TALAR LOCALIZER FAILED AND THE APPROACH WAS CUNTINUED ON STERRS BY THE SAFETY PILOT. THIS MORRED WELL BUT THE OVERALL, WORK LOAD WAS DEGREASED CONSIDERABLY.

DIFFICULTY

7 CONTACL TECHNIQUE

COMMENTS IF DIFFERENT FROM 1.4 S WITH ELEVATOR 4ND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL.

9 LEAST OBJECTIONABLE FEATURES

10 VOST OBJECTIONABLE FEATURES

IL VISCELLANEOUS

SMALL: THE HEADING CONTROL ON APPROACH WAS SLOPPY AND FERTUREATIONS AS GREAT AS 5 TO 10 DEGREES OCCURRED WITHOUT ADSCURED OFFECTION.

THE TALAK TOCALIZER PAITED ON APPROACH AND THE LATTER WAS CONTINUED ON STEEKS GIVEN BY SAFETY PILOT. THIS REDUCED OVERALL WORK LOAD CONSIDERABLY.



CONFIGURATION 2-2L FLIGHT NUMBER 83-3
PILOT B
PILOT-RATING 4/2 D CHARACTERISTIC ROOTS

15 KNOTS WIND(knots) WIND SHEAR SMALL EXTERNAL TURSULENCE LIGHT

-.015 ± .145i -.50 -1.26

CONFIGURATION 2-2L FLIGHT NUMBER 98-3 PILOT G PILOT C PILOT-RATING 6

WINDIknots] ZERO
WIND SHEAR SHALL
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERIST C ROOTS -.015 # .1451 -.50 -1.26

LAIRCHAFT RESPONSE TO CONTROL INPUTS

CONTROL SENS-TIVITY

E.F.E	VATQR	T⊨RJS	LEVER
M&E=.25	(rad/sec2)/in	Zst-11.9	(ff/sec ² l/in
lailia)	Final	In.'ial	Final
SATISTACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION: TURBULENCE MAXIMUM UNDESIRED FLUCTUATIONS

VMC	Long to	dingl veloc	ty (TAS)	Vert	ica velocity	(60)
	VMC	1.MC	I.M.C	V M C	IMC	[M C
SLICHT SLICHT SLICHT SLICHT SLICHT SLICHT	OUT	CUT	IN	00*	OJT	IN
	SUIGHT	SLIGHT	\$14090	SUIGHT	SLIGHT	SLIGHT
F5, -4 knots CK fpm		15, -4	knois		CK	

SPEED FLUCTUATIONS WERE USUALLY CAUSED BY TURBUIENCE.

VERY DISFICULT TO KEEP SPEED TO LESS THAN 70 KNOTS ON GLIDE PATH. WIND SHEAR POSSIBLY HAVING AN EFFECT.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS:

AMPLITUDE "	PER:OD	DAMPING
2680		
ZERO		1
SOURCE		DEGREE

PER-OD MEDLUM AMPLIT JCE SCURCE DEGRÉE HARDLY SFEECTIVE

EXCITATION CONTROL COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

NEGITOTRIE
NO DIFFICULTY

COMMENTS

DIFFICULTY

THREST REQUIREMENTS NOT VERY APPARENT. TENDENCY TO LOSE SPIED AND DAIN ALTITUDE.

5 FLIGHT PAIR CONTROL

DIFFICULTY PRECISION

	initial track				tracs
lide path	Local-zer	Gide path	Locolizer	Glide parh	Localite.
NoXi:	#CNE	NONE	SLIGHT	N+NE	SHIGHT
COCE	caton	COJD	 	FA18 10000	FA.1-4 /0000

WINIMUM ACCEPTABLE BREAKOUT A_TITUDE
IF GREATER THAN 200 FEET

COMMENTS

190 FEET BREAKOUT O.K. IF TIN THE SLOTT, ONLY DIFFICULTIES WERE CAUSED BY SITCHTLY MEAK INSTRUMENT CROSS-CHOCKS AND SOME WIND SHEAR.

Intercept 8 initial track Intermediate track Gide path Localizer Glide path Localizer Fino track Glide path Localizer Localizer SLIGHT GREAT MODERATE SLICHT MODERATE.

DIFFICULTY IN KOMPING SPEED LESS THAN 70 KNOTS. LARGE THRUST LEVER SETTING CHANCES.

ENCESSIVE USE OF THRUST CONTROL AND ELEVATOR IN RETAINING LLIDE PATH DUBLING FINAL APPROACH.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

SOME DIFFICULTY IN MAINTAINING SPEED ON BRINGOUT AND FLARE. PERSARS ONE TO LOW GROUND SPEED.

25C

DIFFICULTY

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

B LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT WONL

SSAL

9 LEAST OBJECTIONABLE FEATURES (AND PRICE ACTILIDE STABILITY, VERTICAL COMMAND RECEIVED BY AN ORDER STABILITY OF THE PRICE OF EAST, BUT BOT BOD.

IO MOST OBJECTIONABLE FEATURES - DELAGRANCE SENSITIVE TO THERE EXCEL

DIVIDORPENSATION IN USE OF THRUST CONTROL.

I! MISCELLANEOUS

INTERCHERO LEDI SERVE V. 1700 ESCI WETHER LEDG SLOPE WITH VSO CLAIM, GERLINE DISCENTIONNING MAD HER THERCAPTER IT RESTURED FOR FIFTH, GATE OF DESCRIT,

CHRUST LAMER DISPLACEMENTS TOO LARGE.



CONFIGURATION 2-31, FLIGHT NUMBER 79-2 PLOT A PILOT-RATING 8

WIND(knots)

WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC RCOTS [+.006 ± .2451 -.51 -1.30

CONFIGURATION 2-3L FLIGHT NUMBER 97-3 PILOT B PILOT-RATING 8D

WIND(knots)
WIND SHEAR
EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROOTS +.006 ± .2451 -.51 -1.30

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL	SENSITIVITY:
OF CHOMICS	

	ELEV	TOR	THRU:	ST LEVER
N 8E = 30		(rod/sec2)/m	Zar=11.90	(It/sec ² i/in
letter		Final	Initial	f na:
SATISFACTO)RY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION	
TURBULENCE	
D-FFICULTY	
MAXIMUM UNDESIRED	FLUCTJATIONS

	Langitu	dinal veloc	ty (IAS)	Verl	col velocity	(h)
	VMC	CMC	LM.C	V 61 C	TMC	[MC
	OUT	CUT	IŅ	OUT	OUT	II)
	MUDERATE.	MODERATE	CREAT	MODERATE	GREAT	GREAT
S		+10, -5	knois		±300	- 'pm

COMMENTS

INSTABLE, AIMSPACE - MEMTICAL SPEED COUPLING. THAT IS, AS AIRSPACE DECREASES, LIFT DECREASES RESULTING IN A DECREASE IN AIRSPACE AND THE AIRCRAFT SINKS AND SIGNAR AT THE SAME THRE, THE RIVERS IS ALSO THEM. THE AIRCRAFT CAT HIGH THE AIRCRAFT CAT HIGH THE GIRD PATA AS AIRSPEED INGREASED.

ELE:	<u>ELEVATOR</u>		LEVÉR
MgE : .30	(rad/sec2)/in	Z _{BT} = 11,90	(ft/sec2)/in
Initial	Fing	Initial	Finai
SAT IS PACTORY	SATISFACTORY	SATISFACTORY	SATISFACTORY

Longilu	d nat veloc	ily (TAS)	Vertic	al velocity	h)
VMC	LMC	LMC	VMC	IMC	1 M C
001	110	IN	TUO	OUT	10
SLIGHT	SCIGHT	SLIGHT	>SLIGHT	>SLIGHT	> SLIGHT
	±8	<nots< td=""><td></td><td></td><td>f p m</td></nots<>			f p m

RATE OF DESCENT UP TO 1200 F.P.M. INADVERTENTLY ONCE WHEN AIRSPEED WAS LOW, DIFFICULTY WAS DUE TO LACK OF PITCH STABILITY (THERE APPEARED TO BE A TOW AMPLITUDE FITCH-HEAVE OSCILATION) AND TO AN INTERACTION SETWEEN AIRSPEED AND VERTICAL SPEED.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH HEAVE	

 AMPLITEDE	PERICO	DAM PING
2E60		•
1Exe		

EXCITATION CCMME NTS

DESREE	
 	-

AMPL TUDE :	PERIOD	DAMPING
SMAL!.	LONG	CERO/LOW
SMAGE	LONG	ZERO/LOW
SOURCE		DEGREE
DN KNOWN		EASILY
ELEVATOR .		EFFECTIVE

MITIGE A "SWING BACK" EFFECT SOMETIMES. CAN JUST SEE AN OSCILLATION IN RESPONSE TO A STEP EVEVATOR INPUT.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

Shata.	
8.46497	OIFFIC.J_T

COMMENTS

DIVIDITY AND ONLY SEA OF AS IGNORAL AT AN ARROY TO MAN SULL, BY IF THIS A REPECT CHARGE, IN SOL, ANTHREST AND A COURTY, TREAST ACTERVITORS SEST GRAPHOLD.

 SMASIL	
 S.JCTT	D FFICULTY

__+J*;

BEREAFTER

SSST OF SURE TO WOLD ALBERTED AND ATTITUDE,

5 FLIGHT PATH CONTROL

DIFF-CULTY-
PREC:S-ON

Intercect & initial fr				track
Glide path Localit	er Gide poth	Localize,	Gide pair	Loco (zer
STIGHT SLIGHT	***********	\$ 10.3H	. 06°T	S D HT
d0.61 d0%.	POVIE	Arc	12.4	AB

COMMENTS

AN POR SECTION 1 AND THE

	in tial track			Final	
Slide path	Local zer	Girae path	Localizer	Glide path	Localizer
v. Silight	Z. SLIGHT	Salight	STIGHT	MODERATE	MODERATE
		L			

NEVER LOST CONTACT AT 800 FEET IN A P.I.C. STARTED AFTER MAKING V QUICK MEVATOR INPUT TO CORRECT PITCH ATTITION.
THIS DISSUPTED FOR PUMBER PATA BRICH WAS GENERALLY LOB

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN FOINT

["	SKADERATE	•	D	FFICULTY
1	.400.1			

HERE WITH THE AND CHARLES WITH CONFIDENTIAL THE MASS AND DOWN COSTEN IN AN INCLUSION. IN MARINE, FOR MY ONE OF STREET, HORSE THESE WITH LATE WITH MY ONE OF STREET, HORSE THE MARINE WITH MY AND MARKET AND MARINE MARKET AND MARKET MAR

SODERATE DEFICULTY

YEST RESIST FUE TEMBENCY TO PITCS AND FLARE THE ALECRAFT OF BY ANGLET MENO: WHOLD REDUCE ALESPIED AND UNDESTRABLY TREPRASE VERTICAL VERTICITY.

7 CONTROL FECHNIQUE

COMMENTS IF DEFERENT FROM IAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

"EFFECT ON FINAL ASSESSMENT COM

9 LEAST CBUECTIONABLE FLATURES

IO VOST OBJECTIONABLE FEATURES (THE Condition of Factor and Applicable) and Applicables.

PITC: ESTABL DIV AND LOW ASPLITTON OSCILLATION COMBINED 2°T - NEED TO HOLD SPEED CONSTANT ECCAUSE OF ALRSPEED - FECTION SPEED COMPLEX, REFECT.

I MISCELLANEOUS



CONFIGURATION 4-2T.
FLIGHT NUMBER 72-2
PILOT A
PILOT-RATING 4¹/2

WIND(knats)

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE LIGHT/MODERATE

CONFIGURATION 4-2 FLIGHT NUMBER 26-2 PILOT B PILOT-RATING 6 72

WIND (knots) WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROOTS -,157 ± .1811 +,12 .1.6

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELEV	ATOR	THRUST LEVER		
MBE = . 25	{rad/sec2}/m	Z _{BT} = 11.9	(f1/sec ²)/ir	
Initial	Final	Initial	Fingl	
SAT IS FACTORY	TOU GREAT	SATISFACTORY	SATIS FACTORY	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

Langitudinal velocity [[AS]			Vertical velocity (h)		
VWC	I.M.C	TIME	VMC	I IMC	TWC
OUT	ΤŲΙ	IN I	QUT	OUT	IN.
MUNE	S IGHT	MODERATE	NONE	SLICHT	SLIGHT
	+10, -5	knols		±100	fpre

COMMENTS

PITCH ATTITUDE REQUIRED TOO MUCH ATTENTION TO STARFLIZE. WIND DIRECTION AND SPEED CHANGED GREATLY DURING APPROACH CAUSING CONSTANT CHANGE IN HEADING AND BATE OF DESCENT.

ELE	ATOR		TLEVER
M8E = 4	(rad/sec2)/in	Z8T:11.9	[ft/sec2]/in
initial	Final	initial	Fngl
SATISFACTORY	NOT ASSESSABLE	SLIGHTLY SMALL	NOT ASSESSABLE

Langitudinal velocity (145)			Vertical velocity (h)		
VMC	IMC	(M C	VMC	I M C	INC
QUT	DUT	N	OUT	TLC	IN -
SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
	+6, -L0	knots		± 200	1 pm

REASON FOR DIFFICULTY NOT KNOWN.

3 RESIDUA: CSCILLIATORY CHARACTERISTICS

HEAVE

AMPLITUDE	FERIOD	CAMPING
ZERO		
ZESO		
SOURCE		DEGREE

EXCITATION CONTROL COMMENTS

4MPLIT JOE	PERIOD	DAMPING
CRES		
\$3 8 0		
SOURCE		DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

DIFFICULTY

COMMENTS

 MEGALIGY BLE		
30	DIFFICULTY	

5 FLIGHT PATH CONTROL

DIFF:CULTY: PRECISION

100	Intercept or minn track		intermedi	are rider	" mai track	
Ģ	lide path	Localizer	Gl de path	Loca ser	Glise path	Loca izer
L	NONE	SLICHT	SLIGHT	MODERATE	SLIGHT	GREAT
L	ggath	FAIR	FAIR	Puar	EA1k	Riok

MINIMUM ACCEPTABLE BREAKOJT ALTITJOE IF GREATER THAN 200 FEET 500

COMMENTS

SEE SECTION 2 ABOV

			Intermediate track		Final track	
Glide path	Lacal zer	Glide path	Caca 1561	Gi de poih	Lacouzer	
SLIGHT	NOME					
FA18/0000	cost	FAIR	FAIR	POOR/PAIR	POOR/FAIR	

+040

DIFFICULTY DUE TO SLOW RESPONSE TO THRUST LEVER, NOT ABLE TO ANTICIPATE PRECISELY THE SLIGHT INTERACTION BETWEEN AIRSPEED AND VERTICAL VELOCITY.

6 BREAKOUT AND FLARE

EASE OF ARRESTING PATE OF DESCENT NO PRECISION OF ATTA-NING TOUCHDOWN POINT 0003

COMMENTS

AIRCRAFT BEHAVED VERY SPOCTHEY IN THIS PART OF THE PAIGHT, AND WAS IN FACT ONE OF THE BUST ENCOUNTERED.

SLIGHT/MODERATE CIFFICULTY
POOR AS BIGS AT BREAKOUT.

DIFFIGURI TO ANTICIPATE THE REQUIREMENTS FOR ARRESTING
AND AFTE OF DESCRIPT THAT REQUEREMENTS FOR ARRESTING, NOWEVER, WAS SUGGESSFUL IN ARRESTING HIGH RATE OF DESCRIPT FROM
400 FERT TO 29 FERT SEGMENT TOUGHOURS, LANDED LONG.

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL, BUT THE DW INFOUENCY YAW RESPONSE MAS TOO SMALL BUDGE INPUTS

NONE

9 LEAST OBJECTIONABLE FEATURES SPECIATED TURBULENCE AND MERY LITTLE IFFECT.

O MOST OBJECTIONABLE FEATURES

NEER TO STABILISE PITCH ATTITUDE. STILL CONFUSING THROTTLE/SPEED RELATIONSHIP.

II MISCELLANEOUS

SELT TIME THE CONFIGURATION WAS BETTER THAN MY PERFORMANCE ON THE APPROACH INDICATED.



CONFIGURATION FLIGHT NUMBER PILOT PLCT-RATING WIND (knois) WIND SHEAR EXTERNAL TURBULENCE CONFIGURATION 4-2L FLIGHT NUMBER 98-2 WIND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE MEGLIGIBLE PILOT C PILOT-RATING 5 CHARACTERISTIC ROOTS __.157± _.1811 _+.1/ ___-1.5 CHARACTERISTIC ROOTS . AIRCRAFT RESPONSE TO CONTROL NEUTS Mag = 25 (va Initial F vator THRUS* LEVER
(rad/sec²)/in Z81=11.9 (H/sec²)/in
Final Initial Final ELEVATOR THRUST LEVER Viag : (rad/sec2)/in Zag :
Init-al Final (fl/sec²)/-n Final CONTROL SENSITIVITY Initial TOO GREAT SATISFACTURY SATISFACTURY TOO SMALL RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudina: velo
VMC LM.C

CUT OUT VMC LIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS DISTIDUT TO CHECK LARGE SPEED CHANGES. MARKE THROTTLE MOVEMENTS REQUIRED TO CONTROL DATE OF DISCENT. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE ZERO JERO DAMP:NG AMP_ITUDE PE RIOD DAMPING SOURCE DEGREE SOURCE DEGREE EXCITATION CONTROL COMMENTS ANY MOLLONS HAD A GANDOM NATIGE RATHER THAN AN ASCILLATORY ONE. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION S JCH. D.FFICULTY DIFF CULTY COMMENTS NEED FOR THRUST NOT EVIDENT. 5 FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Final track | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Localizer | Gide path Gide Intercept 8 init al track | Intermedia's track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | 0:FFICULTY NUMERATE MODERATE PRECISION MINIMUM ACCEPTABLE BREAKOUT ALT TUDE
-F GREATER THAN 200 FEET 19.1 COMMENTS NOSESSIN DIFFERENTALLA COMPROLLING COLDUM PATTEON FINA APPROACH, LARGE TRIOTTLE MORENENES REQUIRED, 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT WYDERATE DEFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT FALS CIFF CULTY COMMENTS district to bus no proprietal early agreed 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NOW: 9 LEAST GBUECTIONABLE FEATURES

IO MOST OBJECTIONABLE FEATURES - TEXPORT IN GREAT WAS EXCHAPATION OF THE PROPERTY OF THE PROPE



CONFIGURATION 4-3L FLIGHT NUMBER 120-2 PILOT A PILOT A
PILOT-RATING 8

WIND(knots) 10 WIND SHEAR SMALL EXTERNAL TURBULENCE MEGLIGIBLE CONFIGURATION 4-3L F_IGHT NUMBER 76-3 PILOT B PILOT B
PICT-RATING BD

V8E - 30

ELEVATOR

W ND (knots) WINC SHEAR SHALL EXTERNAL TURBULENCE MODERATE

CR THRUST LEVER
(roa/sec²)/m ZBI: 15.0 (ft/sec²)/m
Final nital Final

CHARACTERISTIC ROOTS

-.17# .29i +.18 -1.64

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEV	ATOR	THRUS	LEVER
Mag= .25	(rad/sec ²)/in	Z87 41.9	(Hr/sec ² i/-r-
Initia	Final	Initial	Final
SAT IS FACTORY	TOO GREAT	SATIS FACTORY	SAT1S FACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY

MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS

Vertical velocity (h)
C IMC IMC
C OUT IN velocity (IAS) | Ungitualing | Vertical | Vertical | VMC | IMC | IMC | VMC | VMC | VMC | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT | UUT OUT OUT IN SLIGHT MODERATE GREAT GREAT:

AN INCREASE IN AIRSPEED CAUSES AIRCRAFT TO CLIMB AND WICE WERSA, RESILES IN AIRSPEED AND MERTICAL STEED DIFFICULT IES ESPECIALLY ON THE APPROACH, PITCH CONTROL CAUSES A STEADY STATE RATE FOR A STEADY INPUT RESULTING IN A HIGH WORK LOAD. Long tudinol velocity (TAS) VI VMC IMC IMC VMC OUT OUT IN OUT SLIGHT MODERATE NODERATE SLIGHT Vertical velocity (h)

VMC IMC IMC CUT IN MODERATE

Int of Final Art of Final
SATISFACTORY SATISFACTORY SATISFACTORY

DIFFICULTY CAUSED BY BOTH EXTERNAL AND SIMULATED TURBULENCE, AND APPARENTLY HIGH COUPLING BETWEEN ALRSPEED AND VERTICAL VELOCITY.

3 RESIDUAL CSCILLATORY CHARACTERISTICS

EXCITATION.

CONTRO. COMMENTS

AMPLITUDE	PERIOD	DAMPING
ZERO		
ZERC		l
SOURCE		DEGREE

AMP_ITUDE PERIOD DAMPING DEGREE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MODERATE O FFICULTY

THE AIRSPIED FELLOFF IN THE FIRST TURN AND APP LOATION OF A PAIR ANDOEST OF ROMES DID NOT STOF THE AEGORET. THE SECOND TURN WENT WOLL AS THE AIRSPIED WAS WEPT

CONSTANT.

SMALL NUME/SLIGHT D FFICULTY

SLIGHT

FAIR POOR FAIR POOR FAIR

MUST BE CAREFUL WITH THIS MODEL TO HOLD ASSESSED IN TURNS.

DUFFICULTY AT INTERCEPTION CAUSED BY 200 FEET HEIGHT LOSS IN PINAL TURN. SPEED CONTROL VERY IMPORTANT.

SLIGHT

FAIR

MODERATE MODERATE

FAIR/POOR FAIR/POOR

5. FL:GHT PATH CONTROL

DIFFICULTY: PRECISION

	initial frack			Final	
Gude path	Localize	Glide potn	Localizer	Glide path	Localize
морекате	SLIGHT	MODERATE	SLIGHT	GREAT	MODERAT
7003 i	Pook	POOR	POCR.	. VERY POOR	PCOR

COMMENTS

AS THE AIRSPERD INCREASED WE FRAM HIGH ON THE GLIDT PATH. THO MYCH AITENTION WAS REQUIRED TO THROST CONTROL. A VERY HIGH NEAD DESCRIPT RATE SEERIED NECESSARY BY THE ORDER OF 1000 F.P.M.), AND WE STILL DETERMINE HIGH.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT	NO
PRECISION OF ATTAINING TOUCHDOWN POINT	(300 b

COMMENTS

NO	D FFICULTY
GOOD	

POOR POOR

5 LLGHT

DIFFIC-UT NUDEL FOR SPEED AND HEIGHT CONTROL. TOUGHDOWN WOULD HAVE BEEN SHORT BECAUSE OF INABILITY TO ARREST DESCENT IN TIME.

7 CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM : A S WITH ELEVATOR AND VERTICAL SPEED WITH "HRUST LEVER

B LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT S.NA I.

ODERATE.

500

9 LEAST OBJECTIONABLE FEATURES

IO. MOST OBJECTIONABLE FEATURES WIRSPERD EFFECT ON POWER REQUIRED.

POOR ATTITUDE STABLLITY AND LARGE ATTITUDE RESPONSE TO TIRBULENCE, ROUGE RIDE IN TURBULENCE, APPARENT LIN REIGHT-RATE DAMPING.

.I MISCELLANEOUS

RATE OF DESCENT ON APPROACH SEEMED SIGHER THAN

DIFFICULT TO KNOW WHAT TO BO IF LOW ON CLIDE SLOPE AND OUTFOON SPEED. HAD TO SPEAKE THE HEIGHT AND SPEED CONTROLS BY PIRST ADJUSTING AIRSPEED TO SO KNOTS AND THEN THE POWER FOR MEIGHT CONTROL.



CONFIGURATION 19-21 WIND (shots) 10
FEIGHT NUMBER 95-2 WIND SHEAR SMALL
PILOT B EXTERNAL TURBULENCE LIGHT CONFIGURATION 19-2 FLISH* NUMBER 17-2 PLOT A 10-15 WIND(knots) WIND SHEAR MODERA EXTERNAL TURBULENCE LIGHT MODERATE PILOT A
PILOT-RATING 6 PILOT-RATING 7 /2 C CHARACTERISTIC ROOTS 0 ± .1631 -.53 ± .9211 CHARACTERISTIC RCOTS | n ± , 1634 | -.53 ± | .021i LA:RCRAFT RESPONSE TO CONTROL INPUTS E_EVATOR M8E :0.25 (re CONTROL SENSITIVITY 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS SLIGHT THE PITCH ATTITUDE REQUIRES TOO NECH ATTENTION FOR COMPORTABLE PITCH. PITCH CONTROL MAS ABSTLAVE, BUT SHALL INATTENTIONS RESULTED IN THE ACRECIED COMMON TOO REPORT. COMMENTS PITCH CHARACTERISTICS MAKE AIRSPEED AND THEREFORE, HEIGHT CONTINUL BLEFFICHT. (SOME INTERACTION) 3 RESIDUAL OSCIELATORY CHARACTERISTICS AMPLITUDE SMALL AMPLITUDE PERIOD SMALL MEDIUM PERIOD LONG SOURCE EXCITATION CONTROL ELEVATOR, TO RULENCE *DDC-SATIGLY MODERATE EFFECTIVE PERCEIVE A SMALL AMPLITUDE PITCH OSCILLATION DID NOT SHOR SET UNDER LARC. THE FITCH CONTROL WAS SEFFICITIVE IN CONTROLLING THIS, BUT REQUERED FOR MICH ACTIVITIES. 1080 NOTICEABLE (NOT ENTIRELY SORE) OTHERWISE THE MODEL IS UNSTABLE IN PITCH FOR LARGE INPUTS. COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS Mountani. CHANGE REQUIRED FASE OF COMPENSATION SMA...I. SIGSET DIFFICULTY COMMENTS NESO TO MOLD ADSPEAD AND ATTITUDE PRECISELY DUE TO DITERACTION OF WERTICAL AND HO CLAUMIAL SPEED EFFECTS. 5 FLIGHT PATH CONTROLL Intercept 8 mit al track Intermedials track Final track Glide pott Localizer Glide pott Localizer Glide pott Localizer | Interces | 8 n hal track | Intermediate track | Final track | Glide path | local zer | Glide path | Cocalizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide pa DIFF CULTY SAUGHT STARPT MOLERATE MODERATE MODERATE GREAT NONE SEIGHT SGIGHT SLIGHT PRECISION OCOD LEADS POST POCK ATT (a)00) (b)000 CATR PAIR WIN MUM ACCEPTABLE HREAKOUT F GREATER THAN 200 FEET A.1 TJDF THE MIN'S SHOW WAS DESCRICTED TO MESSES AND MESSESS FROM NOTIFICAL SHOPS OF ALL SECTIONS OF THE COLOR STORMS OF ANY AND AND A STORMS OF THE ALL SECTIONS OF THE COLOR AND ANY AND ANY AND AND AND ANY AND AND AND AND AND A DIFFICULT TO WAINTAIN ROOD CROSS CHECK ON LOCALIZER BERGE B.CAUSE OF POOR LONGITHDINA, CHARACTERISTICS (ATTITUDE, AIRSPEED, VERTICAL VELOCITY, COUPLING). COMMENTS 6 BREAKORI AND FLARE FASE OF ARRESTING MATE OF DESCENT IN TERMS OF ALL MATERIAL AND THE COLOR OF ALL MATERIAL AND THE VERY STITUTE OF FIGUREY
FAIR 14000 COMMENTS 7 CONTROL TECHNIQUE COMMEN'S FORFERENT FROM LAS WITH ELEVATOR AND VEHT FALL SPEED WITH THE IST . EVER 6 LATERA SIRECTIONAL CHARACTERISTICS FFFECTION FROM ASSESSMENT NOW. 9 LEAST CBDTC PONABLE REATHERS CONTRACTO TO TRANSPLENCE NOT BAD O MOST OBUE DOMANDE FRANCHES IN THE STREET PICCO INSTACTUTE AND APPARENT INDEPLYING SMALL PICCOUNG COLLIATION IN A WILLOW APPARENT TO BE GIVEN TO LAWFOR THE ACTURE S. A CHARLEMENT CONTROL AND PICCA DOCUMENT AND PICCA DOCUMENT AND PICCA DOCUMENT AND PICCA DOCUMENT of all of interaction of a speed and ventical velocity and the other particles of $G_{\rm s}$ and the factor than the $G_{\rm s}$ and the condition of $G_{\rm s}$ and the condition of $G_{\rm s}$ and $G_{\rm s}$... MIRGELL ANALYSIS CVI marketing to the control of the co



CONFIGURATION 19-2 WIND(knots) LICHT CONFIGURATION W ND (knots) FLIGHT NUMBER 43-2 PILOT D WIND SHEAR SMALL. EXTERNAL TURBULENCE MODERATE WIND SHEAR EXTERNAL TURBULENCE FLIGHT NUMBER PILOT D
PILOT-RATING 61/2 PLOT PILOT-RATING CHARACTERIST C ROOTS I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

MBE = 0.2 (-ad/sec²)/m Z8 = 15.0 (h. ELE VATOR THRUST LEVER [ft/sec²)/in F.nal MaE: (*od/sec²)/ n Z8T :
Finol 7:1 at CONTROL SENSITIVITY TOO GREAT TOO GREAT 2.EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (TAS)
VMC LMC LMC
OUT OUT IN Longitudinal velocity (IAS) Vertico velocity (R)
VNC IMC IMC VNC IMC IMC
OUT OUT N
SELICITE DESCRIPTS PODERATE SELICITE PROBRATE GREAT F: IGHT CONDITION TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTIATIONS ± L0 COMMENTS INITIAL INPUTS DID NOT GIVE IMMEDIATE NOTICEABLE CHANGES BUT THEY, ONCE THEY DID BECOME NOTICEABLE THEY WERT RAPID. 3 RESIDUAL OSCILLATORY CHARACTERISTICS CAMPING PITCH EXCITATION CONTROL COMMENTS CONFIGURATION VERY LOOSE IN FITCH -- LOW ANGLE OF ATTACK STABLLITY OR ZERO DAMPING SERMED OK. 1.01% OF TROUBLE IN HIGHT CONTROL 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED: EASE OF COMPENSATION HODERATE DIFFICULTY DIFFICULTY COMMENTS: DIFFIGURTY DUE TO LAG IN RESPONSE AND THEN LARGE RESPONSE ONCE STARTED, $% \left(1\right) =\left(1\right) \left(5. FLIGHT PATH CONTROL Intermediate track Final track
Glide path Localizer Glide path Localizer Intercept & instal track
Glide path Localizer rtermediate frack Final Irack
Glide path | Localizer | Glide path | Localizer Final Irack DIFFICL.TY: SLICHT MODERATE MODERATE > MC DERATE > MC DERATE PREC-SION GOOD MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
F GREATER THAN 200 FEET COMMENTS: 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT
FAIR D:FF.CULTY COMMENTS: 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES NO STRONG PIC TENDENCY IO. MOST OBJECTIONABLE FEATURES REQUIREMENT TO CONSTANTLY ADJUST THROST CONTROL AND PITCH ATTITUDE BUT MOSTLY POWER. H MISCELLANEOUS PILOT'S PERFORMANCE OF TASK WAS REASONABLY COOD BUT REQUIRED HIGH WORKLOAD.



WIND(knots) 5
WIND SHEAR SMALL,
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION 19-3), FLIGHT NUMBER 92-1 PLOT B PLOT-RATING 80 CONFIGURATION L9-3L FLIGHT NUMBER L17-3 PILOT A PILOT-RATING 9 WIND (knats) WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLICIBLE CHARACTERISTIC ROOTS .04± CHARACTERISTIC ROOTS .04± .261 -.44 -.65 .251 -.49 -.65 LAIRCRAFT RESPONSE TO CONTROL INPUTS Mag = .30 (+0d/sec2)/in Z87 = 15.0 (+1/4 (ft/sec2)/in CONTROL SENSITIVITY: SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY RESPONSE -2 EASE OF MAINTAINING DESIRED VELOCITIES Congitudinal velocity (TAS)

VMC TMC CMC

OUT CUT IN

MODERATE GREAT GREAT FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS WHAT APPEARED TO BE A DIVERGENT LONGITUDINAL OSCILLATION, COUPLED WITH A HIGH TURBULENCE SENSITIVITY AND LARGE COUPLING BETWEEN ALSPEED AND NORMAL FORCE, GAVE THE PT OT A LARGE MOREOUR RESULTING IN POOR CONTROL OF ALRESPEED AND FERLICAL SPEED. DIFFICULTY CAUSED BY AIRSPEED, VERTICAL VELOCITY COUPLING. POWER CHANGES AFFECT PITCH ATTITUDE AND HENCE AIRSPEED. 3 RESIDUAL OSCILLATORY CHARACTERISTICS HEAVE SOURCE DEGREE
ELEVATOR, TORBULENCE EASILY
ELEVATOR, TORBUST LEVER INEFFECTIVE EXCITATION THE MODAL MOTION SEEMED TO BE WIND PERIOD DIVERGENT OR PERIODS A STRAIGHT PITCH DIVERGENCE. COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION NO DIFFICULTY COMMENTS NO DIFFEROUTY AS LONG AS THE AIRSPEED WAS MAINTAINED. THERE IS A NEED TO HOLD AIRSPEED CONSTANT. (ie. GOOD ATTITUDE CONTROL IS NEEDED. 5. FLIGHT PATH CONTROL Intercept & initial track | Intermed ale track | Final track Glide path | Localizer | Glide path | Localizer | Glide path | Localizer intermediate track Glide path | Localizer Glide path Localizer DIFFICULTY MODERATE SLIGHT GREAT SLIGHT GREAT l rook PAIR FALK/POOR VERY POOR MIN:MUM ACCEPTABLE BREAKOUT ACTITUDE
F GREATER THAN 200 FEET 1003 59.) COMMENTS THE SNORMULS REFECT OF APASPEED ON LIFT (INCREASE IN AIR-SPEED INCREASES LIFT) MADE CONTINUE, OF THE MATE OF DESCRIP VERY DIFFEGURE. HEIGHT CONTROL DIFFIGURE DUE TO COUPLING BETWEEN AIRSPEED AND VERTICAL VELDOUTY, AND FITCH AITITUDE CHANGES DUE TO DOMER LEYER OPERATION. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SD DEFICULTY PRECISION OF ATTAINING TOUCHDOWN PCINE SUND SLEGIC DIFFICULTY COMMENTS BESH ON CLIDE SLOPE AND BROKE OUT EARLY (350 FEET AGL) SO AS NOT TO OVERSEOOT LANDING POINT. 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST CEVER NOT INTENTIONALLY DIFFERENT BUT AIRSPRED CHANGES CERTAINLY AFFECTED VERTICAL VELOCITY. 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE HONG. HOWEVER, WABLE TO TRIM LATERAL CHANNEL. 9 LEAST OBJECTIONABLE FEATURES NONE IO MOST OBJECTIONABLE FEATURES AS PER SECTION 2 AMOVO. CHARGE TO RELATE SOME OF THE ALRGRAFT RESPONSES TO PILOT CONTROL APPLICATION. MEIGHT CONTROL POOR, ALRCRAFT DIVERGENT IN PILOT, POWER CHANGES AFFECT PITCHING MOMENT. II MISCELLANEOUS ATTAINED 1700 7.7 M. RATE OF DESCRIT ON APPROACH UNINTENTIONALLY SCHRAL TIMES AUTHOUGH I MEEDED IT.



	CONFIGURATION 19-3 WIND(knors) 5 FLIGHT NUMBER 13-3 WIND SHEAR SHALL PILOT 8 EXTERNAL TURBULENCE LIGHT PILOT-RATING 10	CONFIGURATION WIND (Knots) FLIGHT NUMBER WIND SHEAR PILOT EXTERNAL TURBULENCE PILOT-RATING
	CHARACTER STIC ROOTS .04 ± .2614965	CHARACTERISTIC ROOTS
LAIRCRAFT RESPONSE TO CON- CONTROL SENSITIVITY	Mag: ,20	Wag : Ind/sec2 //m Zag : (ft/sec2 //m Intral Final
RESPONSE: 2 EASE OF MAINTAINING DESIR	SATISFACTORY NOT ASSESSABLE SATISFACTORY NOT ASSESSABLE	
Z EASE OF MAINTAINING DESIR		Langitudinal velocity (IAS) Vertical velocity (fi)
FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATION	VMC IMC JMC VMC IMC IMC VMC IMC VMC IMC VMC IMC VMC IMC VMC Longitudinal velocity (1AST Vertical velocity (n)	
COMMENTS	UNABLE TO ASSESS WHAT IS HAPPENING ALONG THE VERTICAL AXIS.	
3 RESIDUAL OSCILLATORY CHAR	ACTERISTICS	
PITCH	AMPLITUDE PER OC CAMPING	AMPLITUDE PERIOD DAMPING
HEAVE		
FXCITAT: ON	SOURCE DEGREE	SOURCE DEGRÉE
CONTROL		
, COMMENTS		
4. CHANGE IN THRUST REQUIRE	D FOR 20° BANKED TURNS	
CHANGE REQUIRED EASE OF COMPENSATION	EXCESSIVE DIFFICULTY	DIFFICULTY
COMMENTS	PROCERTAINTY AS TO WHAT WAS HAPPENING. ON ONE OCCASION	31.7.800.1
	FOLL THROW OF THE POWER LEVER FAILED TO PRODUCE THE REQUIRED RESPONSE. INCREASING THE VALUE OF 48T FROM 11.9	
	TO 15.0 DID NOT MAKE MUCH [MPROVEMEN].	
5. FLIGHT PATH CONTROL		
	ntercept 8 initial track Intermediate Track Final track Glide path Localizer Glide path Localizer Glide path Localizer	Intercept 8 initial track termediate track Final track Gride path Lacalizer Glide path Lacalizer Glide path Lacalizer
DIFFICULTY	GREAT GREAT GREAT	
PRECISION	VERY POOR VERY POOR	
MINIMUM ACCEPTABLE BREAKOL		
F GREATER THAN 200 FEET	15QQ	
COMMENTS	MODEL NOT SUITABLE FOR LINIG. PID-UT. PRABLE TO TRACK VERHIGAL VERDITIES.	
6 BREAKOUT AND FLARE		
EASE OF ARRESTING PATE OF DI	SCENT CIFFICULTY	
PRECISION OF ATTAINING TOUCHD		DIFFICULTY
COMMENTS.	BREAKOUT AND FLARE MOT AGRIEVED,	_
7 CONTROL TECHNIQUE		
COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND		
VERTICAL SPEED WITH THRUST LEVER		
8 LATERAL DIRECTIONAL CHAR	ACTER(STICS	
EFFECT ON FINAL ASSESSMENT		
9 LEAST OBJECTIONABLE FEA	TURES	
O MOS" OBJECTIONABLE FEAT.	RES HEIGHT CONTROL NOT ACCEPTABLE.	
I MISCEL: ANEQUS		
	THREST EVEN SENSITIVITY CLARGE PROBETLY to 15.0.	



CONFIGURATION 7-2L FLIGHT NUMBER 77-2 PILOT A PILOT-RATING 9

CHARACTERISTIC ROOTS -.013* .1431 -.26 -1.51

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

MBE =0.3 OR THRUST LEVER (Indexes)/in ZBT=9.0 (It/sec?)/in CONTROL SENSITIVITY SATISFACTORY Final Initial Final
TOO GREAT SATISFACTORY SATISFACTORY RESPONSE

2. EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE:
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

Longitu	Congitudinal velocity (IAS)			Vertical velocity (h)		
V.M.C.	LMC	J.M.C.	VMC	1.M.C	IMC	
OUT	OUT	iN	QUT	OUT	IN	
MODERATE	GREAT	GREAT	MODERATE	GREAT	GREAT	
	±15	knots		±400	Ipm.	

COMMENTS:

STRONG COUPLING BETWEEN VERTICAL SPEED AND ATRSPEED MAKES BOTH MISERABLE TO CONTROL. THIS WAS ESPECIALLY TRUE ON APPROACH AND DURING THE 20° BANKED TURNS.

ELEVATOR THRUST LEVER

Mag =0.3 Irod/sec² I/in ZaT=9.0 (11/5)

Employ English English English [ft/sec2Vin trilial Final Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY

CHARACTERISTIC ROOTS -_013 ± .1431 -. 26 -1.51

WIND (knots) S WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

Longitudinal velocity (IAS)		Vertical velocity (h)		(h)	
VMC	LMC	LMC	VMC.	Ţ Ţ₩Ç	IMC
DUT	OUT	IN	DUT	OUT	I N
SLIGHT	SLIGHT	MUDERATE	SLIGHT	SLICHT	SCICHT
	+10, -4	knals		-	fpm

CONFIGURATION 7-2L FLIGHT NUMBER 94-2 PILOT B PILOT-RATING 7C

DIFFICULTY BUE TO:

1. INTERACTION BETWEEN AIRSPEED AND VERTICAL SPEED
2. PITCH INSTABILITY
3. TENDENCY TO PUT MUSE DOWN TO CATCH GLIDE SLOPE.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH HE AVE

AMPLITUDE	PERIOD	DAMPING		
2.ERO		I		
ZE RO				
		'		
SOURCE	!	DEGREE		

EXCITATION CONTROL

COMMENTS

AMPLITUDE	PERIOD	DAMPING
3 E AO		T
ZERO		I
SOURCE		DEGREE
		

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

MODERATE SHEAT DIFFICULTY

COMMENTS :

AS LONG AS THE APREPERD WAS MAINTAINED ACCURATELY, THE ACTITUDE DID NOT VARY, BUT A VARIATION OF 5 KNOTS WOULD INSULT IN A RATE OF DESCENT GREATER THAN SOU F.P.M.

DIFFICULTY

AIRSPEED MUST BE MAINTAINED PRECISELY RECAUSE OF ITS EFFECT ON VERTICAL SPEED.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept & mitial track				Final track	
Glide path	Lacalizer	Glide path	Localizer	Glide poth	Localizer
NODERATE	SLICHT	NODERATE	n/a	GREAT	N/A
200 R	FAIR	VERY POOR		P00 R	

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

IACALIZER FAILED ON APPROACH. PRECISE CONTROL OF AIRSPEED IS REQUIRED FOR RECISE CONTROL OF VERTICAL SPEED. AT ONE STAGE THE AIRSPEED FELL OFF TO ABOVED 50 KNOTS AND THE RATE OF DESCENT HENT TO 1600 F.P.H. CORRECTING THE AIRSPEED FAID ADDISO A TOUCH OF POWER DECREASED THE RATE OF DESCENT TO 300 F.P.H.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT HODERATE DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT POOR

COMMENTS

DIFFICULTY AS IN SECTION 2.

Intercept & initial track				Final track	
Glide path	Localizer	Glide path	Laculizer	Glide path	Lacalizer
NONE	SLIGHT	NONE	SLIGHT	SUIGHT	MUDERATE
GOOD	6000	GOOD	FAIR	FAIR	Poor

400

INITIAL LOCALIZER DIFFIGULTY BECAUSE INTERCEPT ANGLE OF 90° IS TOO LARGE. 'S' TURNING ON TOCALIZER BECAUSE OF DISPLAY/ GROSS-CHECK. LATERAL TASK REQUIRES TOO MUCH ATTENTION.

DIFFICULTY SLIGHT

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM : A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL: READING CONTROL DIFFIGULT

MONE

9 LEAST OBJECTIONABLE FEATURES

O MOST OBJECTIONABLE FEATURES IN PERCEPTIBLE PITCH ATTITUDE STIFFNESS, AIRSPEED EFFECT ON VERTICAL SPEED.

PITCH INSTABILITY.
PITCH SOMEWHAT SENSITIVE TO TUABULENCE.

I MISCELLANEOUS

THE LOGALIZER FAILED PART WAY DOWN APPROACH BUT I DO NOT THINK IT AFFECTED MY RATING.

NOTE: THE ARTIFICIAL TURBULENCE WAS NOT INTRODUCED DURING THIS EVALUATION.



CONFIGURATION 8-21. FL:GHT NUMBER 60-2 PILOT A
PILOT-RATING 7

WIND(knots) WIND SHEAR SNALL EXTERNAL TURBULENCE LIGHT

-.t0± .t2i 0 -1.60

CHARACTERISTIC ROOTS

CONFIGURATION 8-2L F_IGHT NUMBER 44-2 PILOT B P-LOT-FATING 9C

WIND SHEAR EXTERNAL TURBULENCE HODERATE

CHARACTER:STIC ROOTS -.10± .121 0 -1.60

DAMPING

DEGREE

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELEV	ATOR	THRUST LEVER		
MaE = .30	(rod/sec2)/m	Z8T= 12.0	(It/sec ²)/inj	
Initia	Final	Initial	Final	
SATISFACTORY	TOO SMALL	TOO SMALI	TOO SMALL	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE-DIFFICULTY MAX-MUM UNDESIRED FLUCTUATIONS

	Langitudinal velocity (IAS)			Vertical velocity (h)		
	V.MC	1MC	IM C	V M C	I M C	TMC
	OUT	QUT	IN	QUT	OUT	IN
	MODERATE	MODERATE	GREAT	MODERATE	GREAT	GREAT
ŝ	+15.	-30	knois			fpm

THE INTERACTION RETHERN MERTICAL MELOCITY AND AIRSPEED MADE SOTH AIRSPEED AND ALTITUDE MONTHOL OFFICIALT, PILLLING NOSE OF RESTUTION, MUCH TOO NICH AITEMTION REQUIRED TO AIRSPEED CONTROL.

Vertico VMC OUT SLIGHT S ±100 SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT

SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY

REASON FOR DIFFICULTY NOT KNOWN, POSSIBLY TURBULENCE, TURN COORDINATION AND GROSS-CHRCK.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS

AMPLITUDE	PERIOD	DAMPING
ZERO ZERO		
SDJRCE		DEGREE
300402		DEGREE

EXCITATION CONTROL COMMENTS

PILOT-INDUCED PITCH-HEAVE OSCILLATION ON DOWNWIND LEG. COULD HAVE RETAINED CONTROL.

AMPLITUDE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DFFICULTY

COMMENTS

TERUST REQUIREMENTS WE'RE SMALL AS LONG AS THE AIRSPEED WAS MAINTAINED CONSTANT. TRINIST REQUIREMENTS RECAME SUR-PRISINGLY LANGE WITH CHANGING AIRSPEED.

MODERATE/SLICHT DIFFICULTY

SOME THRUST REQUIRED IN TURNS BUT COULDN'T LEARN PHASING OF POWER REQUIREMENTS. REASON FOR DIPPICULTY UNKNOWN.

5 FLIGHT PATH CONTROL

DIFFICULTY

Intercept & initia track				Final track	
Glide path	Localizer	Glide poth	Lacal ger	Glide path	Localizer
SLIGHT	S'.IGHT	GREAT	HC DERATE	FORERATE	GREAT
POUR	POOR	Pook	POOR	V. BOOR	V. POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

DIFFICULT TO CONTROL RATE OF DESCENT AS AIRSPEED AND POWER

Intercept B initial track Intercept B initial track intermediate track Final track
Slide path Localizer Glide path Localizer Glide path Localizer >SLIGHT NONE NONE SLIGHT >NONE FAIR FA LR /0001

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

MC0ERATE:	DIFFICULTY
POOR	

COMMENTS

SLIGHTLY REDUCED PERFORMANCE ON INITIAL TRACK DUE TO RAPID ROLL TO 20 DEG. BANK REQUIRED TO INTERCEPT LOCALIZER.
SOME DIFFICULTY DUE TO WIND SHEAR AND CROSS-CHECK.

SOME P. L.O. TENDENCY JUST PRIOR TO TOUCHDOWN.

NONE

DIFFICULTY

? CONTROL "ECHNIQUE

COMMENTS IF DIFFERENT FROM
LAS WITH ELEVATOR AND LEVER APPEARED TO BE LITTLE GURBELATION BETWEEN THRUST LEVER MOSITION AND RAID OF CLIMB WIRN THE AIRSPEED BROPED OFF.

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

COOD CONTROL OF VERTICAL VELOCITY ON APPROACH. GOOD ATTENUATION OF HIGH FREQUENCY DISTURBANCES IN PITCH.

IC MOST OBJECTIONABLE FEATURES

ENTERACTION RETWEEN ATRISPEED AND VERTICAL SPICED, ATESPETO CONTROL REQUIRED MUCH TOO NORTH ATTENTION.

PITCH-HEAVE DIVERGENCE WHICH SEEMED TO BE A RESULT OF THE SIMULATION OF THE PILOT STATION AHEAD OF THE C.C. UNCERTAINTY OF POWER RESPONSE. PITCH LOOSE IN STEADY STATE.

I. VISCELLANEOUS

THE RATING OF 90 WAS MAINLY INFLOENCED BY A PITCH-HRAFF DIVERSENCE MIJOR WAS INTENTIONALLY EXCITED ON THE DOWNING LEG. OTHERWISE A RATING OF 60 HOULD HAVE BEEN LIVEN.



CONFIGURATION 6-2L FLIGHT NUMBER 103-1 PILOT 0 PILOT-RATING 4;

WIND(knots) 5 WIND SHEAR NEULIGIBLE EXTERNAL TURBULENCE NEULIGIBLE

CHARACTERISTIC ROOTS

-.10 ± .121 0 -1.60

LAIRCRAFT RESPONSE TO CONTROL INPUTS

	ELE:	POTAV	THRUS	
CONTROL SENSITIVITY	MsE: .3	(rod/sec2)/n	ZET = 7.4	(11/sec ²)/in
	Install	Final	citial	= nal
RESPONSE -	SATISFACTORY	SATISFACTORY	SAT 15 FACTURY	SATISFACTORY
		•		

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

	ongitu	dinal veloci	ty (IAS)	Vertical velocity (h)		
	VMC	1 W.C	I M C	AWC	IMC	: M C
	CUT	QU1	IŊ	Out	OUT	lN
	NUNE	STIGHT	SLIGHT	NONE	SLIGHT	MODERATE
S	EXCEPT ON	FINAL, ±	knots			fpm f

COMMENTS

ENGIN- MANIFOLD PRESSURE VERY SERSITIVE TO A RESCRIPT CHARGES HERCE THREE MAS A RELECTANCE TO APPLY PORFE HERMAN ACCORDANCE AND AT TAKE PORCE SETTING. THE RESULT WAS A TOSS OF METHIT, PARTICULABLY ON BASE LCG.

(ft/sec²)/in Intial Final Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY

WIND (knals)

WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION 8-2L FLIGHT NUMBER 126-1 PLOT C PLOT-RATING 4

["]	Long tudinal velocity (LAS)				Vertical velocity (h)		
1	MC	EM C	/ M.C	TV MIC	LWC	IMC	
	DUT	OUT	TN	CUT	Out	N.	
,s	LIGHT	SLICHT	MODERATE	57,LGHT	SLIGHT	MODERATE	
		5	knots			(pm	

DIFFICULTY GAUSSED BY EFFECT OF AIRSPEED VARIATION ON THRUST RECRIRED.

3 RES'DUAL CSC:LLATORY CHARACTERISTICS

AMPLITUDE PER		C	DAMPING	
4.500				
2 (40)				
\$0JRCE			DEGRÉE	

EXCITATION CONTROL COMMENTS

AMPLITUDE .	PERIOD	DAMPING
(ERO		
ZERG		I
SCURCE		DEGREE
SCURCE		DEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MODERATE MODERATE DIFFICULTY

COMMENTS

THRUST RES. LEGEBLES IN THRUSE WHEE PROBABLY GRECORED BY THRUST SENSITIVITY TO MIRSHEST CHANGES.

D FFICULTY

91 FFICULTY ASSOCIATED WITH THRUST LEVER ACTION REQUIRED TO COMMENSATE FOR EFFECTS OF AIRSPEED VARIATIONS.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept & init at Irack					inal track	
Glide path	Localizer	Glide poth	Localizer	Gl de path	Localizer	
ST. GHT	Stateart	STIGHT	SLIGHT	MODERATE	MODERATE	
GOOD	GOUD	6005	GOCD	POOR	PAIR	

MIN:MUM ACCEPTABLE BREAKOU* ACTITUDE IF GREATER THAN 200 FEET TO

BROKE OPT AT 300 FEET BUGAPS, AUSSPIED HAD SWIGEA BEIFW SA KREET IN TRYING TO MAINTAIN GUIDI SOUPE AND LOGALIEUR.

Intercept 8 initial trock | Intermediate track | Final trock | Giide path | Lacahzer | Giide path | Lacahzer | Giide path | Lacahzer | MODERATE SLIGHT SLIGHT NONE SLIGHT coan 0000 FAIR POCK GOOD

DIFFICULTY DURING DISSION JOS PERT ON BASE LEG PRIOR TO GLIDE PATH INTROCPT. MEFECULT TO MAINTAIN BEIGHT AT 1900 FRET MITH CORRECT AIRSPEED AND HEADING.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SUDERY DIFFICULTY PRECISION OF ATTAINING TOUCHDOWN POINT

-MAY B PRICOINY WAS ASSOCIATED WITH SEGMENT OF BY WEST AS SPERD DEGREE STARE.

STATE DIFFICULTY

SONE.

ATRIPEST INCREASED TO 57 KNOTS BURING PLANE DUE TO OVERCOST ROLLING.

7 CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SNACE, LAIRRY, ANGUS SERRES Y COTTES NO 9-EN COMPARISON & DE LONGITUDINAL FORCES,

9 LEAST OBJECTIONABLE FEATURES

NO DESCRIPTION OF ARACTURISTICS AND WEBSTION SERVICE FREEZING.

RELATIVELY PLEASANT MODEL V.M.C.

IC MOST OBJECT GNABLE FEATURES

NOTESTIVIO MAKE ARGE POLIC CHARGES IN LAUGH TO COORDEN FOR THE RESULTS OF SPREN OF CONTESTS.

TAIN DEFICULTY EXPONEENCED IN BUILDING TO KNOTS AND NATHYMENIAL METITUDE ON BASE LES WHILL DECELERATING TO BUILDING KNOTS.

H MISCELLANEOUS

MOST TAME WITH MODEL SLIGHTLY BETTER IF LESS CONCERNED WITH OVER BOOSTING ENGINE.



WIND (knots) WIND SHEAR EXTERNAL TURBULENCE CONFIGURATION 8-2L FLIGHT NUMBER 44-1 WIND(xnots) 5
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING PILOT D PILOT-RATING 8 CHARACTERISTIC ROOTS I AIRCRAFT RESPONSE TO CONTROL NPUTS ELEVATOR MBE = (rod/sec²)/in Zaj = Initial Final Initial CONTROL SENSITIVITY (11/sec²l/in Finol RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES | Lengitudinal velocity [[45] | V.MC. | IMC | I.M.C. | OUT | IN OUT OUT IN OUT
MODERATE NODER, REAT SLIGHT
ALC KNOIS FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS OUT IN MODERATE GREAT DIFFICULTY SEEMED TO BE CAUSED BY MODEL DWAG GRARACTERISTICS. SMALL CHANCES IN FITCH ATTITUDE PRODUCED LANGE AIRSPEED CANNESS. ALSO FELT AS IF THERE HAS A LAC IN THRUST LIVER RESPONSE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUCE PERIOD CAMPING DAMFING AMPLITUDE HEAVE DEGREE DEGREE EXCITATION CONTROL COMMEN*S AIRGRAPT FELT A LITTLE "LOOPE" IN PITCH BUT 300 RGI STOLLARE UNDER GREE-LOOP GONNETIONS. A STIGHT TEMPENCY TO P.1.0. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION MODERATE MODERATE CIFFCULTY CIFFICULTY COMMENTS DIFFICULTY PROBABLY DUE TO ROOK AIRSEED CONTROL. 5 FLIGHT PATH CONTROL Intercept 8 in rial track intermediate track Final track 6 de path Localizer Gilde path Localizer Gilde path Localizer ntercept 8 initial track Intermediate track
G ide pair Localizer Glide path Local zer DIFF.CULTY SLIGHT SLIGHT MODERATE: SLIGHT GREAT PRECISION FAIR V. 900R 200 C EALS | GOOD POUR V NIMUM ACCEPTABLE HREAKOUT ALTITUDE IF GREATER THAN 200 FEET 4(8) COMMENTS VERY HIGH ON GEIDE PATH AND HENCE EAC A SIGH WATE OF DESCENT (1500 7.5%). ATREP FOR LOW (A)-65 KISH AND SCHOOL HELD IT CONSTART AND CONCENTRATED ON STOPPING DESCENT, ENDED UP SHORT OF CONCENTRATED ON STOPPING 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT OF STATE OF ST OF CULTY COMMENTS -DIFFIGURBY DUE TO MERY HERE RATE OF DESCRIPT. 7 CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES PITCH DYNAMICS SEEMED WAIR NITH REASONABLE C MOST OBJECTIONABLE FEATURES VERY PAGE ALTSPIED CONTROL AND, AS A RESULT, DOOR CLIDE PAIT WINTERS SITE LARGE TREUST LEVER EXCURSIONS. I MISCELLANEOUS FLICKEM OF ROTOR SHADOW IN GOODPIT ANNOYING, MODEL RATING DUE MAINLY TO FOUR APPROACH PRECISION BELOW 1000 FEET.



CONFIGURATION 8-2 FLIGHT NUMBER 35-1 FILOT B CONFIGURATION 8-2 FLIGHT NUMBER 43-3 WIND (knots) wIND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT/MODERATE PLOT D PILOT-RATING 8 PILOT-RATING 83 CHARACTERISTIC ROOTS -.10± .121 0 |-1,60 CHARACTERISTIC ROOTS -.10 ± .121 0 -1.60 I AIRCRAFT RESPONSE TO CONTROL INPUTS (rad/sec²)/in Z8T 12.0 THRUST LEVER (fl/sec²l/in Final (fr/sec²)/in CONTROL SENSITIVITY SATISFACTORY SATISFACTORY TOO SMALL RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity ([AS]
VMC IMC IMC IMC
OUT OUT IN
NO SLIGHT MODERATE
±10 k-als Longitud nat | Velocity (LAS) VMC | IMC | I M C OUT | OUT | IN Vertical velocity (F FLIGHT CONDITION: MODERATE GREAT MAXIMUM UNDESIRED FLUCTUATIONS MODERATE INTERACTION BETWEEN AIRSPEED SPEED, APPARENT HEAVE OSCILLATION. SEEMED AS THOUGH HEIGHT DAMPING WAS EITHER ZENO OR NEGATIVE. ALL TROUBLES ASSOCIATED WITH HEIGHT CONTROL WORK LOAD. COMMENTS: AND VERTICAL PITCH MOMENT CONTROL WAS REASONABLE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERIOD MEDIUM TONG AMPLITUDE DAMP NG ZERC MODERATE/LARGE SLIGHTLY HEGATIVE SOURCE DEGREE DEGREE
PAIRLY EASILY
SLIGHTLY AGGRAVATING EXCITATION CONTROL POWER LEVER POWER LEVER COMMENTS EXCURSIONS IN VERTICAL VELOCITY WERE VERY LARGE, EXPECIALLY ON FINAL APPROACH BELOW LONG PRET. SEEMED LIKE AN OSCILLATION IN HEAVE BUT CHARACTERISTICS COULD BE 0.5 TO A LOWE TIPE CONSTANT IN RESPONSE TO EXEMPTE OF POWER LIVER, COULD PERSONS BE CONTROLLED BY FOMER LEVER BUT THIS WAS NOT PURSOED. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS. CHANGE REQUIRED EASE OF COMPENSATION NEGLIGIBLE DIFF CULTY DIFF:CULTY COMMENTS DIPPICULTY DUE TO LAS IN INITIAL RESPONSE TO POWER LEVER DEMANDS . 5 FL GHT PATH CONTROL Intercept 8 in hal track are rired ate track Final track 6 de path Localizer 6 ide path Localizer Side path Localizer Interceot 9 initial track | Intermediate track | Final track |
Slide path | Jocal zer | Glide path | Localizer | Stide path | Localizer | -aca-izer DIFFICULTY MODERATE >SLIGHT MODERATE MODERATE GREAT GREAT PREC SION POOR V. POOR V. POOR PALR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE F GREATER THAN 200 FEET 500 ATRIPER - VERTICAL VELOCITY COUPLING, TOGETHER WITH HEAVE OSCILLATION, CIVES POOR GLIDE PATH CONTROL. AS TALAR SENSITIVITY INCREASED NEAR END OF APPROACH, REASONABLE TRACKING ACCURACY, PARTICULARLY OF GLIDE SLOPE. COULD NOT BE MAINTAINED. 6 BREAKOUT AND FLARE EASE OF ARRESTING HATE OF DESCENT LELECT/NODERATE DEFICULTY
PRECISION OF ATTAINING TOJC-DOWN POINT PALS € FF'CULTY IF BREAKOUT SPOED IS LOW, IT IS MAKE TO REGAIN IT BY LOWEGING THE KOST, IF AT CORRECT AIRSPEED AT BREAKOUT IT IS POSSIBLE TO MAINTAIN AIRSPEED BY NOT FLARING. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM
(AS WITH ELEVATOR AND
VERTICAL SPEED WITH THRUST
LEVER

RESPECTATION OF THE MOUNT 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE. 9 LEAS' OBJECTIONABLE FEATURES FITCH AXIS WAS WELL DAMPED AND REASONABLY RESPONSIVE TO PILOT IMPUTS. HEAVE OSCILLATION: AIRSPIED - VERTICAL SPEED OF FILING, ELIVATOR AND POWER LEVER COSTROL RESPONSES. IC MOST CHUECTIONABLE FEATURES HEIGHT CONTROL REQUIRED EXCESSIVE PILOT ATTENTION. II MISCELLANEOUS MoDEL SERMOD REASONABLE IN VER FLIGST AND INC LEVEL TLIGHT. SOMEVER, WAS SURVEYED WITH GREAT DIFFLOUTY ON INC APPACE AN EARLOG SEPLECTS PILOT PERFORMANCE CURING THIS PART OF THE TASK?



CONFIGURATION 11-21, FLIGHT NUMBER 104-2 PILOT A

WINC(knois) 5 - 10 KNOT WIND SHEAR EXTERNAL TURBULENCE NEGLIGIBLE 5 - 10 KNOTS CONFIGURATION 11-2L FLIGHT NUMBER 101-2 PILOT 8 PILOT-RATING 7½2 C

Longitudina: velocity (145)
VMC LMC LMC
OUT IN

>SLIGHT >SLIGHT >SLIGHT

10 KNOTS

velocity (h)

>SLIGHT >SLIGHT >SLIGHT

WIND (knols)
WIND SHEAR
EXTERNAL TURBULENCE

VMC

CHARACTERISTIC ROOTS +.016 ± .2421 -.78 -1.04

SATISFACTORY SATISFACTORY SLIGHTLY SMALL SLIGHTLY SMALL

DIFFICULTY CAUSED BY LONG PERIOD PITCHING OSCILLATION.

PILOT A
PILOT-RATING 8

CHARACTERISTIC ROO"S +.016± .2421 -.78 -1.04

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENS TIVITY: TOO GRE VT SATISFACTORY SATISFACTORY SAT IS PACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAX MUM UNDES-RED FLUCTUATIONS

Longitu	dinal velaci	y (IAS)	Vert	ical velocity	(h)
V.M.C.	IMC	3 M 1	VMC	IMC	ĺΜC
OUT	QUT	IN	CUT	OUT	IN
SLIGHT	MODERATE	GREAT	SLIGHT	MUDERATE	CREAT
	±10	knots		± 50.7	1 pm

CHANGES IN AIRSPEED CAUSED THE VERTICAL VELOCITY TO CHANGE CHANGES IN AIRSPEED CAUSED THE VERTICAL VELOCITY TO CHANCE
IN AN UNSTABLE SENSE, THAT IS NOTH INCREASES IN AIRSPEED,
POWER INCREASED AND THE AIRCRAFT CLIMBED. THIS CAUSED
GREAT DISPIDUALLY ON THE APPROACH MHERE AIRSPEED CHANGES
MADE VERTICAL VELOCITY CONTROL DISPIDUAL TURBULENCE
DISTURBED PITCH ATTITUDE GREATLY AND VERY "LOCSE" CONTROL
OVER LATTER MADE AIRSPEED CONTROL DISPIDUAL
3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION

ZERC	PER OD LAMPING	
ZERC		
SOURCE	DEGREE	
		_

COMMENTS

THE PITCH ATTITUDE WANDERFO AND INITIALLY FELT LIKE THE BEGINNING OF AN OSCILLATION, BUT IT RESULTED IN A PURE DIVERGENCE.

AMPLITUDE	PERIOD	DAMPING
M:DERATE	LONG	ZERO
?	CONG	7
SOURCE		DÉGRÉÉ
ELEVATOR		EFFECTIVE

CANNOT BE SURE IF IT IS AN OSCILLATION IN HEAVE AS WELL. IF SO IT MAY BE PARTLY RESPONSIBLE FOR POOR HEIGHT CONTROL. THE CSCILLATION IS ALWAYS PRESENT.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED.

NEGLICIBLE
NO D FFICULTY

COMMENTS

SMAUL/MODERATE DIFFICULTY

POOR MEIGHT CONTROL, ESPECIALLY IN THE PRESENCE OF APPRECI-ABLE COUPLING BETWEEN AIRSPEED AND VERTICAL VELOCITY.

5 FLIGHT PATH CONTROL

DIFF: CULTY: PRECISION

		Intermedi		Final track	
Gli de poth	Localizer	Glide path	Lacanzer	Glide potr	Loca zer
MODERATE	SLIGHT	CREAT	SLIGHT	CREAT	SLIGHT
POOR	PA-R	VERY POUR	FAIR	ANNA MOUN	PA 12

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 500

AS PER SECTION ? ABOVE.

Intercept & initial track | Intermediate track | Final | Glide path | Cocalizer | Glide path | Cacalizer | Glide path | C Final track SLIGHT SLIGHT SLIGHT SLICHT FAIR GOOD FAIR/GOOD FAIR/GOOD FAIR/GOOD FAIR GOOD

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT DIFFICULTY

COMMENTS

DIFFIGURTY CAUSED BY SOME WIND SHEAR NEAR THE SURFACE (WIND USCRIASED WITH AUTITUDE). ALSO NEED TO INTENSIFY COOSS-CIECK IN THE PRESENCE OF MUR PITCH AND HEIGHT CHARACTERISTICS.

DIFFICULTY

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAIS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DRECTIONAL CHARACTERISTICS

FFFECT ON FINAL ASSESSMENT SMALL

NONE

SPEED, DESCENT CONTROL FOR FLARE SURPRISINGLY GOOD.

9 LEAST OBJECTIONABLE FEATURES

ID MOST OBJECT ONABLE FEATURES AS MIR SECTION 2 ABOVE.

.NDERLYIMA PITCHING OSCILLATION DEMANDED MORE ATTENTION TO SPEED MATERS THAN PITCH. SHOULD BE CAREFUL OF CONTROLS AGAINST ON THE SERVICE OF CONTROLS AND ATTENDED AND THE CONTROL FOR CAUSED BY LANG TIME CONSTANT AND AIRSPED CHANGES. PITCH DIVERGES QUICKLY IN RESPONSE TO STEP CLEVATOR INPUT.

I MISCELLANEOUS



CONFIGURATION 11-2
FLIGHT NUMBER 29-2
PILOT C
PILOT-RATING 7 CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING 15 KNOTS" WIND(knots) WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE WIND SHEAR EXTERNAL TURBULENCE CHARACTERISTIC ROOTS +,016# , 2421 -.78 -1,04 CHARACTERISTIC ROOTS LAIRCRAFT RESPONSE TO CONTROL INPUTS (rad/sec2)/in ZBT = Fino! ELEVATOR Mag : CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES COMMENTS SLOW FINAL RESPONSE TO CONTROL INPUTS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE DAMPING AMPLITUDE DAMP NG SOURCE EXCITATION CONTROL COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION SMALL MODERATE DIFFICULTY DIFFICULTY LARGE POWER LEVER MOVEMENTS REQUIRED. 5 FLIGHT PATH CONTROL Intercept 8 mittal track | Intermediate track | Final track | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gilde path | Gil initia: *rock | Intermediale trock | | Localizer Glide path | Localizer Final Irack Glide path Localizer DIFFICULTY SLIGHT MODERATE MODERATE PRECISION M/NIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET ATRIPED AND VERTICAL VELOCITY CONTROL OUT OF PAND. SPEED RESPONSE TO CONTROL INPUTS TAKES TOO LONG. COMMENTS: 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT GREAT
PRECISION OF ATTAINING TOUCHDOWN POINT VERY POOR D FFICULTY COMMENTS -BREAKOUT AND FLARE NOT COMPLETED. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES 10. MOST OBJECTIONABLE FEATURES SLOW MINAL RESPONSE TO CONTROL INPUTS. STRONG WIND SHEAR COMPLICATED TASK. UNABLE TO CHECK FINAL DESCRIT AS AIRSPEED FELL DEF TO WE KNOTS. THRUST LEVER DISPLACEMENTS TOO LARGE. II MISCELLANEOUS



CONFIGURATION 14-1L FLIGHT NUMBER 65-2 PILOT A PILOT-RATING 71/2 CONFIGURATION 14-1 FLIGHT NUMBER 39-1 PILOT B PILOT-RATING 7 1/2C WIND (knors) 10
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT WINDERNOTS) CALM WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE CHARACTERISTIC ROOTS .17± .191 +.15 -1.60 CHARACTERISTIC HOOTS -...7 ± ...191 +...15 -1.60 I. AIRCRAFT RESPONSE TO CONTROL INPUTS Mag = 46 (rad/sec²)/m Za_T=11.9 (rad/sec²)/m Za_T=11.9 (rad/sec²)/m (ft/sec²)/in Final CONTROL SENSITIVITY: RESPONSE : SATISFACTORY TOO GREAT SATISFACTORY TOO GREAT 2 EASE OF MAINTAINING DESIRED VELOCITIES VMC FLIGHT CONDITION TURBULENCE.
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS MODERATE REAT COMMENTS PITCH ATTITUDE WAS FERY LOOKE AND CONTINUALLY WANDERED WITH SMALL BLEWATCH INPUTS AND FROM THE EFFECT OF TURBIL-BROKE. WORKED VERY MARD TO KEEP PITCH ATTITUDE DEVIATIONS SMALL, CTHERWISE FELT THAT CONTROL WOULD BE LOST. ELEVATOR SENSITIVITY REDUCED TO 0.3 SHOULD BE ALL RIGHT. NOT, HOWEVER A PACTOM IN RATING. DIFFICULTY DUE TO PITCH ATTITUDE INSTABLLITY AND TO TURBULENCE EMPECTS. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD AMPLITUDE DAMPING PERIOD DAMPING DEGREE SOURCE DEGREE EXCITATION CONTROL THE ELFYATOR WAS RESECTIVE IN CONTIOUNING THE ESCIPLATION AS LONE AS EXACTLY THE RESPECTIVE WAS DONE BIT THE STRADY STATE PESPONSE TO ACCORDING IMPRES WAS EMPERORS. COMMENTS 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED: EASE OF COMPENSATION SNAUL MODERATE
SLIGHT DIFFICULTY DIFF-CULTY COMMENTS STATE THREST REQUIRED IN TURNS BUT WIT ABLE TO LEARN EXACT DESCRIPTION. BUT ABLE TO ASSESS POSSIBLE ATROPPED-VERTICAL RESOLUTY INTER-OSCATIONSHIPS, ETC. 5 FLIGHT PATH CONTROL nitial track Intermediate track Intercept B Final track tercept 8 initial track | Intermediate track | Final track | ide path | Lacolizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide p DIFF-CULTY surga SUIGHT | SUICHT STACTO MODERATE 'A16 / /A16 ALC: G000 MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500 COMMENTS AS PER SECTION 2 AMOVI. LUCALIZER INTERCEPT ANGLE OF 90° IS ALWAYS TOO GREAT. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOJCHDOWN POINT NONE SOLD TO DIFFICULTY COMMENTS NO MEAL DIFFICULTY. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IO MOST OBJECTIONABLE FEATURES

(98.7, 74.8) AS TO BEAUGIASPONSE PROTECTIANTIHOR INSTABILITY both ACTOR BY TURBULENCE UPSETS.

II MISCELLANFOUS

OPERIORABLE OF THE ANGEL COULD BE IN QUESTION DUE TO PITCE ATTITUDES OF MERCANDE



CONFIGURATION 14-1 FLIGHT NUMBER 39-1 CONFIGURATION 14-7 FLIGHT NUMBER 47-3 PILOT 0 WIND (knois) 10
WIND SHEAR SMALL
EXTERNAL TURBULENCE MODERATE WIND SHEAR SMALL MODERATE
EXTERNAL TURBULENCE COURT MODERATE PILOT 3 PILOT-RATING 8E PILOT 0 PILOT-RATING 91/2 CHARACTERISTIC ROOTS -. 45 ± .301 -.21 -1.63 I AIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIV:TY: In tiel SATISFACTORY RESPONSE: TGC SMAL 2 EASE OF MAINTAINING DESIRED VELOCITIES Vertical velocity (fr)

VMC IMC MC
OUT OUT IN

OPERATE MEAT GREAT Vertical velocity (+)
VMC IMC IMC
OUT OUT IN Longitudinal velocity (IAS)

VMC IMC IMC
OUT OUT IN

SOBERATE REAT REAT FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAX-MUM UNDESIRED FLUCTUATIONS REAT REAT knots S .TCHT | S1.TCHT | SHIGHT | ± 10 | Angls MODERATE COMMENTS: THRUST SERBE CONTROL SUCRETAIN SERVER ON MENSION MORRET ON ANTICIPATED, MODERANT PETCHATTUR DE INSTADIOTY STORES. IS SONT STUPPNESS, BUT THE THE CONSTANT AS TOO SERVE. TEELS AS 10 OPERATING NAY BACK ON POWER REQUIRED CURVE, NNO NLSO AS 10 ALKGRAPT IS STATICALLY UNSTABLE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERICO AMPLITUDE DAMP NG AMPLITUDE PERIOD DAMPING 4E00 DEGREE. SOURCE DEGREE EXCITA*ION CONTROL COMMENTS $P_{\rm eff}$. ThenDESCY CUITT PROBE NGED, PROBABLY DUE TO REGATIVE GUATES NAGO N. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION 0 FFICULTY DIFFICULTY COMMENTS SONY THE TEST OF COMMERCIAN ASSETTINGS. SPECIO CONTROL POCA. HENCE SED LARGE POWER LEVER INPUTS UNSTABLA: JUGGICE LI ALTSPECIO IS GARLFULLY CONTROLLED, SSECTIALLA NO POVIN IS OF WIRED IN TUNNS. 5 FLIGHT PATH CONTRO: laterces: 8 milial track | Intermediate track | Firat track Glide path | Localizer | Glide path | Localizer | Glide path | Localizer intercept & initial track intermediate track Final track.
Glide path Localizer Slide path Localizer Glide path Localizer DIFF CULTY 1 . IT SMAGE PACCENTE S. [40] SODIESTE YODERATE WESTE MODERATE GREAT CPEAT PRECIS ON 31: 36 100 R / FATE HARY POOR MERY POOR FM3 MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET TOST CORES LOCATELLE. MECHANIS SERVITORY TRACKING TOP COSTINUES AND CONTROL OF CONTROL O COMMENTS. N' ISPERD CIMIEST, AS THE ROY PERT LEMET MAS APPROACHED WAS 3-BY PROT. PRINT UNABLE DO TEMON CLIPE PATT, RESUCCESS-FIL MORROACH COLLD NOT DANC. 6 BREAKOUT AND FLARE EASE OF ARRESTING MATE OF DESCENT No. DIFFICULTY PRECISION OF ATTAINING TOUCHDOWN POINT D F FIO ÜLTY COMMENTS PODS, BUT SAFT, POSTITINION AND AS THEY SAFE ON BURNOUS AT THE CONTROL CANNOT CORMENT. NOT IN A POSITION TO ATTEMPT LANDING. 7 CONTROL TECHNIQUE COMMENTS IN DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST TOTALIST COMBINE POSES TECHNIAND MINSPEED TO COMPROL FERTEURAL SELECTIONS. SOME SUCCESS, BUT DURING FINAL APPRICAL COAR R TO THACK SCIDE PATH. 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT (30) 9 LEAST OBJECT-ONABLE FEATURES 10 MOST OBJECTIONABLE FRATURES TOTAL VIDOS VILONOVAR ASSENSATION THAN AVERTIS AT A FIGURE OF PILOT AND LIVE OF THE AVERT THAT IT AND LIVE OF THE AVERT THAT IT AND LIVE OF THE AVERT AND LIVE OF THE A I SECTED CESTOM, RECUISED EXCESSIVE PILOT SECONT AND THE SECSES FROMES OF DEVIATING RECVITED THEM ATRAPHED ARE THE TIMEST, PROBLEMS WHICH MRE INACCEPTABLY AND COULD LEAD TO 1988 OF CONTROL. SOME PITC ATTEMPS SET IN OS GUIGORI BUT STILLES SOCIALIDA 10 THE BOUNDES OF SECOL, SET OLI SELIN CHORNEY CONTROL ATTEMPS ROSENSES BUSINESS AND APPLIES, CLOSE ON THE SECOND CONTROL BOOK SECONS CONTROL TO CONTROL DATIN DUE TO THE SECOND SECONS CONTROL TO CONTROL DATIN DUE TO THE SECOND SECONS CONTROL TO CONTROL DATIN DUE TO THE SECOND SECONS CONTROL TO CONTROL DATIN DUE TO THE SECOND SECONS CONTROL TO CONTROL I MISCELLANEOUS



CONFIGURATION 1-PL FLIGHT NUMBER 113+1 PILOT A PILOT-RATING B

CHARACTERISTIC ROOTS -.046# .3081 -.857# .3381.

WIND(knois)
WIND SHEAR SMALL
EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION 1-PL FLIGHT NUMBER 81-L PILOT B PILOT-RATING 5D

WIND (knots:
WIND SHEAR
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS __,046± _3081 __,857± _3381

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELE \	ATOR.	THRUST LEVER		
MaE = . 25	(roo/sec2)/ii	n: Z8T=1L.3	(f1/sec2V	
Initial	Final	In tial	Final	
SATISFACTORY	TOC GREAT	SATISFACTORY	TOO GREAT	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

	Long-tudinal velocity (1AS)			Vert	Vertical velocity (h)		
	V.M.C	1MC.	IMC	VMC	IMC	I.M.C	
	OUT	OUT	IN	OUT	OUT	IN	
	MODERATE	GREAT	GREAT	SLIGHT	MODERATE	GREAT	
S		+1510	krals		± 300	f.p.m.	

COMMENTS

RESPONSE

PITCH ATTITUDE WOULD NOT SETTLE DOWN AND CONSEQUENTLY AIR-SPEED CONTROL GAVE TOO MUCH DIFFICULTY.

Longitu	d nal veloc	fy (IAS)	Vertical velocity (h)		
V.M.C	1 M C	IMC	VMC	1 M C	LM.C
DUT	OUT	IN	DUT	CUT	IN
SLICHT	SLIGHT	SLIGHT	NONE	NONE	NONE
	±8 -5	knots			f n m

SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY

PITCH ATTITUDE DIFFICULT TO TRIN IN TURBULENCE AND WHEN MAKING POWER ADJUSTMENTS, MUST RETRIM PITCH ATTITUDE IN ORDER TO HOLD AIRSPEED.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE	PER	IOD	DAMPING	
MODERATE	MED	LUM	LOW	
ZERO	L			
SOURCE			DEGREE	,
SOUNCE			DEGREE	_
ELEVATOR, TURB	TLENCE		EAS 1), Y	
ELEVATO	R		EFFECTIVE	

EXCITATION CONTROL COMMENTS

APPROXIMATELY 90% OF AVAILABLE ATTENTION HAD TO BE DEVOTED TO PITCS ATTITUDE CONTROL SINCE THE OSCILLATORY CHARACTERISTICS JUST KEPT IT MOVING.

AMPLITUDE	PERIOD	DAMPING
SOURCE		DEGREE

Intermediate track Final track
ide path Localizer Glide path Localizer

GOOD FAIR/GOOD

SLIGHT

SLIGHT

FAIR

> NONE

SOME P.I.O. TENDENCY DURING LANDING FLARE.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

COMMENTS:

SMALL SLIGST D.FFICJ_TY

NEGGIGLBLE NO

Intercept & initial track Glide path Localizer

300

5 FLIGHT PATH CONTROL

DIFFICULTY:

PRECISION

	initial track			Fingl	
Glide path	Loca Irer	Glide poth	Localizer	Glide patr.	Loco-izer
SLIGHT	SLIGHT	MODERATE	MODERATE	ĞdEAT	GREAT
FAIR	PALR	POOR	POOR	VERY POOR	FOOS ÁREA

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE

IF GREATER THAN 200 FEET 800

COMMENTS

TOO MUCH ATTENTION REQUIRED TO PITCH ATTITUDE LEAVING LITTLE FOR OTHER PARAMETERS. OVER-ANTICIPATED THE AMOUNT OF WIND SHEAT AND HAD TO MAKE SOME GROSS READING CORRECTIONS TOWARDS THE APPROACH.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE: OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

SLIGHT	DIFFICULTY
FALR	

COMMENTS:

SLIGHT/MODERATE DIFF-CULTY: FAIR

>NONE

6000

SOME TENDENCY TOWARD P.1.O. NECESSITATED ATTAINING AND MAINTAINING SOME ACCEPTABLE AGTS OF DESCRIPT WHICH COULD AS CARRIED RIGHT TO TOUCHDUM. THAT IG. ALO TO MINIMISE CONTINUL REPORT PRIOR TO TOUCHDUM.

WIND SHEAR CONTRIBUTED TO DIFFICULTY BUT DID NOT AFFECT BATING. THE PITCHING MOMENT DUE TO PONCE CHANGES ON THE APPROACH NECESSITATED A TICHT CONTROL OVER PITCH ATTITUDE IN ORDER TO HOLD ALBEPTED.

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL

NONE

REASONABLE ATTITUDE STABILITY BUT WAS NOT PULLY EFFECTIVE IN THE PRESENCE OF POWER CHANGES ON THE GLIDE PATH.

PITCH MESPONSE TO POWER CHANGES REQUIRES PLOT ATTEMPTION, PITCH MESPONSE TO THRBHINNOE IS NOTICEABLE. P.I.O. TEND-SWYN YEAR GOORND AGGINES CASE POR FLARE AND LANDING. ALL CONTRISUTE TO HIGH PILOT WORK LOAD.

9 LEAST OBJECTIONABLE FEATURES

IO. MOST OBJECTIONABLE FEATURES.

I. MISCELLANEOUS



CONFIGURATION 1-P FLIGHT NUMBER 47-2 PILOT 0 CONFIGURATION 1-N FLIGHT NUMBER 108-1 P-LOT A WIND (knots) 5
WIND SHEAR SMALL
EXTERNAL TURBULENCE NEGLIGIBLE WIND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE P-LOT A PILOT-RATING 4 PILOT D PILOT-RATING 6 1/2 CHARACTERISTIC ROOTS -.046± .3081 -.857± .3381 CHARACTER STIC ROOTS +.10 -.153 -.867 ± .5041 LAIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

Mag = .30 (rad/sec²)/m 281 11.9 (tt/sec²//m SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (TAS)
V.M.C. LMC I M.C. Vertical velocity (h)
VMC (MC Long-tud-not velocity (IAS)
VMC IMC :MC
OUT OUT IN Vertical velocity (A VMC (MC OUT OUT FLIGHT CONDITION 1 M C
 OUT
 OUT
 IN
 OUT
 OUT
 IN

 SLIGHT
 SLIGHT
 MODERATE
 SLIGHT
 MODERATE
 GREAT

 ±5
 knots
 ±>300
 f.pm
 TURBULENCE DIFFICULTY SI IGHT MODERATE MODERATE NONE ___ SLIGHT SLIGHT MAXIMUM UNDESIRED FLUCTUATIONS COMMENTS DIFFICULTY DUE TO NO PITCH ATTITUDE STIFFNESS, TURBULENCE DISTURBED PITCH SUFFICIENTLY TO CAUSE SIGNIFICANT ALESPEED CHANGES. SOME PITCHING MOMENT WITH POWER LEVER IN THE STARLE SERSE WHICH CAUSED MINOR PROBLEMS. AIRCRAFT FELT AS IF IT WAS OPERATING ON BACKSIDE OF POWER 3 RESIDUAL OSCILLATORY CHARACTERISTICS CAMPING 3CUTI19MA PERIOD AMPLITUDE PERIOD DAMPING ZERC ZE30 SOURCE DEGRÉE EXCITATION CONTROL COMMENTS NO DSCILLATORY TENDENCY 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. EASE OF COMPENSATION: DIFFICULTY CIFFICULTY COMMENTS DIFFICULTIES AROSE MEEN AIRSPEED DEVIATED FROM TRIM AND I THEN HAD TROUBLE CONTROLLING RATE OF DESCENT. HOWEVER, IT WAS NAMAGEABLE. 5. FLIGHT PATH CONTROL intercept & initial track Glide path | Localizer ne track Final track
Localizer Glide path Lacabier Intercept 8 in tial track | Intermediate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide poth DIFFICULTY: SLIGHT MODERATE >SLIGHT >MODERATE >MODERATE SLIGHT SLIGHT SLIGHT SLIGHT PRECISION 0000 (300) PAIR FATR 8A1R FAIR MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET AIRSPEED HAD TO BE CONTROLLED PRECISELY OR THE MATE OF DESCENT AND HENCE CLIDE SLOPE TRACKING SUPPERED. COMMENTS WIND SHEAR IN LOWER 500 FEET CAUSED SOME LOCALISER 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRESISION OF ATTAINING TOUCHDOWN POINT NO DIFFICULTY SLIGHT COMMENTS 7. CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM
LAS WITH ELEVATOR AND
USERIES THAN THE LEVATOR AND
USERIES THAN THE RETAIN MAKE LAMPE POWER LEVER CHANGES
LEVER
LEVER CHANGES. 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NORS NONE, HOWEVER RUDDER PEDAL FORCES SKEMED HIGHER THAN USUAL. 9 LEAST OBJECTIONABLE FEATURES GOOD PITCH BYKAMIGS. IO. MOST OBJECTIONABLE FEATURES LARGA PUMER LAWER INPUTS REQUIRED AND AIRSPEED HAD TO BE CONTROLLED PRECISELY TO PREVENT LARGE VERTICAL VELOCITY EXCURSIONS. PITCH AFTITUDE CONTINUALLY INCREASED WITH SMALL OUT-OF-TRIM BLEVATOR HEFLECTIONS, I MISCELLANEOUS NOTE: RUDDER CONTROL SENSITIVITY HAD BEEN REDUCED FROM 0.6 TO 0.4 r/s²/in. AFTER PLICHT \$102.



CONFIGURATION 1-2P FLIGHT NUMBER 129-2 PLOT A PICOT-RATING 8

WIND(knots) WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLICIBLE CONFIGURATION L-ZPL FLIGHT NUMBER 72-1 PILOT A PILOT A
PILOT-RATING 6

WIND (knots) 10
WIND SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEV	ATOR	THRJST LEVER		
MBE = 25	(rod/sec ²)/in	Zar-IL.9	(ft/sec ² l/in	
l miliúl	Final	In tigt	Final	
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

i	Long-tudinal velocity (1AS)			Vertical velocity (fi)		
	V.M.C	1MC	IMC	VMC	, M.C	T.W.C
	OJT	OUT	IN.	QUT	QUT	PN
	SLIGHT	MODERATE	GREAT	SLIGHT	MODERATE	GREAT
5		±)	knots		±300	ſpm

COMMENTS

THE NOSE IS IN CONSTANT MOTION WITH THE TURBULENCE IN, BUT IT BOUNCES IN RESPONSE TO ELEVATOR INPUTS AS WELL. THE VERTICAL VELOCITY WANDERS TOO MUCH BECAUSE OF TURBULENCE INPURS.

ELEV	ATOR	THRUS	LEVER
Mag = .25 (rod/sec2)/in		Z _{BT} =11.9	(f1/sec ²)/:n
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

Longitudinal velocity (!AS)			Vertical velocity (h)		
VMC	I M.C	I_M.C	VMC	IMC.	I M.C
OUT	OUT	IN	QUT	OUT	IN
SLICHT	MODERATE	CREAT	SLIGHT	HODERATE	GREAT
	#10	knots		±200	fp

THE MOSE DID NOT SEEM TO MANY TO STAY WHERE IT WAS PUT WITH TURBULENCE IN, ALTHOUGH BEFORE THERE HAD BEEN MODERATELY GOOD PITCH STABILITY. EXTERNAL TURBULENCE BECAME A FACTOR BEION 1200 FEBT.

3 RES-DUA, OSCILLATORY CHARACTERISTICS

PITCH HEAVE

AMPLITUDE	PERIOD	DAMPING
SMALL	SHORT	LOW.

EXCITATION COMMENTS

i	
SOURCE	DEGREE
ELEVATOR/TURBULENCE	MUDERATELY / EASILY
ELEVATOR	INEFFECTIVE

THE PREGUENCY OF THE BOUNGE WAS SUCH THAT IT WAS DIFFICULT TO CATCH WITH THE ELEVATOR CONSISTENTLY.

AMPL:TUDE	PERIOD	DAMPING
ZERO		
ZERO		
SOURCE		DEGREE

S	OURCÉ	 DEGREE
	,	

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

MCDERATE	
MIDERATE	DIFFICULTY

A SLOW DESCEND THAT WAS DIRFIGURE TO DETECT CREPT IN DURING

THE TURNS.

MODERATE OFFICULTY

5. FLIGHT PATH CONTROL

DIFFICU.TY PRECISION

Intercept 8 milial track	Intermedia	ale track	Final	track
Glide path Localizer	Glide poth	Localizer	Glide poin	Localizer
MODERATE MODERATE	MCDERATE	GREAT	MODERATE	GREAT
FALR POUR	FATR	POOR	POON	VERY POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEE' 500 500

COMMEN'S.

THE TURBULENCE WAS RICKING THE MOSE ABOUND IN BOTH PITCH AND YAW, REQUIRING TOO MIGH ATTENTION.

ntercept 8 in hal track | fatermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path MODERATE MODERATE MODERATS SLIGHT GREAT FAIE. PUOR POOR FAIR VERY POOR POOR

500

DIFFICULTY DUE TO THIS BRING THE FIRST MODEL OF THE DAY AND THE WIND SPEED AND DIRECTION VARYING QUITE A LOT BURING THE DESCRIT.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF CRISCEN! NO. DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT 3200

COMMENTS

DIFFICULTY]

BROKE OUT WELL TO THE LEFT BUT WAS ABLE TO GET TO THE TOUCH

7 CONTROL *FCHN: QUE.

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT MODERATE, TORROUGING KICKING WORE AROUND THE MICH.

9 LEAST COJECTIONABLE FEATURES

TO MOST OBJECTIONABLE FRATURES AS PAR SECTIONS 2, TAXA 5 ARRIVE.

II V SCELLANEOUS

TWO APPROACHES WERE MAD-



CONFIGURATION 1-2PL F_GHT NUMBER 75-2 P:LOT B PILOT-RATING 51/2 C W NDIknots) CALK
WIND SHEAR SHALL/NBGLIGIBLE
EXTERNAL TURBULENCE REGLIGIBLE CONFIGURATION 1-2P F_IGHT NUMBER 46-1 PILOT D PILOT-RATING 4¹/2 WIND (knois) 20 WIND SHEAR NODERATE EXTERNAL TURBULENCE HODERATE CHARACTERISTIC ROOTS -.018± .361 -.89± .351 CHARACTERISTIC ROOTS -.017 ± .361 -.89± .351 I AIRCRAFT RESPONSE TO CONTROL INPUTS Mag = .90 (rad/sec 1/in Zaj = 15.0 (th/sec 1/in Zaj = Mag = 30 (rad/sec²)/n Z_{8T} = 15.0 (tr/sec²)/n rillol Final CONTROL SENS:TIVITY SLIGHTLY SMALL SATISFACTORY SATISFACTORY RESPONSE . SATISPACTORY 2 EASE OF MAINTAINING DESIRED VELOCITIES FLIGHT CONDITION
TURBULENCE.
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS VMC INC OU OJT SLIGHT SLIGHT SLIGHT MODERATE MODERATE COMMENTS DIFFICULTIES DUE TO LEARNING PROCESS AND INSTRUMENT CROSS-3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPL TUDE AMPLITUDE DAMPING DAMPING ZERO MODERATE SCURCE DEGREE SOURCE DEGREE EXCITATION CONTROL THE SHORT PERIOD SEEMS WELL DAMPED AND OF HODERATE PRE-QUENCY. HOWEVER, THE PHINGUID HAS A PATRLY HIGH PRECIDING (I) SECS. APPROX.) AND THIS GAUSES SOME P.I.O. TENDERCIES ESPECIALLY IN TURBULENCE. COMMENTS SMALL ELEVATOR AND POWER LEVER P.1.0. EXCITED IN THE PLANE. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION DFFICJLTY DIFFICULTY SLIGHT COMMENTS 5 FLIGHT PATH CONTROL Intercept & mittal track Intermediate track Final track Glide path Localizer Glide path Localizer Glide path Localizer Intercept & mit al track | Intermediate track | Final track | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Gide path | Localizer | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide DIFFICULTY NONE NONE SUIGRT S' IGHT SLIGHT >SLIGHT >SLIGHT MODERATE MODERATE PRECISION GOOD/FAIR COOD/FAIR GOOD/FAIR GOOD/FAIR FAIR CCOD MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET WENT DIGHTAT 250 FEET FOR NO APPARENT REASON. AVERAGE RATE OF DESCRIPT ON GLIDE PATH WAS 950-1000 MT MIN. SUSPECT WIND SHEAR WITH GRADIENT AT 300-250 FEET CAUSED ME TO GO COMMENTS OVERALL PERFORMANCE SEEMED GOOD. HAD TO HORK REASONABLY HARD BUT ADMAYS ABLE TO GET BACK ON TRACK, SEEMED TO BE LARGE EFFECT OF THRUST LEVER CONTROL ON PITCHING MOMENT. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NOBELITY DEFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT (200) DIFFICULTY GA FAIR COMMENTS SMALL/MODERATE PITCH-BRAVE P.I.O. EXCITED AT TOUCH DOWN. AIRSPEED WAS LOW AND LEVELLED OFF HIGH. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT 9 LEAST OBJECTIONABLE FEATURES VERY LITTLE TURBULENCE RESPONSE, REASONABLE ATTITUDE STIFFNESS, BUT DIPPICUET COOD PITCH DAMPING AND GOOD REIGHT DAMPING. TO TRIM. 10. MOST OBJECTIONABLE FEATURES FITCH-BRAVE P.1.3. TROBERCY AT TORCH BOWN. LARGE PITCHING MOMENT WITH THRUST LEVER APPLICATION, SOME TENDENCY TO P.I.U., PROBABLY DUE TO SMORT PRUGOID PORTOD, PORGOID, HOWEVER IS POSITIVELY DAMPED. II. MISCELLANEOUS



CONFIGURATION 1-2N FLIGHT NUMBER 82-3 P-LOT A P-LOT-RATING 9

WIND(knots)

WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROOTS +.10 -.10 -.89 ± .541

CONFIGURATION 1-2N FLIGHT NUMBER 51-2 PILCY D WIND SHEAR NEGLIC EXTERNAL TURBULENCE LIGHT NEGLIGIBLE PILOT-RATING 8

CHARACTERISTIC ROOTS +.10 -.10 -.89 # .541

WIND (knofs)

CALH

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

ELEV	ATOR	THRUST	LEVER
M8E = .25	(rad/sec2)/in	Z8T=11.9	(ft/sec ²)/.n
Initial	Fino:	initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGH* CONDITION MAXIMUM UNDESIRED FLUCTUATIONS

Long tudinal velocity (1AS)
VMC | 1MC | I.M.C VMC

COMMENTS

THE FITCHING MOMENT WITH AIRSPEED WAS IN THE UNSTABLE SENSE, CAUSING ALARMING EXCURSIONS IN ATTITUDE. THE TRIM WITH AIRSPEED, BEING REVERSED, SKEMED VERY STRANGE.

VISE : 25 100 SMALL SATISFACTORY SATISFACTORY TOO GREAT

Longitud not velocity (TAS)
V.MC LMC MC
OUT OUT IN
FODERATE >HODERATE GREAT Vertical velocity (h)

VMC IMC IMC
OUT OUT IN

SILIGHT MODERATE CREAT

COULD NOT TELL MAAT THE PROBLEM WAS, DID NOT FEEL LIKE BACKSIDE OF POWER CURVE AS DID FREVIOUS NODEL (R1-3). STICK FELT AS IF IT HAD BOB-WEIGHT EFFECT, I COULD NOT CONTROL AIRSPEED VERY WELL.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE

EXC-TATION CONTROL COMMENTS

A SIMPLE PITCH ATTITUDE BIVERGENCE WAS THO OVER-RIDING

PITCH AT FIRST APPEARED TO BE O.K. (1e. DAMPED SHORT PRHIOD) BUT I MAD A LOT OF DIFFICULTY TRIMMING AS IS GENERALLY TRUE WITH A NEGATIVE STATIC MARGIN.

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

NODERATE SLIGHT Ö-FFICJ_1Y

COMMENTS

MODERATE/LARGE MODERATE/GREAT DIFFICULTY

I DON'T KNOW BUT IT ALMOST SEEMED AS THOUGH I NEEDED LESS POWER IN TURNS THAN IN LEVEL FLIGHT.

5 FLIGHT PATH CONTROL

DIFF CULTY: PRECISION

Intercept & mitro: track | Intermediate track | Final track Glide path | Localizer Glide path | Localizer | Glide path | Localizer SLIGHT SUIGHT MODERATE SLIGHT MODERATE SLTGHT PAIR GOOD FAIR/GOOD POOR/FAIR FAIR/GOOD

M:NIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 700

COMMENTS

AS PER SECTION 2 ABOVE.

Intercept B initia track Intermediate track
Glide path Localizer Glide path Localizer Final Irack Lacalizer Glide path Localizer MODERATE MODERATE GREAT GREAT GREAT : GREAT FAIR PAIR VERY POOR VERY POOR VERY POOR

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SILIGHT DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT FALL

COMMENTS

WHEN AIRSPEED INCREASED (FSPECIALLY) I HAD GREAT DIFFICULTY IN REDUCING IT AND THEN I USUALLY OVERCONTROLLED AND COT TOO SIGM. WHILE THIS WAS OCCURRING MY ARTS OF DESCENT SUSPERRU AND HENCE GLIDE SLOPE TRACKING WAS VERY POOR. NONE/SLIGHT DEFICULTY

7. CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL

9 LEAST OBJECTIONABLE FEATURES

NO DECIMATORY TENDENCY. PRECISION OF ATTITUDE SEEMED O.K.

TO MOST OBJECTIONABLE FEATURES AS PER SECTION 2 ABOVE.

ALESPEED CONTROL VERY FOOR. FOR SMALL CHANGES IN PITCH ATTITUDE, THE ALESPEED SEEMED TO DIVERCE.

II. M SCELLANEOUS

EXTERNAL TURBULENCE BECOMING BORDERLINE.

THIS WAS A DISPICULT CONFIGURATION TO PLY ON FINAL APPROACH AND I COULD NOT BE GERTAIN ABOUT WHAT WAS ACTUALLY CAUSING THE DISPICULTY.



CONFIGURATION 1-3F FLIGHT NUMBER 114-1 PILOT A PILOT A
PILOT-RATING 7

WIND(knots) WIND SHEAR REGITETERS EXTERNAL TURBULENCE NEGITETERS

CHARACTERISTIC ROOTS | F.024± | .441 | -.93± ; .361

CONFIGURATION 1-3P FLIGHT NUMBER 26-1 PILOT B PILOT-RATING B 72

WINO (knots) 10
WIND SHEAR SMALL/MODERATE
EXTERNAL TURBULENCE MODERATE

CHARACTERISTIC ROOTS +.024 ± .441 -.93 ± .361

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEV	ATOR	THRU\$	LEVER
MaE =, 25	(rod/sec ²)/:n	Z81=11.9	(1+/sec ²)/in
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATIS /ACTORY

MBE : 4 ELEVATOR THRUST LEVER

MBE : 4 ELEVATOR JET 11.9 (III/sec*V/in
Initial Fund Guttal Fund
SATISFACTORY SATISFACTORY NOT ASSESSABLE NOT ASSESSABLE

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

ſ	Longil	udinal veloci	ty (1AS)	Ve	rtical velocity	(h)
- [V.M.C	1MC	"IMC	VMC	1MC	[MC
- [OUT	OUT	IN	OUT	DUT	IN
ı	SLIGHT	MUDERATE	GREAT	HONE	MODERATE	MODERATE
5 [±10	knots		± 200	f p.m.

COMMENTS

DIPPIDENTY DUE 10: TURBULENCE CONTINUALLY ENGOLING NUSE AROUND IN PITCH, ALSTEED RIVERT ON BOYAGE, FONCE TO BUCK OFFICER. (INCRESSE IS A HISPERD INCRESSES NORMA, VORCE). PITCH CONTROL FUNDER. ATTITUDE CONTINUALLY (NORRASES NUTS SHALL OUT OFFICER ELEVATOR.)

AD TO CLOSELY MONITOP PITCH ATTITUDE TO REEP VERTICAL VEY/CITY INDER CONTROL DUE TO WHAT APPEARED TO BE HIGH ALRSPEED - VERTICAL VELOCITY COUPLING AND PERHAPS TO THE VERTICAL DAMPING CHARACTERISTICS.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PERIOD	DAMPING
	I
	DEGREE
	DEGREE
	PERIOD

AMPLITUDE PERIOD DAMPING ZE30 ZE30 SOURCE DEGREE

EXCITAT ON CONTROL

COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED.

NECLICIBUS NO DIFFICULTY

ATRIPED REMAINED AT 60 CNOTS THROUGHOUT MANORIMESS, AND MERCS REAVE PROBLEMS EXPECTED FROM ATRIPUDED CHANGES DID NOT ALISE.

SMALL MODERATE
SILIGHT MODERATE DIFFICULTY

STICE HAD NOT LEARNY AMOUNT RESULTED. USED ENGINE MANIPOLD PRESSURE AS THRUST QUE WHILE HOLDING AIRSPEED PRECISELY AT BOUNCES.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept &	-nitial Frack	Intermedi	ale track	Final	track
Glide path	_ccalizer	Gl de path	Locolizer	Glide poth	Local zer
MODORATA	SLEGHT	· "EAT	SLUJUT	MODERATE	SULDE
FATR	FAIR 'GOOD	POOR	FAIR	AIR	-A1R

MINIMUM ACCEPTABLE BREAKOUT ALT:FUDE
F GREATER THAN 200 FEET 500

AIRSPEED SPECT ON GLIDE SLAPE (AME PROBLEMS AND PITCH ATTITUDE DISPLICITLY OCCUPIED 100 MICH TIME FOR ADECLAT-KONITORING OF ALL OTHER PARAMETERS

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

 No:	DIFFICULTY
6300	

WENT SURPRISINGLY WELL.

Intercept & initio track | Intermediate track | Final track |
Glide path Localizer | Glide path Localizer | Glide path Localizer | SLIGHT > NONE SLIGHT SLIGHT COOD FAIR GOOD FAIR GOOD FAIR GOOD FAIR GOOD

500

AIRSPEED CONTROL TWO DEMANDING.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

EFFECT ON FINAL ASSESSMENT NONE

9 LEAST OBJECTIONABLE FEATURES

MODERATE DEFICULTY

UNDERTAIN OF WHAT TO DE. MAD TO MAINTAIN SPEED, BUT DIFFICIENT TO PIECEMT PITCUING THE NOSE, WHICH I DID AT TOUGHOUN, INDUCING A WERY HIGE BUT NOT INSAFE VERTICAL MELOCITY UST PRIOR TO TOUGHOUND.

8 LATERAL DIRECTIONAL CHARACTERISTICS

STATED WITE CONVENTIONAL CONTROL TECHNIOUS BUT THEN CHANGED TO CONSERVATIVE MIXTURE OF METHODS USING 4 KNOTS TO AD UST VERTICAL MEDICITY FOR GLIDE PATH CONTROL. GLIDE SLOPE TRACKING O.K. BUT PRECISE PITCH ATTITUDE - ALBSPEED CONTROL TOO TIZING

NONE

ID VOST OBJECTIONABLE FEATURES

PITCH DISTURBANCES ON 1 M.C. APPROACH. AIRSPEED EFFECT ON ME COAL TORCE DURING M.M.C. LYING.

HOT ALBSPEED - CEPTICAL SPEED COUPLING EFFECT. APPARENT LARGE TIME CONSTANT IN POWER LEVER CONTROL.

II MISCELLANEOUS

THIS MODEL SINGLAR TO WIS-ON PLANN PREVIOUSLY AND SO EXPERIENCE OF IT USED FOR LOARNING. HENCE PERSORMANCE WITH THIS MODEL MICE METER.



CONFIGURATION 1-3N FLIGHT NUMBER 107-1 PILOT A

WIND(knots)

PILOT A
PILOT-RATING 81/2

WIND SHEAR EXTERNAL TURBULENCE LIGHT

CHARACTER:STIC ROOTS .04# .161 -.931# .5681

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

ELEV	ATOR	THRUS	
MaE =. 25	(-od/sec²)/m	Z8 = 11.9	(ft/sec ²)/in
Initial	Final	In:tial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTURY

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

	Longitud	inal veloc	ity (IAS)	Ver	tical relacity	(h)
	V.M.C.	IMC	IMC	VMC	I.M.C	LM.C
	OUT	OUT	IN	OUT	OUT	IN
	MODERATE	GREAT	CREAT	SLIGHT	MODERATE	REAT
15		±10	knots		± 200	(pm)

RESPONSE:

DIFFICULTY DUE TO: TURBULENCE ROUNCING MOSE AROUND SEVERYLY PITCHING WITH CHANGE OF VERTICAL SPEED ROTHERSOME. PITCH CONTROL "SIDPEY". POWER CHANGES WITH AIRSPEED VERY BOTHER-SOME AND CAMED REAL DIFFIGULTIES STAYING ON AIRSPEED AND VERTICAL SPEED DURING APPROACH.

3. RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE	PERIOD	DAMPING
TERO		
4E40		
SOURCE		DEGREE
SOURCE		DESKEE

EXCITATION: COMMENTS

AMPLITUDE	PERIOD	DAMPING
SOURCE		DEGREE

WIND (knots)

CHARACTERISTIC ROOTS .04± .161 -,931± .5681

BLEVATOR THRUST LEVER

Mag: .25 (rad/sec*)/m/Z8;:11.9 (f1/sec*//n
Initial Final Initial Final
SATISFACTORY TO GREAT SATISFACTORY SATISFACTORY

MODERATE MODERATE REAT HODERATE MODERATE MODERATE

WEELS LIVE A LOT OF CROSS-COUPLING. PARTICULARLY AIRSPEED-VERTICAL VELOCITY INTERACTION AND POSSIBLY NEGATIVE PITCH-ING MOMENT-AIRSPEED INTERACTION.

CALM

WIND SHEAR SMALL MODERATE EXTERNAL TURBULENCE NEGLIGIBLE

Vertical velocity (n)

VMC JMC JMC JMC

OUT OUT IN

COULD BE AN UNDERLYING PITCHING OSCILLATION. SEEM TO BE DELAYED PITCH DISTURBANCES.

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

SMALL SLIGHT DIFFICULTY

COMMENTS

DIFFICULTY

CONFIGURATION 1-3N FLIGHT NUMBER 92-3 PILOT 8

PILOT-RATING 8D

± 10

NEED TO USUA SPEED PRECISELY AND ALTITUDE CONTROL IS DIFFICULT.

5. FLIGHT PATH CONTROL

ntercept a					rock
Glide path	Localize	Glide poth	Localizer	Glide path	_ocal rer
MODERATE	MODERATE	MODERATE	MODERATE	MUDERATE	MODERATE
FA13	FAIR	POOR	POOK	FAIR	2004

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 506

COMMENTS

DIFFICULTY

PRECISION

AS PER SECTION ! WHOVE

intercept B initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | SLIGHT MODERATE SULBIT MODERATE FAIR MAIR PALE FAIR FAIR FAIR

S-TUONS TO STAY ON LOCALI EN DUE TO DISPLAY DEPICIENCY. GLIDE SCOPE CONTROL POOR DUE TO AIRCRAFT CHARACTERISTICS AND PRIBABLE TAILMING. 1400 F.P.M. DESCENT PATE REQUIRED ONCE - PEAN 900 F.P.M.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

SLICHT	DIFFICULTY
FAIN	

COMMENTS

SLIGHT DIFFICULTY

NEED TO HOLD SPEED PRECISELY AND NOT TO PLACE.

7. CONTROL "ECHNIQUE

COMMENTS IF DIFFERENT FROM I AS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SHALL

VERESSIVE LARGE CONTROL INPUTS WERE USED. THIS RESULTED IN LARGE AFROMATT RESPONSES.

NUME

9 LEAST OBJECT: ONABLE FEATURES

(O. MOST OBJECTIONABLE FEATURES INTERACTION OF AUSTREE AND POWER REQUIREMENTS IN DISTABLE SENSE, (I.e. IS ALISPEED INCREASES FOR DOWN INCREASES WHICH CAUSES ALISPEED TO INCREASE.)

LARGE LOSS-OF-DEIGHT WITH DECREASING SPEED, ATTITUDE, SPEED, AND DETOIT ERRORS WERE DIVERGENT, SEEMED TO BE A LARGE ME WATER ERRORS OF PITCHING WIMERT DUE TO WORMARD SPSED.

II MISCELLANEOUS

CLOUD BASE DOWN TO 1800 PERT PREVENTED LYING FURTHER MODELS. ALSO THREGLENCE PICKING FT.

NEED TO PAY CLUSE ATTENTION TO PITCH ATTITUDE AS IT DIVERGES OUICKLY. NEED BETTER PITCH ATTITUDE DISPLAY. ALSO NEED HEADING ERROR INFORMATION ON DISPLAY.



CONFIGURATION 2-2PL FLIGHT NUMBER 87-3 P-LOT A PILOT-RATING 7

W-ND(knots)

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS +,021± ,381 -.48 -1.37

CONFIGURATION 2-2Pt FLIGHT NUMBER 94-I PILOT B PILOT B PILOT-RATING BE

WIND (knots) WIND SHEAR SHALL EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC RCOTS +.021 ± .381 -.48 -1.37

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

	ATOR	THRUS	
Mag = . 25	(rad/sec2)/in	Zar = 11.90	(*1/sec ²)/ir
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATIS PACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

	Longitu	dinal velaci	ty (TAS)	Verl	ical velocity	
FLIGHT CONDITION:	VM.C.	1MC	I M C	VMC	IMC	I M C
TURBULENCE	DUT	OUT	IN	OUT	OUT	IN
DIFFICULTY	SLIGHT	MODERATE	GREAT	NONE	SLIGHT	SLIGAT
MAXIMUM UNDESIRED FLUCTUATIONS		±5	knots		U.K.	(pm)

COMMENTS

THE MOSE WAS IN CONSTANT MOTION DUE TO THE LIGHTLY DAMPED, MODERATE FREQUENCY OSCILLATION EXCITED BY BOTH ELEVATOR AND TURBULENCE. ALTHOUGH THIS DID NOT PRODUCE LARGE AIR-SPEED CHANGES A DEFINITE DISCOMPRET OF NOT HAVING FULL CONTROL OF AIRCRAFT MOTION PREVAILED.

NONE SLIGHT SLIGHT DIFFICULTY DUE TO PITCH OSCILLATION AND TURBULENCE UPSETS

THRUST LEVER (11/5ec2)/in Zat: 11.90 (11/5ec2)/in lintal Final leulial Final SATISFACTORY SATISFACTORY SATISFACTORY

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPL: TUDE	PERIOD	DAMPING
MODERATE	MEDIUM	ZE30
		<u> </u>
SOURCE		DEGREE
ELEVATOR, TURBUL	ENCE	EASILY
ELEVATOR	l	EFFECTIVE

EXCITATION CONTROL

AS PER SECTION 2 ABOVE.

AMPLITUDE	PERIOD	DAMPING
SMACL/MODERATE	LONG (10 SECS)	T,OW
ZERO/SMALL		
SOURCE		DEGREE
SOURCE		DEGREE EASILY

WEAK OSCILLATION THROUGH ABOUT 4 DEGREES NOT BOTHERSOME AND ONLY MOTICEABLE DURING TIGHT TRACKING TASK APPROACH.

NEGLIGIBLE NO DIFFICULTY

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION:

SYALL NO DIFFICULTY

COMMENTS

5. FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Lizer Glide				
	parn L	ocalizer.	Glide poth	Local zer
NE LSL	IGHT S	LIGHT	SLIGHT	SLIGHT
	E SL	E SLIGHT	E SLIGHT SLIGHT	E SLIGHT SLIGHT SLIGHT

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500.

COMMENTS.

AS PER SECTION 2 ABOVE.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

 No	DIFF CULTY
 COOD	

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS SHALL EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IO. WOST OBJECTIONABLE FEATURES AS PER SECTION ? ABOVE.

Intercept & initial track | Intermediate track | Final | Gilde path | Localizer | Gilde path | Localizer | Gilde path | Final track NONE SLIGHT SLIGHT SLIGHT SLIGHT SLIGHT G000 COOD COOD GOOD FAIR

300

DIFFICULTY DUE TO CROSS-CHECK REQUIRED TO CONTROL PITCH ATTITUDE UPSETS CAUSED BY OSCILLATION AND TURBULENCE. SOME WIND SHEAR WAS ALSO PRESENT.

MCDERATE DIFFICULTY
FAIR

DIFFICULTY DUE TO:

PICOLITY JOE TO: FITCE OSCILLATION WHICH TENDS TOWARDS A P.I.O. NEAR GROUND, ESPECIALLY WHEN POWER COORDINATION IS ATTEMPTED AS WELL. LANGE TRANSIENT WHICH OCCURRED WHEN THE SLIND WAS RAISED (PRODABLY IN MIDDLE OF A PITCH ATTITUDE REVERSAL AT THIS TIME).

NONE

PITCH OSCILLATION DURING T.M.C. PITCH SENSITIVE TO TURBU-LENCE. TENDERCY TO P.I.O. NEAR CROUND, HAVE TO SMOOTH THINGS OUT AND THEN HOLD IT. SOME AIRSPEED - VERTICAL VELOCITY COUPLING NOTICEABLE.

II MISCELLANEOUS



CONFIGURATION 2-2PL FLIGHT NUMBER 104-3 PILOT C PILOT-RATING 4 CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING WIND (knots) WIND SHEAR EXTERNAL TURBULENCE WIND(knots) WIND SHEAR EXTERNAL TURBULENCS 5 KNOTS CHARACTERISTIC ROOTS +.021 ± .381 -.48 -1.37 CHARACTERISTIC ROOTS I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR THRUST LEVER

Mag = .25 (rad/sec^2)/in Zay = 11.90 (tt/sec^2)/in Initial Final ELEVATOR (rad/sec²]/in Zat : Final (11/sec²l/in Final Mag : CONTROL SENSITIVITY: RESPONSE TOO SMALL 2 EASE OF MAINTAINING DESIRED VELOCITIES | Longitudinal velocity ([AS] | V | V.M.C. | IM.C. | IM.C. | V.M.C. | O.M.C. LIGHT CONDITION TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS HARD TO CHECK SPEED CHANGES SUFFICIENTLY QUICKLY. LOW DAMPING AND RATHER LOW CONTROL POWER. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PITCH SOURCE DEGREE SOURCE DEGREE EXCITATION CONTROL EASILY EFFECTIVE COMMENTS RATHER SLOPPY LONGITUDINAL BEHAVIOUR. 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGIBLE DIFF.CULTY DIFFICULTY COMMENTS 5 FLIGHT PATH CONTROL initial trock Intermediale track
Lacatizer Glide path Lacatizer Final track Glide path Loca Intercept & initial track thermediale Irack Final trock
Glide path Localizer Glide path Localizer Glide path Localizer DIFFICULTY PRECISION GOOD MINIMUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET D_K_ BOST ABOUT 10 KNOTS IN MAINTAINING CLIDE PATH ON FINAL, SUT RECOVERED IT DURING THE PLAKE. COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT D:FFICULTY DIFFICULTY COMMENTS: 7. CONTROL TECHNIQUE COMMENTS F DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NONE 9 LEAST OBJECTIONABLE FEATURES IÓ. MOST OBJECTIONABLE FEATURES LUNGITUDINAL BEHAVIOUR LACKS CRISPNESS, (HEAVE BEHAVIOUR ND PROBLEM), IF PITCH BEHAVIOUR WERE A BIT MORE POSITIVE THIS WOULD BE A GOOD MODEL. ELEVATOR MORES WERE LOW. II MISCELLANEOUS



CONF/GURATION 4-2PL FLIGHT NUMBER 110-2 PILOT A
PILOT-RATING 81/2

CHARACTERISTIC ROOTS

WIND(knois) WIND SHEAR EXTERNAL TUABULENCE

+.074 ± .371 -.30 -1.66

CONFIGURATION 4-2PL FLIGHT NUMBER 92-2 PILOT B PILOT-RATING 7 1/2 D

W:NO(knots) 5 KNOTS
WIND SHEAR SNALL
EXTERNAL TURBULENCE NEGLIGIBLE

CHARACTERISTIC ROOTS +.074± ,371 -.30 -1.66

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELE V	ATOR	THRUST LEVER		
V8E - 25	(rad/sec ²)/m	Z8T=11.9	IfI/sec ² l/in	
In Ital	Final	Initial	Final	
SATISPAUTORY	TOO GREAT	SATISFACTORY	SATISFACTORY	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION
TURBULENCE
DIFFICULTY
MAX:MUM UNDESIRED FLUCTUATIONS

			lical velocity	(11)
VMC IMC	IMC	VMC	IMC	1M.C
QUT QUT	IN	OUT	OUT	IN
MODERATE MODERATE	GREAT	SLIGHT	MODERATE	MODERATE
±5 TO 8	knats		±200	fpm.

THE DESIRED PITCH ATTITUDE COULD NEVER BE POIND FOR LONG. THE TURBULENCE AND THE EMORNOUS RESPONSE TO ELEVATOR CAUSED A GREAT WORK LOAD IN CONTROLLING PITCH ATTITUDE.

ELE	VATOR	THAUS	T LEVER
Mag = 25	(rad/sec2)/in	Z _{8T} =11.9	(tt/sec ²)/in
Initial	Final	Initia'	Final
SATISFACTORY	SAT IS FACTORY	SATISFACTORY	SATISPACTORY

Longit	udino) veloci	ty (IAS)	Ver	ical velocit	y (B)
VMC	IMC	I.M.C	VMC	1 M C	I M.C
OUT	Out	IN	OU?	OUT	IN
SLIGHT	MODERATE	MODERATE	SLIGHT	SLIGHT	MODERATE
	+10 -0	knots		± 200	fom

DIFFICULTY-CAUSED BY AN UNDERLYING PITCHING OSCILLATION, REACHED 1300 F.P.M. ON DESCENT AND ALTHOUGH IT WAS NEEDED, NOT SURE HOW IT AROSE.

3 RESIDUAL OSCILLATORY CHARACTER STICS

HEAVE EXC TATION

AMPLITUDE	PERIOD	DAMPING
MODERATE	LONG	NEGAT: VE
SOURCE		DEGREE
	TWO E	EASILY
<u>ELEVATOR, TURBULI</u>	ENCE	PASTE

COMMENTS THE OSCILLATION WAS SEEN TO BE DIVERGENT BY LETTING IT BUILD UP FOR ABOUT THREE CYCLES. THROUGHOUT EVALUATION OSCILLATION WAS PRESENT

AMPLITUDE	PERIOD	DAMPING
SMAILL/MODERATE	LONG (10 SECS)	ZERO
SMALI,	LONG	ZERO
SCURCE		DEGREE

VERY BOTHERSOME TO HAVE TO CONTROL THE OSCILLATION.

4 CHANGE 'N THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

 NEGLIGIBLE	
	DEFICULTY

THE AIRSPEED GOT HIGH AND THE CORRECTION PRODUCED A VERY LARGE FITCH RATE AND AN UNEXPECTEDLY LARGE MOSE-UP ATTITUDE,

SMALI.	
SLIGHT	DIFFICULTY

Intercent & pitial track | Intermediate teach

UNDERLYING PETCH OSCILLATION DEMANDS TOO MUCH ATTENTION.

5 FLIGHT PATH CONTROL

DIFFICULTY: PRECISION

		'rte-med		F-nal	
Glide path	Localizer	Gide poth	Locolizer	Glide path	Localizer
SLIGHT	MUDERATE	SLIGHT	MODERATE	SLIGHT	мопенате
PAIR	VERY POOR	FAIR	FAIR	FAIR	FOOR

TIGHT CONTROL OVER LOCALIZER AND GITDE SLOPE HEROES WAS NEGESSARY TO ORGAIN A "MAIN" PERFORMANCE, RESULTING IN TOO HIGH A WORK LUAD, PERFORDIPATION WITH PITCH ATTITUDE CAUSED THE "VERY PROOF" LOCALIZER INTERCEPT.

6 BREAKOLT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

NO NO	DIFFICULTY
FAIR/COOD	

COMMENTS:

miercep u	milion mack	Intellinediate Huck		Final	rack
Glide path	Localizer	Glide parh	Local zer	Glide palm	Localizer
SLIGHT	SLIGHT	SLICHT	SLIGHT	SLIGHT	SLIGHT
FATR	FA1R	SAIR	FAIR	GOOD	cona

E-nal 4-nah

336

GREATER DIFFICULTY WAS EXPERIENCED WITH THE LOCALISER ON THE FIRST HALF OF THE APPROACH DURING S-TURNS. THIS WAS A DISPLAY CROSS-CHECK PROBLEM WITH NOT ENDEGH HEADING INFORMATION.

DIFFICULT TO WOLD AIRSPERD. AT 75 PEET NOTICED TENDENCY TO PLARE. PUSHED NOSE DOWN AND "BALLOONED", UPSETTING FLIGHT PATH.

SCIGHT DIFFICULTY

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

E LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT NONE

9 LEAST CHIECTIONABLE "EATIRES

NONE, BUT STILL DIFFICULT TO TRIM. NEED SOME RUDDER APPLICATION IN 20 DEGREE BANK TURNS.

IC. MOST OBJECTIONABLE FEATURES

PITCHING OSCILLATION DEMANDS TOO MUCH ATTENTION TO CONTROL ATTITUDE AND HENCE AIRSPEED. RATE OF DESCENT AND GLIDE SLOPE NOT PRECISELY UNDER CONTROL.

II. MISCEL_ANEOUS

SENSITIVE TO TURBULENCE IN PITCH.



CONFIGURATION 19-P FLIGHT NUMBER 119-1 PILOT A PILOT-RATING 9

WINDIknoist WIND SHEAR SMALL EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION 19-P FLIGHT NUMBER 17-1 PILOT B PI_OT-RATING 8

CHARACTERISTIC ROOTS

WIND (knots) 10 WINC SHEAR MODERATE
EXTERNAL TURBULENCE MODERATE

.10 ± .4441 -.47 -.81

CHARACTERISTIC ROOTS

.10± .4441 -.47 -.81

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSIT-VITY:

RESPONSE

ELEVATOR

Mag = 0.3 frod/sec²//in Zag = 11.9 (tr/sec²//in louis) Final louis India Final
SATISFACTORY SATISFACTORY SATISFACTORY TOO GREAT

2.EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE: DIFFICULTY

MAXIMUM UNDESIRED FLUCTUATIONS

	31 4 1	. (110)	···	Van daris	16.
Longitu	dinal vela	CITY (TAS)	vei	tica velocity	(n)
V.M.C.	1MC	LM C	VMC	IMC	1 M C
001	QUT	IN	QUT	OUT	IN
MODERATE	GREAT	GREAT	SLIGHT	MODERATE	MODERATE
±	10	knols		100	fp.m

COMMENTS

MOSE CONSTANTLY BOBBING UP AND DOWN DUE TO A DIVERGENT OSCILLATION PLUS A LARGE STEADY STATE RESPONSE FROM ELEVATOR.

Vac : 0.2 (rad/sec²)/m Z_{BT}:11.9 (f1/sec²)/in Final Initial Final Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY

V.MC i M.C I M.C OUT OUT IN V. SLIGHT V. SLIGHT V. SLIGHT V M.C I M C

SOME DIFFICULTY WITH SPEED CONTROL IN TURNS ESPECIALLY WITH TURBULENCE IN. PROBABLY DUR TO CHARACING ATTITUDE REFERENCE AT HIGHER BANK ANGLES. ALSO PITCH CHARACTERISTICS REQUIRED CREATER ATTENTION TO PITCH ATTITUDE ON INSTRUMENT CROSS-CHECKS.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE	PE	RIOD DAMPING
LARGE	MEDIUM	NEGATIVE
SOURC	E	DEGREE
ELEVATOR, TURBULE	NCE	EAS1LY
BLEVATOR		INEFFECTIVE

EXCITATION CONTROL COMMENTS

THIS OSCILLATION WAS THE MAIN SOURCE OF DIFFICULTY

AMPL-TUDE PÉRIOD DAMPING MEDIUM LOW SOURCE DEGREE ELEVATOR, TURBULENCE ELEVATOR

MOULDN'T NOTICE IT OCCURRING HORMALLY (LIKE AN EASILY CONTROLLED PHUCOID), BUT IN I.M.C. AND TURBULENCE, THE EFFECTS ARE EASY TO SEE.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED: EASE OF COMPENSATION

DIFFICULTY

COMMENTS

FIRST TURN WENT WELL, BUT THE SECOND AND THIRD CAUSED PROBLEMS IN HEIGHT HOLD, PROBABLY DUE TO AMOUNT OF ATTENTION REQUIRED IN PITCH CONTROL.

MODERATE/SMALL SLIGHT D'FFICULTY

IN 1.M.C. CONDITIONS WITH TURBULENCE, IT IS DIFFICULT TO NOTE PITCH ATTITUDE REFERENCE - NEED TO STABILIZE PITCH ATTITUDE IN TURNS.

Intercept & initial track | Intermediate track | Final track |
Glide path | Localizer | Glide path | Localizer | Glide path | Localizer |

NONE

SLIGHT

FAIR

SLIGHT

FAIR

5. FLIGHT PATH CONTROL

DIFFICULTY

PRECISION

		Intermediate track Final track			
Glide path	Localizer	Glide path	_0 CO PEr	Slide potn	Local zer
				l	

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 800

COMMENTS

COMMENTS

THE APPROACH PERFORMANCE WAS QUITE GOOD BUT THE MOXIMIDAD WAS ENDRHOUS, ALL VENT VEIL ENTIL ABOUT 300 FT, WHEN THE VINDSHEAR STATETE TO COME IN IN THE OPPOSITE UTRICTION TO THAT OF PREVIOUS TESTS.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT
PRECISION OF ATTAINING TOUCHDOWN POINT

SLIGHT FAIR/COOD DIFFICULTY:

SURPRISHMELY, THE PITCH OSCILLATIONS WERE MORE PROMOUNCED DURING THIS MANOEUVRE AND COULD GAUSE AS MUCH DIFFICULTY HERE AS WHEN I.M.C.

7 CONTROL TECHNIQUE

COMMENTS F DIFFERENT FROM I A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS FFFECT ON FINAL ASSESSMEN" NONE

9 LEAST OBJECTIONABLE FEATURES

A LOT OF ATTENTION TO PITCH ATTITUDE HAS REQUIRED. AS A RESULT THE AIRSPEED WAS HELD AT 60KTS. SURPRISINGLY WELL.

NONE

IC. MOST OBJECTIONABLE FEATURES OSCILLATORY CHARACTERISTICS

PITCH OSCILLATIONS

II. MISCELLANEOUS

EMGINE MANIFOLD PRESSURE VAS USED AS A QUE FOR THRUST REPULERMENTS DURING APPROACH. NOTS: THE MANIFOLD PRESSURE CAUGE MAS PARTIALLY COVERED AFTER FLIGHT #28 TO ELIMINATE THIS QUE.



FLIGHT NUMBER 106-3
PILOT A
PILOT-RATING 8

CONFIGURATION 19-3PL WIND(knots)
FLIGHT NUMBER 106-3 WIND SHEAR MODERATE
PLOT A EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS .102± .441 -.47 -.81

CONFIGURATION 19-2P FLIGHT NUMBER 33-2 PLOT B PILOT-RATING 9 1/2

WIND (knots)
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS .102 ± .441 -.47 -.81

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

	VATOR	THRUST LEVER	
Mag = . 20	(rod/sec2)/in	Zar = 11.9	(11/sec ²]/in
'ritiol	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2.EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE

MAXIMUM UNDESIRED F_UCTUATIONS

	Langit	udinal veloc	ty (IAS)	Verl	(h)	
	V.M.C	I.MC	IMC	VMC	IMC	I.M.C
	OUT	DUT	IN	OUT	out	1//
	SLIGHT	MODERATE	GREAT			Ī
5	-	10, -10	knois	+1	00, -100	fpm

COMMENTS:

TURBULENCE BOUNCED NOSE AROUND TOO MUCH AND THE STEADY STATE RESPONSE TO PITCH CONTROL IS SO ENDIMOUS THAT STABLE CONDITIONS IN PITCH-ATTITUDE/AIRSPEED ARE IMPOSSIBLE

ELEVATOR		THRUST LEVER	
V 8€ = .30	(rad/sec2)/in	Z _{8↑} = 15.0	Ift/sec21/in
Initial	Final	Initial	Final
TOO GREAT		NOT ASSESSABLE	NOT ASSESSABLE

Long f	udinal veloci	ly (LAS)	Verti	cal velocity	(h)
VMC	IMC	IMC	V.M.C.	[MC	J M.C
DJT	OUT	L.IN.	QUT	OUT	- N
SLIGHT	>SLIGHT	>SLIGHT			
+5	5	knots	+400	-400	fpr

HEAVE/PITCH OSCILLATION.
TIME CONSTANT OF VERTICAL VELOCITY CONTROL (= 30 SECS)
IS LONGER THAN THAT OF LONGITUDINAL VELOCITY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

P:TCh HEAVE

AMPLITUDE	PERIOD	DAMPING
ZERO		
ZERO		
SOURCE		DEGRÉE

EXCITATION -

COMMENTS

AMPLITUDE	PER	100	DAMPING
MODERATE	LONG		ZERO/LOW
LARGE	LONG		ZERO/LOW
SOURCE	2		DEGREE
ELEVATOR		AGGRAVATING	

'ALONG FOR THE RIDE'

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

NEGLIGIBLE NO DIFFICULTY

COMMENTS

NEGLIGIBLE	"
NO	DIFFICULTY

5. FLIGHT PATH CONTROL

DIFFICULTY	
PRECISION	

intercept B				Firal	
Glide path	Localizer	Glide potr	Localizer	Glde oath	Localizer
NONE	SLICHT	MODERATE	MODERATE.	MODERATE	SLIGHT
GUOD	FAIR	FAIR	POOR	POOR	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 500

COMMENTS

AS PER SECTION 2 ABOVE

NONE

THIS MODEL NOT SUITABLE FOR I.M.C. FLIGHT. DID NOT TRY TO FOLLOW GLIDE SLOPE TOU CLOSELY, BUT ALMED TO PICK IT UP AT APPROXIMATELY 800 FEET. ONCE ON GLIDE SLOPE, TRACKING NOT TOO BAD. LOST 500 FEET IN TURN TO BASE AND

intercept 6 initial track | Intermediale track | Final track | Gide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide MODERATE SLIGHT MODERATE SLIGHT SMODERATE SLIGHT > FAIR

GOOD

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTA WING TOUCHDOWN POINT

NO .	 DIFF CULTY
FAIR	

COMMENTS

THE AIRCRAFT FELT AS THOUGH IT HAD TO BE HANDLED GENTLY TO PREVENT OVER-CONTROLLING.

MODERATE DEFICULTY
POOR

DIFFIGULTY IN CONTROLLING PERCEIVED VERTICAL VELOCITY WITH CORRECT PHASING OF THE THRUST LEVER, DIFFIGULTY IN LONGITUDINAL SERSE DUE TO LARGE VERTICAL, VELOCITY AT TOUCHDOWN, FOSITIONING AT BREAKDUT WAS GOOD.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT NONE

9 LEAST OBJECTIONABLE FEATURES

10. MOST OBJECTIONABLE FEATURES AS PER SECTION 2 AROVE

OSCILLATION; THIS LED TO DISORIENTATION, CONSERVATIVE CONTROL APPLICATION AND TOUCHDOWN PROBLEMS.

II. MISCELLANEOUS

AN AFT ELEVATOR STEP INPUT, ACCELERATES THE COCKPIT DOWN AND THEN UP (LIKE FLYING FROM THE TAIL END OF A STEETCHED DG-2). CORFUSING AND DISORIENTATING RESPONSE FOR HIGH FREQUENCY ELEVATOR INPUTS.



CONFIGURATION 19-2NL FLIGHT NUMBER 74-3 PILOT A PILOT-RATING 7

WINDIKnots)
WIND SHEAR SMALL
EXTERNAL TURBULENCE MEGLIGIBLE

CHARACTERISTIC ROOTS -.183 .104 -.489 .0851

CONFIGURATION 19-2NL FLIGHT NUMBER 94-3 PILOT 8 PILOT-RATING 7C

WIND (knots) B
WIND SHEAR
EXTERNAL TURBULENCE NONE

CHARACTERISTIC ROOTS -.183 .104 -.489± .0851

I A/RCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEVATOR		THRUS	T LEVER
Mag = .20	(rod/sec ²)/i	n Zay: 15.0	(ft/sec ²)/in
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE:
DIFFICULTY
MAX:MUM UNDESIRED FLUCTUATIONS

	Langitu	diral veloc	ty (IAS)	Vert	ical velocity	(6)
	V.M.C	IMC	LM C	VMC	: M C	: M C
	OUT	OUT	IÑ	OUT	OJT	IN
	MODERATE	MODERATE	GREAT	SLIGHT	MODERATE	MODERATE
S		+1212	knols	+2	00, -200	f pm

RESPONSE

THE PITCH ATTITUDE WAS CONSTANTLY CHANGING SINCE A PITCH RATE APPARENTLY RESULTED FROM A STEADY STATE ELEVATOR CONTROL INPUT. THE TURBULENCE ADDED TO THIS DIFFICULTY.

ELE	VATOR .	THRUST	LEVER
M _{δE} = , 20	(rad/sec²)/in	Z _{BT} = 15.0	{ft/sec2}/:n
Initial	Final	Initial	Final
SATISFACTORY	SATISFACTORY	SATIS FACTORY	SAT IS FACTORY

| Udinb. | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Verty | Ver VMC SLIGHT fpm

DIFFICULTY DUE TO: 1. CROSSCRECK, 2. INTERACTION BETWEEN LONGITUDINAL AND VERTICAL VELOCITIES, 3. PITCH CHARACTER-

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE PERIOD DAMPINO MEDIUM MODERATE ZERO LQW SOURCE DEGREE ELEVATOR, TURBULENCE ELEVATOR EAS LLY AGGRAVATING

EXCITATION CONTRO: COMMENTS

COMMENTS

THE PITCH ATTITUDE SEEMED TO BOUNCE BACK AFTER A DISTURBANCE, BUT UPON CLOSER EXAMINATION IT APPEARS THAT THIS WAS PILOT-INDUCED THROUGH THE ELEVATOR.

AMPL-TUDE	PERIOD	DAMPING
\$OJRCE		DEGREE

IT WAS NOT POSSIBLE TO EXCITE A PITCH OSCILLATION THAT COULD BE OBSERVED OVER ONE OR MORE CYCLES. HOMEVER I SENSED SEVERAL UNDERLYING PITCH REVESSALS THAT WERE QUITE BOTHERSOME. IN RESPONSE TO SHALL STEP ELEVATOR INPUTS, I WAS ONLY ABLE TO SEE A PITCH DIVERGENCE.

NEED TO HOLD AIRSPEED DUE TO INTERACTION SETWEEN VERTICAL

DIFFICULTY

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

SMALL, NG

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept &	mitial track	Intermedi	ate trock	Final	track
Glide poth	Localizer	Glide path	Locolizer	Gl de path	Localizer
SLIGHT	SLICHT	MODERATE	MODERATE	MODERATE	SLIGHT
EALR	FAIR	POOR	POOR	POOR	FAIR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET 600

COMMENTS

THE CONTROL OF AIRSPEED THROUGH PITCH ATTITUDE REQUIRED TOO MUCH ATTENTION, LEAVING TOO LITTLE TIME FOR APPROACH MONITORING.

DIFFICULTY

6 BREAKOUT AND FLARE

EASE OF ARRI				
PRECISION OF	ATTAINING	TOUCHDOWN	POINT	

COMMENTS

	initial track			Fino'	
Glide poth	Lacalizer	Glide path	Localizer	Glide path	Localizer
HONE	SLICHT	SLIGHT	SLICHT	SLICHT	SLIGHT
COOD	COOD	FAIR	FAIR	POOR	FAIR/POO

300

DIFFICULTY DUE TO:

1. S-THERS TO STAY ON THE LOCALISER - INSTRUMENT DISPLAY AND CONSCHECK PROBLEMS

2. VERY POOR SPEED CONTROL (±10 KNOTS REGULARLY) MADE CLIDE PATH CONTROL MORE DIFFICULT.

SLIGHT DIFFICULTY
FAIR

LOW AT BREAKOUT.

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM I.A.S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FIVAL ASSESSMENT SMALL: THE YAHING CHARACTERISTICS ARE RATHER IBRHANDING IN THAT A LARGE SIDESLIP ANGLE DEVELOPS FROM A VERY SMALL RUDDER INPHT, (APPROX. 15°B POR 0.5 INS. 8;

CONTROL TECHNIQUE VERY ROUGH ON THIS APPROACH - LARGE AGGRESSIVE INPUTS TO CORRECT GENERALLY LARGE AMPLITUDE ERRORS.

SMALL: 5 - TURNS TO STAY ON THE LOCALISER DUE TO INSTRUMENT DISPLAY/CROSS CHECK PROBLEMS.

10. MOST OBJECTIONABLE FEATURES

EXPERIENCED APPARENT PITCH REVERSALS AFTER FITCH CONTROL INPUTS, MAKING SPEED AND ATTITUDE CONTROL VERY DIFFICULT. GENERALLY UNSTABLE IN FITCH (NOTE SO THAN USUAL).

II. MISCE_LANEOUS

SOME PITCH UPSETS DUE TO TURBULENCE COULD BE THE CAUSE OF APPARENT REVERSALS.
NOTE: PILOT CONTROL INPUTS LARGE TO CORRECT LARGE AMPLITUDE ERRORS. NO SIMULATED TURBULENCE FOR THIS EVALUATION.



CONFIGURATION 19-32 FLIGHT NUMBER 3-1

WIND(knots)

PILOT A
PILOT-RATING 7 1/2

WIND SHEAR EXTERNAL TURBULENCE ZERD

CHARACTERISTIC ROOTS

.101± .4211 -.47 -.80

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE :

EL	EVATOR	THRUST LEVER		
Mac = . 20	(rod/sec2)/s	ZBT - 12.0	(ft/sec ² /in	
Initial	Final	Initial	Final	
G000	TOO GREAT	TOO SMALL	TOO SMALL	

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

Γ	_ongi*u	dinat veloci	ty (1AS)	Verl	ical velocity	(fi)
٦	VMC	1MC	LMC	VMC	IMC	I.M.C
Γ	OUT	QUT	IN	QUT	OUT	IN
Г		MODERATE	MODERATE		GREAT	GREAT
ı	±	2	knots	± 40	O	fp.m.

COMMENTS

PITCH ATTITUDE SEEMED DIFFICULT TO SELECT AND HOLD, (SOMEWHAT OSCILLATORY).
LONG FREQUENCY MANDER IN VERTICAL VELOCITY CHAMGED RATE OF DESCENT FROM 900 TO 400 F.P.N. OR APPROAGE. RESULT: MIGH ON CLIDE PATH, TURBULENCE HAD LARGE EFFECT ON VERTICAL.

VELOCITY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE	PER OC	DAMPING
LARGE	MEDIUM	WQ.1
SMALL		

EXCIPATION CONTROL

SOURCE	DEGREE
ELEVATOR	EASILY
ELEVATOR	# PPECTIVE

COMMENTS

AMPL TUDE	PERIOD	DAMPING
MODERATE	LONG	NEGAT I VE
MODERATE	LONG	?

WIND (knots)

WIND SHEAR SMALL EXTERNAL TURBULENCE LIGHT

VATOR THRUST LEVER

(rad/sec²)/in Z8_T: 15.0 ((1/sec²)/in

Final Initial Final

.101 ± .4211 -.47 -.80

SATISPACTORY

SOURCE DEGREE EASILY EFFECTIVE

VERY ANNOYING. ANY SIMILAR HEAVE OSCILLATION WAS MASKED BY INCINE FORER SUBCING LIMITATIONS WHICH RESULTED IN WHAT MIGHT HAVE LOCKED LIKE A THRUST CONTROL P.1.O. ON RECORD-INGS.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DIFFICULTY

COMMENTS

THRIST SENSITIVITY AT REGINNING OF FLIGHT WAS TOTALLY IMADEQUATS EVEN WITHOUT TURBULENCE. AN INGERASE OF ACCUMENOUS THE SITUATION BUT SITUA PROVED TOO LOW TO ARREST THE LANDING FLARE ADEQUATELY.

DIFFICULTY

CONFIGURATION 19-3P FLIGHT NUMBER 115-2 PILOT B

PI_OT-RATING 8 1/2 D CHARACTERISTIC ROOTS

MBE - 20 (re

SATISFACTORY TOO GREAT

PITCH ATTITUDE AND AIRSPEED HAD TO BE MONITORED CLOSELY AS IN MOST MODELS.

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

			initial trac					nai	
Giide	por	h	Local zer	Gide	parh	_acol-zer	Glide	path	Locolger
				MOD	ERATE	SLIGHT			
				P00	3	FAIR			

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE

COMMENTS

	initial track				
Gl de path	Locarizer	Glide poth	Localizer	Glide path	Localizer
v. Si.IGHT	V.SLIGHT	V. SLIGHT	v. Slight	V. SLIGHT	V. SLIGHT
				FAER/GOOD	

300

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT GREAT DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT POOK

COMMENTS

CIFFICULTY TENDENCY FOR A PITCH-KEAVE P.I.O. NEAR THE GROUND,

7 CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM I.A.S. WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL; LOW SUDDER PEDAL PORCES

9 LEAST OBJECTIONABLE FEATURES

ID. MOST OBJECTIONABLE FEATURES

PITCH-HEAVE. DIVERGENT OSCILLATION.

I MISCELLANEOUS

ELEVATOR AND RUDDER FORCES LOW THRUST LEVER SENSITIVITY CHANGED FROM 7.5 to 12.0



CONFIGURATION 19-3N FLIGHT NUMBER 15-1 P:LOT A P:LOT-RATING 9

WIND(knois) WIND SHEAR EXTERNAL TURBULENCE

CHARACTERISTIC ROOTS .077 -.106 -.5144 .0851

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY RESPONSE

ELEV	/ATOR	THRUS	T_LEVER
M8E:.20	(rad/sec2)/in	Z81 = 15.0	(It/sec ²)/in
Initial	Finel	Initia	Finol
SATISFACTORY	TOO GREAT	TOO SMALL	TOO GREAT
		•	

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE:
DIFFICULTY
MAXIMUM UNDES-RED FLUCTUATIONS

i	cal velocity	Vert	ly (TAS)	nal veloci	Longitud
IN C	I.M.C	VMC	IMC	IM'C	VMC.
IN	QUT	0u1	IN	QuT	OUT
REAT	MODERATE	STICHT	GREAT	GREAT	MODERATE
f, p.m	300, -200		kno*s		±7
		2. TCRL		UREAT	#OBERATE ±7

COMMENTS

PITCH ATTITUDE CONSTANTLY WANDERS AND SEEMS TO BOUNCE BACK AFTER BEING PUT AT A DESIRED POSITION. THE HEAVE WANDERS AS WELL AND IN SOME CASES THE CONTROL INPUT SEEDED TO AGGRAVATE THE SITUATION.

CHARACTERISTIC ROOTS	.027106	-,514# .0851
ELEVATOR MRE = .20 (rad	THRU /sec2)/in Zst: 12,0	JST LEVER

Initial Final
SATISFACTORY SATISFACTORY

CONFIGURATION 19-3N WIND(knots) 8
FLIGHT NUMBER 25/26-1 WIND SHEAR ?
PLOT RATING 10

WIND SHEAR ?
EXTERNAL TURBULENCE VERY LIGHT

Longitu	dinal veloci	ly (IAS)	Vert	cal velocity	(8)
VMC	IMC	LMC.	VMC	2.M.C	"IMC
DUT	OUT	IN	DUT	OUT	IN
MODERATE	MODERATE	MODERATE	GREAT	CREAT	CREAT
	±20	knots	+100	1000	fp.n

NOT ASSESSABLE

LARGE AIRSPEED/VERTICAL SPEED INTERACTION. POWER LEVER CHARACTERISTICS CANNOT BE ASSESSED IN THE PRESENCE OF THIS INTERACTION.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

HEAVE

AMPLITUDE	PERIOD	DAMPING
MODERATE	LONG	LDW
MODERATE	LONG	TOM.

EXC TATION CONTROL

SOURCE	DEGREE
ELEVATOR, TURBULENCE	EASTLY
ELSVATOR, THRUST LEVER	INEFFECTIVE
ELEVATOR, THRUST LEVER	INEFFECTIVE

COMMENTS

AS PER SECTION 2 ABOVE.

AMPLITUDE	PERIOD	CAMPING
ZERO		
ZERO		
SOURCE		DEGREE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

SMALI. DIFFICULTY

COMMENTS

	DIFFICULTY
GREAT	DIFFICULT

MUST MAINTAIN AIRSPEED. MUST ADD SOME POWER BUT NEVER KNEW HOW MUCH,

5 FLIGHT PATH CONTROL

D-FFICL_TY PRECISION

	initial track			F:no:	trock
Glide path	Localizer	Gude path	Loconzer	Glide path	Localize:
MODERATE	SLIGHT	MODERATE	SLICHT	MODERATE	SLIGHT
PCOR	GOOD	VERY POOR	COCO	VERY POOR	GOOD

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

INTENUED TO STAY SLIGHTLY LOW ON CLIDE PATH BUT AT ABOUT 500 FEET VENT BELOW THE ROTTOM OF THE BEAM WHICH WAS INCLUDED. BEAM BY KOO FEET, BUT COMPORTABLE.

Intermediate frack Glide path | Localizer Final track Glide path Localizer SLIGHT MODERATE FAIR POOR

DIFFICULTY

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

SLIGHT	D	FICULTY
PAIR		

COMMENTS

LOST CONTROL AT 800 FEET,

NOT SUITABLE FOR IFR PLIGHT. LOST CONTROL AT 800 FEET.

7 CONTROL TECHNIQUE

COMMENTS OF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS NONE

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

.O MOST OBJECT ONABLE FEATURES

TRIED TO CONTROL VERTICAL SPEED WITH AIRSPEED.

NONE

GREAT INTERACTION OF VERTICAL SPEED HITH AIRSPEED
VARIATION.
 LOW HEAVE DAMPING, THUS POWER CONTROL REQUIREMENTS
CONFISSING.

II MISCELLANEOUS

THRUST CONTROL SENSITIVITY CHANGED FROM 12.0 TO 15.0.



CONFIGURATION 8-PL FLIGHT NUMBER 66-1 PLOT A PILOT-RATING 55

CHARACTERISTIC ROOTS

WIND(knots) CALM WINC SHEAR SMALL EXTERNAL TERBULENCE NEGLIGIBLE

- 22 -L.65

CONFIGURATION 8-PL FLIGHT NUMBER 48-2 PILOT D PILOT D
PILOT-RATING 65

WIND (knots) 10
WIND SHEAR SHALL
EXTERNAL TURBULENCE LIGHT

CHARACTERISTIC ROOTS .032± .341 -.22 -1.65

I. AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY: RESPONSE

ELE	VATOR	THRUS	LEVER
Mac : .30	(rod/sec ²)/ n	Z8T - 7.5	(ft/sec2)/in
Incial	Final	initial	Final
SATIS FAUTORY	SATISFACTORY	SATISFACTORY	SATISPACTORY

.032± .341

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION	١
TURBULENCÉ:	
DIFFICULTY	5
MAXIMUM UNDESIRED FLLCTUATIONS	

Longitu	idinol veloc	ily (TAS)	Vert	ical velocity	(6)
V.M.C	1M.C	IMC	VMC	I.M.C	IMC
OUT	TLO	IN	DUT	OUT	IN
SLIGHT	SLICHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
	±5	knots			l.pm

COMMENTS:

SEE SECTION #10.

ELE	VATOR	THRUS	T LEVER
M _{8E} = .35	(rod/sec2 1/in	Z _{8T} = 7.5	(ft/sec ²)/in
Initial	F nat	Initial	Final
TOO GREAT	TOO GREAT	TOO SMALL	TOO SMALL

Longitu	dinal veloc	ity ([A5)	Verl	ical velocity	
VMC	1 M C	IMC	VMC	LMC	IMC
OU-	our	IN	OUT	DUT	1N
SLIGHT	SLIGHT	MODERATE	SLIGHT	>SLIGHT	MODERATE
	±10	knats	± 30	Ď .	for.

DIFFICULTY DUE TO OPERATION ON BACK-SIDE OF POWER REQUIRED CURVE AND TO A SLIGHTLY NEGATIVELY DAMPING PRUGOLD OF MODERATELY SHORT PERIOD.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH HEAVE	ANPLITUDE 2ERO ZERO	FERIOD	DAMPING
EXCITATION:	SOURCE		DEGREE

SOURCE	DEGREE

SOURCE DEGREE

CLOSED-LOOP TENDENCY TO P.I.O.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED.

MODERATE	
SLICHT	DIFFICU_TY

COMMENTS

COMMEN'S

INGREASING RATE OF SINK WITH BANK ANGLE IS EASILY COMPENSATED FOR BY SLIGHT POWER LEVER INPUTS.

MODERATE / LARGE	
MODERATE	DIFFICULTY

LARGE POWER CHANGES REQUIRED FOR MODERATE CHANGES OF ALESPEED. HONEVER, NOT AS RAD AS WITH SOME PREVIOUS CONFIGURATIONS.

5 FLIGHT PATH CONTROL

	Intercept & initial track		latermediate track		Final track	
	Glide path	Localizer	Glide palh	Localizer	Gide path	Localize.
O.≠FICULTY.	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT
PRECISION	HIAS	FAIR	FA1R	FAIR	FAIR	PA1R

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

COMMENTS

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT	SUIGHT DIFFICULTY
--	-------------------

COMMENTS

	initial track		igte frack	Final	
G ide path	Localize	Glide path	Localizer	Gl de palh	Localizer
SLIGHT	SLIGHT	>SLIGHT	> SLIGHT	MODERATE	MODERATE
COOD	FAIR	FAIR	FAIR	FAIR	FAIR

CONSTANT ATTENTION REQUIRED TO AIRSPEED THROUGH ATTITUDE CONTROL, WITH A TENDENCY TOWARD F.1.O. WHEN CLOSING THE ATTITUDE LOOP VERY TIGHTLY.

DIFF CULTY

7 CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

LF LARCE CHANGES WERE REQUIRED IN RATE OF DESCENT, A CHANGE OF AIRSPEED IN THE RIGHT DIRECTION HELPED ADJUST THE RATE OF DESCENT WITHOUT EXCESSIVE THRUST LEVER OPERATION.

SHORT PERIOD SEEMED WELL DAMPED.

VERY SLIGHT

IC. MOST CBUECTIONABLE FEATURES

THE PITCH ATTITUDE SEPHED SLOPPY, ESPECIALLY WHEN THE TURBULENCE WAS SWITCHED IN, AND REQUIRED MUCH TO MUCH ATTENTION. THE APPROACH WENT WELL BUT THE WORK LOAD WAS FAIRLY HIGH.

CONSTANT ATTENTION TO AIRSPEED, AND MUCG POWER LEVER ACTIVITY REQUIRED. A P.I.O. TENDENCY, PARTICULARLY WITH TURBULENCE IN UNDER I.M.C. CONDITIONS.

IL V SCELLANEOUS

FROM A PASSENGER COMPORT STANDPOINT THIS CONFIGURATION WOULD DEFINITELY BE UNACCEPTABLE,



WIND(knots) 5
WIND SHEAR MODERATE
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION 8-2PL FLIGHT NUMBER 127-3 PILOT B PI_OT-RATING 8D CONFIGURATION 8-2PL FLIGH* NUMBER 71-L WIND (knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE PILOT A
PILOT-RATING 54 CHARACTERISTIC ROOTS .028± .351 -.20 -1.67 CHARACTERISTIC ROOTS .028 ± .351 -.20 -1.67 LAIRCRAFT RESPONSE TO CONTROL INPUTS TOO SMALL TÓO CREAT SATISFACTORY SATISFACTORY TOO SHALL TOO GREAT TOO GREAT

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE:
DIFFICULTY
MAXIMUM UNDES:RED FLUCTUATIONS

CONTROL SENSITIVITY:

RESPONSE -

Longitudir	nol veloc	ity (IAS)	Vert	cal velocity	
y.M.C.	IMC	I.M.C	VMC	TMC	1MC
DUT	:UT	IN	OUT	TUQ	10
NONE	S.IGHT	SLICHT	NONE	SLIGHT	SLIGHT
-10.	-5	knots	£ 200		f p.m.

TURBULENCE UPSETTING PITCH ATTITUDE AND MAKING IT DIFFICULT TO MAINTAIN AIRSPEED. POWER LEVER SEEMED TO HAVE LONG TIME CONSTANT RESULTING IN STEADY STATE LEVELS OF VENTICAL VELOCITY DIFFERENT FROM THOSE DESIRED.

	Longitud	nat veloci	Ty (IAS)	vert	-cal ve ocity	(4)
	VMC	LMC	IMC	VMC	IMC	["IMC
	OUT	QUT	IN	OUT	QUI	IN
- 1	NONE	NONE	NONE	MODERATE	MODERATE	MODERATE "
		±5	knots			f p m

MODEL HAD LOW HEIGHT RATE DAMPING AND THIS COUPLED WITH LOW POWER LEVER SENSITIVITY CAUSED SOME DIFFICULTY.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

	AMPLITUDE	PERIOD	DAMP-NG	
PITCH HEAVE	ZERO ZERO			_
EXCITATION: CONTROL	SOURCE		DEGREE	
COMMENTS				

AMPLITUDE	PERIOD	DAMPING
ZERO		
ZERO		
SOURCE		DEGREE

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMALL	
NO	DIFFICULTY

COMMENTS

CIFFICULTY COURDINATION IMPORTANT BECAUSE OF COUPLING EFFECT OF ATASPEED WITH VERTICAL VELOCITY. LONG RESPONSE TIME FOR POWER LEVER CHANGES MAKE IT NECESSARY TO ANTICIPATE POWER REQUIREMENTS WHEN AIRSPEED ERRORS DEVELOP.

SLIGHT

GOOD

HAD TO LEARN TO ANTICIPATE THRUST REQUIREMENTS REQUIRED TO CONTROL VERTICAL VELOCITY. POTENTIAL FOR LARGE HEIGHT RATE EXCURSIONS FXISTS.

initial track | Intermedials Track | Final track | Lacalizer | G. de path | Localizer | Gl de path | Localizer

SLIGHT

COOD

NONE

G000

NONE

COOD

5 FLIGHT PATH CONTROL

	Intercept & mitia track Intermediale to		ale trock			
	Glide poth	Localizer	Glide gath	Luconter	Glide path	Localizer
DIFFICULTY:	SLIGHT	SLICHT	SLIGHT	MODERATE	SLIGHT	MODERATE
PRECISION	FAIR	FAIR	FAIR	POOR	PAIR	PCCK

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

PIRST MODEL OF DAY AND WIND SHEAR HAD NOT BEEN DETERMINED. ONLY ABOUT 400 FPM WAS REQUIRED FOR MAJOR PORTION OF APPROACH.

6. BREAKO∪T AND FLARE

7 CONTROL TECHNIQUE

S RATE OF DESCENT INING TOUCHOOWN POINT	SLIGHT	D FFICUL
	0-0-	

COMMENTS

LT.

SLIGHT DIFFICULTY

WAS WELL SET UP AT BREAKDUT OND JUST HAD TO MAINTAIN CONDITIONS LITTL FOR CHOOMING. THE LONG TIME CONSTANT IN THE TENSIL LEVER CONTROL HAS SENSED JUST PRIOR TO TOUCHDOWN AND POTENTIALLY COULD LEAD TO DIFFICULTY.

LEVER

COMMENTS IF DIFFERENT FROM (A S WITH ELEVATOR AND . VERT:CAL SPEED WITH THRUST B LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

SMALL, AIRCRAFT SCEMED TO MAYE LOW WEATHSROOCK STABILITY. LARGE SIDESLIP RESULTS FROM SMALL MOVEMENT OF RUDDER PEDALS.

9 LEAST CBUECTIONABLE FEATURES

LONG RESPONSE TIME AFTER THRUST LEVER CHANGES. MODERATE COUPLING BETWEEN AIRSPEED AND VERTICAL VELOCITY.

IC. MOST OBJECTIONABLE FEATURES

II MISCELLANFOUS

VERY WEAK PITCH STABILITY APPEARS TO EXIST BUT IT IS MREFECTIVE BECAUSE OF THE MAPID INITIAL RESPONSE TO REFEATOR. DIFFICULT TO TRIM. FREQUENT PITCH UPSETS DUE TO THEMELENCE. RELEVATOR CONTRACT, SENSITIVITY CHANGED FROM 0.3 TO 0.2 AND FINALLY TO 0.25.

260

ntercept 8 Glide path

0000

GOOD

NONE



CONFIGURATION 8-ZP FLIGHT NUMBER 130-1 PILOT A WIND(xnots) 10-15
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION 8-2P FLIGHT NUMBER 36-2 PICOT 8 WIND (knots) WINC SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE PILOT B PILOT-RATING 8E-F PILOT A
PILOT-RATING 61 CHARACTERISTIC ROOTS .028 ± .351 -.20 -1.67 CHARACTERISTIC ROOTS .028 ± .351 -.20 -1.67 I AIRCRAFT RESPONSE TO CONTROL INPUTS Mage 30 trod/sec*)/in Zat 1.14 (tr/sec*)/an Zat 2.14 (tr/sec*)/an CONTROL SENSITIVITY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES | Vertical velocity (h)
| VMC | MC | [MC |
| OUT | OUT | IN
| VON: \$LIGHT | SLIGHT |
| \$200 | FLIGHT CONDITION
TURBULENCE
DIFFICULTY

MAXIMUM UNDESIRED FLUCTUATIONS

Longitudinal veloc by (LAS)
VMC 1MC 1 MC
0 UT 0 UT
IN
SLIGHT NUBBERTE HODERATE
+10 - 5 knots | Longitudinal velocity (TAS) | Veritor velocity (h) | VMC | IMC | MODERATELY HIGH APPARENT COUPLING SETWEEN AIRSPEED AND VERTICAL VELOCITY, REQUIRING CLOSE CONTROL OVER PITCH ATTITUDE. COMMENTS ATTITUDE CONTROL DIFFICULT SINCE SHALL OUT OF TRIM ELEVATOR GIVES CONTINUOUSLY CHANCING ATTITUDE. ALESPEED EFFECT ON POWER REQUIRED CAUSES HEIGHT CONTROL PROBLEMS. AS AIRSPEED INCREASES, POWER SETTING REQUIRED, DECREASES. 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE PERIOD CAMPING 5MALL LONG HEAVE SMALL LONG SOURCE SOURCE DEGREE DEGREE EXCITATION CONTROL COMMENTS ONLY A SLIGHT TRACE OF OSCILLATION WAS APPARENT. ONLY DETECTED OSCILLATION WHILE PUTTING AIRBURNE COURLET (NEWIS IN, THE MOSE DID START TO DIVERGE, HOWEVER, AS A RESULT OF TURBULENCE AND FLEVATOR INPUTS. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED. SMALI, DIFFICULTY SLIGHT DIFFICULTY NO PROBLEM AS LONG AS AIRSPEED WAS MAINTAINED. BUT THIS TYPE OF CONFIGURATION CAN CAUSE PROBLEMS IN HEIGHT WOLD WHEN THE AIRSPEED CHANGES. SEEMED TO NEED SOME ADDITIONAL THRUST EVEN THOUGH 60 KNOT ATREFERD WAS HELD PRECISELY. 5 FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Final Lock | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path Final track Glide poth Lacouser Intercept & mitto: Irack Glide path Locolizer Intermediale track Glide path Local zer MODERATE MODERATE DIFFICULTY SEIGHT SLIGHT SLIGHT SLIGHT NONE NONE NONE NONE NONE NONE PRECISION 6000 FAIR GOOD PAIR coon caron coon coon coop PAIR GOOD FAIR/GOOD HINIMUM ACCEPTABLE BREAKOUT ALTITUDE COMMENTS THE RATE OF CLIEB BERD OFF AS THE ALBSPEED INGREASID TO 70 KNOTS DIG 3D DEFRATION ON THE "BACK-SIDE" OF THE FOJER REQUIRED CURVE. HIGH WORK LOAD DUE TO INCESSITY TO TIGHTEN CONTROL OF PITCH ATTITUDE IN ORDER TO ENSURE GOOD VERTICAL SPEED CONTROL. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO SOOD DIFF.CU.,TY DIFF-CULTY MODERATE FAIR/GOOD BROKE OUT AT 55 KNOTS AND MAINTAINED 55 KNOTS TO THE FLARE. PITCHED AIMCRAFT JUST PRIGG TO TOUCHDOWN AND APPLIED A LOT OF THRUST LEVER IN ANTICIPATION OF THRUST REQUIREMENTS BUT THRUST DID NOT COME ON AS MICH AS NEEDED. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM VERTICAL SPEED WITH THRUST 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SMALL NONE 9 LEAST OBJECT: ONABLE FEATURES IO MOST OBJECTIONABLE FEATURES ROUGH RIDE IN TURBULENCE, POSSIBLE DISORIEMTATION. LA MODERATE COMPLING BETWEEN AIRSPEED AND WERTICAL SPEED REQUIRING TIGHT CONTROL OF PITCH ATTITUDE.

NOTE. ELECTRICAL CONTROL DISTURBANCES WERE INTRODUCED AT BEGINNING OF EVALUATION FOR VALIDATION PURPOSES.

NEED FOR SETTLER DISPLAY DURING CONDITIONS REQUIRING SAPID AND THOROUGH CROSS-CHECK, PARTICULARLY IN NOUGH TURBULENCE, THE INITIAL NORMAL ACCELERATION RESPONSE TO ELEVATOR WAS SHARP AND POTENTIALLY DISORIENTATING.

II MISCEL_ANEOUS



	CONFIGURATION 8-2NL WIND(knois) 5 FLIGHT NUMBER 64-2 WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE:	CONFIGURATION WIND (H-1015) FLIGHT NUMBER WIND SHEAR PILOT EXTERNAL TURBULENCE PILOT-RATING
	CHARACTERISTIC RODTS15± .131 .1059	CHARACTERIST C ROOTS
LARCRAFT RESPONSE TO CONTR	ROL INPUTS	
CONTROL SENSITIVITY RESPONSE:	THRUST LEVER	
2 EASE OF MAINTAINING DESIRE	D VELOCITIES	
FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATION	Longitudinos velocity (7.65) Vertical velocity (5.1) VMC IMC IMC VMC IMC VMC IMC OUT OUT OUT IN OUT CUT IN HODERATE GREAT CREAT NODERATE NODERATE \$\frac{1}{2}\$\$ \text{ NODERATE} \text{ NODERATE} \text{ NODERATE} \text{ NODERATE} \text{ TODERATE} \text{ NODERATE} NODE	Congrisiding Vertical velocity (1h)
COMMENTS:	DIFFIGULTY 'UE TO INTERACTION BETWEEN ALRSPSED AND VERTICAL SPEED - AS ATTSPEED BECKRASED RATE OF DESCENT INCREASED, THIS MADE ALRSPEED AND ALTITUDE CONTINUL VERY DIFFICULT.	
3. RESIDUAL OSCILLATORY CHARA	NATERICTIVE	
	AMPLITUDE PERIOD DAMPING	ANPLITUDE PERIOD DAMPING
PITCH HEAVE	ZERO ZERO	
EXCITATION	SOURCE DEGREE	SOURCE DEGREE
CONTROL		
COMMENTS		
4. CHANGE IN THRUST REQUIRED	FOR 20° BANKED TURNS	
CHANGE REQUIRED: EASE OF COMPENSATION:	MODERATE DIFFICULTY	CIFFICULTY
COMMENTS:		LIFFINALIT
	DIFFICULT TO HOLD AIRSPEED IN THRMS AND HENCE THE RATE OF CLIMB CHANGED RATHER RAPIDLY. (SEE SECTION ! ABOVE).	
5. FLIGHT PATH CONTROL		
	Intercept & initial track intermediate track Final track	Intercept & initial track Intermediate Irack Final track
DIFFICULTY	Glide path Local zer Glide path Local zer Glide path Localizer	Glide path Localizer Gi de path Localizer
PRECISION	FAIR FAIR POOR FAIR DOCK FAIR	
MINIMUM ACCEPTABLE BREAKOUT	ALTITUDE	
IF GREATER THAN 200 FEET COMMENTS	500	
COMMENTS	THE STRONG INTERACTION BETWEEN PITCH ATTITUDE, AIRSPEED, AND RATE OF DESCENT CAUSES A HIGH PILOT WORK LOAD,	
6 BREAKOUT AND FLARE		
EASE OF ARRESTING RATE OF DES PRECISION OF ATTAINING TOUCHDO		DIFFICU_TY
COMMENTS:		
7 CONTROL TECHNIQUE		
COMMENTS OF DIFFERENT FROM I 4 S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER		
8 LATERAL DIRECTIONAL CHARA	ACTERISTICS	
EFFECT ON FINAL ASSESSMENT	SMACL	
9 LEAST OBJECTIONABLE FEAT	URES	
IO. MOST OBJECTIONABLE FEATUR	RES	
II. MISCELLANEOUS		



CONFIGURATION 11-1P FLIGHT NUMBER 36-3 PLOT 8 PILOT-RATING 81/2 WIND(knots) CONFIGURATION FLIGHT NUMBER PILOT PILOT-RATING WIND SHEAR EXTERNAL TURBULENCE CHARACTERISTIC ROOTS CHARACTER-STIC ROOTS +.041± .361 -.83 -1.06 I AIRCRAFT RESPONSE TO CONTROL INPUTS ELEVATOR (rod/sec²)/in ZaT = Mag = CONTROL SENSITIVITY: Initial SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE. 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (TAS)

VMC. TMC TMC

OUT QUT IN

SLIGHT SLIGHT SLIGHT
 Verticol velocity (h)

 VMC
 IMC
 IMC

 OUT
 OUT
 IA

 SUIGHT
 SLIGHT
 SLIGHT
 TURBULENCE.
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS NEED TO CLOSELY MONITOR PITCH ATTITODE. 3 RESIDUAL OSCILLATORY CHARACTERISTICS DAMPING AMPL/TUDE AMPLITUDE IDNG (=10 SECS) SOURCE DEGREE SOURCE EXCITATION CONTRO: ELEVATOR EFFECTIVE COMMENTS A TRACE OF HEAVE ONLY MIXED WITH PITCH ATTITUDE. NEED TO TIGHTEN UP ON PITCH ATTITUDE CONTROL. NET A P.1.O. N.T. CIRS A SEMIT-PRIOR PROCESS WHICH SCONTROLLABLE BY THE PILOT. THE OSCILLATION IS ALKAYS PRESENT. 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS SUICHT DIFFICULTY DIFFICULTY COMMENTS SOME THROST REQUIRED, BUT SO PROBLEM. IT IS JUST DIF-FIGURE TO MAINTAIN COOP ATTITUDE REFERENCE IN TURNS. 5 FLIGHT PATH CONTROL Intercept & initial track intermediate track final G de path Localizer Gide path Localizer Glide path Intercept & initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | DIFFICULTY SLIGHT PRECISION. MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEST COMMENTS CLIDE SLOPE WITHIN 1 1/2 DOTS THRESHOLT AND LOCALISER WITHIN 2 DOTS. BETTER RESIDES THEN EXPELTED, ESPECIALLY WITH LOCALISER CONTROL. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT SOSE GIFF CULTY:
PRECISION OF ATTAINING TOUCHDOWN POINT FALRYCOUD NOT SURE MAY SOME CIPPICULTY WAS EXPERIENCED. AIRSPEED WAS O.K., JUST CHOULD NOT BE SIDE SHAT WAS GAING TO HAPPEN AT COUCHDONN. MATE OF DESCRIPT WAS O.K. THROUGH. COMMENTS 7 CONTROL TECHNIQUE COMMENTS IF DEFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

DIFF CITY			
	Γ	 DIFF C	ULTY

WIND (knots)

PERIOD

WIND SHEAR EXTERNAL TURBULENCE

Initial

THRUST LEVER

DAMPING

DEGREE

(11/sec²)/in Final

II MISCELLANEOUS

LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NON-

9 LEAST OBJECTIONABLE FEATURES transmissione restance was the

NO MOST OBJECTIONABLE FEATURES RELATIVEL ARRESTMENT AND AUTO-INCOME LATERTION. PLUM ATTITUDE DEVANDS GLISE ACTIVITION.

NAMES OF BRITISH, INTIGRATED INSTRUMENT DISPLAY TO MINIBULE PURCE ARE DISPLAYED IN MUNICIPAL ACTUREDS.



CONFIGURATION 14-P FLIGHT NUMBER 82-2 PLOT A PILOT-RATING 81/2

+,10 + ,301 -.40 -1,60

CHARACTERISTIC ROOTS

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE LIGHT

CONFIGURATION 14-P FURGHT NUMBER 97-1 PILOT 3 PLOT-RATING 71/2 C

SAT1S FACTORY

CHARACTERISTIC ROOTS

WIND (knots) WIND SHEAR EXTERNAL TURBULENCE

SATISFACTORY SATISFACTORY SATISFACTORY

+.10 ± .301 -.40 -1.60

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELÉ	VATOR	THRU	ST LEVER
Mag = . 30	(rad/sec ²)/in	Zaj-15.0	(11/sec ²)/in
initial	Final	Initial	Fino:
SATISFACTORY	TOO GREAT		SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

TURBULENCE
DIFFICULTY
MAXIMUM UNDESIRED FLUCTUATIONS

Longile	idinal veloc	ity ([AS]	Ver	lical velocity	(fi)
VMC.	IMC	: M C	VMC	IMC	LMIC
OUT	OUT	IN	OUT	QUT	IN
GREAT	PREAT	GREAT	MODERATE	MODERATE	MODERATE
	± 5	knats		± 200	ſpm,

COMMENTS

RESPONSE:

THE LONG PERIOD DIVERGENT PITCH OSCILLATION OVERGODE EVERY-THING ELSE. THE APPROACH TURNED OFT FAIRLY WELL BUT THE WORK LOAD WAS ENOUNCES.

Loi	ngitudina	if veloci	ry (IAS)	Vertico		(A)
VM	C	IMC.	LMC	VMC	IMC	1 M: C
OU	1	OL T	IN	OUT	Out	IN

SSLIGHT SSLIGHT SSLIGHT: MODERATE MODERATE

2 7 Anols fpm

SPEED ERBORS ARE A RESULT OF THE PITCH OSCILLATION, AND SOMETIMES THE INITIAL AND FINAL RESPONSES TO ELEVATOR WREE TOO REAT 17 ON THE WRONG \$108 OF THE PITCH ATTITUDE OSCILLATION.

3. RESIDUAL OSCILLATORY CHARACTERISTICS

PITCH

AMPLITUDE	PERIOD	DAMPING
LARGE	LONG	NEGATIVE
	1	
SOURCE		DEGREE
ELEVATOR, TURBU	LENCE.	FASILY
ELEVATOR		ZF/ECTIVE

EXCITATION CONTROL COMMENTS

THE ALGORACT MOSE WAS IN CONSTANT MOTION AT LOW PREPUBLICY, THE TURBULENCE ADDRESS ENGINEERING TO THE DISCLUSIVE AND ABOUT $1_{\rm CL}^2=-$ TO THE RATING.

AMPL:TJDE	PERIOD	DAMPING
MODERATE	LONG	ZERO
ZERO SMAL	LONG	L
SOURCE UNKNOWN ELZVATOR		DEGREE EASILY EFFECTIVE

ALRORAFT OSCILLATION SERMED TO MAYE A 10 SEC. PERIOD. BIT OCCASIONALLY, DIGHARD TIGHT ATTITUDE OR SPEED TRACKING ON THE APPROACH, THE SREDUENCY COULD BE INCREASED (TO 1 cps) TO RESULT IN A P.1.0.

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

MODERATE	
SLIGHT	D:FFICULTY

COMMENTS

NEGLICIBLE DIFFICULTY

MOST TRACK PITCH ATTITUDE DURING TURNS. PARTICULARLY DIPFICULT BECAUSE OF UNDERLYING PITCH ATTITUDE OSCILLATION.

5. FLIGHT PATH CONTROL

DIFFICULTY: PRECISION

Slide path	Lacalizer	Glide path	Locolizer	Glide path	Localizer
MODERATE	M1000100	MODERATE			
PODERGIE	MODERALE	MODERATE	FODERATE	MODERATE	MODERATE
G00 D	GOOD	goop	coon	0000	G00D

Final track

Intercent & initial track: Intermediate track

MIN:MUM ACCEPTABLE BREAKOUT ALTITUDE

OF GREATER THAN 200 FEET 700

COMMENTS

PRECISION WAS GOOD BECAUSE 1 DID NOT DAME LET AN ERROR SILLS UP. HENGE THE WORK LOAD HAS TEREMOUS. FORTUNATELY TYPER MAS NOT MUCH WIND SHEAS OF-MENISE THERE WOLLD NOT HAVE BEEN THE TO OFFE WITH THE CHANGES.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT	SLIGHT DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT	POOR

WAS REQUIRED.

WOULD TWE MISSED LANDING BY AT LEAST 500 PRET SINCE CAUTION

Intercept & initial track | Intermediate Track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | > SLIGHT MODERATE MCDERATE MODERATE FAIR RIAS

__300

PITCH OSCILLATION DEMANDS CLOSE ATTENTION

SLIGHT DIFFICULTY

PITCH DSCILLATION CAUSES SOME CONCERN BUT CAN BE SUPPRESSED FOR THE PLANE $0..\kappa_{\odot}$

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL BECAUSE BEADING WAS WELL TELD.

SMAL'. THE PITCH, SPEED, MEIGHT TASK RESULTED IN THE NEED 60.2 SOME S-TURNING TO STAY ON THE LOCALISER.

9 LEAST OBJECTIONABLE FEATURES CONTROL WAS NOT COST.

IO. MOST OBJECTIONABLE FEATURES AS PER SECTIONS 2, 3 AND 5 ARMS.

MODERALE TO LARGE AMPLITUDE PLTCH ATTITUDE OSCILLATION. MUST BE CAMEFUL OF OSCILLATION ADDING TO ELEVATOR INFOTS TO CLAFFOL LARGE A RESPONSE. ALSO MIST BE CAREFUL OF DELAYAD RESPONSES IS OSCILLATION SMINGS BACK.

I. MISCELLANEOUS

ELEVATOR CONTROL SUNSITIVITY INCREASED FROM 0.2 TO -0.3



WIND (knots) WIND SHEAR EXTERNAL TURBULENCE CONFIGURATION 14-IN FLIGHT NUMBER 46wiND(knots) WIND SHEAR MODERATE EXTERNAL TURBULENCE MODERATE F_GHT NUMBER PILOT PILOT D PILCT-RATING 7 PILOT-RATING CHARACTERISTIC ROOTS -.15 t .151 -.11 -1.60 CHARACTER STIC ROOTS I AIRCRAFT RESPONSE TO CONTROL INPUTS | THRUST LEVER | Z8T : 15.0 | CH | Final | Introd | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Final | Fi Mae = . 25 E VATOR M_{8E} : (ft/sec²)/in Final CONTROL SENSITIVITY TOO SNAL. RESPONSE -THO SMALL TOO GREAT 2 EASE OF MAINTAINING DESIRED VELOCITIES TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS ±10 fpm YEAV LARCT MOVER LEVER CLANDES TO OBTAIN RELATIONLY SHALL CHANGES IN MERICAL PRINCIPS. ALSO POWER LIVES FAR LAMBE EFFECT ON MICE ATTITUDE. COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE (ERG DAMPING AWPLITUDE HEAVE DEGREE DEGRES EXCITATION CONTROL COMMENTS SPECIO TO MAJE A MEGATIVA STATIC HARLIN SUTTA 1917E (AZID DAVERGENCE IN PITO), BUT MEGAT STABILITY MAS MAITO 167 HIPFOCHE TO SET UP 500 A.P.Y. DESCRIT BOOLDS OF MAILURG LARGE POWER LEVER CHANGES IN OBTAIN SMALL CHARLES IN ZERTICAL VELOCITY. 4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS SMALL NEGLIGIBLE
NOBERATE DIFFICULTY CHANGE REQUIRED EASE OF COMPENSATION DIFFICULTY SOMEWIAT CONFUSING AS 1 COULD MAYE & 15-10 D. FEES BANGED TURN THEOLOGY FOR DEGREES MITTHUT CHARGING THURST BUT ON FILE-OUT THREE KOULD SUDDENLY BI A 200-100 C.T.F. BUSGERT 5 FLIGHT PATH CONTROL intercept 8 initial track Intermediate track Final track Glide path Localizer Glide path Localizer Glide path Localizer Intercept B nitial track - stermed are track Finol track
Slide path Localizer Glide path Localizer
Glide path Localizer DIFFICULTY RUAT NO PRECISION CERY PORT COOP MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET COMMENTS 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT NO. DEFICULTY
PRECISION OF ATTAINING TOUGHDOWN POINT 15.4Y POINT 15.4Y POINT DIFFICULTY COMMENTS TOO SIGN ON GLOBE POT ALL THE MAY AND COULD NOT CATCH UP. SPENSED AS THOUGH I COULD NOT EXCEPD 1000 $\kappa(r,\nu)$ DESCENT REGARDLESS OF POWER SETTING. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM I.A S WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT NOVE 9 LEAST OBJECTIONABLE FEATURES FROM MAINT DAMPING, GEORGES, IT MAY ARE AREN TOO MUCH,

IC. MOST OBJECT ONABLE FEATURES OMNSTANT ATTENTION TO JETPS AND THEM JOHN BID. ESPECIALS IN THE BLOWN FEATURE SEARCH, ADMINISTRATION OF THE FEATURE SEARCH ADMINISTRATION OF THE FORE THE PRINT ADMINISTRATION OF THE PRINT ADMINI

MASICALLY THIS CONFIDENTIAN TROUTERS TOO MEET PRINCIPLES OF ORGAN PRECISION, AND THE HEIGHT RUSHWASE FACTOR PROPERTY.

II MISCELLANEOUS



CONFIGURATION 14-22
FLIGHT NUMBER 50-2
PILOT U PILOT-RATING 9 1/2

W:NDIkootsi

WINDERHOESE CONTROL TO SHEAR NECESSION OF SHEAR NECESSION OF SHEAR TURBULENCE VEGILISTELS

CONFIGURATION FLIGHT NUMBER WINC (knots) WIND SHEAR EXTERNAL TURBULENCE

PILOT-RATING CHARACTERISTIC ROOTS

LAIRCRAFT RESPONSE TO CONTROL INPUTS

2 EASE OF MAINTAINING DESIRED VELOCITIES

CONTROL SENSITIVITY: RESPONSE

ELE	VATOR	THRUST LEVER	
M8E - 35	(rod/sec ²)/in	Z8 T 15. ?	(ft/sec ² l/in
Initial	Final	Init al	Final
TOO GREAT	T72 125 CCT	TOD SMALL	D92 23EAT

<u>Ε_ΕVATOR</u> M_{δE} : (-α. In fig1 F

(-ad/sec²)/m ZsT = THRUST LÉVER (ft/sec²)/ini hilial Final

FLIGHT CONDITION TURBULENCE

MAXIMUM UNDESIRED FLUCTUATIONS

Longitudinal velocity (EAS)
VMC IMC IMC
OUT OUT IN Vertical velocity (h) : M C OJT

COMMENTS

MELATIVE STYTIC MALGIN, AND SERGS III. OPERATING ON BACK OF TOWNS CHOSEL, PARES AS SICUTIONS SUBSTICITATES SYMMETS, (C-0.0 BS LOST DATA OF STABLE TYPE)

3 RESIDUAL OSCILLATORY CHARACTERISTICS

4MP_ITUDE	PERIOD	DAMPING
Labbara		
SOURCE ELEVATOR DE PUST Y	property and	DESREE
EUS AT 15		Sale WATER

DAMPING AMPLIUDE PERIOD SCURCE DEGREE

EXCITATION CONTROL COMMENTS.

COMMENTS

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

SMANT HODIZATY
SOUTHIE DIFFICULTY

ATTERNISH CONTROL DITTOUTH AND CONFUS ENTRY SECTION ASSOCIATION OF STREET ASSOCIATION OF STREET ASSOCIATION ASSOCI

DIFF CULTY

5 FLIGHT PATH CONTROL

DIFFICULTY

		Intermedic		Final	
Glide path	Localizer	Glide poth	Locolizer	Gide path	Local-zer
. SIDET1	\$1,61112	SENDER VIE	MADERATE	SOREAT	GREAT
7514	DOCE	>ains	571.	26 X 130%	9639 2539
				117.11	

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE IF GREATER THAN 200 FEET

APPRIED EXCENSIONS BULLE OF TOO FIGHT (NOTE) AND SO WESTICAL PRINCIPAL STEEL OF TANK MAN, SCHEMEN STORY OF TAKE MAN, SECURITY AND SALES AND ASSESSMENT AT 1880 COST.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT SUITED DIFFICULTY PRECISION OF ATTAINING TOUCHDOWN POINT TELLY PROPERTY.

COMMENTS:

CONTROL OF THE PROPERTY OF THE

7 CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM COMPLET THIS TONG VESSMED TO MENT OF MENTION MENTION. COMPLET THE STORE THE STREET OF THE HEALTH THE STREET OF THE HEALTH THE STREET OF THE STREET OF THE STREET OF THE STREET OF THE STREET OF T

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT MOST

9 LEAST OBJECTIONABLE FEATURES ORIGIN DOPPING SLOPE FOR SECURITION OF THE CONTROL

RO MOST OBJECTIONABLE FEATURES SCHIPTING HITTO HITTORIAN (CONSIDERATION OF PLANTING HITTORIAN OF SPRING LONG SPRING OF HITTORIAN OF SPRING OF HITTORIAN OF SPRING OF HITTORIAN OF SPRING OF HITTORIAN OF SPRING OF HITTORIAN OF SPRING OF HITTORIAN OF SPRING OF

I .₩ SCFLLANEOUS

NOUNCES TO SO SOFT, ACREA TAY OF COMES ASSOCIATION OF THE STANDARD AND ACCOUNT OF THE

266

CIFFICULTY



CONFIGURATION 1-21L FLIGHT NUMBER 113-2 PILOT A PILOT-RATING 6 CHARACTERISTIC ROOTS -, 717 19 1 -, 89 1 .481 I.A:RCRAFT RESPONSE TO CONTROL INPUTS

WIND(knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION L-217, FLIGHT NUMBER 127-2 PILOT B PILOT-RATING 31/2 B

WIND (knots) 5 WIND SHEAR NECT; GIBLE EXTERNAL TURBULENCE NEGLIGIBLE

CONTROL SENSITIVITY: RESPONSE

	ATOR	THRUS	T LEVER
Mac = .25	(rad/sec²)/in	Zar=11.90	(It/sec ²)/in
Initial	Final	Initial	Final
SATISFACTORY	TOO GREAT	SATISFACTORY	SATISFACTORY

2 EASE OF MA:NTAINING DESIRED VELOCITIES

FLIGHT CONDITION:	
TURBULENCE	
DIFFICULTY	
MAXIMUM UNDESIRED	FLUCTUATIONS

- 1	Longit	udinal velaci		Vertical velocity (h)		
	V M.C.	LMC	I M C	VMC	I.M.C.	:MC
	OUT	OUT	IN	OUT	QUT	IN
	SLIGHT	MODERATE	GREAT	SLIGHT	MODEPATE	MODE PATE
45		+12, -L3	knots		± 200	/ pm

Longitudino! velocity (IAS)
VMC IMC (MC
OUT OUT IN Vertical velocity (h)

V.M.C. I.M.C. I.M.C.

OUT OUT IN

VERY "LOOSE" PITCH CONTRO! WHICH TOGETHER WITH TURBULENCE GAVE "MAL PROBLEMS IN AIRSPEED CONTROL.

SMALL COUPLING EFFECT BETWEEN AFRSPEED AND VERTICAL VELOCITY

3 RESIDUAL OSCILLATORY CHARACTERISTICS

COMMENTS

AMPLITUDE	PERIOD	DAMP:NG
25 lats		
SE 30		
SOURCE		DEGREE

PE.RIOD	DAMPING
	DEGREE

EXCITATION CONTROL COMMENTS

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED. EASE OF COMPENSATION

 SMALI.	
 7/3	DIFFICUL

SMALL NEGLIC BYS
NO DIFFICULTY MIST OF CHURSE TOLD ATTREED

COMMENTS

5 FLIGHT PATH CONTROL

DIFFICULTY

Intercept &		Intermedia		Final	trock
Glide path	Local.zer	Giide path	Locoliger	Glide parh	Locolizer
NONE	SLICHT	MODERATE	SLICET	TREAT	MODERATE
6000	EVIS	PO:39	5/10	7897 P109	200.2

MINIMUM ACCEPTABLE BREAKOJT ALT TUDE
IF GREATER THAN 200 FEET 500

COMMENTS:

	initial teack		are track	t inal 1	rack
Glide path	Local 2er	Glide path	Tocol1561	Glide path	Localizer
NONE	NONE	NONE.	NONE	NONE	NONE
ดวาก	G09b	าตดก	ดาดข	dece	conp

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCRINT	NO DIFFICULTY
PRECISION OF ATTAINING TOUCHDOWN POINT	G998

COMMENTS

MIST BE CAPEFUL TO HOLD ALESPEST IN FLAME "OWEVER, TO AVOID COUPLING REFECT OF ALESPEST WITH VERTICAL VEHICLITY.

DIFF CULTY

7 CONTROL TECHNIQUE

COMMENTS IF DEFERENT FROM IAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SYALL.

9 LEAST OBJECTIONABLE FEATURES

TO MOST OBJECTIONABLE FEATURES AS PER SECTION 2 ABOVE

9.3

DOES AMAINE OF ATTITUTE STABILITY. EASY TO CONTROL YET ASSOCIATELY STABLE. FASY TO THIM ATTITUTES AND APPREED. RESPONSE TO TURBLISHED HIM.

MODELAGE COMPLIES E-FEST OF PITCHING MOMENT WITH POWER, NOTICEABLE, BUT NOT DANGEROUS. AMOUNT OF ALESPEED-VERTICAL VELOCITY COMPLINE.

I MISCELL ANEOUS



CONFIGURATION 1-22L FLIGHT NUMBER 112-2 PILOT A

PILOT-RATING

WIND SHEAR MODERATE EXTERNAL TURBULENCE NEGLIGIBLE

CONFIGURATION 1-22L F_IGHT NUMBER 102-2 PILOT B PLOT-RATING JC

WIND (knots) 10
WIND SHEAR SMALL
EXTERNAL TURBULENCE LIGHT

Final Track

- NONE

Intermediate Irack Final Irack
Glide path Lacalizer Glide path Lacalizer

> NON E

> NONE

FALR/COOD FALR/COOD FAIR/GOOD FAIR GOOD FAIR/COOD

CHARACTERISTIC RCOTS -.910 ± .19 1 -.87 ± .481

I AIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEV	ATOR	THRUST	LEVER
M8E 25	(rad/sec ²)/m	Z8⊤÷11.9	(ft/sec ² i/in
Initial	Final	Initial	Final
SAT1SFACTORY	TOO GREAT	SATISFACTURY	

CHARACTERISTIC ROOTS -.010± .19 i -.89± .48i

ELEV	VATOR	THRUST	LEVER
M8E = . 25	(rad/sec2)/in	ZBT=11.9	(ft/sec2)/ir
Initial	Final	Initial	Final
SATISFACTORY	SATISFACTORY	SATIS FACTORY	SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE

MAXIMUM UNDESIRED FLUCTUATIONS

ſ	Longit	dinol veloci	ity (IAS)	Ver	tical velocity	(h)
ı	VMC.	IMC	IMIC	V,M C	LMC	LM: C
1	100	OUT	:N	Out	QUT	:N
ı	NONE	MODERATE	MODERATE	NONE	MODERATE	MODERATE
١		± 1012			± 350	f.pm.

SLIGHT SLIGHT SLIGHT SLIGHT

COMMENTS:

MODERATS INFLUENCE OF AIRSPEID ON NORMAL PORCE MADE IT DIFFICULT TO SETTLE ON EITHEY THE DESIRED AIRSPERD OR VERTICAL SPEED. THE ATTITUDE WOULD NOT SETTLE DOWN TO HOLD AN AIRSPEED, SECRED LITTLE CORRELATION BETWEEN PUBER LEYER POSITION AND MATE OF DISCENT.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXC:TATION CONTROL COMMENTS

COMMENTS

AMPLITUDE	PER	OD	DAMPING
ZERO			
ZERO)			
SOURCE			DEGREE

AMPLITUDE PERIOD DAMP NG SCURCE DEGRÉÉ

4. CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED : EASE OF COMPENSATION

 SMAL.	
NO	DIFFICULTY

NEGI, IGIBLE SMALL NO/SLIGHT DIFFICULTY

5 FLIGHT PATH CONTROL

DIFFICULTY PRECISION

Intercept 8		Intermedi			track
Glide path	_ocalizer	Glide poth	Localizer	Glide pot	Locolizer
S L I G.IT	suron	MODERATE	MODERATE	SLUGAT	GREAT
FA13	_ MIR	POOR	FALR	POOR	VERY POOK

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500

COMMENTS

WIND SHEAR GORE IN SUBDINES AROUND FOR SEXT, A ASPRED WHYTHIGH AND KILLED THE DESCRIPT SATE DRACK THE INTERPROLATE PART. WIND DIRECTION 500 20 at altitrop and 50.3° at 4000Mb.

30)14

>NONE

Intercept 8 initial track Glide path | Localizer

> NONE

TENDERCY TO PUSH NOSE DOWN IF HIGH ON GLIDE SLOPE.

> NONE

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT 95 PRECISION OF ATTAINING TOUCHDOWN POINT (4857) DIFFICULTY.

SILIGHT NO DIFFICULTY

WAS SUIGHTLY RECH AT BREAKOUT,

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT ANAL

NOME

9 LEAST OBJECTIONABLE FEATURES

MOT RESPONSIVE TO TURBULENCE UPSETS.

IO VOST OBJECTIONABLE FEATURES

NO ACTITUDE STARILITY BUT WAS NOT RAD, PITCHING MORENT DUZ TO POWER CHANGES NOTICEASE BUT NOT TWO MUCH OF A PROBLEM ON APPROACH AS THRUST LEWIS NOT TORN TOO MUCH.

as a contract of the first of the ample bags,

SATISFACTORY DIEGHT CONTROL.
MODEL BATTER MAINLY ON BASIS OF PITCH INSTABILITY.



WIND(knots) CALM
WIND SHEAR NECLIGIBLE
EXTERNAL TURBULENCE NECLIGIBLE CONFIGURATION R1-21I, WIND(knots)
FLIGHT NUMBER 89-1 WIND SHEAR
PILOT A EXTERNAL T
PILOT-RATING 5 CONFIGURATION R1-21L FLIGHT NUMBER 190-2 WIND SHEAR SMALL EXTERNAL TURBULENCE MEGLICIBLE PILOT B PILOT-RATING 40 CHARACTERISTIC 400"S -.09 -.31 -1.04 1.031 AIRCRAFT RESPONSE TO CONTROL INPUTS CONTROL SENSITIVITY SATISFACTORY TOU GREAT SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY RESPONSE 2 EASE OF MAINTAINING DESIRED VELOCITIES Long tudinal velocity (IAS)
VMC IMC IMC
OUT OUT IN Congitudinal velocity (TAS)

VMC TMC TMC TMC

OUT OUT IN

SLIGHT MODERATS GREAT Vertical velocity (F VMC JMC OUT OUT TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS SLIGHT > SLIGHT > SLIGHT NON THE MOSE MOULD NOT STAY POT. IN FACT IT SERMED TO RESPOND 45 THOSEON IT WERE OBEYING ATTETIBE COMMANDS AT FIRST BUT THEN THE ATTETUTE MOULD CONTINUE AFTER HAVING STOWED OR EVEN STOPPED FOR A CONSTANT UNDER. DISFIGULTY DUE TO TENDENCY TO PUT NOSE DOWN IF HIGH ON 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE SMALL AMPLITUDE COIRSA DAMPING SOURCE DEGREE EXCITATION MODERATELY EFFECTIVE ELEVATOR COMMENTS THE OSCILLATION DID NOT ACTUALLY PRODUCE A MOTION IN OPPOSITE DIRECTION BUT MERSLY A HESITATION THAT WAS KISLEADING. 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION MODERATE. D-FF-CULTY DIFFICULTY COMMENTS 5 FLIGHT PATH CONTROL nitia track Intermediate track Finat Irack
Localizer Glide path Localizer Glide path Localizer Intercept & nitial track | Intermediate track Glide path | Local zer | Glide path | Localizer Glide path Lacalizer DIFF!CULTY STUCHT SLICHT SLIGHT SLIGHT \$LIGHT SLICHT SLIGHT PRECISION 0000 FAIR FAIR M:NIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEET 500 300 COMMENTS BROKE CUT AT 300 FEET BECAUSE VERTICAL VELOCITY WAS 1000 F.2.M. TOO UNCOMPORTABLE NEAR GROUND. VERTICAL VELOCITY INCREASED ONCE TO 1200 F.F.M. MOMENTARILY. AS PER SECTION 2 ABOVE. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN PCINT SCICHT DIFF:CULTY COMMENTS HICHER THAN USUAL GROUND SPEED (60 KNOTS) REDUCES TIME ON APPROACH. 7 CONTROL TECHNIQUE COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER 8 LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SMALL. NONE 9 LEAST OBJECTIONABLE FEATURES ATTITUE STABILITY SATISFACTORY. IO MOS" OBJECTIONABLE FEATURES AS PER SECTION 1 ABOVE. MANUER LEVER SENSITIVITY STILL A LITTLE HIGH FOR POWER CHANGES ON GLIDE FATE. (AFTER BEING REDUCED 151) I: MISCELLANEOUS IF RATE D: DESCENT GETS UP D) 1000 F.P.M. NEAR GROUND IT FEELS UNCOMPORTABLE ESPECIALLY IF HEAVE RESPONSE IS SION, AND IF THERE IS ANY AIRSPEED-VERTIGAL VELOCITY COUPLING.



CONFIGURATION R1-22L WINDERNOTS 10
FLIGHT NUMBER 103-3 WIND SHEAR SMALL
PILOT-RATING 3

WIND SHEAR NBGLIGIBLE
EXTERNAL TURBULENCE NBGLIGIBLE

CONFIGURATION R1-22% WIND Is not s)
FLIGHT NUMBER 91-3 WIND SHEAR
PILOT-RATING 8 V/2 C
WIND SHEAR
EXTERNAL TURBULENCE

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY

ELEVATOR		THRUST LEVER	
M&E : . 35	(rad/sec2)/in	Z8T=15.0	(Ir/sec²)∕in
Initial	Fina!	Initial	Finoi
SAT1S FACTORY	SATIS FACTORY	SATISFACTORY	SATISFACTORY

Mag = .35 Mag = .35 ELEVATOR THRUST LEVER
Mag = .35 (rod/sec2)/in Zat = 13.0 (rif/sec2)/in
Initial Final
SATISFACTORY SATISFACTORY SATISFACTORY

2 EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE: DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS

Longilu	dinal veloci	ty (IAS)	Ver	lical velocity	(h)
. V.M.C.	1MC	TMC	VWC	IMC	IMC
OUT	out	IN	Out	OUT.	1N
SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLIGHT	SLICHT
	-13, +5	knats		± 500	f.p.m

Vertical velocity (f)
VMC IMC
OUT OUT
NONE > NONE > N

COMMENTS

DIFFICULTY PROBABLY MOSTLY DUE TO LACK OF RECENT PRACTICE. ATTITUDE CONTROL WAS A BIT "SOFT". A NEW STEADY-STATE ATTITUDE DID NOT RESULT FROM A STEADY-STATE ELEVATOR POSITION.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

EXCITATION CON*ROL COMMENTS

COMMENTS

PERIOD DAMPING	AMPLITUDE
	ZERO ZERO
RCE DEGREE	SOURCE
RCE DEGREE	SDURCE

AMPLITUDE	PERIOD	DAMPING
ZERO		1
2.630		
SOURCE		DEGREE
ELEVATOR		HARDLY

CHANGE REQUIRED EASE OF COMPENSATION

 NEGLIGIBLE	
 NO.	DIFFICULTY

4 CHANGE IN "HRUST REQUIRED FOR 20° BANKED TURNS

SMAL4 SLIGHT DIFFICULTY

NOT PRECISELY SURE OF WHAT THE HEIGHT CONTROL CHARACTER-

5 FLIGHT PATH CONTROL

DIFFICULTY.	
PRECISION	

		rtermediate track		Final track	
Gl-de path	Local zer	Gide path	-oco ze-	Glide path	Lacalizer
MODERATE	MODERATE	SLIGHT	SLIGHT	<u>эгтсят</u>	MODERATE
9003	PCOR	FAIR	FAIR	FA1:	POOR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE F GREATER THAN 200 FEE)

THE INITIAL BATE OF DESCENT RESCRING FROM THE POWER DEGREES AT GLID! PATH INTERCEPTION WAS SURPRISINGLY HIGH AT 1500 F,PAL, ABB WIND SHEAR CAURED LOCALIZER PROBLEMS. MUST OF THIS COULD BE DUE TO LONG LAY-OFF PERIOD.

	initial track			Final	rack
Gide path	Localizer	Glide poth	Localizer	Glide path	Localizer
NONE	NONE	NONE	NONE	SLIGHT	SULCHT
G30 D	FA1R	6000	FAIR	300n	PAIR

0.4.

DIFFICULTIES FUE TO S-TURNS TO STAY ON THE LOCALIZER AND WIND ESFECTS ON THE CLIDE PATH.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT PRECISION OF ATTAINING TOUCHDOWN POINT

[NC	 DIFF	CULTY
Γ,	 3000	 	

COMMENTS

CIFF CULTY MODERATE

LOST 15 KMOTS AFTER BREAKOUT, NOT SURE WHY. COULD HAVE BEEN UNCONSCIOUS FLARE OR WIND EFFECTS ETC.

7 CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT SMALL

NONE EXCEPT FOR S-TURNS TO STAY ON LOCALIZER.

9 JEAST OBJECTIONABLE FEATURES

O MOST OBJECT CHARLE FEATURES SOME PROBLEMS OF MACROADING PRICE APTITUDE.

DUT ACCEPTABLE.

MERGAT CONTROL TAKES SOME CETTING USED TO BUT NOT BAD.

II V SCEULANEOUS



WIND(knots) 5
WIND SHEAR NEGLIGIBLE
EXTERNAL TURBULENCE NEGLIGIBLE CONFIGURATION 2-2LL FLIGHT NUMBER 115-1 PILOT A PILOT-RATING 8 CONFIGURATION 2-21L FLIGHT NUMBER 124-1 PILO* B PILOT-RATING 7D WIND (knots) WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE HEGLIGIBLE CHARACTERISTIC ROOTS -.014# .1451 -.50 -1.26 SAIRCRAFT RESPONSE TO CONTROL INPUTS Mag: 0.25 (rad/sec²)/in ZaT=11.9 (fl/sec²/in Initial Final ELEVATOR THRUST LEVER
WaE = 0.25 (rad/sec2)/in ZaT=11.9 (ft/ (ff/sec²)/in CONTROL SENSITIVITY: Initial Final Initial Final
SATISFACTORY TOO GREAT SATISFACTORY SATISFACTORY RESPONSE: 2 EASE OF MAINTAINING DESIRED VELOCITIES Longitudinal velocity (IAS)

VM.C. IMC IMC Vertice: velocity (h) I M C VMC TURBULENCE DIFFICULTY MAXIMUM UNDESIRED FLUCTUATIONS OUT OUT
SLIGHT GREAT LARGE PITCHING NUMERT WITH POWER BUT IT PRESENTED NO PROBLEM.
JUST MEED TO RETRIM IN PITCH WHEN MAKING POWER CHANCES,
SOME COUPLING BETWEEN AIRSPEED AND VERTICAL VELOCITY. PITCH CONTROL "MOSE" AND THE ATTITUDE DISTURBED BY THE TURBULENCE. AIRSPEED EFFECT ON THE POWER REQUIRED WAS OUTE A PROBLEM SSPECIALLY ON L.M.C. APPROACH. 3 RESIDUAL OSCILLATORY CHARACTERISTICS PERIOD AMP_ITUDE AMPLITUDE DAMPING DAMPING PERIOD ZERO HEAVE ZERO SOURCE DEGREE DEGREE SOURCE EXCITATION COMMENTS SIGN PITCH DIVERGENCE. 4 CHANGE N THRUST REQUIRED FOR 20° BANKED TURNS CHANGE REQUIRED EASE OF COMPENSATION MODE BATE DIFFICULTY D-FFICULTY COMMEN'S $\sigma, \kappa,$ as long as the ausspeed was not allowed to wander, but ween it bropped to 35 knyrs a sign; loant fower change THERE WOULD BE A NEED TO MONETOR PITCH AND ALMSPEED IN THE TURN, ESPECIALLY IF USING POWER, NO PROBLEM ENCOUNT-ERED HOWEVER, NAS REDUIRED. 5 FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Final track |
Glide cath | Coca izer | Glide path | Cocaizer | Glide path | Cocaizer | Intercept & initial trac Gide path Localizer l Intermediate track Final track
Glide path Localizer Glide path Localizer DIFFICULTY: SUI JUT SLIGHT MODERATE MODERATE MODERATE SLIGHT PRECISION Poor GCOG MIN MUM ACCEPTABLE BREAKOUT IF GREATER THAN 200 FEET 11. K. THE BREASOUT WAS O.K. BECAUSE THE POSITIONING TURNED OUT WELL, BUT POYER AD UNSTHEMYS USED TO CONTROL SATE OF DESCENT, PUPCE ATTENTION TO MAINTAIN AND RETRIM PITCH ATTITUDE AND ALBEFRED ON THE APPROACH. COMMENTS AS PER SECTION : ABOVE. 6 BREAKOUT AND FLARE EASE OF ARRESTING RATE OF DESCENT MODERATE DIFF CULTY
PRECISION OF ATTAINING TOUCHCOWN POINT SULCTT DIFFICULTY COMMENTS -INSTEAD OF LEVELLING, THE $\sim 5.99^{\circ}$ T STARTED TO CLIMP AGA N AFTER DESIRED TOUGHDAIN, ATTENTION NEEDED TO GOLD ACHSPEED AND PITCH ATTITUDE WHILE FLYING DUE TO PITCHING MOMENTS CAUSED BY THRUST CHANCES. 7 CONTACT TECHNIQUE COMMENTS IF DIFFERENT FROM (A S W TH ELEVATOR AND VERTICAL SPEED WITH THRUST LEVER B LATERAL DIRECTIONAL CHARACTERISTICS EFFECT ON FINAL ASSESSMENT SKAUL NINE

9 LEAST OBJECTIONABLE FEATURES

IO MOST CBUECTIONABLE FEATURES

II MISCELLANEOUS

CANCER TEAN NECMAL (FO DESIRABLE) PLICHING MOMENTS WIT! THEST CHANGES, PLICE DIVENGENCE.

SENSIFICATIVE BETTO TO TURBULENCE.
NOTICEABLE, BUT NOT BOT PROCHE ALSPEED-VERTICAL VELOCITY

CO TELLING,

CONTROL ACTIVITY ON APPROACH WAS SCREEKINGLY LOW.

APPROACH WAS EASY TO MMY EXCEPT THAT SOME LOCALIZER ST
THIS PERSONNEL BELOW SOC PERT DUE TO DISPLAY/APPROACH
ALT DEVICENCENS.

271



CONFIGURATION 2-22L FLIGHT NUMBER 79-3 PILOT A PILOT-RATING 7

wiND[knots] 5-10 WIND SHEAR SMALL EXTERNAL TURBULENCE MODERATE

CONFIGURATION 2-22L FLIGHT NUMBER 85-2 PILOT 8 PILOT-RATING 8D

CHARACTERISTIC ROOTS -.014# .1454 -.50 -1,26

LAIRCRAFT RESPONSE TO CONTROL INPUTS

CONTROL SENSITIVITY:

2.EASE OF MAINTAINING DESIRED VELOCITIES

FLIGHT CONDITION TURBULENCE DIFFICULTY MAX: MUM UNDESIRED FLUCTUATIONS

| Longitudinal velocity (TAS) | VMC | IMC | I.M.C | OUT | IN | OUT | IN | SLIGHT | MIDERATE | VRS.VT | IO | Knots Vertical velocity (fi) VMC IMC IMC
OUT OUT IN
SLIGHT MODERATE CREAT

COMMENTS:

PITCH ATTITUDE CONTROL WAS MUCH THO EFFECTIVE AND REGALAED CONSTANT ATTENTION. THERE SEEMED TO BE SOME EFFECT OF ATRISPED ON VERTICAL SPEED TO PRODUCE A DESCENT AS AIR-SPEED INCREASED AND VICE MERSA.

Initial Final (nitial Final SATISFACTORY SATISFACTORY SATISFACTORY SATISFACTORY

WIND SHEAR NEGLIGIBLE EXTERNAL TURBULENCE NEGLIGIBLE

Vertical velocity (b) VMC I.MC I.OUT I M.C SLIGHT

CARGE SPEED-VERTICAL VELOCITY COUPLING CAUSING VERTICAL VELOCITY FLUCTATIONS DUE TO AIRSPEED CHANGES.

3 RESIDUAL OSCILLATORY CHARACTERISTICS

AMPLITUDE	PERIOD	DAMPING
ZERO		
ZERG		

SCURCE DEGREE

EXCITATION CONTROL COMMENTS

AMPLITUDE	PERIOD	DAMPING
1930		
4ERC	L	
SOURCE		CEGREE

4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS

CHANGE REQUIRED EASE OF COMPENSATION

DIFFICULTY

COMMENTS:

5 FLIGHT PATH CONTROL

DIFFICULTY:

PRECISION

		Intermedi		Final	
Glide path	Localizer	Glide poth	Localizer	Glide poth	Localizer
SLIGHT	SLIGHT	MODE RATE	SLIGHT	MODERATE	SLUGIT
FAIR	FAIR	POOR	FALR	P00E	FALR

MINIMUM ACCEPTABLE BREAKOUT ALTITUDE
IF GREATER THAN 200 FEE! 500

DURING THE INTERMEDIATE START THE ALASPEED HOSEASED TO TO TO STATE AND THE MATE OF DESCENT DECIDANCE CONSTRUCTION, ONLY DRIES USE OF THE POWER DIVER MET THE ALAGRAP ON THE BLUE PATT.

6 BREAKOUT AND FLARE

EASE OF ARRESTING RATE OF DESCENT S.I.G.IT DIFFICULTY
PRECISION OF ATTA NING TOUCHDOWN POINT (7417)

7. CONTROL TECHNIQUE

COMMENTS IF DIFFERENT FROM LAIS WITH ELEVATOR AND VERTICAL SPEED WITH THRUST

8 LATERAL DIRECTIONAL CHARACTERISTICS

EFFECT ON FINAL ASSESSMENT

9 LEAST OBJECTIONABLE FEATURES

IO. MOST CBJECTIONABLE FEATURES

DIFFICULTY SLIGHT MAINTAINING AIRSPEPD IS MOST IMPORTANT.

400

NOT ENGUGE "MEADING CROSS-CHECKS RESULTING IN A LOT OF S-TIZNING TO STAY ON "OGALIZER. VERTICAL VELOCITY INTER-ACTION WITH EVER SMALD AIRSPEED CHANGES MADE IT DIFFICULT TO STAY ON CLIDE PATH, AND INVOLVED THE USE OF POWER TO TRY TO COMPENSATE.

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COMMENTS 3 RESIDUAL OSCILLATORY CHARACTERISTICS AMPLITUDE 'E30 DAMPING 2ER0 DEGREE DEGREE COMMENTS 4 CHANGE IN THRUST REQUIRED FOR 20° BANKED TURNS NEGLIGIBLE OFFICULTY CHANGE REQUIRED: EASE OF COMPENSATION DIFFICULTY COMMENTS: 5 FLIGHT PATH CONTROL Intercept & initial track | Intermediate track | Final track | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Localizer | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide path | Glide intercept 8 initial track | Intermediate track | Final track | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Localizer | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gide path | Gid DIFF CULTY \$1.16 ·T ME DERATE MODERATE MODERATE IMODERATO PMR MINIMUM ACCEPTABLE BREAKOUT A_TITUDE IF GREATER 1 MAN 2005 EET 800 500 COMMENTS AS REC SECTION ! 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APPENDIX A: EQUATIONS GOVERNING SIMULATOR AND MODEL MOTION

In this section, the simulator and model equations of motion are considered. The autopilot loop closures required to ensure that the simulator motion corresponded to that demanded by the model equations of motion are then described.

A.1 BRIEF DESCRIPTION OF SIMULATOR

The simulator utilized (based on the Bell 47G-3Bl helicopter) is characterized by four independent force and moment motivators: the main rotor collective and longitudinal and lateral cyclic controls, and the tail rotor collective control. These motivators are used to control the normal force and the pitching, rolling and yawing moments of the simulator respectively. The fore-and-aft and transverse forces of the simulator cannot be controlled independently and the motions along these axes are governed by the inherent characteristics of the simulator as modified by crosscoupling terms resulting from the closure of the four controlled loops.

A.1.1. Equations Governing Longitudinal Motion of the Simulator

To implement a linear-velocity sensing system for the simulator, it was assumed that the latter's motion could be adequately represented by the following equations of motion:

$$\dot{\mathbf{U}}_{H} = \mathbf{A}_{\mathbf{x}_{H}} - \mathbf{g} \ \mathbf{\Theta}_{H} - \mathbf{Q}_{H} \mathbf{W}_{MIX} + \mathbf{R}_{H} \mathbf{V}_{MIX}$$
 Al

$$\dot{\mathbf{v}}_{H} = \mathbf{A}_{\mathbf{y}_{H}} + \mathbf{g} \left(1 - \frac{\Theta_{H}^{2}}{2} \right) \Phi_{H} - \mathbf{R}_{H} \mathbf{U}_{MIX} + \mathbf{P}_{H} \mathbf{W}_{MIX}$$
 A2

$$\dot{W}_{H} = A_{z_{H}} + g \left[1 - \frac{\Theta_{H}^{2}}{2} - \frac{\Phi_{H}^{2}}{2} \right] + Q_{H} U_{MIX} - P_{H} V_{MIX} A3$$

The suffix MIX indicates that the velocity is the composite of high frequency inertial data and low frequency air-mass data.

Furthermore, in order that the longitudinal velocity response of the simulator to disturbances could be predicted, the longitudinal acceleration was, for small perturbations about the operating point, divided into a component due to the main rotor and another arising from the remaining fuselage X-force and pitching moment derivatives, that is,

$$a_{x_H} = a_{x_R} + a_{x_F} = - K_3 \dot{q}_H + K_F F$$
, A4

where

$$K_3 = \frac{B}{mh_R} = 3.0$$

and

$$X_F = K_3 M_f + X_f$$

For small perturbations, equation Al could thus be rewritten as

$$\dot{\mathbf{u}}_{H} = - K_{3}\dot{\mathbf{q}}_{H} - W_{o}\mathbf{q}_{H} - g\theta_{H} - Q_{o}W_{H} + R_{o}V_{H} + a_{x_{F}}$$
 A5

The form of this equation differs from the more general form of Equation Al through the introduction of a second-order lead term in the longitudinal velocity response to pitching motions which accounts for the closed-loop variability, and

thereby allows the remaining component of the longitudinal acceleration to be described by the more conventional constant coefficient X-force derivatives arising, for this simulator, entirely from the fuselage.

The second-order lead term results in a notch filter in longitudinal responses to pitching motions at a natural frequency given, to good approximation for the prevailing levels of X-force derivatives, by

$$\omega \simeq \sqrt{\frac{g}{K_3}} = 3.3 \text{ rad/sec}$$

The bandwidth of the filter is established principally by

$$\zeta = \frac{W_o}{2K_3\omega} = .05 W_o$$

A.1.2 Evaluation of the Equivalent Open-Loop X-Force Derivatives

Analysis of flight data, utilizing an analogue matching technique, was undertaken to obtain the equivalent open loop X-force derivatives. The identity matched was

$$a_{x_H} - x_F \cdot F = - \kappa_3 \dot{q}_H$$

Good fidelity was obtained with the following values for K_3 and X-force derivatives about the flight-operating condition of U = 60 knots, \dot{h} = 0.

$$K_3 = 3.0$$

$$x_{u_{F}} = -.04$$

$$X_{W_{F}} = -.03$$

$$X_{\mathbf{w}_{\mathbf{F}}} = 0$$

$$X_{\mathbf{q}_{\mathbf{F}}} = -.022$$

$$X_{\mathbf{\theta}_{\mathbf{F}}} = 0$$

$$X_{\mathbf{\delta}\mathbf{e}_{\mathbf{F}}} = 0$$

$$X_{\mathbf{\delta}\mathbf{e}_{\mathbf{F}}} = 0$$

The negligible values obtained for the equivalent force derivatives X_{Ψ_F} , X_{θ_F} , $X_{\delta e_F}$, $X_{\delta e_F}$, were achieved through the removal of the horizontal stabilizer of the simulator, an action which markedly reduced the interaction between the simulator's control displacements and the fuselage forces and moments.

A.2 EQUATIONS GOVERNING THE LONGITUDINAL MOTION OF THE MODEL

The equations utilized in the mathematical model to be followed by the autopilot loops were:

Z-Force

$$\dot{\mathbf{w}}_{M} = \mathbf{U}_{O}\mathbf{q}_{M} + \mathbf{a}_{\mathbf{Z}_{M}} + \mathbf{g}\left[1 - \frac{\Theta_{H}^{2}}{2} - \frac{\Phi_{H}^{2}}{2}\right] - \mathbf{P}_{H}\mathbf{V}_{MIX}$$
 A6

Available on the simulator was the quantity \dot{W}_{H} of Equation A3 calculated from inertial and mixed inertial - air data velocity. Equation A6 was thus rewritten as

$$\dot{w}_{M} = \dot{W}_{H} + (a_{z_{M}} - A_{z_{H}}) + U_{o}q_{M} - U_{MIX}Q_{H}$$
 . A7

For perturbations about the operating point Equation A7 was further simplified to:

$$\dot{w}_{M} = \dot{W}_{H} + (a_{z_{M}} - A_{z_{H}}) + U_{o}(q_{M} - Q_{H})$$
 A8

This was the form utilized in the calculation of the model equations of motion. The error term $U_{0}(q_{M}-Q_{H})$ was, however, not passed to the heave autopilot for reasons discussed in Section A.3.2.

The normal velocity obtained from Equation A8 was that for the centre of gravity. The simulation of a pilot's station ahead of the centre of gravity was achieved in the longitudinal plane by a direct feed forward term to the heave autopilot loop.

The commanded normal acceleration was composed of

$$a_{z_{M}} = z_{u_{M}} u_{H} + z_{w_{M}} w_{M} + z_{q_{M}} q_{M} + z_{\theta_{M}} \theta_{M}$$

$$+ z_{\delta e_{M}} \delta e_{M} + z_{\delta T_{M}} \delta_{T_{M}} + z_{u_{M}} u_{g_{M}} + z_{w_{M}} w_{g_{M}}$$

A9

M-Moment

$$\dot{\mathbf{q}}_{\mathbf{M}} = \frac{\Delta \mathbf{M}}{\mathbf{R}}$$
 Alo

All other inertial terms were considered to be negligible in this moment equation.

The angular acceleration was composed of:

$$\dot{q}_{M} = M_{u_{M}} u_{H} + M_{w_{M}} \dot{w}_{M} + M_{w_{M}} w_{M} + M_{q_{M}} q_{M} + M_{\theta_{M}} \theta_{M}$$

$$+ M_{\delta e_{M}} \delta e_{M} + M_{\delta T_{M}} \delta T_{M} + M_{u_{M}} u_{g_{M}} + M_{w_{M}} w_{g_{M}}$$

All

The commanded pitch attitude was obtained from the expression,

$$\theta_{M} = \theta_{H} + \int (q_{M} - q_{H})dt$$
.

This compares with the exact expression

$$\theta_{M} = \theta_{H} + \left[(q_{M} - q_{H}) \cos \phi \right] dt$$
 . Al2

The error $\int (q_M - q_H)dt$ was forced to be small by the autopilot

through the use of a low frequency lag-lead pair on this signal, and the error which resulted from the assumption

$$\int (q_{M}-q_{H})\cos\phi dt = \int (q_{M}-q_{H})dt$$

was considered to be negligible in view of the quality of model following achieved at low frequencies.

X-Force

No independent means is available for controlling the X-forces but model calculations to obtain modal parameters utilized the identity

$$\dot{\mathbf{u}}_{M} = - K_{3} \dot{\mathbf{q}}_{M} - W_{o} \mathbf{q}_{M} - g \theta_{M} + a_{\mathbf{x}_{F_{M}}} - Q_{o} w_{H} + R_{o} v_{H}$$

$$= \dot{\mathbf{u}}_{H} + K_{3} (\dot{\mathbf{q}}_{H} - \dot{\mathbf{q}}_{M}) + W_{o} (\mathbf{q}_{H} - \mathbf{q}_{M}) + g(\theta_{H} - \theta_{M})$$

$$+ (a_{\mathbf{x}_{F_{M}}} - a_{\mathbf{x}_{F_{M}}}) . \qquad A14$$

Providing that the pitch-loop model-following is of sufficient fidelity in the frequency range of interest for the control of longitudinal perturbations, and that the equivalent fuselage X-force derivatives are accurately estimated, one may write

$$\dot{\mathbf{u}}_{\mathbf{M}} \simeq \dot{\mathbf{u}}_{\mathbf{H}}$$
 . A15

Equation Al5 is that which was assumed to govern the longitudinal velocity of the simulator, and the feedback consequently used in the model equations of motion during the simulations was $\mathbf{u}_{\mathbf{H}}$.

Kinematic Relationship

The relationship utilized to transform the normal, body axes system velocity to that in an earth fixed system is

$$\dot{\mathbf{h}} = -\mathbf{w} + \mathbf{U}_{0}\theta + \theta_{0}\mathbf{u} . \tag{A16}$$

The Collected Model Equations of Motion

The small-perturbation, longitudinal equations of motion, used to calculate the model characteristics for the conditions of zero disturbances in the lateral-directional degrees of freedom and $P_0=Q_0=R_0=\Phi_0=V_0=0$, are collected below.

$$\begin{bmatrix} s - X_{u_{F}} & - X_{w_{F}} & K_{3}s^{2} + (W_{o} - X_{q_{F}})s + g \\ - Z_{u} & (1 - Z_{w}^{*})s - Z_{w} & - (U_{o} + Z_{q})s + g\theta_{o} - Z_{\theta} \\ - M_{u} & - M_{w}^{*}s - M_{w} & s^{2} - M_{q}s - M_{\theta} \end{bmatrix} \begin{bmatrix} u \\ w \\ \theta \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 & 0 \\ Z_{\delta e} & Z_{\delta T} & Z_{u} & Z_{w} \\ M_{\delta e} & M_{\delta T} & M_{u} & M_{w} \end{bmatrix} \begin{bmatrix} \delta e \\ \delta T \\ u_{g} \\ w_{g} \end{bmatrix}$$
Al7



A.3 AUTOPILOT LOOP CLOSURES FOR LONGITUDINAL MODES OF MOTION

The major effort expended on the autopilot loop closures was aimed at improving the low frequency fidelity without compromising the crossover frequency.

A.3.1 Pitch Loop

The removal of the horizontal stabilizer and the desire to achieve better low frequency fidelity required changes to the inner-loop control law.

The pitch loop was closed with longitudinal cyclic on an error signal of the form, F_q (s). $(q_M - q_H) + \frac{Ks}{s - Z_{W_H}} \delta_{c_H}$.

The high-passed crosscoupling lead term from collective to cyclic, which was small, was introduced to allow increased loop gains without instability occurring when large simultaneous collective and cyclic movements were demanded during the control of some configurations.

The resulting loop exhibited frequency response characteristics which could be well represented in the frequency range of interest to the pilot by

$$\frac{q_H}{q_M}$$
 (s) = $\frac{36}{s^2 + 2(.5)(6)s + 6^2}$

The loop remained insensitive to disturbances originating from the other controls and external gusts.

A.3.2 Heave Loop

When heave-loop closure had been employed on the simulator in the past, the primary error signal had been



generated from F_{a_z} (s)($a_{z_M} - a_{z_H}$). This had led to low

frequency drift problems. To avoid these, the error signal employed in this investigation to drive the main rotor collective was changed to

$$F_{w}(s) \left[(w_{M_{cg}} - w_{H_{cg}}) - \frac{U_{o}(q_{M} - q_{H})}{s - Z_{w_{M}}} - LQ_{H} \right].$$

The pitch loop error included in the calculation of the commanded normal velocity in Equation A8 was removed to prevent the heave loop from attempting to respond to pitch loop errors. The term LQ_H was added to allow the simulation of a pilot's station ahead of the centre of gravity in the longitudinal plane.

The resulting heave loop exhibited frequency response characteristics which could be well represented in the frequency range of interest to the pilot by

$$\frac{W_H}{W_M}$$
 (s) = $\frac{100}{s^2 + 2(.5)10 + 10^2}$

The drift problem disappeared with the new form of loop closure.

Probably the major limitation imposed on the heave loop arose from the demands on engine power required to maintain constant main rotor r.p.m. during manoeuvres requiring large normal accelerations.

The strategy employed to alleviate this problem was to climb to circuit height at the best lift to drag ratio



under visual conditions without the introduction of artificial turbulence. Only when sufficient power reserves were available, during level flight and descent, were the more challenging tasks of flying under instrument conditions in the presence of artificial turbulence imposed on the pilot.

Although only having indirect control over the power output of the engine, the evaluation pilots felt the need for an indication of engine manifold pressure when operating near power limits. To prevent this indication from becoming an additional motion cue in the normal plane, only the final 18% of available power was displayed to the pilot after Flight No. 28. For the task being evaluated, the mean manifold pressures during climb, cruise and descent were 85-88%, 76-79% and 48-55% respectively. The evaluation pilot was thus able to perceive his mean manifold pressure only during the climb.

When a tight loop is closed along the Z-axis on normal velocity, $\mathbf{w}_{\text{H}_{\text{C.G.}}}$, the damping in heave, - $\mathbf{Z}_{\mathbf{w}}$, is augmented significantly. If the normal velocity feedback information is obtained directly from an angle of attack vane, the heave response to gusts becomes accentuated. The low frequency data in this experiment was derived from an angle of attack vane but, to ensure that the effect of external turbulence was attenuated, the vane data were low-passed by a second-order filter with a crossover frequency of 0.5 rad/sec. The required complementary, high-frequency information



was provided by an on-board, six degree of freedom, mixed inertial and air-data calculation. The mixed normal velocity information thereby obtained was characterized by a high signal-to-noise ratio which allowed high loop gains without structural modes being excited. In heave, the simulator, in general, responded only to those external gusts characterizing convective instabilities with long wave lengths and, to minimize the effects of this class of disturbance, flying was restricted to conditions notable for their absence.



APPENDIX B: PILOT'S CONTROL FEEL SYSTEM

The simulator has, since 1971, been equipped with electro-hydraulic feel systems for the evaluation pilot's elevator, aileron and rudder controls. This facility allows the simulation of a wide range of force-displacement characteristics through the adjustment of the electric gain of various feedback paths.

In the present experiment, the feel characteristics were adjusted to lie in the centre of the limits specified for Level 1 operation in MIL-F-83300. Adjustments about these conditions were then made by one of the evaluation pilots to give what he considered to be good, unobtrusive characteristics. These settings, tabulated in Figure 2, were maintained for the duration of the experiment.

In general, both a preload force and a slightly smaller dry friction reaction were desired in addition to the second-order, linear velocity and displacement feedback.

(This allows quickened and absolute centring of the controls.)

The level of forces chosen remained within the Level 1 range of the above requirements for elevator and aileron but were high and just in the Level 2 range for the rudder pedals in both spring gradient and total breakout force.

The dynamic response has been specified in Figure 2 only in terms of the basic, linear second-order system but it should be recognized that the dynamic response of the system is markedly and non-linearly affected both by the preload and



the friction. The former increases the stiffness and thus the natural frequency of the controller system, particularly near the trim position, whereas the latter provides resistance to system motion which is independent of velocity.

The elevator and aileron were each provided with a thumb-wheel force trim and, after starting with a trim rate of twice that tabulated, the pilots expressed satisfaction with the rate finally selected for all configurations other than those which were of the attitude stabilized, attitude command form. The elevator trim rate was considered to be slightly on the slow side for these configurations because of the greater steady state stick displacements required to change pitch attitude.

The only force feel provided on the thrust lever was mechanical dry friction which could be adjusted by the evaluation pilot to suit his desires.



APPENDIX C: ARTIFICIAL TURBULENCE GENERATION

In order to create a repeatable statistical disturbances environment for the evaluations, the output of three independent, random-noise, signal generators was shaped in such a manner that the model equations of motion were disturbed appropriately for turbulence components exhibiting Von Karman spectra and normal distributions.

The absence of independent control over either the fore-and-aft or transverse motions of the simulator meant that these artificial turbulence components could affect only the three rotary and the heave controls of the simulator. The pure Von Karman spectra were thus shaped to ensure that the simulator responses to artificially generated turbulence in heave, pitch roll and yaw were those that would result from external turbulence components of the same magnitude.

The output power-spectrum of a linear filter is related to the input power-spectrum by

$$\phi_{OO}(\omega) = |H(i\omega)|^2 \phi_{ii}(\omega)$$

The filter characteristics applied to the output of the random noise generators took the forms

$$H_{u}(s) = \frac{s}{s - X_{u_{F}}} H_{u_{VK}}(s) + \frac{X_{w_{F}}}{s - X_{u_{F}}} H_{w_{VK}}(s)$$
,

$$H_v(s) = \frac{s}{s - Y_{v_F}} H_{v_{VK}}(s)$$
,

$$H_{W}(s) = H_{WVK}(s)$$
.

The filters $H_{u_{VK}}$ (s), $H_{v_{VK}}$ (s), $H_{w_{VK}}$ (s) which were implemented, when applied to the output of the random signal generator, resulted in a close approximation to the Von Karman turbulence spectra given by

$$\phi_{uu}(\omega) = \frac{2\sigma^2}{\pi} \frac{L}{U} \left[\frac{1}{[1 + (1.339 \frac{L}{U} \omega)^2]^{5/6}} \right],$$

$$\phi_{VV} (\omega) = \phi_{WW} (\omega) = \frac{\sigma^2}{\pi} \frac{L}{U} \left[\frac{1 + \frac{8}{3} (1.339 \frac{L}{U} \omega)^2}{[1 + (1.339 \frac{L}{U} \omega)^2]^{-11/6}} \right].$$

The characteristic scale length, L, of the turbulence was kept fixed, for reasons of limited computational capacity, at L = 400 ft for all three components, whereas the r.m.s. turbulence level for all components was held to 2.5 ft/sec.

The following filter characteristics were used to approximate the Von Karman spectra for these conditions:

$$H_{u_{VK}}(s) = 3.96 \frac{(.641s + 1)}{(4.36s + 1)(.436s + 1)}$$
,

$$H_{v_{VK}}(s) = H_{w_{VK}}(s) = .707 H_{u_{VK}} \cdot \frac{(8.63s + 1)}{(5.28s + 1)}$$
.



APPENDIX D: VALIDATION OF X-FORCE SIMULATION

In order to determine if the estimates for the X-force derivatives were adequate to obtain the predicted model motions, a ground-based simulation of the longitudinal equations of motion using the assumed form for the X-force equation was undertaken for several configurations. The equations of motion of a particular configuration were disturbed by the pilot's inputs recorded during the flight evaluation of the same configuration. This allowed a comparison to be made between the responses so obtained and the actual in-flight helicopter responses. In particular, the correspondence between the longitudinal velocity responses is an indication of the adequacy of the X-force modelling.

The equations utilized in the ground-based simulation are as follows:

$$\dot{q}_{M} = M_{u} u_{M} + M_{q} q_{M} + M_{w} w_{M} + M_{w} \dot{w}_{M} + M_{\theta} \theta_{M}$$

$$+ M_{\delta e} \delta e + M_{\delta T} \delta T$$
D1

$$\dot{\mathbf{u}}_{\mathbf{M}} = - \kappa_{3} \dot{\mathbf{q}}_{\mathbf{M}} - \mathbf{g} \theta_{\mathbf{M}} + \mathbf{a}_{\mathbf{x}_{\mathbf{F}_{\mathbf{M}}}}$$
 D2

$$\dot{\mathbf{w}}_{\mathbf{M}} = \mathbf{U}_{\mathbf{0}} \mathbf{q}_{\mathbf{M}} + \mathbf{a}_{\mathbf{z}_{\mathbf{M}}}$$
 D3

$$\theta_{M} = \theta_{H_{S.C.}} + \int (q_{M} - q_{H}) dt$$
 D4

where, $\theta_{HS.C.}$, is the signal-cancelled, helicopter pitch attitude, and the subscript M refers to the ground model.

These equations should be compared with equations, All, Al3, A6, and Al2 respectively in Appendix A to show the possible sources of error originating from the initial conditions, unrecorded lateral-directional inputs, or external disturbances.

The following three configurations, with differing degrees of crossfeed from longitudinal velocity perturbations to the heave and pitch equations of motion, were selected for validation purposes:

Configuration 1 : $M_u=Z_u=0$

Good pitch stiffness and damping characteristics.

Configuration Al4-1: $M_u=0$, $Z_u=-.2$,

A pitch stabilized configurations with the attitude command form.

Configuration 1-2P: $M_u = .005$, $Z_u = -.2$,

Poorly damped, oscillatory phugoid characteristics.

Configuration 1

Because there is no crossfeed from the longitudinal velocity perturbations to the pitch and heave equations of motion, the pitch and heave responses remain independent of speed changes. Figure 4 shows the pitch rate, pitch attitude, normal velocity and longitudinal velocity responses of this configuration to a step reduction in thrust followed by elevator activity to constrain the pitch attitude perturbations.



The comparison between the helicopter and ground based simulation responses in this figure shows good correspondence between the various responses.

Configuration Al4-1

based simulation responses to a series of step like elevator inputs and a step reduction in thrust for this attitude stabilized configuration with longitudinal velocity perturbation crossfeed to the heave equation of motion. Again the correlation between the various responses is good. The drift in the ground-calculated longitudinal velocity starting after 90 seconds is probably due to a gentle turn initiated at this time by the pilot. Not all the relevant parameters necessary for an adequate ground simulation of this manoeuvre were recorded.

The time histories illustrate the good attitude-hold characteristics of the simulator.

Configuration 1-2P

Longitudinal velocity perturbations affected both the pitching moment and the heave equations of motion. The response of this configuration, because of the low stiffness and damping ratio of the phugoid mode, was very sensitive to initial conditions. To alleviate the problems associated with starting the integration, the term, $\int (q_M - q_H) dt$, was removed for the ground simulation. The resulting pitch



attitude synchronization allowed a comparison to be made between the longitudinal velocity fluctuations due to attitude changes, which was not dominated by errors with long settling times that would otherwise arise from the initial conditions. It did mean, however, that a slight mismatch due to lateral-directional inputs could occur.

Figure 6 illustrates the responses to a thrust-lever step input and Figure 7 those for a forward elevator pulse.

In Figure 7 the elevator pulse has excited the phugoid. It is seen that the period and damping ratio of the oscillation are close to the estimated values of 17.3 seconds and .05 respectively for both the helicopter and the groundsimulation responses. This factor provides additional evidence of the adequacy of the X-force derivative estimates.

Concluding Remarks

It is seen from the good correlations above, between the various responses obtained in flight and on the ground, that the estimates for the X-force derivatives adequately defined the longitudinal velocity responses of the simulator to various disturbing influences.



APPENDIX E: STATISTICAL ANALYSIS OF THE PILOTS' CONTROL INPUTS

The measured pilots' control inputs of fifteen configurations were analyzed for their statistical properties during the IMC flight phase of the landing approach. The purpose of this was to supplement the control usage data for the STOL class of aircraft on the approach and to ascertain the sensitivity of the statistical characteristics to changes both in pilots and in handling qualities.

E.1 Analysis Procedure

The evaluations by one pilot of three configurations, 1, 2L and 5L were used to examine the effect of varying the stiffness of the short-period mode through $\rm M_{\rm W}$, as described in Sections 5.1.1.1 and 5.1.3.1. Three configurations, 7L, 2L and 1lL, evaluated by the same pilot, were used to examine the effect of varying the basic pitch-control time-constant through $\rm Z_{\rm W}$ while the short-period total damping was maintained at a constant level, as described in Sections 5.1.1.2 and 5.1.3.4. The remaining nine evaluations were used to study the effect of $\rm Z_{\rm U}$ on the pitch-stabilized configurations with the rate-command form, R4, R4-2 and R4-3, and to examine the effect of inter-pilot variability.

The portion of the landing approach from the time that the pilot had established flight on the glideslope to the time just before reaching breakout was selected for analysis. Established flight was indicated by either a zero or a small and convergent tracking error after the glideslope



had been intercepted. A record length of 51.2 seconds was selected from the middle part of this approach, and the quantities being investigated were digitized at the rate of 40 samples per second, giving a total of 2048 data points for each quantity.

Prior to being digitized the raw, recorded data was filtered for anti-aliasing purposes by a four-pole, low-pass Butterworth filter with a cutoff frequency of 10 Hz. The mean values of the data during the sample time were removed. linear trend in the data, defined here arbitrarily as the slope of the straight line joining the mean values of the amplitudes of the first and last third of the data points, although calculated for each paramater, was not removed in the calculation of the power spectral and probability density distributions of the data. When it is large, the linear trend can have a pronounced effect both on the power spectral densities at low frequencies and on the amplitude probability distributions obtained for the data. The changes in amplitude resulting from the linear trend during the analyzed segments of the approaches for elevator and thrust lever displacements are presented in Table El together with the r.m.s. levels of control activity. In general, the amplitude change due to the linear trend in the time scales characterizing the dominant control activity, when compared with the r.m.s. levels, was small for elevator but often large for thrust lever. The significant linear trend for thrust lever probably resulted



from the adjustments required of the pilot to compensate either for the effects of wind-shear or for incorrect energy dissipation rates during the portion of the approach being analyzed.

It was felt that if the statistical properties of the pilot's control usage were of significance as indicators of his workload, then this correlation would best be seen in those data that were relatively uncontaminated by such inputs as linear trends which have a significant effect on the statistical properties but little effect on workload. For this reason the power spectral and probability density distributions were calculated only for the elevator control, firstly because the characteristic frequencies associated with control difficulty were better separated from the frequencies associated with the trim task than they were for the thrust control, and secondly because the need for elevator trim adjustments was generally not significant when the pilot was established on the approach.

Probability density distributions, normalized by their mean zero-level density, and power spectra, normalized by their r.m.s. values, were computed for the elevator movement and are presented in Figures 30 to 35, together with the sample time histories of elevator and thrust lever activity. The r.m.s. values of commanded acceleration, $M_{\delta e} \cdot \delta e_{r.m.s.}$, are included in the figures.

The power spectra were calculated using the Fast Fourier Transform method and then smoothed by means of a

low-pass filter having the characteristic,

$$x_{i_{LP}} = \frac{1}{m+1} \left[x_i + \frac{1}{2} \sum_{j=1}^{m} \left(1 + \cos \frac{j\pi}{m+1} \right) \left(x_{i-j} + x_{i+j} \right) \right],$$

where m is the number of points before and after the centre point. In this case, the values of m = 4 was chosen as a compromise between the suppression of high frequency noise and the retention of significant energy characteristics.

E.2 Results

E.2.1 The Effect of Changing Handling Qualities

Significant variations in handling qualities, due mainly to changing the pitch control characteristics, occurred for the two configuration groups in which the short-period stiffness and the pitch control time-constant were varied. The statistical properties of Pilot A's elevator control displacements are presented in Figures 30 and 31. From these evaluations and that for the pitch stabilized configuration of Figure 32, it is seen that the spectral forms of his elevator usage were relatively insensitive to the difficulty caused by the various pitch control characteristics of the configurations. In general, the spectra exhibited energy peaks at about 1.25 to 1.5 rads/sec and 3.5 to 4.5 rads/sec, the relative energy at these frequencies being affected somewhat by the configuration characteristics. The correlation between the spectra and the pilot's workload, obtained from his comments, was weak. The probability density distributions and r.m.s. levels showed greater variations with handling qualities but neither can be uniquely

correlated with workload.

E.2.2 The Effect of Changing Pilots

In the last group of configurations, the short-term pitch control characteristics remained invariant, but the flight path control characteristics changed from operation on the frontside to that on the backside of the power-required curve.

Each pilot demonstrated a characteristic spectral form in his elevator control displacements which differed somewhat from those of the other pilots. The pilots' main concern, when - Z_u was large, was with the coupling between longitudinal and vertical velocity but the increase in work-load, arising from the need to control precisely long-term speed fluctuations with elevator in order to alleviate the speed-coupling effects, was not reflected in a significant change in the statistical properties of any pilot's elevator usage.

It is seen from the pilots' use of thrust modulation, that thrust was used primarily as a long-term control even when operating on the backside of the power-required curve.

In summary the analysis of this sample of evaluations indicates that the statistical properties of the pilot's elevator movement show some effect of changing pitch characteristics but the correlation with workload is, at best, weak. Modulation of thrust magnitude was primarily for long-term control even when operating on the backside of the power-required curve.

R.M.S. Levels and Amplitude Change Due to Linear Trend STATISTICAL PROPERTIES OF PILOTS' CONTROL USAGE TABLE E1.

PARAMETER	CONFIG.	FLIGHT NO.	PILOT	M _{&e} erms	dM _{Se} ^{6e} AT	Z _{&T} erms	dZ _{&T} &T dt · AT
×	٦	60-1	A	.0330	016		
•	2L	69-1	А	.0222	002	0.186	-0.09
	5L	90-1	А	.0456	.025	1.24	-3.69
Z Z	7.1	74-1	А	.0276	024	1.40	-1.79
:	2L	69-1	A	.0222	002	0.19	60.0-
	111	69-2	А	.0303	600.	1.45	4.07
Z ₁₁	R4-3L	72-3	A	.0245	900	1.02	1.56
\$	R4L	38-1	ф	.0324	.010	0.99	2.00
	R4-2L	45-3	Ф	.0415	900.	1.66	1.73
	R4-3L	97-2	Д	0690.	008	1.98	2.73
	R4	48-1	Ö	.0415	.001	06.0	-3.10
	R4-2L	126-3	υ	.0282	800.	1.03	₩Z.0-
	R4-3L	121-3	O	.0394	003	1.36	-1.34
	R4L	40-1	Ω	.0456	.003	0.29	-0.79
	R4-3	47-1	Q	.0420	002	2.24	5.83

Note: $\Delta T = 51.2 \text{ secs}$, $\frac{dM_{\delta e} \delta e}{dt}$ • $\Delta T = \text{rad/sec}^2$

 $\frac{dZ_{\delta T} \delta T}{dt} \cdot \Delta T = ft/sec^2$

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