

TURBULENT BOUNDARY LAYER SKIN FRICTION, HEAT TRANSFER AND PRESSURE MEASUREMENTS ON HYPERSONIC INLET COMPRESSION SURFACES

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FOREWORD

The experimental research effort reported herein was conducted by the Hypersonic Facilities Department of Cornell Aeronautical Laboratory of Cornell University, Buffalo, New York, for the Flight Dynamics Laboratory, Air Force Systems Command, United States Air Force, on Contract F33615-67-C-1203 of Project No. 1366. The contractor's report number is AF-2389-Y-3.

The work reported herein covers both phases of a two-phase program which began in January 1967 and was conducted under the technical cognizance of Mr. Dennis Sedlock of the Flight Dynamics Laboratory's Internal Aerodynamics Group. The final report was submitted in April 1968.

This technical report has been reviewed and is approved.

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ABSTRACT

An experimental study of turbulent boundary layer flow, under the influence of adverse pressure gradients typical of hypersonic inlets, was conducted in the Cornell Aeronautical Laboratory 96-inch Leg of the Hypersonic Shock Tunnel on a two-dimensional and an axisymmetric model each instrumented with skin friction, heat transfer and pressure gages. Tests were conducted over a Mach and Reynolds number range of 6.74 to 11.37 and 1.05 x 10⁶ per ft. to 2.93 x 10⁷ per ft., respectively. These test conditions produced boundary layer transition on the forward portions of the models without resorting to artificial trips. It was possible to attain a fully turbulent boundary layer before the start of the adverse pressure gradient region for most of the axisymmetric model tests but for most of the two-dimensional tests, transition was not completed until after the start of the pressure gradient.

A comparison of the pressure data with the inviscid pressure distribution was made and good agreement is generally found indicating very little change in effective model shape due to boundary layer growth. This result is a consequence of the large model size relative to the boundary layer thickness, i.e., high Reynolds number flows over large models.

An important conclusion resulting from this program was that turbulent boundary layers can negotiate large adverse pressure gradients without separating. Comparison with some existing laminar boundary layer data indicate that a turbulent boundary layer can negotiate adverse pressure gradients at least an order of magnitude greater than those gradients which will separate a laminar layer.



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NOMENCLATURE AND SYMBOLS

Symbol		Unit
$c_{\mathbf{p}}$	Specific heat at constant pressure	ft-lbs/slug-°R
Н	Enthalpy	ft-lbs/slug
M	Mach number	
P	Pressure	psia
q	Dynamic pressure, $1/2 \rho U^2$	psia
q	Heat transfer rate	Btu/ft ² -sec
Re/ft	Reynolds number per foot, $\frac{\rho \nu}{\mu}$	
T	Temperature	°R
U	Velocity	ft/sec
x	Axial distance from leading edge	inches
√ C*	Square root of the constant of proportionality in the linear viscosity law based on a reference temperature T*	
	$C^* = \underbrace{\mathcal{L}}_{\mathcal{L}}^* \underbrace{T}_{T^*}$	
α	Angle of attack	degrees
м	Absolute viscosity coefficient	slugs/ft-sec
P	Density	slugs/cu.ft
ø	Roll	degrees
*	Yaw	degrees
~	Skin friction	psia



NOMENCLATURE AND SYMBOLS (Concluded)

Subscripts	
AV	Average
i	Incident shock in shock tube
0	Nozzle reservoir conditions
o†	Stagnation conditions behind a normal shock
ts	Test section initial conditions
w	Initial conditions at wall
x	Axial distance from leading edge
∞	Free stream conditions
1	Initial driven tube conditions
4	Conditions behind reflected shock
Superscripts	
*	Eckert reference temperature



SECTION I

INTRODUCTION

Hypersonic inlet design and performance estimation are dependent upon a thorough knowledge of the boundary layer flow on the various compression surface comprising the inlet configuration. Boundary layer growth can alter the effective shape of the inlet giving a different shock wave pattern both at the leading edge of the inlet and internally with the result that the mass flow captured and the total pressure losses are both affected. In addition, boundary layer separation from the inlet compression surfaces may occur creating additional shock waves with further losses in total pressure. Boundary layer transition will occur, except at very high altitudes (>150K) and Mach numbers (>12), with a resultant increase in aerodynamic heating and skin friction drag. Despite the increased heating and drag, a turbulent boundary layer may be an asset because of its ability to negotiate larger adverse pressure gradients than laminar boundary layers can without separating. The wall skin friction of turbulent boundary layers in adverse pressure gradients comprises the subject matter of this report.

The effort reported herein is concerned with the experimental investigation of turbulent boundary layers on continuous compression surfaces at hypersonic Mach numbers under the influence of large adverse pressure gradients. Freestream conditions of sufficiently high Reynolds numbers were available to attain natural boundary layer transition within reasonable model lengths and thereby avoid introducing boundary layer trips as an influence in the experiments. Direct local skin friction measurements, in addition to pressure and heat transfer rates, were made on continuous compression surfaces to provide data which can be used to evaluate the applicability of existing turbulent boundary layer theories. In addition the data can be used to improve existing, or develop new, methods of predicting turbulent boundary layer characteristics.

SECTION II

TEST EQUIPMENT

CAL 96-INCH LEG OF THE HYPERSONIC SHOCK TUNNEL

The basic components of the 96-Inch Leg of the Hypersonic Shock Tunnel are shown in Figure 1. The tunnel employs a chambered reflected shock tube with a 5-inch inside diameter driver and a 4-inch inside diameter driven section. The driver tube is 16 feet long and is externally heated with a resistance heater up to temperatures of 1200°R. The driven tube length is 48.5 feet long and is always at the ambient temperature. The driver gas was a mixture of helium and air with a maximum helium purity of 98.5% while the driven gas was dry air. Steady flow test times of the order of 2 to 5 milliseconds, which allowed ample time to measure skin friction, pressure and heat transfer rates on the models, were achieved using the tailored-interface technique to be described later.

The long models tested in the present program made it desirable to avoid the streamwise pressure gradients typical of conical nozzle expansions. Consequently two axisymmetric contoured nozzles, providing parallel flow with no pressure gradients in the streamwise direction for several feet, were used for the expansion. One nozzle is designed for a Mach number of 8 and the other for 16. Both nozzles were used over a Mach number range by employing removable throat inserts of various diameters. Both nozzles have been calibrated, using pitot pressure survey rakes, over the range of operating conditions used in the subject program.

The test air expands through the nozzles into a 96-inch diameter test section in which the models are supported on an angle of attack sector as shown in Figures 2 and 3. Test air passes downstream of the test section into a receiver tank large enough to maintain flow for the desired duration. The models are isolated from tunnel accelerations by mounting the model support system on the laboratory floor and using a flexible bellows to provide a vacuum seal between the sector and the tunnel. The 16-inch diameter schlieren windows shown in the figures were used to obtain a single spark flow photograph for most runs of the test program.

2. SHOCK TUNNEL OPERATING PRINCIPLES

The shock tube is separated into regions of high and low pressure by a diaphragm (Figure 4). The wave phenomena begin with the rupture of the diaphragm, permitting expansion of the high-pressure driver gas into the lower pressure section and the generation of a shock wave which propagates through the low-pressure air. Between the shock wave and the gas interface (the contact surface separating the driver gas and the driven air) there exists a steady state region which is at a high temperature and pressure.



The downstream end of the shock tube is terminated by a convergent-divergent nozzle. The ratio of the nozzle throat area to the shock tube cross-sectional area is small, however, so that the primary shock wave is nearly completely reflected upstream from the throat, leaving a region of almost stagnant, compressed, and heated air at the end of the low-pressure section of the shock tube. This processed air is expanded through the nozzle to the desired test condition.

By proper control of the initial conditions in the driver and driven sections, the gas interface becomes transparent to the shock wave reflected upstream from the throat, i.e., no gasdynamic waves result from this interface—shock interaction that can subsequently disturb the steady testair—supply conditions. Since the states of the gases on both sides of the interface must be carefully matched, this method is called the "tailored—interface" technique (Reference 1). The limiting wave, which then determines the maximum available testing times for the tailored—interface technique, is the leading expansion wave reflected from the driver end of the tube. The test times available are approximately eight times those achieved with the same length tube operating as a conventional nonreflected shock tunnel.

The temperature of the air behind the reflected shock in the driven section of the tube (corresponding to the "reservoir" or "supply" temperature in conventional wind tunnel terminology) is a function of the strength or velocity of the shock wave through the driven tube. If the stagnation temperature is to be duplicated at a given flight Mach number, the shock velocity or shock Mach number is then uniquely determined. The shock Mach number is, in turn, a function of the pressure ratio across the diaphragm for given driver gas mixtures and initial temperatures of the driver and driven gas. In order to tailor at various shock strengths, provision is made to vary the velocity of sound of the driver gas by mixing the driver gas with other gases and by heating.

MODELS

The models are of two basic shapes, two-dimensional (Phase I tests) and axisymmetric (Phase II tests) and are typical of the types of compression surfaces which might be used in hypersonic inlets. High shock losses at hypersonic speeds dictate that initial angles of inlet surfaces be small. Consequently the two-dimensional model has a sharp leading edge and an initial wedge angle of 3 degrees and the axisymmetric nose is a sharp hollow cylinder which was vented downstream of the model, allowing flow through the interior of the body. The aft regions of both models are designed for isentropic continuous compression which produces the adverse pressure gradient regions of interest in this test program.



a. Two-Dimensional Model, E-2

The two-dimensional model was designed and fabricated by the General Electric Company on Air Force Contract Number AF 33(675)-11747. This model, with a cowl attached, was tested by General Electric in their Missiles and Space Division shock tunnel facility. The G.E. test program (Reference 2) investigated cowl shock and compression surface laminar boundary layer interaction whereas the present tests are concerned with turbulent boundary layer characteristics under the influence of isentropic compression.

The two-dimensional model consisted of a wedge with an angle of 3° for the first 5 inches followed by a region designed for isentropic compression. The curved surface aerodynamic contours are based on a Method-of-Characteristics solution and laminar boundary layer analyses. Using the GE/Bertram viscous interaction program described in Reference 3, a solution for the upstream wedge region determined the boundary layer displacement thickness and surface pressure distribution. At the station 5 inches from the leading edge, the computed value of the Cohen and Reshotko (Reference 4) pressure gradient parameter, \mathcal{N} , is -0.5 reflecting the viscous induced weak favorable pressure gradient. Aft of this 5 inch station \mathcal{N} is varied linearly to a value of 0.12 at station 15 inches. Downstream of the 15-inch station the wall contour is designed to maintain a constant value of \mathcal{N} of 0.12. The final wall angle was approximately 17.5 degrees. Photographs and drawings of the two-dimensional model comprise Figures 5 and 6, respectively. Locations of the model instrumentation are given in Figure 7.

b. Axisymmetric Model

The axisymmetric model was designed and fabricated by the Lockheed-California Company on Air Force Contract Number AF 33(657)-8833. This model was tested by Lockheed in the Arnold Engineering Development Center (AEDC) 50-inch diameter Tunnel B and the 40-inch Tunnel A, both of the von Karman Facility. The model was tested at Mach numbers of 5, 6 and 8 over a range of Reynolds numbers per foot of 1.6 to 6.9 million. Boundary layer trips were used for the AEDC tests whereas natural transition was achieved for the tests reported herein. Heat transfer and pressure data were obtained in the AEDC test which are reported in Reference 5.

The axisymmetric model consisted of a sharp leading edge hollow cylinder nose followed by an isentropic compression region which was designed for a focused isentropic compression at a Mach number of 8. The high rate of wall turning in the aft region of this model is readily apparent in the pressure data which will be discussed later. In addition, a blunt nose was provided to be interchanged with the sharp hollow nose to obtain blunt nose data. The downstream end of the model was terminated with a conical flare specifically designed to prevent the expansion from feeding upstream and modifying the boundary layer in the aft region. The final wall angle was approximately 30 degrees. Photographs and drawings of the axisymmetric model comprise Figures 8 and 9, respectively. Locations of the model instrumentation are given in Figure 10.



4. INSTRUMENTATION

a. Skin Friction

The large aerodynamic forces involved in this test program necessitated the development of a new high load skin friction gage with both a linear response to higher skin friction forces and a mechanically stronger gage structure to survive the large tunnel stopping loads experienced by the model and gages. Early attempts in this current program to use existing skin friction gages which had been previously used at lower Reynolds number conditions (Reference 6) indicated that these gages were not linear up to the maximum wall shear forces expected in this program and that they would not physically survive the environment. Hence a more rugged skin friction gage using the same basic principles as the existing gages was developed.

The CAL skin friction gage designed for this test employs the piezoelectric effect to convert a mechanical stress to an electric charge output. Lead zirconium titanate crystals are stressed by a force acting on a diaphragm and flexure system shown in Figure 11. Response is to a force applied tangentially to the diaphragm as shown by the arrow in Figure 11 indicating airflow direction. The flexures, which are cemented to the diaphragm and crystals with a high temperature bonding material, carry the skin friction force from the diaphragm to the crystals. These flexures are designed to be weak in bending to isolate the crystals from diaphragm warping which could be caused by pressure or thermal effects. Force normal to the diaphragm resulting from pressure loading is eliminated by allowing the gas to flow underneath the diaphragm and around the crystals. In addition, what little normal force does get to the crystal is in a direction in which the crystal has zero theoretical and little actual sensitivity. Using Invar for the diaphragm further reduces temperature effects by minimizing thermal warping which could transmit forces to the crystals. Compensation for acceleration effects is accomplished by an additional crystal and mass system which has the same acceleration sensitivity as the active system and is electrically wired in opposition to the active system.

The crystals are bimorph configurations which consist of two layers of lead zirconium titanate that have been polarized in opposite directions in order that the combination will be sensitive to bending in one plane but relatively insensitive to all other strains. They will, therefore, have little response to temperature change. The crystals are used in a cantilevered beam mode with one end rigidly bonded into the gage housing and the other end attached to the diaphragm. Two bimorphs are used in the active gage in order to make a stronger crystal-diaphragm structure. The crystals are coated with an electrical insulator to avoid effects of charged particles in the airflow.

In addition to developing a more rugged skin friction gage for this program, a new technique of mounting the gage in the model was used to isolate the gage from model accelerations. Although the internal acceleration compensation of the skin friction gage was generally sufficient to



eliminate errors due to acceleration from the average output during the test time, it was discovered that the gages were being physically damaged by accelerations of the model during tunnel flow breakdown (Figure 12(a)). These model accelerations were measured and were found to be many times greater than the accelerations experienced during the test time and to contain frequencies on the order of 10 to 12 kc which is approximately the natural frequency of the gages. The resulting resonance of the gages was felt to be largely responsible for the damage experienced. To isolate the instrumentation from the model excitation, a shock mount was designed and bench checked for the skin friction gage. This mount provided for rubber support of the gage with no metal-to-metal contact between the gage and the model. To further "de-tune" the gage from the model excitations, a mass was added to the back of the gage housing which lowered the natural frequency of the gagemass system. Typical skin friction gage outputs during testing are indicated in Figure 12.

The new shock mounting system for the skin friction gages ensures that the gage unit is not stressed by the gage mounting and consequently the need to calibrate the gages after installation in the model is eliminated. Calibration of the gage outside the model was not only possible but desirable since, for concave curvatures, such as existed on these models, it is not possible to apply a purely tangential force to the gage diaphragms. The calibration consists of applying known forces to the diaphragms in the skin friction direction using weights. The gages were calibrated from .006 psi to 2.8 psi and were linear over this range to within ±2%.

The flat diaphragm shown in Figure 11 was used for model E-2 which had very little curvature over a surface distance in the flow direction of 1/4-inch. These same diaphragms were then hand-contoured to the local model radius for the axisymmetric model and again the surface contour over a length of 1/4-inch was neglected.

b. Heat Transfer

Heat transfer rates were determined by a technique that relies on sensing the transient surface temperature of the model. The sensing element is a thin platinum strip painted on a Pyrex substrate which conforms to the local model contour. The gage is then fired at controlled conditions, resulting in a thin film of metal, typically 0.1 micron thick by 5 mm by 0.5 mm, and fused to the Pyrex insert. Since the heat capacity of the gage is negligible, the film temperature is equal to the instantaneous surface temperature and is related to the heat transfer rate to the model by the theory outlined in Section V of this report and discussed in detail in Reference 7. Temperature histories from the platinum strips were fed into a passive analog network which produced a step output that was proportional to the heat transfer rate to the model. An IBM 360 computer program then uses the analog network output voltages to compute heat transfer rates. The computer automatically makes small corrections for the variation with temperature of the heat transfer gage substrate (Pyrex) properties and the nonlinear resistance-temperature characteristics of the platinum strip.



c. Pressure

The model pressures were measured with miniature ceramic piezoelectric crystal transducers. Their small size permits installation inside the model close to the orifice in the model surface, thus minimizing pneumatic lag. These transducers are available in several sizes and pressure ranges so that the type best suited for the estimated pressure range at a given model position can be used. Proper shielding of the sensing element precludes temperature effects during the short test time. In the transducer used to measure the pressures of the current program, a dualelement transducer was used to reduce acceleration effects to an indicated pressure of ≤ .0008 psi/g. Pressures on the order of 0.1-60 psi were measured with this transducer. The pressure transducer indicates the pressure rise over the initial pre-run test section pressure which is usually on the order of 3 microns as determined by a Pirani vacuum gage which is periodically checked against a McLeod gage as a standard. The voltage output of each gage is calibrated against applied pressure through the model surface orifice after the gage has been installed in the model. Transducers are selected such that the voltage output is linear with pressure over the range of pressures encountered. Pressure transducers are normally calibrated before a series of runs. The details of the design, fabrication, and calibration of the pressure transducers used in the present test series are described in Reference 8.

d. Flow Visualization

Flow photographs were taken, either schlieren or shadowgraph, for both test phases using a single-pass parallel light system which viewed approximately the aft 16 inches on both models. This region of the models had the maximum adverse pressure gradient and consequently was of the most interest. The majority of the photographs were taken using shadowgraph since this system was superior to schlieren for observing the boundary layer. The schlieren system generally had too much sensitivity for these high density flows. The few schlieren photographs obtained were taken with the knife edge horizontal.

5. DATA ACQUISITION

The electrical signals from the heat transfer, skin friction and pressure transducers were recorded on 44 channels at 50-microsecond intervals on the magnetic storage drum of a Navigation Computer Corporation MCL-100 data acquisition system. The information was then transferred to magnetic tape for use as the input to the data reduction program. The data were also reproduced on a pen-type recorder for immediate examination and preliminary calculation.

SECTION III

TEST PROCEDURE

TEST PROGRAM

The two-dimensional and axisymmetric model test program and test conditions are presented in Tables I and V, respectively. The test program was specified by the Air Force Flight Dynamics Laboratory. Run 18, which is not shown in the test program, was an instrumentation diagnostic run which produced no model data. On Run 19, the first run on the axisymmetric model, most of the rearward data on the model were lost because the recording equipment gain settings were based on pretest estimates which proved to be too small in the aft region of the model.

2. CALIBRATION

The detailed calibration data are kept on file at CAL.

a. Skin Friction

The skin friction gages were calibrated using known weights to apply shear forces to the gage diaphragm. Gage outputs were displayed on oscilloscopes and photographed using Polaroid cameras. Dividing the weights by the area of the diaphragm gave the equivalent shear stresses corresponding to the respective gage outputs. The gages were checked for electrical leakage after installation in the models. The gage sensitivities determined by the calibration were used to select recording equipment gains during the test.

b. Heat Transfer

The heat transfer gages were calibrated prior to the tests to determine the changes in resistance of the elements with temperature. At the temperatures encountered in these tests, these changes are linear and the resistance at only two temperatures need be determined. This calibration is then used to set the gain of the recording equipment for the expected temperature increase.

c. Pressure

The pressure gages were calibrated (i.e., voltage output versus applied pressure) and checked for air and electrical leakage after installation in the model. The voltage-pressure relation is linear over the range of pressure normally encountered during testing.

These calibrations, in conjunction with estimated values of model pressures provide the basis for adjusting amplifier gains to achieve maximum "readability" of the data recording system.

SECTION IV

TEST CONDITIONS

The test conditions of pressure, temperature and Reynolds number are computed by assuming isentropic expansion of the test gas from the conditions behind the reflected shock in the tube to the test section Mach number which has been previously determined from airflow calibrations. The calculation of test section free-stream parameters includes the effect of molecular vibration assuming a simple harmonic oscillator model for the diatomic constituents of air.

The stagnation enthalpy and temperature of the air behind the reflected shock are determined respectively from

$$H_0 = H_1 \quad (H_4/H_1) \tag{1}$$

and

$$T_o = T, \left(T_4 / T, \right) \tag{2}$$

where $\mathcal{H}_{4}/\mathcal{H}_{1}$ and $\mathcal{T}_{4}/\mathcal{T}_{1}$, are functions of \mathcal{U}_{1} , the incident shock velocity (Reference 9-11). \mathcal{U}_{1} is obtained by measuring the time taken by the shock wave to pass between two stations in the shock tube. \mathcal{H}_{1} is taken from Reference 12 and \mathcal{T}_{1} is measured prior to each run. Free-stream static temperature is obtained from

$$T_{\infty} = \frac{H_0}{\overline{C}_{P_{\infty}AV}} \left(1 + \frac{\gamma_{\infty} - 1}{2} \frac{C_{P_{\infty}}}{\overline{C}_{P_{\infty}AV}} M_{\infty}^2 \right)$$
(3)

where γ_{∞} is a function of $C_{P\infty}$; $C_{P\infty}$ and $C_{P\infty}$ include vibrational heat capacity and are functions of T_{∞} , requiring an iteration between T_{∞} and $C_{P\infty}$. Free-stream pressure is calculated using

$$P_{\infty} = \frac{P}{P_{\rho}} P_{o} \left(1 + \frac{\gamma - 1}{2} M_{\infty}^{2} \right)^{-\frac{\gamma}{\gamma - 1}} \tag{4}$$

where

$$\frac{P}{P_{p}} = \frac{(P/P_{o})}{(P/P_{o})} \text{ real }$$
perfect

is the real gas correction to the ideal static to total pressure ratio as described in Reference 13 but suitably modified to include vibrational specific heat in the test section, and R is the measured pressure behind the reflected shock. The source data used in this technique are References 12 and 14.

Free-stream velocity, density and dynamic pressure are respectively calculated from

$$U_{\infty} = M_{\infty} \sqrt{Y_{\infty} R} T_{\infty}$$
 (5)

$$\rho_{\infty} = \rho_{\infty} / R T_{\infty} \tag{6}$$

$$g_{\infty} = \frac{1}{2} \rho_{\infty} U_{\infty}^2 \tag{7}$$

Values for absolute viscosity (μ) used to compute Reynolds numbers were obtained from Reference 15 for temperatures below 500°R and from Reference 16 for temperatures above 500°R.

Stagnation conditions behind a normal shock in the test section are based on the data of Reference 14.

SECTION V

DATA REDUCTION

1. SKIN FRICTION

The skin friction gage output is a direct function of the average shear stress over the gage diaphragm and the sensitivity of the gage, which was determined during gage calibration. Dividing gage output by gage sensitivity gives average shear stress directly.

2. HEAT TRANSFER

The "thin-film" heat transfer gage is a resistance thermometer which reacts to the local surface temperature of the model. The theory of heat conduction in a nonhomogeneous body is used to relate the surface temperature to the rate of heat transfer. Since the resistance element has negligible effect on the Pyrex substrate surface temperature, the substrate can be characterized as being semi-infinite, homogeneous and isotropic. The general heat conduction equation is

$$\rho_{C}(\tau) \frac{\partial \tau}{\partial \tau} = \frac{\partial}{\partial x} \left[K(\tau) \frac{\partial \tau}{\partial x} \right] \tag{8}$$

where ρ , C, and K are substrate density, specific heat and thermal conductivity, respectively, and X is the substrate depth.

If the substrate properties are independent of temperature; i.e., if the temperature change is less than 100°R, a closed-form solution is obtained for the heat transfer rate,

$$\dot{g}(t) = \frac{1}{2} \left(\frac{\pi \rho c k}{t} \right)^{1/2} \left[\tau(t) + \frac{1}{\pi} \int_{-\infty}^{t} \frac{\lambda^{1/2} \tau(t) - t^{1/2} \tau(\lambda)}{(t - \lambda)^{3/2}} d\lambda \right]$$
(9)

For evaluating the integral numerically, the equation is recast in the following form:

$$\dot{g}(n) = \frac{1}{2\sqrt{\pi}\Delta t} \left(\rho_{CK} \right)_{n}^{1/2} T_{n} \left(\frac{T + \sum_{p=0}^{E} \frac{\rho^{1/2}}{(n-p)^{3/2}}}{n^{1/2}} \right) \frac{\rho_{-n-1}}{\rho_{-0}} \frac{T_{p} (\rho_{CK})^{1/2}}{(n-p)^{3/2}}$$
(10)

where t = time interval between tabulated data points (typically, 50 microseconds)

n = time index of the point

p = running time index



subscript n = value of parameters at n th time increment th subscript p = value of parameters at p time increment

When the gage temperature rise is greater than $100^{\circ}R$ the temperature dependence of $(\rho cK)^{1/2}$ and the variation of the electrical properties of the resistance element with temperature are accounted for in the computer program.

Frequently heat transfer data are obtained by solving Equation (9) directly by the use of q-meters, which are passive electrical analog networks, in conjunction with the heat transfer gage. The analog is based on the fact that the equation for heat conduction in a semi-infinite solid is identical to that for a semi-infinite electrical transmission line with distributed series resistance and shunt capacitance. In practice, it has been found feasible to construct the analog of a number of circuit elements consisting of parallel resistor-capacitor elements in a series arrangement. A time and heat transfer rate dependent correction must be applied to the q-meter output to account for gage property variations with temperature.

PRESSURE

The pressure transducers measure the difference between the internal case pressure and the model pressure. The case pressure is equal to the initial test section pressure (on the order of 3 microns) and is added to the measured pressure to obtain the absolute pressure.

SECTION VI

DISCUSSION OF RESULTS

The results of this program provide wall skin friction data for turbulent boundary layers in adverse pressure gradients on slender continuous compression bodies typical of the components of hypersonic inlets. In addition one very important characteristic of turbulent boundary layer flows, namely resistance to separation from the wall, can be observed from the wall measurements of skin friction, heat transfer and pressure. The ability of turbulent boundary layers to negotiate rather large adverse pressure gradients without separating is clearly seen by comparing the data herein with the work of Reference 6 which contains wall data obtained for laminar boundary layers in adverse pressure gradients. All the turbulent data obtained in this program were taken using natural boundary layer transition.

The two models were tested at nominal Mach numbers of 7, 8, 10, and 11, and a range of Reynolds numbers at each Mach number. The maximum Reynolds number was limited by the facility and/or instrumentation capabilities and the minimum Reynolds number was limited by the desire to have transition occur before the start of the adverse pressure gradient. This latter restraint was relaxed for many of the two-dimensional tests in order to obtain a larger range in Reynolds number variation. The two-dimensional model was tested at zero degrees angle of attack for Mach numbers of 8, 10 and 11 and at zero, four and eight degrees for a Mach number of 7. These angle of attack runs at Mach 7 were included to obtain data for a lower local Mach number since it was not possible to run the facility at a lower free stream Mach number. The axisymmetric model was tested at zero degrees angle of attack only. In addition to the sharp nose runs on the axisymmetric model, three runs were made with a blunt nose installed in order to obtain a lower local Mach number.

TWO-DIMENSIONAL MODEL TEST

The details of the test conditions and run schedule for the two-dimensional model are given in Table I. Data obtained were skin friction, heat transfer rates, pressure and flow photographs. Tabulated skin friction, heat transfer rates and pressure data are given in Tables II, III, and IV, respectively. Skin friction, heat transfer rates and pressure plots are given in Figures 13, 14, and 15, respectively. Flow photographs, either schileren or shadowgraph, for the two-dimensional model test comprise Figure 16. A reference length is indicated in Figure 16(a) to aid in scaling from the photographs. The testing was started using schlieren photography of the flow but a change to shadowgraph was made when it became apparent that the over-sensitive schlieren system showed little boundary layer detail.

Examination of the plotted heat transfer rates and skin friction data shows the approximate location of transition on the model. Although it was desired to have transition completed at the start of the adverse pressure



gradient which was five inches from the leading edge, this generally was not possible since the short distance requires free stream Reynolds numbers beyond the facility capability. However, for the Mach number 7 runs transition was completed within about 10 inches of the model nose and for two of the angle of attack runs transition was completed before the start of the adverse pressure gradient. The higher Mach number testing required a foot or more to achieve a fully turbulent boundary layer. Included on the heat transfer rates plots (Figure 14), are maximum and minimum readings of the transitional heat transfer data. A sample of transitional heat transfer and skin friction data can be seen in Figure 12(c). Note that the heat transfer and skin friction excursions due to turbulent bursts are not as large of a percentage of the average reading for skin friction as they are for heat transfer. This lesser sensitivity to turbulent burst is believed to be a result of an averaging nature of the relatively large area of the skin friction gauge diaphragm. The ratio of the area of the diaphragm to the area of the platinum element on a surface temperature gauge is greater than 10. However, it is still possible to see differences in the skin friction traces as well as the heat transfer for transitional and laminar or turbulent traces as is illustrated in Figure 12.

It should be noted that data from skin friction position 5 have been excluded from this report since these data were always about one half the expected value and examination of the gage after the test indicated some irregularities in its construction. Also the skin friction data from the first four positions on Runs 4 and 5 (see Figure 13(b)) were of poor quality and therefore no significance should be given to the distributions indicated for these points. It is clear that the values of skin friction were small indicating laminar or transitional flow which is in agreement with the heat transfer measurements shown in Figure 14(b).

The heat transfer and skin friction data distributions along the model exhibit considerable waviness even in the turbulent boundary layer region. This waviness is believed to be real and not a fault of the instrumentation since two rather different types of instrumentation operating on fundamentally different principles both show waviness and pre- and post-test calibrations of the skin friction gages showed excellent linearity and repeatability. Admittedly, the argument would be stronger if the waviness shown by the two types of instrumentation was always in phase but there may be reasons for a phase shift. The waviness may result from the fact that for most runs transition is occurring in an adverse pressure gradient or from nonisentropic compression. Careful examination of the flow photographs of Figure 16 reveals what appear to be weak shock waves emanating from the surface in some cases. The fact that the pressure distributions generally appear smooth is not necessarily a contradiction in that it has been observed in the past that sensitivity to flow irregularities is greatest for skin friction gages, somewhat less for heat transfer and least for pressure. A good example of these relative sensitivities will be shown later in the discussion of the blunt nose data from the axisymmetric models.



Edge effects, which could affect the levels of the data distributions on the model do not appear to be significant judging from the pressure data. Comparison of the overall pressure rise from the data with the predicted inviscid pressure rise shows good agreement of the lower Mach number, higher Reynolds number conditions; a decrease in the experimental pressure rise compared to the inviscid pressure rise is observed at the higher Mach number, lower Reynolds number conditions. This behavior is qualitatively correct for viscous effects since at the lower Mach number, higher Reynolds number conditions the boundary layer is thinner and the pressure distribution should be closer to the inviscid predictions. Conversely, edge effects should be more important at the lower Mach numbers and would tend to make agreement with the inviscid values poorer. Base effects at the rear of the model appear to affect only the last pressure measurement on some runs as can be seen in Figure 15(c) and (d).

The apparent double shock visible in the flow photographs of Figure 16 is believed to be caused by very small amounts of leading edge waviness which produces a shock sheet of increasing thickness in the downstream direction. The optical system photographs the cross-section projection of this shock sheet. The work of References 2 and 6 using similar models indicates the same shock behavior. Work performed at CAL and reported in Reference 2 shows several flow photographs of a sharp leading edge model with the leading edge in the field of view and the origination of the apparent double shock at the leading edge is visible.

AXISYMMETRIC MODEL TEST

The details of the test conditions and run schedule for the axisymmetric model are given in Table V. Data obtained were skin friction, heat transfer rates, pressure and flow photographs. Tabulated skin friction, heat transfer and pressure data are given in Tables VI, VII, and VIII, respectively. Skin friction, heat transfer and pressure plots are given in Figures 17, 18, and 19, respectively. Flow photographs, either schlieren or shadowgraph, for the axisymmetric model test comprise Figure 20. A reference length, the distance normal to the side of the pitot probe to the model surface, measured in the plane of the forward face of the probe, is included in Figure 20(a) to aid in scaling from the photographs. The testing was started using shadowgraph based on what was learned from the two-dimensional model testing and changed to schlieren when it was observed that more system sensitivity was needed.

As a result of having about 23 inches of model length upstream of the start of the adverse pressure gradient region for the sharp nose configuration, transition was completed before the start of the gradient on all but two sharp nose model test runs at a nominal Mach number of 10. Natural transition was desired since data obtained from tripped boundary layers can be affected by the tripping process as is evident in Reference 17 and as will be shown a little later in this discussion. On the blunt nose configuration the effect of bluntness delayed transition into the gradient region for the two lower Reynolds



number runs. For the sharp nose model all the data distributions appear reasonably smooth and rise to very high values at the rear of the model. With the exception of the Mach number 11 runs, the pressure data agrees quite well with the inviscid estimates as can be seen in Figure 19. At the Mach number 11 condition the boundary layer apparently had more influence in reducing the amount of compression of the flow over the model. It should be noted that due to the very rapid rise in the data at the rear of the model, waviness in the distributions like that observed on the two-dimensional model would be difficult to observe and hence it cannot necessarily be concluded that the waviness isn't present. The only evidence of possible base effects appears to be in the Mach number 11 data where the last pressure position appears to be reading low compared to the experimental distribution suggested by the pressures upstream of it. For the lower Mach number data the most rearward pressures seem to be slightly above the inviscid estimates, suggesting that a local shock may be present near the rear of the model. The flow photographs of Figure 20 do show a rather abrupt compression near the rear of the model but it is difficult to conclude that a secondary shock is present.

In an attempt to see if the large increase in all the data levels toward the rear of the model was reasonable, a comparison of heat transfer data from the present tests with data from Reference 5 was made for a Mach number 8 test condition that was common to both sets of data. The results of this comparison can be seen in Figure 18(c). The data of Reference 5 were obtained with tripping devices on the forward portion of the model. As can be seen the tripped boundary layer data, which are shown for wall to total temperature ratios of 0.36 and 0.44 as noted, fall considerably below the natural transition results of the present tests which were conducted at a wall temperature ratio of 0.34. The upstream data points from the tripped test fell below the range of the plot but are included with appropriate notations. Included on the plot is a flat plate theory line from the method of Reference 18. Other predicted heating rates from the work of Van Driest and Von Karman were also examined and were found to range up to a value of about 3.4 Btu/ft²sec for the two foot station on the forward cylindrical section of the model. It is clear that the present data obtained with natural boundary layer transition is in better agreement with theory than the data resulting from boundary layer tripping. The qualitative relationship of the natural transition data to the tripped boundary layer data is in agreement with the results of Reference 17 which indicates that for a given distance aft of the natural transition point on a model, tripped boundary layers give lower heating rates than boundary layers which have experienced natural transition. Interestingly enough the tripped boundary layer heat transfer data indicate a ratio of increase from the front to the rear of the model which is greater than the corresponding ratio for the natural transition data but the maximum level reached is less. Consequently, the large rise in heat transfer rate from the front to the rear of the model observed in the present test does not appear unusual and from the relationship between heat transfer and skin friction a large increase in skin friction from the front to the rear of the model is also reasonable.

^{*}Comparing flat plate estimates with data from axisymmetric bodies is valid when the boundary layer thickness is small compared to the body radius as is certainly the case for these high Reynolds number test conditions and large model size.

16



The last three runs of the axisymmetric model test were conducted with a blunt nose installed on the model to reduce the local flow Mach number. Unfortunately this blunt configuration produced a bow shock which intersected the nozzle wall and reflected back over the rear of the model nearly hitting the rear corner as can be seen in Figures 20(m), 20(n), and 20(o). Since the model length and the length of the test rhombus were nearly the same, it was not possible to withdraw the model from the nozzle without affecting the flow over the rear of the model and furthermore hardware did not exist to allow this change in model position. Theoretically, since the reflected shock missed the rear of the model, the flow over the model should be unaffected. Examination of the pressure distributions (Figure 19(e)) and comparison with the inviscid estimates seems to bear this out and the heat transfer data (Figure 19(e)) exhibit a smooth distribution from front to rear. However, the skin friction data distributions are very erratic in the adverse pressure gradient region as can be seen by examining Figure 17(e). In this Figure all the skin friction data traces for the blunt nose runs are presented to demonstrate the erratic nature of these data. An average reading from a step output, typical of the other data presented in this report, would have little meaning for most of these traces.

These blunt nose runs were made at the same free stream conditions as Runs 28 and 29 which did not produce erratic data. The two primary differences between the two groups of runs were first, nose geometry and second, the bow shock reflection from the nozzle. Both the nose geometry and the bow shock intersection with the nozzle could combine to give a system of compression and expansion waves. The waves from the expansion around the blunt nose reflecting from the bow shock and/or shocks from the nozzle boundary layer separation ahead of the model bow shock intersection point may very well interact to produce the observed skin friction gage behavior. The lack of visible evidence of the hypothetical wave systems in the flow photographs and the apparent smoothness in the pressure and heat transfer distributions may not be contradictory but may be only the result of relative sensitivities of the instrumentation. It is very possible that a secondary weak wave system may not show in the flow photographs because of the basic sensitivity of the schlieren system or the predominance of the basic flow structure. It is also known to be true from previous work (Reference 6), that skin friction gages are much more sensitive to flow disturbances than heat transfer or pressure. Careful examination of the heat transfer raw data does show more unsteadiness than usual but not enough, it is felt, to invalidate the time averaged reading presented herein.

Admittedly, this explanation of the erratic skin friction data is very hypothetical but the alternative of condemning the skin friction gage performance does not seem to be justified since pre- and post-test calibrations agreed within ±3% in magnitude and ±2% in linearity. The absolute skin friction and pressures levels to which the skin friction gages were subjected were actually considerably less on the blunt nose runs than on the sharp nose runs 28 and 29 conducted at the same free stream conditions, hence the blunt nose testing did not represent an extreme test environment. The pressure data in fact indicate that the gross model flow field was about as predicted as can be seen in Figure 19(e).

SECTION VII

PRECISION OF DATA

Test Conditions

The data reduction program computes free-stream static pressure from the following equation:

$$P = (P/P_p)(1 + .2M^2)^{-3.5}P_0 \tag{11}$$

where (P/P_p) is the real gas correction for static to total pressure ratio and is subject to negligible error in an individual program. Based on the agreement of pressure transducers, the reservoir pressure measurements are considered accurate to $\pm 3\%$.

The effect of Mach number on free-stream pressure may be determined as follows: Each nozzle-throat combination employed is calibrated prior to its use on a program by measuring the ratio of pitot to reservoir pressure. The computed values of free-stream Mach number from a large number of runs normalized to a given condition are used to calculate a standard deviation in nominal Mach number at that condition and these deviations are as follows:

Nominal Mach Number	Standard Deviation (σ)
11.2	.1255
9.9	.0911
8.0	.0765
6.8	.0709

If there is a normal error distribution in the calibration, then the mean Mach number value may be taken to be the actual value of $\mathcal{M}_{\boldsymbol{\omega}}$. The validity of assuming a normal error distribution may be seen by an analysis of pitot and reservoir pressure errors as they affect $\mathcal{M}_{\boldsymbol{\omega}}$. The ratio of pitot to reservoir pressure can be expressed as:

$$P_o'/P_o = \left(\frac{6M_o^2}{M^2 + 5}\right)^{7/2} \left(\frac{6}{7M_o^2 - 1}\right)^{5/2}$$
 (12)

but since the Mach numbers of interest are hypersonic, a reasonable assumption is:

$$M_{\infty}^2 + 5 \approx M_{\infty}^2$$
, and $7M_{\infty}^2 - 1 \approx 7M_{\infty}^2$ (13)

therefore

$$P_o'/P_o = C/M_o^5 \tag{14}$$

Applying the "most probable error" analysis (Reference 19) to equation (14) yields:

 $\frac{dM_{\infty}}{M_{\infty}} = \sqrt{\frac{1/25 \left(\frac{dP_o}{P}\right)^2 + 1/25 \left(\frac{dP_o}{P'}\right)^2}{1/25 \left(\frac{dP_o}{P'}\right)^2}}$ (15)

Again based on the agreement of pressure transducers, pitot pressure measurements are considered accurate to $\pm 5\%$. Using accuracy figures of $\pm 3\%$ and $\pm 5\%$ for reservoir and pitot pressure, respectively, in the above equation it can be shown that the "most probable error" for M_{∞} is $\pm 1.2\%$. Since $\sigma/M \leq 1.2\%$ then, σ can be seen to be within the accuracy of reservoir and pitot pressures.

The precision within within which P_{∞} is known is affected by both the accuracy within which P_{o} is measured and the accuracy within which is known.

Now by applying the 'most probable error' analysis to equation (1), it can be shown that:

$$\frac{dP_{\infty}}{P_{\infty}} = \sqrt{\left[\frac{1.4M_{\infty}^2}{1+2M_{\infty}^2}\right]^2 \left(\frac{dM_{\infty}}{M_{\infty}}\right)^2 + \left(\frac{dP_o}{P_o}\right)^2}$$
(16)

Employing accuracies of $\pm 3\%$ and $\pm 1.2\%$ for reservoir pressure and Mach number, respectively, it can be shown that the "most probable errors" in P_{∞} to be expected during this test program are:

Mag	MPEPO
11.2	±8.7%
9.9	±8.5%
8.0	±8.3%
6.8	±8.2%

Model Attitude

The model attitude was set with an inclinometer at the desired angle of attack which is estimated to be within $\pm 0.1^{\circ}$.

Skin Friction

The errors involved in calibrating the skin friction gages are the following:



Calibrating weight errors ±0.4% Metric diaphragm diameter ±0.22% Reduction of calibration data ±2%

Taking the square root of the sum of the squares of these errors gives an overall error for the calibrations of $\pm 2.4\%$. The skin friction gage pre- and post-test calibrations actually agreed to within $\pm 3\%$ for all models. Linearity of all skin friction gages is within $\pm 2\%$ as determined from the calibrations.

To assess the accuracy of the test data it is necessary to consider calibration accuracy, the Navcor recording equipment resolution, and trace reading accuracy. The calibrations are known to within $\pm 3\%$. Navcor resolution is ± 0.05 volts which produces an error of $\pm 1\%$ assuming a five volt data output. Maximum error in the data reduction trace reading is $\pm 2\%$. Combining these gives a 'most probable error' of $\pm 3.8\%$.

Two other potentially important sources of error in skin friction measurement are acceleration and pressure sensitivity of the gages. The acceleration sensitivity of the gages utilized in this investigation is so low that model acceleration does not affect the accuracy of the skin friction data. The data have a maximum error due to pressure sensitivity of $\pm 7\%$ pressure sensitivity error is computed for those gages, gage locations and test conditions giving the maximum error. The majority of the skin friction data have a smaller pressure sensitivity error because the test conditions and gage locations were such as to give a larger ratio of measured skin friction to measure pressure. The resulting overall accuracy for most of the skin friction data then becomes about $\pm 6\%$.

Heat Transfer

Calibrations to determine the heat gages' temperature-resistance characteristics are conducted with an error potential of 1 percent. Far more significant than this is the repeatability of the heat gage during test. A series of shock tunnel tests designed to determine repeatability of the heat transfer data has shown that the RMS deviation of the repeatability is ±3 percent. Combining these errors indicates that the relative RMS deviation of the heat transfer data is about ±3.2 percent.

Pressure

The pressure transducers are accurate to $\pm 1\%$ of their maximum calibration pressure. On the basis of consistency and repeatability of the pressure data, it is estimated that these data are accurate to within $\pm 5\%$.

SECTION VIII

CONCLUSIONS

Hypersonic shock tunnel tests were conducted on a two-dimensional and an axisymmetric compression body typical of hypersonic inlet compression surfaces to obtain wall skin friction data for a turbulent boundary layer in an adverse pressure gradient. Both models were instrumented in the continuous compression regions with skin friction, heat transfer and pressure gages. Each model was tested at a nominal Mach number of 11, 10, 8 and 7 with a Reynolds number variation at each Mach number. Testing was conducted at large Reynolds numbers to obtain natural boundary layer transition on the models. Wall measurements were concentrated in the adverse pressure gradient regions and included laminar, transitional and turbulent data, depending upon the location of transition relative to the instrumentation. Flow photographs, either schlieren or shadowgraph, were obtained for most runs of the program.

As a result of the experimental hypersonic turbulent boundary layer investigation reported herein the following conclusions are reached.

- 1. Turbulent boundary layers can negotiate much larger adverse pressure gradients without separating compared to laminar boundary layers. The validity of this conclusion is easily seen by comparing the data herein with the data from Reference 6 which contains separated laminar boundary layer data taken in an adverse pressure gradient. Comparison of the two-dimensional model data indicates that the maximum adverse pressure gradient for the turbulent tests was about two times the gradient for the laminar tests and comparison of the axisymmetric model data from the present tests with the axisymmetric data of Reference 6 indicate a ratio of about ten to one for the adverse pressure gradient. No indications of separation were observed in the data presented herein.
- 2. Nose bluntness delays transition as can be seen by comparing the data from the blunt nose axisymmetric model with the sharp nose results at the same freestream conditions.
- 3. The boundary layer does not appreciably change the model pressure from the inviscid distribution if the boundary layer thickness is small compared to the model thickness.
- 4. Skin friction gages appear to be sensitive to flow non-uniformities that are undetected by heat transfer or pressure instrumentation.
- 5. At a given position downstream of the natural transition point on a model, heat transfer and skin friction data from a tripped boundary layer will be less than the corresponding data resulting from natural transition.

SECTION IX

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RUN SCHEDULE AND TEST CONDITIONS FOR THE TWO-DIMENSIONAL MODEL TESTS Table I

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Table I (CONCLUDED)

RUN NO.	17
α	4.0006 00
4	0.0
ø	0.0
M i	4.9115 00
Po	9.253F 03
Ho	3.6225 07
т。	5.0355 03
Mao	5. RKRE 11
υ _∞	8.0025 03
Τœ	5.7705 02
P∞	1.4905 00
٩œ	4.0445 01
Poo	2.1755-04
U oo	4.0415-07
Re/FT	4.3375 04
P' _O	0.300E 01
T.	1.5075 12
м*	8.0595-07
√ <u>C*</u>	9.4705-01
H _w	3.2105 06
τ‴	5.350E 02
P _{ts}	1.934F-05



Table II
TWO-DIMENSIONAL MODEL SKIN FRICTION DATA

RUN	GAGE	Mão	τ
1	1	1.104F 01	3.472F-13
•	,	1.104F 01	4.958F-03
1	3	1.104F 01	5.772E-03
1	4	1.1045 01	1.175F-02
1	6	1.104F 01	3.736F-02
1	7	1.1045 01	4.501F-02
Ť.	9	1.104F 01	4.741F-02
1	3	1.1045 01	4.538F-02
1	10	1.104E 01	F. 705F-12
1	11	1.104F 01	6.481F-02
1	12	1.1045 01	7.149F-92
1	13	1.1045 01	7.9915-12
?	14	1.1045 01	1.034F-01
1	15	1.1045 01	1.0565-01
2	1	1.1195 01	5.307F-03
2	2	1.1185 01	7.027F-03
?	2	1.1185 01	1.1505-02
2	4	1.1185 01	2.300F-02
7	5	1.1185 01	4.658F-02
2	7	1.1186 01	5.686F-02
2	3	1.1185 01	6.4045-02
2	3	1.11 RF 01	6.539F-12
2	10	1.1185 01	9.066F-12
2	1 7	1.1185 01	9.560F-02
2	12	1.1186 01	9.247E-32
2	13	1.118E 01	1.1435-11
2	14	1.118F 01	1.461F-01
2	15	1.1185 01	1.3965-01
3	1	1.127F 01	5.692F-03
3	?	1.1275 01	9.620F-13
3	2	1.1275 01	2.026F-02
3	4	1.127F 01	3.369F-12
3	5	1.1275 01	6.3235-02
2	7	1.1275 01	7.43]F-02
3	9	1.1275 01	P. 461F-02
3	3	1.1275 01	9,924E-02
3	10	1.1275 01	1.138F-01
2	11	1.1275 01	1.3315-01
3	12	1.1275 01	1.1785-01
3	13 14	1.127F 01	1.515F-01 2.055F-01
3	15	1.1275 01	1.913E-01
:•	1 -)	1 • 1. / / - //1	1 • 71 16-71



RUN	GAGE	Moo	~
4	1	9.454F 20	3.7735-03
4	2	9.4545 00	3.383F-03
4	3	9.454F 10	2.3055-03
4	4	0.454F 30	5.5555-03
4	5	9.4545 00	4.005F-02
4	7	9.4545 77	R. 986F-92
4	٩	0.454F 00	1.1175-71
4	3	9.454F 00	1.034F-01
4	10	9.454F 00	1.1155-01
4	11	9.454F 00	1.313E-01
4	15	9.4545 00	1.1245-01
4	13	0.4545 00	1.444F-11
4	14	0.4545 00	1.742F-71
4	15	9.454F 30	1.417F-01
E.	1	0.544F 00	R. 344E-03
5	2	9.5445 00	1.[845-03
5	3	9.544E 00	4.1005-03
5	4	0.5445 00	7.430F-03
5	5	9.5445 00	ዓ. ፋቦርE – ዓን
5	7	9.544F 30	1.2158-01
5	J	0.5445 00	1.409F-71
5	9	9.544F 00	1. 3945-01
5	17	9.5445 00	1.526E-01
5	11	9.5445 00	1.354F-01
5	12	9.5445 00	1.477F-01
5	13	9.5445 00	2.120F-11
5	14	9.5445 30	7.644F-01
5	15	9.5445 30	2. 3475-71
6	3	7.9025 00	3.1155-12
4	4	7. 9925 10	2.902F-02
4	4	7.8925 00	3.776F-02
6	7	7.8925 00	4.0415-02
6	Я	7.992F 00	4.4405-32
4	7	7.8975 00	4.568F-72
4	10	7,9025 00	5.359E-12
4	1.1	7,8025 11	4.306F-02
4	12	7.8025 00	5.962F-92
4	43	7.9025 00	6.1456-02
4	14	7.9925 00	9.9215-02
6	15	7.4025 00	4.5735-02



RUN	GAGE	M_{∞}	au
7	1	7.8935 00	1.242E-02
7	2	7.8935 00	3.088F-02
7	3	7.9935 00	3.049F-02
7	4	7.8935 00	2.949E-92
7	5	7.9935 00	3.776E-02
7	7	7.803F 00	4.174F-12
7	8	7.8935 00	4.540F-02
7	0	7.8935 00	4.525F-02
7	10	7.4935 00	E-320E-03
7	11	7.8935 77	4.222F-02
7	12	7.8935 00	6.059F-02
7	13	7.9035 00	6.9825-02
7	14	7.8935 00	8.309E-02
7	15	7.8935 00	R. 449F-02
Ą	1	7.992F 00	3.468F-12
А	2	7.0925 10	4. 9155-12
O	3	7.992E 10	4.775F-92
Ω	4	7.902F 00	4.624F-02
Я	5	1.003E 00	6.622E-02
Ω	7	7.9925 11	6.7915-12
R	7	4.005E UV	7.587F-02
Ω	9	7.992E 00	7.550E-02
8	10	7.997F 00	0.2815-02
Ω	11	1.992E 00	1.0895-01
b	12	7.9925 00	1.072E-01
А	13	7.9925 00	1.1935-91
Я	14	7.9925 00	1.543E-01
ρ	15	7.9025 00	1.516F-01
O	1	8.127E 00	5.479F-12
0	3	9.127F 00	7.729F-92
Q	3	8.127F 00	A. 1195-02
0	4	9.127F 00	7.43RF-72
0	6	8.127E 00	1.146F-01
C	7	8.127E 00	1.23[F-0]
C	q	8.127F 00	1.371F-01
n	•	8.127F 00	1.366F-01
Q	17	8.127F 00	1.679F-01
C	1.1	9.127F 00	1.4345-01
Ġ	12	9.1275 00	1.3195-01
Ģ	13	9.1275 00	2.165F-01
ū	14	8.1275 00	2.452F-01
0	15	8.127F 00	2.754F-01
		29	



RUN	GAGE	М 🚙		~
10	2	6.805E	90	1.4535-02
10	3	6.9055	90	9.3785-93
10	4	5.905E	20	3.352F-12
10	5	K.805E	90	9.029E-02
10	7	6.8050	70	8.515F-02
Īυ	Q	6.RM5E	00	1.0326-01
10	Ġ	6.8055	20	9.957F-02
10	10	ሉ. ጸጣፍር	11	1.144E-01
10	11	ፋ _• ጳሳፍE	77	1.3686-01
1 ^	12	6.8050	30	1.136F-01
10	13	4.905	40	1.446E-01
10	14	6.975F	90	1.9516-01
10	15	6.8755	40	1.540F-01
11	1	6.868E	20	2.550F-02
7.7.	6	6.9595	00	1.533E-01
11	7	K.RKRE	O O	1.4985-01
1 1	0	ሐ .ዓለጸគ	ÜÜ	1.9995-01
11	12	6.8685	40	2.280F-01
12	1	6.970=	20	2.495F-92
12	2	6.8795	00	1.169F-21
12		6.879F	00	1.314E-01
12	4	6.9795	00	1.140E-01
12 12	5 7	6.879E	20	1.594F-01
12	ģ	6.879F	00	1.938F-01
12	J.	6.879=	00	1.909F-01
12	10	6.879F	20	2.2835-01
12	11	6.879F	20	2.591F-01
12	12	6.8795	nn	2.311E-01
12	15	6.979E)n	3.191E-01
12	1	6.9555	20	1.000E-01
13	3	6.9555	90	1.930F-01
13	4	6.9555	Ůυ	1.6286-01
13	5	6.955E	20	2.266F-01
13	9	A.955E	Ú.O	2.681E-01
12	3	6.955F	20	2.7536-01
13	10	6.0550	00	3.242F-01
12	11	6.955	99	3.361F-01
13	13	6.9555	nn	3.329F-01
13	13	6.955F	30	4.212F-01
12	14	5.955E	<u>00</u>	5.0165-01
Ĺj	15	6.955F	υû	4.5955-71



RUN	GAGE	M 😞	au
14	1	6.79RE 00	3.838E-02
14	2	6.798F 00	1.4756-01
14	3	6.798F 00	1.839F-01
14	5	6.79RE 00	2.170F-01
1.4	7	6.798F 00	2.112F-31
14	я	6.798# 00	2.238F-01
14	9	6.798F 00	2.019E-01
14	10	6.798F 00	2.344E-01
14	11	6.7985 00	2.401F-01
1.4	12	6.798F 00	2.269F-01
1 4	13	6.798F 00	2.689F-01
14	14	6.798F 00	2.887E-01
14	15	6.798E 00	2.92[F-0]
15	1	6.868E 00	1.727F-01
15	2	6. BERE DO	2.524E-01
15	7	6.868F 30	2.781F-01
15	4	6.868F 30	2.524F-01
15	5	6.868F 00	3.450F-01
† 5	7	6.868F 00	3.725E-01
15	8	6.8685 00	3.977F-01
15	J	6. ዓለጻም ሰሰ	3.902F-01
15	10	6.869F 00	4.327F-01
15	11	5.868F 10	4.459F-71
15	12	6.868E 00	4.194E-01
1 5	13	6.868F 00	4.8925-01
15	14	6.868F 00	5.440E-01
3 5	15	6.868E 00	5.850F-01
16	1	6.9565 00	2.743F-01
16	2	6.956F 00	3.5006-01
16	3	6.9565 00	3.7465-01
16	4	6.95KE 10	7.5175-71
16	5	6.756F 00	5.143E-01
16	7	6.9565 77	5.413F-01
16	۵	6.95KF 00	5.983F-01
16	9	6.9565 00	5.4946-01
16	11	6.0565 00	
16	12	6.956F 00	
16	13	6.95KE 00	7.702E-01
16	14	6.956F 00	7,9716-91
16	15	6.95KF 00	8.213E-01



Table II (CONCLUDED)

RUN	GAGE	M oo	て
17	1	6.868F 00	1.5835-01
77	7	6.868E 00	
17	3	6.868F 00	
17	4	6. RARE OF	
17	6	6.868E 00	
17	7	6.868E 00	
17	4	6.868E 10	
17	9	K.RKRE OF	
17	10	6.868E 00	
7 7	11	6.868E 00	
17	12	6.8685 00	
17	13	K. RKRE OF	
17	14	6.868E 00	
17	15	6. RERE DO	



Table III
TWO-DIMENSIONAL MODEL HEAT TRANSFER DATA

RUN	GAGE	qev		RUN	GAGE	φaν	RUN	GAGE	qav
1	1	2.1785	20	5	1	1.129F 01	0	1	2.3375 01
1	2	7.756E	90	5	2	1.4485 01	0	'n	2.1115 01
1	3	1.268F	21	5	3	5.6335 01	9	3	2.962F 01
1	4	1.0205	21	5	4	1.1475 02	C	4	4.192F 01
1	5	2.510F	21	5	5	1.4545 02	n	5	5.5425 01
7	5	3.5615	71	5	6	1.9265 12	Ģ	4	6.861F 01
7	7	3.439F	01	5	7	1.816F 02	g	7	7.009= 01
1	4	3.483E	01	5	а	2.2265 02	g	Q,	7.649F 01
7	Q)	7.070E	Λį	5	9	2.0165 02	ņ	7	7.578F 01
1	12	5,454F	0.1	5	10	3.1375 02	Q	10	9.815F 01
2	ŧ	2.646F	nn				10	1	1.1145 01
2	2	3.5705	00	6	1	2.446F 00	10	2	1.8275 01
2	3	1.9945	21	Ą	?	1.1425 01	1 ^	3	6.129F 01
2	4	2.9435	01	<u>۸</u>	3	1.1408 01	10	4	8.4795 01
2	5	3,9515	01	6	4	1.7305 01	10	5	9.5205 01
2	5	5.6425	01	4	5	1.9995 01	10	4	1.393E 02
2	7	5.341F	01	K	6	2.7465 01	10	7	1.400F 02
2	3	6.1185	01	6	7	2.783E 01	10	Q.	1.5535 12
?	G	6.8635	Λj	6	Q _	2.951F 01	10	9	1.364F 02
2	10	9.9155	01	6	9	3.049F 01	• •		14 ንክትሮ ሀሪ
	•	• •		۴	10	3.940F 01	17	1	1.7065 01
7	1	3.4025	30				11	1 2	1.1045 02
3	2	6.8615	20	7	1	2.155F 00	11	3	1.131F 02
3	3	2.580F	Oξ	7	7	1.051F 01	11		1.5395 02
3	4	4.022E	01	7	3	1.1075 01	11	4 5	2.011F 02
2	5	5.5385	01	7	4	1.567F 01			2.675F 02
3	4	9.7955	าร	7	5	1.0155 01	11	6 7	2.4715 02
7	7	Q. 217F	01	7	5	2.508E 01	11 11	ر ب	
7	G.	9.7595	21	7	9	2.711F 01	1.1	o o	2.917F 02
7	7	9.5785	01	7	G	2.734F 01		10	2.898E 02
7	10	1.2305	02	7	10	3.491E 01	1 1	t.''	7. RYRE 177
	_			В	1	8.367E 00	12	1.	1.911E 01
4	1	1.1215		R	,	1.531F 01	12	7	1.016F 02
4		1.252F		ρ	3	1.617F 01;	12	3	1.074F 02
4	3	3.423F	ΩĪ	R	4	2.3515 01	12	4	1.451F 02
4	4	9.3025		B	5	2.929F 01	12	5	1.837F 02
4	5	1.361F	12	Д	5	4.0045 01	12	6	2.541F 02
4	4		02	R	7	3.820= 01	12	7	5.303E 03
4	7	1.658E	05	R	q	4.247E 01	12	ঀ	2.4385 02
4	9	1.830=	^7	R	o,	4.6695 01	12	•	2.5955 02
4	9	1.4916	92	Ŗ	10	5.881F 01	12	12	2,955E 12
4	10	2.446F	32	•,1		2 € 22 (3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			



Table III (CONCLUDED)

RUN	GAGE	φaν		RUN	GAGE	qav	
12	1	2.932F	01	17	1	7.1125	21
12	2	-	02	17	2	1.423F	92
13	- 3	1.539F	02	17	3	1.550F	02
13	4	2.073F	0.3	17	4	1.99AF	22
13	5	2.6625	n 2	17	5	2.5775	92
13	6	3.594F	92	17	4	3.268F	72
13	7	3.912	92	17	7	3.0755	22
13	o,	3.670	02	17	Q	3.3425	02
13	3	3.787E	0.5	17	0	3. 2475	72
13	10	4. 180F	υS	17	10	3.4745	77
14	1	2.444F	01				
14	2	1.1655	92				
1.4	7	1.235F	95				
14	4	1.6035	0.5				
1.4	5	1.9605	2				
14	5	2.1335	72				
14	7	2.400F	72				
14	8	1.974F	02				
14	Ġ	2.0585	02				
14	10	2.4625	0.5				
15	7	2.097E	72				
15	2	2.0175	υŞ				
15	3	2.0675	92				
15	4	2.6400	92				
15	5	3.3315	J.S.				
15	5	4.122F	92				
15	7	4.038F	U 5				
15	8	4.3255	02				
1 5	0	3.878F	02				
15	17	4.024F	02				
16	1	3.0245	3.5				
16	2	2.854F	Öδ				
16	3	2.9365	02				
14	4	3.7855	0.5				
16	5	4.458F 5.449F	ÜS				
16 16	5 7	5.7315	02				
16	9	5.374F	02				
16	g	5.113F	02				
16	10	5.6655					



Table IV
TWO-DIMENSIONAL MODEL PRESSURE DATA

RUN	GAGE	Мω	P	P/P ∞
1	1	1.104F 01	2.966F-01	2. 2215 00
1	2	1.104E 01	2.691F-01	2.0855 00
1	3	1.104E 01	2.922E-01	2.264F 00
1	4	1.104F 01	3.997F-01	3.019F 00
Ţ	5	1.104F 01	5.912E-01	4.581F 00
1	6	1.104F 01	8.391F-01	6.502F 00
1	7	1.1045 01	1.077F 00	8.342F 00
1	23	1.104F 01	1.320E 00	1.0235 01
1	Ġ	1.104F 01	1.656E 00	1.2835 01
1	10	1.104F 01	2.21 9E 00	1.720F 01
1	11	1.104E 01	2.391F 00	1.845F 01
1	12	1.104F 01	2.733F 10	2.118F 01
1	13	1.104F 01	3.003F 10	2.327F ^1
1	14	1.104F 01	3.356F 00	2.601E 01
2	1	1.1195 01	3.993F-01	2.050F 00
2	?	1.1185 01	3.624F-01	1.860E 00
2	3	1.118F 01	3.790F-01	1.946E 00
2	4	1.118F 01	5.148F-01	2.643F 00
2	5	1.118F 01	7.922F-01	4.066F 00
2	6	1.118E 01	1.197F 00	6.147E 00
?	7	1.1185 01	1.6125 00	9.273F 00
2	9	1.118F 01	1.988E 00	1.021F 01
2	9	1.118E 01	2.579F 00	1.324F 01
2	10	1.1195 01	3.422E 00	1.757E 01
2	11	1.118F 01	3.546E 30	1.8725 01
2	12	1.118F 01	4.261F 00	2.197F 01
2	13	1.118F 01	4.539F 00	2.330F 01
2	14	1.118F 01	4. 990E 30	2.5106 01
ż	4	1.1275 01	6.661E-01	2.601E 00
3	5	1.1275 01	1.021F 00	3.989F 00
3	6	1.127F 01	1.526F 00	5.9595 00
7	7	1.127F 01	2.062E 00	9.053E 00
3	Я	1.1275 01	2.562F 10	1.0005 01
3	3	1.127F 01	3.388F 00	1.323E 01
3	10	1.1275 01	4.514E 30	1.763F 01
3	11	1.127F 01	5.046F 00	1.971F 01
3	13	1.127F 01	6.336F 00	2.474F 01
3	14	1.1275 01	6.637E 00	2.592F 01



RUN	GAGE	M co	P	P/P 🕳
4	2	9.454F 00	6.005E-01	1.914E 00
4	3	9.454F 00	6.016F-01	1.917F 00
4	4	9.4545 00	7.678E-01	2.447F 00
4	5	9.454F 00	1.106F 00	7.5245 00
4	6	9.4545 00	1.544F 00	4.9225 00
4	7	9.4545 00	1.959E 00	6.243F 00
4	8	7.454E 00	2.409E 00	7.679F 00
4	n	9.454F 00	3.037F 00	9.679E 00
4	10	9.4545 00	3.035E JU	1.253F 01
4	11	9.454F 00	4. 381E 00	1.396F 01
4	12	9.454F 00	5.014F 00	1.5988 01
4	13	9.4545 00	5.545F 00	1.7675 01
4	1.4	9.454F 00	5.782E 00	1.943F 01
5	2	9.5445 00	7.046F-01	1.6958 00
5	3	9.544F 00	7.530E-01	1.812E 03
5	4	9.5448 00	9.4995-01	2.334F 00
5	5	9.544F 10	1.433F 00	3.448F 00
5	6	9.544F 00	2.052F 00	4.937F 00
5	7	9.544F 00	2.641F 10	6.3535 00
5	R	9.544F 11	3.187F 00	7.468F 00
5	q	9.544F 30	4.012E 00	9.4545 00
5	Ĭυ	0.544F 00	5.228E 00	1.259F 01
5	11	9.544F 30	5.774F 00	1.389F 01
5	12	9,5445 00	6.641F 00	1.598F 01
5	13	9.544F 00	7.244F 10	1.743F 01
5	14	9.544F 00	7.547E 00	1.816F OI
4	2	7.8925 00	6.007E-01	1.965E 09
6	3	7.892F 00	6.226F-01	2.0375 00
6	4	7.8925 00	9.000E-01	2.417F 00
6	5	7.992F 00	1.039F 00	3.398E 00
6	4	7.9925 00	1.36BE 10	4.475E 00
6	7	7.892E 00	1.707F 00	5.583F 00
6	9	7.892F 00	5.005E 00	6.54RE 00
4	Ċ	7.992F 00	2.419F 00	7.913F 00
4	10	7.8925 00	3.028E 00	9,9045 03
6	11	7.892F 10	3.296E 00	1.078E 01
4	13	7.892F 00	4.747F 10	1.324F 01
6	14	7.8925 00	4.161F 00	1.361E 01

Table IV (CONTINUED)

RUN	GAGE	Мю	P	P/P co	
7	1	7.893F 00	5.786F-01	1.986F 0	7
7	7	7.9975 00	5.714E-01	1.951F 0	9
7	3	7.8935 ባር	6.104F-01	2.095F 0	1
7	4	7,8935 00	7.6805-01	2.636E 0	0
7	5	7.893F 00	1.010F 00	3.465F 0	O
7	4	7.893F 00	1.327F 10	4.556E 0	ņ
7	7	7,8935 00	1.650E 00	5.665F 0	^
7	9	7.897F 00	1.939E 00	6.655F 0	0
7	9	7.993F 00	2.306F 00	7.916F 0	0
7	10	7.8935 00	2.901F 00	9.959F 0	Û
7	11	7.893E 00	3.094E 00	1.0625 0	ŧ
7	12	7.9935 00	3.549F 00	1.2185 0	Į.
7	13	7.9935 00	3.906F 00	1.306F 0	1
7	14	7.8936 00	4.101E 00	1.408F 0	1
Д	1	7,9925 00	1.073F 00	1.995E 0	0
R	?	7.99 2E 00	1.030E 00	1.9055 0	n
Я	3	7.992F 00	1.065E 00	1.971F 0	1
æ	4	7.992F 00	1.419F 00	2.674F 0)
8	5	7.997F 00	1.898F 00	3.5125 0	9
А	6	7,992F 00	2.517F 00	4.657F 0	ŋ
Q	7	7.992F 00	3.124F 00	•	Û
Я	9	7.9925 00	3.655F 00	6.762F 0	^
8	9	7.992E 00	4.337F 00	8.025F 0	Û
R	17	7.992F 00	5.461E 00		ì
ρ	11	7.992F 00	5.910E 00	1.093E 0	
8	12	7.9925 00	6.978F 00	1.291F 0	
ρ	13	7.992F 00	7.244F 00	1.340E 0	
Я	14	7,992E 00	7.673F 00	1.420F 0	7
Ò	1	8.127F 00	3.306E 00	2.121E 0	ŋ
9	2	8.127F 00	2.051E 00	1.971F 0	0
O	3	9.127E 00	2.104E 00	2.022F 0	C
a	4	8.127F 00	2.570E 00	2.471E 0	^
٩	5	9.1275 00	3.746F 00	3.601E 0	\bigcirc
O	5	8.1275 00	4.852F 00	4.654F 0	
n	7	9.127F 00	5.909F 00	5.680E 0	
۵	я	8.1275 00	7.036F 00	6.763E 0	
G.	Q	8.127F 00	8.350F 00	8.0265 0	
9	10	8.1275 00	1.060E 01	1.019F 0	-
9	11	8.127F 00	1.161F 01	1.115E 0	
0	12	8.1275 00	1.321F 01	1.2695 0	
0	13	8.127F 00	1.4595 01	1.403F 0	
O	1.4	8.1275 00	1.554E 01	1.4945 0	J.
10	1	6.805F 00	1.209F 10	1.653F 0	1
10	2	6.8055 00	1.112E 00	1.521F 0	1
1 ^	3	6.8055 00	1.168F 00	1.597E 0	O

RUN	GAGE	Мю	P	P/P $_{\infty}$
ĮΛ	4	6.905E 00	1.453E 00	1.987F 00
10	5	6.8055 00	1.930F 00	2.640F 00
10	5	6.805= 00	2.583E 00	3.532F 00
10	7	6.805F 00	3.264F 00	4.465E 00
10	Я	6.8055 00	3.698F 00	5.05RE OO
10	9	6.805F 00	4.399E 00	6.016F 00
10	10	6.805F 00	5.4508 00	7.454F 00
įο	11	6.8055 00	6.187E 00	8.451F 00
1 ^	12	6.8055 00	6.545E 00	8.9515 00
10	13	6.805E 00	7.325F 00	1.0025 01
10	14	6.805F 00	7.205F 00	9.8535 00
11	?	6.8685 00	2.432F 10	1.587F 00
11	4	6.8685 00	3.089E 00	2.016F 00
11	6	6.8685 00	5.494F 00	3.716F 00
11	8	6.868E 00	7.647F 00	4.991F 00
11	12	6.8685 00	1.438E 01	9.385E 00
11	14	6.868F 00	1.574F 01	1.027E 01
	_			
12	1	6.879F 00	2.574F 00	1.7085 00
12	2	6.879E 00	2.368F 00	1.5715 00
12	3	6.8795 00	2.573F 00	1.707F 00
12	4	6.879F 00	2.968F 00	1.9595 07
12	5	6.4795 00	4.155F 00	2.757F 00
12	5	6.879F 10	5.576E 00	3.699F 00
12	7	6.8795 00	6.725F 00	4.462F 00
12	Ŗ	6.8795 00	7.603F 00	5.045F 00
12	9	6.8795 00	9.260F 00	6.144F 00
12	10	6.879F 00	1.120E 01	7.430F 00
12	11	6.8795 00	1.253F 01	8.316F 00
12	12	6.879F 00	1.419F 11	9.4125 00
12	13	6.879F 00	1.506F 01	9.9905 00
12	14	6.879E 00	1.505F 01	1.058F 01
13	1	6.955F 00	3.902F 00	1.737E 00
12	?	6.955F 00	3.646F 00	1.666E 00
13	3	6.9555 00	3.847F 00	1.758F 00
13	4	4.955F 00	4.544F 00	2.0765 00
12	5	6.955F 00	6.232F 00	2.849F 00
12	5	6.955E 00	8.305F 00	3.795F 00
13	7	6.9555 00	9.855E 00	4.5035 00
12	Q	6.9555 00	1.147F 01	5.239E 00
13	Ġ	6.9555 00	1.382F 01	6.316E 00
12	10	6.955F 00	1.685F 01	7.699F 00
įz	11.	6.9555 00	1.843F 01	8.423F 00
13	12	6.9555 00	2.090E 01	9.5525 00
13	13	6.955F 00	2.239F 01	1.023F 01
17	14	6.9555 00	2.403F 01	1.0985 01



RUN	GAGE	Μœ	P	P/P co
14	1	6.798F 00	4.257F 00	5.809F 00
14	?	6.798E 00	3.749F 90	5.1165 00
14	3	6.798F 00	3.963F 10	5.409F 00
14	4	5.798F 00	4.519E 00	6.167F 00
14	5	6.7985 00	5.750E 00	7.847E 00
14	6	6.798F 00	7.434F 00	1.0155 01
14	7	6.798F 00	8.471F 00	1.156F 01
14	Я	6.798E 00	9.1006 00	1.242F 01
14	G	6.799F 90	1.104F 01	1.507F 01
14	10	6.798F 00	1.261E 01	1.7218 01
7.4	11	6.798F 00	1.353E 01	1.946E 01
14	12	6.798F 00	1.482F 01	2.0235 01
14	13	6.798F 00	1.520E 01	2.074F 01
14	14	6.798F 00	1.592F 01	2.173E 01
15	1	6.868F 00	9.691F 00	6.370F 00
15	2	6.868F 00	8.085E 10	5.315F 00
15	3	6.868F 00	8.589F 00	5.646F 00
j s	4	6.8685 00	9.399F 00	6.178F 00
15	5	6.868E 00	1.156F 01	7.599E 00
15	6	6.868F 00	1.449F 11	9.527F 00
15	7	6.868F 00	1.718F 01	1.1295 01
15	я	6.868F 00	1.836F 01	1.207F 01
15	•	6.868F 00	2.146E 21	1.411F 01
15	10	6.868E DO	2.499F 31	1.643F 01
15	7.7	6.868F 00	2.736E 01	1.7995 01
15	1?	6.8685 00	2.996F 01	1.970F 01
75	1.3	6.968F 00	3.095E 01	2.034E 01
15	14	6.868F 00	3.302F 01	2.171F 01
16	2	6.956F 00	1.275F 01	5.853F 00
16	3	6.9565 00	1.250E 01	5.7425 00
1.6	4	6.956F 00	1.411F 01	6.479E 00
16	5	6.956E 00	1.761E 01	8.0856 00
16	5	6.956E 00	2.217E 01	1.018F 01
16	7	6.9565 00	2.612F 01	1.199F 01
16	8	6.9565 10	2.714E 01	1.246F 01
16	?	6.956F 00	3.284F 01	1.509F 01
16	12	6.956E 00	3.815E 01	1.752F 01
16	11	6.9565 00	4.073F 01	1.870E 01
16	12	6.956E 00	4.530F 01	2.080E 01
16	13	6.956E 00	4.642F 01	2.13?E 01
4 %	14	6.956F 00	4.890F 01	2.246E 01



Table IV (CONCLUDED)

RUN	GAGE	Moo		Р		P/P a	
17	1	6.868F	10	4.617F	90	3.083E	ÇO
17	•	6.868F		4.587F		3.063F	00
17	3	6.868E		4. 943F	20	3.234E	0.0
17	4	6.868F		5.424F	0.0	3.627E	00
17	5	A.RERE C		7.586E	ÚÜ	5.066E	00
17	5	K. 9685 (8.968F	20	5.989E	0.0
1.7	7	6.868F		1.031E	21	6.885F	ÇC
17	я	6.868E (1.1915		7.954E	00
17	9	6.868F		1.427E		9.528F	2
17	10	6.RARE		1.682F	21	1.123F	01
17	11	6.8685		1.923F		1.284F	
17	12	6. 86 BF		2.117F		1.414F	
17	13	6.868F		2.333E	01	1.558E	01
17	14	6.868F		2.366F		1.580F	

Table V RUN SCHEDULE AND TEST CONDITIONS FOR THE AXISYMMETRIC MODEL TESTS

RUN NO.	10	20	۱,	22	٤,	54	25	98
४	C • C	0.0	c c		۲.	c.	0	Ċ
e	c c	C.	•	C.	•	•	•	•
ø	ر د د	C.	ر ن• ن		0.0	•	•	0.0
¥	17¢1.	<u>.</u>	3556.	.134F O	.220E	390F	.631E	4491F
م	477£	u	. 258F	. 975F O	¥.	.063F	.293E	3960.
±°	1.6435 07	1.662E 07	3.719E 07	3.917E 07	1.704F 07	1.870F 97	1.199F 07	1.101E 07
) <u>-</u> C	U.	u.	152E	.364F 0	щ	92 PF	.895F	.741E
₹	1.1135 01	u.	.752F	. 558E 0	Œ.	.137F	.777F	.887E
0 8	C	u.	4 COE	.617E O	T.	-0C4F	.709F	.516F
8	0.82E 9	ш.	3160°	STAF O	1 1 1 2	156F	. 525E	363E
8	د	1	-367E-	.978E-0	3.F-	-409E-	.584E-	-447F-
8	. 016E n	.024F	.571F	.249F O	. 579F	.183E	.711F	.067F
8	257F-0	.221E-	-300E-	-9226.	-386E-	-744F-	-716F-	.506E-
\mathcal{U}_{∞}	-932F-0	l L	-477E-	0-3019 *	-9040.	-3057.	-278E-	.145E-
Re/FT	C	-765E	* 172E	o appa.	.783E	.074E	.212E	.943E
<u>a</u> °	1.880F 01) E	. 388F O	نفا +	-047E	.237E	4 E
<u>,</u>	C	י.נו	5565	.620F 0	.554F	132F	.029E	.658E
Ę.	0-3705.	u:	-40 to	13951.	-388F.	- 635E-	.692E-	.512E-
*2\	Ċ	I L	i L	-966F-	.654E-	-566E-	-925F-	-983E-
±³	0 318C.	.231	375	0 3E16.	219E	-231F	.195F	.195E
·_3	5 300E 02	ц	Įi.	SEGE O	.340F	386F	.320F	.320F
Pts	160.	1.9345-05	0-37	<u>0-346</u> -	-934F-	-984F-	.868E-	.934E-
NOSE	SHARP LEADING	EDGE HOLLOW CYL!	INDER					1

Table V (CONCLUDED)

RUN NO.	7.0	5.8	66	vk	3.1	32	33
४	0.0		Ċ,	•	•	•	c.
Ŀ	C • C		•	c • c	•	•	0.0
æ	ر د			c c		0.0	•
 Z (2.54FF OF	4.875F	306K.	O HOLE	.842E	344E	.912E
o.	4.490F 03	1.9395	.1215	.122E C	.016E	.857E	.231F
≖°	1.1335 07	3.551E	.564F	Ç.	481F	•366E	.593E
-°	1.932 03	4.937F	4556°	.552F n	.854E	.723F	3266°
. 8	7.000F 01	4.742E	.792F	C JEIR.	.756F	.785E	.786E
e D	4. 596F 03	7.997E	718F	. 277E O	9176.	793F	.050E
Ť B	1. 273F no	5.850E	9804F	.246F O	.722E	492F	3658.
8	5.0500-01	3.767E-	.785F-	-382F-	-90.0E-	.593E-	-91F-
8	2.258PT C1	1.196E	₹ £ 1 ₹ •	0 7819.	.252F	.158E	.575F
8	3.091F-04	5.385E-	126F-	J-HROF.	- 740E-	-400E-	-145E-
η_{∞}	1.1535-07	4.104E-	-3770°	-047F-0	-31E0.	-917P.	-104E-
Re/FT	1.23AF 97	1.049E 06	2,215F 06	3.801E 06	1.130F 06	1.095 06	2.245E 06
<u>.</u> 0	4.15AF 01	2.271F	777F	. 987F O	377F.	.195E	3168.
*_	6.767F n2	1.576	.579E	.26AF 0	.551E	-511F	.589E
į	4.5638-07	9.004F-	-3210.	. 316F-0	-925E-	-797F-	-344D.
*2 ∧	4.965F-01	9.515E-	-4602E-	.051F-0	-5115°	-518E-	-501E-
Ŧ.	3. 190F 06	3.201E	-201E	.207F 0	.189E	199₽.	.201F
⊢3	5.310E 02	5.330F	-330F	346F Ω	310F	.320E	.330E
P _{ts}	1.0345-95	1.9345-	1	.934F-n	014	-934E-	-34E6
NOSE	SHARP LEADING	EDGE HOLLOW CYLI	NDER		BLUNT		



Table VI
AXISYMMETRIC MODEL SKIN FRICTION DATA

RUN	GAGE	Mac	$\boldsymbol{\gamma}$
10	1	1.113F 01	6.774E-03
10	16	1.113F 01	9.455E-02
10	3	1.113F 01	1.463E-02
Į٩	4	1.113F 01	1.7876-02
10	5	1.113F 01	2.341F-02
10	6	1.113E 01	3.129F-02
10	7	1.113F 01	3.788F-02
10	я	1.113F 01	4.878E-02
10	9	1.113E 01	7.681F-12
10	12	1.1135 01	1.523E-01
0	1 3	1.1135 01	2.929E-01
20	1	1.1125 01	7.135E-03
50	16	1.112F 01	9.411E-02
SU	3	1.112F 01	1.473E-02
ŜΟ	4	1.112F 01	1.733E-02
20	5	1.112F 01	2.344F-02
20	5	1.112F 01	3.216E-02
20	7	1.1125 01	3.912F-02
20	8	1.112F 01	4.981F-02
20	3	1.112F 01	7.944E-02
ŠÚ	11	1.1125 01	1.178E-01
20	12	1.112F 01	1.493F-01
20	13	1.112E 01	2.939E-01
50	15	1.1125 01	9.085E-01
21	1	9.7525 00	4.6455-03
21	1.5	9.752F 10	2.027F-01
21	3	9.752F 00	3.116E-02
21	4	9.7528 00	4.291E-02
21	5	9.752E 00	5.688E-02
21	7	9.752E 00	7.482F-02
21	વ	9.752F 00	1.115E-01
21	9	9.7525 00	1.809E-01
21	11	9.752F 00	1.8976-01
21	12	9.752F 10	2.794F-71
21	ĮЗ	9.752F 00	6.783E-01



RUN	GAGE	Moo		~
22	1	9.5685	29	3.204F-03
22	1.5	9.5685	20	1.4335-01
22	3	9.5685	20	2.193F-02
22	4	9.568E	20	3.004E-02
3.3	5	9.568F	0.0	4.012F-02
2?	6	9.5685	0.0	9.0435-02
22	7	9.5685	20	5.835F-02
22	8	9.568E	90	7.4255-02
22	9	9.568E	99	1.31CE-01
22	11	9.5685	10	1.787F-01
22	12	9.568F	ÜΩ	S. 269E-01
22	13	9.5685	20	5.042E-01
23	}	1.127E	21	7.785E-03
23	16	1.127F	Oι	1.382F-01
53	3	1.1275	01	1.6606-02
23	4	1.1275	91	2.174F-02
23	5	1.1275	ា។	3.2106-02
23	6	1.1275	01	4.820E-02
23	7	1.1275	0.1	5.935F-92
23	Я	1.1275	\cap 1	7.078E-02
23	q	1.127F	21	1.118E-01
23	11	1.1275	ሳኒ	1.613F-01
23	12	1.1275	71	2.138E-01
23	13	1.1275	1 1	3.965F-01
23	וְק	1.127E	71	1.129F 00
24	1	1.1375	01	1.435F-02
24	15	1.1375	0.1	1.841F-01
24	3	1.1375	0.1	1.984F-02
24	4	1.1375	٦ <u>۱</u>	2.417E-32
74	5	1.1375	7.1	4.166F-02
24	٨	1.1375	21	6.991F-02
24	7	1.1375	0.1	6.065E-02
24	9	1.1375	$^{\circ}1$	8.537F-02
24	G	1.137F	21	1.3985-11



RUN	GAGE	Maa	γ
25	1	7.777F 00	7.613F-03
25	16	7.777E 00	4.050F-02
25	3	7.777E 00	9.278F-03
25	4	7.7775 00	1.027F-02
25	5	7.7775 00	1.253E-02
25	6	7.777F 00	1.904E-12
25	7	7.7775 00	2.243F-02
25	3	7.777E 00	2.634F-02
25	q	7.777F 00	4.112F-02
25	11	7.777E 00	5.076F-02
25	12	7.777F 00	5.768F-02
25	13	7.7775 00	9.9495-32
25	14	7.777E 00	4.491F-01
26	1	7.8875 00	1.0456-02
26	1.6	7.887E 00	7.253F-02
26	7	7.887F 00	1.334F-02
5.V	4	7.8875 00	1.529E-02
24	5	7.887E 00	2.C66E-92
26	6	7.8875 00	2.692F-02
26	7	7.8875 00	3.384E-02
26	я	7.9875 00	4.103F-12
26	G	7.8875 00	6.005E-02
56	11	7.8875 00	8.067E-02
26	13	7. 887F 00	9.683F-02
36	13	7.887F 00	1.547F-21
26	14	7.887F 00	1.311E 00
26	15	7.987# 00	1.458F 10
27	1	7.980= 00	1.658E-02
27	1.6	7.9805 00	1.543F-01
27	3	7.9805 00	2.1195-02
27	4	7.980= 00	2.763F-02
27	5	7.990F 00	3.534E-02
27	6	7.9805 00	4.660E-02
27	7	7.980F 30	6.3845-02
27	8	7.980F 00	8.130F-02
27	9	7.980E 00	1.257E-01
27	11	7.9805 00	1.624F-01
27	12	7.9805 00	1.899F-01
27	דן	7.9805 00	3.464E-01
27	14	7.980F 00	3.076E 00
27	15	7.980F 00	3.618E 00



Table VI (CONCLUDED)

RUN	GAGE	Moo	Ţ
28	1	6.742F 00	1.585F-02
28	16	6.742E 00	1.005E-01
28	7	6.742F 00	2.473E-02
28	4	6.742E 00	2.624F-02
28	5	6.742F 00	2.9C6F-02
28	5	6.742F 11	4.860E-02
29	7	6.742E 00	5.307F-02
28	g	6.7425 00	5.811F-02
28	g	6.742E 00	8.910E-02
28	11	6.742F 00	1.335E-01
28	12	6.742F 00	1.413F-01
28	13	6.742E 00	2.629E-01
29	7	6.792F 00	3.336E-02
20	1.5	6.7925 00	1.730E-01
20	3	6.7925 00	3.548F-02
20	4	6.792F 00	3.663F-02
29	5	6.792F 00	4.154F-02
29	5	6.792E 11	6.4146-02
29	7	6.792F 00	7.974E-02
50	Я	6.792F 00	9.1105-02
29	- CI	6.792F 00	1.449E-01
29	1]	6.7925 00	2.274E-01
20	12	6.792F 00	2.7196-01
20	13	6.792F 00	4.706F-01
20	14	6.792F 00	2.968F 00
29	15	6.792F 00	3.169F 00
30	1	7.9135 00	6.116F-03
30	16	7.9135 00	3.785E-02
30	·3	7.8135 00	8.43CE-03
30	4	7.813E 00	9.273F-03
30	5	7.8135 00	1.208E-02
30	5	7.8135 00	1.2255-02
30	7	7,9135 00	1.820F-02
30	q	7.813F 00	2.095E-02
30	:)	7.813E 00	3.049F-02
30	11	7.813E 00	4.423E-02
30	12	7,813F 10	4.5125-02
30	14	7.813F 00	4.452E-01
30	15	7.813F 00	6.0425-01



Table VII
AXISYMMETRIC MODEL HEAT TRANSFER DATA

RUN	GAGE	ďav	RUN	GAGE	qav
10	1	3.9895	23	1.	5.1905 00
10	2	9,1515	23	2	1.150F 01
10	3	1.147E	23	3	1.5315 01
Įο	4	2.3815	23	4	3.4215 01
19	5	3.853F	23	5	6.424F 01
ļο	6	6.789F	23	6	1.049E 02
₹ □	7	1.7235	23	7	1.350= 02
			23	13	2.151F 02
			23	G	3.145F 02
			23	17	3,442F 12
20	1	4.3945	24	1	7.676E 00
20	2	9.5835	24	?	1.747E 01
20	3	1.2285	24	3	2.919E 01
20	4	2.5CAE	24	4	4.9325 01
20	5	4.1985	24	5	9.288E 01
20	5	6.730F	24	6	1.497F 02
20	7	1.060E	24	7	2.230= 02
20	Q	1.609F	24	Я	3.511F 02
3.0	Ġ	2.280F	24	J	4.2835 02
3.0	ויו	2.773F	24	רו	4.302F 02
21	1	4.186F	25	1	2.4165 00
21	2	3.477F	25	2	5.151F 00
21	3	4.739F	25	3	5.71 RE 00
21	4	8.856F	25	4	1.028F 01
21	5	1.5295	25	ጓ	1.6475 01
21	6	2.4245	25	5	2.414F 01
21	7	3.815F	25	7	3.231E 01
21	9	K.ORGE	25	9	4.824F 01
21	7	8.617E	25	9	6.992E 01
21	IJ	1.006F	25	10	8,7305 01
22	1	3.434F	26	l	3.1305 00
52	2	3.146F	26	2	6,491E 00
22	3	3.596F	26	3	8.179F 00
22	4	6.5565	26	4	1.4125 01
22	5	1.114F	26	5	2.015E 01
22	5	1.657F	26	5	3.067E 01
22	7	2.578F	26	7	4,3305 01
22	9	4.325F	26	9	6.035F 01
22		6.640F	26	Ġ	0.030E 01
22	10	8.572E	26	רו	1.0715 02



Table VII (CONCLUDED)

RUN	GAGE	qav		RUN	GAGE	qav	
27	1	5.017F	10	31	1.	3.596F	20
27	,	1.2555	01	31	2	6.1655	90
27	3	1.687F	21	31	3	1.3655	71
27	4	2.962E	21	31	4	2.234F	O.I.
27	5	4.54RF	11	31	5	2.965F	71
27	6	6.534F	21	31	5	4.541F	01
27	7	8.737F	01	31	7	5.2445	7
27	3	1.2755	02	31	9	7.711F	01
クフ	Ĵ	1.680F	0.2	31	Q	9.5425	21
27	17	2.036F	02	3]	10	1.439F	77
28	1	1.763E	01	32	1	3.0555	ŋn
28	2	2.930F	01	32	2	6.414E	0.0
28	3	3.202F	01	32	3	1.001F	ΟŢ
28	4	5.761F	01	32	4	1.8925	21
5 b	5	7.607E	~ 1	32	5	2.994	~ 1
28	4	1.235F	72	32	5	4.2145	0.1
28	7	1.790F	92	3.2	7	4.942F	01
28	9	2.6935	72	32	9	6.5855	ÜΙ
28	C	3.4565	02	32	Ü	8.8705	0.1
28	10	4.841F	12	32	10	1.3585	02
20	1	2.771F	^1	32	1	2.1015	<u>^1</u>
29	?	4.7085	^ <u>1</u>	33	2	2.434F	7
20	3	5.5715	01	33	3	2.213F	7.
50	4	9.502F	01	33	4	4.4045	21
20	5	1.4165	1 2	33	5	5.355E	71
20	- 6	2.114F	0 .5	33	5	1.1925	02
20	7	3.020F	02	33	7	1.3465	0.2
29	8	4.337F	72	33	8	5.013E	0.8
20	3	5.801E	0.2	33	9	2.088E	72
29	17	7.363F	12	33	10	4.191E	02
30	1	1.7635	00				
30	2	3.437F	20				
30	3	4.150F	1 0				
30	4	7.6075	20				
30	5	1.0355	21				
30	4	1.6955	01				
30	7	2.413F	1				
30	Q	3.443F	01				
30	a	4.619F	^1				
30	10	6.015F	71				



Table VIII
AXISYMMETRIC MODEL PRESSURE DATA

RUN	GAGE	Мω	P	P/P co
1º	1.	1.1135 01	1.493E-01	1.2755 00
19	15	1.113F 01	2. GADE 00	1.759F 01
ľα	2	1.113F 01	2.564F-01	2.189E CC
10	4	1.1135 01	3.511F-01	2.499E 00
19	8	1.1135 01	1.070F 00	9.133F 00
10	14	1.113F 01	2.167E 01	1.851F C?
20	1	1.1125 01	1.533F-01	1.2975 00
20	15	1.112F 01	2.069F 00	1.750F 01
20	3	1.112E 01	2.541F-01	2.151F 00
30	4	1.1125 01	3.564F-01	3.017F 00
20	5	1.1125 01	5.036F-01	4.263F 00
20	6	1.1125 01	6.234F-01	5.277F 00
20	7	1.1125 01	8.259F-01	6.990F 00
20	Ω	1.1125 01	1.077F 00	9.118F CC
30	a	1.1125 01	1.981F 00	1.6775 01
20	10	1.112F 01	3.82CF 00	3.233F 01
20	11	1.112F 01	7.267E 00	6.1515 01
20	12	1.1125 01	1.188E 01	1.006F 02
30	13	1.1125 01	2.073E 01	1.755F 02
Su	14	1.1125 01	2.208E 01	1.869F 02
21	1	9.7526 00	2.687F-01	1.140F 00
21	15	9.752F 00	3.627F OC	1.539F 01
21	3	9.75?F 00	4.962F-01	2.1055 00
21	4	9.752F 00	6.585E-01	2.794F 00
21	5	9.7525 00	9.081F-01	3.853F CC
21	6	9.752F 00	1.095E 00	4.648F 00
21	7	9.752E 00	1.439F 00	6.104F 00
21	8	9.7525 00	1.915E 00	9.124F 00
21	9	9.752F 00	3.199E OC	1.357F C1
21	10	9.752F 00	6.698E 00	2.842F 01
21	11	9.752F 00	1.166F 01	4.949F 01
21	1.2	9.752E 00	2.041E 01	8.661E 01
21	13	9.7525 00	3.401F 01	1.443F 02
21	14	9.752F CO	4.279F C1	1.816F 02



RUN	GAGE	Мω	P	P/P ထ
22	1	9.568E 00	2.146E-01	1.085E 00
22	15	9.5685 00	2.932F 00	1.432E 01
22	` ٦	9.56PF 00	4.048F-01	2.046F 00
22	4	9.5685 00	5.452F-01	2.756E 00
22	5	9.568E 00	7.692E-01	3.893F 00
22	5	9.568E 00	9.202E-01	4.651E CO
22	7	9.568F 00	1.193F 00	6.030F 00
22	9	9.568F 00	1.507E 00	7.616F 00
22	Ċ	9.5 <u>68</u> F 00	2.696F 00	1.363E 01
22	10	9.5685 10	5.093E 00	2.5745 01
22	11	9.568E 00	8.938F 00	4.467F G1
22	12	9.568E 00	1.456E 01	7.361F 01
22	13	9.568F 00	2.605F 01	1.3178 02
22	14	9.5685 00	3.428F 01	1.733E C2
23	1	1.1278 01	1.939E-01	1.036F 00
23	15	1.1275 01	3.114F 00	1.754F CI
23	3	1.1275 01	3.456F-01	1.9475 00
23	4	1.127F 01	4.4475-01	2.505E 00
23	5	1.1275 01	6.906E-01	3.891E CC
23	6	1.1275 01	8.7245-01	4.915E 00
23	7	1.127F 01	1.195E 00	6.731E 00
23	я	1.1275 01	1.557F 00	8.771E 00
23	0	1.1278 01	2.783E 00	1.5685 01
23	10	1.127F 01	5.996F 00	3.378F C1
23	11	1.127E 01	9.706F 00	5.4685 01
23	12	1.127F 01	1.653F 01	9.314F 01
23	13	1.127E 01	2.716E 01	1.530F 02
23	14	1.127F 01	2.885F C1	1.625F 02

RUN	GAGE	Мф	P	P/P ထ
24	1	1.137F 01	2.587E-01	1.074F 00
24	15	1.137F 01	4.460F 00	1.851F 01
24	マ	1.137F 01	4.621E-01	1.9185 00
74	4	1.137F 01	5.992F-01	2.487F 00
24	5	1.137E 01	9.081F-01	3.769F 00
24	4	1.137E 01	1.215F 30	5.043E CO
24	7	1.137F 01	1.612E 00	6.690E 00
24	9	1.137F 01	2.185F 00	9.0685 00
24	9	1.137F 01	3.908E 00	1.5915 01
24	1 ^	1.1375 01	8.354E 00	3.467E 01
24	1.1	1.137F 01	1.379F 01	5.725F C1
24	12	1.137F 01	2.391E 01	9.9245 01
24	13	1.1375 01	3.737E 01	1.551E 02
24	14	1.137F 01	3.900E 01	1.6195 02
25	15	7.777F 00	1.569E 00	9.907F 00
25	3	7.777F 00	2.726F-01	1.7215 00
25	4	7.777E 00	3.634E-01	2.294E 00
25	5	7.7776 00	4.971E-01	3.076F 00
25	5	7.777E 00	5.550F-01	3.505F 00
25	7	7.777F 00	6.953E-01	4.391E 00
25	8	7.777F 00	8.337F-01	5.2648 00
25	c)	7.777F 10	1.394E 00	8.804E 00
25	1 ^	7.7775 00	2.312E 00	1.460E 01
25	11	7.7775 00	3.691F 00	2.3315 01
25	12	7.777E 00	5.513F 00	3.481F 01
25	13	7.777E 00	9.656E 00	6.0975 01
25	14	7.7775 00	1.542E 01	1.0375 02
26	1	7.987F 00	2.585F-01	1.220F 00
25	35	7.987F 00	2.522F 00	1.031F 01
26	3	7.887E 00	4.411E-01	1.803E 00
26	4	7.887F 00	5.519F-01	2.256E 00
26	5	7.887F 00	7.764F-01	3.173E 00
26	6	7.887E 00	8.982E-01	3.671E 00
26	7	7.8875 00	1.125F 00	4.596E 00
26	q	7.887E 00	1.375E CC	5.618E 00
26	C	7.887E 00	2.214E 00	9.0505 00
26	10	7.887F 00	3.688F 00	1.507F 01
26	11	7.887E 00	6. 384E 00	2.568E 01
26	12	7.887E 00	9.214F 00	3.766F 01
26	13	7.887F 00	1.56BF 01	6.409F 01
26	14	7.887F 00	2.573E 01	1.052E C2



RUN	GAGE	M co	P	P/P 🕳
27	1	7.980F 00	6.045E-01	1.195E 00
27	15	7.9805 00	5.867E 00	1.1605 01
27	3	7.980E 00	8.649F-01	1.710F 00
27	4	7.980F 00	1.095E 00	2.164F 00
27	5	7,980F 00	1.576F 00	3.1156 00
27	6	7.980F 00	5.000E 00	3.952E 00
77	7	7.9806 00	2.564F 00	5.068F CC
27	3	7.980F 00	3.079E 00	5.086F 00
27	ú	7.9905 00	4.989E 00	9.862E 00
27	10	7.980E CO	8.610E 00	1.702F 01
27	11	7.980F 00	1.438F 01	2.842F C1
27	12	7.980F 00	2.121E 01	4.193F 01
27	13	7.980F 00	3.557F 01	7.030F 01
27	14	7.980E 00	5.947F 01	1.176F 02
28	1	6.742F 00	3.993F-01	1.062F 00
28	15	6.742E 00	2.939E 00	7,9155 00
ŠΒ	7	6.742F 00	5.830E-01	1.551F 00
28	4	6.742F 00	7.135E-01	1.898F CC
28	5	6.742F 00	9.620E-01	2.558E 00
28	4	6.742F 00	1.099F 00	2.924F 00
ŠВ	7	6.742F 00	1.371F 00	3.645F 00
20	3	6.742F 00	1.648E 00	4.3825 00
28	9	6.742F 00	2.799E 00	7.443F 00
28	1 ^	6.742F 00	4.568E 00	1.215F 01
28	11	6.742F 00	7.809E 00	2.077F 01
20	12	6.742F 00	1.051F 01	2.902F C1
2 A	13	6.742E 00	1.931E 01	4.870E 01
28	14	6.742F 00	3.250F 01	8.642F 01
29	1	6.792E 00	7.516F-01	9.655F-01
20	15	6.7925 00	5.770F 00	7.412F 00
ŠΟ	3	6.792F 00	1.116F 00	1.433F 00
50	4	6.7925 00	1.359E 00	1.746E 00
29	5	6.792F 00	1.819E 00	2.336E 00
29	6	6.792E 00	S.191E 00	2.686E 00
Şü	7	6.792E 00	2.667F 10	3.426F 00
50	ρ	6.792E 00	3.258E 00	4.185F 00
29	9	6.792E 00	5.413F 00	6.954E 00
50	11	6.792F 00	8.610E 00	1.106E 01
29 29	11 12	6.7925 00 6.7925 00	1.354E 01 2.003E 01	1.739F C1
50 50	13	6.792F 00	2.003F 01 3.524F 01	2.573F 01 4.527F 01
29	14	6.792F 00	5.769F 01	7.411F 01
r., "	. 7		7 € 1 12 71 3 %	1 1 7 1 L 2 1 / L

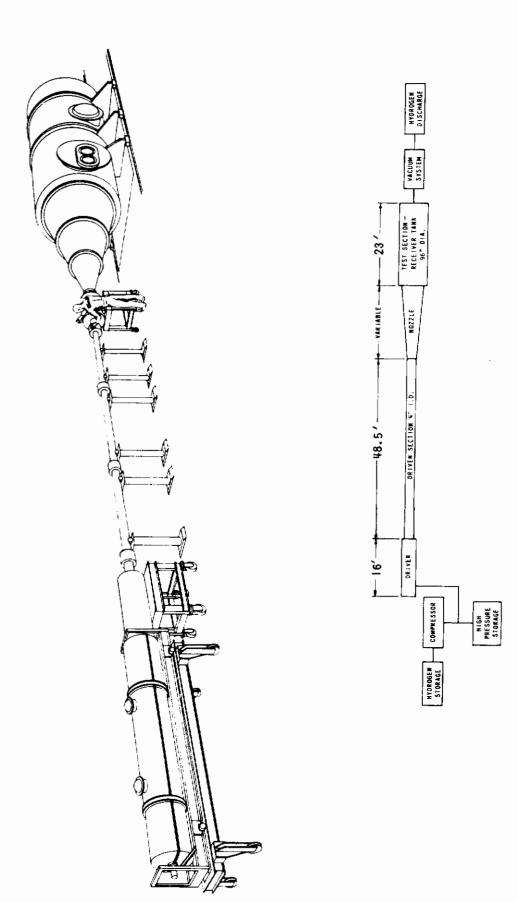


Table VIII (CONTINUED)					
RUN	GAGE	Mω	P	P/P _{co}	
30	1	7.8136 00	1.524F-01	1.103F 00	
30	15	7.813F 00	1.226F 00	8.868F 00	
30	7	7.813F 00	2.305E+01	1.668F 00	
30	4	7.813F 00	3.014F-01	2.181F 00	
30	5	7.813F 00	3.924F-01	2.839E 00	
30	6	7.9136 00	4.561E-01	3.300F 00	
30	7	7.913E 00	5.555F-01	4.0198 00	
30	.8	7.813F 00	6.905E-01	4.996F 00	
30	r	7.913E 00	1.128E 00	8.160E 00	
30	17	7.913F 00	1.835E 00	1.328F 01	
30	11	7.913E 00	3.006E 00	2.175E 01	
30	17	7,8135 00	4.397F 00	3.191F 01	
30	13	7.813F 00	7.390E 10	5.347F 01	
30	14	7.813F 00	1.278F 01	9.250F C1	
31	1	6.756E CO	4.7275-01	1.206F 00	
31	15	6.756F 00	1.321E 00	3.371F 00	
31	3	6.756E 00	4.817E-01	1.229E 00	
31	4	6.756E 00	5.082F-01	1.296F 00	
31	5	6.756F 00	6.105F-01	1.557F 00	
31	6	6.7565 00	6.393F-01	1.6315 00	
31	7	6.756F 00	7.932E-01	2.0245 00	
3]	3	6.756F 00	8.986E-01	2.292E 00	
31	J	6.756F 00	1.394F 00	3.557F 00	
31	IJ	6,756E 00	1.859F 00	4.743E 00	
31	11	6.756F 00	2.554E 00	6.516E 00	
31	12	6.7565 00	3.415E 00	8.711F 00	
31	13	6.756E 00	5.639E 00	1.439E 01	
31	14	6.756E 00	8.488E 10	2.165F 01	
32	1.	6.785F 00	4.329F-01	1.205E 00	
32	15	6.785F 00	1.240E 00	3.451F 00	
32	3	6.785F 00	4.199E-01	1.1695 00	
32	4	6.785E 00	4.648F-01	1.2945 00	
32	5	6.785E 00	5.280E-01	1.497F ^^	
32	6	6.785F 00	5.816F-01	1,6[9F 00	
32	7	6.785F 10	6.913F - 01	1.924F 00	
32	q	5.785E CO		2.2625 00	
32	Ġ	6.785F 00	1.185F 00	3.299E 00	
32	10	6.785F 00	1.691E 00	4.707F 00	
32	11	6.785E 00	2.478E 00	6.896F 00	
32	12	6.785E 00	3.090E 00	8.6025 00	
32	13	6.7855 10	4.918F 00	1.369F 01	
32	14	6.785E 00	7.799F 00	2.171E 01	
			53		



Table VIII (CONCLUDED)

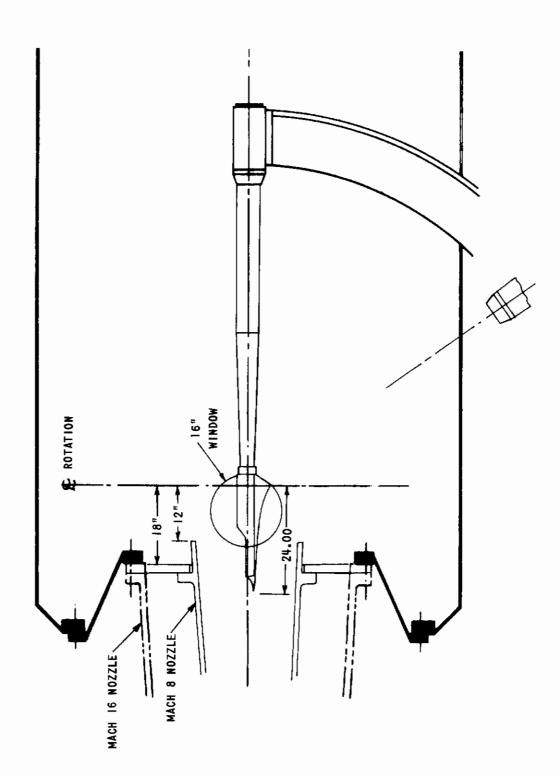
RUN	GAGE	Мω	P	P/P $_{\infty}$
33	1	6.786F 00	9.31CE-01	1.1655 00
33	15	6.786E 00	2.595E 00	3.248E 00
33	3	6.786F 00	9.518F-01	1.191E 00
33	4	6.786E 00	1.004F 00	1.256F 00
3,3	5	6.786F 00	1.224E 00	1.531F CO
33	6	6.786F 00	1.267E 00	1.5855 00
32	7	6.786E 00	1.562E 00	1.9556 00
33	Ω	6.786F 00	1.695E 00	2.121E 00
32	Q	6.786E 00	2.768F 00	3.464E 00
33	10	6.786F 00	3.678F 00	4.603E 00
32	1.1	6.786F 00	5.517F 00	6.904F 00
33	12	6.786F 00	6.410F 00	8.031E 00
33	13	6.786E 00	1.087E 01	1.361F 01
33	14	6.786F 00	1.558E 01	1.950F 01



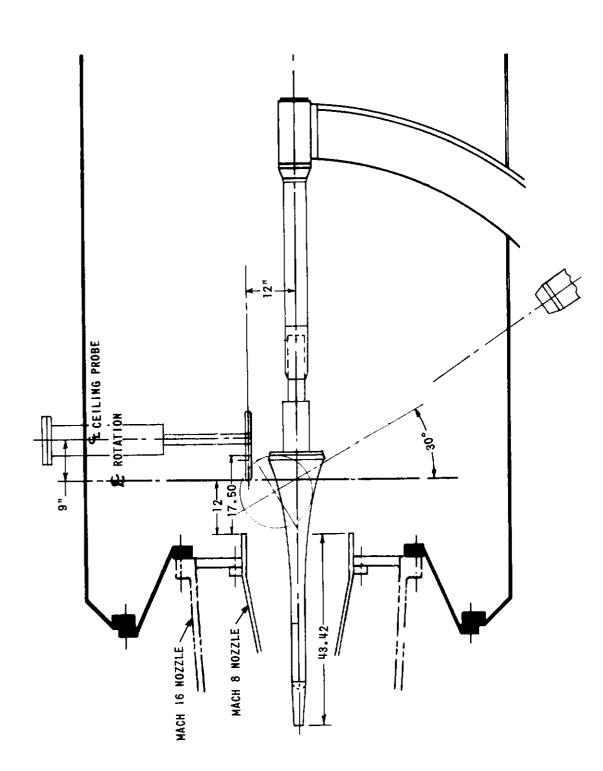
96" LEG HYPERSONIC SHOCK TUNNEL Figure 1. BASIC COMPONENTS OF THE CAL

3416

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INSTALLATION OF THE TWO-DIMENSIONAL MODEL IN THE CAL 96" LEG HYPERSONIC SHOCK TUNNEL Figure 2



INSTALLATION OF THE AXISYMMETRIC MODEL IN THE CAL 96" LEG HYPERSONIC SHOCK TUNNEL Figure 3

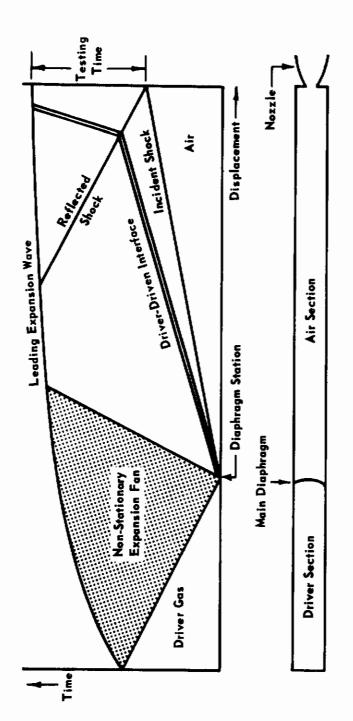


Figure 4 WAVE DIAGRAM FOR TAILORED-INTERFACE SCHOCK TUBE

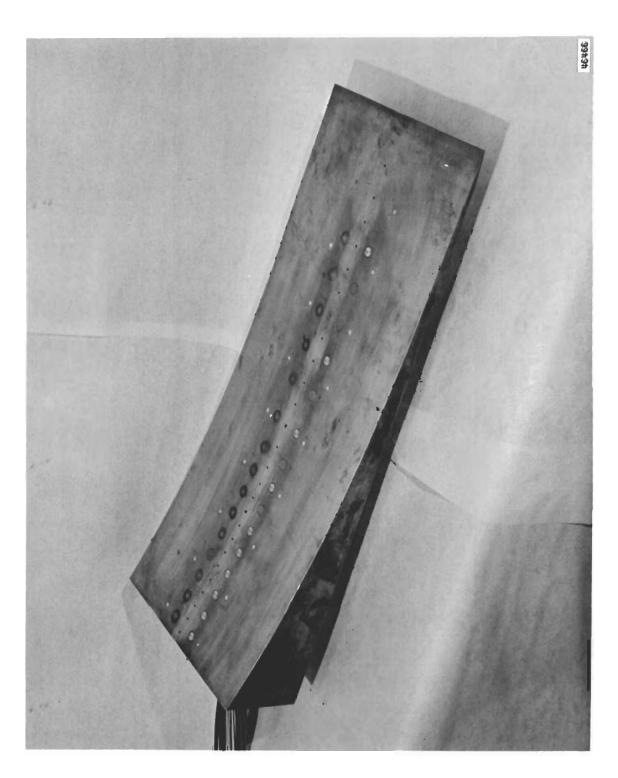
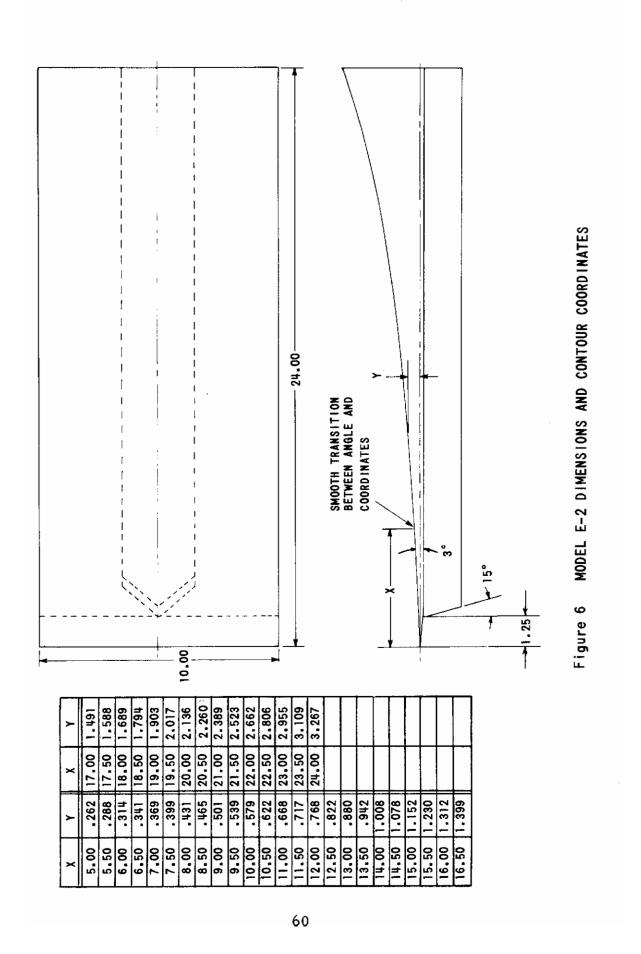


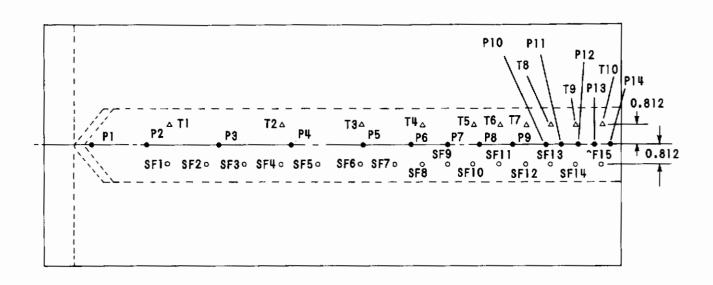
Figure 5 TWO-DIMENSIONAL MODEL, E-2

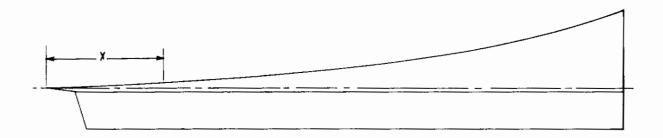
59











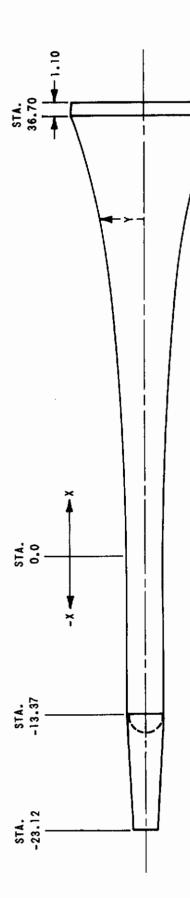
GAGE	Х	GAGE	Х	GAGE	Х
TI	5.25	Pi	2.00	SF1	5.25
T2	9.93	P2	4.31	SF2	6.81
Т3	13.25	Р3	7.31	SF3	8.37
T4	15.80	Р4	10.31	SF4	9.93
T5	17.92	P5	13.31	SF5	11.49
T6	18.98	P6	15.30	SF6	13.25
Т7	20.04	P7	16.76	SF7	14.69
T8	21.10	P8	18.12	SF8	15.80
T9	22.16	P9	19.48	SF9	16.86
T10	23.22	P10	20.84	SF10	17.92
		P11	21.52	SF11	18.98
		P12	22.20	\$F12	20.04
		P13	22.88	\$F13	21.10
		P14	23.56	SF14	22.16
				SF15	23.22

Figure 7 MODEL E-2 INSTRUMENTATION LOCATIONS



Figure 8 AXISYMMETRIC MODEL

62



×	Υ	X	٨	×	٨	×	٨
 -23.12	6h6.	20.677	2.514	28.188	3,516	32.490	ll#*h
-13.37	1.500	21.396	2.590	28.510	3.571	33.100	#·576
0.0	1.500	22.072	2.665	29.109	3.679	33,508	£69°h
5.709	1.575	23.316	2.810	29.623	3.781	210.4E	158'h
10.381	1.747	24.426	2:952	30.148	3.880	34.588	5.050
13.008	1.890	25.420	3.087	30.601	3.973	35.082	5.245
 15.307	2.043	26.316	3.217	31.015	4.062	35,560	29†°S
17.326	2.200	27.121	3.340	31.570	₩.186	36.00౻	17.73
19.105	2.359	27.495	3.400	32.059	4,303	36,750	6.188

AXISYMMETRIC MODEL COORDINATES Figure 9

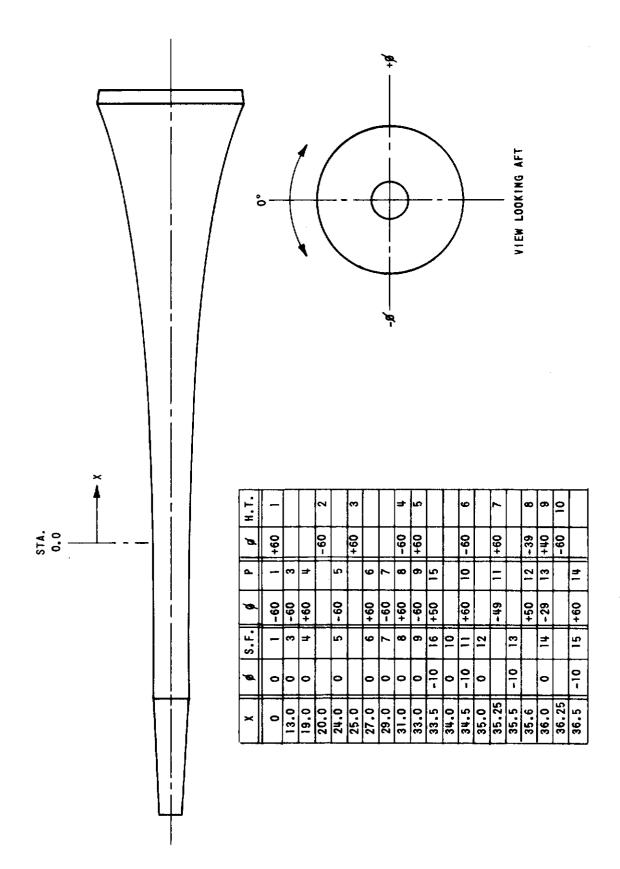


Figure 10 AXISYMMETRIC MODEL INSTRUMENTATION LOCATIONS



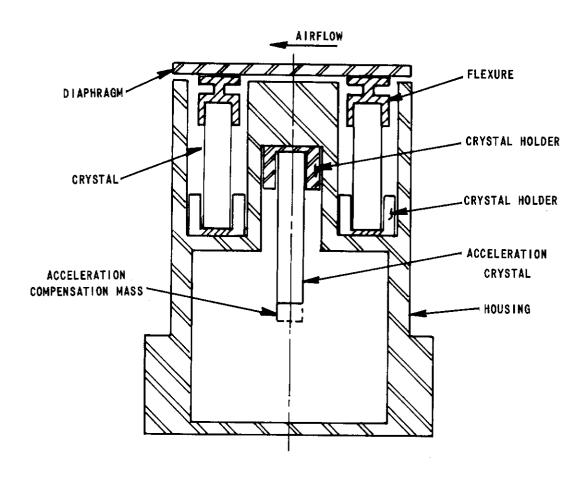
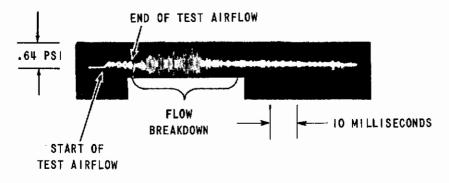
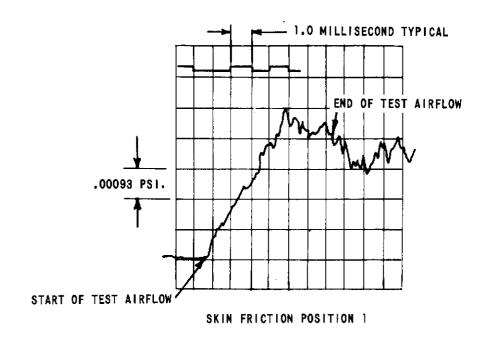


Figure 11 DRAWING OF SKIN FRICTION GAGE 25-38 AC



SKIN FRICTION POSITION 8

Figure 12 TYPICAL SKIN FRICTION AND HEAT TRANSFER GAGE RESPONSES
(a) TUNNEL FLOW BREAKDOWN - RUN 2



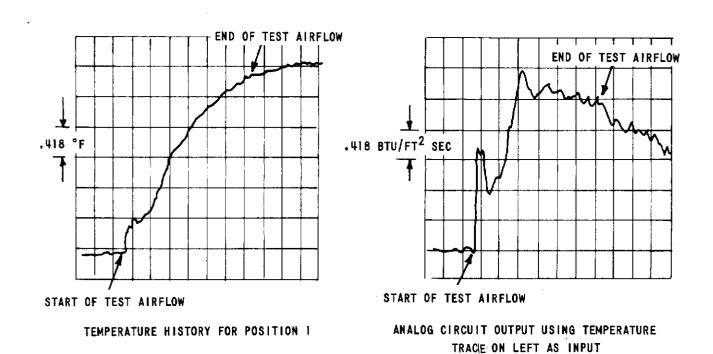
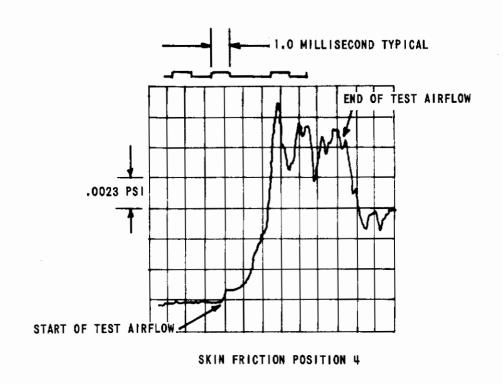
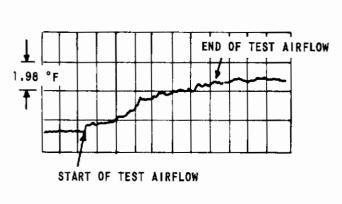
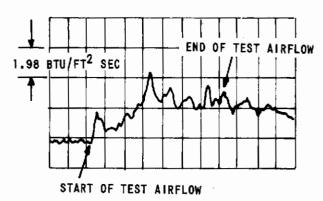


Figure 12 (CONTINUED) (b) LAMINAR BOUNDARY LAYER - RUN 1



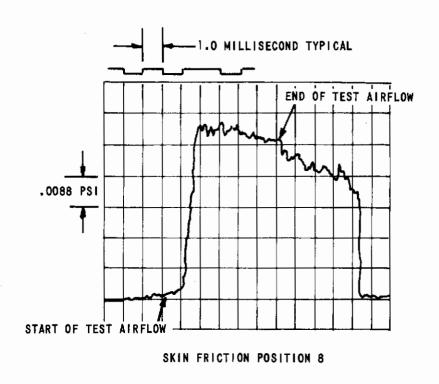






ANALOG CIRCUIT OUTPUT USING TEMPERATURE
TRACE ON LEFT AS INPUT

Figure 12 (CONTINUED) (c) TRANSITIONAL BOUNDARY LAYER - RUN 1



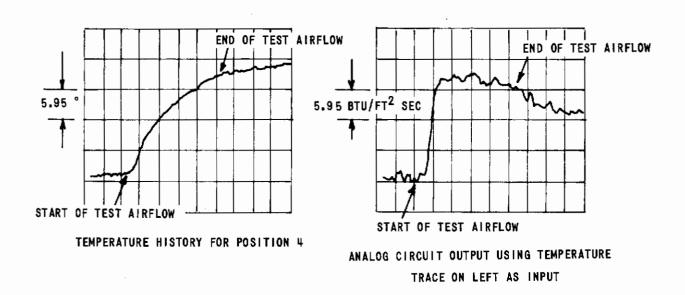


Figure 12 (CONCLUDED) (d) TURBULENT BOUNDARY LAYER - RUN 1

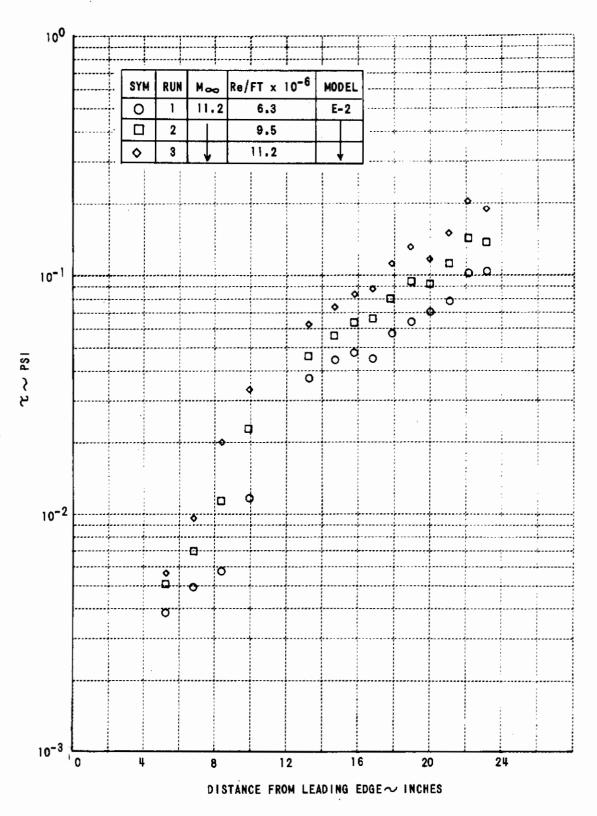


Figure 13 SKIN FRICTION DISTRIBUTIONS ON THE TWO-DIMENSIONAL MODEL (a) MACH NUMBER 11, ANGLE OF ATTACK = 0°



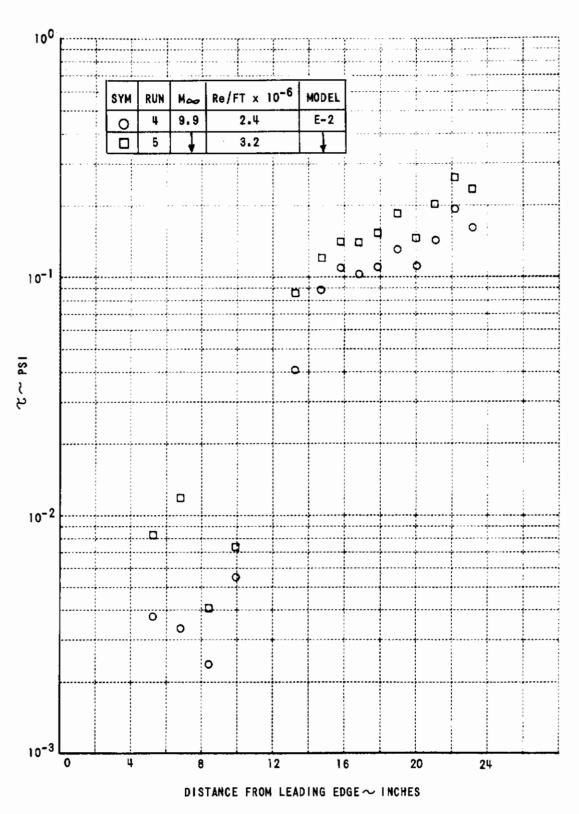


Figure 13 (CONTINUED) (b) MACH NUMBER 10, ANGLE OF ATTACK = 0°

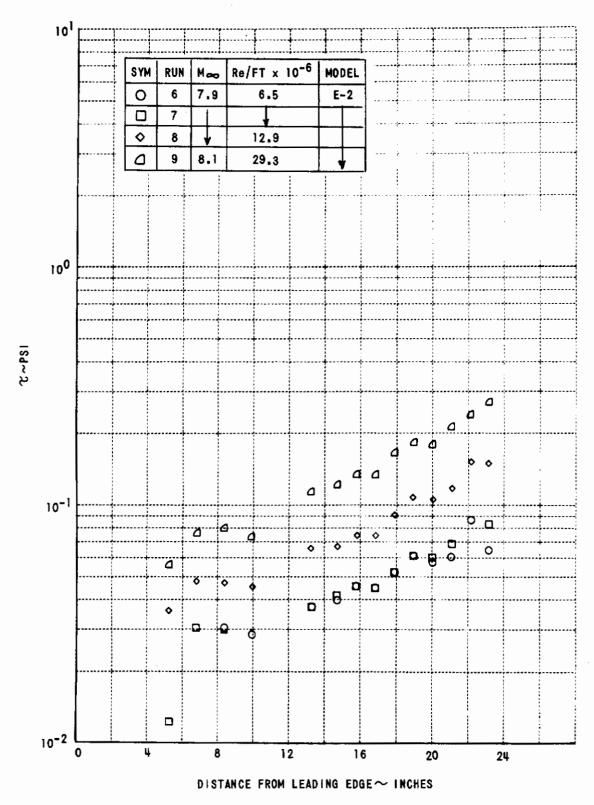


Figure 13 (CONTINUED) (c) MACH NUMBER 8, ANGLE OF ATTACK = 0°



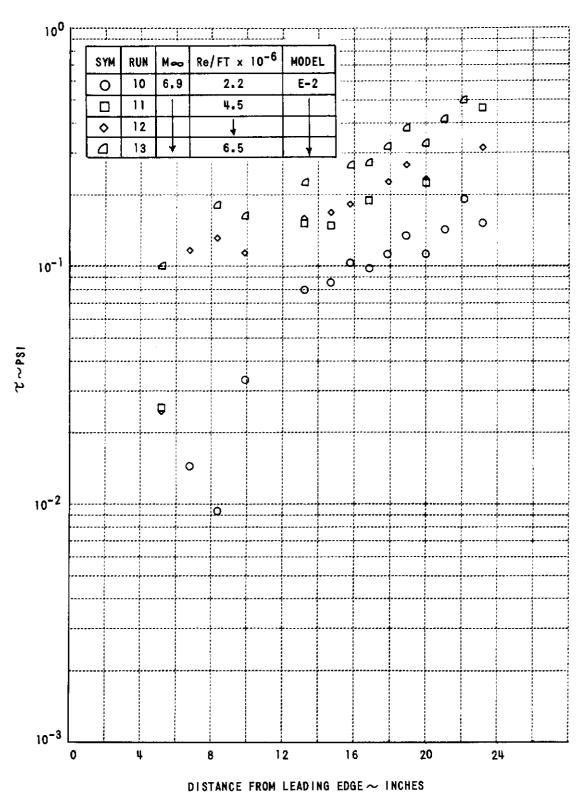


Figure 13 (CONTINUED) (d) MACH NUMBER 7, ANGLE OF ATTACK = 0°

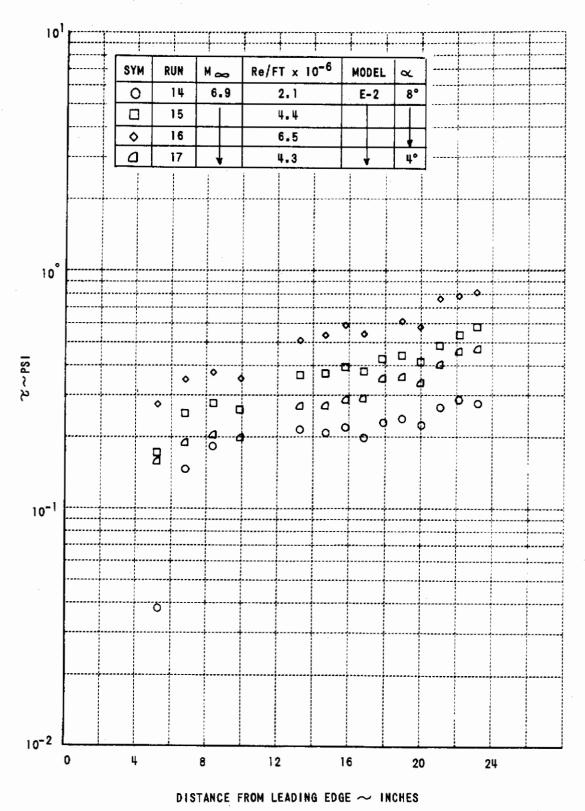


Figure 13 (CONCLUDED) (e) MACH NUMBER 7, ANGLE OF ATTACK = 4° , 8°



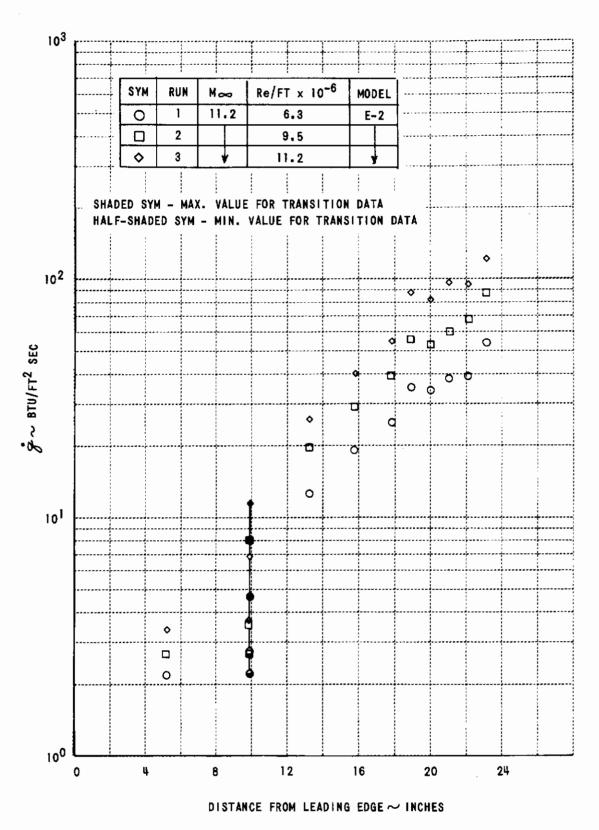


Figure 14 HEAT TRANSFER DISTRIBUTIONS ON THE TWO-DIMENSIONAL MODEL (a) MACH NUMBER 11, ANGLE OF ATTACK = 0°

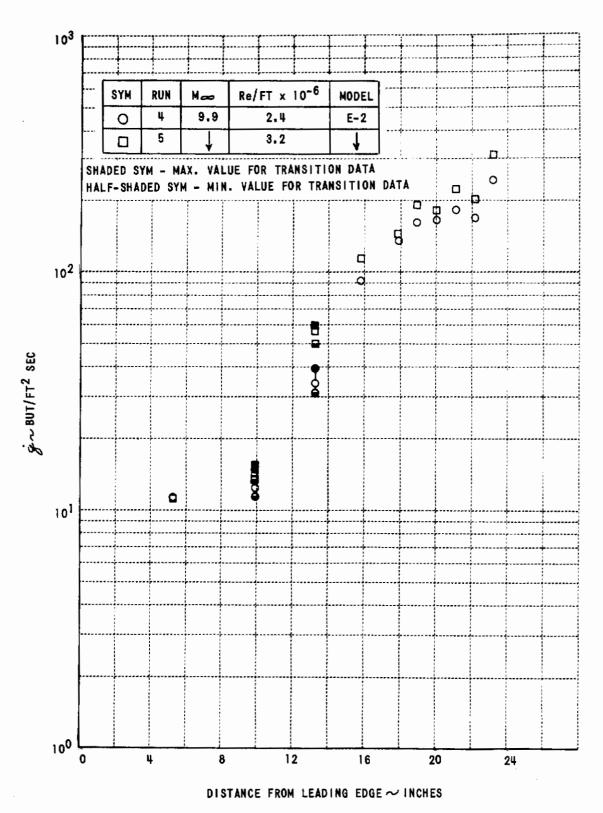


Figure 14 (CONTINUED) (b) MACH NUMBER 10, ANGLE OF ATTACK = 0°



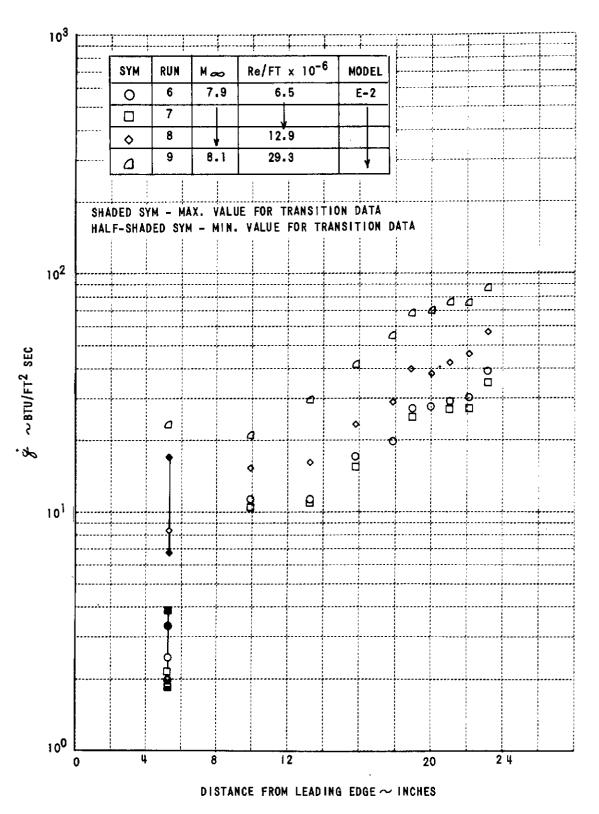


Figure 14 (CONTINUED) (c) MACH NUMBER 8, ANGLE OF ATTACK = 0°



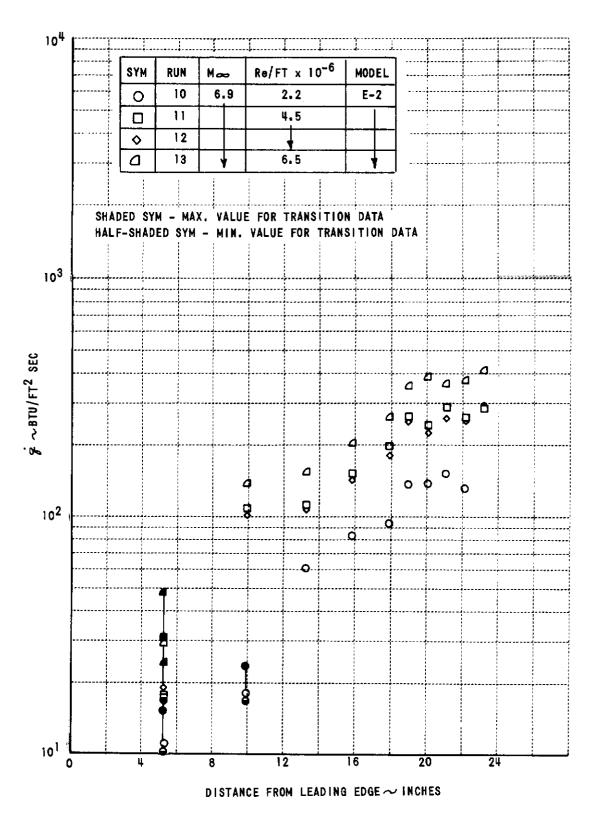


Figure 14 (CONTINUED) (d) MACH NUMBER 7, ANGLE OF ATTACK = 0°



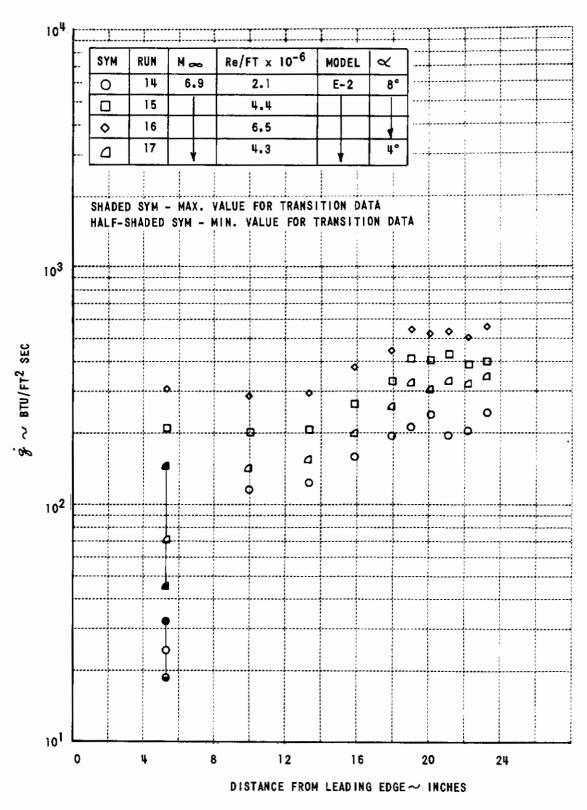


Figure 14 (CONCLUDED) (e) MACH NUMBER 7, ANGLE OF ATTACK = 4°, 8°

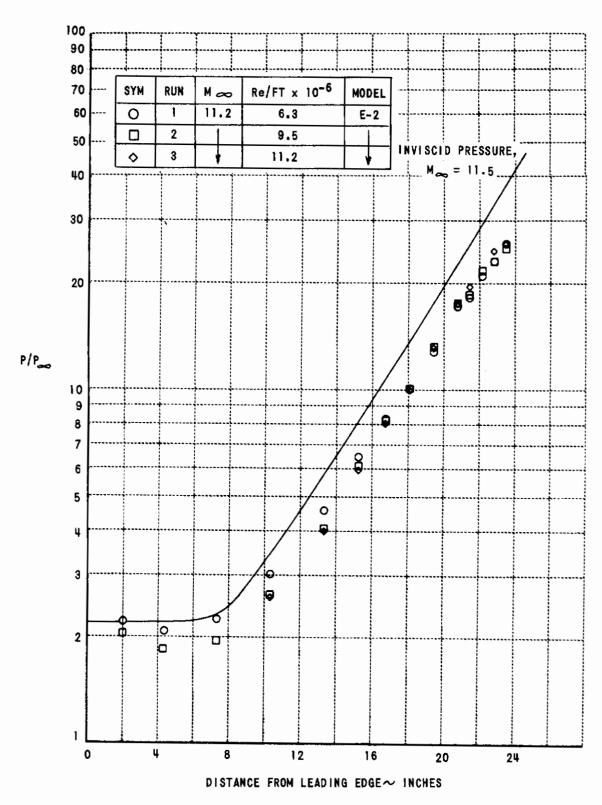


Figure 15 PRESSURE DISTRIBUTIONS ON THE TWO-DIMENSIONAL MODEL
(a) MACH NUMBER 11, ANGLE OF ATTACK = 0°



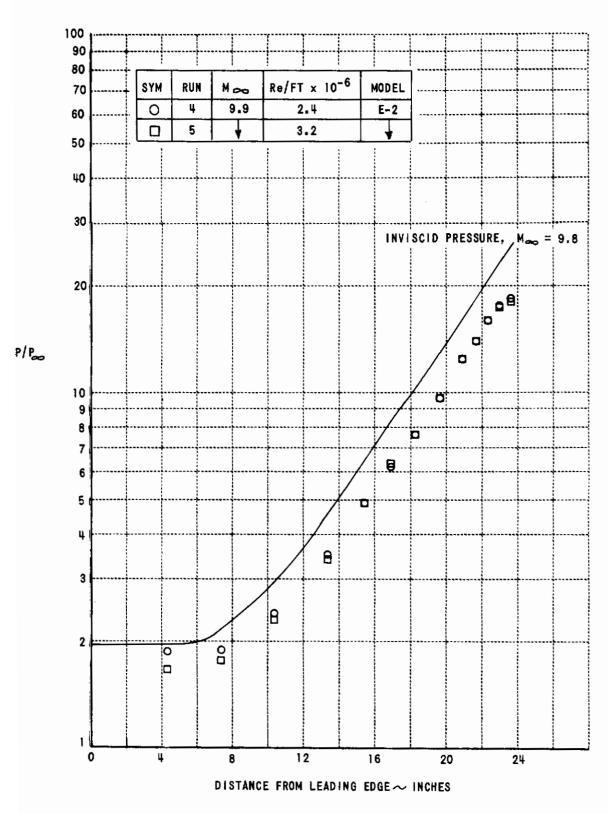


Figure 15 (CONTINUED) (b) MACH NUMBER 10, ANGLE OF ATTACK = 0°

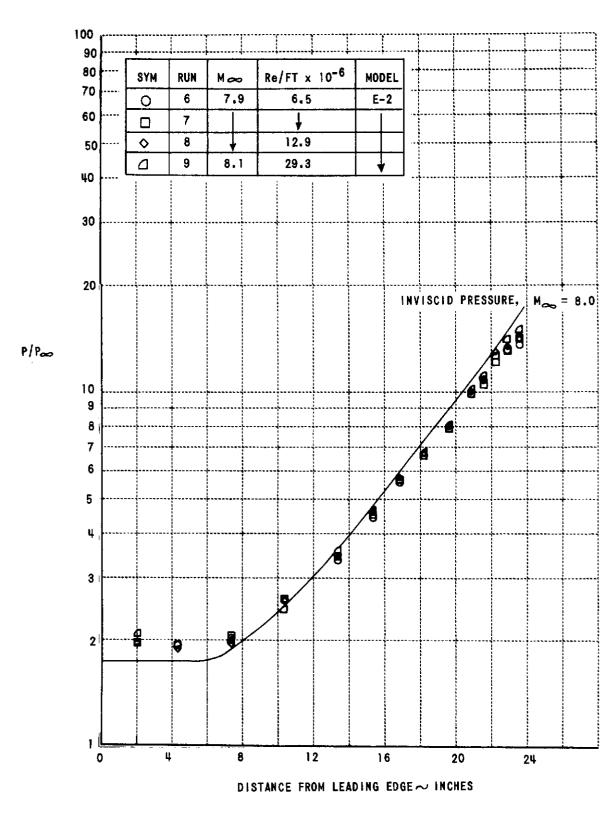


Figure 15 (CONTINUED) (c) MACH NUMBER 8, ANGLE OF ATTACK = 0°



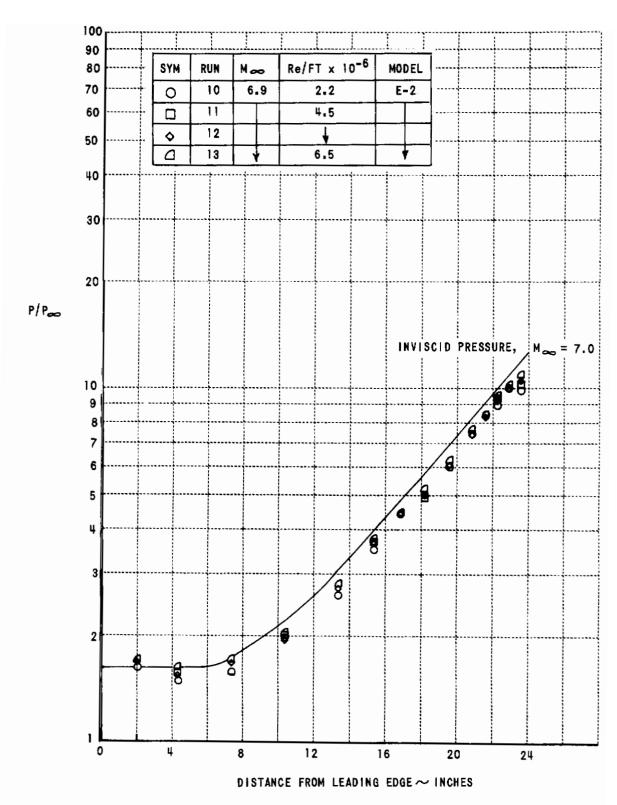


Figure 15 (CONTINUED) (d) MACH NUMBER 7, ANGLE OF ATTACK = 0°

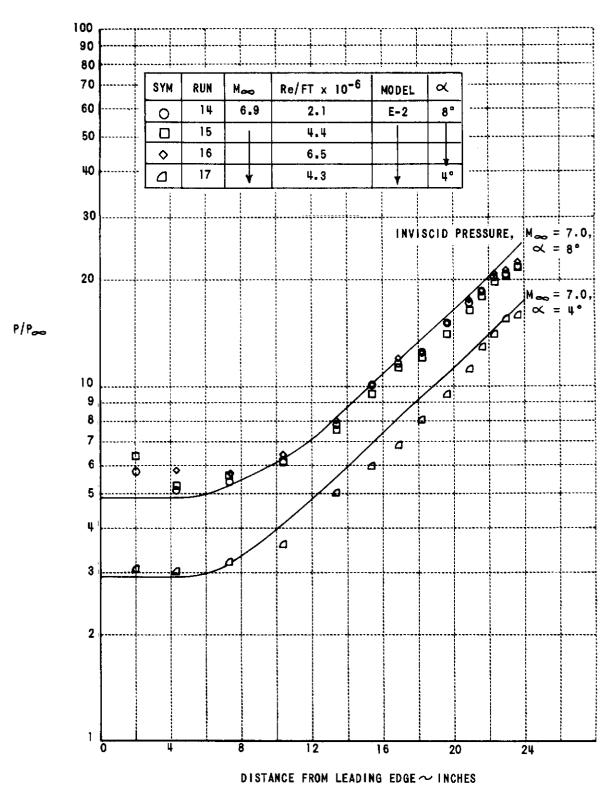


Figure 15 (CONCLUDED) (e) MACH NUMBER 7, ANGLE OF ATTACK = 4°, 8°

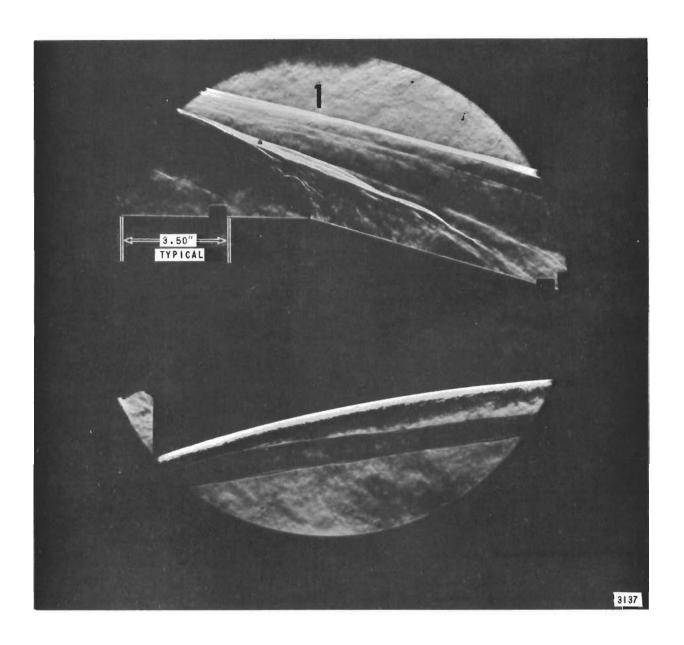


Figure 16 TWO-DIMENSIONAL MODEL FLOW PHOTOGRAPHS
(a) MODEL E-2 SCHLIEREN, RUN 1

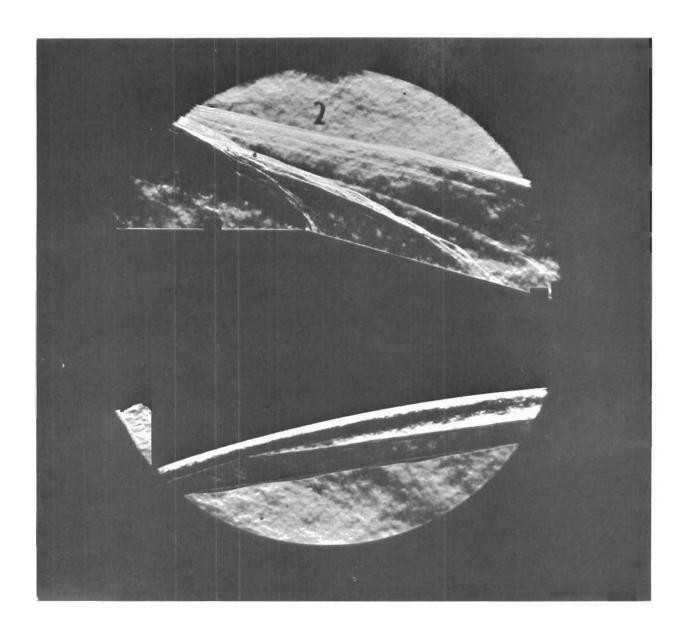


Figure 16 (CONTINUED) (b) MODEL E-2 SCHLIEREN, RUN 2

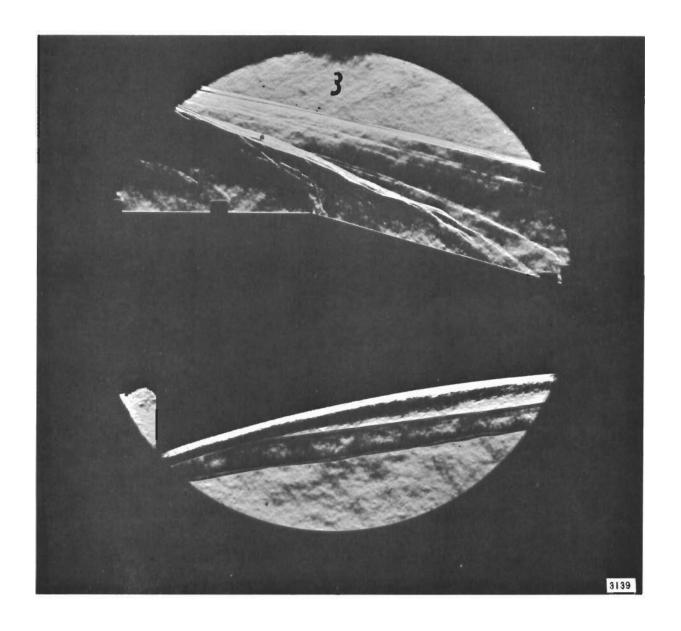


Figure 16 (CONTINUED) (c) MODEL E-2 SCHLIEREN, RUN 3

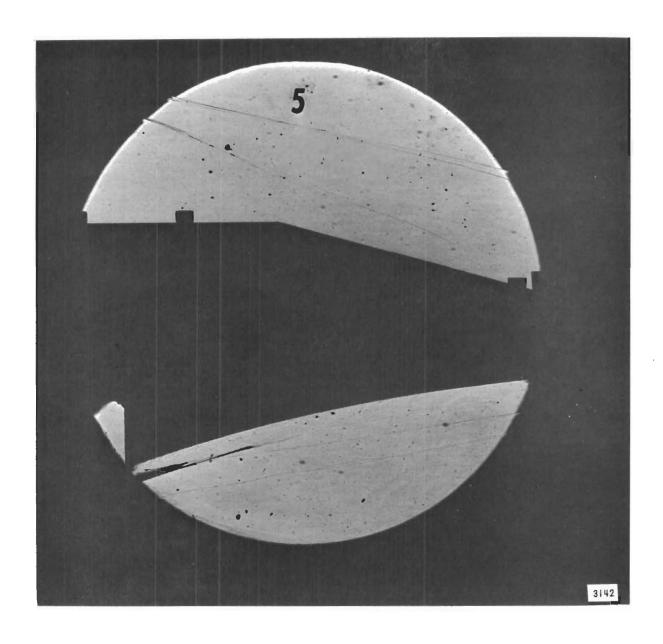


Figure 16 (CONTINUED) (d) MODEL E-2 SHADOWGRAPH, RUN 5

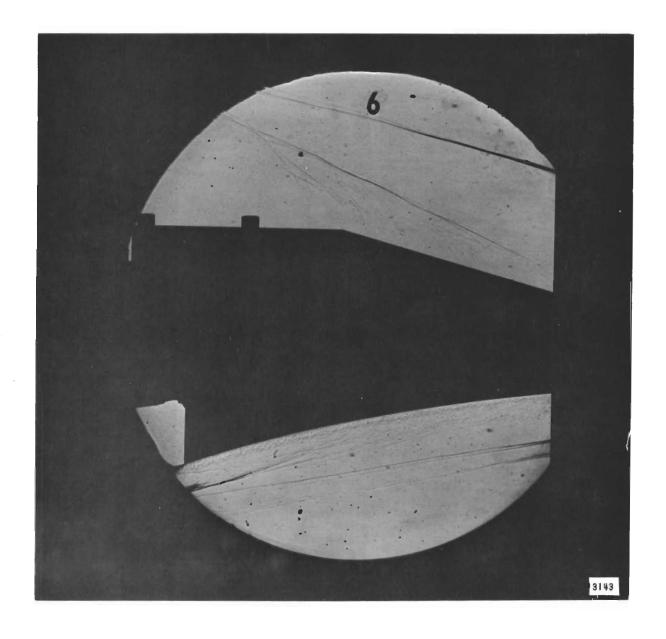
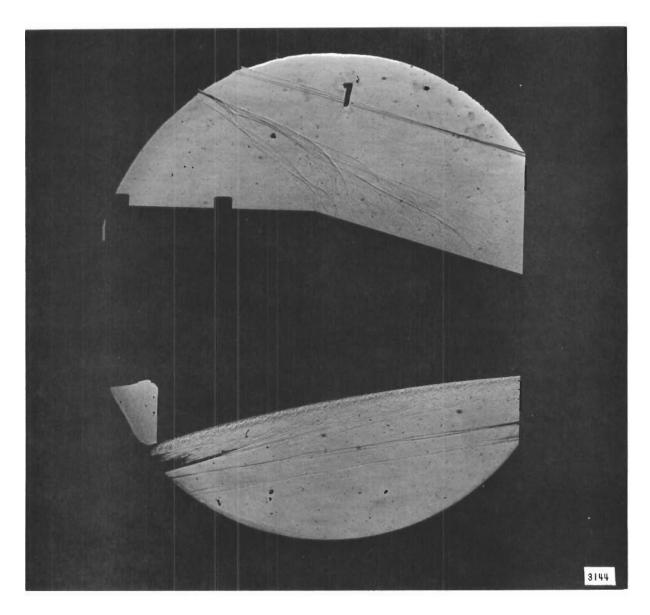


Figure 16 (CONTINUED) (e) MODEL E-2 SHADOWGRAPH, RUN 6



Ft.

Figure 16 (CONTINUED) (f) MODEL E-2 SHADOWGRAPH, RUN 7

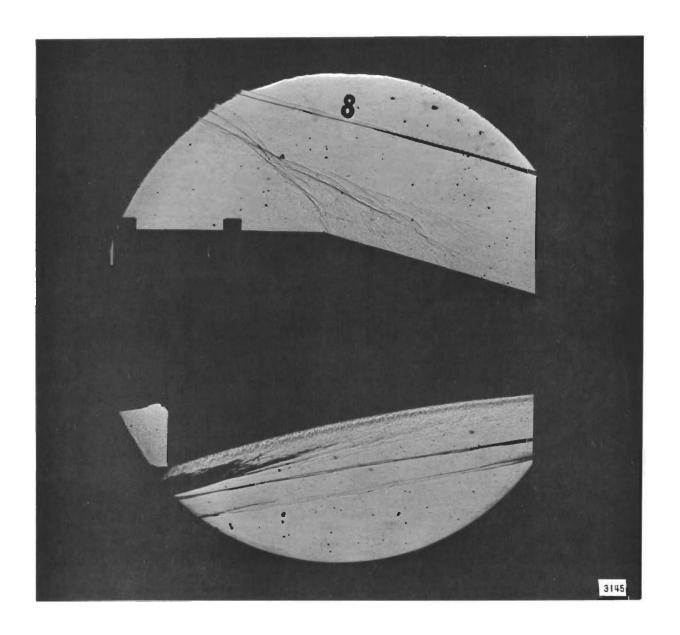


Figure 16 (CONTINUED) (g) MODEL E-2 SHADOWGRAPH, RUN 8

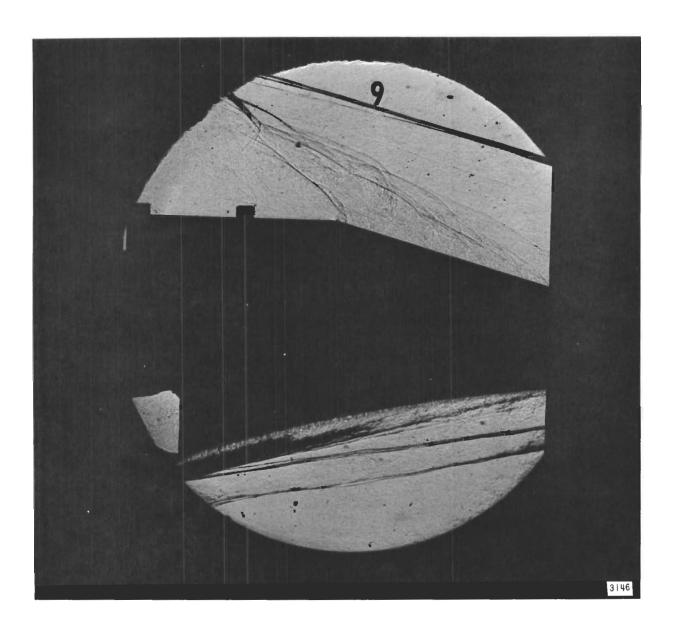


Figure 16 (CONTINUED) (h) MODEL E-2 SHADOWGRAPH, RUN 9

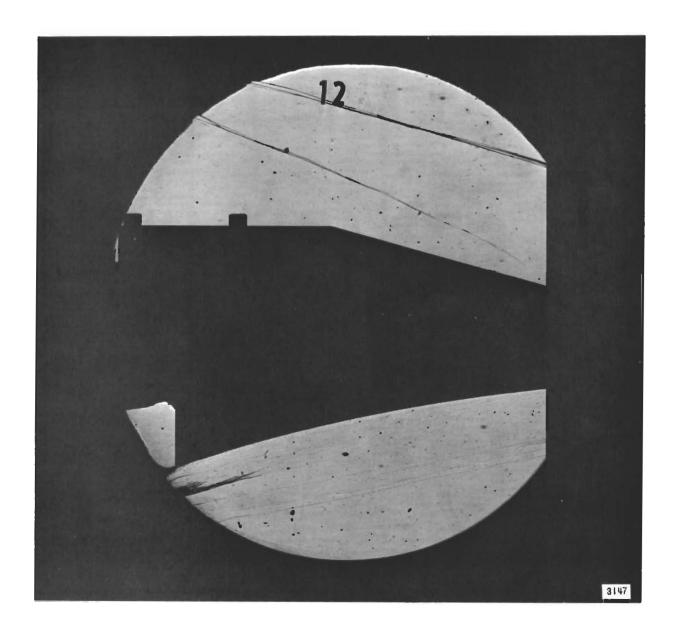


Figure 16 (CONTINUED) (i) MODEL E-2 SHADOWGRAPH, RUN 12

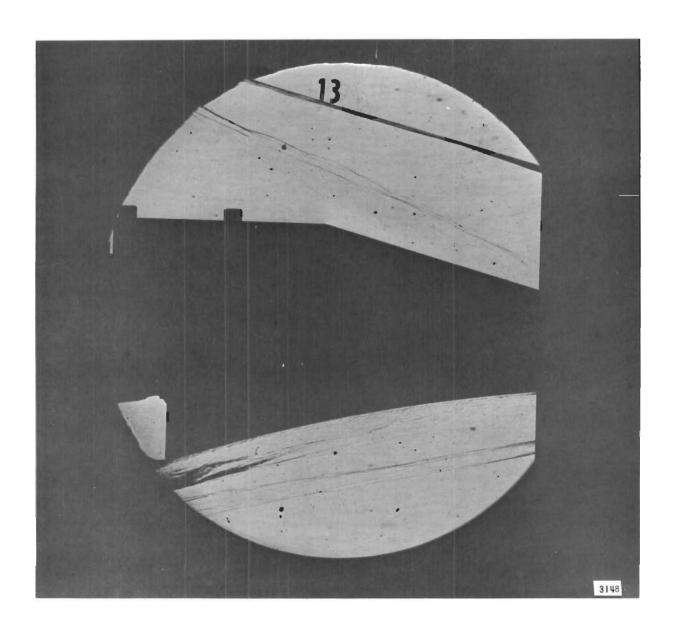


Figure 16 (CONTINUED) (j) MODEL E-2 SHADOWGRAPH, RUN 13

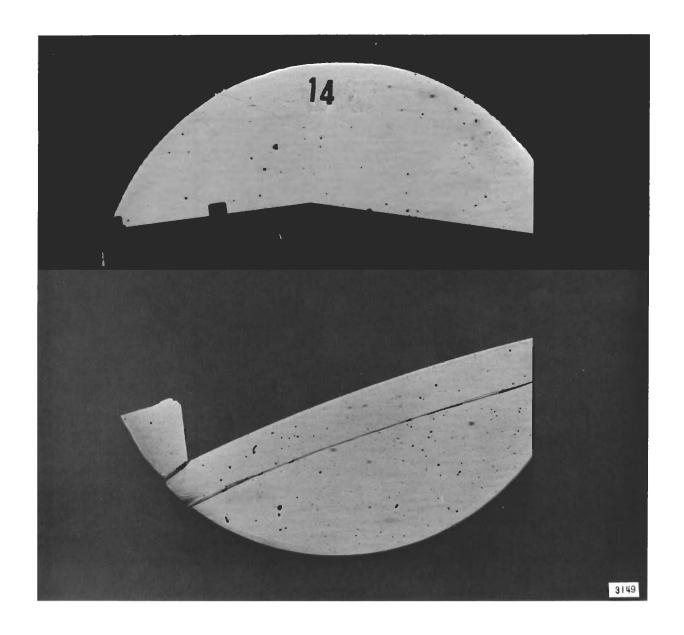


Figure 16 (CONTINUED) (k) MODEL E-2 SHADOWGRAPH, RUN 14

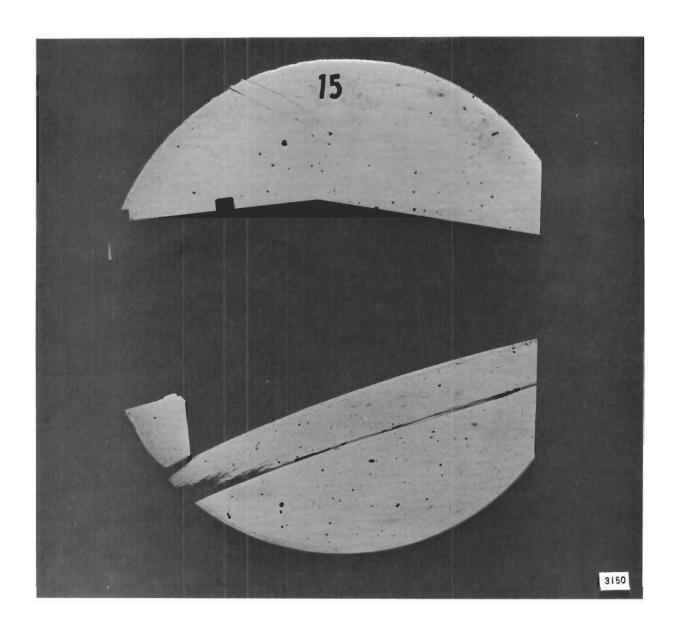


Figure 16 (CONTINUED) (L) MODEL E-2 SHADOWGRAPH, RUN 15

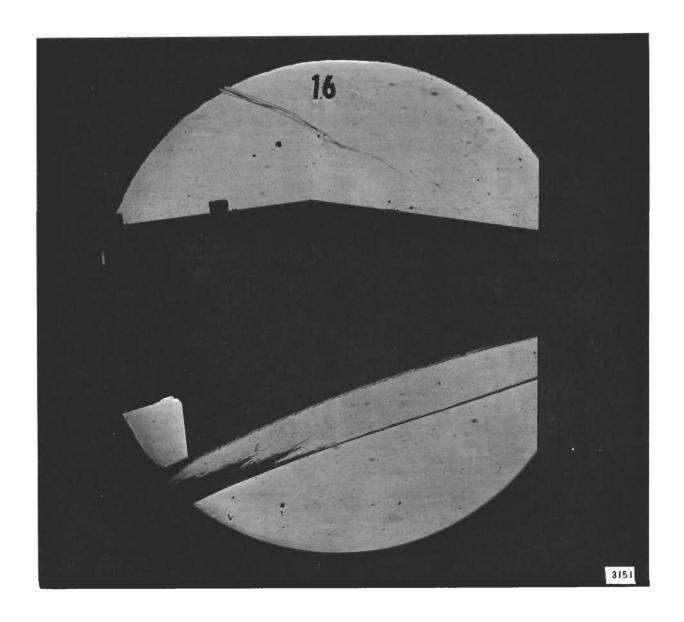


Figure 16 (CONTINUED) (m) MODEL E-2 SHADOWGRAPH, RUN 16

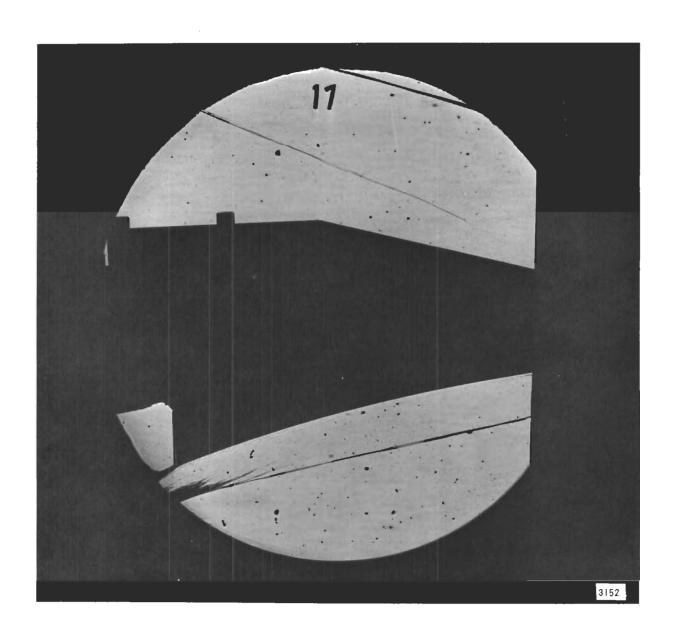


Figure 16 (CONCLUDED) (n) MODEL E-2 SHADOWGRAPH, RUN 17



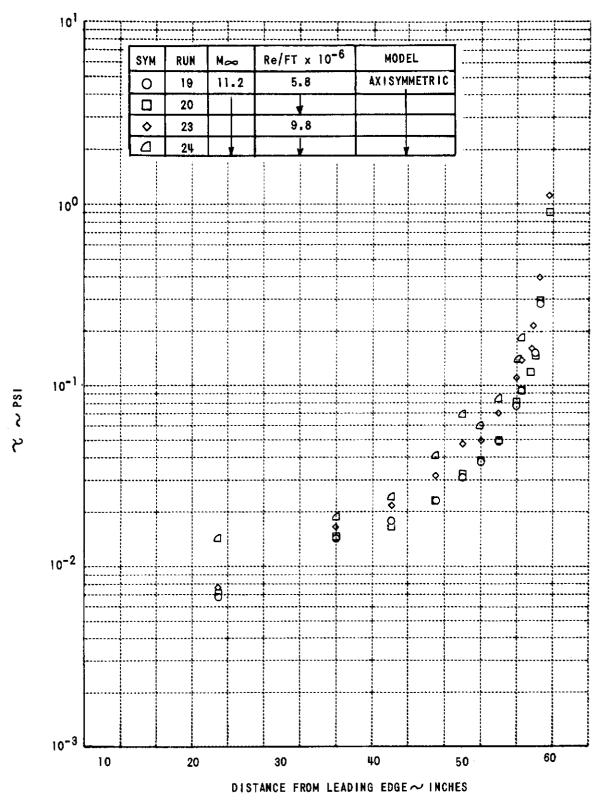


Figure 17 SKIN FRICTION DISTRIBUTIONS ON THE AXISYMMETRIC MODEL (a) MACH NUMBER 11, SHARP NOSE



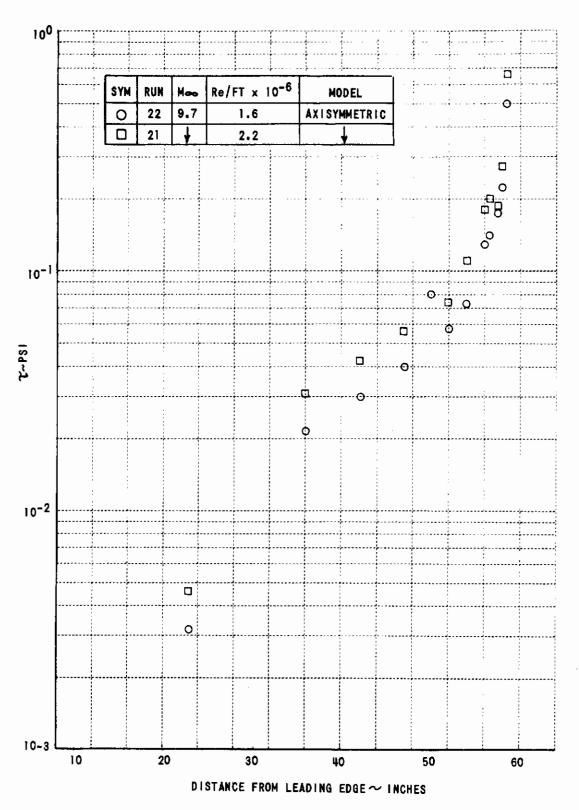


Figure 17 (CONTINUED) (b) MACH NUMBER 10, SHARP NOSE



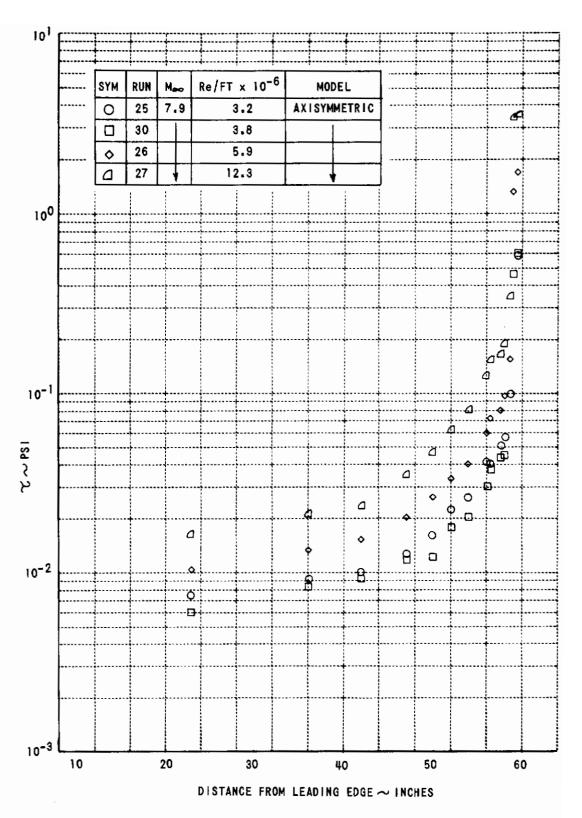
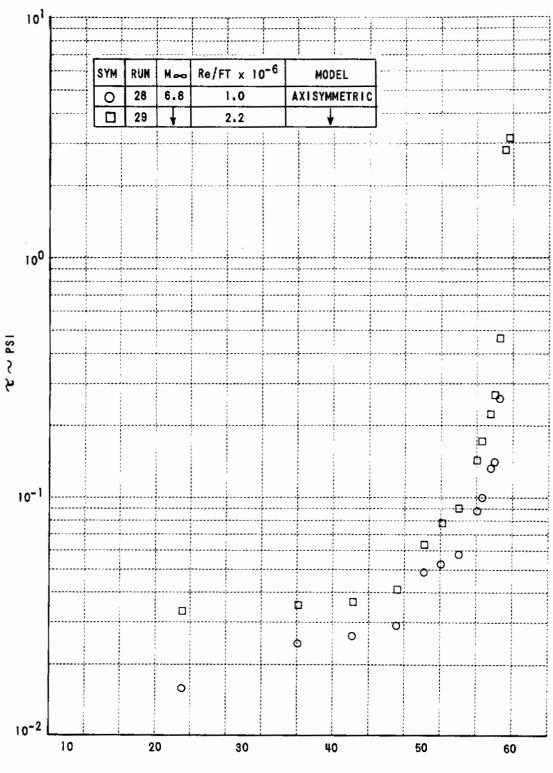


Figure 17 (CONTINUED) (c) MACH NUMBER 8, SHARP NOSE





DISTANCE FROM LEADING EDGE \sim INCHES

Figure 17 (CONTINUED) (d) MACH NUMBER 7, SHARP NOSE



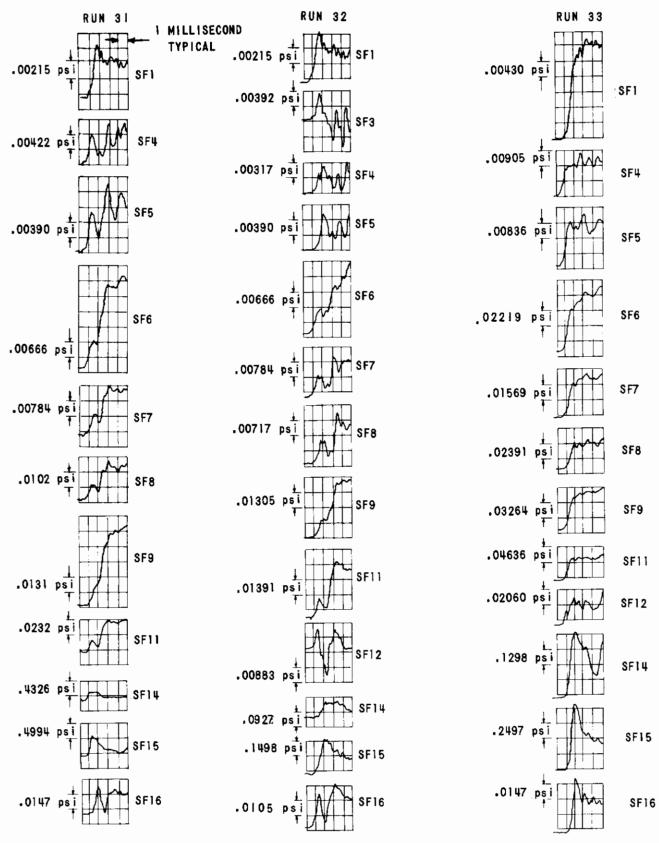


Figure 17 (CONCLUDED) (e) MACH NUMBER 7, BLUNT NOSE

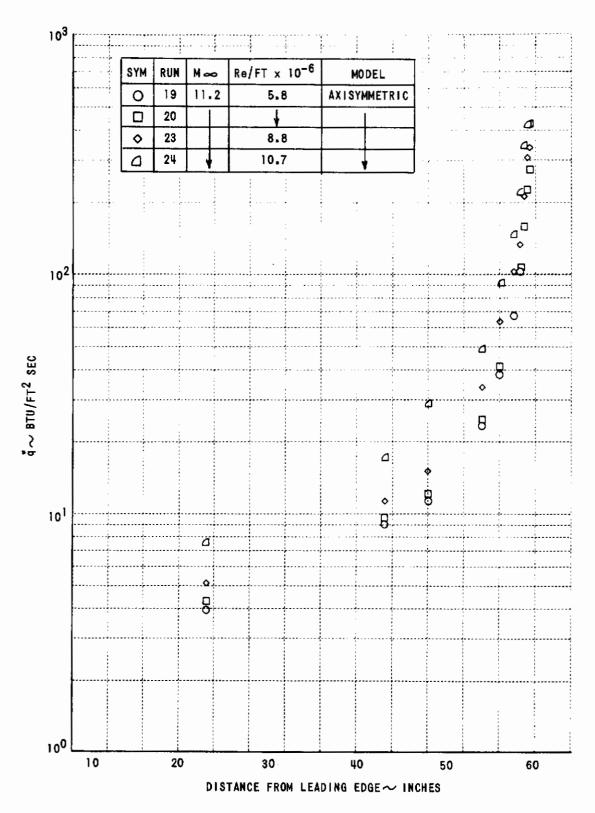


Figure 18 HEAT TRANSFER DISTRIBUTIONS ON THE AXISYMMETRIC MODEL
(a) MACH NUMBER 11, SHARP NOSE



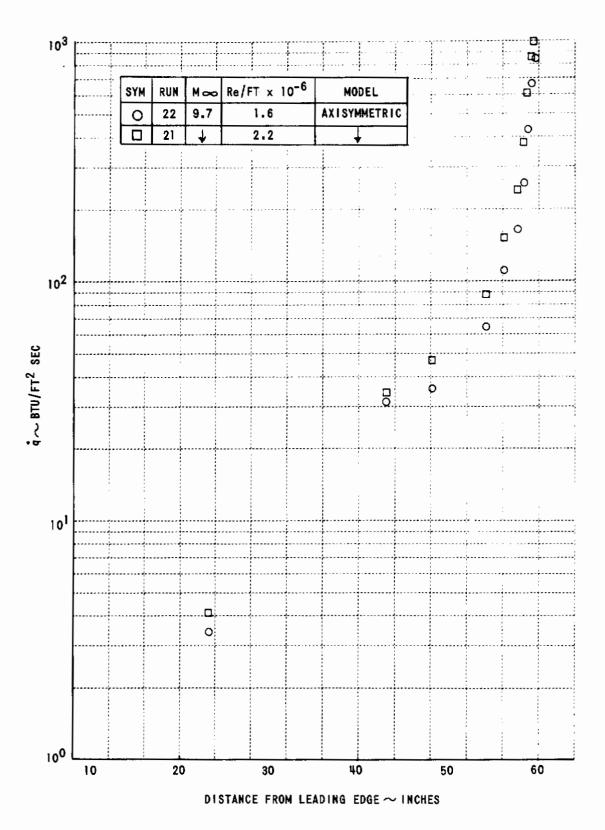


Figure 18 (CONTINUED) (b) MACH NUMBER 10, SHARP NOSE

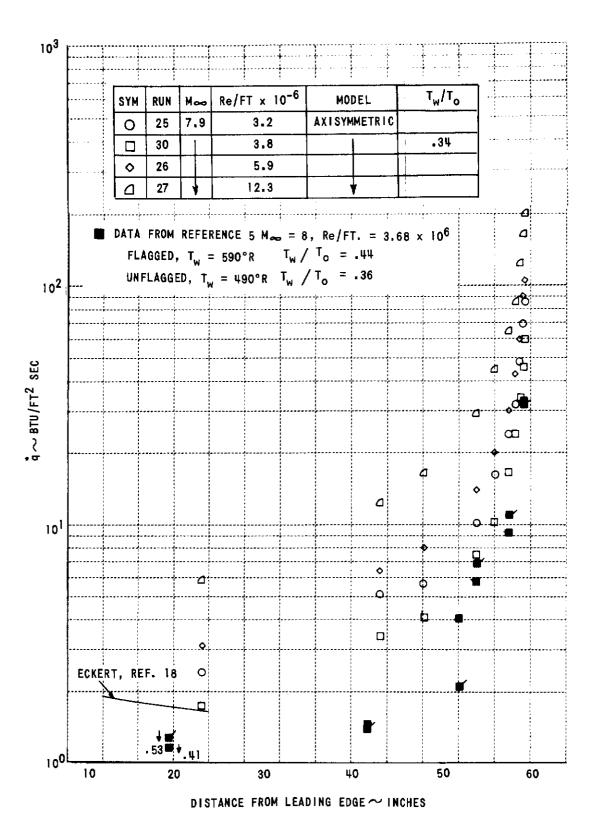


Figure 18 (CONTINUED) (c) MACH NUMBER 8, SHARP NOSE



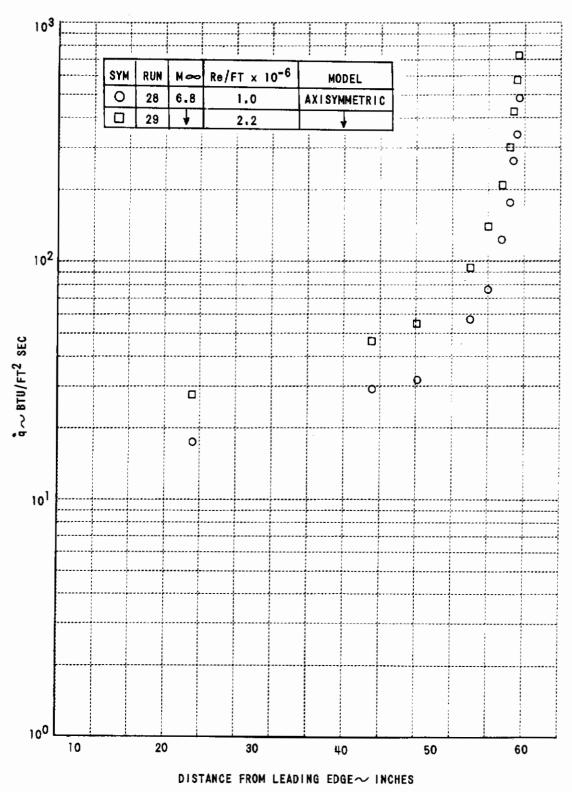


Figure 18 (CONTINUED) (d) MACH NUMBER 7, SHARP NOSE

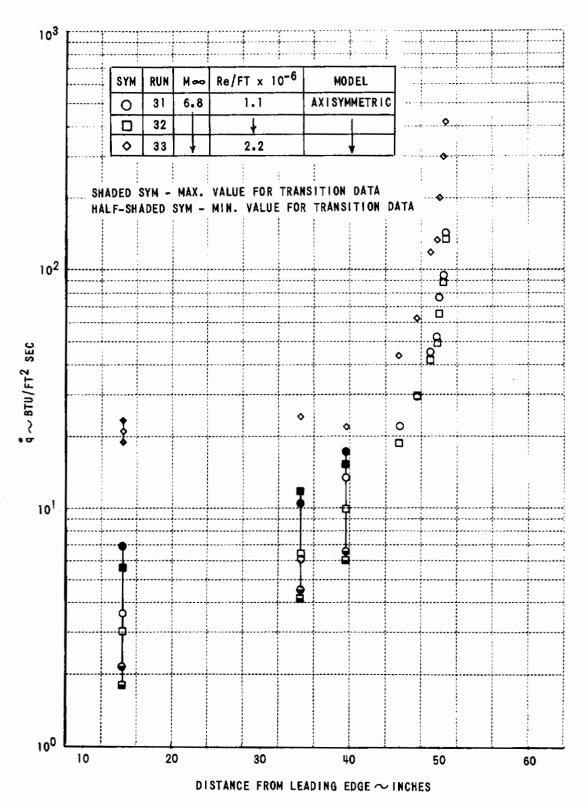


Figure 18 (CONCLUDED) (e) MACH NUMBER 7, BLUNT NOSE



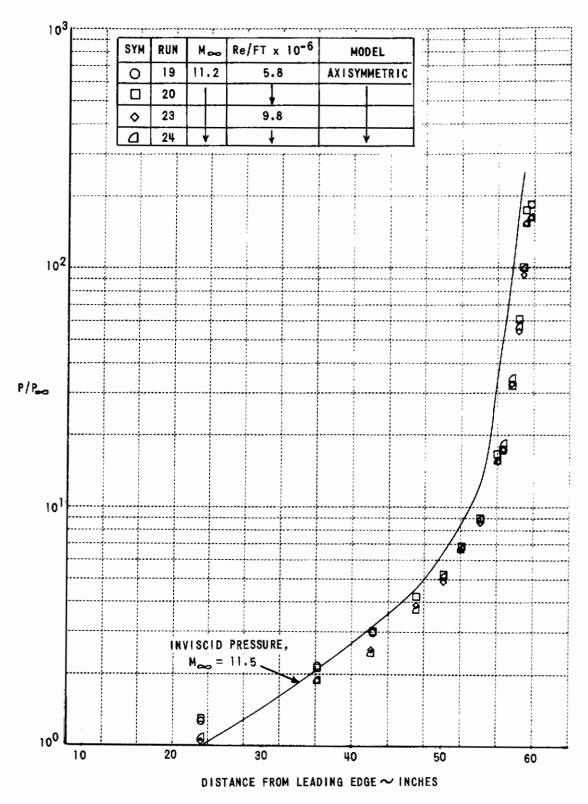
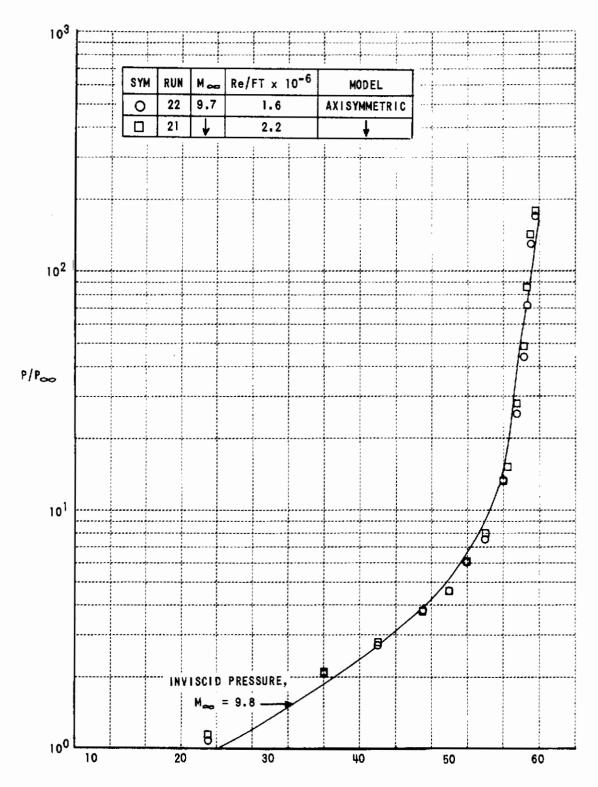


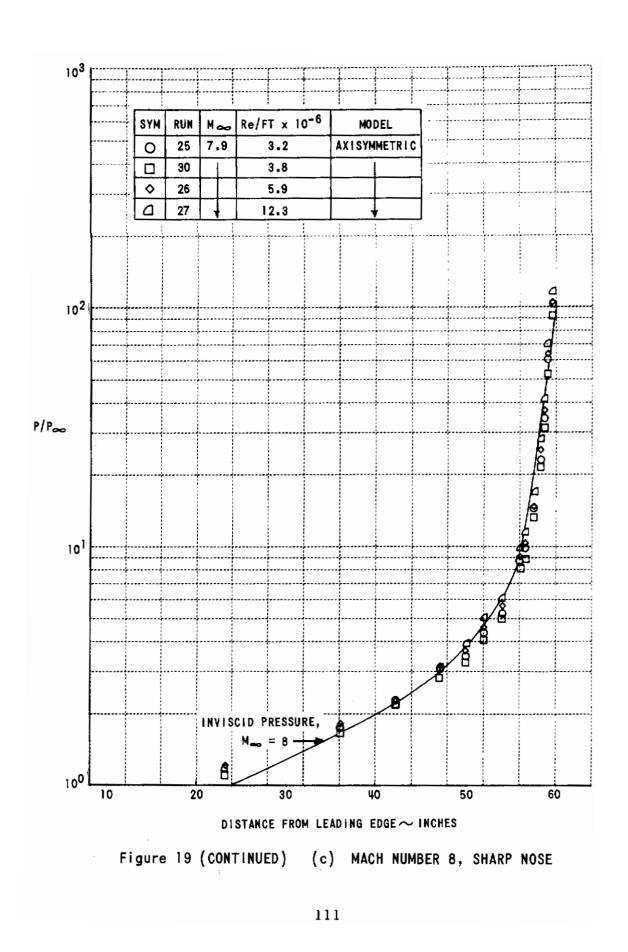
Figure 19 PRESSURE DISTRIBUTIONS ON THE AXISYMMETRIC MODEL
(a) MACH NUMBER 11, SHARP NOSE



DISTANCE FROM LEADING EDGE \sim INCHES

Figure 19 (CONTINUED) (b) MACH NUMBER 10, SHARP NOSE







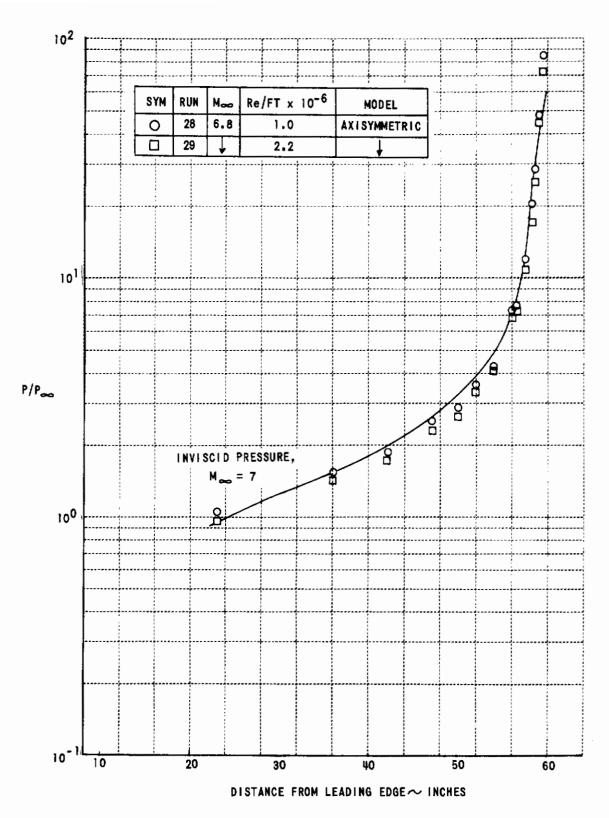


Figure 19 (CONTINUED) (d) MACH NUMBER 7, SHARP NOSE



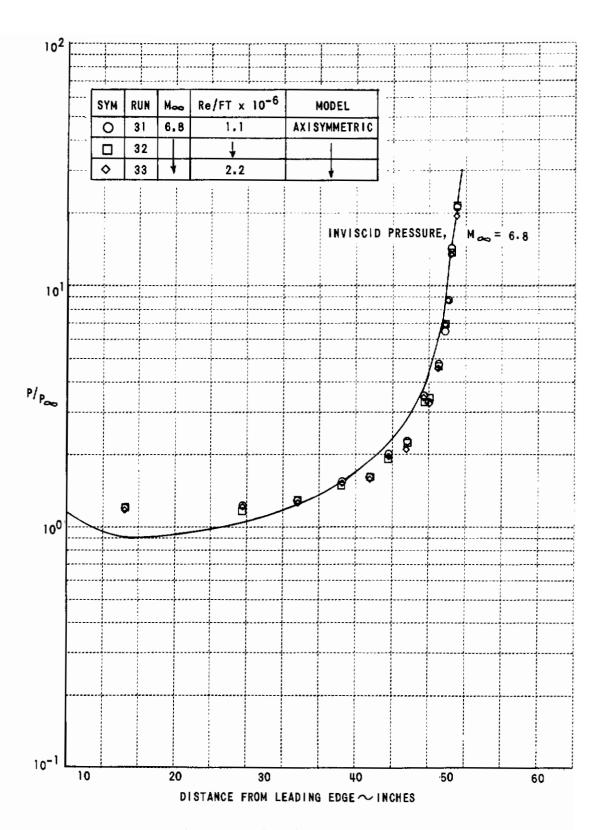


Figure 19 (CONCLUDED) (e) MACH NUMBER 7, BLUNT NOSE

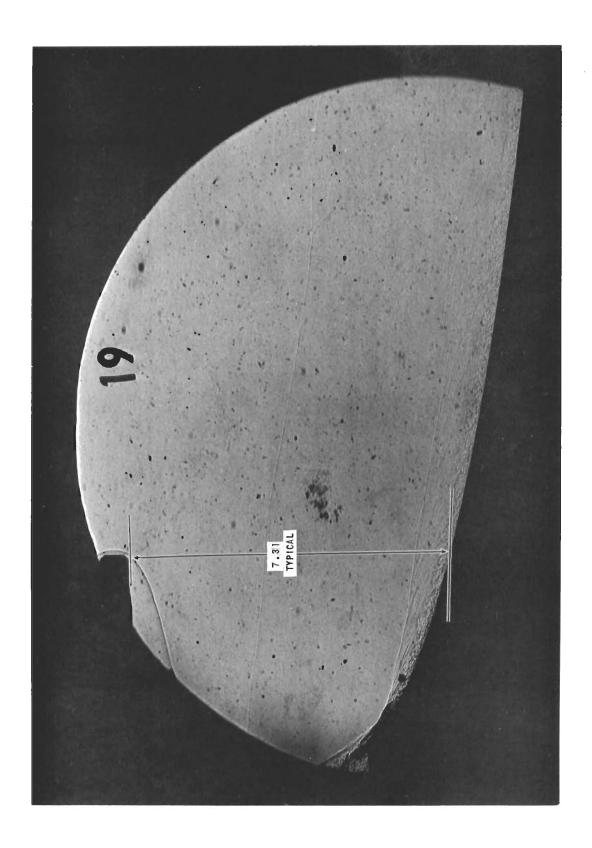
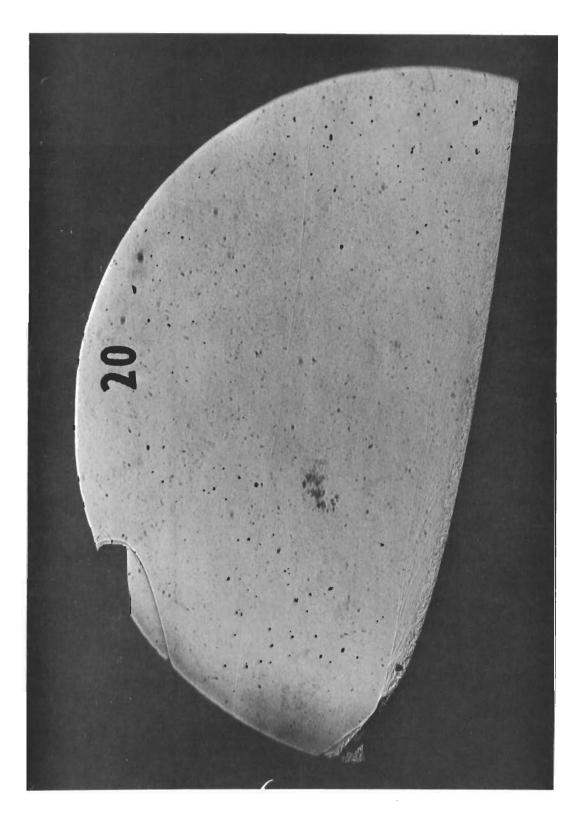


Figure 20 AXISYMMETRIC MODEL FLOW PHOTOGRAPHS (a) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 19

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(CONTINUED) (b) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 20

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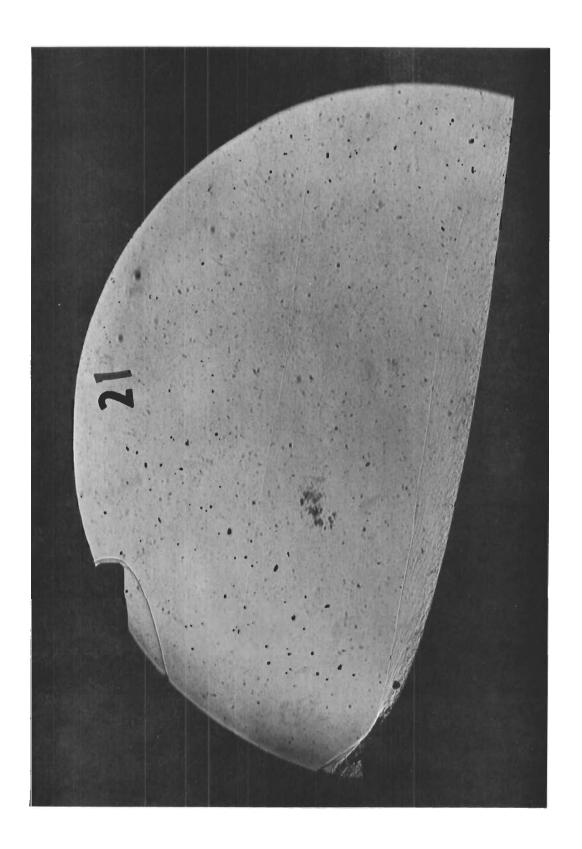


Figure 20 (CONTINUED) (c) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 21

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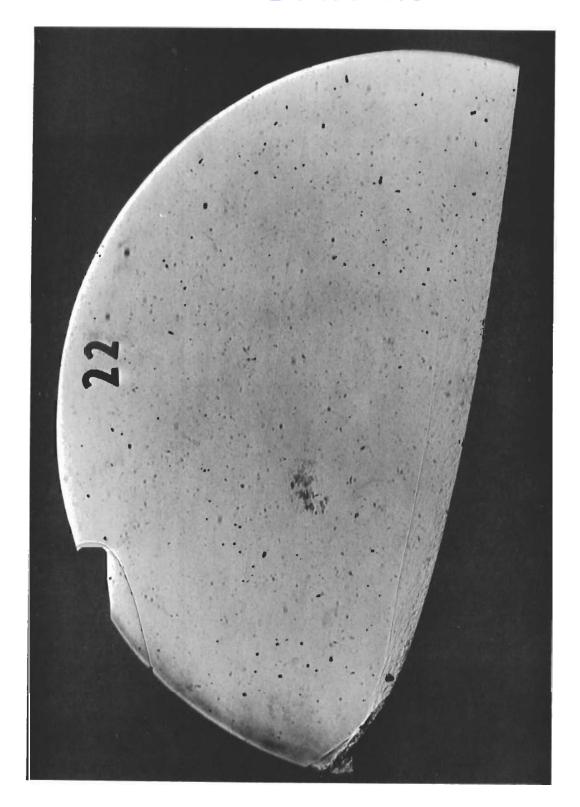
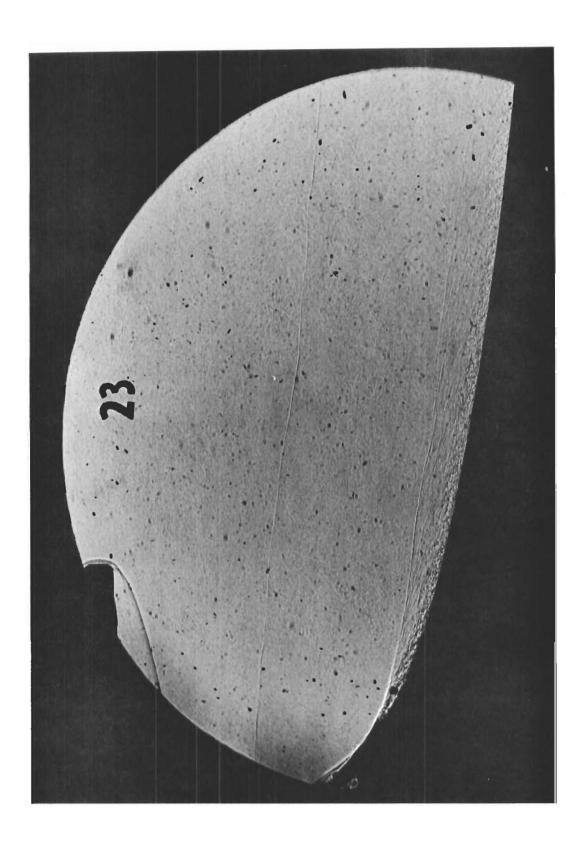


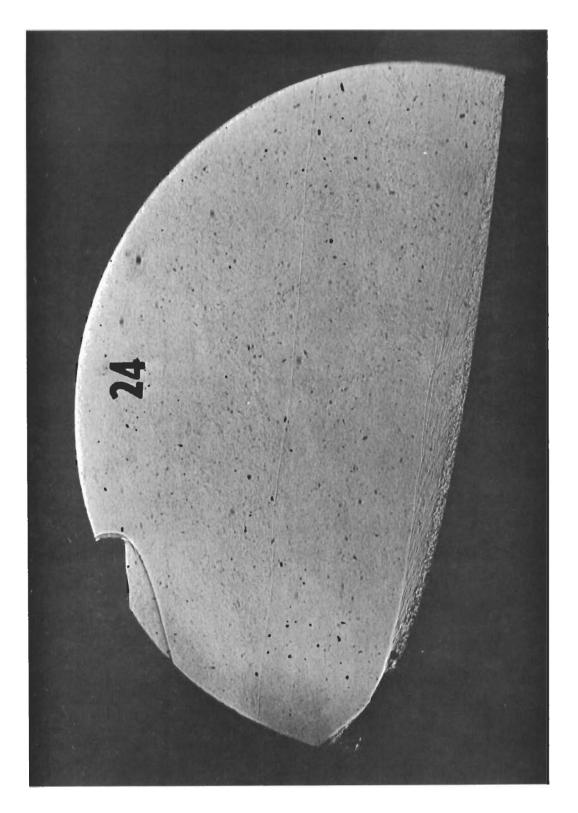
Figure 20 (CONTINUED) (d) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 22

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(CONTINUED) (e) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 23 Figure 20

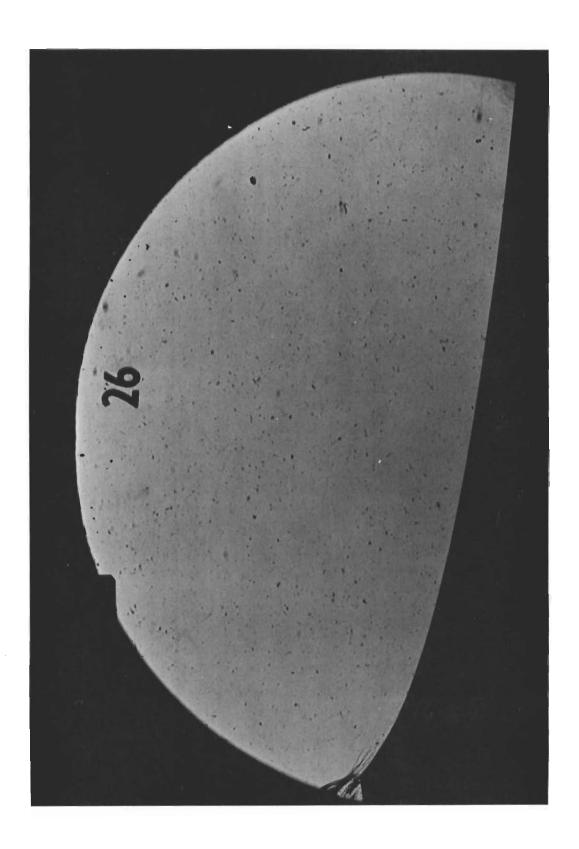
118



(CONTINUED) (f) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 24 Figure 20

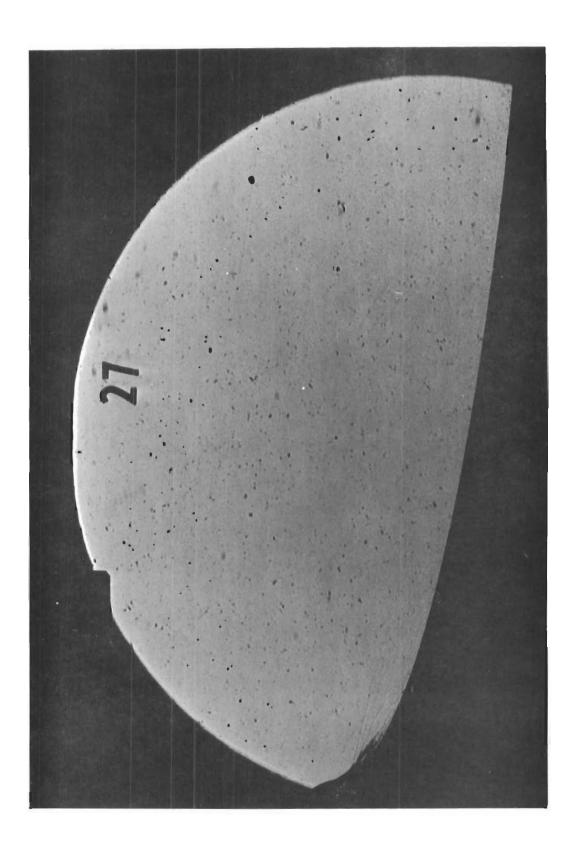
119





(CONTINUED) (h) AXISYMMETRIC MODEL SHADOWGRAPH, RUN 26 Figure 20

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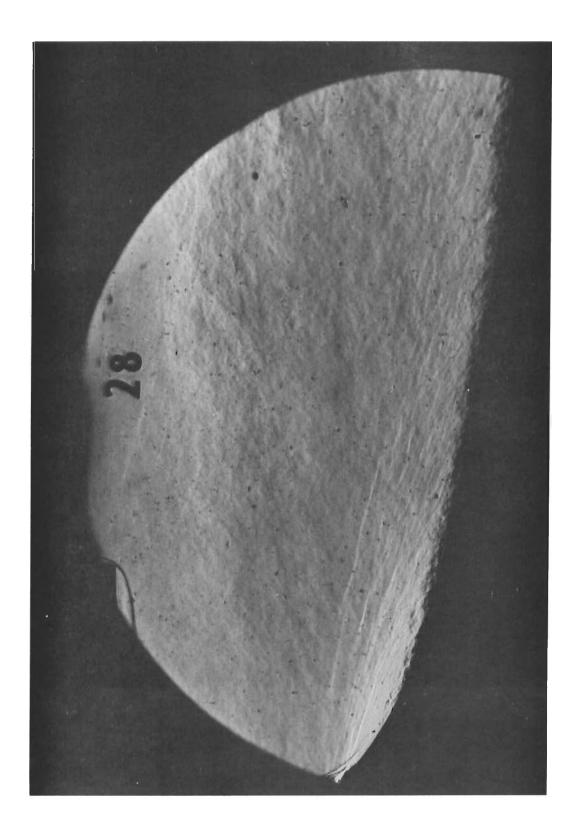


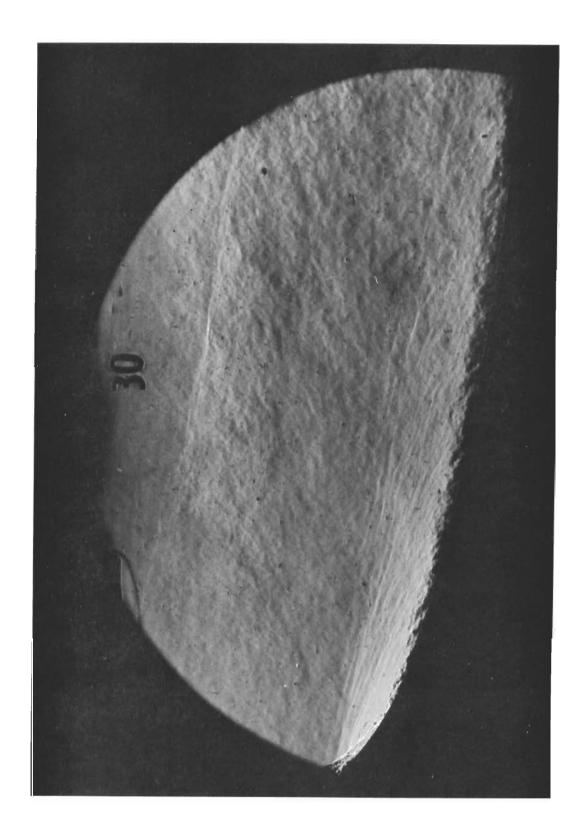
Figure 20 (CONTINUED) (j) AXISYMMETRIC MODEL SCHLIEREN, RUN 28

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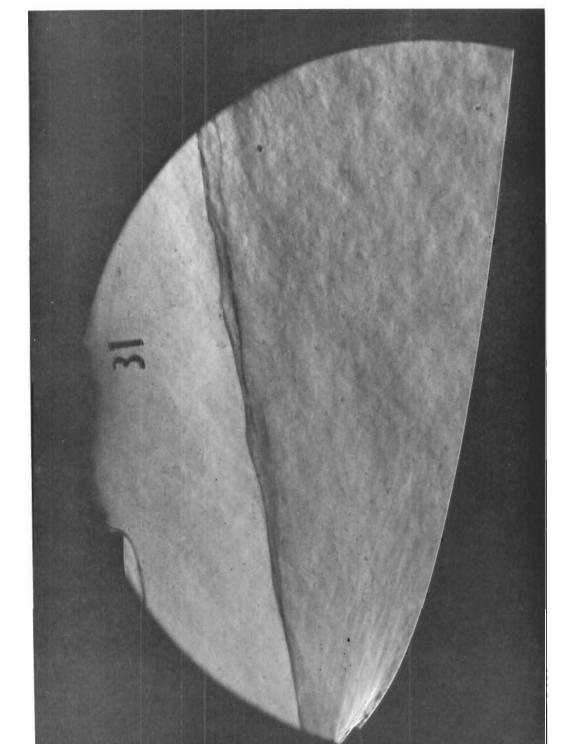
(CONTINUED) (K) AXISYMMETRIC MODEL SCHLIEREN, RUN 29 Figure 20

124



(CONTINUED) ($\mathcal L$) AXISYMMETRIC MODEL SCHLIEREN, RUN 30 Figure 20

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(CONTINUED) (m) AXISYMMETRIC MODEL SCHLIEREN, RUN 31

Figure 20

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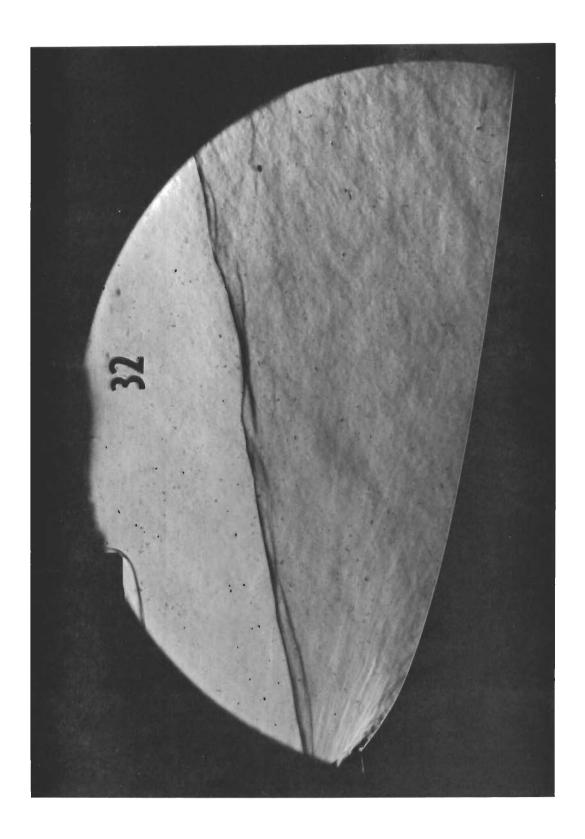


Figure 20 (CONTINUED) (n) AXISYMMETRIC MODEL SCHLIEREN, RUN 32

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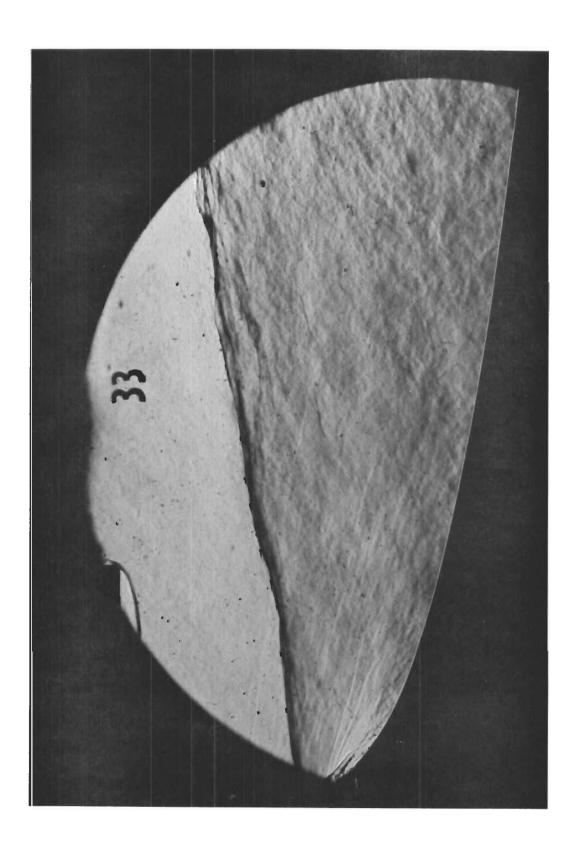
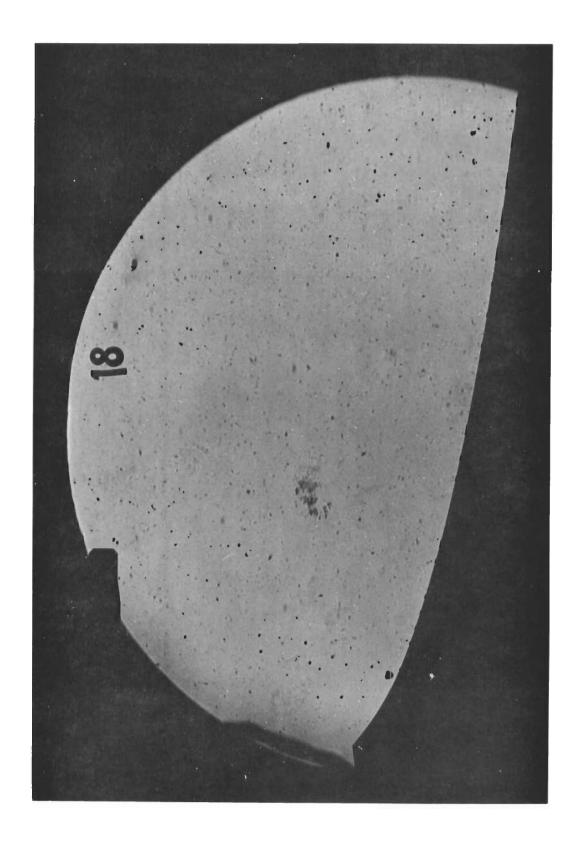


Figure 20 (CONTINUED) (o) AXISYMMETRIC MODEL SCHLIEREN, RUN 33

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(CONCLUDED) (P) AXISYMMETRIC MODEL SHADOWGRAPH, NO FLOW Figure 20

129



DOCUMENT CONT					
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Buffalo, New York		1 none			
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An experimental study of turn influence of adverse pressure gradien conducted in the Cornell Aeronautical Shock Tunnel on a two-dimensional an strumented with skin friction, heat traconducted over a Mach and Reynolds in per ft. to 2.93 x 10 ⁷ per ft., respective boundary layer transition on the forwatto artificial trips. It was possible to before the start of the adverse pressuraxisymmetric model tests but for mos was not completed until after the start A comparison of the pressure	ts typical of Laboratory d an axisym ansfer and p number rage vely. These ard portions attain a fully re gradient at of the two-t of the pres	hypersonic 96-inch leader in the metric moderns are sure gas of 6.74 to be test condof the modern for egion for dimention sure grading and sur	ic inlets, was eg of the Hypersonic odel each in- ages. Tests were o 11.37 and 1.05 x 10 litions produced dels without resorting t boundary layer most of the hal tests, transition ient.		

A comparison of the pressure data with the inviscid pressure distribution was made and good agreement is generally found indicating very little change in effective model shape due to boundary layer growth. This result is a consequence of the large model size relative to the boundary layer thickness, i.e. high Reynolds number flows over large models.

An important conclusion resulting from this program was that turbulent boundary layers can negotiate large adverse pressure gradients without separating. Comparison with some existing laminar boundary layer data indicate that a turbulent boundary layer can negotiate adverse pressure gradients at least an order of magnitude greater than those gradients which will separate a laminar layer.

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Security Classification 14. KEY WORDS	LINKA		LINK B		LINKC	
	ROLE	₩T	ROLE	₩T	ROLE	Wτ
Turbulent Boundary Layer						
Adverse Pressure Gradients						ĺ
Skin Friction						
Hypersonic Inlet						
Heat Transfer		}				
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