FOREWORD

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Mr. L. V. Andrew was the Program Manager for North American Aviation. Dr. E. R. Rodemich developed the technical approach and wrote the computer programs. Several valuable suggestions were given by Dr. M. T. Landahl of the Massachusetts Institute of Technology.

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ABSTRACT

The fundamental equations of the transonic box method were derived, based on the representation of the velocity potential by a doublet distribution. They form the basis of a systematic method of treating an oscillating wing at M = 1, analogous to the supersonic Mach box method.

A digital computer program, written in Fortran IV, is presented. The program applies to a planar wing of polygonal planform, with a straight trailing edge, and as many as three sweep angles along the leading edge. For a maximum of ten modes of oscillation, the program computes the oscillatory potentials and pressures and a generalized force matrix.

Results obtained from the program are compared with existing theoretical and experimental values. Several possible extensions of the method are described.

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LIST OF SYMBOLS

Symbol	Definition
a	Local speed of sound; speed of sound at infinity
a_{nm}	Coefficient in the potential series
$A(i - i', \|j - j'\|)$	Influence coefficient: the upwash at the center of B_{ij} caused by a unit doublet distribution over $B_{i'j'}$
A_{jr}	Term in $\bar{\varphi}$ evaluated at (x_j, y_j)
AXY (I, J)	An integral over the wing planform
AY (J)	An integral along the trailing edge
b	Root chord length
B	Region composed of boxes, approximating S
B_{ij}	A box
$(B_{rr'})$	Matrix used in least squares surface fits
BXY	Part of AXY (I, J)
BY	Part of AY (J)
$\bar{C}_p$	Pressure coefficient
(C'_r), (C''_r)	Column matrices used in least squares surface fits
d	Dimensionless length of box side
d_{nm}	Coefficient in deflection polynomial
DA	The data array
f	Function which describes the wing deflection
F	Factor which gives $\bar{\varphi}$ the proper edge behavior

(Continued on next page.)

Symbol	Definition
$\tilde{g}_u$, $\tilde{g}_\ell$, $\tilde{f}$	Functions used in the equations of upper and lower wing surfaces
h_j	Weight used in Gaussian quadrature
i	$\sqrt{-1}$
i, j	Indexes specifying box position
I, J	Indexes
k	Reduced frequency: $\omega b/U_\infty$
ℓ	kd
L_{ij}	Generalized force coefficient
M	Mach number
n, m	Indexes equal to power of x and power of y^2
NC	Number of coefficients
NP	Number of points
NS	Number of segments of leading edge given by the data
p, q	Integration variables
Q	Quantity minimized in least squares surface fits
r	Index
S	Function used in the equation of a surface
S	Region in the xy-plane occupied by the wing; the area of this region
t	Time
u, v	Integration variables
u_j	Point used in Gaussian quadrature
U_∞	Air speed of the wing; speed of flow at infinity

(Continued on next page.)

Symbol	Definition
w	Upwash at $z = 0+$
W	The region of the xy-plane occupied by the wing's wake
$\tilde{x}, \tilde{y}, \tilde{z}$	Coordinates with dimensions of length
x, y, z	Dimensionless coordinates
(x_i, y_j)	Center of B_{ij}
(x_j, y_j)	Point at which a value of potential or deflection is given
$x_1, \ldots, x_{NS}$; $y_0, \ldots, y_{NS}$	Coordinates of points on the leading edge given by the data
x_0	Function which describes the leading edge: $x = x_0(y)$
y_{max}	Value of y at the wing tip
y_+, y_-	Limits of integration
α_{nm}, α_r	Real part of a_{nm}
β_r	Imaginary part of a_{nm}
δ	Constant factor in the deflection
Δp_i	Lifting pressure in the ith mode
ξ, η	Integration variables equivalent to x, y
ν	Frequency
ρ	Density
ρ	Source or doublet strength
σ	The integral over x involved in BXY
Φ	Velocity potential
ϕ	Steady ~~perturbation~~ flow potential
φ	Unsteady perturbation potential

(Continued on next page.)

Symbol	Definition
$\bar{\varphi}$	Time independent factor of φ
$\bar{\varphi}_o$	Potential of a point source
$\bar{\varphi}_1$	Potential of a point doublet
$\bar{\varphi}_s$	Potential of a source distribution
$\bar{\varphi}_d$	Potential of a doublet distribution
$\bar{\varphi}_{ij}$	Value of $\bar{\varphi}$ in B_{ij}
$\bar{\varphi}'_j$	Real part of value of $\bar{\varphi}$ at (x_j, y_j)
Ψ	Upwash in the xy-plane caused by a point doublet
ω	Angular frequency, $2\pi\nu$

1. INTRODUCTION

The transonic box program is designed to calculate the unsteady potentials for a given set of modes of wing oscillation and to compute the generalized forces. Pressure distributions may be obtained from the potentials.

A planar wing with a straight trailing edge is assumed. The oscillations are assumed to be symmetric in the spanwise coordinate y. None of these assumptions is necessary for the method. (See Section 5.)

The basic step in the box method is the solution of the system of simultaneous equations [Equation (33)] which determine a set of values of potential on the wing from a corresponding array of upwash values. A surface is fitted to these values, giving a functional representation of the potential that is used subsequently to find pressures and generalized forces.

The method used is suggested by the success of supersonic box methods (References 1 through 4). The potential is generated by a doublet distribution rather than by a source distribution because the latter method would involve diaphragm regions of infinite extent, whereas the doublet distribution is confined to the wing and its wake.

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2. THEORETICAL DEVELOPMENT OF THE METHOD

1. THE DIFFERENTIAL EQUATION

We consider an oscillating body moving at speed U_∞ through a nonviscous fluid. From the point of view of a moving coordinate system $(\tilde{x}, \tilde{y}, \tilde{z})$ in which the average position of the body is fixed, there is a flow past the body with velocity U_∞ at infinity. Assume that the flow is irrotational; then the velocity field of the flow is the gradient of a potential function Φ, which satisfies the differential equation

$$\nabla^2 \Phi - \frac{1}{a^2}\left[\Phi_{tt} + 2\,\nabla\Phi \cdot \nabla\Phi_t + (\nabla\Phi \cdot \nabla)\, 1/2\, (\nabla\Phi)^2\right] = 0 \qquad (1)$$

(See Reference 5, p. 193) where a is the local speed of sound.

Suppose that the flow is approximately uniform in the direction of the positive $\tilde{x}$-axis. This may be true, for example, if the body is almost plane and the oscillations are small. Then Φ may be broken up into several parts, as

$$\Phi = U_\infty(\tilde{x} + \phi + \varphi) \qquad (2)$$

where the first term gives a uniform flow, the second term gives the correction for a steady flow about the body, the third term gives the correction to this for the oscillating body, and ϕ and φ are small.

To the first order, ϕ and φ are different solutions of the same differential equation

$$(1 - M^2)\,\varphi_{\tilde{x}\tilde{x}} + \varphi_{\tilde{y}\tilde{y}} + \varphi_{\tilde{z}\tilde{z}} - \frac{2\,U_\infty}{a^2}\,\varphi_{\tilde{x}t} - \frac{1}{a^2}\,\varphi_{tt} = 0 \qquad (3)$$

where M, a are the Mach number and speed of sound at infinity. (See Reference 5, p. 198.) φ is a periodic function of t. Since the differential equation is linear, we may put $\varphi = \overline{\varphi}\,(x, y, z)\, e^{i\omega t}$, where ω is the angular frequency of oscillation. In terms of the nondimensional quantities,

$$x = \tilde{x}/b$$
$$y = \tilde{y}/b$$
$$z = \tilde{z}/b$$
$$k = \omega b/U_\infty$$

(b is a characteristic length of the body); Equation (3) becomes

$$(1-M^2)\bar{\varphi}_{xx} + \bar{\varphi}_{yy} + \bar{\varphi}_{zz} - 2iM^2k\bar{\varphi}_x + M^2k^2\bar{\varphi} = 0 \quad (4)$$

For M = 1, this reduces to

$$\bar{\varphi}_{yy} + \bar{\varphi}_{zz} - 2ik\bar{\varphi}_x + k^2\bar{\varphi} = 0 \quad (5)$$

the linearized transonic equation (see Reference 6, p. 7). It has been suggested by Landahl (Reference 6) that the proper equation to use instead of (4) is

$$\bar{\varphi}_{yy} + \bar{\varphi}_{zz} - 2iM^2k\bar{\varphi}_x + M^2k^2\bar{\varphi} = 0$$

if $k \gg |M-1|$. Comparison of this equation with (5) leads to a similarity rule for flows in the transonic range (see Reference 6, p. 18).

The range of validity of this equation is duscussed by Landahl (Reference 6, Chapter 1). First, there is the requirement for linearization in any speed range, that the perturbation potential $\phi + \varphi$ be small. This is not satisfied at the leading edge of a wing for any realistic cross-sectional shape; however, it may be satisfied over the rest of the wing, if the wing has small thickness, and the results on parts of the wing away from the leading edge are not much affected by the error there.

Another restriction peculiar to transonic speeds is associated with the absence of the term in $\bar{\varphi}_{xx}$. The actual flow has some variation in local Mach number which may influence the nature of the flow considerably if M is near 1. The presence of the term in $\bar{\varphi}_x$ tends to reduce this influence, but for k small or zero, the equation is valid only for a highly swept wing with a pointed nose.

The difference of the local Mach number from the value 1 assumed in Equation (5) may come from two sources: (1) wing thickness, and (2) a change in the free stream Mach number. Thus, for any value of k, there are limits on the thickness ratio and the Mach number range, which increase with k. Estimates of these limits are not possible, because of the small amount of experimental data available.

2. BOUNDARY CONDITIONS

The solution of Equation (1) must give a velocity field which is such that a particle at the body surface moves along the moving surface. If the equation of the surface is

$$S(\tilde{x}, \tilde{y}, \tilde{z}, t) = 0$$

this equation must be satisfied when $(\tilde{x}, \tilde{y}, \tilde{z})$ moves with the velocity $\nabla\Phi$. Differentiating with respect to t gives the condition

$$\nabla\Phi \cdot \nabla S + \frac{\partial S}{\partial t} = 0 \qquad (6)$$

This determines the normal velocity at the surface.

Now suppose that the body (to be referred to henceforth as a wing) is almost planar, lying ~~almost~~ in the xy-plane (see Figure 1). For vertical

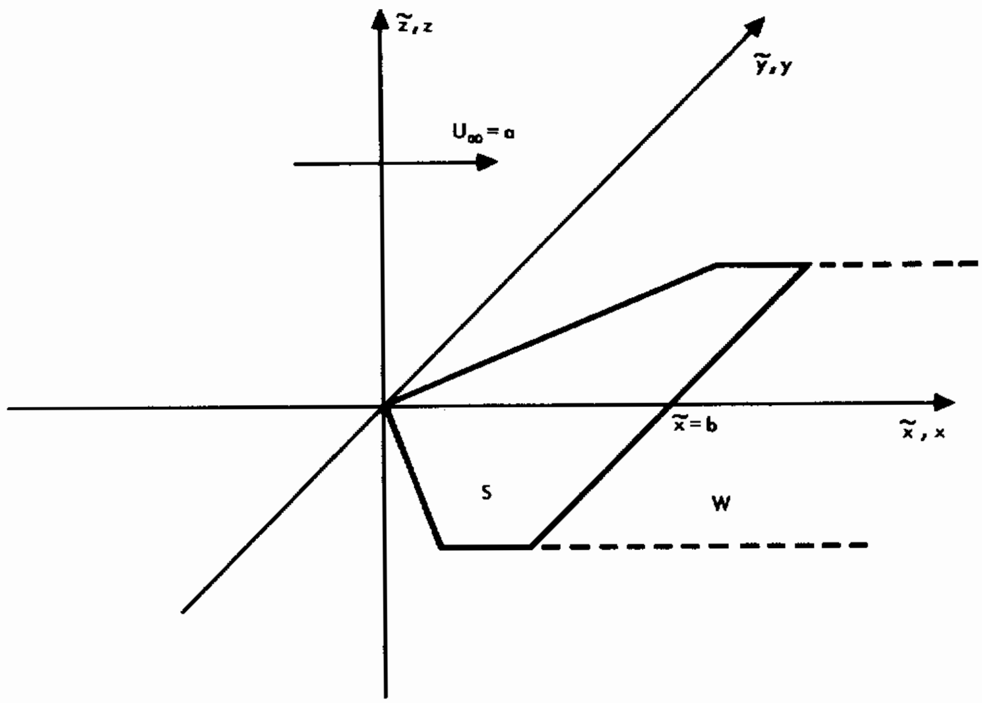


Figure 1. Coordinate Systems

oscillations of the body, the upper and lower surfaces may be represented by the equations

$$\tilde{z} = \tilde{g}_u (\tilde{x}, \tilde{y}) + e^{i\omega t} \tilde{f} (\tilde{x}, \tilde{y})$$

$$\tilde{z} = \tilde{g}_\ell (\tilde{x}, \tilde{y}) + e^{i\omega t} \tilde{f} (\tilde{x}, \tilde{y})$$

where the functions $\tilde{g}_u, \tilde{g}_\ell$ are associated with the deviation of the shape of the body from planar, and $\tilde{f}$ depends on the mode of oscillation. Then on the two surfaces, we may take

$$S = \tilde{z} - \tilde{g}_u - e^{i\omega t} \tilde{f}$$

$$S = \tilde{z} - \tilde{g}_\ell - e^{i\omega t} \tilde{f}$$

Use these expressions for S and Equation (2) in Equation (6). Neglecting terms that involve products of φ or ϕ with $\tilde{g}_u, \tilde{g}_\ell$, or $\tilde{f}$, the resulting equation may be broken up into a steady part, which gives the boundary condition for ϕ, and an unsteady part, which gives the boundary condition for $\overline{\varphi}$. The unsteady part is

$$\frac{\partial \overline{\varphi}}{\partial z} = \frac{\partial f}{\partial x} + ikf \tag{7}$$

where $f = \tilde{f}/b$. To the present degree of approximation, this condition should be applied at $z = 0$, over the region of the xy-plane on which the body projects.

3. THE BOUNDARY VALUE PROBLEM FOR $\overline{\varphi}$

In linearized theory, a disturbance of a flow at Mach 1 does not have any influence upstream. Consequently,

$$\overline{\varphi}(x, y, z) = 0, \quad x < 0 \tag{8}$$

if the body lies in the region $x \geq 0$. This is one of the conditions $\overline{\varphi}$ must satisfy.

$\overline{\varphi}$ is a solution of Equation (5) in all space outside S and W, the regions in the xy-plane occupied by the wing and its wake (see Figure 1). In general, $\overline{\varphi}$ is discontinuous in these regions. A boundary condition on W is obtained by equating the pressures above and below the surface of the wake. From the linearized form of the pressure coefficient,

$$\overline{C}_p = -2 (\overline{\varphi}_x + ik\overline{\varphi})$$

(see Reference 6, p. 15) we get

$$\left[\overline{\varphi}_x (x,y,z) + ik\overline{\varphi} (x,y,z) \right] \Bigg|_{z=0-}^{0+} = 0, \quad (x,y) \text{ in } W \tag{9}$$

This condition, plus Equation (7) applied on the two sides of S, plus Equation (8), determine $\overline{\varphi}$ as a solution of Equation (5).

The conditions satisfied by $\overline{\varphi}(x,y,z)$ are satisfied also by $-\overline{\varphi}(x,y,-z)$. Hence, $\overline{\varphi}$ is an odd function of z. This implies that $\overline{C}_p$ is zero in the wake. In the half space $z > 0$, $\overline{\varphi}$ is a solution of Equation (5), which satisfies Equation (8) and the boundary conditions

$$\overline{\varphi}_z(x,y,0+) = \frac{\partial f}{\partial x} + ikf, \quad (x,y) \text{ in } S \tag{10}$$

$$\overline{\varphi}_x(x,y,0+) + ik\overline{\varphi}(x,y,0+) = 0, \quad (x,y) \text{ in } W \tag{11}$$

$$\overline{\varphi}(x,y,0+) = 0, \quad (x,y) \text{ not in } S + W \tag{12}$$

Such a solution may be built up from a doublet distribution over S + W or a source distribution over the half plane $z = 0$, $x > 0$.

4. BASIC SOURCE AND DOUBLET SOLUTIONS OF THE DIFFERENTIAL EQUATION (See References 7, 8, and 9.)

The solution of Equation (5) which represents a point source at the origin is

$$\overline{\varphi}_o(x,y,z) = \begin{cases} 0, & x \le 0 \\ -\dfrac{1}{2\pi}\dfrac{1}{x} e^{-\frac{1}{2} ik \left(x + \frac{y^2+z^2}{x} \right)}, & x > 0 \end{cases} \tag{13}$$

(See Reference 9.) The potential of a point doublet oriented parallel to the z-axis is obtained by differentiation, as

$$\overline{\varphi}_1(x,y,z) = \frac{\partial \overline{\varphi}_o}{\partial z} = \begin{cases} 0, & x \le 0 \\ \dfrac{ik}{2\pi}\dfrac{z}{x^2} e^{-\frac{1}{2} ik \left(x + \frac{y^2+z^2}{x} \right)}, & x > 0 \end{cases} \tag{14}$$

It is easily verified that these functions satisfy Equation (5) for $x \neq 0$. They are poorly behaved at $x = 0$ for real values of k.

To improve the behavior of $\overline{\varphi}_0$ and $\overline{\varphi}_1$ at x = 0, assume that k has a small negative imaginary part. This causes $\overline{\varphi}_0$ and $\overline{\varphi}_1$ to approach zero exponentially as $x \to 0+$, except at the origin. All partial derivatives of all orders have the same property. Thus, $\overline{\varphi}_0$ and $\overline{\varphi}_1$ are solutions of Equation (5) everywhere except at (0, 0, 0). In the final formulas to be obtained, the imaginary part of k can be put equal to zero.

Solutions of Equation (5) for $z > 0$ which satisfy Equation (8) are given for a distribution of sources as

$$\overline{\varphi}_s(x, y, z) = \iint_{\xi > 0} \rho(\xi, \eta)\, \overline{\varphi}_0(x-\xi,\ y-\eta,\ z)\, d\xi\, d\eta \tag{15}$$

and for a distribution of doublets as

$$\overline{\varphi}_d(x, y, z) = \iint_{\xi > 0} \rho(\xi, \eta)\, \overline{\varphi}_1(x-\xi,\ y-\eta,\ z)\, d\xi\, d\eta \tag{16}$$

where, to be completely general, $\rho(\xi, \eta)$ may be any function such that the integrals exist. From the form of $\overline{\varphi}_0$ and $\overline{\varphi}_1$, the region of integration may be restricted to the plane strip $0 < \xi < x$. It is shown in Appendix I that these functions satisfy the following boundary conditions for $z = 0$, $x > 0$:

$$\overline{\varphi}_{sz}(x, y, 0+) = \rho(x, y) \tag{17}$$

$$\overline{\varphi}_d(x, y, 0+) = \rho(x, y) \tag{18}$$

(in fact, if the same function ρ is used in both integrals, $\overline{\varphi}_d = \partial\overline{\varphi}_s/\partial z$).

5. THE DETERMINATION OF $\overline{\varphi}$ BY A SOURCE DISTRIBUTION

One method of attack on the problem of finding $\overline{\varphi}$ is to set $\overline{\varphi} = \overline{\varphi}_s$. Then, in terms of the upwash

$$w(x, y) = \overline{\varphi}_z(x, y, 0+) \tag{19}$$

we have from Equations (17) and (15)

$$\overline{\varphi}(x, y, z) = \iint_{\xi > 0} w(\xi, \eta)\, \overline{\varphi}_0(x-\xi,\ y-\eta,\ z)\, d\xi\, d\eta \tag{20}$$

for $z \geq 0$.

The values of w on S are known by Equation (10). Elsewhere, w is unknown, and it must be chosen so that the boundary conditions (11) and (12) are satisfied. We may take the limit as $z \to 0+$ in Equation (20) by taking the limit under the integral sign:

$$\overline{\varphi}(x, y, 0+) = \iint\limits_{\xi > 0} w(\xi, \eta)\, \overline{\varphi}_o(x-\xi,\ y-\eta,\ 0)\, d\xi\, d\eta \tag{21}$$

From Equations (11) and (12) are obtained the system of integral equations

$$\iint\limits_{\xi > 0} w(\xi, \eta)\, \overline{\varphi}_o(x-\xi,\ y-\eta,\ 0)\, d\xi\, d\eta = 0, \quad (x, y) \text{ not in } S + W \tag{22}$$

$$\left(\frac{\partial}{\partial x} + ik\right) \iint\limits_{\xi > 0} w(\xi, \eta)\, \overline{\varphi}_o(x-\xi,\ y-\eta,\ 0)\, d\xi\, d\eta = 0, \quad (x, y) \text{ in } W \tag{23}$$

Solution of Equations (22) and (23), followed by evaluation of $\overline{\varphi}$ according to Equation (21), would yield the values of $\overline{\varphi}$ on S, from which pressures and forces can be computed.

A box method based on a source distribution, described briefly in Reference 9, has been used by Weatherill at the Boeing Company. Some of his preliminary results are given in Reference 9.

6. THE DETERMINATION OF $\overline{\varphi}$ BY A DOUBLET DISTRIBUTION

If we set $\overline{\varphi} = \overline{\varphi}_d$, then by Equations (18), (16), and (12)

$$\overline{\varphi}(x, y, z) = \iint\limits_{S+W} \overline{\varphi}(\xi, \eta, 0+)\, \overline{\varphi}_1(x-\xi, y-\eta, z)\, d\xi\, d\eta \tag{24}$$

In terms of

$$\psi(x, y) = \lim_{z \to 0} \frac{1}{z} \overline{\varphi}_1(x, y, z) = \begin{cases} 0, & x \leq 0 \\ \dfrac{ik}{2\pi} \dfrac{1}{x^2}\, e^{-\frac{1}{2} ik\left(x + \frac{y^2}{x}\right)}, & x > 0 \end{cases} \tag{25}$$

the normal derivative of $\bar{\varphi}$ at z = 0 is given by a singular integral:

$$w(x, y) = \iint_{S+W} \bar{\varphi}(\xi, \eta, 0+)\, \psi(x-\xi, y-\eta)\, d\xi\, d\eta \qquad (26)$$

The values of $\bar{\varphi}$ $(\xi, \eta, 0+)$ must be determined then from

$$\iint_{S+W} \bar{\varphi}(\xi, \eta, 0+)\, \psi(x-\xi, y-\eta)\, d\xi\, d\eta = w(x,y), \quad (x, y) \text{ in } S \qquad (27)$$

$$\left(\frac{\partial}{\partial x} + ik\right) \bar{\varphi}(x, y, 0+) = 0, \quad (x, y) \text{ in } W \qquad (28)$$

7. A COMPARISON OF THE METHODS

Except for the singularity of the integral in Equation (27), all points of difference are in favor of solving the problem by doublets. There are these points:

a. The region of integration in the source method extends theoretically to $\pm\infty$ in η; even practically, the region must be extended an extreme distance. In the doublet method, the region is restricted to S + W. This distinction is not so great for supersonic flows. There, the region of influence of the wing is swept back along Mach lines, and the set of points in this region that influences the wing is bounded (see Reference 10).

b. After the unknown function under the integral sign is known, the source method requires an extra step – the evaluation of $\bar{\varphi}$ on the wing from Equation (21).

c. If values in the wake must be considered, the condition in the wake for the source method, Equation (23), is more complicated than the corresponding condition, Equation (28), for the doublet method.

The doublet method was used because of point a.

8. THE ADVANTAGE OF A STRAIGHT TRAILING EDGE

Suppose the wing has a straight trailing edge perpendicular to the direction of flow (x = constant along the edge); then the wing is not influenced by the wake. This is reflected in the equations by the fact that the integrands are zero when $\xi > x$. Hence, in either method, for the determination of $\bar{\varphi}$ on the wing, the condition in W need not be used.

9. THE DOUBLET BOX METHOD

Consider a flow at Mach 1 past an oscillating wing with its nose at the origin, lying approximately in the xy-plane, with x = 1 along the trailing edge. The value of the unsteady potential $\bar{\varphi}$ on the wing may be found by solution of Equation (27), which may be written as

$$\iint_S \bar{\varphi}(\xi, \eta, 0+)\, \psi(x-\xi, y-\eta)\, d\xi\, d\eta = w(x, y), \quad (x, y) \text{ in } S \tag{29}$$

To get an approximate solution of this equation, let the xy-plane be covered with a grid of square boxes with sides of length d, so that box edges lie along the coordinate axes (see Figure 2). Let the region B be composed of all boxes whose centers lie in S; B is an approximation to S by boxes. Let i, j be box indexes in the x- and y-directions. Approximate $\bar{\varphi}$ by a constant value $\bar{\varphi}_{ij}$ in the (i, j)-th box B_{ij}. Impose the condition of Equation (7) at the center (x_i, y_j) of each box B_{ij} in B, with the region of integration replaced by B. Then Equation (29) gives a system of linear algebraic equations for the $\bar{\varphi}_{ij}$'s:

$$\sum_{i', j'} \bar{\varphi}_{i'j'} \iint_{B_{i'j'}} \psi(x_i-\xi, y_j-\eta)\, d\xi\, d\eta = w(x_i, y_j) \tag{30}$$

Examination of the integral in Equation (30) shows that it depends on i, j, i', j' only via i-i', |j-j'|. The notation

$$A(i-i', |j-j'|) = \iint_{B_{i'j'}} \psi(x_i-\xi, y_j-\eta)\, d\xi\, d\eta \tag{31}$$

is introduced. Formulas for the evaluation of this quantity are given in Appendix II.

Segregating the terms with i'=i on the left, Equation (30) becomes

$$\sum_{j'} A(0, |j-j'|)\, \bar{\varphi}_{ij'} = w(x_i, y_j) - \sum_{i'<i} \sum_{j'} A(i-i', |j-j'|)\, \bar{\varphi}_{i'j'} \tag{32}$$

For fixed i and varying j, this is a smaller system of equations that may be solved for each consecutive value of i.

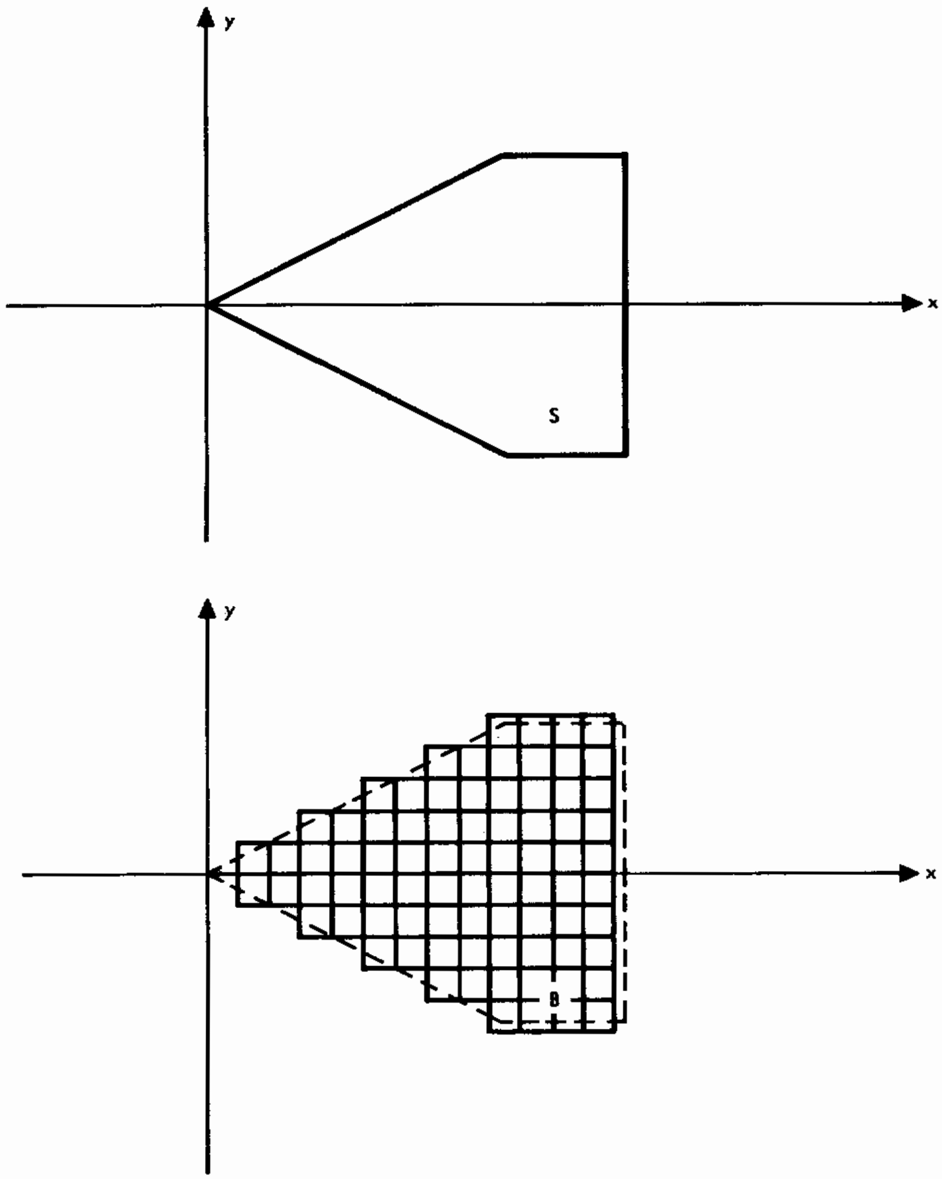


Figure 2. Approximation of the Wing by Region B

Now suppose the wing is symmetric about the x-axis; then only modes of oscillation that are symmetric or antisymmetric in y need be treated. Consider a symmetric mode. $\overline{\varphi}_{ij}$ will have the same value at corresponding boxes across the x-axis. This may be used to reduce the range of the sums in Equation (32) and the range of j. Let j = 1 in the row of boxes in which $0 < y < d$. Then, combining terms for symmetrically placed boxes,

$$\sum_{j' \geq 1} [A(0, |j-j'|) + A(0, j+j'-1)] \overline{\varphi}_{ij'} \tag{33}$$

$$= w(x_i, y_j) - \sum_{i'<i} \sum_{j' \geq 1} [A(i-i', |j-j'|) + A(i-i', |j-j'|)] \overline{\varphi}_{i'j'}, \quad j \geq 1$$

The equations for $j \leq 0$ are implied by those with $j \geq 1$. Thus, the size of the system has been reduced by a factor of 2.

For antisymmetric modes, Equation (33) applies, with the sums of values of A replaced by differences.

10. EXTENSIONS OF THE METHOD

The computer program discussed in Section 3 has some restrictions that are not inherent in the box method, such as the requirement of a straight trailing edge. Some possible modifications that extend the applicability of the program will now be described.

To modify the program for modes antisymmetric in y, it is only necessary to change some of the signs in Equation (33), as indicated in the discussion above, and replace even powers of y by odd powers in the formulas used for deflection and potential.

To deal with a more general trailing edge, it is necessary to use the values of $\overline{\psi}$ in the wake. For fixed y, if $x = x_T$ at the trailing edge, Equation (28) may be integrated to give

$$\overline{\psi}(x, y, 0+) = e^{-ik(x - x_T)} (x_T, y, 0+)$$

in W. In addition to the set of boxes B on the wing, a corresponding set of boxes B_W on W must be considered. After finding a value $\overline{\psi}_{ij}$ in a box of B along the trailing edge, the formula above may be used to find values in the boxes directly downstream. If the ith row of boxes includes boxes of B_W, to the right side of Equation (33) must be added the contribution of all boxes $B_{i'j'}$ in B_W with $i' \leq i$. The computer program must also be modified in several other respects, to take into account the more general wing shape.

A wing that consists of several almost planar sections in different planes, such as a wing with folded tips, may also be handled by the doublet box method. Equation (33) applies, if $\bar{\Psi}_{ij}$ is interpreted as one-half of the discontinuity in $\bar{\Psi}$ between the upper and lower surfaces. The influence coefficients involved are given by a more general formula (not given in this report), allowing for out-of-plane influence of the doublets. Formulas analogous to those of Appendix II may be developed, which are not much more complicated. The main effect of this extension on the computer program would be a greater number of distinct values of the influence coefficients, so that it would not be possible to store them all in an array in core unless the limit on the number of boxes in each direction were considerably reduced.

Rectangular boxes, not necessarily square, may be used. Let the boxes have sides of length d_1 chordwise and d_2 spanwise.

If

$$\ell_1 = kd_1, \; \ell_2 = kd_2^2/d_1$$

the formula for the influence coefficients, Equation (39) in Appendix II, must be replaced by

$$A\,(n,\;m) = \frac{ik}{2\pi} \iint\limits_{\substack{|v-m|<1/2 \\ |u-n|<1/2 \\ u>0}} \frac{du\,dv}{u^2}\, e^{-1/2\, i\,(\ell_1 u + \ell_2 v^2/u)}$$

This may be evaluated by the methods of Appendix II. Except for this difference, the method is essentially the same. The best choice of box shape probably depends on the aspect ratio of the wing.

3. DESCRIPTION OF THE COMPUTER PROGRAM

1. COORDINATE SYSTEMS

An initial coordinate system $(\tilde{x}, \tilde{y}, \tilde{z})$ is assumed, with the $\tilde{x}$-axis in the direction of the flow. The undisturbed position of the wing is in a region S in the $\tilde{x}\tilde{y}$-plane, with the x-axis along the center line and the origin at the nose (see Figure 1). This coordinate system is used in the data.

In the program, a dimensionless coordinate system (x, y, z) is used, based on the root chord length b:

$$x = \tilde{x}/b$$

$$y = \tilde{y}/b$$

$$z = \tilde{z}/b$$

2. WING GEOMETRY

The wing is symmetric, with trailing edge $\tilde{x} = b$. To complete its description, the portion of the leading edge on which $\tilde{y} > 0$ must be specified. This is done by giving the coordinates of the end points of NS line segments along the edge $(1 \le NS \le 3)$, beginning at a point at which $\tilde{y} = 0$: $(0, \tilde{y}_o)$, $(\tilde{x}_1, \tilde{y}_1)$, . . . , $(\tilde{x}_{NS}, \tilde{y}_{NS})$. The edge of S includes the polygonal line through these points. If $\tilde{y}_o > 0$, it also includes the line from the origin to $(0, \tilde{y}_o)$. If $\tilde{x}_{NS} < b$, it includes the line from $(\tilde{x}_{NS}, \tilde{y}_{NS})$ to $(b, \tilde{y}_{NS})$. (See Figure 3.)

Leading edges of fairly general shape may be approximated by such polygonal lines.

3. THE DEFLECTION DATA

A mode is specified by the vertical deflection function $f(\tilde{x}, \tilde{y})$ in terms of which the equation for the instantaneous position of the planform is

$$\tilde{z} = \text{Re}\,[\delta \cdot e^{i\omega t} f(\tilde{x}, \tilde{y})]$$

where δ is a constant.

In the program, f is assumed to be a polynomial in $\tilde{x}$ and $\tilde{y}^2$. The data may give either the coefficients of this polynomial, or values of f at a

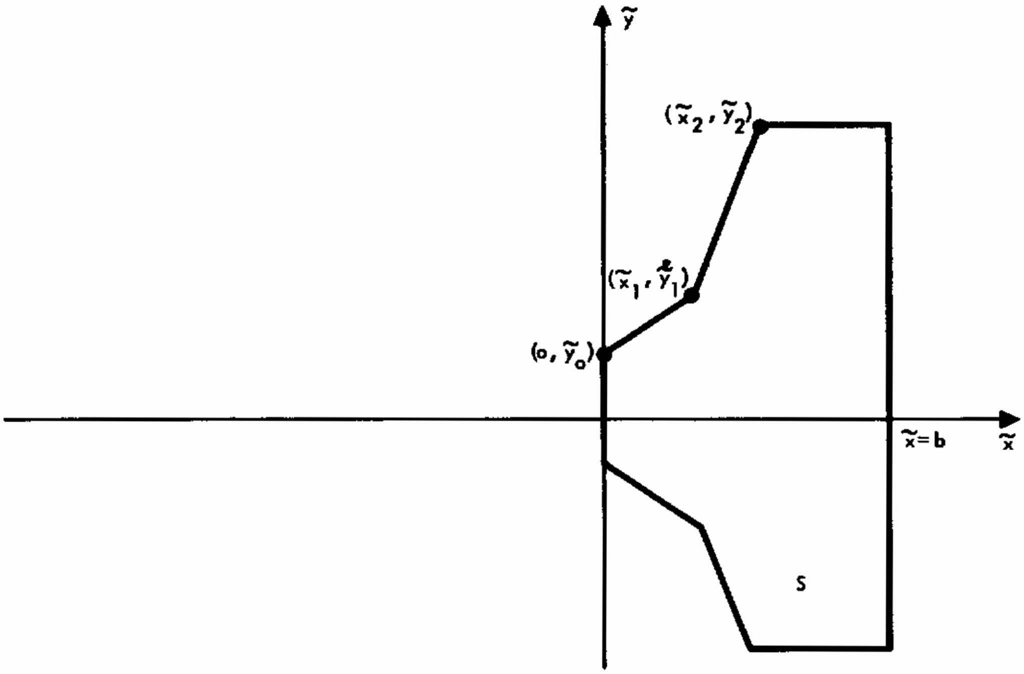


Figure 3. Wing Geometry (NS = 2)

set of points on the wing. In the latter case, a polynomial is fitted to the given values by a least square error technique.

4. LEAST SQUARE SURFACE FITS

The problem involved here is the approximation of a function of x and y by an expression of the form

$$\overline{\varphi}(x, y) = \sum_{n, m} a_{nm} \, x^n \, y^{2m} \, F_{(x, y)}$$

when a set of values of the function is known. This arises in the program in two places. The subroutine DRED fits a representation of the deflection of this type with F = 1 to the given deflection values. In the subroutine BØXP, such a fit is made for the potential, with

$$F(x, y) = \left\{ \begin{array}{l} \sqrt{x^2 - x_o(y)^2} \\ \text{or} \\ \sqrt{x - x_o(y)} \end{array} \right\} \cdot \left\{ \begin{array}{l} \sqrt{1 - y^2/y^2{}_{max}} \\ \text{or} \\ 1 \end{array} \right\}$$

($x = x_o(y)$ is the equation of the leading edge) depending on the wing shape. This factor approximates the proper behavior of $\overline{\varphi}$ at the edges. The factor $\sqrt{x^2 - x_o(y)^2}$ is used for a pointed nose ($\tilde{y}_o = 0$), and $\sqrt{x - x_o(y)}$ for an unswept nose ($\tilde{y}_o > 0$). The factor $\sqrt{1 - y^2/y^2_{max}}$ is included if the planform has a side edge along which $y = y_{max}$.

The factor $F(x, y)$ is real, so the values of $\overline{\varphi}$ have real and imaginary parts that involve only the corresponding parts of the a_{nm}'s. Hence, these real and imaginary parts may be handled separately, reducing the problem from one in complex numbers to one in real numbers.

Let $\alpha_{nm} = \text{Re}\left[a_{nm}\right]$, and let the real parts of given values of the function at data points be $\overline{\varphi}'_j$ at (x_j, y_j), $j = 1, \ldots, NP$. Then for the real parts we wish to have

$$\sum_{n,m} \alpha_{nm}\, x_j^{\,n}\, y_j^{\,2m}\, F(x_j, y_j) \cong \overline{\varphi}'_j, \quad j = 1, \ldots, NP$$

The least squares method minimizes

$$Q = \sum_j \left[\sum_{n,m} \alpha_{nm}\, x_j^{\,n}\, y_j^{\,2m}\, F(x_j, y_j) - \overline{\varphi}'_j \right]^2$$

(See Reference 11, Chapter 16.)

For condensed notation, let r be a single index over the pairs (n, m), let $\alpha_{nm} = \alpha_r$, and $x_j^{\,n}\, y_j^{\,2m}\, F(x_j, y_j) = A_{jr}$. Then

$$Q = \sum_j \left[\sum_r \alpha_r A_{jr} - \overline{\varphi}'_j \right]^2$$

Let the range of r be from 1 to $NC \leq NP$.

To minimize Q, we set

$$\frac{\partial Q}{\partial \alpha_r} = 0, \quad r = 1, \ldots, NC$$

This leads to the system of equations

$$\sum_{r'} \left(\sum_{j} A_{jr} A_{jr'} \right) \alpha_{r'} = \sum_{j} A_{jr} \bar{\varphi}_j', \quad r = 1, \ldots, NC \tag{34}$$

Put

$$\left. \begin{aligned} \sum_{j} A_{jr} A_{jr'} &= B_{rr'} \\ \sum_{j} A_{jr} \bar{\varphi}_j' &= C_r' \end{aligned} \right\} \tag{35}$$

Then Equation (34) reduces to

$$\sum_{r'} B_{rr'} \alpha_{r'} = C_r', \quad r = 1, \ldots, NC \tag{36}$$

The matrices $(B_{rr'})$ and (C_r') must be set up to solve Equation (36). It is not necessary, however, to set up the matrix (A_{jr}). Only one row of (A_{jr}) is needed at a time. This is fortunate, because the program allows (A_{jr}) to become as large as 2500 x 20. For each value of j, the jth row of (A_{jr}) is computed, and from this the jth terms in the sums in Equation (35) are formed and added in.

In the complex case, there is a corresponding system of equations for the imaginary parts:

$$\sum_{r'} B_{rr'} \beta_{r'} = C_r''$$

The two systems of equations are solved together by the subroutine XSIMEQ, which allows for more than one set of values on the right.

5. GENERALIZED FORCES

The generalized force coefficient L_{ij} is defined (Reference 6) by

$$L_{ij} = \frac{1}{1/2\, \rho U_\infty^2 S} \iint_S \Delta p_i(x, y)\, f_j(x, y)\, dx\, dy$$

where Δp_i is the lifting pressure difference in the ith mode, and f_j is the deflection function in the jth mode. In terms of the potential $\overline{\varphi}(x, y)$ on the upper surface,

$$\Delta p_i = 2\rho U_\infty^2 (\overline{\varphi}_x + i k \overline{\varphi})$$

$$L_{ij} = \frac{4}{S} \iint_S (\overline{\varphi}_x + i k \overline{\varphi}) f_j \, d x \, d y$$

After integration by parts,

$$L_{ij} = \frac{4}{S} \left\{ \int_{x=1} \overline{\varphi} f_j \, dy + \iint_S \overline{\varphi}\left(i k f_j - \frac{\partial f_j}{\partial x}\right) d x \, d y \right\} \tag{37}$$

In Equation (37) insert the series

$$\overline{\varphi} = \sum_{n, m} a_{nm} x^n y^{2m} F(x, y)$$

$$f_j = \sum_{n', m'} d_{n'm'} x^{n'} y^{2m'}$$

The result is

$$L_{ij} = \frac{8}{S} \sum_{n', m'} d_{n'm'} \sum_{n, m} a_{nm} \left[\frac{1}{2} \int_{x=1} y^{2m+2m'} F(1, y) \, dy \right.$$

$$+ ik \cdot \frac{1}{2} \iint_S x^{n+n'} y^{2m+2m'} F(x, y) \, d x \, d y$$

$$\left. - n' \cdot \frac{1}{2} \iint_S x^{n+n'-1} y^{2m+2m'} F(x, y) \, d x \, d y \right]$$

The integrals in this expression depend only on the wing shape. They are computed by the subroutine FØRCI before the work on the individual modes begins. During the work on the ith mode, the sum over n and m is performed in the last part of the subroutine BØXP, for each set of values of n' and m'. The sum over n' and m' and multiplication by 8/S is performed in the last part of the main program.

6. THE USE OF GAUSSIAN QUADRATURE IN THE EVALUATION OF GENERALIZED FORCES

Gaussian quadrature is an approximation of the form

$$\int_a^b f(u)\,du \cong \sum_{j=1}^{N} h_j\, f(u_j)$$

exact for polynomials of degree $\leq 2N - 1$. (See Reference 11, Chapter 7.) This formula is used with $(a, b) = (0, 1)$, $N = 6$. The values of the h_j's and u_j's for this case were obtained from values listed in Reference 11. They are given as H(1), . . . , H(6), U(1), . . . , U(6) in the subroutine SECT.

Subroutine FØRCI finds the values of

$$AXY(I, J) = \frac{1}{2} \iint_S x^{I-1}\, y^{2J-2}\, F(x, y)\, dx\, dy$$

and

$$AY(J) = \frac{1}{2} \int_{x=1} y^{2J-2}\, F(1, y)\, dy$$

for I, J = 1, . . . , 9. To do this, the contributions to the integrals from each section of wing behind a straight piece of leading edge are calculated separately in SECT.

The form of F(x, y) is

$$F(x, y) = \begin{Bmatrix} \sqrt{x - x_o(y)} \\ \text{or} \\ \sqrt{x^2 - x_o(y)^2} \end{Bmatrix} \cdot \begin{Bmatrix} \sqrt{1 - y^2/y^2_{max}} \\ \text{or} \\ 1 \end{Bmatrix}$$

depending on the wing shape. We have integrals that behave like square roots at the leading edge. The integrals over one wing section are of the form

$$BXY = \int_{y-}^{y+} dy \int_{x_o(y)}^{1} dx\, x^{I-1}\, y^{2J-2}\, F(x, y)$$

and

$$BY = \int_{y_-}^{y_+} dy\, y^{2J-2}\, F(1, y)$$

In BXY, the chordwise integral is evaluated first at each value of y at which it will be needed. The new variable

$$u = \sqrt{x - x_o(y)} \Big/ \sqrt{1 - x_o(y)} \qquad (38)$$

is introduced. Then

$$\int_{x_o(y)}^{1} dx\, x^{I-1}\, y^{2J-2}\, F(x, y) = \int_{0}^{1} du \cdot 2\left[1 - x_o(y)\right] x^{I-1}\, y^{2J-2}\, F(x, y)$$

The integrand, as a function of u, is well-behaved at the leading edge. It is approximated by

$$\sigma(y) = \sum_{i=1}^{6} h_i \cdot 2\left[1 - x_o(y)\right] x_i^{I-1}\, y^{2J}\, F(x_i, y)$$

where x_i is computed from the value of u_i according to Equation (38).

In the y-integration in BXY and BY, the integrand approaches zero as as $y \to y_{max}$ like $\sqrt{1 - y/y_{max}}$ or $(1 - y/y_{max})^{3/2}$. Accordingly, the change of variable

$$y = \begin{cases} y_+ - (y_+ - y_-)v, & y_+ < y_{max} \\ y_+ - (y_+ - y_-)v^2, & y_+ = y_{max} \end{cases}$$

is used, which makes the interval of integration $0 < v < 1$ and removes the square root behavior in the last section of the wing. This leads to the formulas

$$BXY = (y_+ - y_-) \sum_{j=1}^{6} h_j \, \sigma(y_j) \cdot \begin{cases} 1, & y_+ < y_{max} \\ 2u_j, & y_+ = y_{max} \end{cases}$$

$$BY = (y_+ - y_-) \sum_{j=1}^{6} h_j \, y_j^{2J-2} \, F(1, y_j) \cdot \begin{cases} 1, & y_+ < y_{max} \\ 2u_j, & y_+ = y_{max} \end{cases}$$

7. LEADING EDGE CORRECTION

The value of potential found for each box from Equation (33) is taken to be the value of $\overline{\varphi}$ at the box center. Thus, the values obtained are in error only by virtue of the error introduced in the values of upwash when the actual distribution of potential in a box is replaced by this constant value. This error is especially important in the first row of boxes, for a wing with an unswept leading edge. The major effect is on the upwash values in that row.

To estimate this error, consider the two-dimensional case, in which $\overline{\varphi}$ is independent of y. In Equation (26), the expression for upwash due to a doublet distribution, integrate by parts over ξ, then integrate over η. The result is

$$\overline{w}(x, y) = \frac{ik}{2\pi} \iint_{0<\xi<x} \frac{d\xi \, d\eta}{(x - \xi)^2} \overline{\varphi}(\xi, \eta, 0+) \, e^{-\frac{1}{2} ik \left(x - \xi + \frac{(y - \eta)^2}{x - \xi}\right)}$$

$$= \frac{1}{\pi} \iint_{0<\xi<x} \frac{d\xi \, d\eta}{(y - \eta)^2} \left(\overline{\varphi}_\xi + \frac{1}{2} ik\overline{\varphi}\right) e^{-\frac{1}{2} ik \left(x - \xi + \frac{(y - \eta)^2}{x - \xi}\right)}$$

$$= -\sqrt{\frac{2ik}{\pi}} \int_0^x \frac{d\xi}{\sqrt{x - \xi}} \, e^{-\frac{1}{2} ik(x - \xi)} \left(\overline{\varphi}_\xi + \frac{1}{2} ik\overline{\varphi}\right)$$

For $x = \frac{1}{2} d$, if kd is small,

$$\overline{w}\left(\frac{1}{2}\,d, y\right) \cong -\sqrt{\frac{2ik}{\pi}} \int_0^{\frac{1}{2}d} \frac{d\xi}{\sqrt{\frac{1}{2}d - \xi}}\, \overline{\varphi}_\xi(\xi, \eta, 0+)$$

The correct leading edge behavior is possessed by the expression $\overline{\varphi} = C\sqrt{\xi}$. We have

$$\overline{w}\left(\frac{1}{2}\,d, y\right)\Bigg|_{\overline{\varphi} = C\sqrt{\xi}} = -\sqrt{\frac{2ik}{\pi}}\,\frac{C}{2}\int_0^{\frac{1}{2}d} \frac{d\xi}{\sqrt{\xi\left(\frac{1}{2}d - \xi\right)}} = -\sqrt{\frac{2ik}{\pi}}\,C\,\frac{\pi}{2}.$$

If $\overline{\varphi}$ is constant on $0 < \xi < d$, and has the value $C\sqrt{1/2\,d}$, then $\overline{\varphi}_\xi$, in the above integral, can be expressed in terms of a delta function:

$$\overline{\varphi}_\xi = C\sqrt{\frac{1}{2}d}\;\delta(\xi)$$

Accordingly,

$$\overline{w}\left(\frac{1}{2}\,d, y\right)\Bigg|_{\overline{\varphi} = C\sqrt{\frac{1}{2}d}} = -\sqrt{\frac{2ik}{\pi}}\;C\,.$$

Note that the latter value is smaller than the value of $\overline{w}$ evaluated for $\overline{\varphi} = C\sqrt{\xi}$ by the factor $2/\pi$. This implies that the values of potential found for the first row of boxes will be more accurate if the upwashes in that row are multiplied by $2/\pi$.

8. THE FORM OF OUTPUT

The viewpoint is taken that calculation of the generalized forces is the basic purpose of the program. They are always printed out. There are other outputs that will be printed if the appropriate data signal is given. Each of the following is printed if the data item specified in parentheses is non-zero:

a. The coefficients of the deflection polynomial, if it has been computed as a fit to given values of deflection, DA(87)

b. The upwash array, DA(88)

c. The potential array, DA(89)

d. The coefficients of the potential series, DA(90)

e. Values of pressure and potential at the box centers, computed from the series, DA(91).

9. THE DATA SUBROUTINE DATRD

This subroutine reads all data items into the array DA. Punched cards used for data are considered to contain six fields of length 12 as indicated in the sample data sheets. The first field contains information for DATRD. Ending in column 12 is an integer giving the location in the data array for the entry in the second field. The following fields go into consecutive locations, if the data are numeric. Floating point numbers should be written with decimal points, and fixed point numbers adjusted to the right end of the field.

The word ALPHA in columns 2 through 6 indicates that the data on the card are alphanumeric. These are stored in DA in a different way, taking up ten locations per card. The data may be printed later, just as they appeared on the card.

On a numeric card, if a field is blank the corresponding location in DA is unchanged. This is not true for an ALPHA card.

A minus sign in column 1 indicates the last card to be read at the time. DATRD reads cards until this minus sign is encountered, then returns to the main program.

10. A NOTE ON THE USE OF TAPES

In writing of this program, the following tape numbers have been used: output tape, number 6; input tape, number 5; and tape simulated by an internal file, number 99.

The tape numbers 5 and 99 appear in the subroutine DATRD. Elsewhere only the output tape number is used. It occurs in the main program, and in the subroutines SHAPE, DRED, BØXP and BØXPØ.

11. USE OF THE PROGRAM FOR FIXED WING AND MODES AT VARIOUS FREQUENCIES

If a non-zero quantity is entered in the appropriate location in the data array, (DA26), it indicates that a wing shape and set of modes to be used are the same already used for another frequency. Then quantities that depend only on wing shape and deflection data will not be computed, but will be taken from the permanent arrays in which they were stored in the previous case. The number of boxes along the root chord, DA(27), may not be changed when this is done.

When this option is exercised, all work for the present frequency will be carried out after reading one set of data, which need only include the frequency and the indicator, DA (26). Titles for the individual modes are not printed.

12. DESCRIPTION OF THE DATA ARRAY

All data are entered into the array DA, dimensioned for 700, as described in Paragraph 9. The layout of the array is as follows:

1 - 10	Title
13 - 22	Mode Title
23 :	Frequency (cycles per unit of time), ν
24 :	Root chord length, b
25 :	Speed of sound, a
26 :	Indicator for new frequency (See Paragraph 11)
27 :	Number of boxes along root chord
28 :	Number of modes
29 :	Number of sections of leading edge to be given (See Paragraph 2)
30 - 36	Coordinates of points on the leading edge (See Paragraph 2)
39 :	Indicator to suppress calculation of potential for a mode
46 - 70	Coefficients of the deflection polynomial (See Paragraph 3)
87 - 91	Output indicators (See Paragraph 8)
98 :	Number of points at which deflections are given (See Paragraph 3)
99 :	Number of $\tilde{x}$ values
100 :	Number of $\tilde{y}$ values
101 - 700	Deflection data for a maximum of 150 points

Note: 23, 24, 25 and 30-36 must be entered in consistent units of length and time.

13. OUTLINE OF THE PROGRAM

For the purpose of description, the main program has been divided into 20 parts, as indicated in Figure 4, which shows the flow of the program and the subroutines called.

14. SIZE LIMITATIONS OF THE PROGRAM

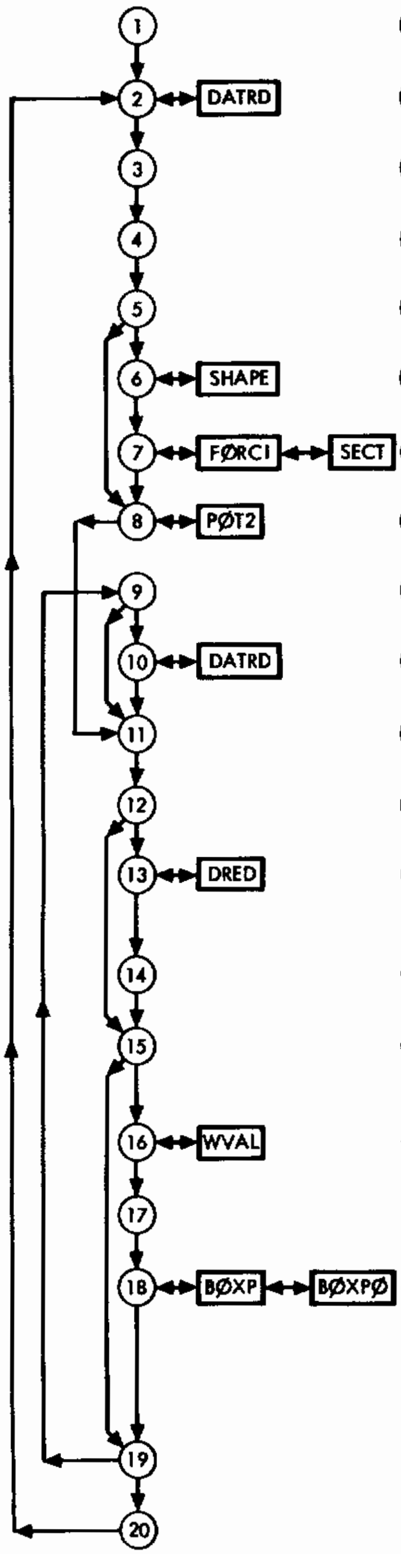
The program's size limitations are as follows:

a. Box size – the half wing must be enclosed in a rectangle that contains no more than 50 boxes in each direction. (The use of a large number of boxes is not recommended, because the time required is roughly proportional to the cube of the number of boxes along the root chord. The possibility of 50 boxes in each direction is intended to allow a large range in aspect ratio.)

b. Number of modes – ten at most.

c. Number of points at which the deflections are given for one mode – 150 at most.

d. Terms in the deflection polynomial – this is $\sum d_{nm} x^n y^{2m}$, where $0 \leq n \leq 4$, $0 \leq m \leq 4$.



(1) The data array is initialized by making the titles blank and weights 1.0.

(2) Subroutine DATRD reads the first block of data

(3) The following quantities are computed: reduced frequency $k = 2\pi\nu b/a$, D = dimensionless box size, DH = 0.5D.

(4) The title is printed, with the values of L (the number of boxes along the chord), k, and ν.

(5) If DA(26) ≠ 0 (See Paragraph 11 of this section) control transfers to Part (8)

(6) Subroutine SHAPE computes the number of boxes in each row and the wing area.

(7) Subroutine FØRCI computes the integrals to be used in evaluation of generalized forces (See Paragraphs 5, 6 of this section).

(8) Subroutine PØT2 computes the influence coefficients. Control goes to Part (11)

(9) If DA(26) ≠ 0 (see Paragraph 11 of this section) control goes to Part (11)

(10) DATRD reads the next block of data.

(11) The mode number and title are printed.

(12) If DA(26) ≠ 0, control goes to Part (15)

(13) The subroutine DRED computes the deflection polynominal if deflection values were given. The coefficients are transformed into coefficients of a polynominal in the dimensionless variables x, y and stored in the permanent array DF.

(14) G(M) = DA(39)

(15) If G(M) ≠ 0, this indicates that the potential should not be computed for the current mode. In this case, this mode will be used only as a deflection in the computation of generalized forces. Control goes to Part (19)

(16) Subroutine WVAL sets up the array of downwash values W.

(17) The first row of values in W are corrected as described in Paragraph 7 of this section.

(18) Subroutine BØXP is called. The subroutine BØXPØ solves Equation (33) to get the array of potential values. A least-squares fit is made to these values as described in Paragraph 8 of this section. The print options (b), (c), (d), (e) listed in Paragraph 8 of this section are handled by this subroutine. The final section of the subroutine stores in the array PS the sums over the potential coefficients a_{nm} shown in Paragraph 5 of this section.

(19) If there are more modes, control returns to Part (9)

(20) The generalized forces are computed by summing over the deflection coefficients d_{nm} as described in Paragraph 5 of this section. Control goes to Part (2)

Figure 4. Program Flow Diagram

4. RESULTS

1. THE ASPECT RATIO 1.5 DELTA WING

The computer program was run for the plunging and pitching modes (pitch axis at $x = 0$) at the reduced frequencies $k = 0.2,\ 0.5,\ 0.8,\ 1.0$. Forty boxes along the root chord were used, which leads to about 300 boxes on the half-wing.

Theoretical values for comparison were calculated from Davies' formulas (Reference 12). These are analytic expressions of the solution of Equation (5) for the potential and generalized forces for the delta wing in rigid modes of oscillation, expressed as series in k. Figures 5 through 7 show the values of generalized forces L_{11} (lift due to plunge), L_{21} (lift due to pitch), and L_{22} (moment due to pitch). Note that the vertical scales have been expanded in the portion of interest, especially for L_{11}. Most of the values agree to within 2 or 3 percent.

The differences indicate the errors introduced by the box method in the solution of Equation (5), as distinguished from the errors inherent in this equation.

Figure 8 gives the chordwise distribution of values of $\bar{\phi}$ for the plunging mode at $k = 0.5$, for $y = y_{max}/3 = 0.125$.

2. THE ASPECT RATIO 2.0 RECTANGULAR WING

The plunging and pitching modes were again used at $k = 0.3,\ 0.6,\ 0.9$. Twenty-five boxes were allowed along the chord, giving 625 boxes on the half-wing. The values of L_{21} and L_{22} are shown in Figures 9 and 10, with values from Landahl (Reference 6, page 84) for comparison. Landahl's values were obtained by a method of solution of Equation (5) which applies only to a rectangular wing in modes of oscillation with a deflection independent of y.

3. THE ASPECT RATIO 3.0 RECTANGULAR WING

Finally, for the aspect ratio 3.0 rectangular wing, a comparison is made with experimental pressure values. These values were given in Reference 13 for a 5-percent thickness wing oscillating in an elastic bending mode. At Mach 1, the reduced frequency was 0.24. The chordwise pressure distribution at $y = y_{max}/2$ is shown in Figure 11.

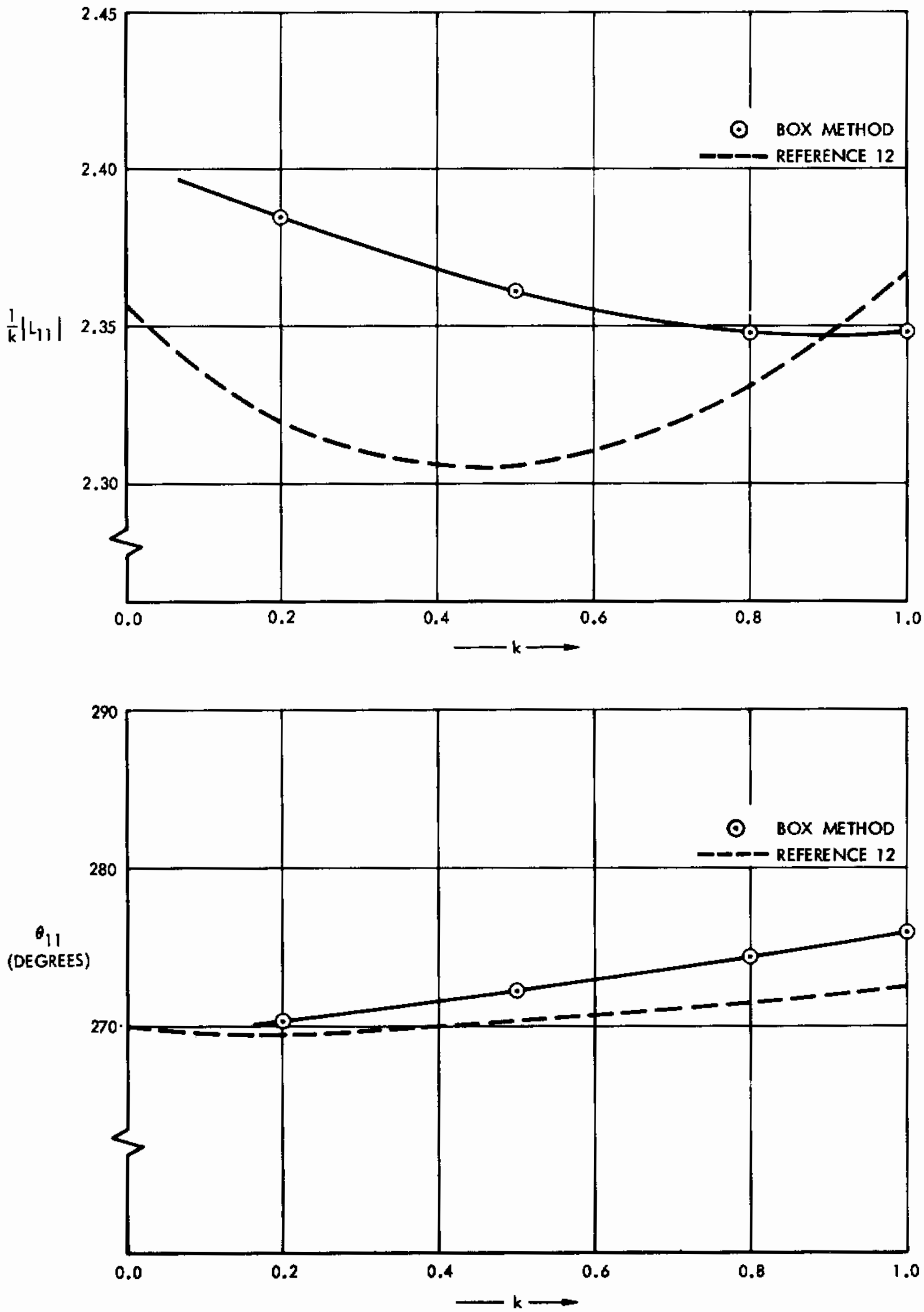


Figure 5. Lift Due to Translation for an Aspect Ratio 1.5 Delta Wing (Compared With Reference 12)

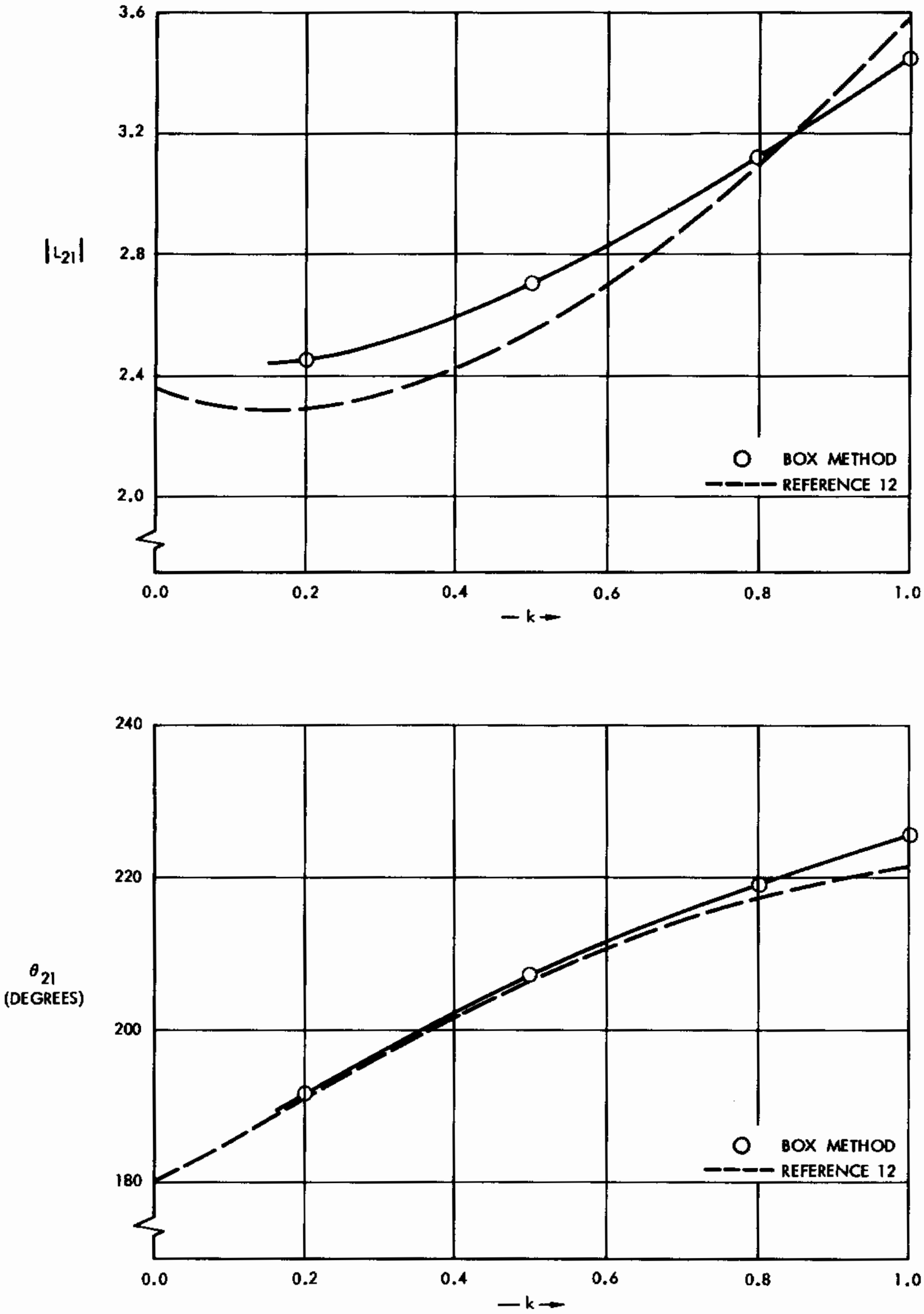


Figure 6. Lift Due to Pitch for an Aspect Ratio 1.5 Delta Wing (Compared With Reference 12)

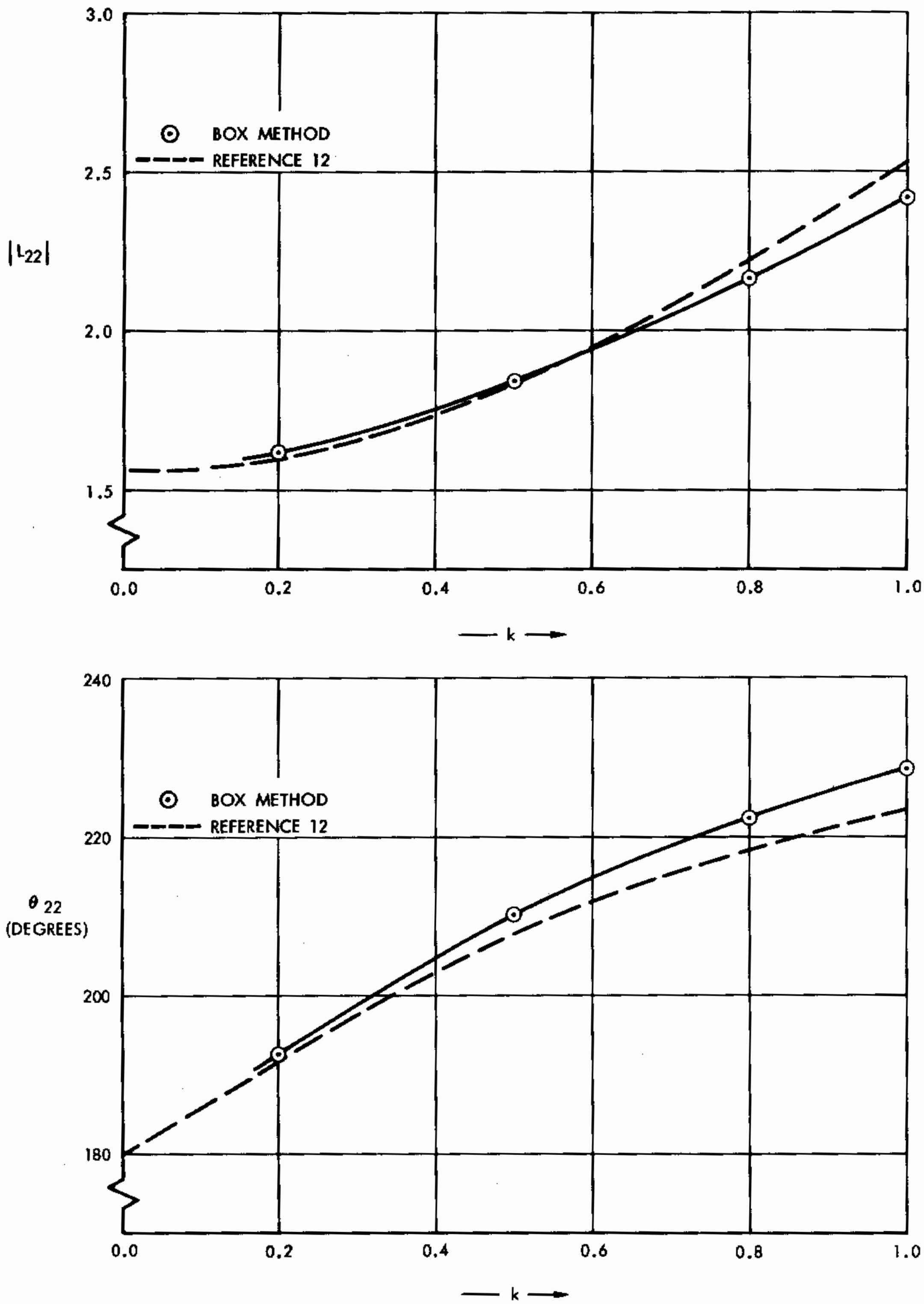


Figure 7. Moment Due to Pitch for an Aspect Ratio 1.5 Delta Wing (Compared With Reference 12)

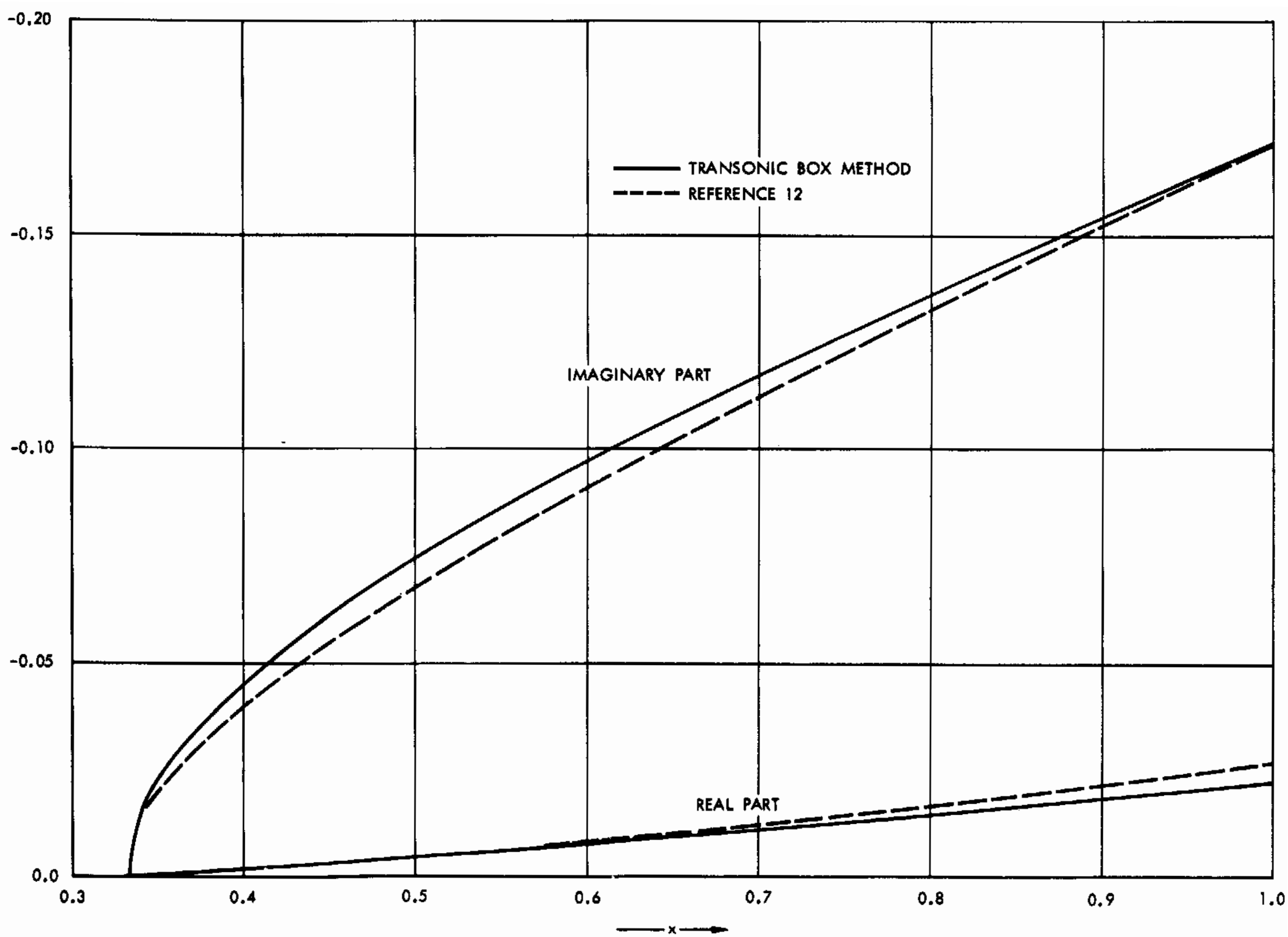


Figure 8. Real and Imaginary Parts of the Unsteady Potential $\overline{\varphi}$ in the Plunging Mode for an Aspect Ratio 1.5 Delta Wing at k = 0.5; Chordwise Distribution for y = 0.125 = g Max/3 (Compared With Reference 12)

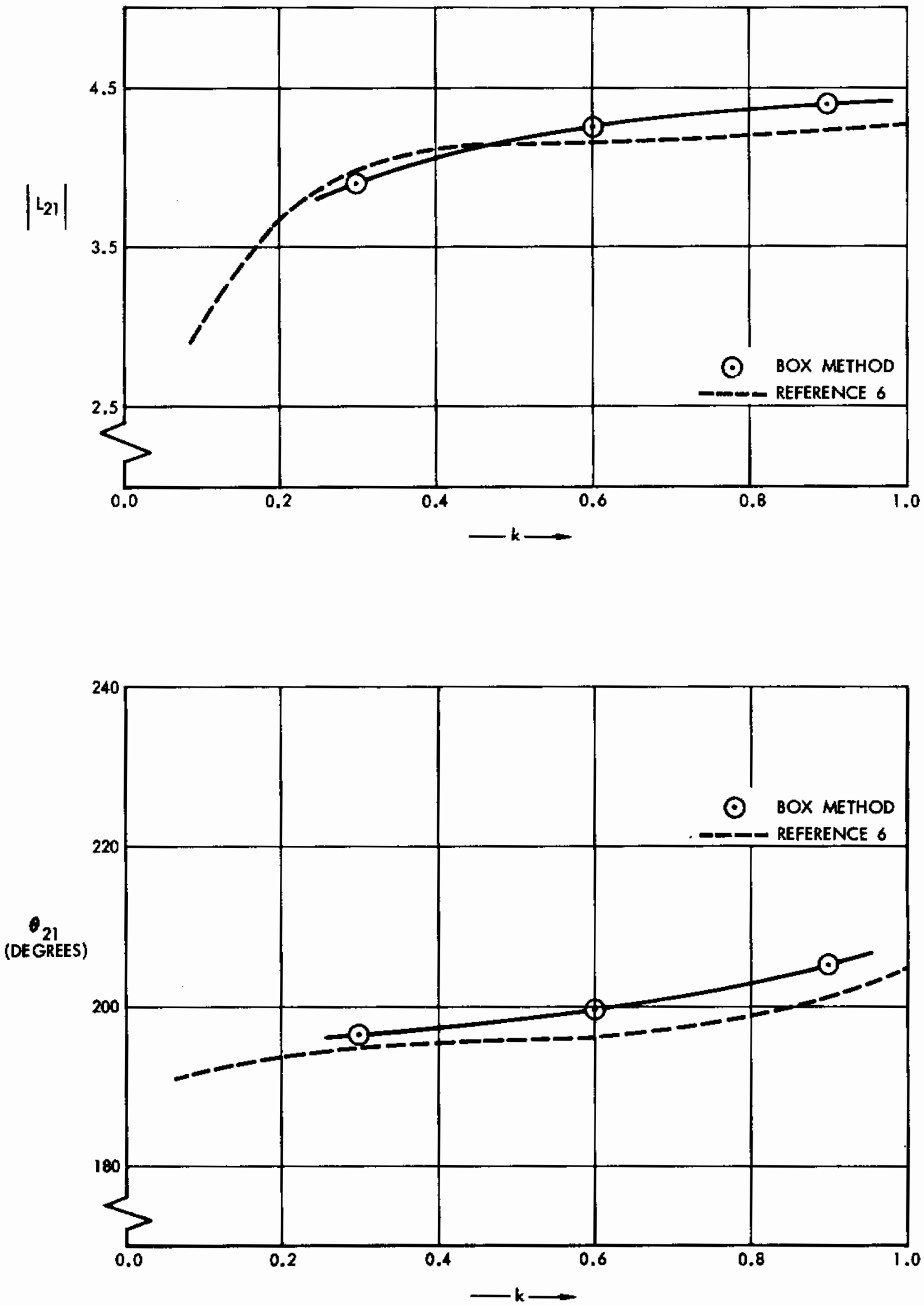


Figure 9. Lift Due to Pitch for an Aspect Ratio 2.0 Rectangular Wing (Compared With Reference 6)

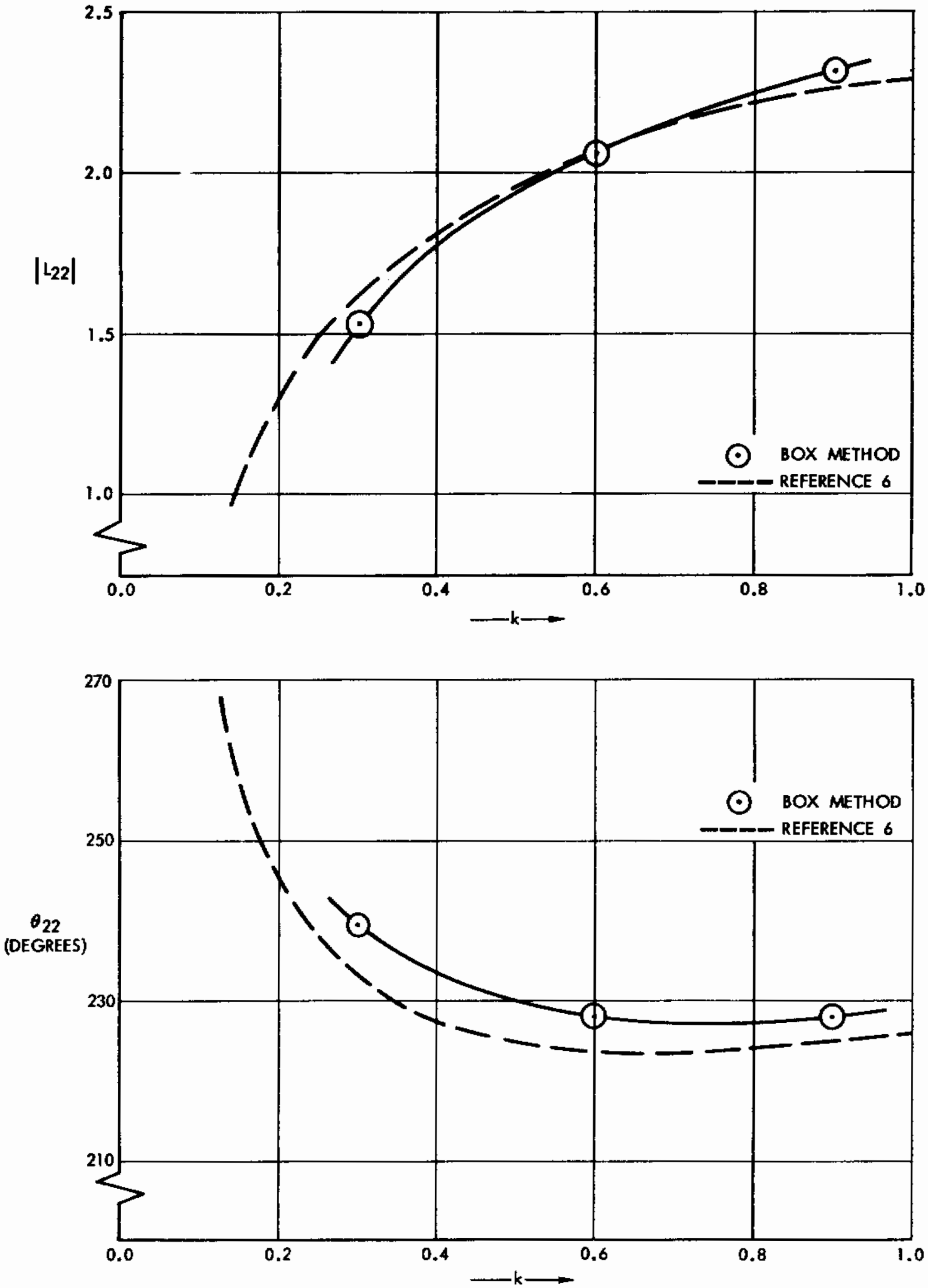


Figure 10. Moment Due to Pitch for an Aspect Ratio 2.0 Rectangular Wing (Compared With Reference 6)

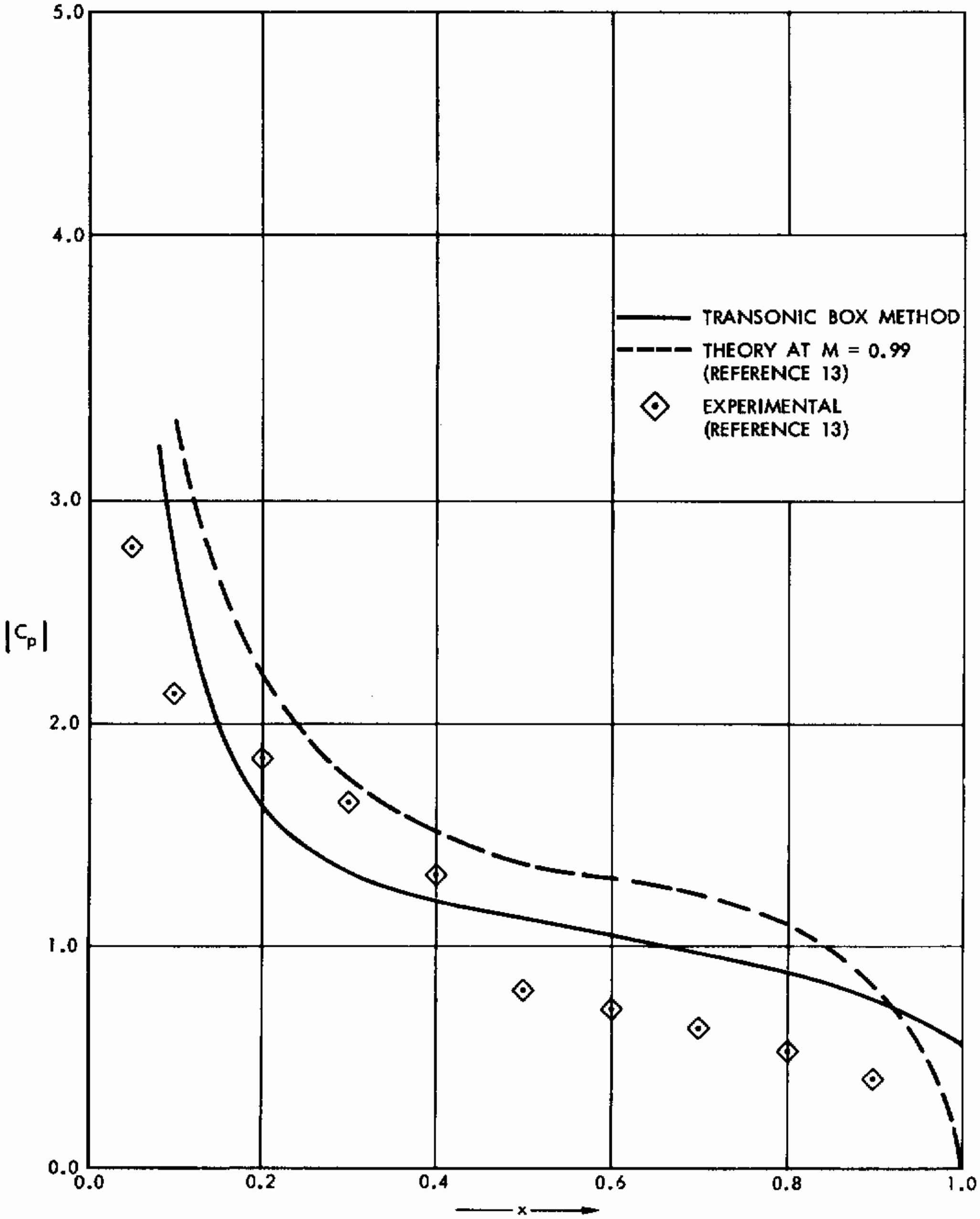


Figure 11. Chordwise Pressure Distribution on an Aspect Ratio 3.0 Rectangular Wing in an Elastic Mode; $y = y_{max}/2 = 0.75$ (Compared With Reference 13)

The variation of the experimental values from the computed values is of the type that thickness effects should be expected to cause: the measured pressure is (1) smaller near the leading edge, (2) larger before the point of maximum thickness (x = 0.5), and (3) smaller beyond this point. The experimentally determined values of local Mach number along this chord range from 0.84 to 1.35, which indicates that the thickness has a considerable effect on the flow.

The theoretical curve given in Reference 13 was obtained from the subsonic kernel function method, applied at M = 0.99. This curve is included to show how another theoretical method compares with the experimental values.

4. COMPUTER RUNNING TIME

The results described in this section required about 20 minutes total computer time on the IBM 7094. With nonessential output omitted, this time could have been reduced. All optional output was given, resulting in about 40,000 lines of output.

5. CONCLUSIONS

A procedure has been developed for predicting unsteady aerodynamic forces and pressures on an oscillating wing by the use of the transonic box method. The results obtained by this method agree quite well with theoretical values from other methods that are applicable only to special planforms. The box method has the advantage of applicability to a general planform. The only other method of this generality at Mach 1 is the sonic limit of the subsonic kernel function method (see Reference 16) that has not been very successful.

The comparison with experimental values in Figure 11 indicates that the most serious limitation of the method is that thickness is neglected. Thickness may be incorporated into a box program by using modified forms for sources and doublets, depending on the local Mach number (see Reference 14). This was not accomplished under the present program. Other possible extensions of the transonic box method, that would not require much change in the existing computer program, are described in Paragraph 10 of Section 2.

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APPENDIX I. PROPERTIES OF SOURCE AND DOUBLET DISTRIBUTIONS

1. BOUNDARY BEHAVIOR OF A DOUBLET DISTRIBUTION

We wish to evaluate

$$\overline{\varphi}_d(x, y, 0+) = \lim_{z \to 0+} \iint_{\xi > 0} d\xi \, d\eta \, \rho(\xi, \eta) \, \overline{\varphi}_1(x-\xi, \ y-\eta, \ z) .$$

The integrand is zero for $\xi > x$. If we define $\rho(\xi, \eta) = 0$ for $\xi < 0$, then

$$\overline{\varphi}_d(x, y, 0+) = \lim_{z \to 0+} \iint_{\xi < x} d\xi \, d\eta \, \rho(\xi, \eta) \, \overline{\varphi}_1(x-\xi, \ y-\eta, \ z) .$$

Put

$$\xi = x - z^2 u$$

$$\eta = y - zv$$

Then, using Equation (14), we have

$$\overline{\varphi}_d(x, y, 0+) = \lim_{z \to 0+} \iint_{u>0} du dv \ \rho(x-z^2 u, \ y-zv) \cdot z^3 \, \overline{\varphi}_1(z^2 u, \ zv, \ z)$$

$$= \lim_{z \to 0+} \iint_{u>0} du dv \ \rho(x-z^2 u, y-zv) \cdot \frac{ik}{2\pi} \frac{1}{u^2} e^{-\frac{1}{2} ik \left(z^2 u + \frac{1+v^2}{u} \right)}$$

Let (x, y) be a point at which ρ is continuous. Then the value of ρ in the integrand approaches $\rho(x, y)$ as $z \to 0$. Taking the limit under the integral sign,

$$\overline{\varphi}_d(x, y, 0+) = \rho(x, y) \cdot \frac{ik}{2\pi} \iint_{u>0} du dv \cdot \frac{1}{u^2} e^{-\frac{1}{2} ik \frac{1+v^2}{u}}$$

Let $v = s\sqrt{u}$. Then

$$\overline{\varphi}_d(x, y, 0+) = \rho(x, y) \cdot \frac{ik}{2\pi} \int_0^\infty \frac{du}{u^{3/2}} e^{-\frac{1}{2} ik/u} \int_{-\infty}^\infty ds\, e^{-\frac{1}{2} iks^2}$$

These integrals may be reduced to a standard form by rotating the paths of integration in the complex plane into positions in which the exponents are negative, then making the substitutions

$$u = \frac{ik}{2p}$$

$$s = \sqrt{\frac{2}{ik}}\, q$$

The result is

$$\overline{\varphi}_d(x, y, 0+) = \rho(x, y) \cdot \frac{1}{\pi} \int_0^\infty e^{-p} p^{-\frac{1}{2}} dp \int_{-\infty}^\infty e^{-q^2} dq$$

$$= \rho(x, y)$$

since both integrals have the value $\sqrt{\pi}$ (see Reference 12, formulas 507, 512). Consequently, Equation (18) is valid at any point of continuity of $\rho(x, y)$.

2. BOUNDARY BEHAVIOR OF A SOURCE DISTRIBUTION

To evaluate $\overline{\varphi}_{sz}(x, y, 0+)$, note that

$$\frac{\partial \overline{\varphi}_s}{\partial z} = \iint_{\xi > 0} d\xi d\eta\ \rho(\xi, n) \frac{\partial}{\partial z} \overline{\varphi}_o(x-\xi,\ y-\eta,\ z)$$

$$= \iint_{\xi > C} d\xi d\eta\ \rho(\xi, \eta) \overline{\varphi}_1(x-\xi,\ y-\eta,\ z)$$

$$= \overline{\varphi}_d$$

Hence, by the result of the preceding section, if (x, y) is a point at which $\rho(x, y)$ is continuous,

$$\overline{\varphi}_{sz}(x, y, 0+) = \overline{\varphi}_d(x, y, 0+) = \rho(x, y)$$

which verifies Equation (17).

APPENDIX II. EXPRESSIONS FOR THE INFLUENCE COEFFICIENTS

Equation (31) may be expressed more conveniently in terms of

$$u = (x_i - \xi)/d$$

$$v = (y_j - \eta)/d$$

$$m = \left| j - j' \right|$$

$$n = i - i'$$

$$\ell = kd$$

(d = box side length). By Equation (14) we have

$$A(n,m) = \frac{ik}{2\pi} \iint\limits_{\substack{|v-m|<\frac{1}{2} \\ |u-n|<\frac{1}{2} \\ u \geq 0}} \frac{du\,dv}{u^2}\, e^{-\frac{1}{2} i\ell \left(u + \frac{v^2}{u}\right)} \tag{39}$$

It is assumed that ℓ is small. If $\ell < 0.1$, the following approximation gives an error of less than 0.1 percent in the value of A:

$$e^{-\frac{1}{2} i\ell u} = e^{-\frac{1}{2} i\ell n}\, e^{-\frac{1}{2} i\ell (u-n)}$$

$$\cong e^{-\frac{1}{2} i\ell n} \left[1 - \frac{1}{2} i\ell (u-n) - \frac{1}{8} \ell^2 (u-n)^2 \right]$$

This reduces Equation (39) to

$$A(n,m) = \frac{ik}{2\pi} e^{-\frac{1}{2} i\ell n} \left\{ \left(1 + \frac{1}{2} i\ell n - \frac{1}{8} \ell^2 n^2\right) \iint \frac{du\,dv}{u^2} e^{-\frac{1}{2} i\ell\, v^2/u} \right.$$

$$+ \left(-\frac{1}{2} i\ell + \frac{1}{4} \ell^2 n\right) \iint \frac{du\,dv}{u} \quad e^{\frac{1}{2} i\ell\, v^2/u} \tag{40}$$

$$\left. - \frac{1}{8} \ell^2 \iint du\,dv\, e^{-\frac{1}{2} i\ell\, v^2/u} \right\}$$

where the limits of integration are the same as in Equation (39).

The following formula expresses these double integrals in terms of single integrals:

$$\int_{u_1}^{u_2} du \int_{v_1}^{v_2} dv \frac{1}{u^p} e^{-\frac{1}{2} i\ell\, v^2/u} = \frac{1}{3-2p} \int_{u_1}^{u_2} \frac{v\,du}{u^p} e^{-\frac{1}{2} i\ell\, v^2/u} \Bigg|_{v=v_1}^{v_2}$$

$$+ \frac{2}{3-2p} \int_{v_1}^{v_2} \frac{dv}{u^{p-1}} e^{-\frac{1}{2} i\ell v^2/u} \Bigg|_{u=u_1}^{u_2}$$

Equation (40) becomes

$$A(n,m) = \frac{ik}{2\pi} e^{-\frac{1}{2} i\ell n} \cdot \begin{cases} A_n(n+\frac{1}{2}, m) - A_n(n - \frac{1}{2}, m), & n > 0 \\ A_o(\frac{1}{2}, m), & n = 0 \end{cases} \tag{41}$$

where

$$A_n(u,m) = v \int_0^u du\, e^{-\frac{1}{2} i\ell v^2/u} \left[-\frac{1}{u^2}\left(1 + \frac{1}{2} i\ell n - \frac{1}{8}\ell^2 n^2\right) + \frac{1}{u}\left(-\frac{1}{2} i\ell + \frac{1}{4}\ell^2 n\right) - \frac{1}{24}\ell^2 \right] \Bigg|_{v = m - \frac{1}{2}}^{m + \frac{1}{2}}$$

$$+ \left[-\frac{2}{u}\left(1 + \frac{1}{2} i\ell n - \frac{1}{8}\ell^2 n^2\right) + 2\left(-\frac{1}{2} i\ell + \frac{1}{4}\ell^2 n\right) - \frac{1}{12}\ell^2 u \right] \int_{m-\frac{1}{2}}^{m+\frac{1}{2}} dv\, e^{-\frac{1}{2} i\ell v^2/u} \qquad (42)$$

$$= B_n(u,m) + C_n(u,m)$$

B_n and C_n denote the contributions of the terms containing the u - integrals and v - integrals, respectively.

$B_n(u,m)$ may be expressed in terms of the sine and cosine integrals

$$S(x) = \int_1^\infty \frac{\sin xt}{t}\, dt$$

$$C(x) = \int_1^\infty \frac{\cos xt}{t}\, dt$$

(C(x) and S(x) are evaluated by the subroutine CIN.) The resulting formula for B_n is

$$B_n(u,m) = \left\{ \left[\frac{2i}{\ell v}\left(1 + \frac{1}{2} i\ell n - \frac{1}{8}\ell^2 n^2\right) - \frac{1}{24}\ell^2 uv \right] e^{-\frac{1}{2} i\ell v^2/u} + \left[v\left(-\frac{1}{2} i\ell + \frac{1}{4}\ell^2 n\right) + \frac{1}{48} i\ell^3 v^3 \right] \left[C\left(\frac{\ell v^2}{2u}\right) - i\,S\left(\frac{\ell v^2}{2u}\right)\right]\right\} \Bigg|_{v = m - \frac{1}{2}}^{m + \frac{1}{2}} \tag{43}$$

To evaluate $C_n(u,m)$, put $v = s + m$. Expanding part of the exponential gives the approximation

$$\int_{m-\frac{1}{2}}^{m+\frac{1}{2}} dv\, e^{-\frac{1}{2} i\ell v^2/u} = \int_{-\frac{1}{2}}^{\frac{1}{2}} ds\, e^{-\frac{1}{2} i\ell (m^2 + 2ms + s^2)/u}$$

$$\cong e^{-\frac{1}{2} i\ell m^2/u} \int_{-\frac{1}{2}}^{\frac{1}{2}} ds\, e^{-i\ell ms/u}\left(1 - \frac{1}{2} i\ell s^2/u\right)$$

and performing the integration gives

$$\int_{m-\frac{1}{2}}^{m+\frac{1}{2}} dv\, e^{-\frac{1}{2} i\ell v^2/u} = e^{-\frac{1}{2} i\ell m^2/u} \left\{ \frac{\sin(\ell m/2u)}{\ell m/2u}\left(1 - \frac{1}{8}\frac{i\ell}{u}\right) + \frac{iu}{\ell m^2}\left[\frac{\sin(\ell m/2u)}{\ell m/2u} - \cos(\ell m/2u)\right]\right\}, \quad m \neq 0$$

For small values of $\ell m/2u$, the trigonometric functions of this argument are expanded in power series. To sufficient accuracy,

$$\int_{m-\frac{1}{2}}^{m+\frac{1}{2}} dv\, e^{-\frac{1}{2} i\ell v^2/u} = e^{-\frac{1}{2} i\ell m^2/u}\left[1 - \frac{1}{6}\left(\frac{\ell m}{2u}\right)^2 - \frac{1}{24}\frac{i\ell}{u}\right], \quad \ell m/2u < 0.2$$

It may be verified that this is valid for $m = 0$.

Combining these expressions,

$$C_n(u,m) = e^{-\frac{1}{2}i\ell m^2/u}\left[-\frac{2}{u}\left(1+\frac{1}{2}i\ell n-\frac{1}{8}\ell^2 n^2\right)+2\left(-\frac{1}{2}i\ell+\frac{1}{4}\ell^2 n\right)-\frac{1}{12}\ell^2 u\right]$$

$$\cdot\begin{cases}\left(1-\frac{1}{8}\frac{i\ell}{u}\right)\frac{\sin(\ell m/2u)}{\ell m/2u}+\frac{iu}{\ell m^2}\left[\frac{\sin(\ell m/2u)}{\ell m/2u}-\cos(\ell m/2u)\right], & \ell m/2u > 0.2 \\ 1-\frac{1}{24}\frac{i\ell}{u}-\frac{1}{6}\left(\frac{\ell m}{2u}\right)^2, & \ell m/2u < 0.2\end{cases} \tag{44}$$

The subroutine PØT2 evaluates the influence coefficients according to Equations (41), (42), (43), and (44).

APPENDIX III. COMPUTER PROGRAM LISTINGS

MAIN PROGRAM

```
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      DIMENSION G(10)
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      DATA Z/1H /
C
C     INITIALIZATION OF DATA ARRAY
C
      DO 1 I=1,700
    1 DA(I)=0.0
      DO 11 I=1,24
   11 DA(I)=Z
      DO 13 I=104,700,4
   13 DA(I)=1.0
C
   16 CALL DATRD(DA)
      CK=DA(23)*DA(24)/DA(25)*6.28318531
      DI=DA(27)
      L=DI
      D=1.0/DI
      DH=0.5*D
      WRITE
     O  (6, 49)(DA(I),I=1,12)
   36 IF (L) 83,83,37
   37 IF (50-L) 83,38,38
   38 WRITE
     O  (6, 41)L,CK
   41 FORMAT(1H010X,I2,23H BOXES ALONG ROOT CHORD/1H010X,19HREDUCED FREQ
     1UENCY =F6.3)
      WRITE
     O  (6, 42)DA(23)
   42 FORMAT(1H011X,10HFREQUENCY=1PE11.3)
      IF (DA(26)) 33,35,33
   33 DO 34 I=13,22
   34 DA(I)=Z
      GO TO 27
```

```
   35 CALL SHAPE
      CALL FØRCI
   27 LIM=ML(L)
      IF (LIM-50) 22,22,101
   22 LIM2=2*LIM
      LPØT=  MINO(L,15)
      CALL PØT2(100,LIM2,LPØT,CK,D)
      M=0
      K=DA(28)
      GØ TØ 4
C
C     PRELIMINARY CALCULATIØNS ARE FINISHED.
C     THE NEXT SECTIØN IS GØNE THRØUGH FØR EACH MØDE.
C
    3 IF (DA(26)) 4,28,4
   28 CALL DATRD(DA)
    4 K=K-1
      M=M+1
      WRITE
     0  (6, 48)M
   48 FØRMAT (1H115X,8HMØDE NØ.I3)
      WRITE
     0  (6, 49)(DA(I),I=13,22)
   49 FØRMAT (1H010X,12A6)
      IF (DA(26)) 29,7,29
    7 CALL DRED
    9 G(M)=DA(39)
   29 IF (G(M)) 74,72,74
   72 CALL WVAL
      IF (ML) 24,26,24
   24 LIM2=2*ML
      DØ 25 J=1,LIM2
   25 W(J,1,1)=W(J,1,1)*2.0/3.14159265
C     LEADING EDGE CØRRECTIØN
   26 CØNTINUE
      CALL BØXP
   74 IF (K) 6,6,5
```

```
    5 IF (M-10) 3,6,6
C
C     FINAL SECTION OF PROGRAM - COMPUTATION OF GENERALIZED FORCES
C
    6 WRITE (6 ,46)
   46 FORMAT (1H110X,18HGENERALIZED FORCES/1H05X,5HMODES/4X,11HOSC.  DEF
     1L.8X,9HREAL PART10X,9HIMAG PART10X,10HABS. VALUE6X,11HPHASE ANGLE)
      AC=8.0/AREA
      DO 12 M1=1,M
      IF (G(M1)) 12,14,12
   14 DO 18 M2=1,M
      S1=0.0
      S2=0.0
      N1=5*(M1-1)
      N2=5*(M2-1)
      DO 8 J=1,5
      J1=J+N1
      J2=J+N2
      DO 8 I=1,5
      S1=S1+PS(1,I,J1)*DF(I,J2)
    8 S2=S2+PS(2,I,J1)*DF(I,J2)
      S1=AC*S1
      S2=AC*S2
      S3= SQRT(S1**2+S2**2)
      S4=  ATAND(S2,S1)
   18 WRITE
     0  (6, 47)M1,M2,S1,S2,S3,S4
   47 FORMAT (1H02I6,1P3E19.5,0P1F16.4)
   12 CONTINUE
      WRITE  ( 6,43)
   43 FORMAT(1H1)
      GO TO 16
C
C     ERROR EXITS
C
   83 IPR=27
   84 WRITE
```

```
  0  (6, 45)IPR                                                        00001530
 45 FØRMAT(1HO10X,8HBAD DATAI4)                                        00001540
    GØ TØ 102                                                          00001550
101 WRITE   ( 6,56)                                                    00001560
 56 FØRMAT(1HO10X,42HLATERAL LIMIT ØN NUMBER ØF BØXES EXCEEDED.)       00001580
102 STØP                                                               00001600
    END                                                                00001610
```

SUBROUTINE SHAPE

```
      SUBROUTINE SHAPE
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      IEDG=0
      NS=DA(29)
      IF (NS) 81,81,1
    1 IF (NS-3) 2,2,81
    2 NSP=NS+1
      IF (DA(24)) 82,82,3
    3 DO 4 I=1,NSP
      XEDG(I)=DA(2*I+27)/DA(24)
    4 YEDG(I)=DA(2*I+28)/DA(24)
      XEDG=0.0
      XEDG(NS+2)=1.0
      YEDG(NS+2)=YEDG(NS+1)
      Y1=DA(30)
      IF (Y1) 83,20,20
   20 K=0
      X=DH
      AREA=0.0
    6 DO 15 I=1,L
    7 IF (X-XEDG(K+1)) 8,8,9
    8 ML(I)=0.5+DI*(YEDG(K)+F*(X-XEDG(K))/G)
      GO TO 15
    9 K=K+1
      G=XEDG(K+1)-XEDG(K)
      F=YEDG(K+1)-YEDG(K)
      IF (G) 84,12,12
   12 IF (F) 85,13,13
   13 AREA=AREA+G*(YEDG(K+1)+YEDG(K))
      GO TO 7
   15 X=X+D
      IF (XEDG(NS+1)-1.0) 17,16,84
   16 IF (YEDG(NS+1)-YEDG(NS)) 17,17,18
   17 IEDG=1
```

```
      SUBROUTINE SHAPE
 18   RETURN
 81   IPR=29
      GO TO 86
 82   IPR=24
      GO TO 86
 83   IPR=30
      GO TO 86
 84   K=  MINO(K,NS)
      IPR=2*K+29
      GO TO 86
 85   IPR=2*K+30
 86   WRITE
     0  (6, 41)IPR
 41   FORMAT(1H010X,8HBAD DATAI3)
      STOP
      END
```

```
      SUBROUTINE FORCI
C
C     CONTROL SUBROUTINE FOR CALCULATION OF INTEGRALS USED
C     TO FIND GENERALIZED FORCES
C
      SUBROUTINE FORCI
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      COMMON YMAX2,N
      YMAX2=YEDG(NS+1)**2
      DO 3 J=1,9
      DO 2 I=1,9
    2 AXY(I,J)=0.0
    3 AY(J)=0.0
      IF (DA(30)) 4,5,4
    4 N=0
      CALL SECT
C
C     SECT DOES THE CALCULATIONS FOR EACH SECTION OF THE PLANFORM
C
    5 DO 7 I=1,NS
      IF (YEDG(I)-YEDG(I+1)) 6,7,7
    6 N=I
      CALL SECT
    7 CONTINUE
      RETURN
      END
```

```
      SUBROUTINE SECT

C
C     AXY(I,J) IS THE INTEGRAL OVER THE PLANFORM OF
C             X**(I-1)*Y**(2J-2)*P(X,Y)*Q(Y)
C
C     IN TERMS OF THE EQUATION OF THE LEADING EDGE  X = XO(Y)
C             P(X,Y) = SQRTF(X**L-XO**L)
C     WHERE L = 1 OR 2
C             Q(Y) = 1 OR SQRTF(1-(Y/YMAX)**2)
C     DEPENDING ON THE WING SHAPE
C
C     AY(J) IS THE INTEGRAL OVER THE TRAILING EDGE OF
C             Y**(2J-2)*P(1,Y)*Q(Y)
C
      SUBROUTINE SECT
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      COMMON YMAX2,N
      DIMENSION U(6),H(6)
C
C     COMPUTES THE CONTRIBUTION TO AXY,AY OF THE SECTION OF WING
C     BOUNDED BY A SEGMENT OF THE LEADING EDGE, THE TRAILING EDGE,
C     AND TWO LINES ON WHICH Y IS CONSTANT
C
C     A SIX POINT GAUSSIAN FORMULA IS USED FOR THE INTEGRATION
C     OVER EACH VARIABLE
C
      U(1)=0.61930959
      U(2)=0.83060469
      U(3)=0.96623476
      U(4)=0.03376524
      U(5)=0.16939531
      U(6)=0.38069041
      H(1)=0.23395697
      H(2)=0.18038079
      H(3)=0.08566225
```

```
      SUBROUTINE SECT
      H(4)=H(3)
      H(5)=H(2)
      H(6)=H(1)
C
C     GAUSSIAN POINTS AND WEIGHTS FOR THE INTERVAL (0,1)
C
      X2=XEDG(N+1)
      X1=XEDG(N)
      Y2=YEDG(N+1)
      Y1=YEDG(N)
      IF (N) 4,2,4
    2 X1=0.0
      Y1=0.0
    4 DY=Y2-Y1
      DO 19 J=1,6
      V=U(J)
      G=H(J)*DY
      IF (Y2**2-YMAX2) 7,6,7
    6 G=2.0*V*G
      V=V*V
    7 Y=Y2-V*DY
      X0=X2+V*(X1-X2)
      XOP=1.0-X0
      G=G* SQRT(XOP)
      YQ=Y*Y
      IF (IEDG) 8,9,8
    8 G=G* SQRT(1.0-YQ/YMAX2)
    9 E=2.0*XOP*G
      IF (DA(30)) 10,10,11
   10 G=G* SQRT(1.0+X0)
   11 DO 17 I=1,6
      U2=U(I)**2
      X=X0+XOP*U2
      F=E*H(I)*U2
      IF (DA(30)) 12,12,13
   12 F=F* SQRT(X+X0)
   13 YP=1.0
```

```
      SUBROUTINE SECT
      DO 16 M=1,9
      XP=YP
      DO 15 L=1,9
      AXY(L,M)=AXY(L,M)+XP*F
   15 XP=X*XP
   16 YP=YQ*YP
   17 CONTINUE
      YP=1.0
      DO 18 M=1,9
      AY(M)=AY(M)+YP*G
   18 YP=YQ*YP
   19 CONTINUE
      RETURN
      END
```

SUBROUTINE DRED

```
      SUBROUTINE DRED                                                   00003400
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)      00003410
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)          00003420
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG   00003430
      COMMON AREA,DH                                                    00003440
      DIMENSION IXB(5),B(25),C(25,25),G(25)                             00003450
      COMMON C,B,G,IXB                                                  00003460
      NP=DA(98)                                                         00003470
      IF (NP) 83,24,30                                                  00003480
C                                                                       00003490
C     A POLYNOMIAL FOR THE DEFLECTION IS FITTED TO VALUES               00003500
C     OF DEFLECTION AT GIVEN POINTS.                                    00003510
C                                                                       00003520
   30 NX=DA(99)                                                         00003530
      NY=DA(1C0)                                                        00003540
      IF (NX) 81,81,31                                                  00003550
   31 IF (NY) 82,82,32                                                  00003560
   32 IF (150-NP) 83,38,38                                              00003570
   38 IF (NP-NX) 81,34,34                                               00003580
   34 IF (NP-NY) 82,35,35                                               00003590
   35 MX=  MINO(NX,5)                                                   00003600
      MY=  MINO(NY,5)                                                   00003610
      IY=MY                                                             00003620
      IXY=MX+MY                                                         00003630
      DO 2 J=1,5                                                        00003660
      DO 1 I=1,5                                                        00003662
    1 COE(I,J)=0.0                                                      00003664
    2 IXB(J)=MX                                                         00003670
      NC=MX*MY                                                          00003680
    3 DO 5 I=1,NC                                                       00003690
      DO 4 J=1,NC                                                       00003700
    4 C(I,J)=C.0                                                        00003710
    5 B(I)=0.C                                                          00003720
      KP=100                                                            00003730
      DO 11 IP=1,NP                                                     00003740
      X=DA(KP+1)/DA(24)                                                 00003750
      Y2=(DA(KP+2)/DA(24))**2                                           00003760
```

```
      SUBROUTINE DRED

      DEF=DA(KP+3)                                                        00003770
      WT=DA(KP+4)                                                         00003780
      IF (WT) 84,84,6                                                     00003790
    6 YP=1.0                                                              00003800
      K=1                                                                 00003810
      DO 8 J=1,IY                                                         00003820
      XYP=YP                                                              00003830
      JX=IXB(J)                                                           00003840
      DO 7 I=1,JX                                                         00003850
      G(K)=XYP                                                            00003860
      XYP=X*XYP                                                           00003870
    7 K=K+1                                                               00003880
    8 YP=Y2*YP                                                            00003890
      DO 10 I=1,NC                                                        00003900
      DO 9 J=1,NC                                                         00003910
    9 C(I,J)=C(I,J)+G(I)*G(J)*WT                                          00003920
   10 B(I)=B(I)+G(I)*DEF*WT                                               00003930
   11 KP=KP+4                                                             00003940
      K=MSIMER(25,NC,1,C,B)                                               00004030
      IF (K-1) 22,22,15                                                   00004040
   15 DO 16 I=1,IY                                                        00004050
      IP=IY+1-I                                                           00004060
      IF (IXB(IP)+IP-IXY) 16,17,17                                        00004070
   16 CONTINUE                                                            00004080
      IXY=IXY-1                                                           00004090
      GO TO 15                                                            00004100
   17 IXB(IP)=IXB(IP)-1                                                   00004110
      IF (IXB(IP)) 18,18,19                                               00004120
   18 IY=IP-1                                                             00004130
   19 NC=0                                                                00004140
      DO 20 I=1,IY                                                        00004150
   20 NC=NC+IXB(I)                                                        00004160
      GO TO 3                                                             00004170
   22 K=1                                                                 00004180
      DO 23 J=1,IY                                                        00004190
      JX=IXB(J)                                                           00004200
      DO 23 I=1,JX                                                        00004210
```

```
      SUBROUTINE DRED

      COE(I,J)=B(K)
   23 K=K+1
      IF (DA(87)) 61,66,61
   61 WRITE  ( 6,41)
      DO 64 J=1,IY
      JX=IXB(J)
      DO 63 I=1,JX
      WRITE
     0  (6, 42)I,J,COE(I,J)
   63 CONTINUE
   64 CONTINUE
   66 CONTINUE
      GO TO 28
   24 YP=1.0
      K=1
      DO 27 J=1,5
      XYP=YP
      DO 26 I=1,5
      COE(I,J)=XYP*DA(K+45)
      K=K+1
   26 XYP=XYP*DA(24)
   27 YP=YP*DA(24)**2
   28 K=25*(M-1)
      DO 29 I=1,25
      K=K+1
   29 DF(K,1)=COE(I,1)
      RETURN
   81 IPR=99
      GO TO 85
   82 IPR=100
      GO TO 85
   83 IPR=98
      GO TO 85
   84 IPR=K+4
   85 WRITE
     0  (6, 45)IPR
      STOP
```

```
      SUBROUTINE DRED

   41 FORMAT(1H010X,56HCOMPUTED DEFLECTION = SUM OF DEF(N,M)*X**(N-1)*Y*00004610
     1*(2M-2)/1H010X,54H(IN DIMENSIONLESS COORDINATES - DISTANCE/CHORD L00004620
     2ENGTH)/1H09X,1HN7X,1HM16X,8HDEF(N,M))                            00004630
   42 FORMAT(3X,2I8,1PE25.5)                                            00004640
   45 FORMAT(1H010X,8HBAD DATAI4)                                       00004650
      END                                                               00004660
```

```
      SUBROUTINE WVAL

      SUBROUTINE WVAL
C
C     EVALUATION OF THE UPWASH ARRAY
C
      DIMENSION A(2,100,16),W(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      COMMON A,W,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      DIMENSION G(5,5),H(5,5)
      COMMON G,H
      J1=5*(M-1)
      DO 3 J=1,5
      J1=J1+1
      CI=1.0
      DO 2 I=1,5
      G(I,J)=CI*DF(I+1,J1)
      H(I,J)=CK*DF(I,J1)
    2 CI=CI+1.0
    3 G(5,J)=0.0
C
C     G AND H ARE THE COEFFICIENTS OF THE REAL AND IMAGINARY PARTS
C      OF THE UPWASH
C
      X=DH
      DO 10 I=1,L
      JL=ML(I)
      IF (JL) 5,10,5
    5 Y=DH
      DO 9 J=1,JL
      Y2=Y*Y
      W(1,J,I)=0.0
      W(2,J,I)=0.0
      YP=1.0
      DO 8 J1=1,5
      XYP=YP
      DO 7 I1=1,5
      W(1,J,I)=W(1,J,I)+G(I1,J1)*XYP
```

```
      SUBROUTINE WVAL

      W(2,J,I)=W(2,J,I)+H(I1,J1)*XYP                                    00005060
    7 XYP=X*XYP                                                         00005070
    8 YP=Y2*YP                                                          00005080
    9 Y=Y+D                                                             00005090
   10 X=X+D                                                             00005100
      RETURN                                                            00005110
      END                                                               00005120
```

SUBROUTINE BOXP

```
      SUBROUTINE BOXP
      DIMENSION A(2,100,16),S(2,50,50),DA(700),PS(2,5,50),DF(5,50)
      DIMENSION ML(50),AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5)
      DIMENSION EDG(50),PR(2,50),PSI(2,50),G(20),XO(50),IXB(4)
      DIMENSION C(20,20),B(20,2)
      COMMON A,S,DA,PS,DF,ML,AXY,AY,XEDG,YEDG,COE,M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH
      COMMON B,C,EDG,PR,PSI,G,XO,IXB
C
      IF (DA(88)) 71,75,71
   71 WRITE  ( 6,47)
   47 FORMAT(1H110X,43HTHE UPWASH ARRAY (REAL AND IMAGINARY PARTS))
      DO 74 I=1,L
      JL=ML(I)
      IF (JL) 73,74,73
   73 WRITE
     0  (6, 42)I
      IF (I-1) 77,77,79
   77 DO 78 J=1,JL
      S1=S(1,J,I)*1.57079633
      S2=S(2,J,I)*1.57079633
   78 WRITE
     0  (6, 142)S1,S2
      GO TO 74
   79 WRITE
     0  (6, 142)(S(1,J,I),S(2,J,I),J=1,JL)
  142 FORMAT(1H 1P2E24.5)
   74 CONTINUE
C     THESE ARE THE UPWASHES
C
   75 CONTINUE
      CALL BOXPO
C      BOXPO COMPUTES THE POTENTIAL VALUES IN EACH BOX.
C     THEY ARE STORED IN THE ARRAY S.
C
      IF (DA(89)) 91,95,91
   91 WRITE  ( 6,143)
```

```
      SUBROUTINE BOXP
  143 FORMAT(1H110X,46HTHE POTENTIAL ARRAY (REAL AND IMAGINARY PARTS))
      DO 94 I=1,L
      JL=ML(I)
      IF (JL) 93,94,93
   93 WRITE
     0  (6, 42)I
      WRITE
     0  (6, 142)(S(1,J,I),S(2,J,I),J=1,JL)
   94 CONTINUE
C     THESE ARE THE POTENTIALS
C
   95 CONTINUE
C     FIT OF A SERIES TO THE POTENTIAL VALUES
C
      JL=ML(L)
      DY=D/YEDG(NS+1)
      Y=0.5*DY
      DO 201 J=1,JL
      IF (IEDG) 202,203,202
  202 EDG(J)= SQRT(1.0-Y*Y)
      Y=Y+DY
      GO TO 201
  203 EDG(J)=1.0
  201 CONTINUE
      N=0.5+DI*YEDG
      IF (N) 4,4,2
    2 DO 3 I=1,N
    3 XO(I)=0.0
    4 X1=0.0
      N1=N
      Y1=YEDG
      DO 8 K=1,NS
      X2=XEDG(K+1)
      Y2=YEDG(K+1)
      N=DI*Y2+0.5
      IF (N1-N) 5,7,7
    5 N1=N1+1
```

```
      SUBROUTINE BOXP

      DO 6 I=N1,N
      Y=D*( FLOAT(I)-0.5)
    6 XO(I)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)
    7 X1=X2
      Y1=Y2
    8 N1=N
      AS=0.0
      DO 119 I=1,L
      JL=ML(I)
      IF (JL) 119,119,217
  217 DO 118 J=1,JL
      AS=AMAX1(AS, ABS(S(1,J,I)), ABS(S(2,J,I)))
  118 CONTINUE
  119 CONTINUE
      IX=5
      IY=4
      IXY=9
   13 DO 14 I=1,IY
   14 IXB(I)=IX
   16 NC=0
      DO 17 I=1,IY
   17 NC=NC+IXB(I)
      DO 19 I=1,NC
      DO 18 J=1,NC
   18 C(I,J)=0.0
      B(I,1)=0.0
   19 B(I,2)=0.0
      X1=0.5*D
      DO 25 I=1,L
      JL=ML(I)
      Y=0.5*D
      IF (JL) 25,25,20
   20 DO 24 J=1,JL
      XR=X1-XO(J)
      IF (YEDG) 601,601,602
  601 XR=XR*(X1+XO(J))
  602 XR= SQRT(XR)
```

```
      SUBROUTINE BOXP

      YP=1.0
      K=1
      DO 23 N1=1,IY
      XP=XR*YP
      JX=IXB(N1)
      DO 22 N=1,JX
      G(K)=XP*EDG(J)
      XP=X1*XP
   22 K=K+1
   23 YP=Y*Y*YP
      Y=Y+D
      DO 24 N1=1,NC
      DO 124 N=1,NC
  124 C(N1,N)=C(N1,N)+G(N1)*G(N)
      DO 24 N=1,2
   24 B(N1,N)=B(N1,N)+G(N1)*S(N,J,I)
   25 X1=X1+D
      K=MSIMER(20,NC,2,C,B)
      IF (K-1) 30,30,29
C
C     IF XSIMEQ FAILS, THE FOLLOWING SECTION REDUCES THE NUMBER OF TERMS
C      IN THE SERIES.
C
   29 DO 61 I=1,IY
      IP=IY+1-I
      IF (IXB(IP)+IP-IXY) 61,62,62
   61 CONTINUE
      IXY=IXY-1
      GO TO 29
   62 IXB(IP)=IXB(IP)-1
      IF (IXB(IP)) 63,63,16
   63 IY=IP-1
      GO TO 16
C
   30 K=1
      AC=0.0
      DO 133 I=1,IY
```

```
      SUBROUTINE BOXP

      JX=IXB(I)                                                         00006740
      CJ=1.0                                                            00006750
      DO 33 J=1,JX                                                      00006760
      C(K,1)=B(K,1)                                                     00006764
      C(K,2)=B(K,2)                                                     00006766
      AC=AMAX1(AC, ABS(C(K,1)), ABS(C(K,2)))                            00006770
      IF (J.EQ.1) GO TO 33                                              00006780
      B(K-1,1)=CJ*C(K,1)                                                00006785
      B(K-1,2)=CJ*C(K,2)                                                00006790
      CJ=CJ+1.0                                                         00006800
   33 K=K+1                                                             00006810
      B(K-1,1)=0.0                                                      00006820
  133 B(K-1,2)=0.0                                                      00006830
      IF (AC-50.0*AS) 117,117,29                                        00006840
C                                                                       00006850
C     GO TO 29 IF COEFFICIENTS ARE TOO LARGE.                           00006860
C                                                                       00006870
  117 IF (DA(90)) 110,113,110                                           00006880
C                                                                       00006890
C     PRINTOUT OF COEFFICIENTS OF POTENTIAL                             00006900
C                                                                       00006910
  110 WRITE  ( 6,44)                                                    00006920
      IF (YEDG) 603,603,605                                             00006940
  603 WRITE  ( 6,45)                                                    00006950
      IF (IEDG) 604,607,604                                             00006970
  604 WRITE  ( 6,48)                                                    00006980
      GO TO 607                                                         00007000
  605 WRITE  ( 6,145)                                                   00007010
      IF (IEDG) 606,607,606                                             00007030
  606 WRITE  ( 6,148)                                                   00007040
  607 WRITE  ( 6,46)                                                    00007060
      K=1                                                               00007080
      DO 111 I=1,IY                                                     00007090
      JL=IXB(I)                                                         00007100
      DO 111 J=1,JL                                                     00007110
      WRITE (6,49) J,I,C(K,1),C(K,2)                                    00007120
  111 K=K+1                                                             00007140
```

```
      SUBROUTINE BOXP

      WRITE  ( 6,149)
  113 IF (DA(91)) 114,116,114
C
C     PRINTOUT OF VALUES OF POTENTIAL AND PRESSURE
C
  114 WRITE  ( 6,41)
   41 FORMAT(1H010X,9HPOTENTIAL45X,8HPRESSURE)
      X1=0.5*D
      DO 39 I=1,L
      JL=ML(I)
      Y=0.5*D
      IF (JL) 39,39,34
   34 DO 38 J=1,JL
      XR=X1-XO(J)
      XQ=0.5
      IF (YEDG)  608,608,609
  608 XQ=X1
      XR=XR*(X1+XO(J))
  609 XQ=XQ/XR
      XR= SQRT(XR)
      DO 37 N=1,2
      PSI(N,J)=0.0
      PR(N,J)=0.0
      K=1
      YP=EDG(J)
      DO 37 N1=1,IY
      XP1=XR*YP
      JX=IXB(N1)
      DO 36 M1=1,JX
      PSI(N,J)=PSI(N,J)+C(K,N)*XP1
      PR(N,J)=PR(N,J)+B(K,N)*XP1
      XP1=X1*XP1
   36 K=K+1
   37 YP=Y*Y*YP
      PR(1,J)=2.0*(PR(1,J)+PSI(1,J)*XQ-PSI(2,J)*CK)
      PR(2,J)=2.0*(PR(2,J)+PSI(2,J)*XQ+PSI(1,J)*CK)
   38 Y=Y+D
```

```
      SUBROUTINE ROXP

      WRITE
     0  (6, 42)I
   42 FORMAT(1H010X,I2,6HTH ROW)
      WRITE
     0  (6, 43)(PSI(1,J),PSI(2,J),PR(1,J),PR(2,J),J=1,JL)
   43 FORMAT(1H 1P2E24.5,5X,2E24.5)
   39 X1=X1+D
C
  116 JMO=5*(M -1)
      CJ=0.0
      DO 172 I=1,5
      DO 72 J=1,5
      JO=J+JMO
      PS (1,I,JO)=0.0
      PS (2,I,JO)=0.0
      K=1
      DO 72 K2=1,IY
      J2=J+K2-1
      JX=IXB(K2)
      DO 72 K1=1,JX
      J1=K1+I-1
      X1=AY(J2)-CJ*AXY(J1-1,J2)
      Y=AXY(J1,J2)*CK
      PS (1,I,JO)=PS (1,I,JO)+C(K,1)*X1-C(K,2)*Y
      PS (2,I,JO)=PS (2,I,JO)+C(K,1)*Y +C(K,2)*X1
   72 K=K+1
  172 CJ=CJ+1.0
      RETURN
C
   44 FORMAT(1H-10X,53HPOTENTIAL = SUM OF PO(M,N)*X**(M-1)*Y**(2N-2)*SQR
     1TF(X)
   45 FORMAT(1H+63X,10H**2-XO**2))
  145 FORMAT(1H+63X,4H-XO))
   48 FORMAT(1H+73X,21H*SQRTF(1-(Y/YMAX)**2))
  148 FORMAT(1H+67X,21H*SQRTF(1-(Y/YMAX)**2))
   46 FORMAT(1H015X,52HWHERE X = XO(Y) IS THE EQUATION OF THE LEADING ED
     1GE./1H020X,21HCOEFFICIENTS  PO(M,N)/1H07X,1HM7X,1HN14X,9HREAL PART
```

```
      SUBROUTINE BOXP

     216X,10HIMAG. PART)
   49 FORMAT(1H 2I8,1P2E25.5)
  149 FORMAT(1H1)
      END
```

```
      SUBROUTINE BOXPO
C     SOLUTION OF SIMULTANEOUS EQUATIONS FOR THE POTENTIAL
      COMMON A(2,100,16),S(2,50,50),DA(700),PS(2,5,50),DF(5,50),ML(50)
      COMMON AXY(9,9),AY(9),XEDG(5),YEDG(5),COE(5,5),M,L,NS,D,DI,CK,IEDG
      COMMON AREA,DH,E(2,50,50)
      I1=0
      DO 9 I=1,L
      KO=MAXO(1,I-14)
      JL=ML(I)
      IF (JL.EQ.0) GO TO 9
      IF (I1.EQ.0) GO TO 6
C     SUBTRACTION OF CONTRIBUTIONS OF PRECEDING ROWS TO UPWASH
      DO 5 J=1,JL
      DO 5 K=KO,I1
      KL=ML(K)
      K1=I+1-K
      IF (KL.EQ.0) GO TO 5
      DO 4 N=1,KL
      N1=N+J
      N2=IABS(N-J)+1
      A1=A(1,N1,K1)+A(1,N2,K1)
      A2=A(2,N1,K1)+A(2,N2,K1)
      S(1,J,I)=S(1,J,I)-A1*S(1,N,K)+A2*S(2,N,K)
    4 S(2,J,I)=S(2,J,I)-A2*S(1,N,K)-A1*S(2,N,K)
    5 CONTINUE
C     SETTING UP MATRIX FOR SIMULTANEOUS EQUATIONS
    6 DO 8 J=1,JL
      DO 8 K=1,J
      N1=J+K
      N2=IABS(J-K)+1
      E(1,J,K)=A(1,N1,1)+A(1,N2,1)
      E(2,J,K)=A(2,N1,1)+A(2,N2,1)
      E(1,K,J)=E(1,J,K)
    8 E(2,K,J)=E(2,J,K)
C     SOLUTION OF EQUATIONS
      K=MSIMEC(50,JL,1,E,S(1,1,I))
      IF (K.NE.1) GO TO 12
    9 I1=I1+1
```

```
      SUBROUTINE BOXPO

      RETURN
   12 WRITE ( 6,41)
   41 FORMAT(1H010X,59HSOLUTION OF SIMULTANEOUS EQUATIONS FOR THE POTENT
     1IAL FAILED)
      STOP
      END
```

```
      SUBROUTINE POT2
C
C     THE VELOCITY FIELD OF A UNIFORM DOUBLET DISTRIBUTION
C     OVER A BOX IS COMPUTED AT ALL POINTS AT WHICH IT WILL BE
C     NEEDED AND STORED IN THE ARRAY A IN COMMON
C
C     MO,NO CONTROL THE NUMBER OF VALUES COMPUTED
C
C     M2 IS THE RANGE OF THE SECOND SUBSCRIPT IN THE ARRAY,
C     DIMENSIONED A(2,M2,N2), BUT TREATED HERE AS AN ARRAY
C     WITH TWO SUBSCRIPTS
C
      SUBROUTINE POT2(M2,MO,NO,CK,D)
      DIMENSION A(2,1)
      COMMON A
      M=MO
      N=NO
      DK=CK*D
      DK2=DK**2
      M1=M-1
      DK8=DK2/8.0
      DK4=2.0*DK8
      DK12=DK2/12.0
      CM=0.5
      DH=DK*0.5
      DM=0.5*DH
      DD=2.0*CK
      DDM=DD
      D1=0.25*DK2
      B5=DK2/24.0
      DO 3 I=1,M
      B1=0.0
      B4=2.0/DM
      B2=B5/B4-DH
      B3=-0.5*B5
      D3=DH*B4+B5
      D4=DK8*B4
      DD4=2.0*D4
```

```
      SUBROUTINE POT2
      CN=1.0
      K=I
      C3=0.0
      C4=0.0
      C7=0.0
      C8=0.0
      DO 2 J=1,N
      A1=DM/CN
      C1=CM* COS(A1)
      C2=-CM* SIN(A1)
      C5=CM*CIN(A1,C6)
      C6=-CM*C6
      C9=C1-C3
      C10=C2-C4
      C11=C5-C7
      C12=C6-C8
      A(1,K)=B3*C9-B4*C10-B5*C3-B1*C11-B2*C12
      A(2,K)=B4*C9+B3*C10-B5*C4+B2*C11-B1*C12
   23 C3=C1
      C4=C2
      C7=C5
      C8=C6
      B1=B1-D1
      B3=B3-D3
      B4=B4-D4
      D4=D4+DD4
      CN=CN+2.0
    2 K=K+M2
      CM=CM+1.0
      DM=DM+DDM
    3 DDM=DDM+DD
      DO 5 L=1,2
      K1=1
      DO 5 J=1,N
      DO 4 I=1,M1
      K=K1+M-I
    4 A(L,K)=A(L,K)-A(L,K-1)
```

```
      SUBROUTINE POT2

      A(L,K1)=2.0*A(L,K1)
    5 K1=K1+M2
      CM=0.0
      DM=0.0
      DDM=DK
      DO 12 I=1,M
      C7=0.0
      C8=0.0
      C9=0.0
      C10=0.0
      P1=0.0
      P2=0.0
      CN=1.0
      B6=0.5*DK12
      K=I
      DO 10 J=1,N
      A1=CM/CN
      A2=DM/CN
      IF (A1-0.2) 7,7,8
    7 B1=2.0-A1**2/3.0
      B2=-DK/(6.0*CN)
      GO TO 9
    8 B3= SIN(A1)/A1
      B1=2.0*B3
      B2=(B3- COS(A1))/A2-DH/CN*B3
    9 B3= COS(A2)/CN
      B4= SIN(A2)/CN
      C3=B1*B3+B2*B4
      C4=B2*B3-B1*B4
      B5=DH*CN
      C1=B5*C4-2.0*C3
      C2=-2.0*C4-B5*C3
      C5=C1-C7
      C6=C2-C8
      P3=P2-B6*CN
      P4=P3+2.0*DK12*(CN-1.0)
      A(1,K)=A(1,K)+C5-P1*C6+P3*C3-P4*C9
```

```
      SUBROUTINE POT2
      A(2,K)=A(2,K)+C6+P1*C5+P3*C4-P4*C10
      P1=P1+DH
      P2=P2+CN*DK4
      CN=CN+2.0
      C7=C1
      C8=C2
      C9=C3
      C10=C4
      B6=B6+DK12
   10 K=K+M2
      CM=CM+DK
      DM=DM+DDM
   12 DDM=DDM+DD
      D3=CK/(2.0*3.14159265)
      M1=M2-M
      K=1
      A1=0.0
      DO 14 J=1,N
      C1=D3* SIN(A1)
      C2=-D3* COS(A1)
      DO 13 I=1,M
      DF    =A(1,K)*C1+A(2,K)*C2
      A(2,K)=A(2,K)*C1-A(1,K)*C2
      A(1,K)=DF
   13 K=K+1
      K=K+M1
   14 A1=A1+DH
      RETURN
      END
```

```
      CIN(X,S)

C     SINE AND COSINE INTEGRAL SUBROUTINE
C
C     IF CALLED BY THE STATEMENT  C=CIN(X,S)
C     C AND S ARE THE INTEGRALS OVER T FROM 1 TO INFINITY OF
C         COS(XT)/T  AND  SIN(XT)/T
C
      FUNCTION CIN(X1,S)
      SG=1.0
      X=X1
      IF (X) 1,2,2
    1 SG=-SG
      X=-X
    2 X2=X*X
      IF (X-1.0) 3,3,4
C
C     FOR ABS(X) LESS THAN 1 A SERIES EXPANSION IS USED
C
    3 V=(((X2/98.0-0.6)*.05*X2+1.0)*X2/18.0-1.0)*X+1.57079633
      U=((X2/45.0-1.0)*X2/24.0+1.0)*X2/4.0-.577215665-ALOG(X)
      GO TO 5
C
C     FOR ABS(X) GREATER THAN 1 APPROXIMATIONS OF HASTINGS ARE USED
C
    4 P=(((X2+19.394119)*X2+47.411538)*X2+8.493336)/((((X2+21.361055)
     1  *X2+70.376496)*X2+30.038227)*X)
      Q=(((X2+21.383724)*X2+49.719775)*X2+5.089504)/((((X2+27.177958)
     1  *X2+119.918932)*X2+76.707876)*X2)
      CO=COS (X)
      SI=SIN (X)
      U=Q*CO-P*SI
      V=P*CO+Q*SI
    5 S=V*SG
      CIN=U
      RETURN
      END
```

DATRD

```
C                 CARD-READ SUBROUTINE 'DATRD(DATA(I))'            00021410
      SUBROUTINE DATRD(DATA)                                       00021420
      DIMENSION DRBU(14),DATA(1)                                   00021430
      DATA ATEST/5HALPHA/,DTEST/1H /,ETEST/1H-/                    00021435
    1 READ   ( 5,2) EMIN,ALP,IND,(DRBU(I),I=1,12)                  00021450
    2 FORMAT(A1,A5,I6,12A6)                                        00021455
      IF (ALP.EQ.ATEST) GO TO 9                                    00021460
C                                                                  00021465
      WRITE (99,2) EMIN,ALP,IND,(DRBU(I),I=1,12)                   00021470
C      CARD IS WRITTEN IN INTERNAL BUFFER                          00021475
      REWIND 99                                                    00021480
      IF (ALP.NE.DTEST) GO TO 8                                    00021490
C                                                                  00021500
C     NUMERIC CARD                                                 00021510
C                                                                  00021520
      READ (99,990) (DRBU(I),I=1,5)                                00021530
      REWIND 99                                                    00021540
      DO 5 I=1,5                                                   00021550
      IF(DRBU(I))4,6,4                                             00021560
 4    DATA(IND)=DRBU(I)                                            00021570
 5    IND=IND+1                                                    00021580
      GOTO 11                                                      00021590
C                                                                  00021600
C     TEST FOR BLANK FIELD                                         00021610
 6    IF(SIGN (1.0,DRBU(I)))5,5,4                                  00021620
C                                                                  00021630
C     ALPHA CARD                                                   00021640
C                                                                  00021650
 9    DO 10 I=1,10                                                 00021770
      DATA(IND)=DRBU(I)                                            00021780
 10   IND=IND + 1                                                  00021790
   11 IF (EMIN.NE.ETEST) GO TO 1                                   00021800
C                                                                  00021805
C     RETURN IF COLUMN 1 CONTAINS A MINUS SIGN                     00021810
C                                                                  00021815
 13   RETURN                                                       00021820
C                                                                  00021825
```

```
       DATRD

C      BAD CARD                                                          00021830
C                                                                        00021835
     8 READ (99,992) DRBU                                                00021840
       WRITE  ( 6,993) DRBU                                              00021845
       WRITE  ( 6,991)                                                   00021850
       REWIND 99                                                         00021855
       STOP                                                              00021860
  990  FORMAT(12X,5E12.0)                                                00021870
  991  FORMAT(38H BAD DATA ON THIS CARD. JOB TERMINATED  )               00021880
  992  FORMAT(14A6)                                                      00021890
  993  FORMAT(12HOCARD IMAGE=14A6)                                       00021900
       END                                                               00021910
```

SIMULTANEOUS EQUATION SUBROUTINE

```
$IBMAP SIMR                           K=MSIMER(N,L,LB,A,B)
*      SOLVES THE SYSTEM OF EQUATIONS  A*X=B.
*      TO USE, SET K=MSIMER(N,L,LB,A,B)
*        WHERE N IS THE NUMBER OF ROWS FOR WHICH A IS
*        DIMENSIONED, AND L IS THE NUMBER OF EQUATIONS.
*        LB IS THE NUMBER OF COLUMNS IN B.
*      K=1 DENOTES SUCCESSFUL SOLUTION
*      K=2 FOR A SINGULAR OR ILL-CONDITIONED MATRIX
*      K=3 IF IMPROPER DATA IS GIVEN.
*        TO AVOID THIS SIGNAL, L MUST BE POSITIVE AND AT MOST 100,
*        N MUST NOT BE LESS THAN L, A MUST NOT INCLUDE A ROW
*        OF ZEROS.
*      A IS DESTROYED.
*      IF K=1, THE SOLUTION IS RETURNED IN B
*
*     ENTRY
*
MSIMER SAVE    1,2,3,4,5,6,7
*
*     PROLOGUE
*
       CLA*    3,4
       PAX     0,1
       TXL     E1,1,0
       TXH     E1,1,100
       PCD     0,1
       STD     A4-1
       STD     A6-1
       STD     2A6-1
       STD     A16
       STD     A16+1
       STD     2A21
       STD     A12+1
       STD     2A26
       STD     2A26+1
       STD     2A37
       STD     2A37+1
```

SIMULTANEOUS EQUATION SUBROUTINE

```
        STD     A12+2                                   00050380
        STD     A20                                     00050390
        STD     A22                                     00050400
        STD     A25+1                                   00050410
        STD     A25+2                                   00050420
        STD     A33                                     00050430
        STD     A36+1                                   00050440
        STD     A36+2                                   00050450
        SXD     A52,1                                   00050460
        TXI     *+1,1,1                                 00050470
        SCD     A32,1                                   00050480
        TXI     *+1,1,-2                                00050490
        SCD     A22+1,1                                 00050500
        CLA*    5,4                                     00050510
        PAX     0,7                                     00050520
        SXA     1A6-1,7                                 00050530
        SXA     A14,7                                   00050540
        SXA     1A21-1,7                                00050550
        SXA     A26,7                                   00050560
        SXA     A37,7                                   00050570
        CLA*    4,4                                     00050580
        PAX     0,1                                     00050590
        TXL     E1,1,0                                  00050600
A52     TXH     E1,1,**                                 00050610
        SXA     A2,1                                    00050620
        SXA     A5-1,1                                  00050630
        SXD     A9,1                                    00050640
        SXD     A12,1                                   00050650
        TXI     *+1,1,-1                                00050660
        SXD     A7,1                                    00050670
        SXD     A36,1                                   00050680
        SXD     A18,1                                   00050690
        SXD     A38-1,1                                 00050700
        SXD     A21-1,1                                 00050710
        SXD     A23,1                                   00050720
        SXD     A25,1                                   00050730
        SXD     A31,1                                   00050740
```

SIMULTANEOUS EQUATION SUBROUTINE

```
         SCD     A51,1                                             00050750
         SCD     A51+1,1                                           00050760
         TXI     *+1,1,1                                           00050770
         CLA     6,4                                               00050780
         PAC     0,3                                               00050790
         CLA     7,4                                               00050800
         PAC     0,5                                               00050810
A51      TXI     *+1,3, -L+1                                       00050820
         TXI     *+1,5, -L+1                                       00050830
*                                                                  00050840
*       NORMALIZATION OF ROWS                                      00050850
*                                                                  00050860
A2       AXT     L,2                                               00050870
         PXA     0,3                                               00050880
         PAX     0,6                                               00050890
         PAX     0,7                                               00050900
         PXA     0,0                                               00050910
A3       LDQ     A,6                                               00050920
         LRS     0                                                 00050930
         TLQ     *+2                                               00050940
         XCA                                                       00050950
         TNX     A4,2,1                                            00050960
         TXI     A3,6, -N                                          00050970
A4       TZE     E1                                                00050980
         STO     T                                                 00050990
         CLA     =1.0                                              00051000
         FDP     T                                                 00051010
         STQ     T                                                 00051020
         AXT     L,2                                               00051030
A5       FMP     A,7                                               00051040
         STO     A,7                                               00051050
         LDQ     T                                                 00051060
         TNX     A6,2,1                                            00051070
         TXI     A5,7, -N                                          00051080
A6       PXA     0,5                                               00051090
         PAX     0,6                                               00051100
         AXT     LB,4                                              00051110
```

```
                SIMULTANEOUS EQUATION SUBROUTINE

1A6     FMP     B,6                                                     00051120
        STO     B,6                                                     00051130
        LDQ     T                                                       00051140
        TNX     2A6,4,1                                                 00051150
        TXI     1A6,6, -N                                               00051160
2A6     TNX     A7,1,1                                                  00051170
        TXI     *+1,3,1                                                 00051180
        TXI     A2,5,1                                                  00051190
A7      TXH     B7,2,L -1                                               00051200
*                                                                       00051210
*      SEARCH FOR MAXIMUM PIVOT IN COLUMN                               00051220
*                                                                       00051230
        PXA     0,2                                                     00051240
        PAX     0,1                                                     00051250
        PXA     0,3                                                     00051260
        PAX     0,6                                                     00051270
        PXA     0,0                                                     00051280
A8      LDQ     A,6                                                     00051290
        LRS     0                                                       00051300
        TLQ     *+3                                                     00051310
        XCA                                                             00051320
        SXA     A10,1                                                   00051330
        TXI     *+1,1,1                                                 00051340
A9      TXH     *+2,1,L                                                 00051350
        TXI     A8,6,-1                                                 00051360
        LDQ     TOL                                                     00051370
        TLQ     *+2                                                     00051380
        TRA     E3                                                      00051390
A10     AXT     **,1                                                    00051400
        SXD     *+1,2                                                   00051410
        TNX     A17,1,**                                                00051420
*                                                                       00051430
*      ROW INTERCHANGE                                                  00051440
*                                                                       00051450
        PXA     0,3                                                     00051460
        PAX     0,6                                                     00051470
        PAX     0,7                                                     00051480
```

SIMULTANEOUS EQUATION SUBROUTINE

```
         SCD    *+1,1                                       00051490
         TXI    *+1,7,**                                    00051500
         PXA    0,2                                         00051510
         PAX    0,4                                         00051520
A11      CLA    A,6                                         00051530
         LDQ    A,7                                         00051540
         STO    A,7                                         00051550
         STQ    A,6                                         00051560
         TXI    *+1,4,1                                     00051570
A12      TXH    A13,4,L                                     00051580
         TXI    *+1,6, -N                                   00051590
         TXI    A11,7, -N                                   00051600
A13      PXA    0,5                                         00051610
         PAX    0,6                                         00051620
         PAX    0,7                                         00051630
A14      AXT    LB,4                                        00051640
         SCD    *+1,1                                       00051650
         TXI    *+1,6,**                                    00051660
A15      CLA    B,7                                         00051670
         LDQ    B,6                                         00051680
         STO    B,6                                         00051690
         STQ    B,7                                         00051700
         TNX    A17,4,1                                     00051710
A16      TXI    *+1,6, -N                                   00051720
         TXI    A15,7, -N                                   00051730
*                                                           00051740
*       DIVISION OF ROW BY PIVOT                            00051750
*                                                           00051760
A17      CLA    =1.0                                        00051770
         FDP    A,3                                         00051780
         STQ    AM                                          00051790
A18      TXH    A21,2,L -1                                  00051800
         PXA    0,2                                         00051810
         PAX    0,4                                         00051820
         PXA    0,3                                         00051830
         PAX    0,6                                         00051840
A20      TXI    *+1,6, -N                                   00051850
```

SIMULTANEOUS EQUATION SUBROUTINE

```
         LDQ     A,6                                              00051860
         FMP     AM                                               00051870
         STO     A,6                                              00051880
         TXI     *+1,4,1                                          00051890
         TXL     A20,4,L -1                                       00051900
A21      PXA     0,5                                              00051910
         PAX     0,6                                              00051920
         AXT     LB,4                                             00051930
1A21     LDQ     B,6                                              00051940
         FMP     AM                                               00051950
         STO     B,6                                              00051960
         TNX     *+2,4,1                                          00051970
2A21     TXI     1A21,6, -N                                       00051980
*                                                                 00051990
*      ROW REDUCTION                                              00052000
*                                                                 00052010
         PXA     0,2                                              00052020
         PAX     0,1                                              00052030
         PAX     0,4                                              00052040
         TNX     A31,1,1                                          00052050
         PXA     0,3                                              00052060
         PAX     0,6                                              00052070
         PAX     0,7                                              00052080
         STA     A29                                              00052090
         SXA     A26+1,5                                          00052100
         SXA     3A26,5                                           00052110
         TXI     *+1,6,1                                          00052120
A22      TXI     *+1,7, -N                                        00052130
         TXI     *+1,3, -N+1                                      00052140
         SXA     A28,7                                            00052150
A23      TXH     A26,2,L -1                                       00052160
         SXA     A27,3                                            00052170
A24      LDQ     A,6                                              00052180
         FMP     A,7                                              00052190
         CHS                                                      00052200
         FAD     A,3                                              00052210
         STO     A,3                                              00052220
```

SIMULTANEOUS ECUATION SUBROUTINE

```
        TXI     *+1,4,1                          00052230
A25     TXH     A27,4,L -1                       00052240
        TXI     *+1,3, -N                        00052250
        TXI     A24,7, -N                        00052260
A27     AXT     **,3                             00052270
A26     AXT     LB,4                             00052280
        AXT     **,7                             00052290
        TXI     *+1,7,1                          00052300
        SXA     *-2,7                            00052310
1A26    LDQ     A,6                              00052320
        FMP     B,5                              00052330
        CHS                                      00052340
        FAD     B,7                              00052350
        STO     B,7                              00052360
        TNX     3A26,4,1                         00052370
2A26    TXI     *+1,5, -N                        00052380
        TXI     1A26,7, -N                       00052390
3A26    AXT     **,5                             00052400
        TNX     A29,1,1                          00052410
A28     AXT     **,7                             00052420
        PXA     0,2                              00052430
        PAX     0,4                              00052440
        TXI     *+1,3,1                          00052450
        TXI     A23,6,1                          00052460
A29     AXT     **,3                             00052470
A31     TXH     A43,2,L -1                       00052480
        PXA     0,2                              00052490
        PAX     0,1                              00052500
        PAX     0,4                              00052510
        PXA     0,3                              00052520
        PAX     0,6                              00052530
        PAX     0,7                              00052540
A32     TXI     *+1,3, -N-1                      00052550
        TXI     *+1,6,-1                         00052560
A33     TXI     *+1,7, -N                        00052570
        SXA     A37+1,5                          00052580
        SXA     A41,5                            00052590
```

SIMULTANEOUS EQUATION SUBROUTINE

```
        SXA     A40,3                         00052600
        SXA     A39,7                         00052610
A34     SXA     A38,3                         00052620
A35     LDQ     A,6                           00052630
        FMP     A,7                           00052640
        CHS                                   00052650
        FAD     A,3                           00052660
        STO     A,3                           00052670
        TXI     *+1,4,1                       00052680
A36     TXH     A37,4,L -1                    00052690
        TXI     *+1,3, -N                     00052700
        TXI     A35,7, -N                     00052710
A37     AXT     LB,4                          00052720
        AXT     **,7                          00052730
        TXI     *+1,7,-1                      00052740
        SXA     *-2,7                         00052750
1A37    LDQ     A,6                           00052760
        FMP     B,5                           00052770
        CHS                                   00052780
        FAD     B,7                           00052790
        STO     B,7                           00052800
        TNX     A41,4,1                       00052810
2A37    TXI     *+1,5, -N                     00052820
        TXI     1A37,7, -N                    00052830
A41     AXT     **,5                          00052840
        TXI     *+1,1,1                       00052850
        TXH     A40,1,L -1                    00052860
A38     AXT     **,3                          00052870
A39     AXT     **,7                          00052880
        PXA     0,2                           00052890
        PAX     0,4                           00052900
        TXI     *+1,3,-1                      00052910
        TXI     A34,6,-1                      00052920
A40     AXT     **,3                          00052930
        TXI     *+1,5,-1                      00052940
        TXI     A7,2,1                        00052950
A43     CLA     =1                            00052960
```

SIMULTANEOUS EQUATION SUBROUTINE

```
         TRA      MSIMER+1
*
*       BRANCH FOR LAST ROW
*
B7       CLA      A,3
         SSP
         LDQ      TOL
         TLQ      A17
*
*       ERROR BRANCHES
*
E3       CLA      =2
         TRA      MSIMER+1
E1       CLA      =3
         TRA      MSIMER+1
*
*       STORAGE
*
TOL      OCT      1514CCC00000
AM       EQU      E.1
T        EQU      E.2
A        EQU      0
B        EQU      0
L        EQU      0
N        EQU      0
LB       EQU      0
         END
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
$IBMAP SIMC                    K=MSIMEC(N,L,LB,A,B)                    00053240
*      SOLVES THE SYSTEM OF COMPLEX EQUATIONS A*X=B.                   00053260
*      TO USE, SET K=MSIMEC(N,L,LB,A,B)                                00053270
*        WHERE N IS THE NUMBER OF ROWS FOR WHICH A IS                  00053280
*        DIMENSIONED, AND L IS THE NUMBER OF EQUATIONS.                00053290
*        LB IS THE NUMBER OF COLUMNS IN B.                             00053300
*      K=1 DENOTES SUCCESSFUL SOLUTION                                 00053310
*      K=2 FOR A SINGULAR OR ILL-CONDITIONED MATRIX                    00053320
*      K=3 IF IMPROPER DATA IS GIVEN.                                  00053330
*        TO AVOID THIS SIGNAL, L MUST BE POSITIVE AND AT MOST 100,     00053340
*        N MUST NOT BE LESS THAN L, A MUST NOT INCLUDE A ROW           00053350
*        OF ZEROS.                                                     00053360
*      A IS DESTROYED.                                                 00053370
*      IF K=1, THE SOLUTION IS RETURNED IN B                           00053380
*                                                                      00053390
*     ENTRY                                                            00053400
*                                                                      00053410
MSIMEC SAVE    1,2,3,4,5,6,7                                           00053420
*                                                                      00053430
*     PROLOGUE                                                         00053440
*                                                                      00053450
       CLA*    3,4                                                     00053460
       ALS     1                                                       00053470
       PAX     0,1                                                     00053480
       TXL     E1,1,1                                                  00053490
       TXH     E1,1,200                                                00053500
       PCD     0,1                                                     00053510
       STD     A4-1                                                    00053520
       STD     A6-1                                                    00053530
       STD     2A6-1                                                   00053540
       STD     A16                                                     00053550
       STD     A16+1                                                   00053560
       STD     2A21                                                    00053570
       STD     A12+1                                                   00053580
       STD     2A26                                                    00053590
       STD     2A26+1                                                  00053600
       STD     2A37                                                    00053610
```

COMPLEX SIMULTANECUS EQUATION SUBROUTINE

```
         STD      2A37+1                                    00053620
         STD      A12+2                                     00053630
         STD      A20                                       00053640
         STD      A22                                       00053650
         STD      A25+1                                     00053660
         STD      A25+2                                     00053670
         STD      A33                                       00053680
         STD      A36+1                                     00053690
         STD      A36+2                                     00053700
         SXD      A52,1                                     00053710
         TXI      *+1,1,2                                   00053720
         SCD      A32,1                                     00053730
         TXI      *+1,1,-4                                  00053740
         SCD      A22+1,1                                   00053750
         CLA*     5,4                                       00053760
         PAX      0,7                                       00053770
         SXA      1A6-1,7                                   00053780
         SXA      A14,7                                     00053790
         SXA      1A21-1,7                                  00053800
         SXA      A26,7                                     00053810
         SXA      A37,7                                     00053820
         CLA*     4,4                                       00053830
         ALS      1                                         00053840
         PAX      0,1                                       00053850
         TXL      E1,1,1                                    00053860
A52      TXH      E1,1,**                                   00053870
         SXA      A2,1                                      00053880
         SXA      A5-1,1                                    00053890
         SXD      A9,1                                      00053900
         SXD      A12,1                                     00053910
         TXI      *+1,1,-2                                  00053920
         SXD      A7,1                                      00053930
         SXD      A36,1                                     00053940
         SXD      A18,1                                     00053950
         SXD      A38-1,1                                   00053960
         SXD      A21-1,1                                   00053970
         SXD      A23,1                                     00053980
```

```
          COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

          SXD     A25,1                                          00053990
          SXD     A31,1                                          00054000
          SCD     A51,1                                          00054010
          SCD     A51+1,1                                        00054020
          TXI     *+1,1,2                                        00054030
          CLA     6,4                                            00054040
          PAC     0,3                                            00054050
          CLA     7,4                                            00054060
          PAC     0,5                                            00054070
A51       TXI     *+1,3,2L -2                                    00054080
          TXI     *+1,5,2L -2                                    00054090
*                                                                00054100
*         NORMALIZATION OF ROWS                                  00054110
*                                                                00054120
A2        AXT     2L,2                                           00054130
          PXA     0,3                                            00054140
          PAX     0,6                                            00054150
          PAX     0,7                                            00054160
          PXA     0,0                                            00054170
A3        LDQ     A,6                                            00054180
          LRS     0                                              00054190
          TLQ     *+2                                            00054200
          XCA                                                    00054210
          LDQ     A+1,6                                          00054220
          LRS     0                                              00054230
          TLQ     *+2                                            00054240
          XCA                                                    00054250
          TNX     A4,2,2                                         00054260
          TXI     A3,6,2N                                        00054270
A4        TZE     E1                                             00054280
          STO     T                                              00054290
          CLA     =1.0                                           00054300
          FDP     T                                              00054310
          STQ     T                                              00054320
          AXT     2L,2                                           00054330
A5        FMP     A,7                                            00054340
          STO     A,7                                            00054350
```

```
          COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

          LDQ     T
          FMP     A+1,7
          STO     A+1,7
          LDQ     T
          TNX     A6,2,2
          TXI     A5,7,2N
A6        PXA     0,5
          PAX     0,6
          AXT     LB,4
1A6       FMP     B,6
          STO     B,6
          LDQ     T
          FMP     B+1,6
          STO     B+1,6
          LDQ     T
          TNX     2A6,4,1
          TXI     1A6,6,2N
2A6       TNX     A7,1,2
          TXI     *+1,3,2
          TXI     A2,5,2
A7        TXH     B7,2,2L -2
*
*        SEARCH FOR MAXIMUM PIVOT IN COLUMN
*
          PXA     0,2
          PAX     0,1
          PXA     0,3
          PAX     0,6
          PXA     0,0
A8        LDQ     A,6
          LRS     0
          TLQ     *+3
          XCA
          SXA     A10,1
          LDQ     A+1,6
          LRS     0
          TLQ     *+3
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
        XCA                                                    00054730
        SXA     A10,1                                          00054740
        TXI     *+1,1,2                                        00054750
A9      TXH     *+2,1,2L                                       00054760
        TXI     A8,6,-2                                        00054770
        LDQ     TOL                                            00054780
        TLQ     *+2                                            00054790
        TRA     E3                                             00054800
A10     AXT     **,1                                           00054810
        SXD     *+1,2                                          00054820
        TNX     A17,1,**                                       00054830
*                                                              00054840
*     ROW INTERCHANGE                                          00054850
*                                                              00054860
        PXA     0,3                                            00054870
        PAX     0,6                                            00054880
        PAX     0,7                                            00054890
        SCD     *+1,1                                          00054900
        TXI     *+1,7,**                                       00054910
        PXA     0,2                                            00054920
        PAX     0,4                                            00054930
A11     CLA     A,6                                            00054940
        LDQ     A,7                                            00054950
        STO     A,7                                            00054960
        STQ     A,6                                            00054970
        CLA     A+1,6                                          00054980
        LDQ     A+1,7                                          00054990
        STO     A+1,7                                          00055000
        STQ     A+1,6                                          00055010
        TXI     *+1,4,2                                        00055020
A12     TXH     A13,4,2L                                       00055030
        TXI     *+1,6,2N                                       00055040
        TXI     A11,7,2N                                       00055050
A13     PXA     0,5                                            00055060
        PAX     0,6                                            00055070
        PAX     0,7                                            00055080
A14     AXT     LB,4                                           00055090
```

```
        COMPLEX SIMULTANEOUS ECUATION SUBROUTINE

        SCD     *+1,1                                   00055100
        TXI     *+1,6,**                                00055110
A15     CLA     B,7                                     00055120
        LDQ     B,6                                     00055130
        STO     B,6                                     00055140
        STQ     B,7                                     00055150
        CLA     B+1,7                                   00055160
        LDQ     B+1,6                                   00055170
        STO     B+1,6                                   00055180
        STQ     B+1,7                                   00055190
        TNX     A17,4,1                                 00055200
A16     TXI     *+1,6,2N                                00055210
        TXI     A15,7,2N                                00055220
*                                                       00055230
*       DIVISION OF ROW BY PIVOT                        00055240
*                                                       00055250
A17     NZT     A,3                                     00055260
        TRA     B1                                      00055270
        LDQ     A,3                                     00055280
        FMP     A,3                                     00055290
        STO     T                                       00055300
        LDQ     A+1,3                                   00055310
        FMP     A+1,3                                   00055320
        FAD     T                                       00055330
        STO     T                                       00055340
        CLA     A,3                                     00055350
        FDP     T                                       00055360
        STQ     AM                                      00055370
        CLA     A+1,3                                   00055380
        FDP     T                                       00055390
        STQ     AN                                      00055400
A18     TXH     A21,2,2L -2                             00055410
        PXA     0,2                                     00055420
        PAX     0,4                                     00055430
        PXA     0,3                                     00055440
        PAX     0,6                                     00055450
A20     TXI     *+1,6,2N                                00055460
```

```
       COMPLEX SIMULTANEOUS EQUATION SUBROUTINE
       LDQ     A,6                                        00055470
       FMP     AN                                         00055480
       STO     T                                          00055490
       LDQ     A+1,6                                      00055500
       FMP     AM                                         00055510
       FSB     T                                          00055520
       LDQ     A+1,6                                      00055530
       STO     A+1,6                                      00055540
       FMP     AN                                         00055550
       STO     T                                          00055560
       LDQ     A,6                                        00055570
       FMP     AM                                         00055580
       FAD     T                                          00055590
       STO     A,6                                        00055600
       TXI     *+1,4,2                                    00055610
       TXL     A20,4,2L -2                                00055620
A21    PXA     0,5                                        00055630
       PAX     0,6                                        00055640
       AXT     LB,4                                       00055650
1A21   LDQ     B,6                                        00055660
       FMP     AN                                         00055670
       STO     T                                          00055680
       LDQ     B+1,6                                      00055690
       FMP     AM                                         00055700
       FSB     T                                          00055710
       LDQ     B+1,6                                      00055720
       STO     B+1,6                                      00055730
       FMP     AN                                         00055740
       STO     T                                          00055750
       LDQ     B,6                                        00055760
       FMP     AM                                         00055770
       FAD     T                                          00055780
       STO     B,6                                        00055790
       TNX     *+2,4,1                                    00055800
2A21   TXI     1A21,6,2N                                  00055810
*                                                         00055820
*     ROW REDUCTION                                       00055830
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
*
         PXA     0,2
         PAX     0,1
         PAX     0,4
         TNX     A31,1,2
         PXA     0,3
         PAX     0,6
         PAX     0,7
         STA     A29
         SXA     A26+1,5
         SXA     3A26,5
         TXI     *+1,6,2
A22      TXI     *+1,7,2N
         TXI     *+1,3,2N -2
         SXA     A28,7
A23      TXH     A26,2,2L -2
         SXA     A27,3
A24      LDQ     A,6
         FMP     A,7
         STO     T
         LDQ     A+1,6
         FMP     A+1,7
         FSB     T
         FAD     A,3
         STO     A,3
         LDQ     A,6
         FMP     A+1,7
         STO     T
         LDQ     A+1,6
         FMP     A,7
         FAD     T
         CHS
         FAD     A+1,3
         STO     A+1,3
         TXI     *+1,4,2
A25      TXH     A27,4,2L -2
         TXI     *+1,3,2N
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
         TXI     A24,7,2N                                00056210
A27      AXT     **,3                                    00056220
A26      AXT     LB,4                                    00056230
         AXT     **,7                                    00056240
         TXI     *+1,7,2                                 00056250
         SXA     *-2,7                                   00056260
1A26     LDQ     A,6                                     00056270
         FMP     B,5                                     00056280
         STO     T                                       00056290
         LDQ     A+1,6                                   00056300
         FMP     B+1,5                                   00056310
         FSB     T                                       00056320
         FAD     B,7                                     00056330
         STO     B,7                                     00056340
         LDQ     A,6                                     00056350
         FMP     B+1,5                                   00056360
         STO     T                                       00056370
         LDQ     A+1,6                                   00056380
         FMP     B,5                                     00056390
         FAD     T                                       00056400
         CHS                                             00056410
         FAD     B+1,7                                   00056420
         STO     B+1,7                                   00056430
         TNX     3A26,4,1                                00056440
2A26     TXI     *+1,5,2N                                00056450
         TXI     1A26,7,2N                               00056460
3A26     AXT     **,5                                    00056470
         TNX     A29,1,2                                 00056480
A28      AXT     **,7                                    00056490
         PXA     0,2                                     00056500
         PAX     0,4                                     00056510
         TXI     *+1,3,2                                 00056520
         TXI     A23,6,2                                 00056530
A29      AXT     **,3                                    00056540
A31      TXH     A43,2,2L -2                             00056550
         PXA     0,2                                     00056560
         PAX     0,1                                     00056570
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
         PAX     0,4                                        00056580
         PXA     0,3                                        00056590
         PAX     0,6                                        00056600
         PAX     0,7                                        00056610
A32      TXI     *+1,3,2N +2                                00056620
         TXI     *+1,6,-2                                   00056630
A33      TXI     *+1,7,2N                                   00056640
         SXA     A37+1,5                                    00056650
         SXA     A41,5                                      00056660
         SXA     A40,3                                      00056670
         SXA     A39,7                                      00056680
A34      SXA     A38,3                                      00056690
A35      LDQ     A,6                                        00056700
         FMP     A,7                                        00056710
         STO     T                                          00056720
         LDQ     A+1,6                                      00056730
         FMP     A+1,7                                      00056740
         FSB     T                                          00056750
         FAD     A,3                                        00056760
         STO     A,3                                        00056770
         LDQ     A,6                                        00056780
         FMP     A+1,7                                      00056790
         STO     T                                          00056800
         LDQ     A+1,6                                      00056810
         FMP     A,7                                        00056820
         FAD     T                                          00056830
         CHS                                                00056840
         FAD     A+1,3                                      00056850
         STO     A+1,3                                      00056860
         TXI     *+1,4,2                                    00056870
A36      TXH     A37,4,2L -2                                00056880
         TXI     *+1,3,2N                                   00056890
         TXI     A35,7,2N                                   00056900
A37      AXT     LB,4                                       00056910
         AXT     **,7                                       00056920
         TXI     *+1,7,-2                                   00056930
         SXA     *-2,7                                      00056940
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
1A37    LDQ     A,6                     00056950
        FMP     B,5                     00056960
        STO     T                       00056970
        LDQ     A+1,6                   00056980
        FMP     B+1,5                   00056990
        FSB     T                       00057000
        FAD     B,7                     00057010
        STO     B,7                     00057020
        LDQ     A,6                     00057030
        FMP     B+1,5                   00057040
        STO     T                       00057050
        LDQ     A+1,6                   00057060
        FMP     B,5                     00057070
        FAD     T                       00057080
        CHS                             00057090
        FAD     B+1,7                   00057100
        STO     B+1,7                   00057110
        TNX     A41,4,1                 00057120
2A37    TXI     *+1,5,2N                00057130
        TXI     1A37,7,2N               00057140
A41     AXT     **,5                    00057150
        TXI     *+1,1,2                 00057160
        TXH     A40,1,2L -2             00057170
A38     AXT     **,3                    00057180
A39     AXT     **,7                    00057190
        PXA     0,2                     00057200
        PAX     0,4                     00057210
        TXI     *+1,3,-2                00057220
        TXI     A34,6,-2                00057230
A40     AXT     **,3                    00057240
        TXI     *+1,5,-2                00057250
        TXI     A7,2,2                  00057260
A43     CLA     =1                      00057270
        TRA     MSIMEC+1                00057280
B1      STZ     AM                      00057290
        CLA     =1.0                    00057300
        FDP     A+1,3                   00057310
```

COMPLEX SIMULTANEOUS EQUATION SUBROUTINE

```
        STQ     AN                                      00057320
        TRA     A18                                     00057330
*                                                       00057340
*      BRANCH FOR LAST ROW                              00057350
*                                                       00057360
B7      CLA     A,3                                     00057370
        SSP                                             00057380
        LDQ     TOL                                     00057390
        TLQ     A17+2                                   00057400
        CLA     A+1,3                                   00057410
        SSP                                             00057420
        TLQ     A17                                     00057430
*                                                       00057440
*      ERROR BRANCHES                                   00057450
*                                                       00057460
E3      CLA     =2                                      00057470
        TRA     MSIMEC+1                                00057480
E1      CLA     =3                                      00057490
        TRA     MSIMEC+1                                00057500
*                                                       00057510
*      STORAGE                                          00057520
*                                                       00057530
TOL     OCT     151400CC0000                            00057540
AM                                                      00057550
AN                                                      00057560
T                                                       00057570
A       EQU     0                                       00057580
B       EQU     0                                       00057590
2L      EQU     0                                       00057600
2N      EQU     0                                       00057610
LB      EQU     0                                       00057620
        END                                             00057630
```

APPENDIX IV. SAMPLE DATA SHEETS

The following pages are sample data sheets for a computer run on three modes at three frequencies. The potential will not be computed for the first mode. The generalized forces found will be L_{21}, L_{22}, L_{23}, L_{31}, L_{32}, L_{33}.

Of the first fourteen cards, the cards numbered 6, 9, 10, 11, 12, 13, 14 do nothing and are included only to indicate how all data is entered. Cards 1 through 14 are complete in this respect, and all later cards are of the same type as one of the first fourteen. The data used in the least squares surface fit for the deflection is entered in locations 101 through 700.

Card number 22 represents 56 cards for the intermediate data points which would have to be included in an actual run.

FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ___ of ___ JOB NO. ______

Col.		NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH	
1		A L P H A 1		title - columns 13 - 72	
13	6	0 D E G R E E C R		(optional)	
25	∅	P P E D D E L T A			
37	A	T 2 0 C P S			
49			73 80		
61			0 1		
1		A L P H A 1 3		mode title - columns 13 - 72	
13		P L U N G E		(optional)	
25					
37					
49			73 80		
61			0 2		
1		2 3			
13		2 0 . 0		frequency, ν	use consistant
25		2 5 . 0		root chord length, b	units here and
37		1 2 8 7 5 . 0		speed of sound, a	in items 30 - 36
49			73 80	Indicator for Subsequent frequencies	
61			0 3		
1		2 7			
13		3 0		no of boxes along root chord, L	
25		3		no. of modes to be given	
		1		no. of sections of leading edge given, NS	
			73 80		
			0 4		

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ___ of ___ JOB NO. ______

Col.	NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH
1	3 0		coordinates of points on leading edge
13	0 . 0		$\tilde{y}_0$
25	1 5 . 6 0		$\tilde{x}_1$
37	9 . 0		$\tilde{y}_1$
49		73 80	$\tilde{x}_2$ used if NS $\geq$ 2
61		0 5	$\tilde{y}_2$
1	3 5		
13			$\tilde{x}_3$ used if NS = 3
25			$\tilde{y}_3$
37			
49		73 80	
61		0 6	
1	3 9		
13	1		G non zero value suppresses calculation of potential
25			for this mode
37			
49		73 80	
61		0 7	
1	− 4 6		
13	1 . 0		d_{00} beginning of list of coefficients of deflection series
25			d_{10} $\sum d_{nm} x^{2n} y^{2m}$
37			d_{20}
49		73 80	d_{30}
61		0 8	d_{40}

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ____ of ____ JOB NO. ______

Col.	NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH
1	5 1		
13			d_{01}
25			d_{11}
37			d_{12}
49		73 80	etc
61		0 9	
1	8 7		
13			indicator for deflection coefficient pointout
25			indicator for upwash array pointout
37			indicator for potential array printout
49		73 80	indicator for potential coefficient printout
61		1 0	indicator for potential and pressure printout
1	9 8		
13			NP number of points at which deflection is given
25			NX number of x values
37			NY number of y values
49		73 80	
61		1 1	
1	1 0 1		
13			$\hat{x}_1$ data for first point
25			$\hat{y}_1$
37			$f(\tilde{x}_1,\tilde{y}_1)$
49		73 80	weight (optional - weight 1.0 used if no entry is made)
61		1 2	

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ________ PROGRAMMER ________ DATE ________ PAGE ____ of ____ JOB NO. ________

Col.	NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH
1	1.05		
13			$\tilde{x}_2$ data for second point
25			$\tilde{y}_2$
37			$f(\tilde{x}_2,\tilde{y}_2)$
49		73 80	weight
61		13	
1	1.09	2	
13			$\tilde{x}_3$ data for third point
25			$\tilde{y}_3$
37			etc
49		73 80	
61		14	
1	ALPHA 13		
13	PITCH ABØUT		beginning of data for second mode
25	X = 0		
37			
49		73 80	
61		15	
1	39		
13	0		zero cancels previous value, causing potential to be computed
25			
37			
49		73 80	
61		16	

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ____ of ____ JOB NO. ______

Col.		NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH
1		8 7		
13		1		
25		1		
37		1		
49		1	73 80	
61		1	1 ∅	
1	—	4 6		last card for second mode
13		0 . 0		this entry cancels previous value of d_{oo}
25		0 . 0 4		
37				the polynomial is $0.04\tilde{x}$, normalised for maximum value 1.0
49			73 80	
61			1 8	
1		A L P H A 1 3		
13	F	I R S T B E N D I N		beginning of data for third mode
25	G	M O D E		
37				
49			73 80	
61			1 9	
1		9 8		
13		5 8		
25		9		
37		8		
49			73 80	
61			2 0	

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ____ of ____ JOB NO. ______

Col.	Sign	NUMBER	IDENTIFICATION (73–80)	DESCRIPTION DO NOT KEY PUNCH
1		1.01		
13		23.6		data for first point
25		0.5		
37		0.0235		
49				
61			21	
1		105		
13		etc		
25				
37				
49				
61			22	
1	—	331		data for last point; last data for this mode
13		5.8		
25		0.6		
37		0.01286		
49				
61			23	
1	—	23		data for a second frequency
13		30.0		new frequency
25				
37				
49		1		indicator
61			24	

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FORTRAN FIXED 10 DIGIT DECIMAL DATA

DECK NO. ______ PROGRAMMER ______ DATE ______ PAGE ____ of ____ JOB NO. ______

		NUMBER	IDENTIFICATION	DESCRIPTION DO NOT KEY PUNCH
1	—	.2 3		data for a third frequency
13		4 0 . 0		
25				
37				
49			73 80	
61			2 5	
1				
13				
25				
37				
49			73 80	
61				
1				
13				
25				
37				
49			73 80	
61				
1				
13				
25				
37				
49			73 80	
61				

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13. ABSTRACT

The fundamental equations of the transonic box method were derived, based on the representation of the velocity potential by a doublet distribution. They form the basis of a systematic method of treating an oscillating wing at M=1, analogous to the supersonic Mach box method. A digital computer program, written in Fortran IV, is presented. The program applies to a planar wing of polygonal planform, with a straight trailing edge, and as many as three sweep angles along the leading edge. For a maximum of ten modes of oscillation, the program computes the oscillatory potentials and pressures and a generalized force matrix. Results obtained from the program are compared with existing theoretical and experimental values. Several possible extensions of the method are described.

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