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## X-20 HIGH TEMPERATURE SIDE WINDOW TEST EVALUATION

JOHN C. McGINNIS

THE BOEING COMPANY

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#### FOREWORD

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This program is an extension of the X-20 (Dyna-Soar) structural development in the area of high temperature windows. The program was sponsored by the Air Force Flight Dynamics Laboratory (AFFDL), Research and Technology Division, Air Force Systems Command, United States Air Force. Initially listed under Project Number 620A, Task Number 620A, Item Number 2-9, this work was accomplished under Contract AF 33(615)-2013; Project Number 1368; Task Number 136802, "Window Systems Concepts".

The hot side window assembly of an X-20 (Dyna-Soar) was fabricated by The Boeing Company, Aerospace Division, Seattle, Washington under EWA 00114. Vibration, air, and thermal load tests were accomplished by the Structures Test Branch (FDTT) at AFFDL, Wright-Patterson AFB, Ohio.

The first test of the series was conducted on 20 January 1965 with termination occurring on 2 April 1965 during Test No. 3 when the window failed during heating. The tabulated data on all tests performed are stored at the Structures Test Branch (FDTT), AFFDL and at The Boeing Company, Aerospace Division.

Acknowledgment is given to Lt. J. Pharmer (FDTS), Program Coordinator, and Mr. Murry England (FDTT), Test Project Engineer, of the Air Force Flight Dynamics Laboratory for supplying photographs, drawings, descriptions and test data.

The manuscript was released by the author in August 1965 under Boeing Document No. D2-81310-1 for publication as an RTD Technical Report.

Publication of this report does not constitute Air Force approval of the report's findings or conclusions. It is published only for the exchange and stimulation of ideas.

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FREDERICK C. KRUG / Colonel USAF Chief, Structures Division

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#### ABSTRACT

This document presents the results of testing an X-20A (Dyna-Soar) high temperature side window assembly under vibration, air, and thermal loading.

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The purpose of this program was to experimentally verify the X-20A side window assembly and provide experience for improved window design. The objective of this program was to verify the structural integrity of an X-20A high temperature window design in the X-20A flight environment and provide test data to evaluate the design analysis and development procedures utilized.

The X-20 side window provides pilot vision throughout all phases of flight, and is exposed to all flight environments. The side window is triangular in shape (28 inches by 24 inches by 16 inches) with rounded corners. The window assembly includes three separate glass panes of fused silica, seals fabricated from Hastelloy-X wire mesh with foil covering, Superalloy Rene' 41 mounting springs, fairing, and frame.

The window was subjected to a low-level boost vibration environment, limit boost pressure of -7 pounds/inch<sup>2</sup> (gage) and a simulated re-entry heating time-temperature history.

The window failed during the re-entry temperature cycle. The primary cause of failure was the high temperature gradient through the depth of the window frame of approximately 850°F which exceeded by a factor of 2 the ultimate design value. The extreme thermal gradient caused thermal curvature of the window frame which induced glass curvature in excess of allowable.

Measured temperatures and deflections are presented and compared with analytical values. A thermal analysis is presented and compared with test values. Deficiencies of the X-20 window design as determined from the test program are pointed out and suggested methods of improvement are given.

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### NOMENCLATURE

A	= Aluminum plate thermocouple
C	= Control Thermocouple
CPS	= Cycles/second
DA	= Deflection indicator - section A-A
DB	= Deflection indicator - section B-B
DC	= Deflection indicator - section C-C
DD	= Deflection indicator - section D-D
DE	= Deflection indicator - section E-E
F	= Fairing thermocouple
g	= Acceleration - 32.2 ft/sec <sup>2</sup>
I	= Moment of inertia - in $\frac{\mu}{\mu}$
I.R.	= Infrared
J	= Polar moment of inertia - in <sup>4</sup>
M, M	= Bending moment - in.lbs./inch
psi	= Pressure lbs/in <sup>2</sup>
P	= Load lbs or lbs/in
PS	= Surface pressure - lbs/ft <sup>2</sup>
Pv	= Vent pressure - 1bs/ft <sup>2</sup>
₽∞	= Free stream pressure - lbs/ft <sup>2</sup>
PSD	= Power spectral density - 🖌 CPS
<sub>6</sub> χ, <sub>6</sub> γ	= Shear lbs/in
ନ	= Amplification factor - g's output/g's input
rms	= Root mean square

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### NOMENCLATURE (Continued)

R <sub>x</sub> ,R	= Rotation - radians
т	= Thermocouple or temperature-°F
TM	= Thermistor
TCPL	= Thermocouple
V	= Shear - pounds
z	= Vertical deflection - inches
0 xx' 6 33	= Stress - 1bs/in <sup>2</sup>
$\mathcal{T}_{xy}$	= Shear stress - lbs/in <sup>2</sup>

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1 INTRODUCTION

#### 1.1 GENERAL DESCRIPTION

The requirement for pilot vision necessitated the installation of five windows within the cooled pilots compartment and the surrounding primary hot structure of the X-20A (Dyna-Soar) vehicle. The three forward facing windows require thermal protection during re-entry, which is provided by an ejectable windshield cover. This cover is ejected following re-entry at velocities between Mach 6 and Mach 4. This allows the pilot to make a visual approach and landing. The left and right side windows are provided for pilot vision throughout all phases of flight, and are exposed to all flight environments, boost through landing.

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This program deals with the test of one of the hot side windows only. The hot side windows must prevent the hot gas plasma associated with aerodynamic heating from entering the fuselage cavity. The hot windows are triple pane, 100 percent fused-silica, polished plates having an infrared coating on all surfaces except on the outer surface. The window panes are of a triangular shape approximately 24 inches by 28 inches by 16 inches with rounded corners. Each of the window installations consists of three panes of glass mounted in a continuous superalloy (Rene' 41) frame, as shown on page 3 . Each frame is mounted on a three-point suspension pivot principle so as to allow the glass to carry only normal loads either to the edge or the face of the pane. The attachments shown on page 20 show the hot frames are fully restrained at only one pivot point. This restraint point will accept all inertia loads as well as dampen vibrations of the installation. The "hot" glass, itself, is mounted in the frame in such a manner as to prevent the glass from coming free when the frame expands under high-temperature conditions. This is accomplished by use of flat Rene' 41 side springs and Rene' 41 leaf spring in series with the seals. The seal material for this "hot" environment consists of five pads of Hastelloy-X wire mesh wrapped in Hastelloy-X foil nominally clamped up at 35 pounds per lineal inch of periphery. Under the "hot" environment the material retains a clamped up pressure of approximately 8 pounds per lineal inch of periphery.

The "hot" structural window assembly is directly adjacent to the "cold" windows of the pilots compartment. The pilots compartment is suspended within the glider primary structure in such a manner as not to accept basic structural loads. The cold window is a laminated two-pane low-expansion, alumino-silicate polished plate having an infrared reflective coating on the outboard surface. These panes are mounted in a silicone rubber seal that is clamped in place to provide for a near-zero leakage rate of the pressurized pilots compartment. The "cold" windows are not a part of this test program.

The "hot" side window test specimen was instrumented with accelerometers for determining response of the structural system during vibration testing; thermistors for measurement of the fused silica glass pane temperatures; thermocouples for measurement of the window frame, cab frame, and support structure temperatures; and deflection gages for measurement of window and

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1.1 GENERAL DESCRIPTION (Continued)

cab frame translations and/or rotations. The window test setup is instrumented to measure net pressure on the window and leakage rates through the seals during the boost air load test No. 2. All instrumentation data is recorded, reduced, and is documented herein.

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An outline of the test plan as prepared in Reference 4 is shown on page 3. The planned test series were not completed due to the failure of the glass during Test Condition 3, Re-entry Thermal Cycle. Although the full planned program of tests was not completed, limited tests were run for each of the three design environments---pressure, vibration and temperature.

This report presents the results of the tests completed and a comparison with analytical data. A thermal and stress analysis of the window assembly is included. The cause of the window failure is discussed and methods of improvement are suggested.

Developmental testing and stress analysis for the X-20 "hot" side window in support of X-20A drawing release has been documented in Reference 5. High Temperature Windows RE-ENTRY PRESSURE + 4.3 LBS/ IN<sup>2</sup> AT 800° F RE-ENTRY THERMAL CYCLE 1600°F WINDOW SEAL HASTELLOY-X WIRE MESH ENCLOSED IN HASTELLOY-X FOIL BOOST PRESSURE, - 7LBS/IN<sup>2</sup> ULTIMATE BOOST PRESSURE - 10.5 LBS/IN<sup>2</sup> TEST CONDITIONS RE-ENTRY VIBRATION **BOOST VIBRATION** N CAB FRAME m 4 ท่ Ó ---- FUSED SILICA WINDOW PANES SIDE LEAF SPRINGS -WINDOW FAIRING X-20 SIDE WINDOW ASSEMBLY

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WINDOW FRAME

LEAF SPRINGS.

SEALS-

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2 TEST SPECIMEN

#### 2.1 GENERAL DESCRIPTION

The window test specimen as shown in the photograph on page 5 is defined in detail by the window test assembly drawing (25-86200) which includes three triangularly shaped flat glass panes with rounded corners, a retaining frame, mounting seals, mounting springs, and retaining frame support bearings. A portion of the glider cab frame was included to correctly simulate the support conditions at the three bearing locations. A special vacuum box was also fabricated to allow for the application of air loads without structural interactions.

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#### 2.2 WINDOW PANES

The three glass panes are Corning fused silica Code Number 7940. They were fabricated by the Corning Glass Works, Corning, New York per The Boeing Company specifications as outlined in Reference 7. The window panes are of a triangular shape approximately 24-inches by 28-inches by 16-inches with rounded corners. The outer pane was .65 inch thick except in the rebate area where it was machined to a thickness of .45 inch. The inner two panes were of a constant thickness of .18 inch. An infra-red reflective coating of stannous oxide was applied on all surfaces of the panes except on the most outer surface for the purpose of decreasing the radiant heat transfer through the panes. The infra-red reflectance from each of these coated surfaces was equal to or greater than the values shown on Figure 3 page 6. The actual thickness of the stannous oxide coating was not determined. During the coating process it has been found that a measurement of the electrical resistance of the coating is a good indication of coating performance. It was found that an electrical resistance of approximately 40 ohms per square (square = length) would give a satisfactory coating. Final acceptance was made by measuring the reflectance between 2.0 to 16.0 microns to meet the requirements of Figure 3 page 6.

The requirements of Reference 7 Paragraph 3.1.2.1.1.6, Optical Deviation; Paragraph 4.3.2, Test Specimen Samples; Paragraph 4.3.2.2, Degradation of Glass Coatings Test; and Paragraph 4.3.2.3, Optical Inspection, were deleted for the test specimen.

#### 2.3 THERMISTORS

Thermistors were fabricated and installed by the Corning Glass Works, Corning, New York on both sides of all fused silica window panes to measure glass temperatures. The infrared coating was removed 1/8 inch from each side of the thermistor and its leads. See photograph on page 9.

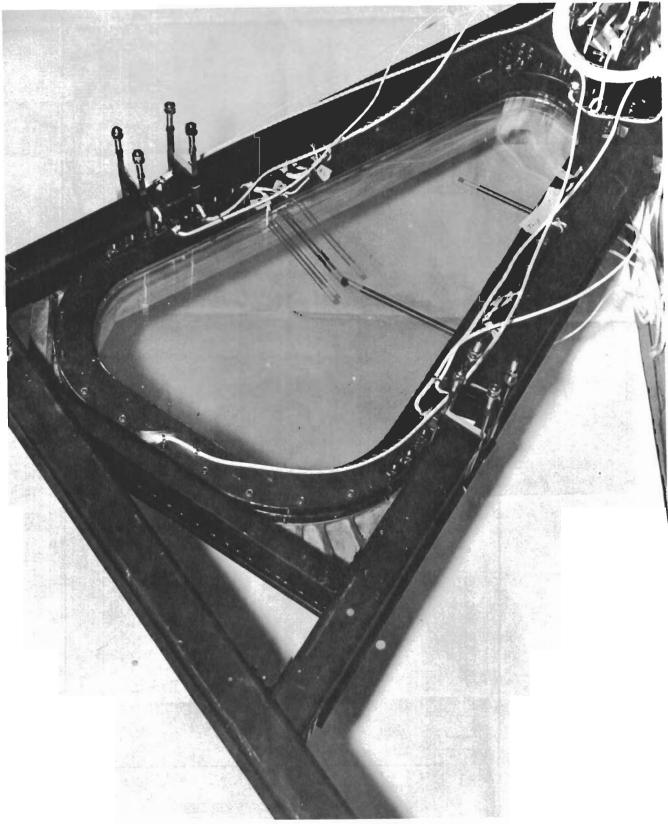
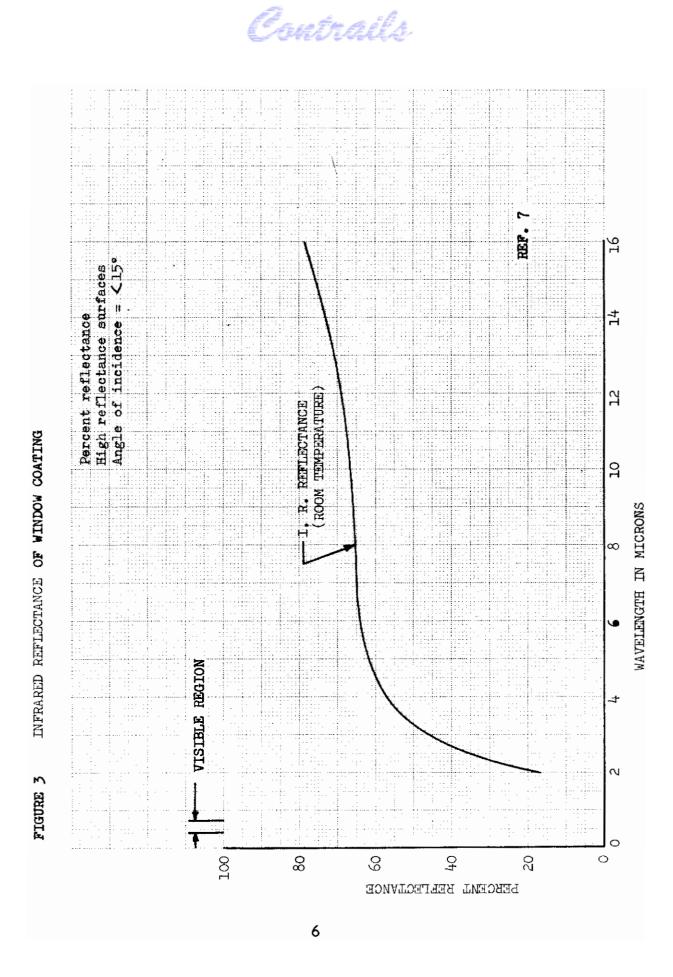


FIGURE 2 X-20 SIDE WINDOW ASSEMBLY



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#### 2.3 THERMISTORS (Continued)

Thermistors (a contraction of thermally sensitive resistors) are electrical circuit elements formed of solid semiconducting materials which are characterized by a high negative coefficient of resistivity. Their use for temperature measurement is based on the direct or indirect determination of the resistance of a thermistor immersed in the environment whose temperature is to be measured. Thermistors are quite stable where they are properly aged before use (less than .1% drift in resistance per month—according to most data). Thermistors exhibit great temperature sensitivity (up to 10 times the sensitivity of the usual base-metal thermocouples) while thermistor response can be in the order of milliseconds. Accuracies of 0.1°F are not unusual. However, the current through the thermistor must be limited to a value which does not increase its temperature by resistant ( $I^2R$ ) heating.

A program was initiated under Air Force Contract AF 33(657)8922 to improve upon existing surface temperature measurements of transparent materials applicable to aircraft glazing. The initial investigation was to develop a thermistor bolometer using high resistance tin oxide films doped with materials that give a high negative temperature coefficient. These films were successful for a high T.C. but became unstable for a temperature range above 500°F which is of primary concern on research aircraft. At this point effort was shifted to a noble metal bolometer.

The Boeing Company Experimental Laboratories had conducted tests on thin film type heat sensors for use in the hot-shot and shock tunnels. Such films as tungsten, and tantalum applied to quartz have been tested. A sample of a silicon-platinum sensor using gold thin film leads installed on fused silica was received from the Corning Glass Works. It was evaluated by the Experimental Laboratories and found to measure temperatures with accuracy.

The bolometer made for special application by Corning Glass Works is a platinum pattern, silk screened on the glass surface and fired in a temperature in excess of 1200°F. The thin film gold leads as well as the siliconplatinum sensor are applied in the form of a paste by a silk screen method. The platinum sensor is fired on first, followed by the gold leads. During the firing processes the platinum sensor and the gold leads are cohesion bonded to the fused silica. The actual firing temperature depends to a large extent on the end use and the glass substrate.

Since the material used is a relatively thin film the actual resistance of the bolometer depends on the number of squares being used. (A square =  $\frac{\text{length}}{\text{width}}$ .) Platinum generally will have a resistivity of 10 ohms/square.

Calibration has shown the bolometer to be completely stable to 1400°F on Vycor or fused silica. The resistance/temperature curve is a straight line between 0°F and 1400°F. The temperature coefficient in parts/million is 1200 ( $\Delta R \over R_{\rm X} \Delta T$  x 10<sup>6</sup>). Gold film used for leads to the sensors have been very successful.

2.3 THERMISTORS (Continued)

A sensor of this type had been used on the X-15 and reached temperatures of  $1700^{\circ}F^{+}$ .

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One point to remember is that high heat flux on external sensors is shorted out by ionized gases at high temperatures-effectively a parallel conductor.

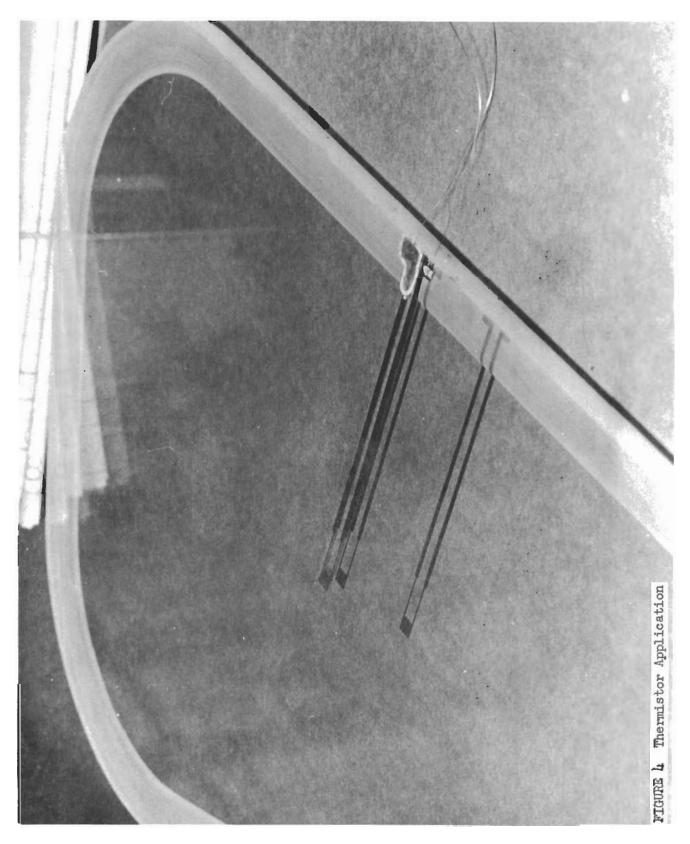
These sensors have been compared against platinum disc type sensors and with various radiation blocking devices. The thermistors are intimately in contact with the glass and do not promote any stress risers to weaken the surface of the glass. They stay on as long as the glass retains its integrity. The thermistors are not adversely affected by optical glass cleaning methods but can be damaged by abrasion.

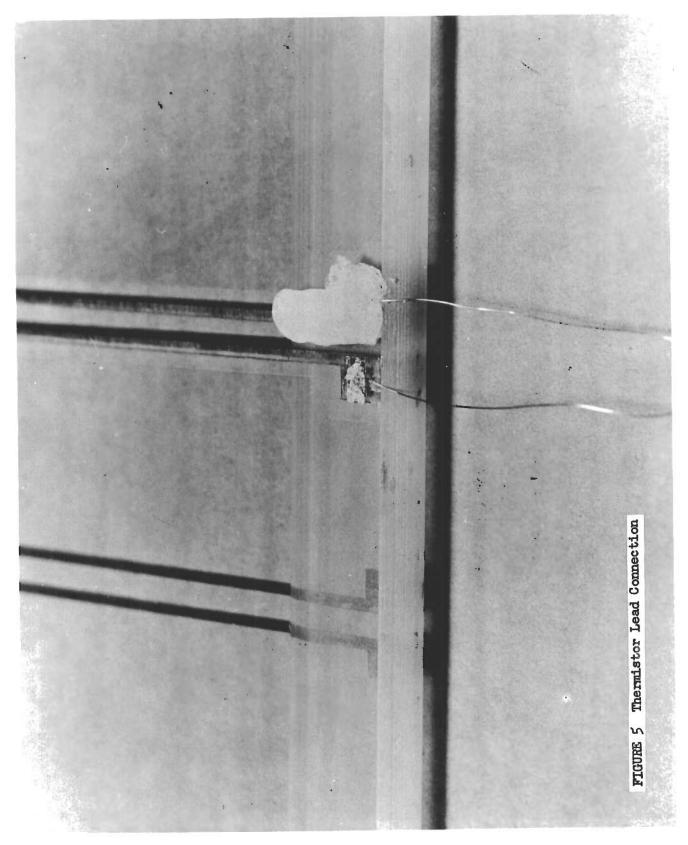
A total of eight (8) thermistors are used to measure the glass temperature. Six thermistors are located on the inside and outside surfaces of each glass pane. The remaining two are located on the exterior surface of the external glass pane, and the internal surface of the internal glass pane. Figure 17 on page 27 shows the location of all thermistors.

The gold thermistor leads are .002 inch thick and are parallel to each other. They lead to the edge of the glass in the same direction for each pane. The leads are terminated at the edge of the glass by forming 1/4 inch by 1/4 inch square gold contact patches.

An external electrical connection is made using a .010 diameter gold wire as a lead through the window frame. The end of the .010 diameter gold wire is flattened to a thickness of .001 to .002. The flattened end is thermocompression bonded (spotwelded) to the thermistor lead at the edge of the glass using a layer of .001 gold foil superimposed. This bonded connection then has a one square inch refrasil tape pad, .010 inch thick, impregnated and tapered out with "Ecco-ceram" compound to act as an electrical insulator. See photograph on page 11. The gold wire is insulated with refrasil tubing except for the leads of the outer pane which must be sealed. At this location 1 mm quartz tubing is used for sealing purposes. Expansion loops are provided. The photograph on page 11 shows the thermistor lead wires. This installation was expected to withstand the vibration and heat environment without failure due to the malleable characteristics of the gold wire with adequate expansion loops provided.

The photograph on page 9 shows one thermistor lead wire after the spotwelded connection was made while the other lead has "Ecco-ceram" compound applied over the connection. The photograph on page 10 shows a close-up view after the same operations have been completed. Figures 6%7 pages 11&12 shows how the thermistor lead wires were routed through the window frame and seals. Only four lead connections occurred at the same location, however.





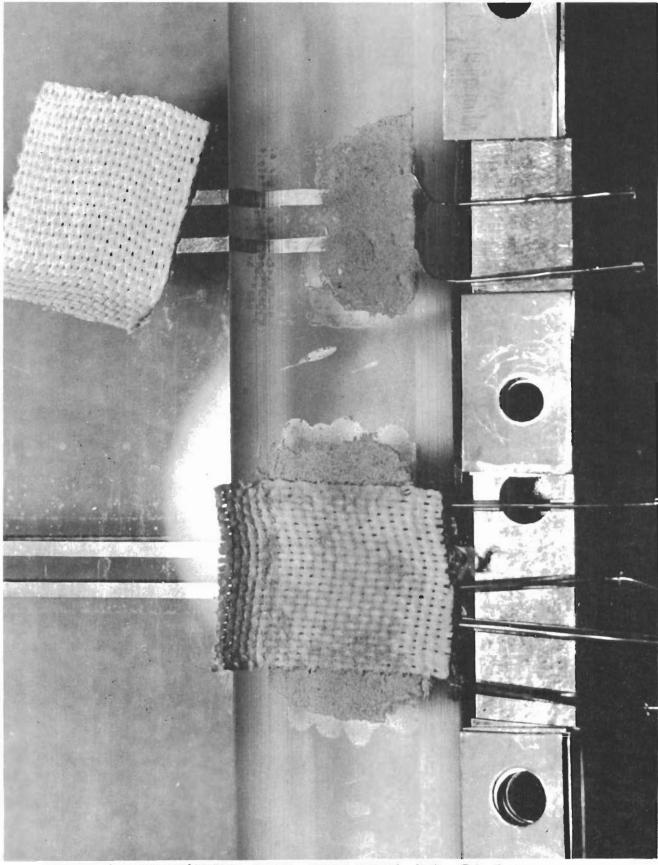
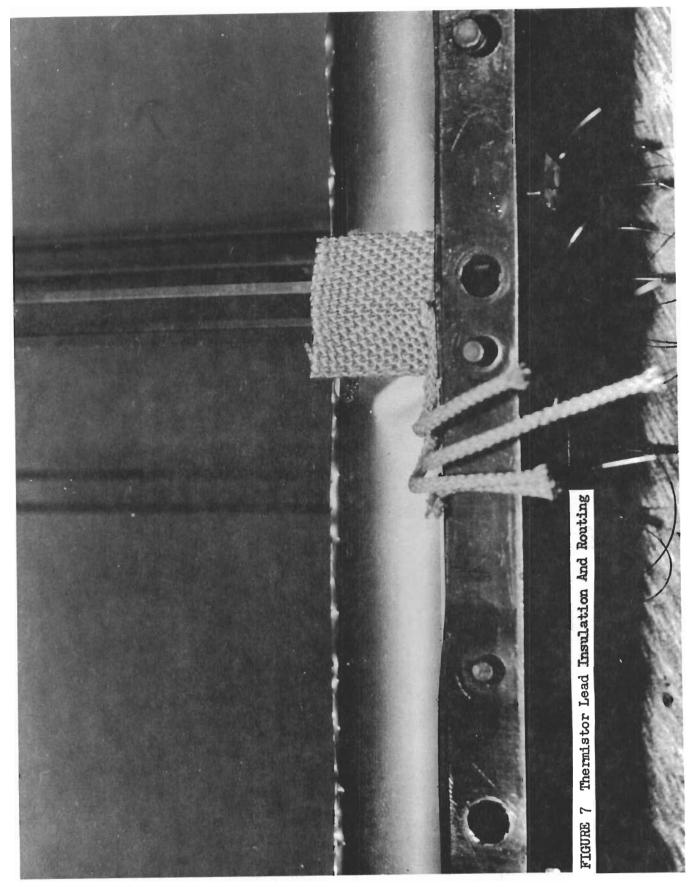


FIGURE 6 THERMISTOR LEAD INSULATION AND ROUTING

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#### 2.4 WINDOW FRAME

The glass panes are supported by a Rene' 41 multi-layered retaining frame. The edges of the panes are clamped between protruding layers of the retaining frame, see page 15. The upper portion of the frame is a continuous rectangular ring section .50-inch wide by .625-inch fabricated from Rene' 41. The lower frame portion is a rectangular section .50-inch wide by .724-inch. The lower portion of the frame is removed at the intersection of the three bearing blocks. The bearing blocks splice this portion of the frame that is removed. The two frame halves are counterbored and riveted together with 3/16 inch diameter Rene' rivets as shown on page 14. This riveting process provides shear continuity between the frame members and also ties in the inner two seals, leaf spring and center backup strip. The outer fairing and inner backup strip are continuous members and are considered as effective frame material.

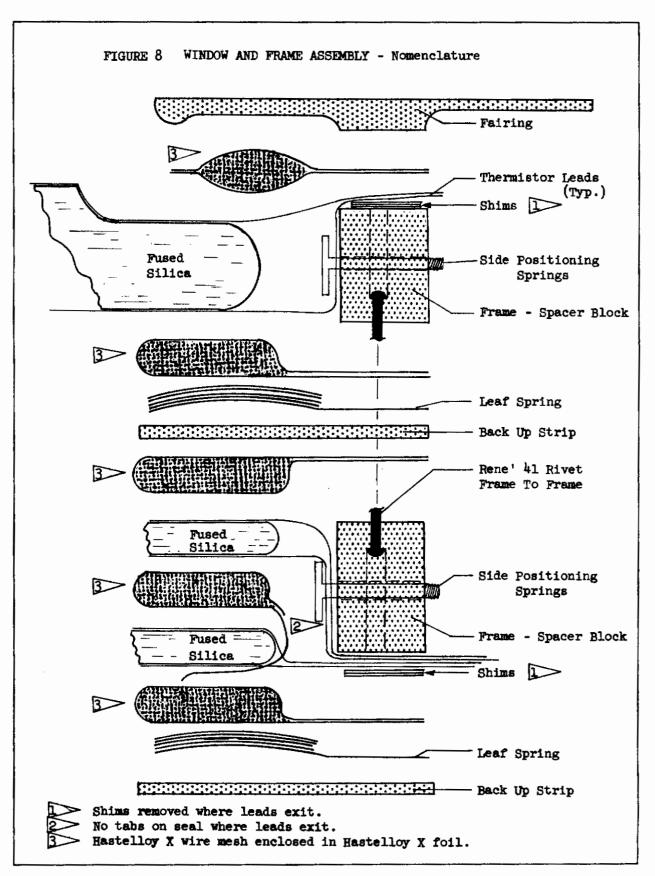
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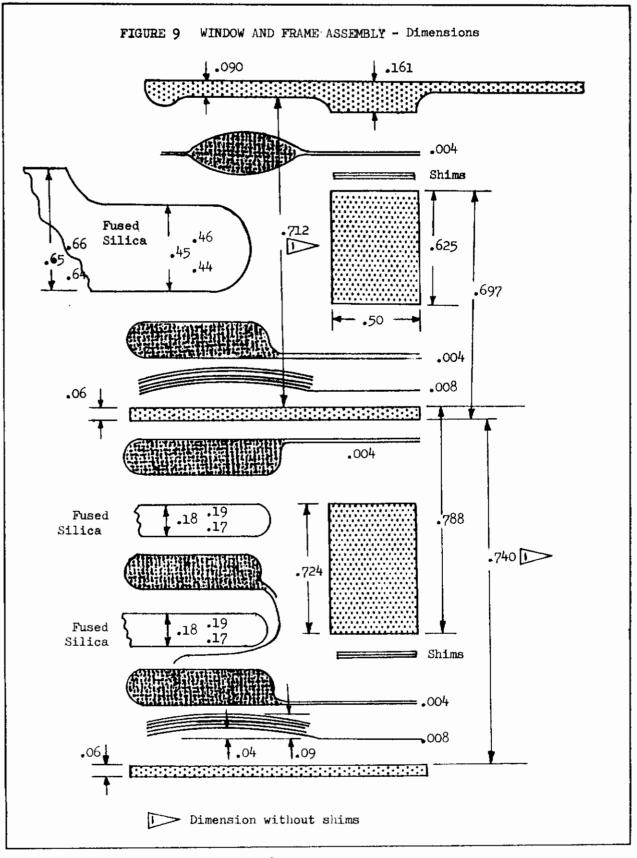
#### 2.5 WINDOW SEALS

The seals are made of a Hastelloy-X wire matrix manufactured by Johns-Manville and enclosed in a wrapping of Hastelloy-X foil which is .002 inch thick. All seals are made from the same size oval-shaped Hastelloy-X wire mesh. The outer seal is made with a continuous covering to act as a seal plane to restrict the flow of hot gas plasma into the fuselage cavity. All seals are wrapped in a jacket that is .80 inch wide except the seal that is between the two .18 inch thick inner glass panes. This seal has a jacket width that is .60 inch wide to give a greater window spacing between these glasses to assure adequate clearance during out of phase vibrations. The seals are approximately .21 inch to .25 inch thick in the uncompressed position. The seals offer a cushion for the glass panes as they are clamped between the layers of the window frame. Tests were run on the window seal configuration to obtain their spring rate and the stress relaxation at high temperature. This information is presented in the Appendix on page 181. A photograph showing the complete seals is shown on page 17. Figures 11 and 12 show positioning of the metallic window seals during assembly.

#### 2.6 WINDOW SPRINGS

Rene' 41 leaf springs are installed in series with the seals. These springs eliminate the slack in the seal system which results from installation tolerances and relative motion and relaxation in the assembly when subjected to heat and load. These springs provide clamping forces after exposure to the maximum temperature environment and allow the window to withstand reentry and approach vibrations. Two sets of the leaf springs are used. They are fabricated from 5 layers of .008 Rene' 41 material. The maximum spring travel is .04 inch. The leaf springs flatten to an overall thickness of .05 inch under a loading of 35 pounds per running inch. The leaf springs exhibit a spring constant of 875 pounds/in per inch of length at room temperature. The seals are nominally clamped up at 35 pounds per lineal inch at room temperature. Under the "hot" environment the springs retain a clamped up pressure of approximately 8 pounds per lineal inch of periphery in the window assembly.





#### 2.6 WINDOW SPRINGS (Continued)

Side springs are provided to position the glass, absorb in plane vibrational loads, and prevent the glass from coming free when the frame expands under high temperature conditions. It is to be noted that the coefficient of thermal expansion of the Rene' 41 window frame is approximately 25 times as great as the fused silica glass. The side springs are fabricated from .05 Rene' 41 material. Stude are welded to the peak of the side springs and extend through the side of the frame. This allows a method of retracting the springs during window installation. The springs are gold plated at their peaks where they come into contact with the edge of the glass to provide a low friction sliding surface and adequate bearing surface. The side springs have a spring rate of approximately 720 pounds/inch at room temperature. A photograph of the leaf seal springs, side springs, and seals is shown on page 17.

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#### 2.7 WINDOW SUPPORTS

The window frame is supported at three locations around its periphery by spherical bearings. The bearing block assemblies are also designed to permit relative movement of the window frame and the cab frame in the plane of the window without inducing redundant force systems. This is accomplished by allowing certain bearing shafts to slide longitudinally and/or transversely in the cab frame.Photographs of the bearing block assemblies attached to the cab frame are shown on pages 20-22. This method of attachment also allows for removal of the window from the outside of the glider which was a design requirement. The window and frame assembly can be unbolted from the bearing block assembly from the outside of the glider for removal and refurbishment.

#### 2.8 CAB FRAME

The cab frame as shown on page 20 is fabricated from rectangular Rene' 41 tubing (2.5 inches by 1.0 inch by .09 inch). The cab frame simulates the glider structure in order to provide proper support conditions for the window structure. It was also desired to show that the thermal elongations and distortions of the cab frame would not be induced into the window structure due to the special three-point window suspension system. A .05 inch thick Rene' 41 fairing extends from the cab frame around the window specimen.

#### 2.9 VACUUM-PRESSURE BOX

A vacuum-pressure box was fabricated from Rene' 41 for the application of air loads to the window specimen in both the hot and cold conditions. A photograph of the vacuum-pressure box is shown on page 23. The vacuumpressure box was designed with an expansion bellows and special foil seal to prevent structural interactions with the window specimen. A mylar seal was used for the boost airload negative pressure test. No conditions were run with airload applied during high temperature due to premature glass failure. It was planned to make a continuous seam weld of the foil seal to the vacuumpressure box for the high temperature load condition.

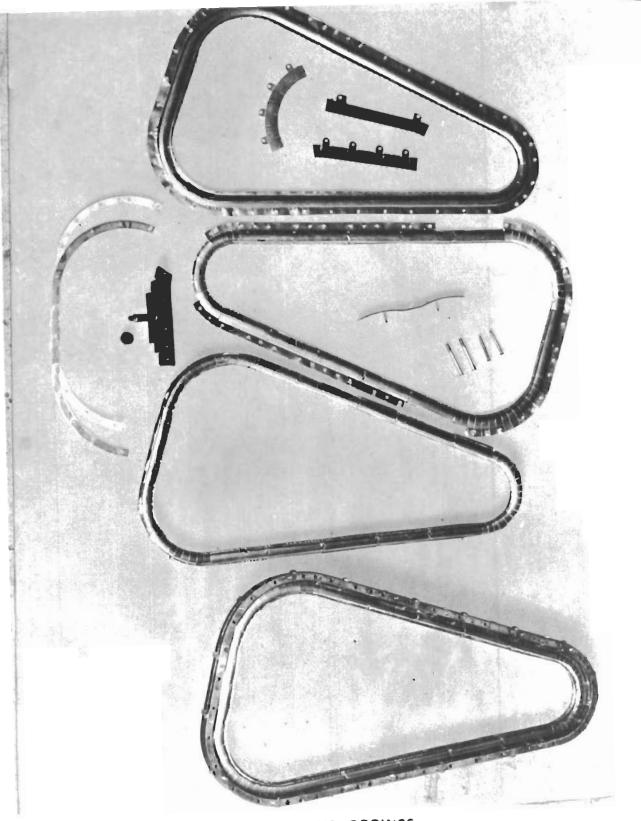
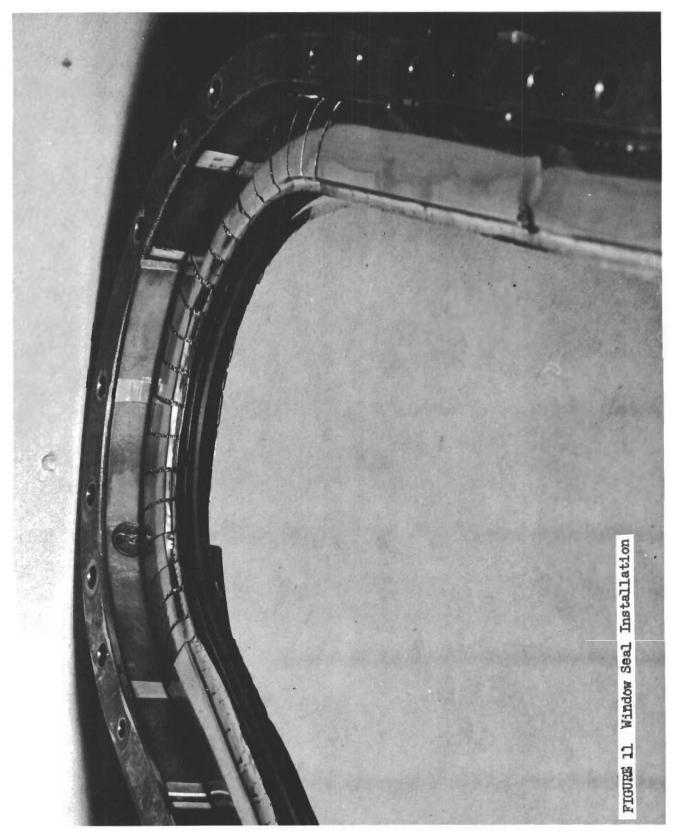
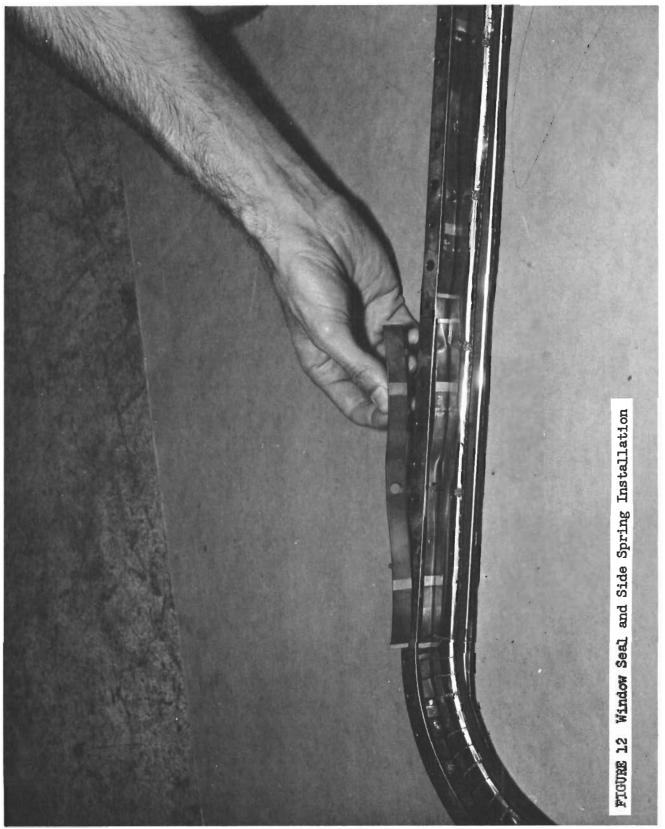
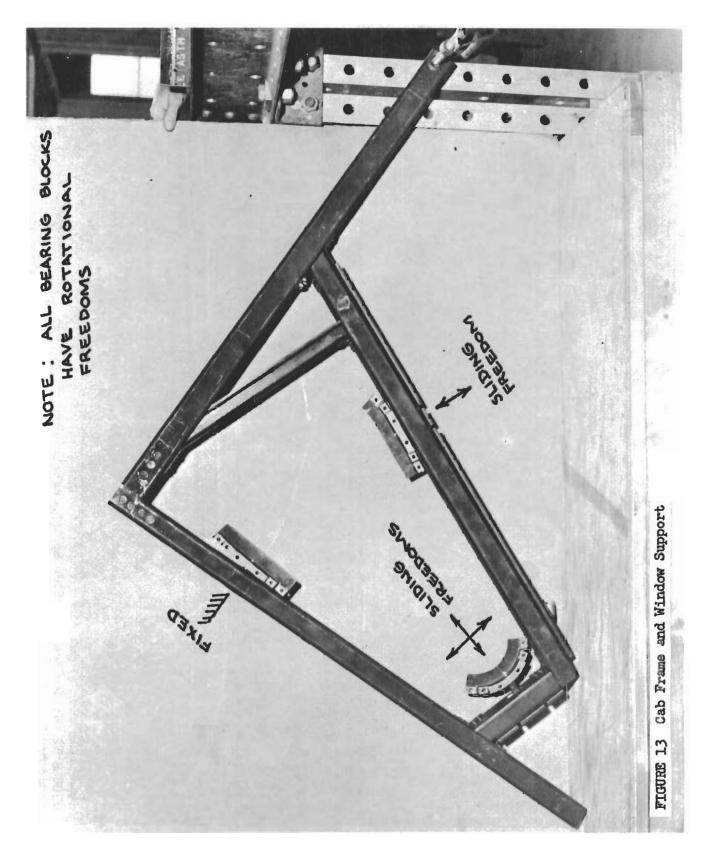


FIGURE 10 WINDOW SEALS AND SPRINGS



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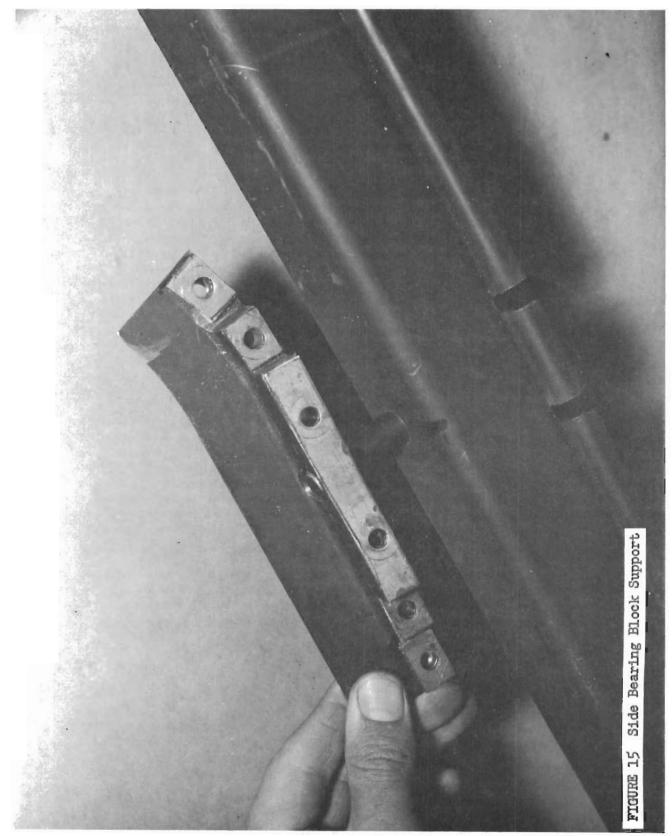




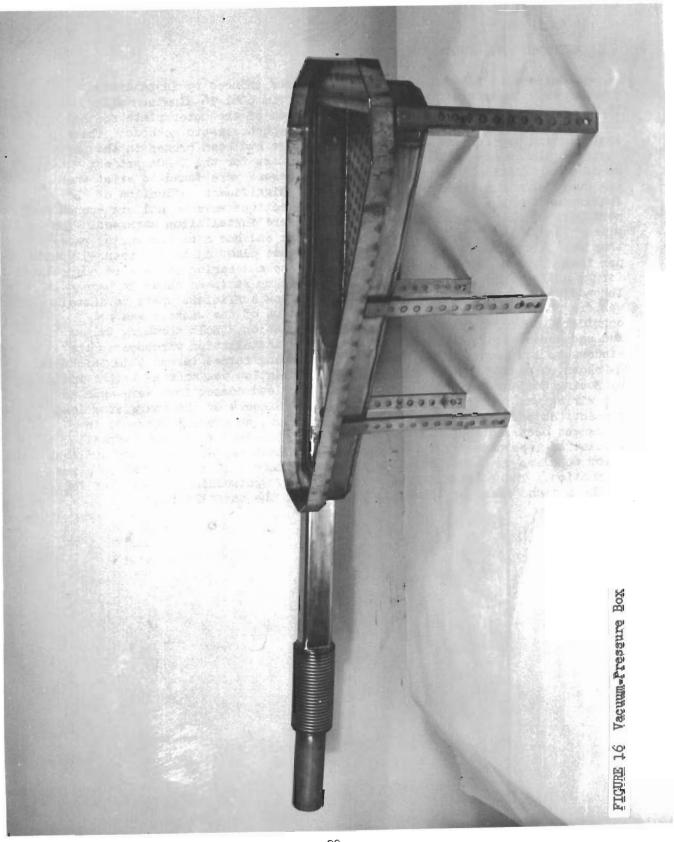
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#### 2.10 ASSEMBLY AND WINDOW INSTALLATION

It was desired to determine the glass stresses induced by installation procedures. Dummy windows were fabricated from 6061-T6 aluminum alloy. Photoelastic plastic was bonded to the outside of the outer plate so that installation stresses could be determined by photoelastic methods. These installation precautions were taken as a glass had been broken in the past during a window edge attachment development test for the X-20A project during installation. Large installation stresses were found to exist when the dummy aluminum windows were installed. Significant deflection of the fairing and backup strip occurred. The deflections were nonuniform around the periphery of the glass which lead to the severe installation stresses. The primary cause was that the seals were thicker and had a higher spring rate than was called for by the design giving higher clamping forces than 35 pounds per inch. These differences in seal thickness and spring rates were compensated for by adding shims under the fairing and backup strip as shown on page 15. The addition of the shims however did not allow sufficient space to install washers under the retaining nuts. The deletion of the washers was not considered deterimental to the window installation. Bolt torquing values and sequences were established to reduce the installation stresses in the windows to low levels. Calculations of clamping forces versus shim thickness are shown on page 191. The final glass installation was made at Wright Field by Boeing Company personnel. The thermistor lead connections were made and the wiring was routed as shown on page 14. Since 4 of the thermistor lead connections occurred at the same frame location, an overall increase in thickness occurred equal to the thickness of the lead wires and refrasil insulation tape pads. This increase in thickness was approximately .05 inch prior to clamp up. This resulted in a small hard spot in the seal to glass foundation. The retaining nuts were locked by spotwelding Hastelloy-X foil to the nut and shank of the bolts to complete the installation.

3 INSTRUMENTATION

Instrumentation of the test specimen and supporting test fixtures includes accelerometers, thermistors, thermocouples, deflection gages, pressure gage, and flowmeters. A detailed description of instrumentation and its location follows:

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### 3.1 ACCELEROMETERS

Accelerometers were of the crystal piezoelectric type. Control accelerometers were installed rigidly to the specimen. Glass accelerometers were installed with double-backed tape. Locations of the accelerometers are shown on pages  $\frac{1}{12}$  and  $\frac{1}{14}$ .

### 3.2 THERMISTORS

Thermistors are of the thin film type as described on page  $l_1$ . A total of eight thermistors are used to measure the glass temperature. Six thermistors are located on the inside and outside surfaces of each glass pane. The remaining two are located on the exterior surface of the external glass pane, and the internal surface of the internal glass pane. Figure 17 on page 27 shows the locations of all thermistors.

### 3.3 THERMOCOUPLES

A total of 19 Refrasil-insulated, 22 gage, Type K (chromel-alumel) thermocouples are spotwelded to the Rene' 41 window frame assembly and cab frame as follows: 7 on the window frame outer fairing, 6 on the window frame at the bearings, 2 on the window frame at the inner flanged backup ring, and 4 on the cab frame. See figure 17 page 27 for locations.

These thermocouples are used to establish temperatures and gradients of the window frame and cab frame.

Where possible, the thermal junction was formed by spotwelding the individual thermocouple wires to the specimen parallel to each other and approximately 1/10 inch apart, thereby including a small section of the Rene' 41 specimen in the thermocouple circuit. The ends of the Refrasil insulation wire covers were treated with Synar (trade name for a silica acid solution manufactured by the Pennsylvania Salt Company) to inhibit raveling.

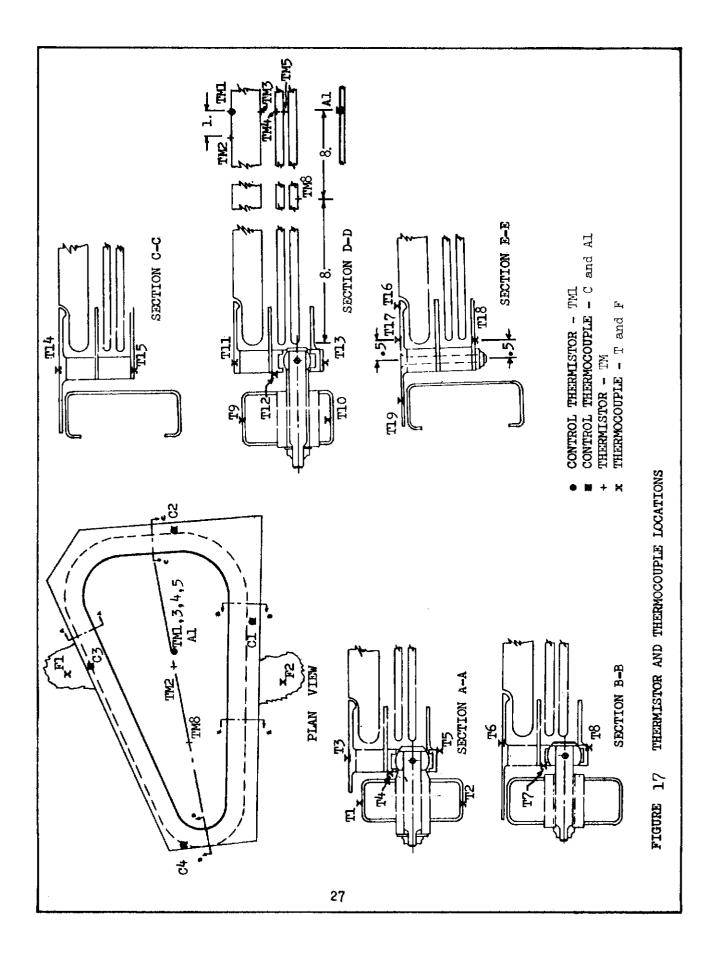
### 3.4 DEFLECTION GAGES

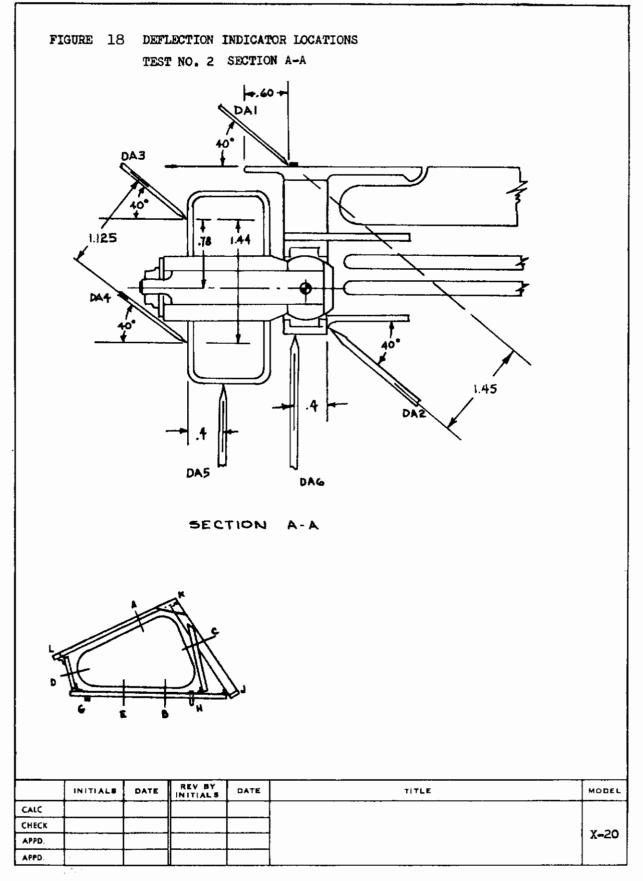
A total of 2<sup>4</sup> deflection measurements were made as shown in Figures 17 through 19 pages 27 through 37 for heat and load test conditions. A system employing low thermal expansion quartz rods in conjunction with strain gage-cantilever beam deflection transducer devices was used for all deflection measurements. The deflection transducer devices were manufactured by Structures Branch FDTT at the Flight Dynamics Laboratory.

3.5 PRESSURE GAGE AND FLOWMETER

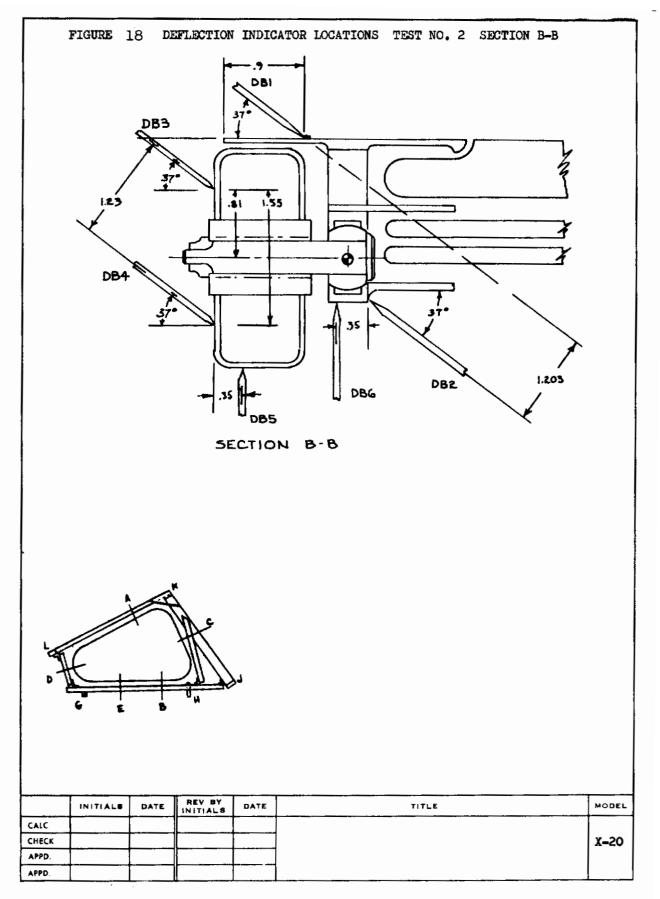
Pressure and flow measurements for the pressure box test fixture were made using the following equipment: Meriam Laminar Flow Meter Element -Model 50NH10; Meriam Inclined Manometer - Model 40HE 34; Meriam Mercury Pressure Manometer - Model 338A and Air Temperature Sensor manufactured by the Structures Branch (FDTT).

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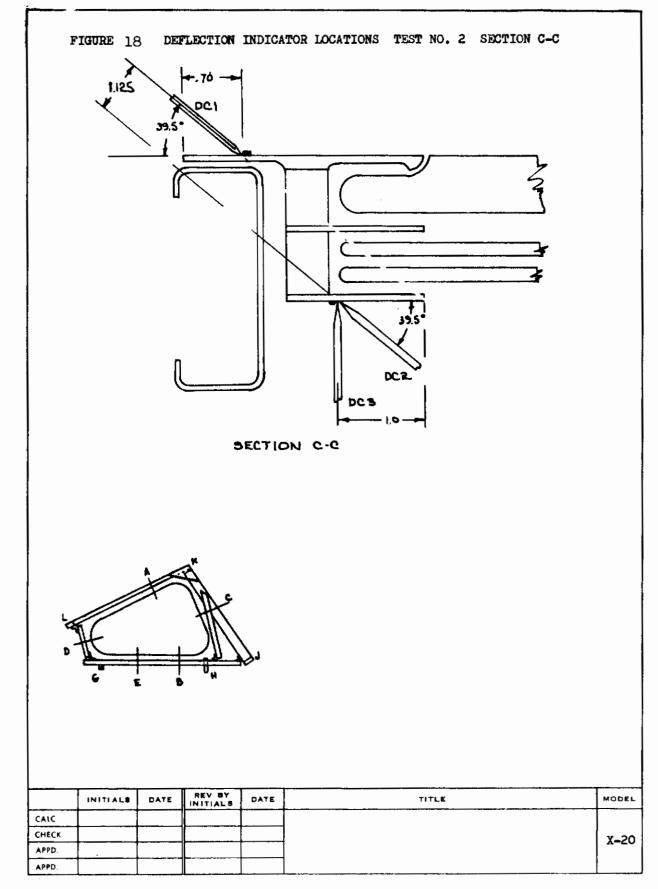




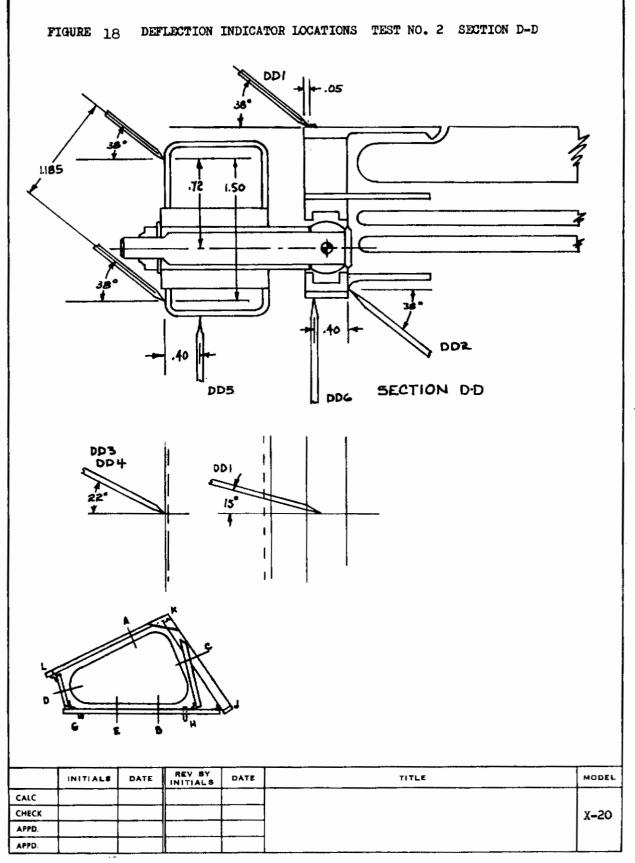
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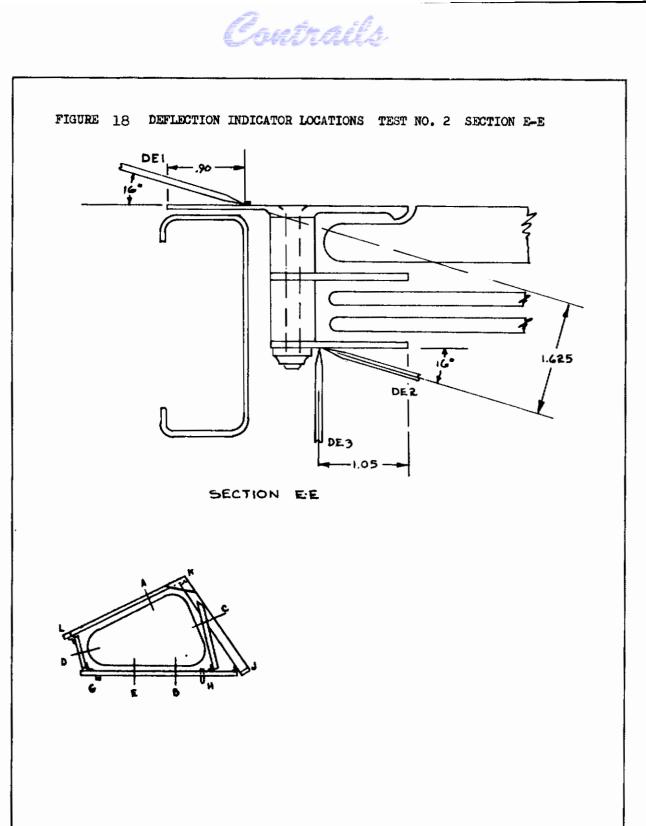


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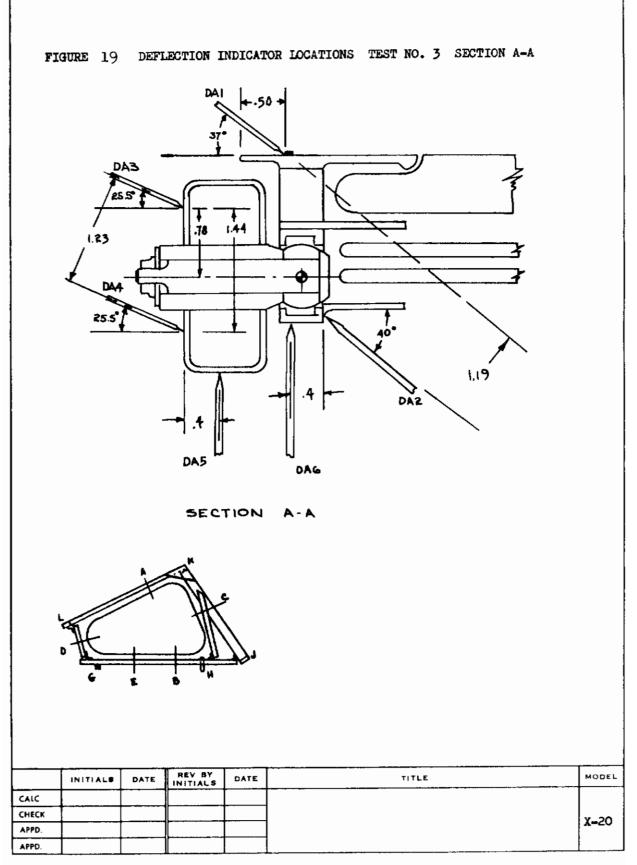


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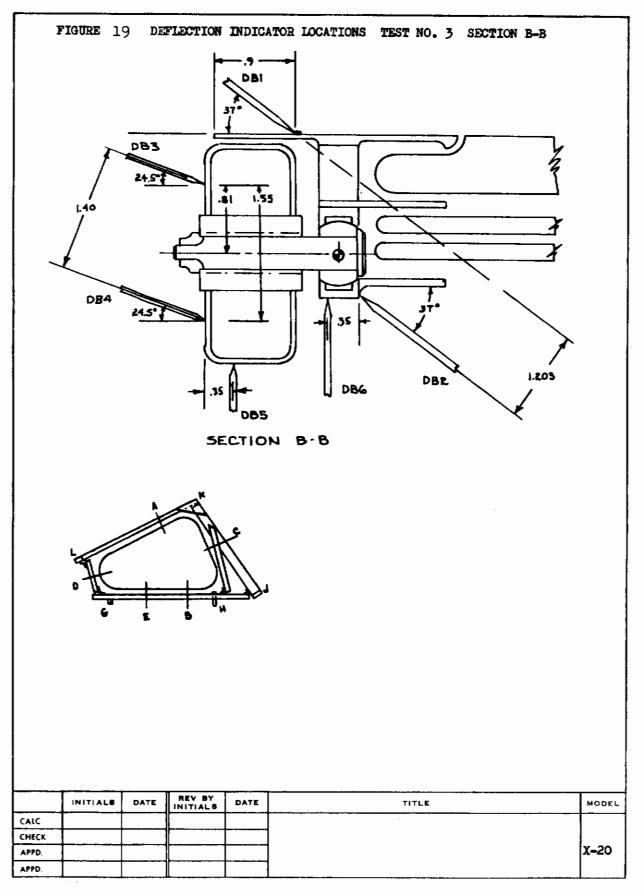


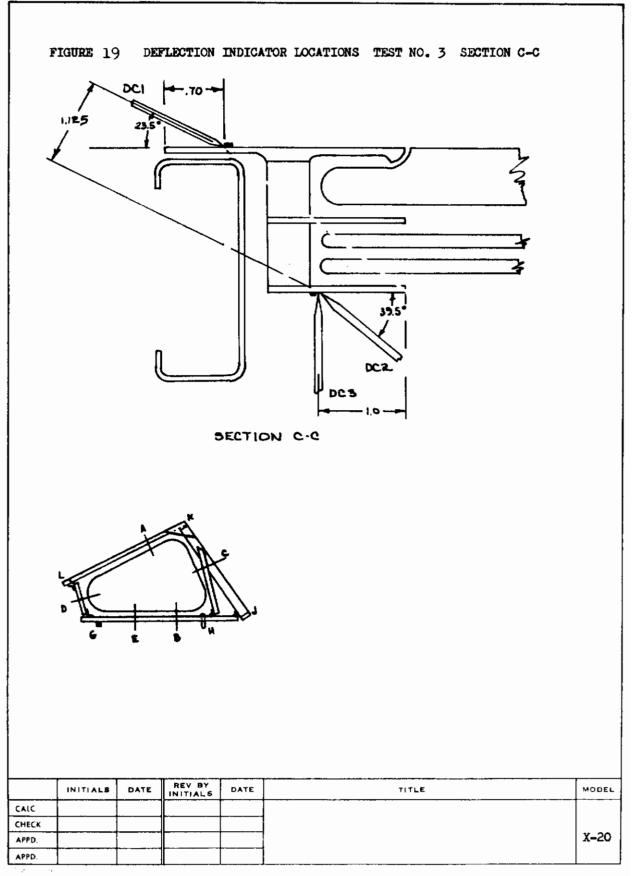


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APPD						

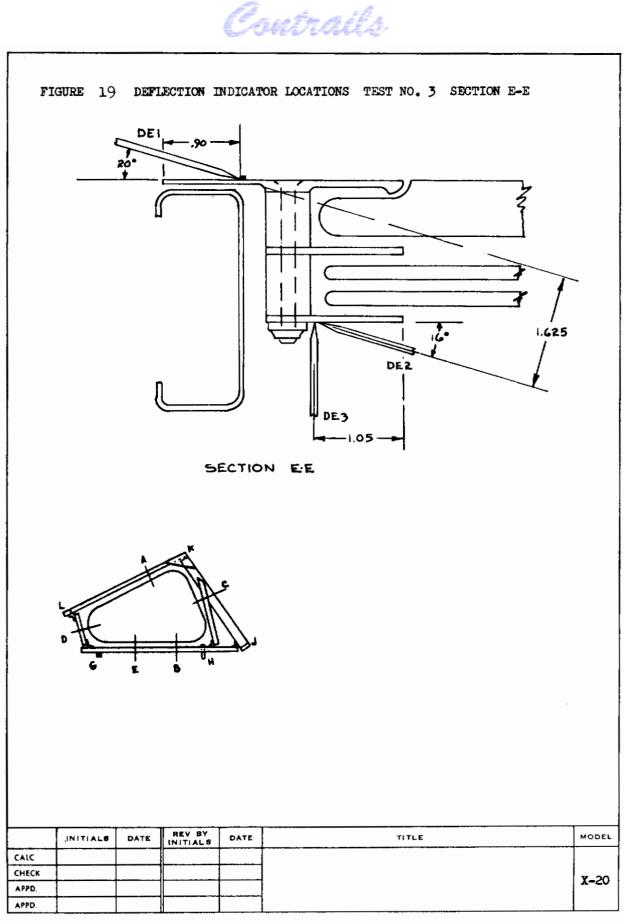


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4 TEST PROCEDURES AND RESULTS

4.1 TEST CONDITION NO. 1 (BOOST VIBRATION)

4.1.1 TEST CONDITION NO. 1 PLAN

This test condition was planned to verify the structural integrity of the X-20 window assembly when subjected to the boost vibration environment.

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Sinusoidal vibration scans were planned as shown on page 39 conducted normal to the plane of the window (Axis "A") and in the plane of the window (Axis "B"). Resonant responses of the window assembly could thus be determined between 50 and 2000 cycles per second by using travelling accelerometers attached with double-backed tape. These measurements could be analyzed to show resonant frequencies, resonant bandwidths and amplification factors, and mode shapes for all measurable resonances.

After the sinusoidal vibration testing was completed it was planned to subject the window assembly to two room temperature random vibration tests, one in the "A"-axis direction, and one in the "B"-axis direction. The planned test envelope is shown on page 40. Input to the shaker while supporting the specimen could be limited at specific frequencies as necessary so that resonant responses of the window assembly would not exceed the upper tolerance of the test envelope. The test duration of 10 minutes for each axis was planned. A record of the acceleration power spectrum and overall acceleration applied in each axis at each monitor point could then be prepared.

### 4.1.2 VIBRATION EQUIPMENT

The largest shaker system available for the vibration testing at the Flight Dynamics Laboratory consisted of:

Ling Electronics

A-300B Shaker, Maximum Load = 300 Pounds

PP20/35 Power Amplifier

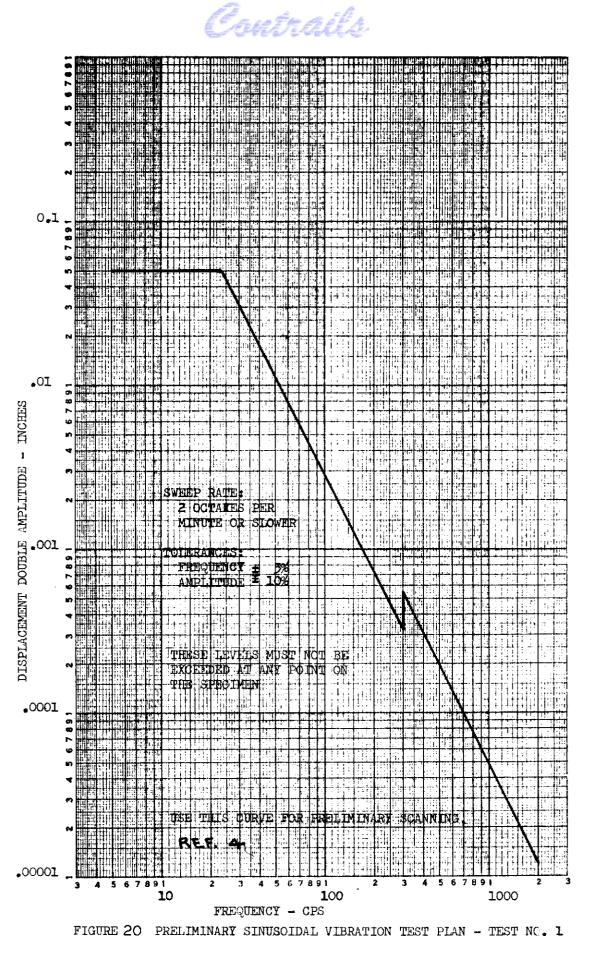
R1003C Sine Console

R1001-2 Random Console

ASD-20 26 Channel Analyzer

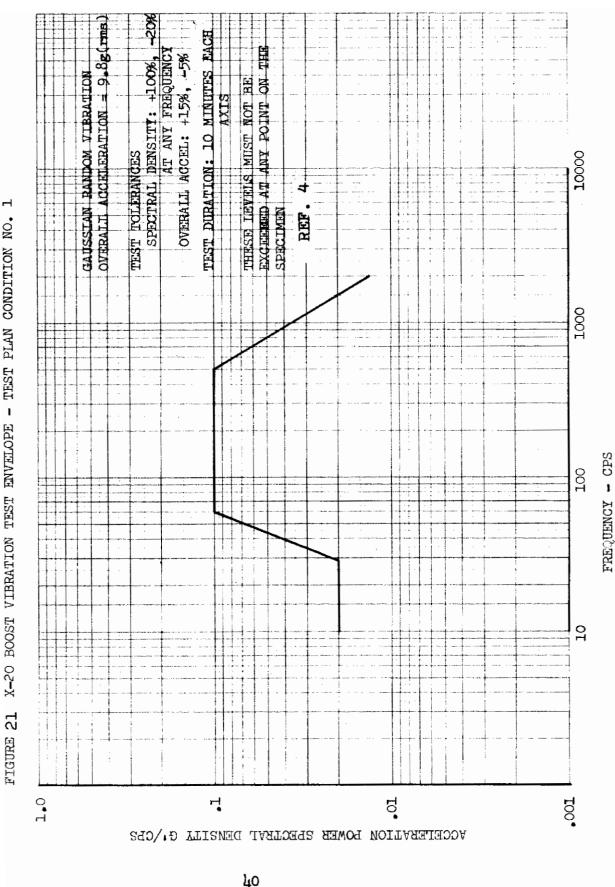
ESD-20 Equilizer (Band Width varies from 17 cps at 100 cps to 100 at 700 cps and on)

Since the weight of the window test specimen assembly was approximately 100 pounds, the test fixture weight was limited so as not to exceed the maximum load capability of the shaker. The test fixture consisted of a two inch thick aluminum plate.





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X-20 BOOST VIBRATION TEST ENVELOPE - TEST PLAN CONDITION NO.

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4.1.3 TEST PROCEDURES

The following paragraphs are a record of the vibration tests as conducted.

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The window frame was rigidly attached to the test fixture and a Ling Model A300 vibration exciter. Vibration was first applied vertically, perpendicular to the plane of the glass.

For preliminary information, initial scanning was accomplished for the vertical direction by performing a sinusoidal frequency sweep from 5 cps to 2000 cps. The sweep rate was less than 2 octaves/minute. The input double amplitude was 0.025 inch from 5 cps to 23 cps and 0.2 g from 23 cps to 2000 cps.

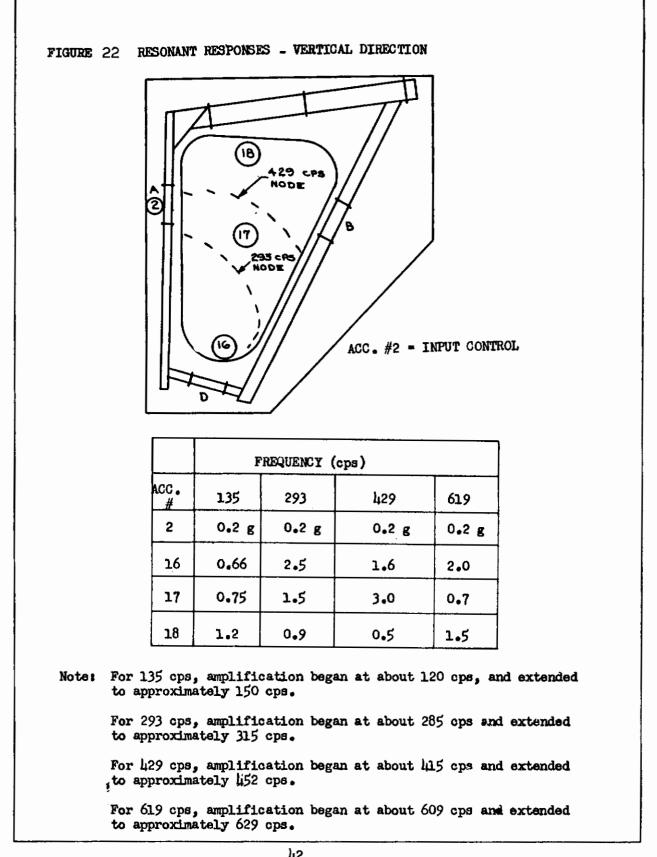
Rather severe resonances were found to exist in the A-frame members which overhung the edge of the fixture. Consequently, the two projecting members were removed at the fixture edge by means of a high speed cutting wheel.

The fixture without the window test specimen was installed on the shaker and a complete dynamic survey was conducted on the fixture alone. An amplification factor (Q) of 56 was noted at one point on the fixture (2 g input gave 112 g's on plate). This data indicated that the fixture did not have sufficient stiffness to accurately control the vibration levels.

The fixture and specimen were then instrumented to determine the resonant modes of the upper glass pane and the frame unit in which it was installed.

The window was again mounted on the fixture and a complete dynamic survey of the fixture and specimen was accomplished. The Q of the fixture had dropped from 56 to 15 at the most severe point. The outer .65 inch thick window had a Q of approximately 30. Wide band random vibration was then applied to the specimen, perpendicular to the plane of the glass. The random vibration input was applied at extremely low level, 0.001 PSD maximum, in lieu of 0.1 PSD as recommended by Boeing Document D2-81293, Window Test Plan, Reference 4. The test plan level is shown on page 40. The response of the upper glass was monitored and the input vibration level was reduced so that the response of the glass would not exceed twice the input PSD value. A recording and analysis of this data was made so that it could be compared with data planned to be taken after the heat test.

The specimen and test fixture were next mounted on an oil film table, oriented so that vibration was applied horizontally, along the "B" axis, as shown on page  $\frac{1}{14}$ . Initial scanning was accomplished for this direction by means of a sinusoidal frequency sweep from 5 cps to 2000 cps, with an applied double amplitude of 0.025 inch from 5 to 23 cps, and 0.2 g from 23 cps to 2000 cps. Resonant responses of the upper glass pane and frame were recorded.



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4.1.3 TEST PROCEDURES (Continued)

Wide band random vibration was then applied for this "B" axis direction, also at the extremely low level of 0.001 PSD maximum, in lieu of 0.1 PSD. A recording and analysis of this data was also made for comparison with data planned to be taken after the heat test.

A review of the vibration test data was made. The following factors were areas which were found to exist that could result in overtesting the X-20 side window specimen during the required random vibration testing:

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a. Due to equipment force limitations and physical size limitations, the vibration fixture design had very limited parameters and therefore several resonances (two severe) exist in the fixture which may cause serious overtesting at these frequencies.

b. The test plan (Reference 4 ) requires that all responses are to be limited to the overall upper tolerance level (100% above spectrum) of the random vibration spectrum. Due to limitations of analyzing equipment, this requirement will be difficult to meet. There are also areas of the specimen (the two lower glass panes) that cannot be instrumented so control at these points will not be accomplished.

c. The equalizing equipment is manually operated for adjustment purposes so it must be adjusted while exciting the specimen and therefore, may result in short periods of overtesting. A dummy mass in this case would not help unless it were a dynamic simulation of the specimen. There is approximately a factor of 5 difference in the fixture amplification factor between the fixture alone and the fixture with the window mounted. (Q = 56 unloaded, Q = 15 with specimen mounted.)

Since the above uncontrollable areas were present a possibility of window failure due to overtesting existed. It was decided to postpone the fullscale boost vibration testing until after the heat and load test had been accomplished.

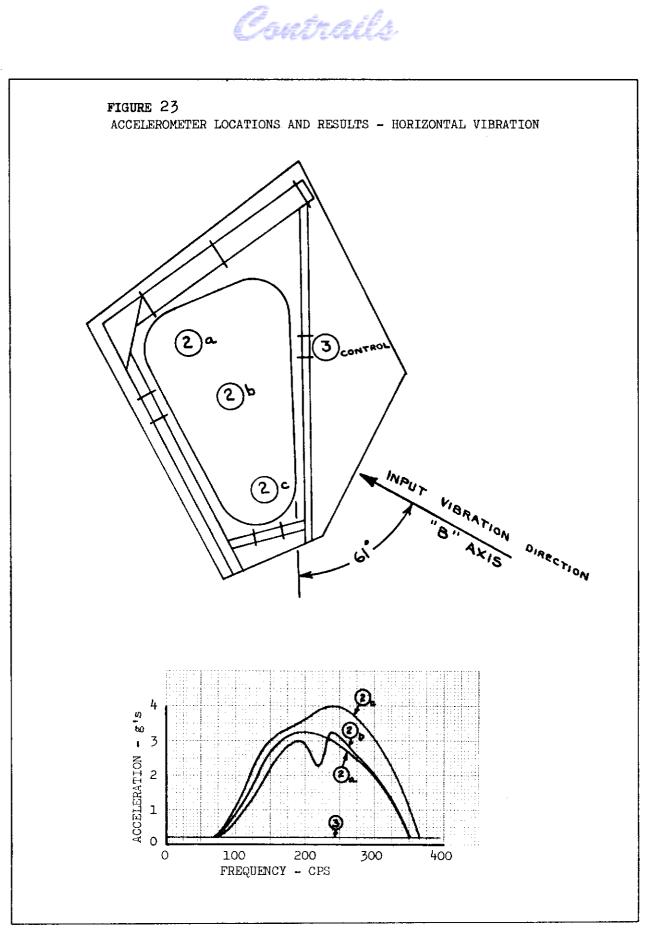
4.1.4 TEST RESULTS

Significant resonant frequency data recorded during the initial sinusoidal frequency surveys are as follows:

4.1.4.1 RESONANT FREQUENCIES - VIBRATION APPLIED PERPENDICULAR TO GLASS - AXIS "A"

a. No resonances were detected below 120 cps.

b. 120 cps to 150 cps, chatter occurred which was manifested in movement of the sliding joint at point D, Reference 4 & page 42. Maximum chatter was observed at 135 cps. This chattering motion resulted in amplification factors as high as 6, when measured on the upper pane of glass and on the frame immediately adjacent to the glass. (See Figure 22 page42).



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4.1.4.1 RESONANT FREQUENCIES - AXIS "A" (Continued)

c. The only resonances of the upper glass pane for which a mode shape could be drawn were observed at 293 cps and 429 cps. The frequency of 293 cps was attributed to a fixture resonance. The frequency of 429 cps is the only authentic glass pane resonance found. (See Figure 22 page 42). It has an amplification factor of 15 at the center of the glass.

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4.1.4.2 RESONANT FREQUENCIES - VIBRATION APPLIED HORIZONTALLY IN A PARALLEL PLANE WITH GLASS - AXIS "B"

a. A very gradual buildup in amplification for accelerometer locations on the glass began at around 70 cps. For location 2a, Figure 23 page 14 the gradual rise reached a maximum amplification of 3.25 at 190 cps, 3.0 at 240 cps, continuing at 2.5 up to 275 cps, dropping to input level at 350 cps.

b. For location 2b, Figure 23 page 44 initial amplification began at around 70 cps, with a gradual rise to a maximum of 3.0 at 190 cps, 2.25 at 220 cps, 3.25 at 240 cps, continuing at approximately 2.5 to 280 cps, dropping to input level at 350 cps.

c. For location 2c, Figure 23 page 44initial amplification began at around 70 cps, with gradual rise to a maximum of 2.75 at 140 cps, 3.5 at 190 cps, 4.0 at 240 cps, 3.75 at 270 cps, dropping to input level at 365 cps. 4.2 TEST CONDITION 2

4.2.1 TEST CONDITION 2 PROCEDURE

The window specimen was pressure loaded with air at room temperature to a negative 7 psi (outward acting). This pressure simulates the X-20 boost limit pressure and is the limit load design condition for the window.

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The window was mounted securely to the test stand. The pressure-vacuum box was mounted on the window. Mylar was initially proposed to seal the pressure box to the window frame for this test condition. The mylar was installed but did not provide a satisfactory seal. It was removed and zinc chromate putty was used to make a satisfactory seal. A photograph of the test setup is shown on page 52.

Pressure was applied to the specimen as shown on page49. The pressure leakage rate, and window and cab frame deflections were recorded for all test times.

A schematic of the apparatus for measuring the air leakage is shown on pageh7. Prior to the test, the vacuum line was capped off at the test specimen. The valve was closed and the pump shut off to assure that no leakage existed.

The procedure followed during the test was to close Bleed Valve B until the pressure manometers read the correct pressure in the pressure box and then read the Meriam Flow Meter. This indicated the amount of air flowing back to the vacuum pump and thus the amount leaking into the pressure box through the window seals. The flow meter was calibrated to read up to 1.6 SCFM with water in the manometer. When it became apparent the leakage was going to exceed 1.6 cfm, mercury was substituted for the water in the inclined manometer to extend the range.

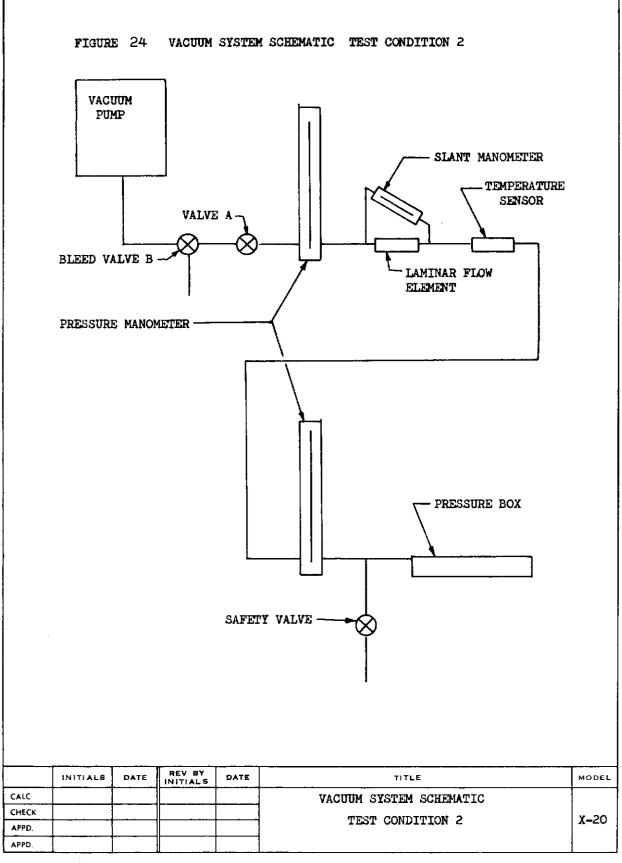
Following the test, a value was installed at the test specimen end of the vacuum line and a series of flow versus pressure readings were made with the value opened to different amounts in order to verify the linearity of the flow meter up to the flow value measured during the test.

### 4.2.2 TEST CONDITION 2 RESULTS

### 4.2.2.1 WINDOW SEAL LEAKAGE RATE

The target leakage rate as defined in Reference 2 is  $1.17 \times 10^{-4}$  ft<sup>2</sup> per foot of seal with a corresponding leakage rate of .55 x 10-5 pounds/second per foot, for choked flow at standard conditions. These target requirements were set-up to control the design from the standpoint of aerodynamic heating. The above sealing capability was desired at the time of high heating during re-entry in order to seal the hot gas plasma from heating the internal fuselage cavity. Fortunately the maximum pressure during the critical heating

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4.2.2.1 WINDOW SEAL LEAKAGE RATE (Continued) period during re-entry is quite low. The pressures should not exceed .50 pound/inch<sup>2</sup> during the significant heating period for the X-20 side window during re-entry. The following calculations were made to determine the target leakage rate: LENGTH OF SEAL = 5.58 Feet TARGET LEAKAGE RATE = 5.58 (.55 x 10<sup>-5</sup>) = 3.06 x 10<sup>-5</sup> pounds/second AT .5 PSI = .001836 pounds/minute = .001836/.0766 = .024 cubic feet/minute TARGET LEAKAGE RATE = .34 cubic feet/minute

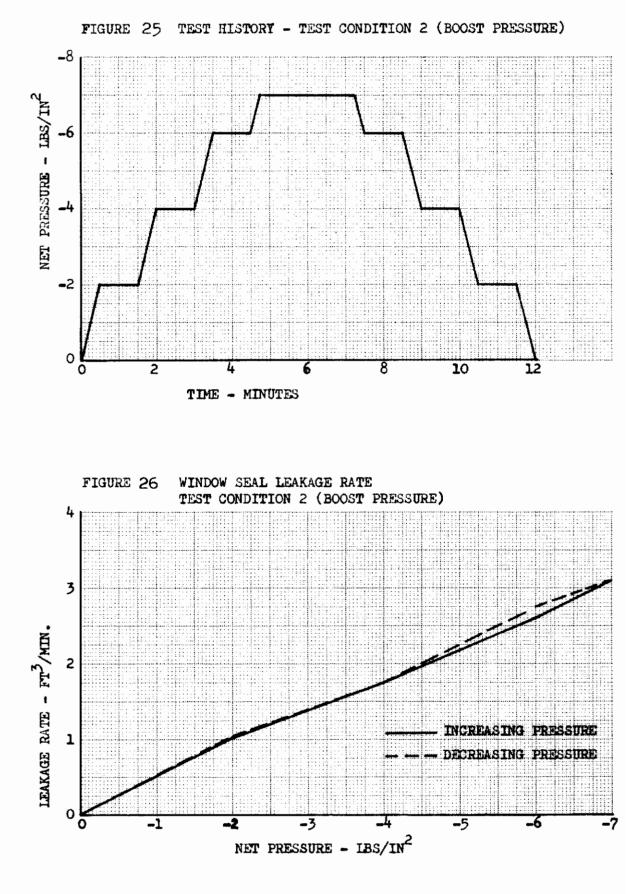
The leakage rates recorded during the test are shown on page 19. It is seen that the recorded leakage rates exceed the design target value by a factor of 10. Since the thermistor lead wires ran across the seal as outlined on page 24, it is believed this resulted in the high leakage rate. Therefore the leakage rates are not considered conclusive of the sealing qualities of the seals as the flight article would not have these thermistor leads.

#### 4.2.3 DEFLECTIONS AND ROTATIONS

Deflection and rotation locations for Test No. 2 are shown on pages 50 through 51 . The test deflection and rotation measurements were corrected for rigid body movements as outlined in the Appendix on page 195. These data were then compared with calculated values. The calculated values were determined from an analysis based on the direct stiffness method as programmed for the digital IBM 7094 computer by The Boeing Company. The analysis is shown in the Appendix on page 195. The comparison of window frame rotations (torsional angular twist) with analysis values are shown on page 50. It is seen that the test values lie in most part between the fixed and pinned analysis cases. The comparison of vertical frame deflections are shown on Reasonable agreement between test data and analysis exists. It page 51. is concluded that the good agreement between the analysis and test data is evidence that the window assembly has no structural weakness. Extrapolation of this data to ultimate load indicates that the window assembly could withstand the ultimate load without failure.

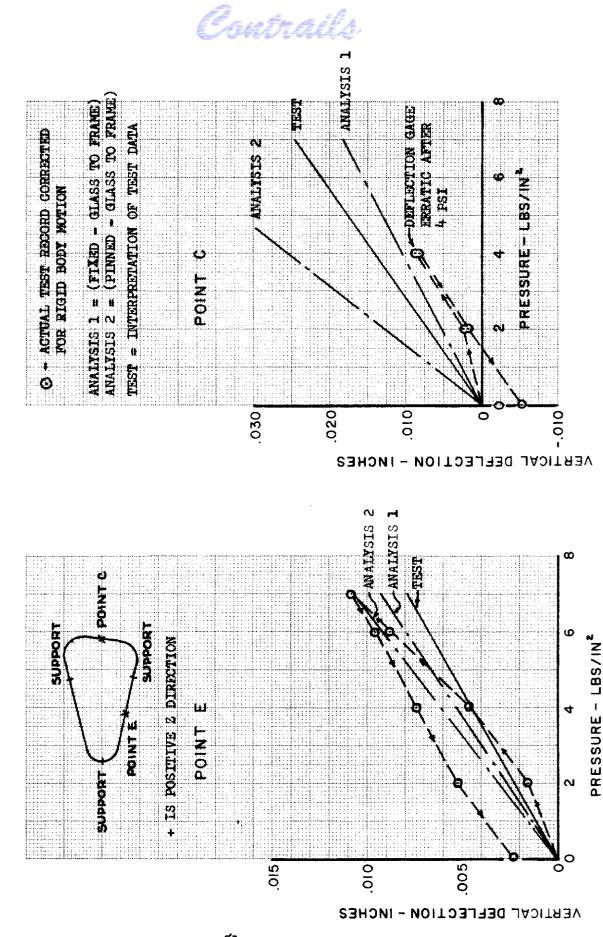
The window frame to glass gaps were recorded before and after the test as shown on page 121.

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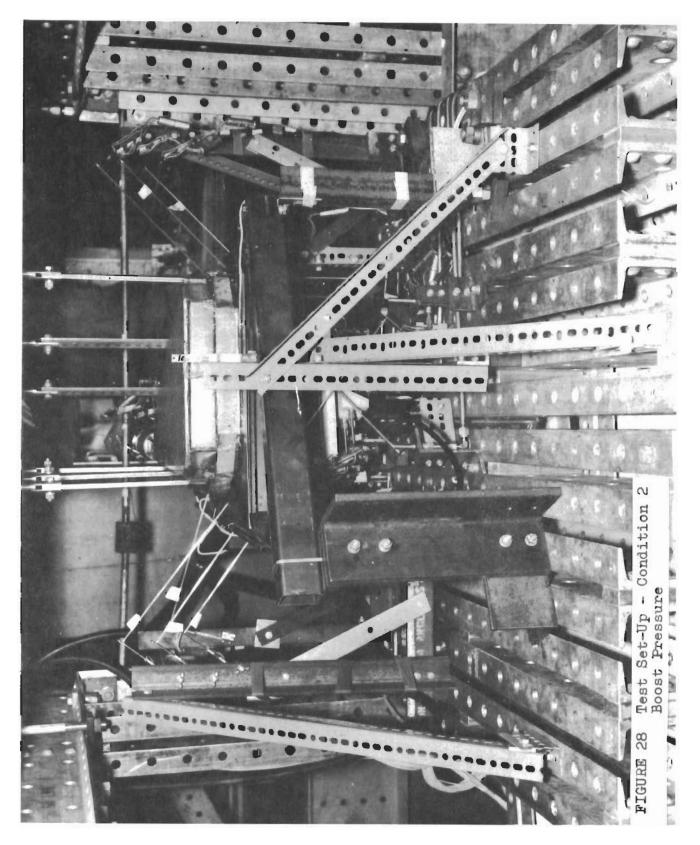
TABLE 1 ROTATION COMPARISON AT -7 LBS/IN <sup>2</sup> PRESSURE													
	WINDOW FRAME ROTATION - RADIANS												
		<b></b>											
			1	ŒD	PINNED	TEST DATA							
							4						
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4.3 TEST CONDITION 3 (RE-ENTRY THERMAL CYCLE)

4.3.1 TEST CONDITION 3 PROCEDURE

The window specimen was to be heated as shown in Figure 29 page 54. The time-temperature requirements represent a thermal cycle which simulates the X-20 maximum lateral range re-entry. Figure 30 page 57 is a photograph of the test set-up. The test specimen support conditions are shown on page 58.

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Efficiency tests conducted prior to the actual test indicated the silicon carbide powder installed per the test plan (Reference 4) over the surface of the outer glass to aid heating caused the glass to heat much too rapidly. The silicon carbide powder was removed with a vacuum cleaner, which left a small residue, for the actual test.

Figure 32 page 59 shows the upper surface lamp layout and also the location of the four control thermocouples (C1, C2, C3, C4) and the two fairing thermocouples ( $F_1$  and  $F_2$ ). The deflection and rotation measurement locations for Test No. 3 are shown on pages 33 through 37.

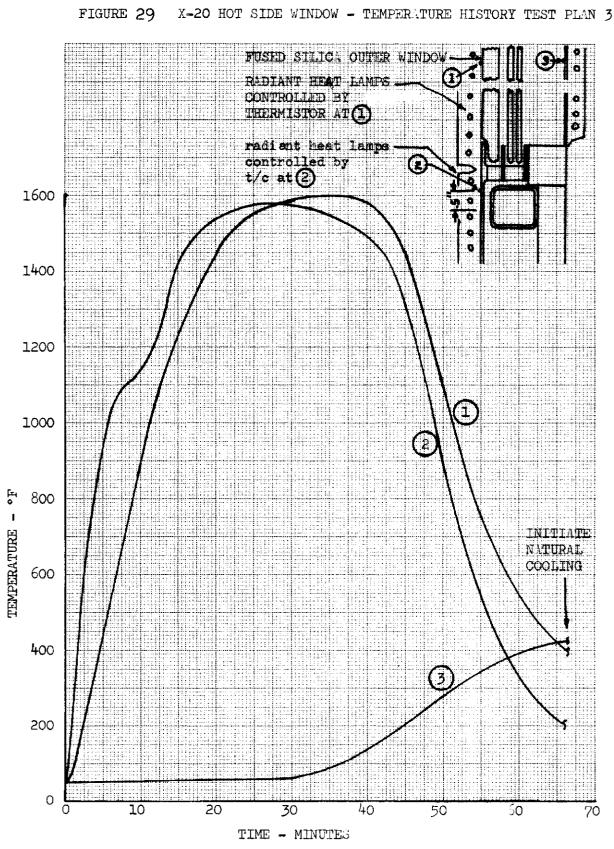
The electrical power applied to the lamps in each control area was determined by the Structures Test Branch (FDTT) Heat Rate Computer which matches the actual temperature of the control thermocouple or thermistor with the desired temperature as programmed on a magnetic drum and adjusts heat lamp voltages accordingly.

### 4.3.2 TEST CONDITION 3 RESULTS

Two efficiency tests were conducted on the test specimen to check out heating set-up. These consisted of applying a constant voltage to all heat lamps and recording temperatures from all the thermocouples and thermistors and all deflections. This data is on file at the Structures Branch FDTT of the Air Force Flight Dynamics Laboratory.

Included in the data under Serial No. 206 are the temperatures and deflections recorded during a run which lasted 80 seconds and was then aborted when the ignitrons malfunctioned. The plotted data for this rapid rate heating is on file as noted above. Following this run the specimen was inspected and no damage was observed.

The final test was terminated after 380 seconds when it was observed that the top glass had broken. From the data it appears the break occurred after 352 seconds. A photograph of the failed glass is shown on page 61. An accurate drawing of the failed glass is shown on page 63. The test set-up after the glass failure is shown on page 62. Only the top glass failed and no apparent damage was sustained by the rest of the test specimen.



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4.3.2 TEST CONDITION 3 RESULTS (Continued)

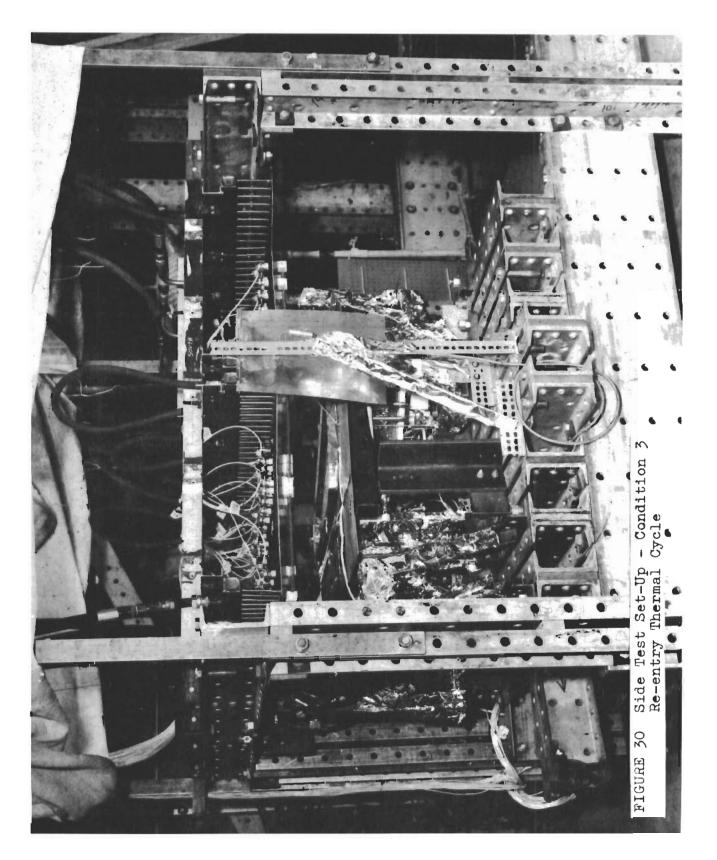
The heat lamps in the control zone directly over the glass and controlled by Thermistor No. 1 did not come on. This was because sufficient heat was arriving from the area of Control Zone 2 for Heat Control Zone 1 to follow the planned temperature profile. The lower surface lamps heating the aluminum dummy window did not come on since heating was not programmed until later in the cycle.

Results of the final Test Condition 3 are presented in plotted form under Serial No. 207 on pages 65 through 120 Figure 37 page 121 shows the window gap measurements.

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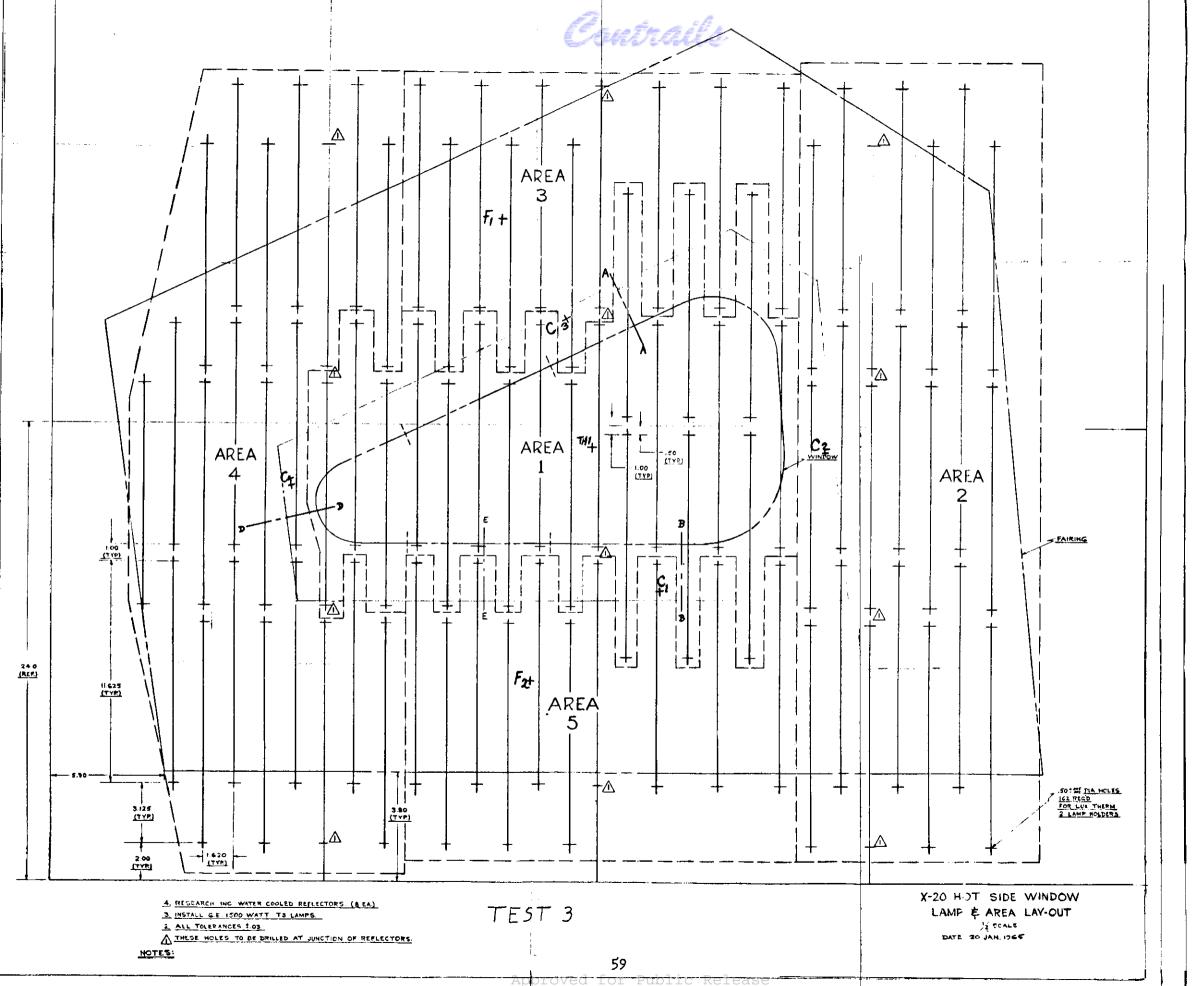


FIGURE 32

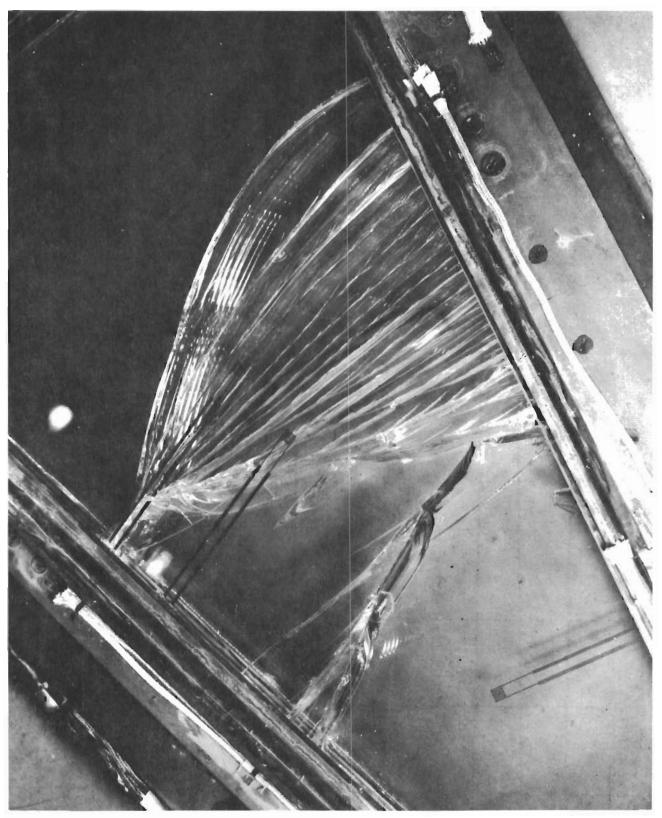
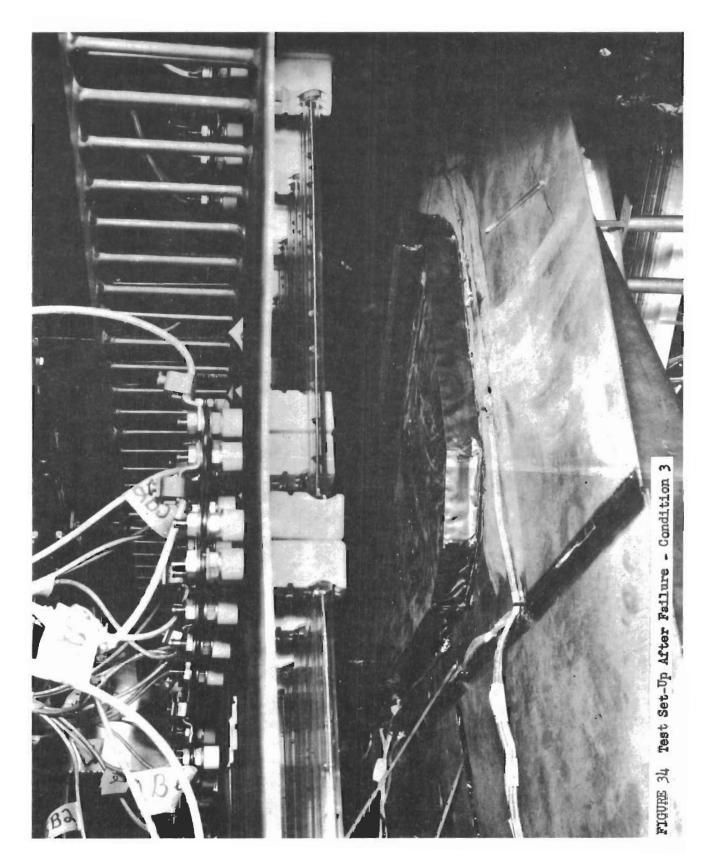
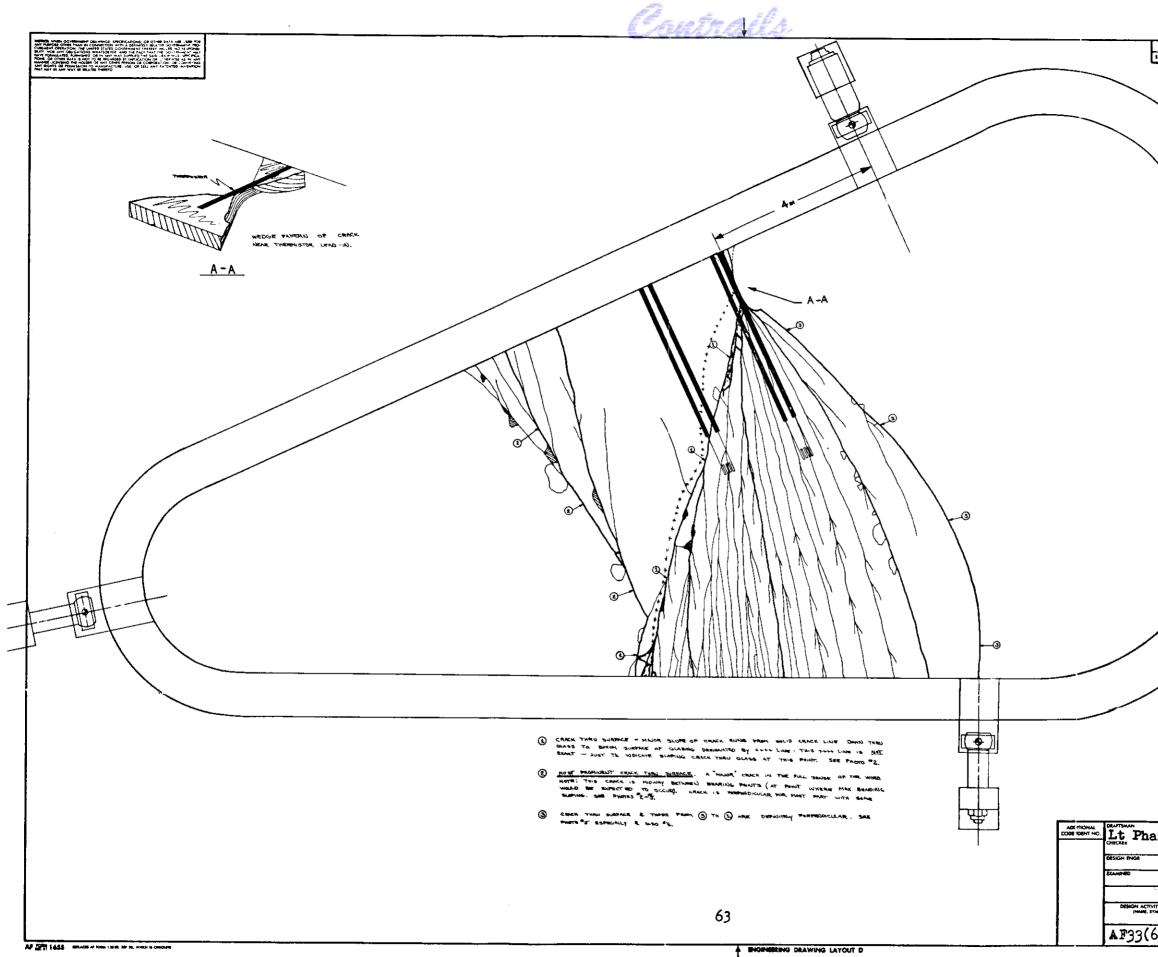


FIGURE 33 Photograph of Window Fracture

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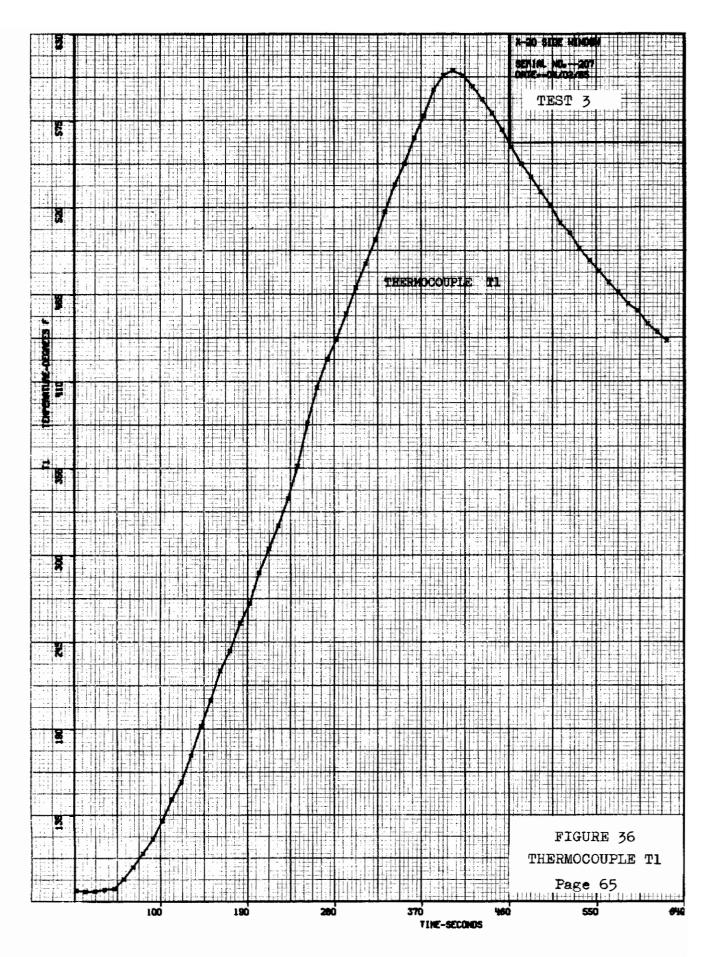




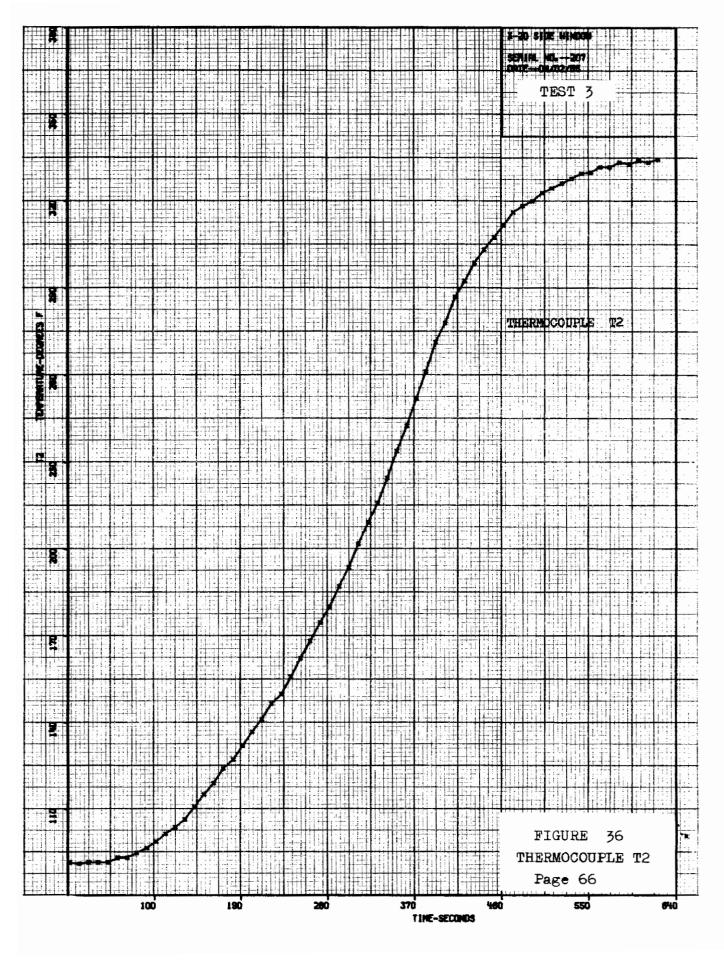
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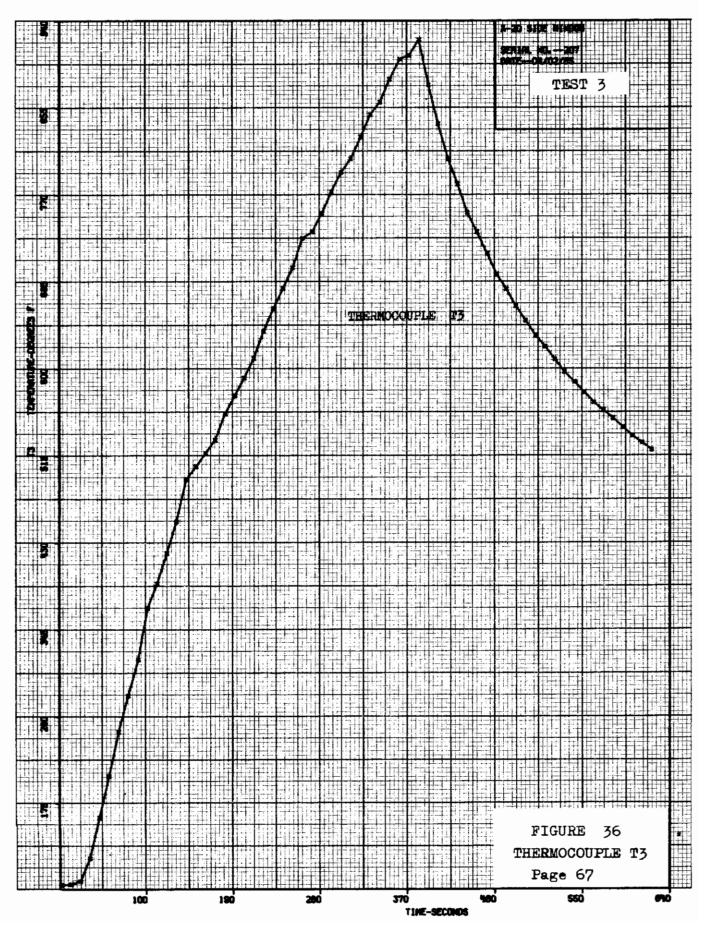
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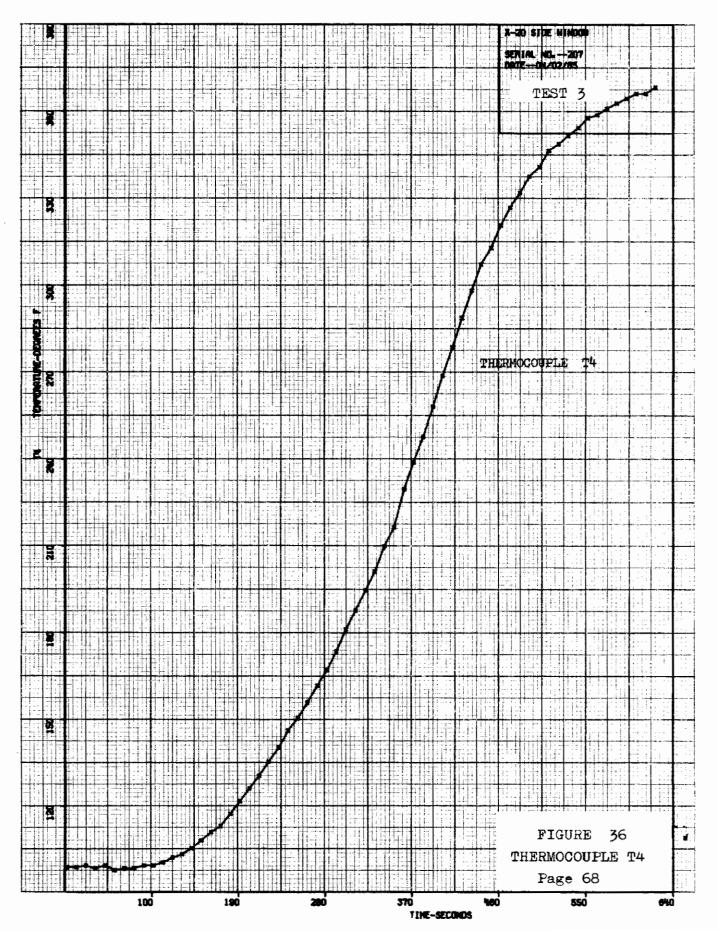
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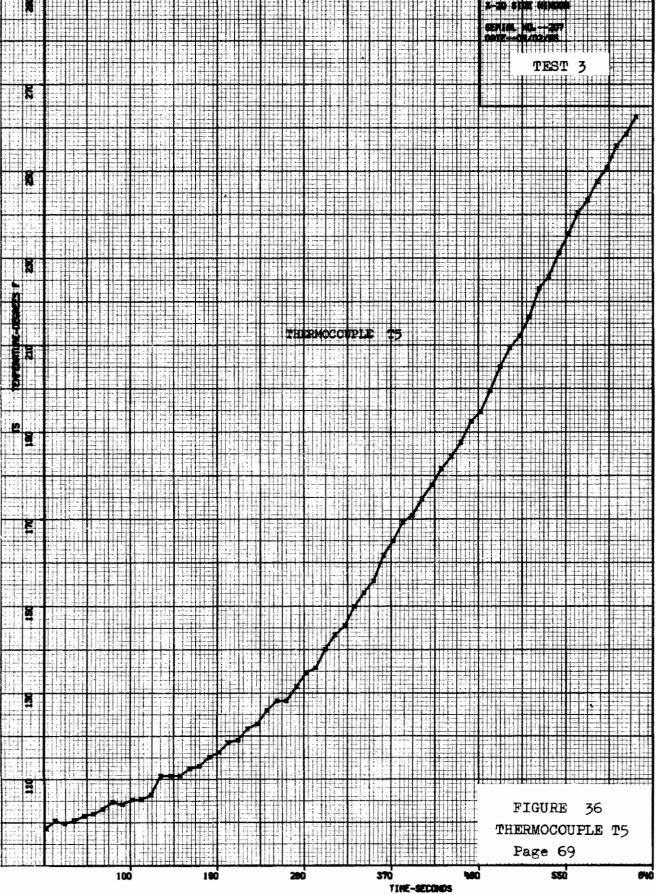
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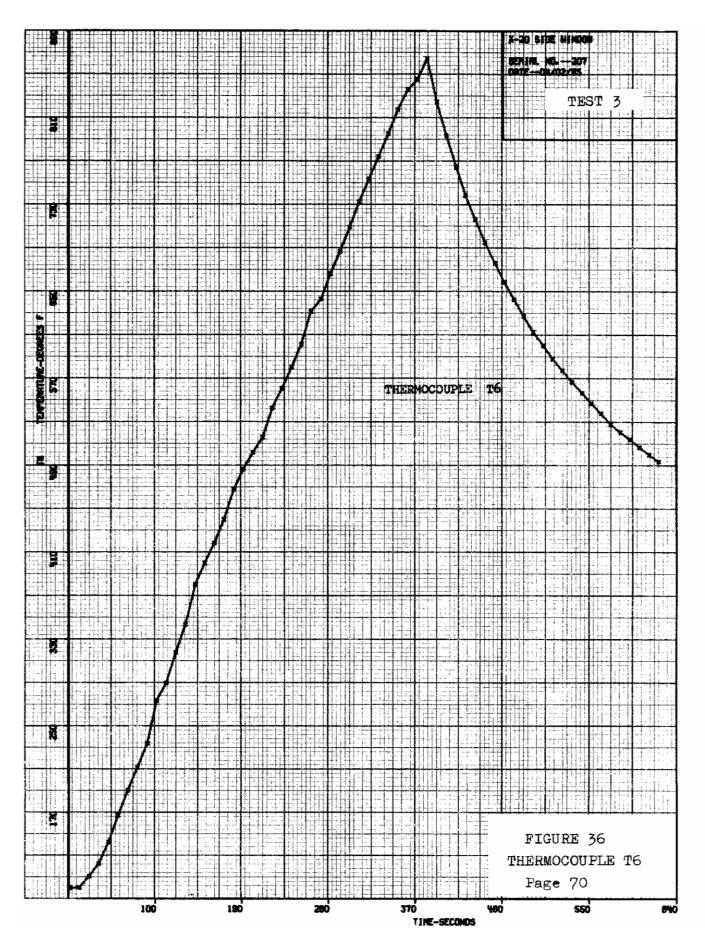
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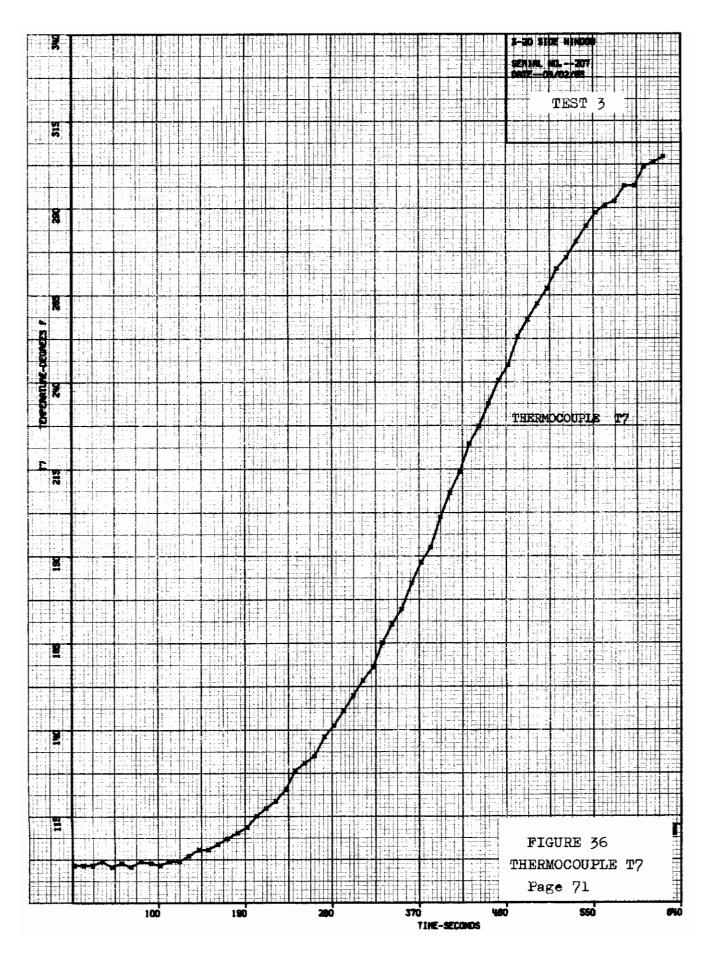
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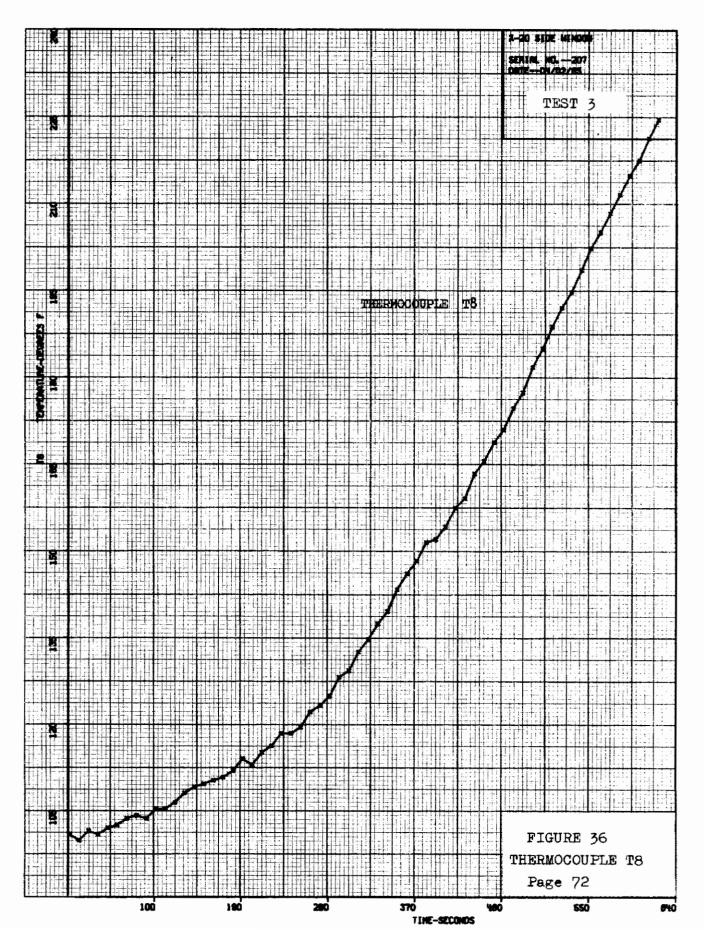
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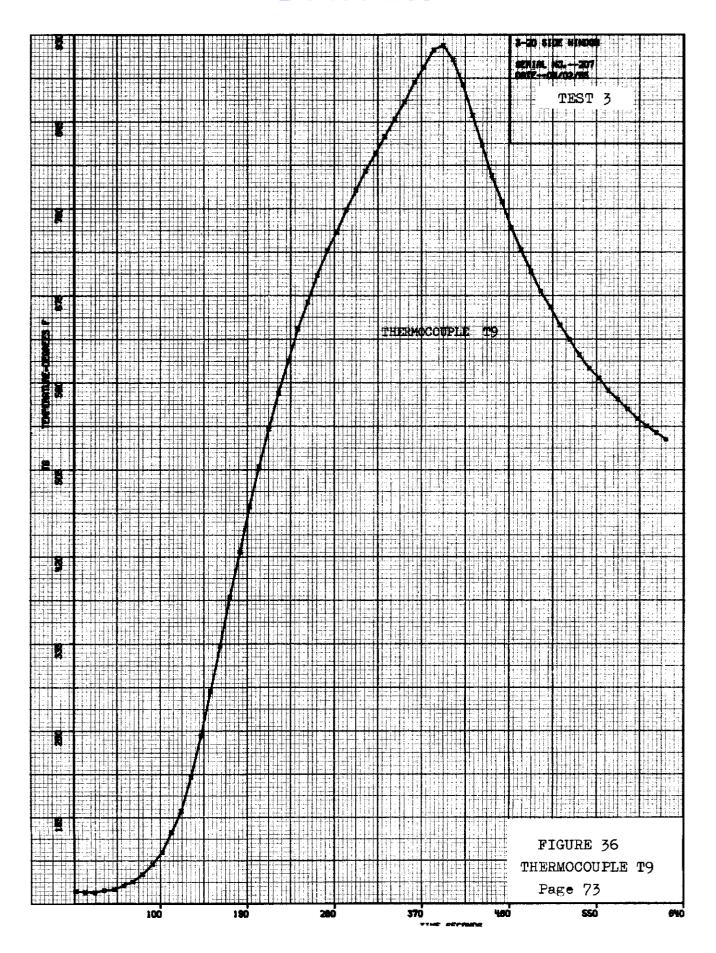
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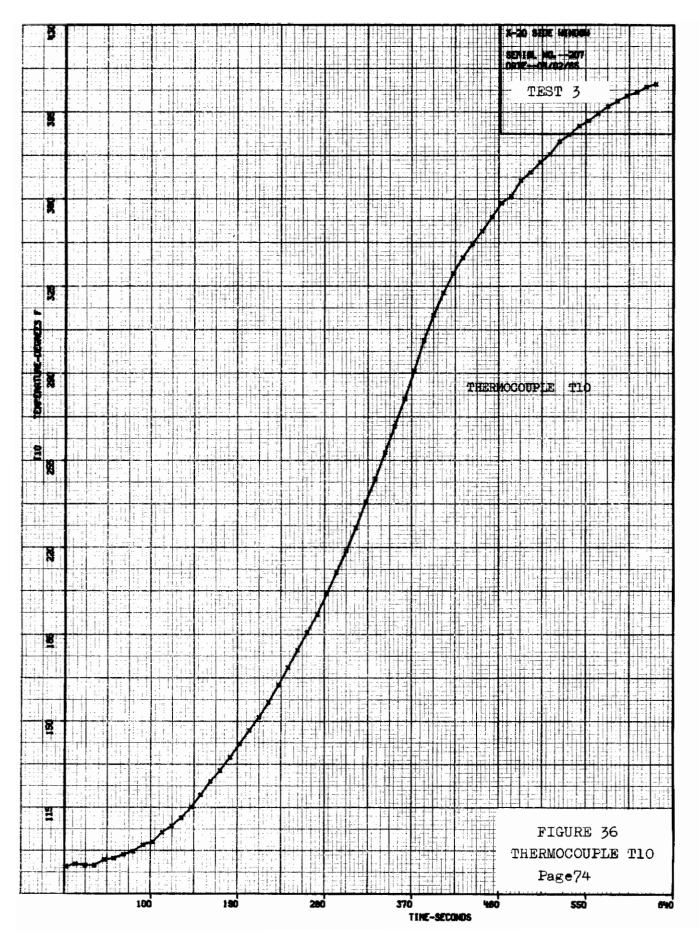
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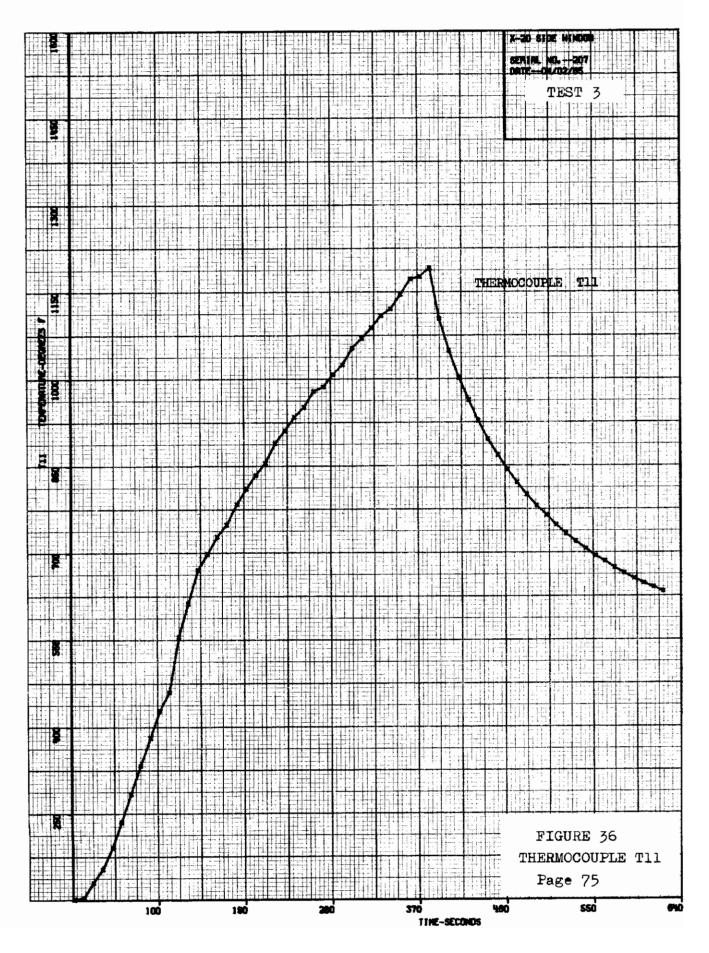
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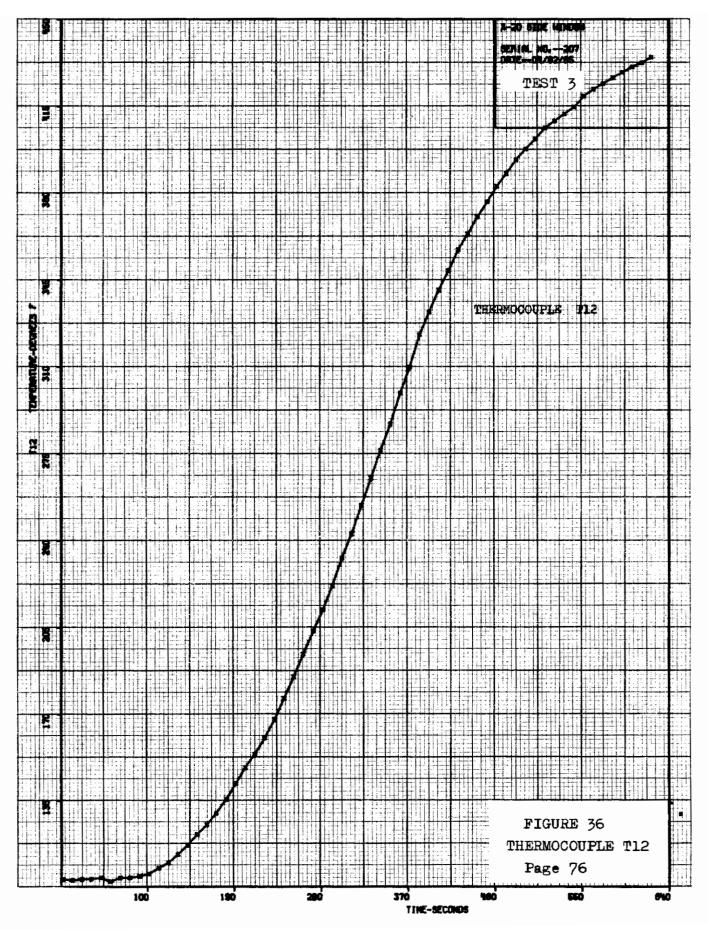
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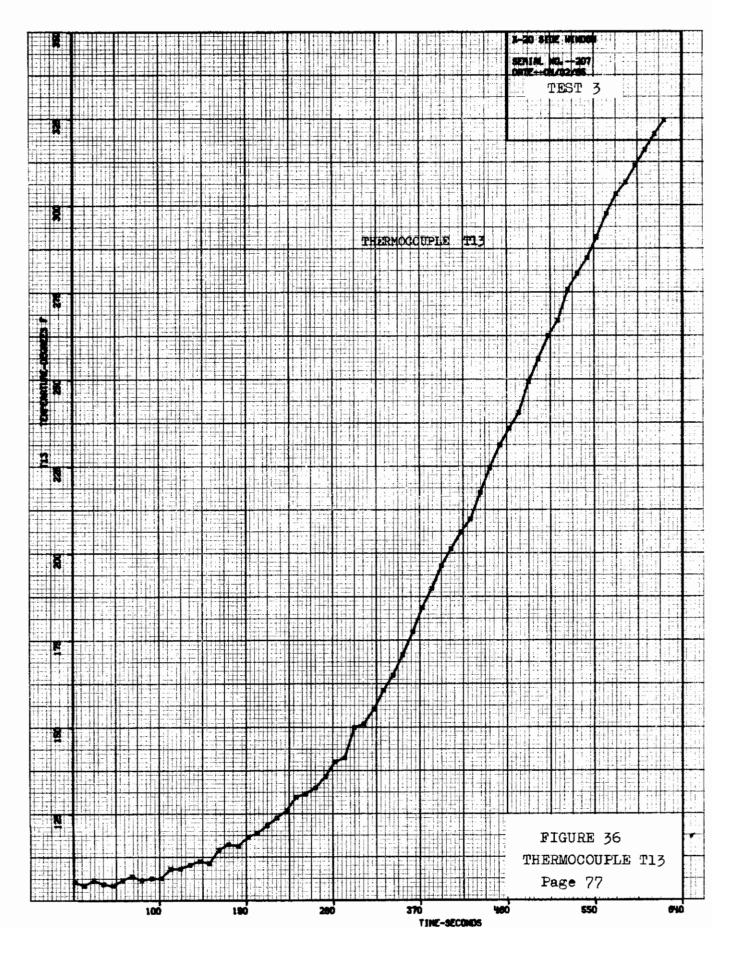
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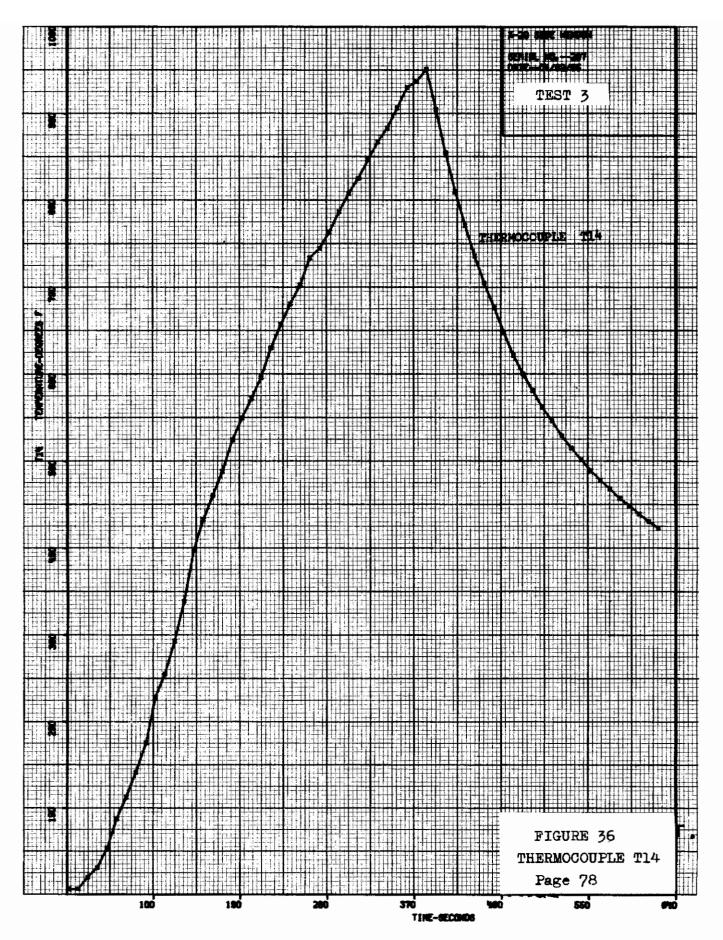
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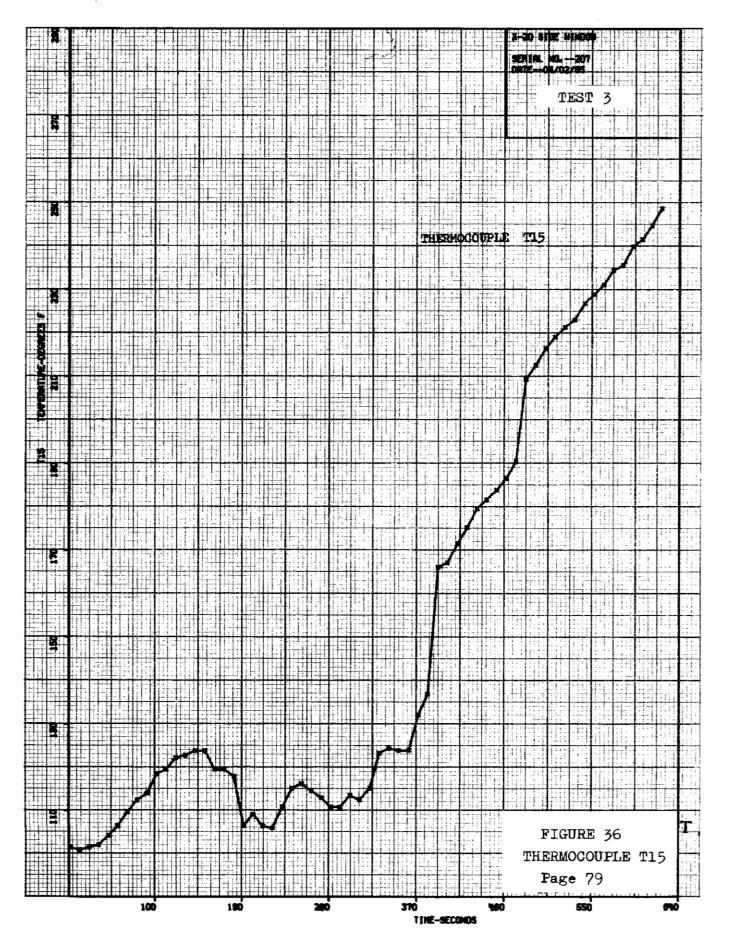
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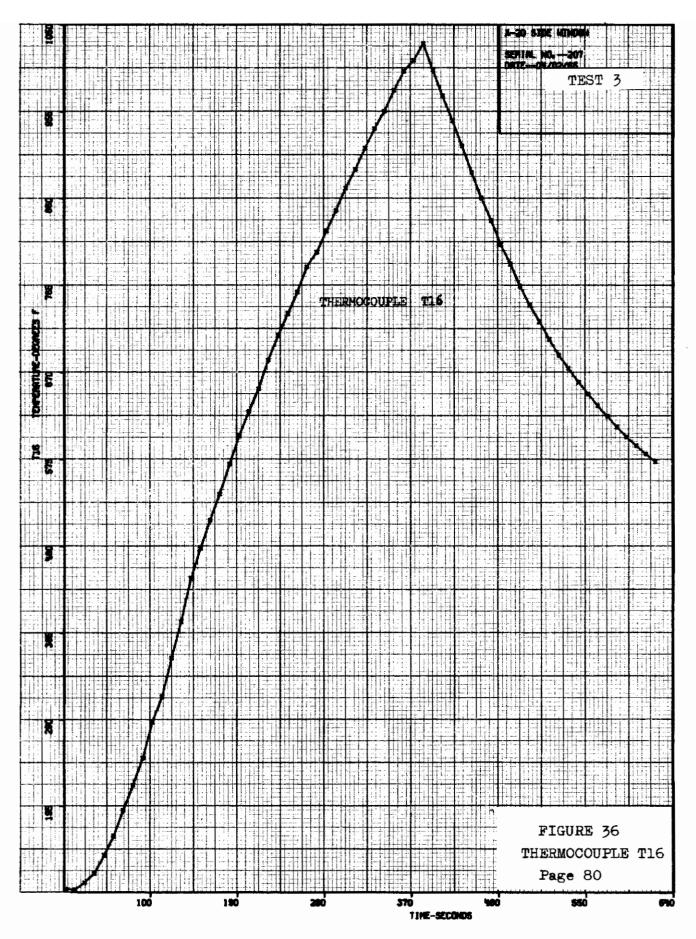
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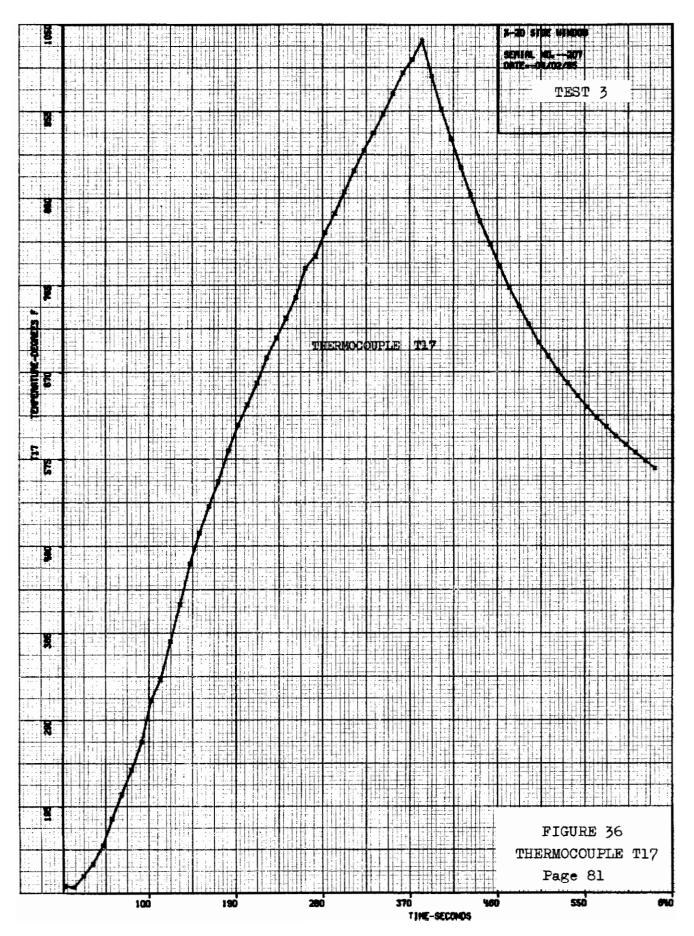
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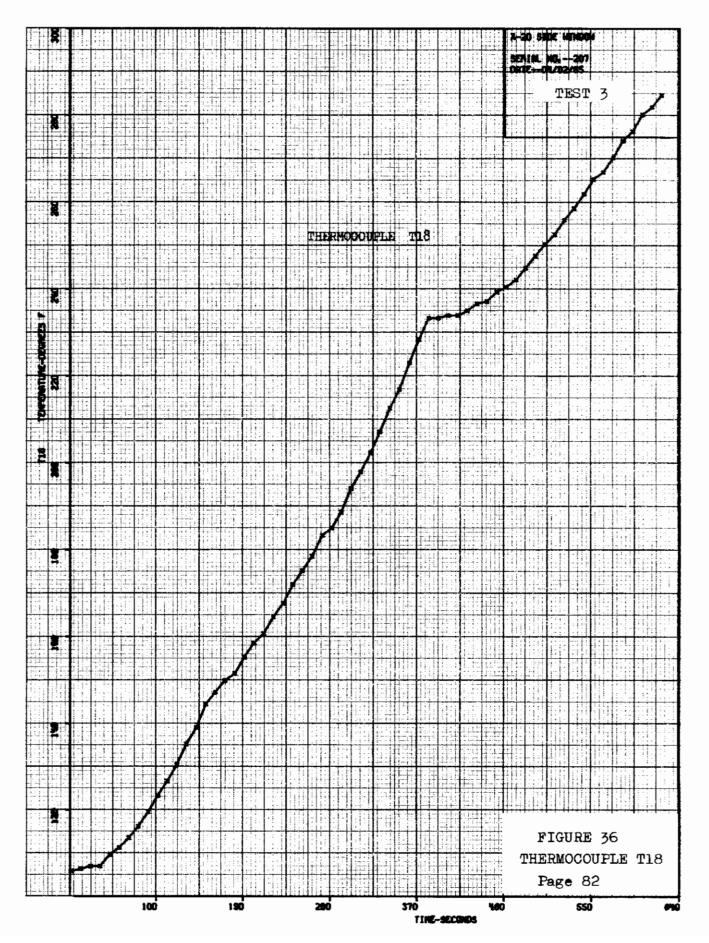
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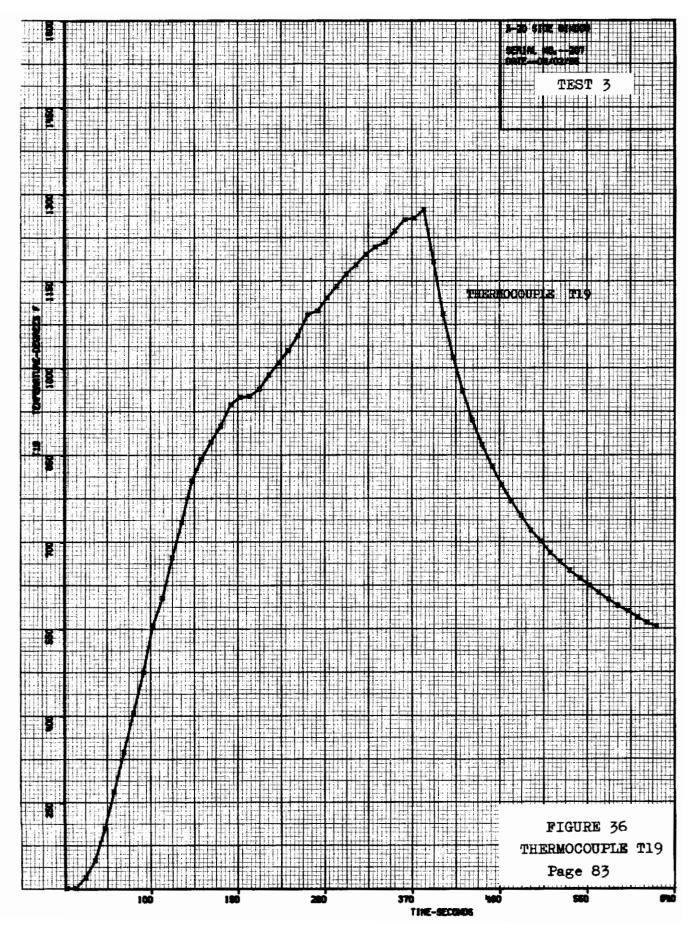


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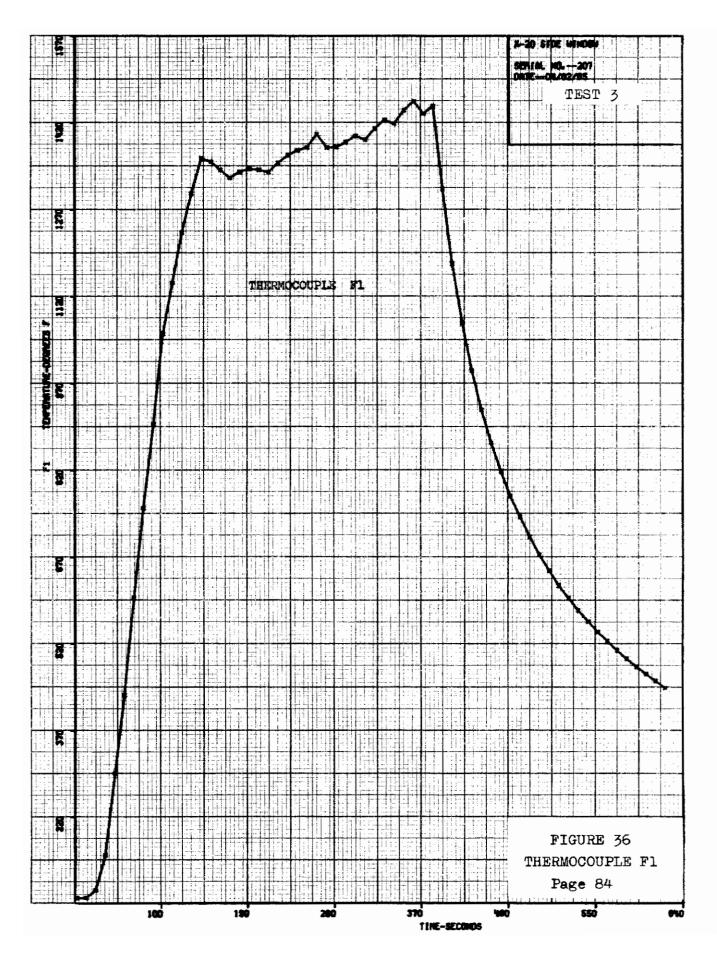


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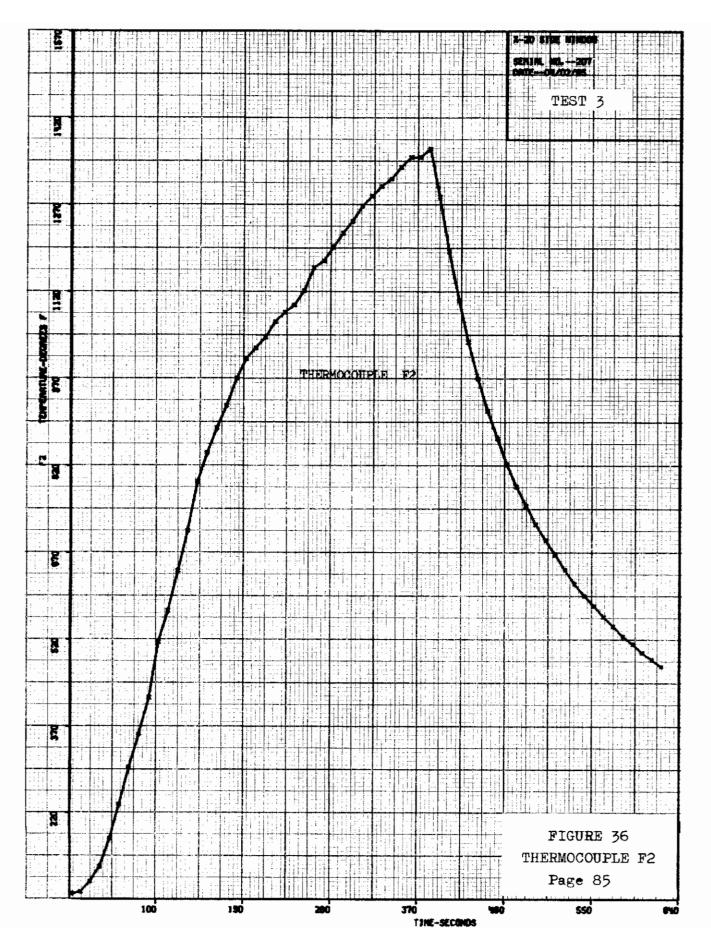
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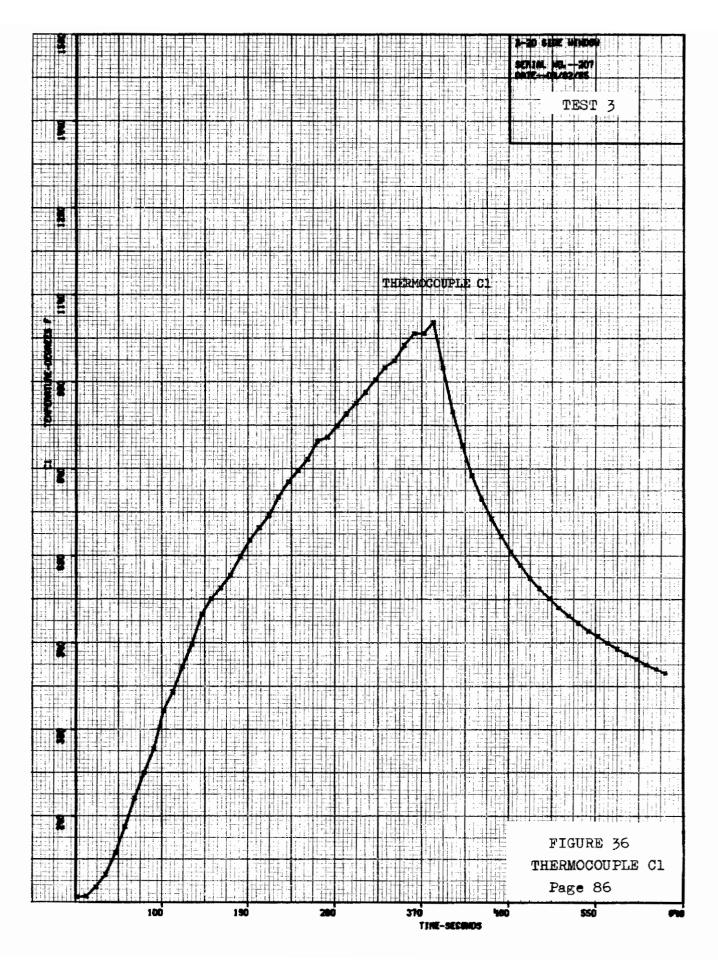
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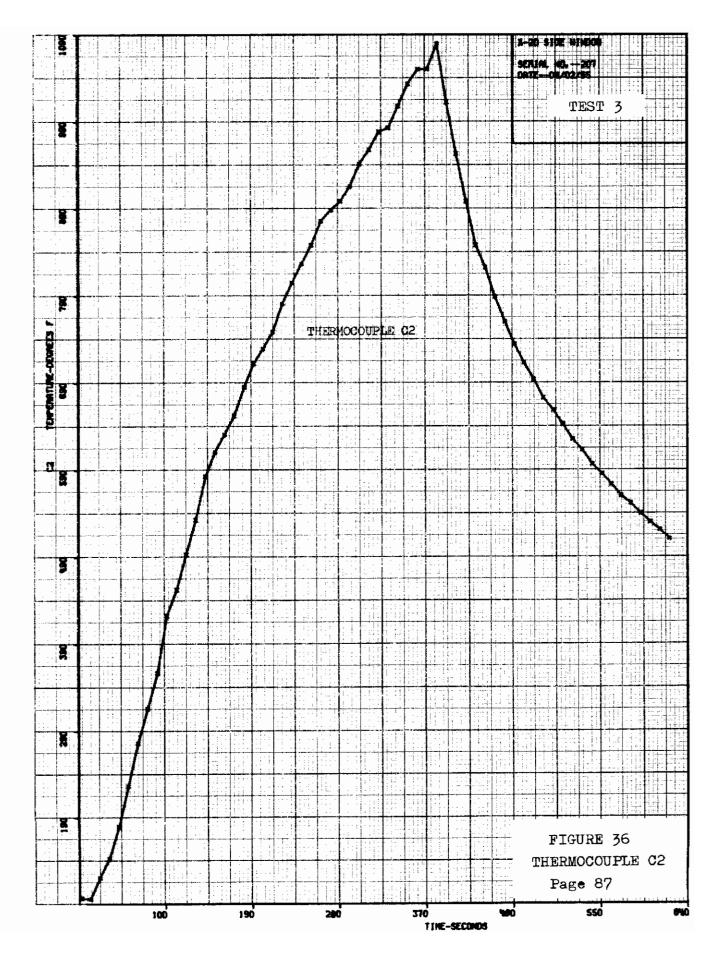
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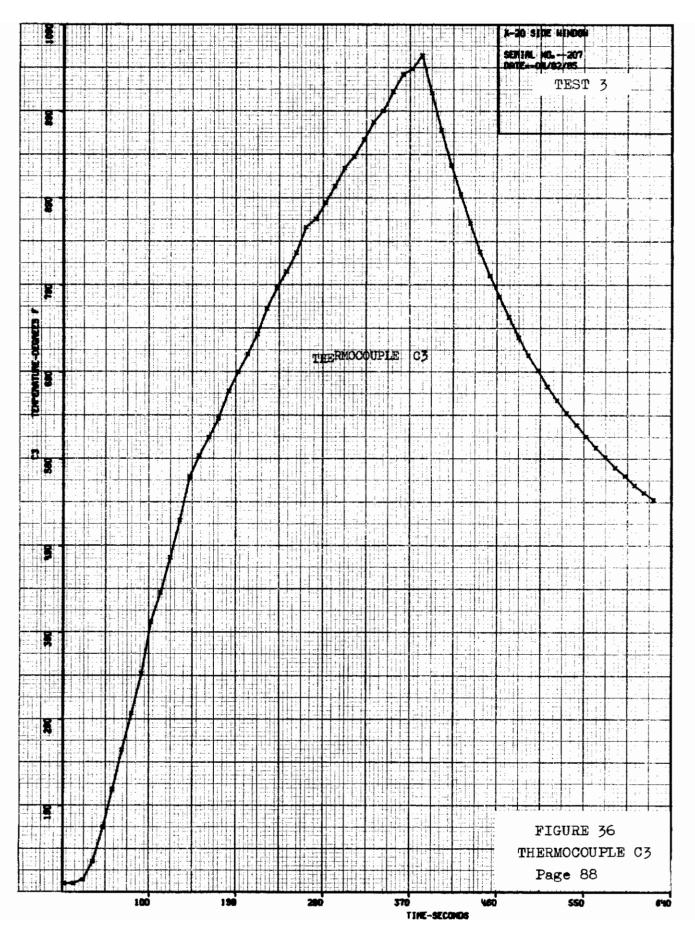
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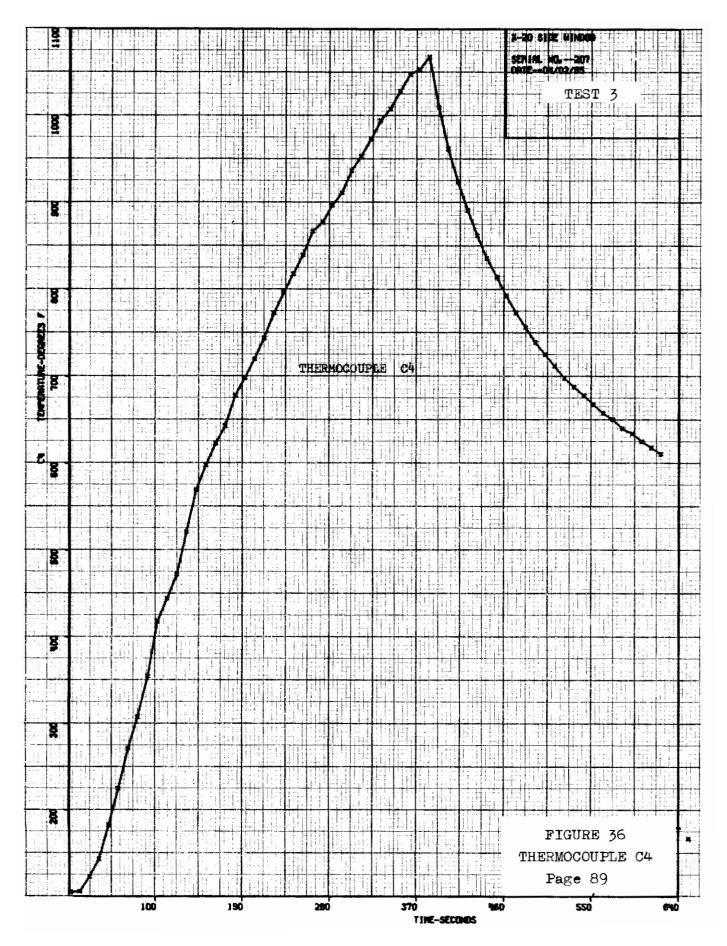
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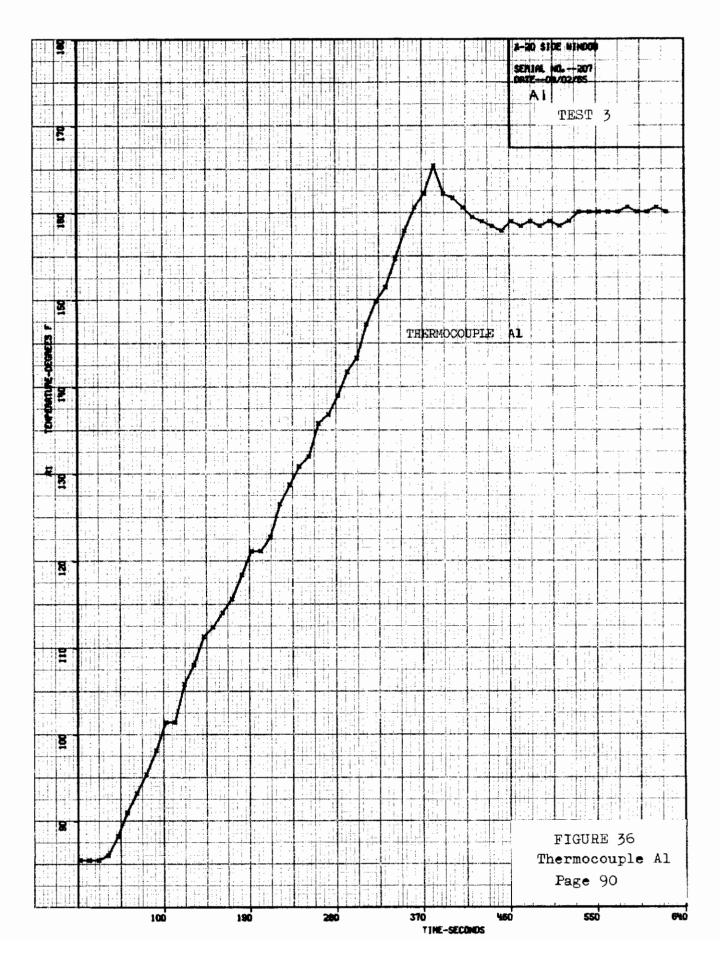
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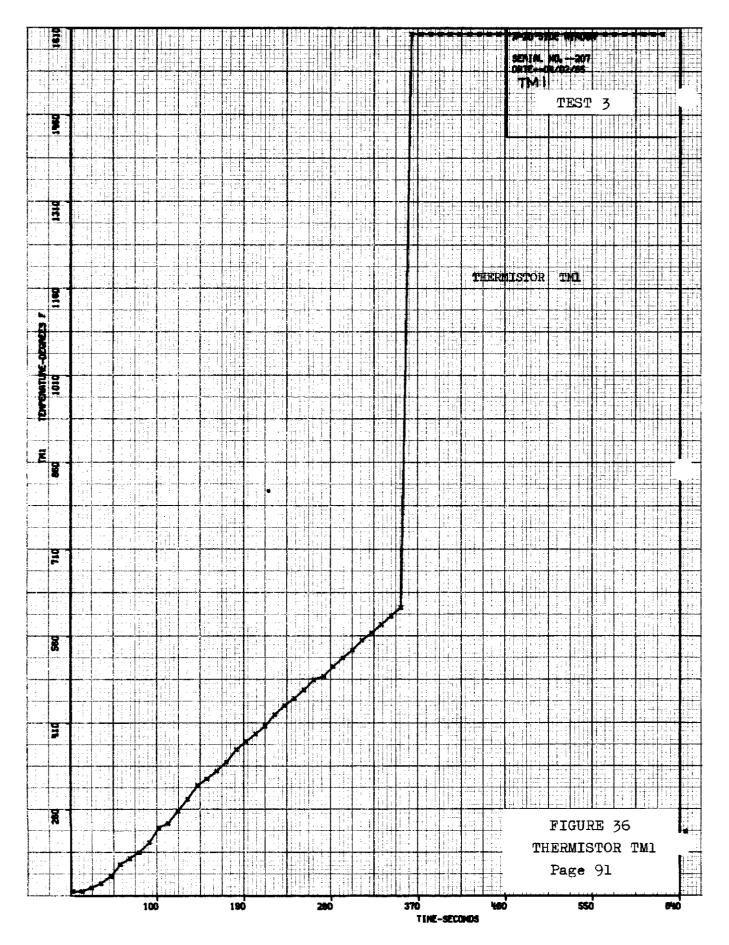
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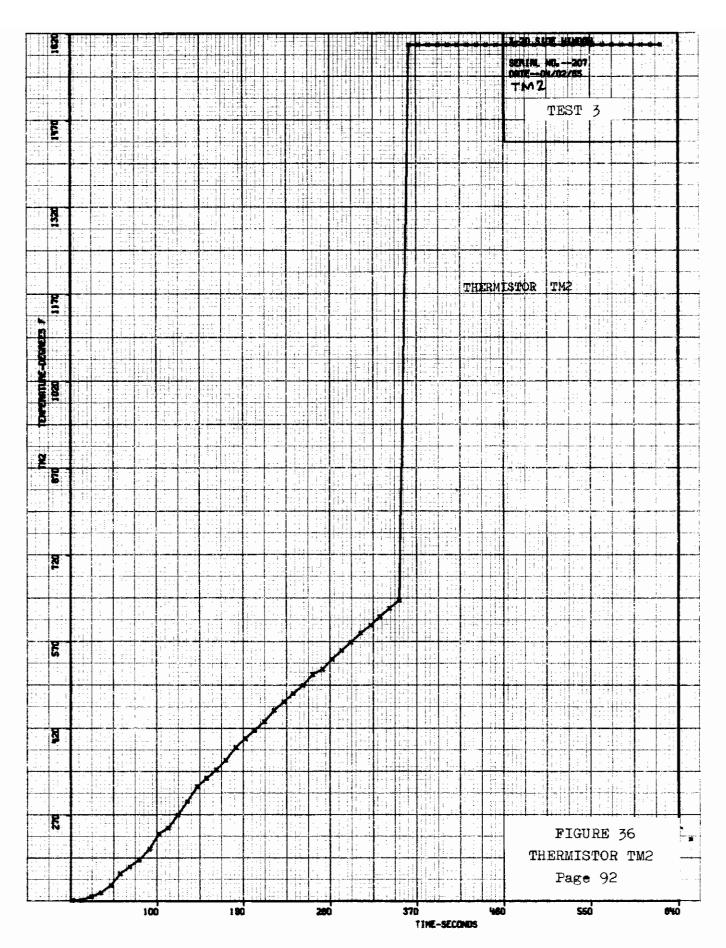
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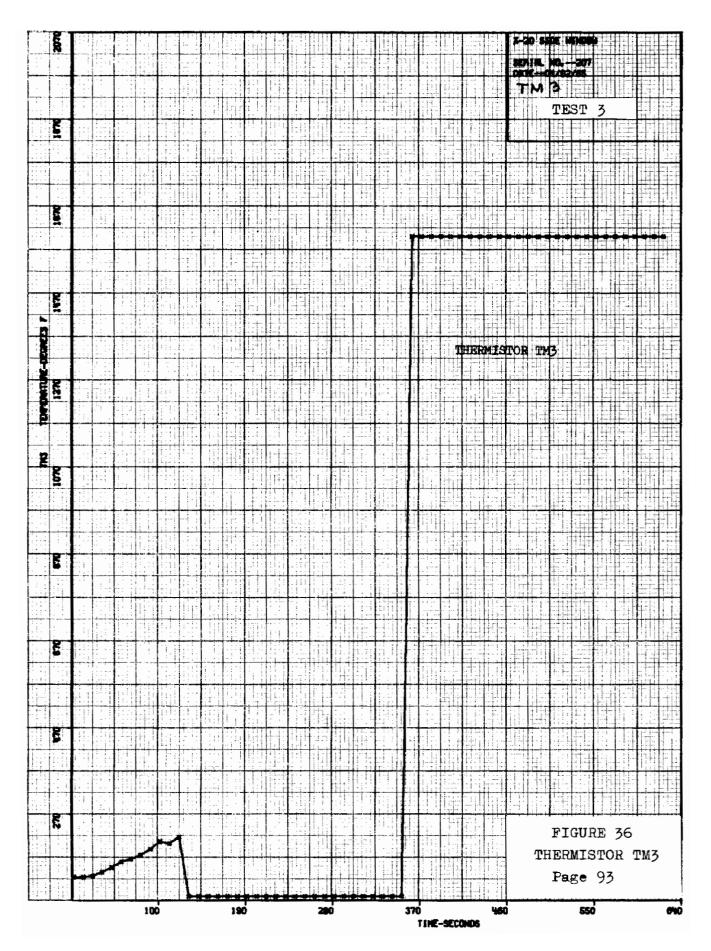
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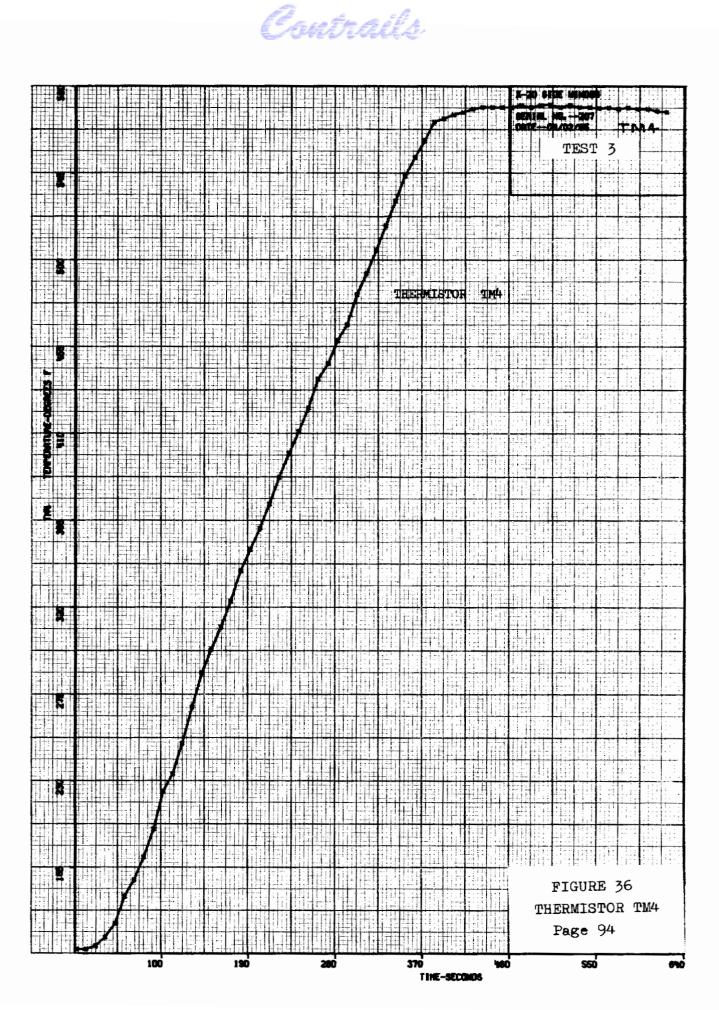


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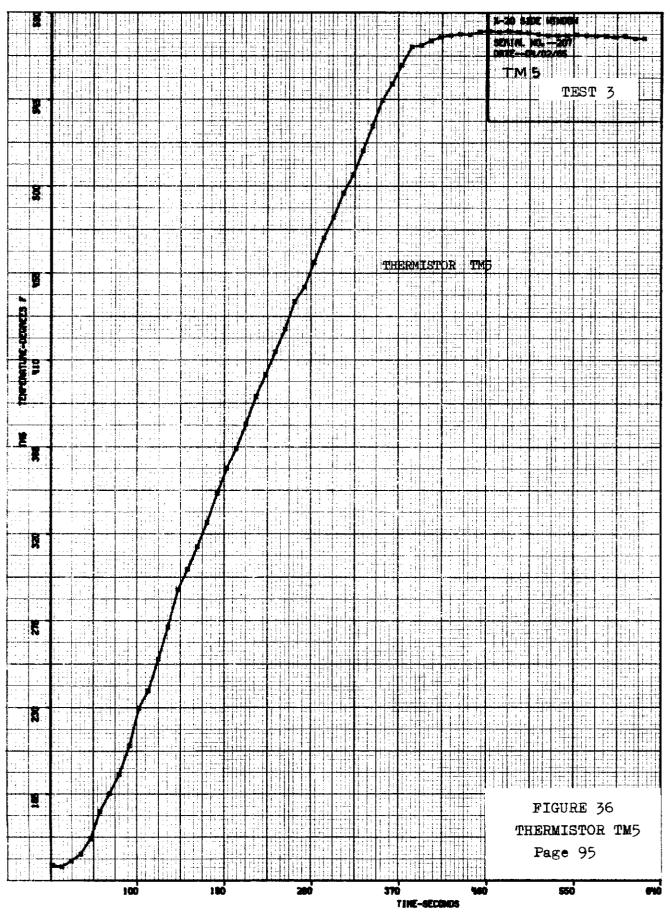


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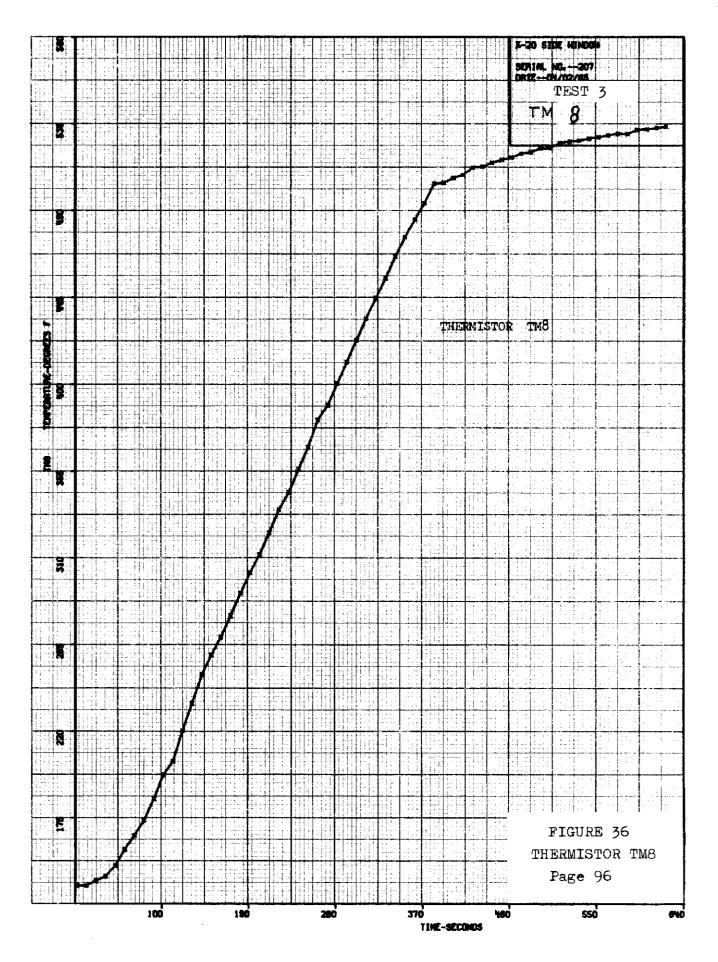




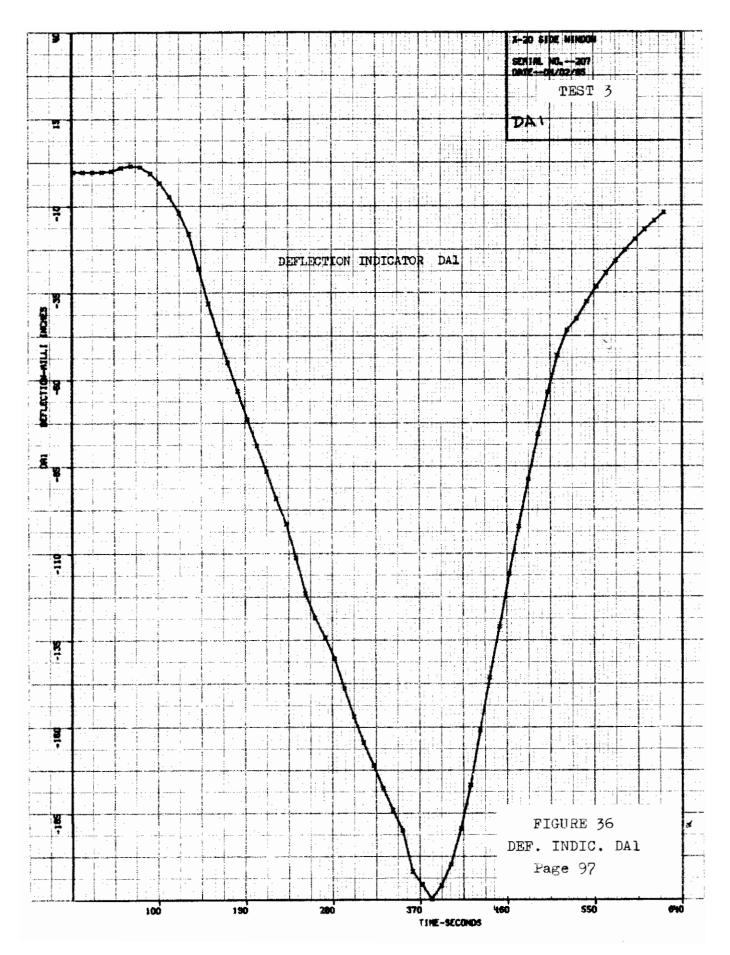
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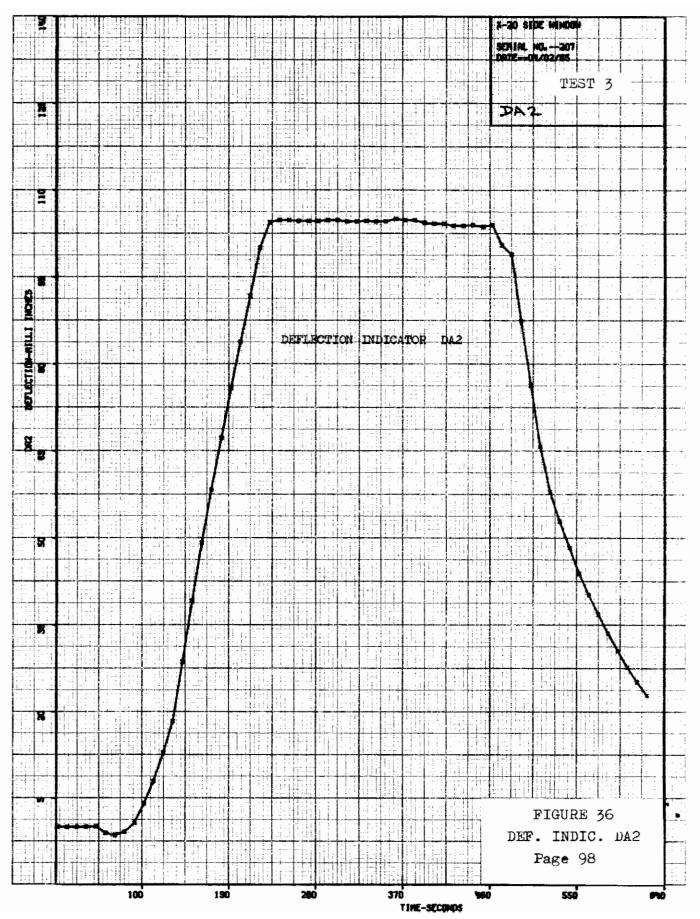
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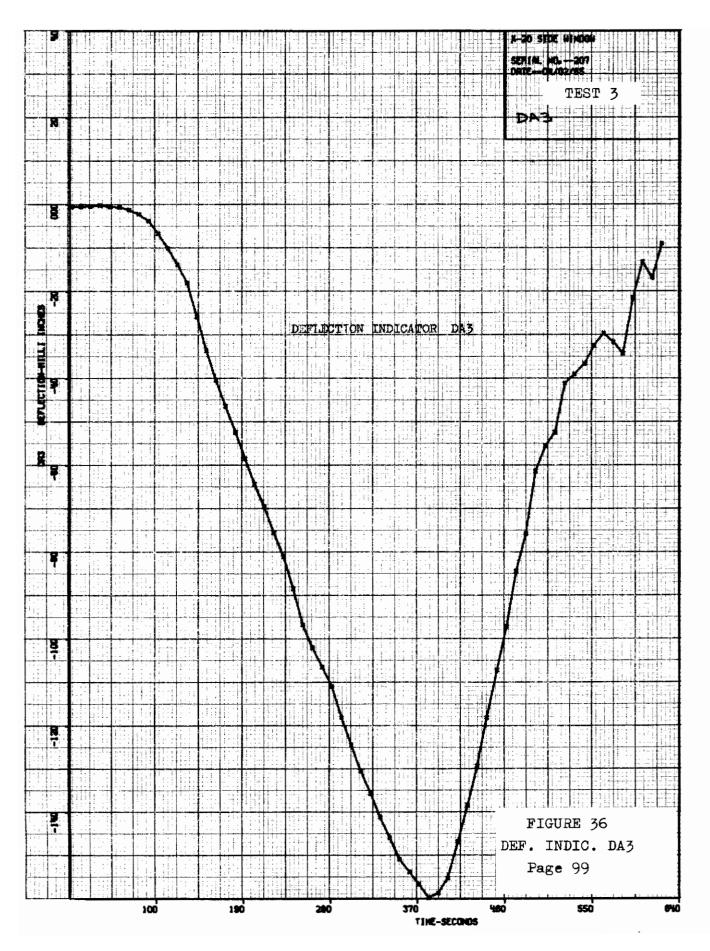
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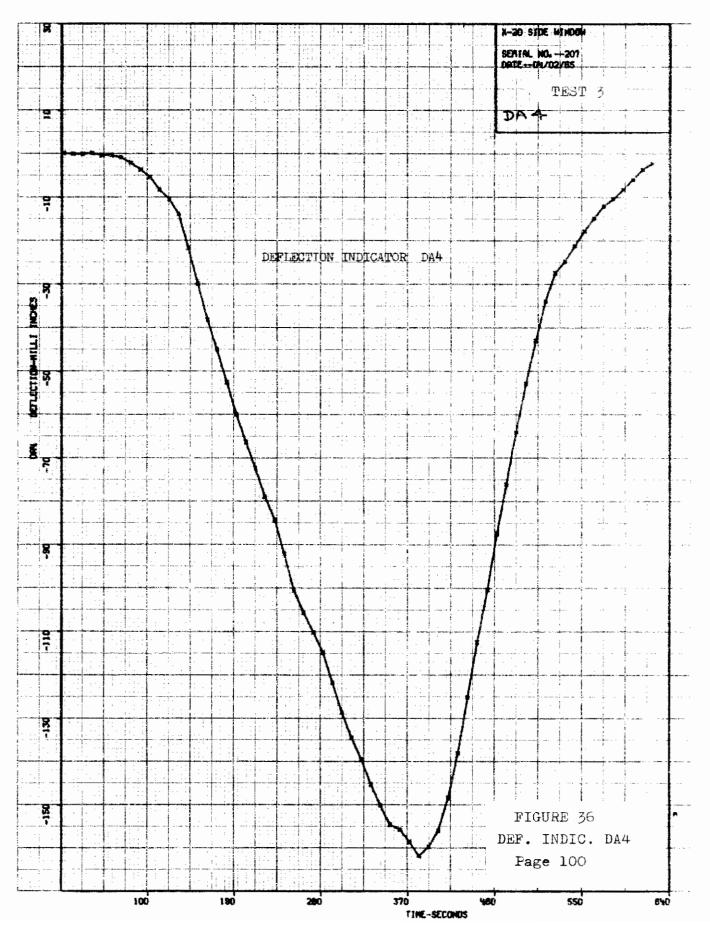
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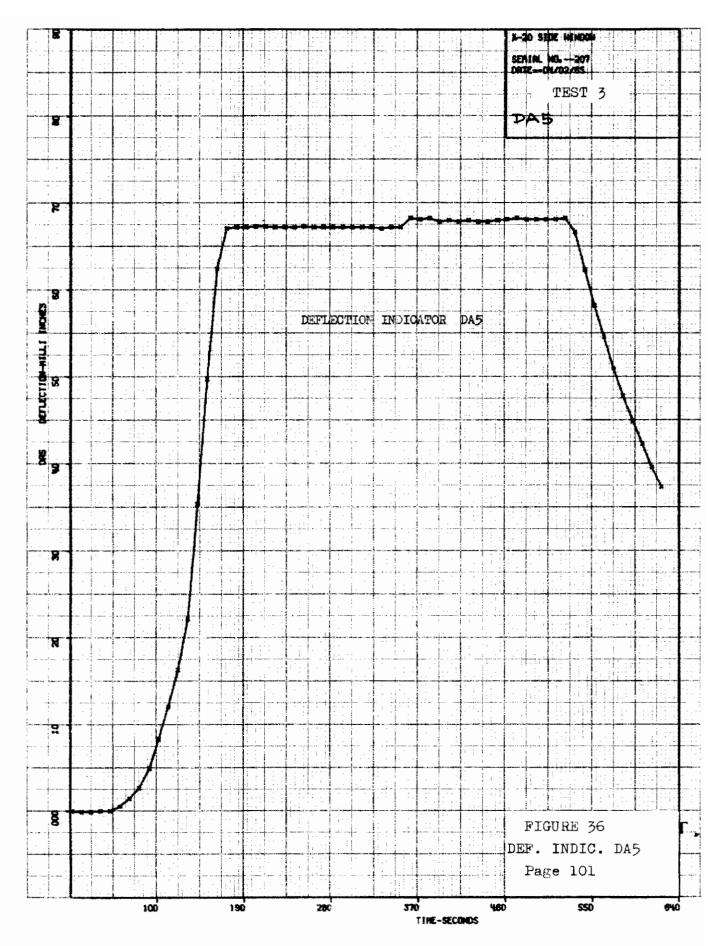
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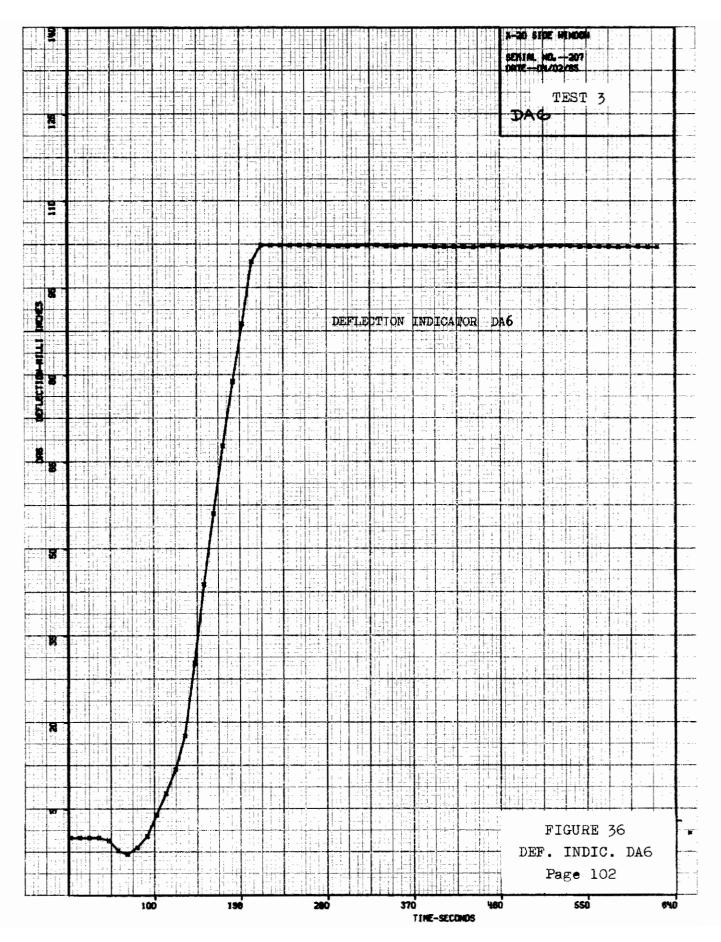
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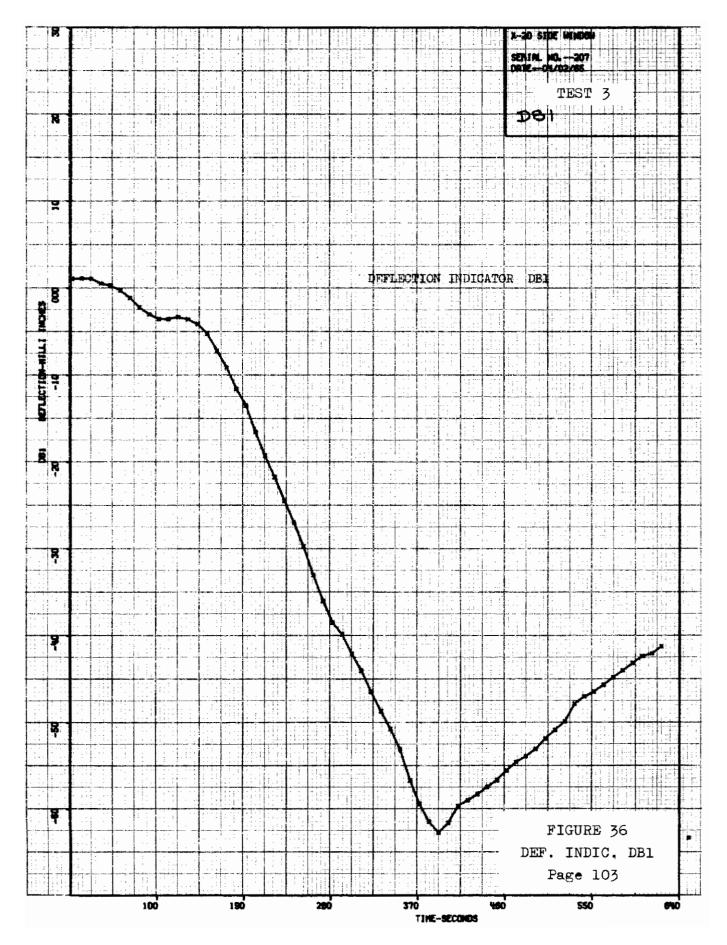
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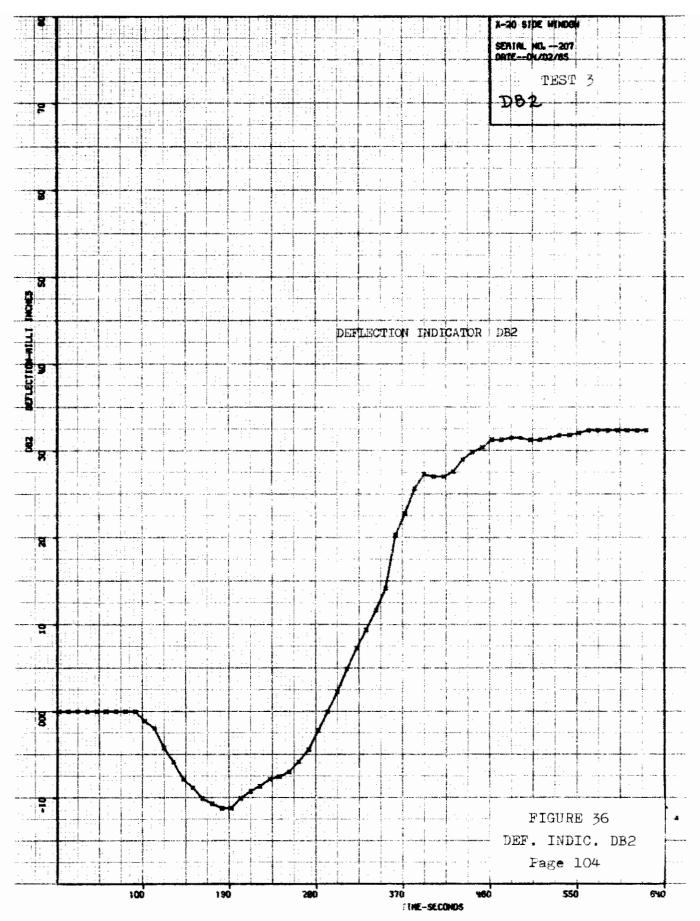
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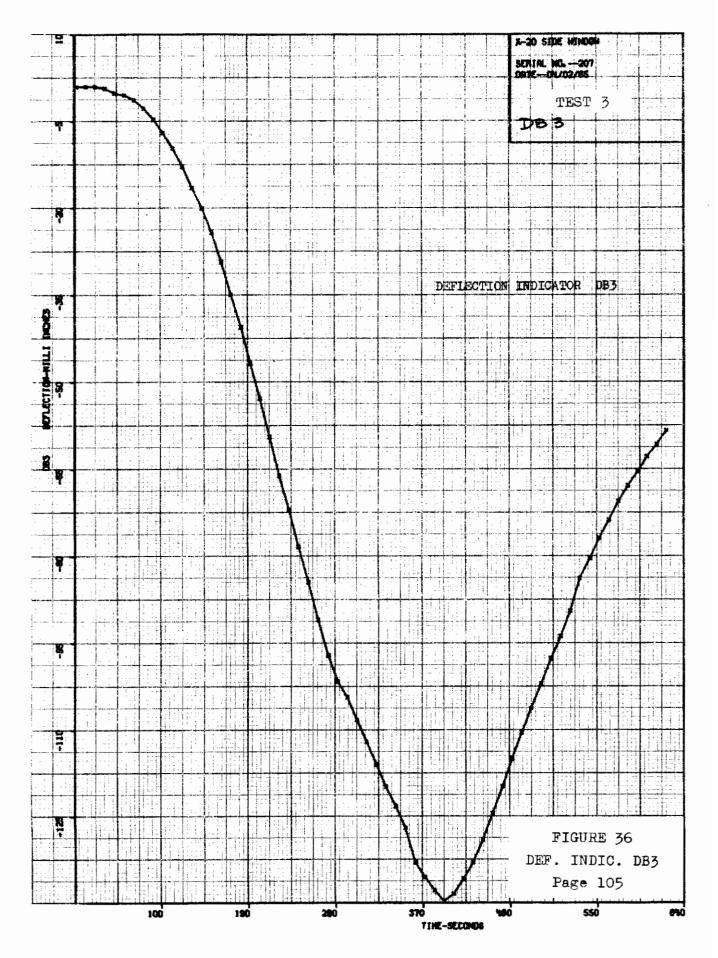
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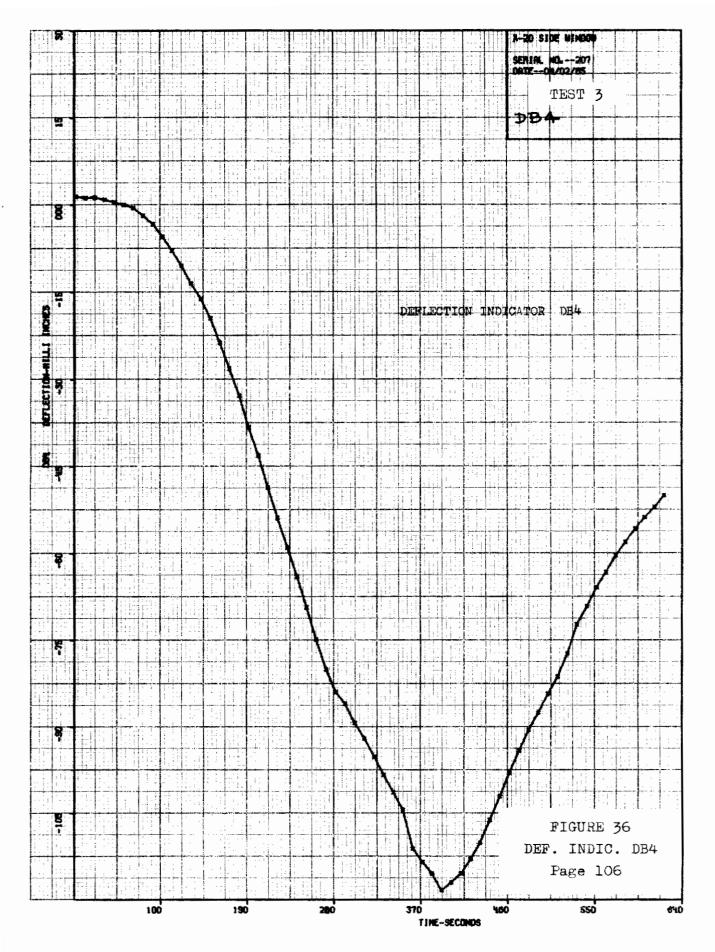
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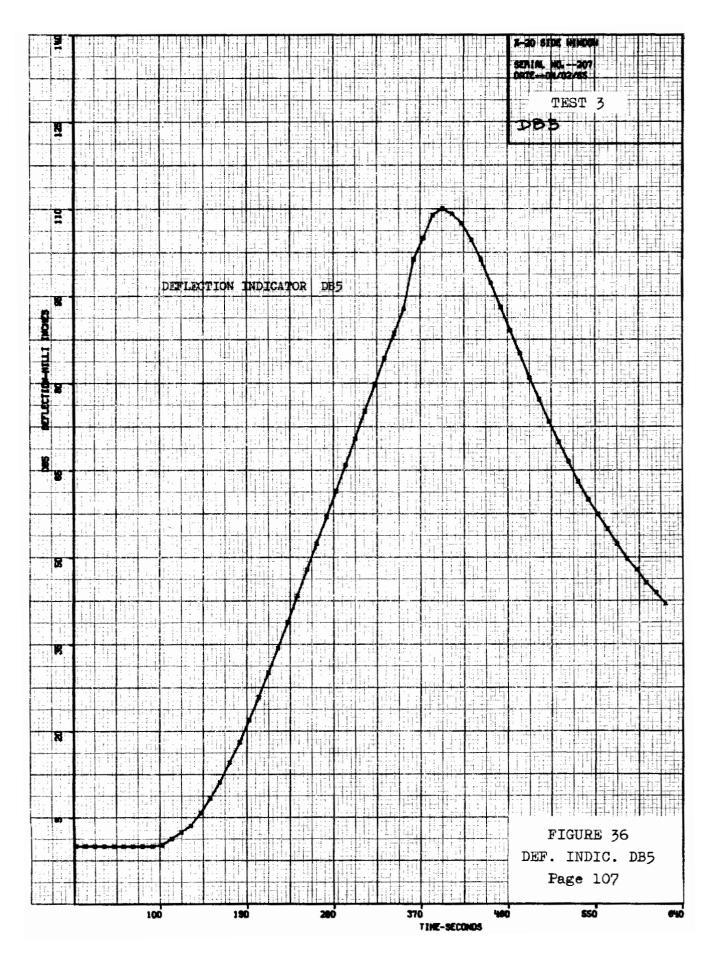
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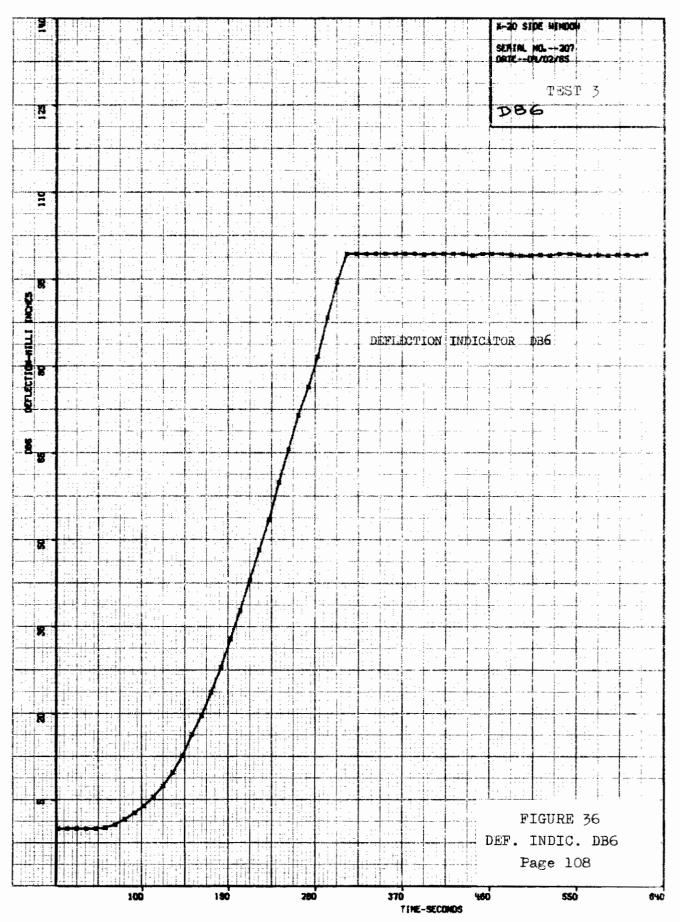
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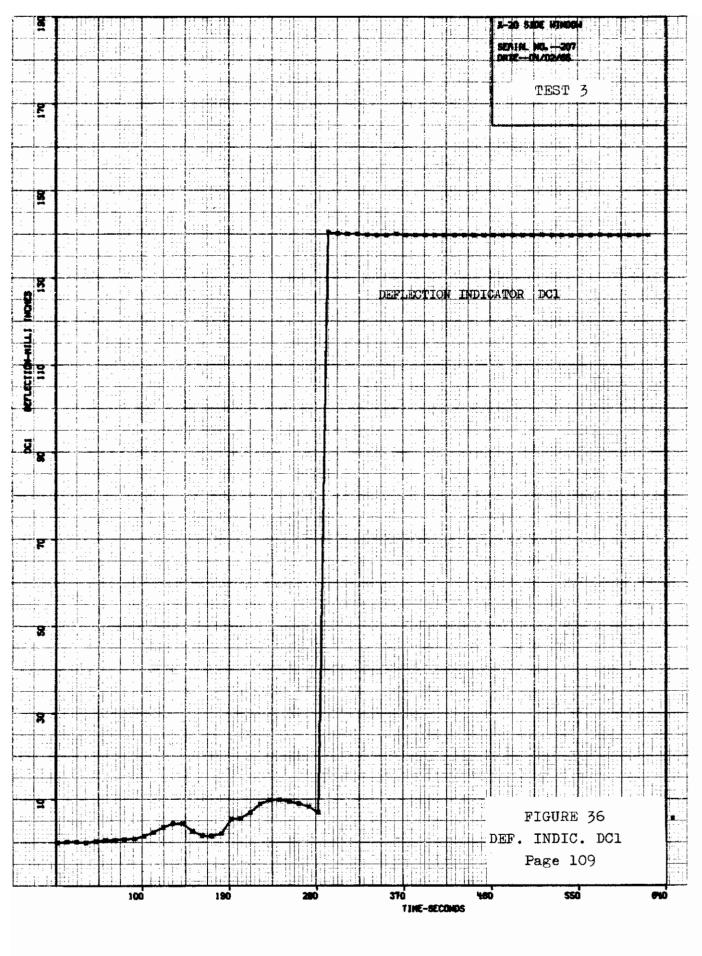
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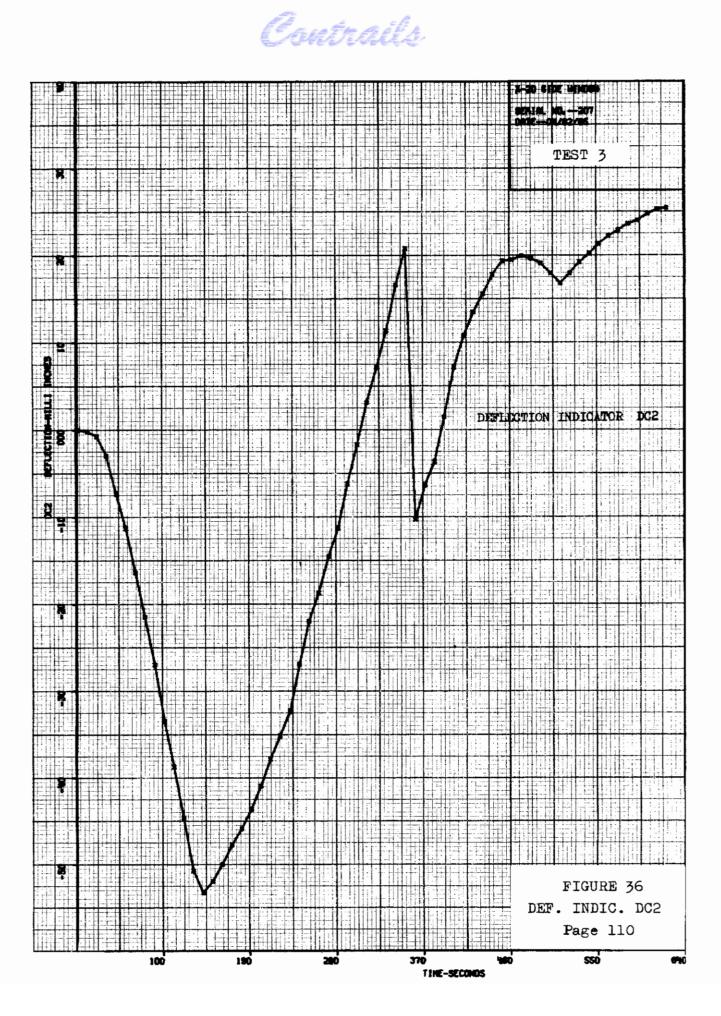


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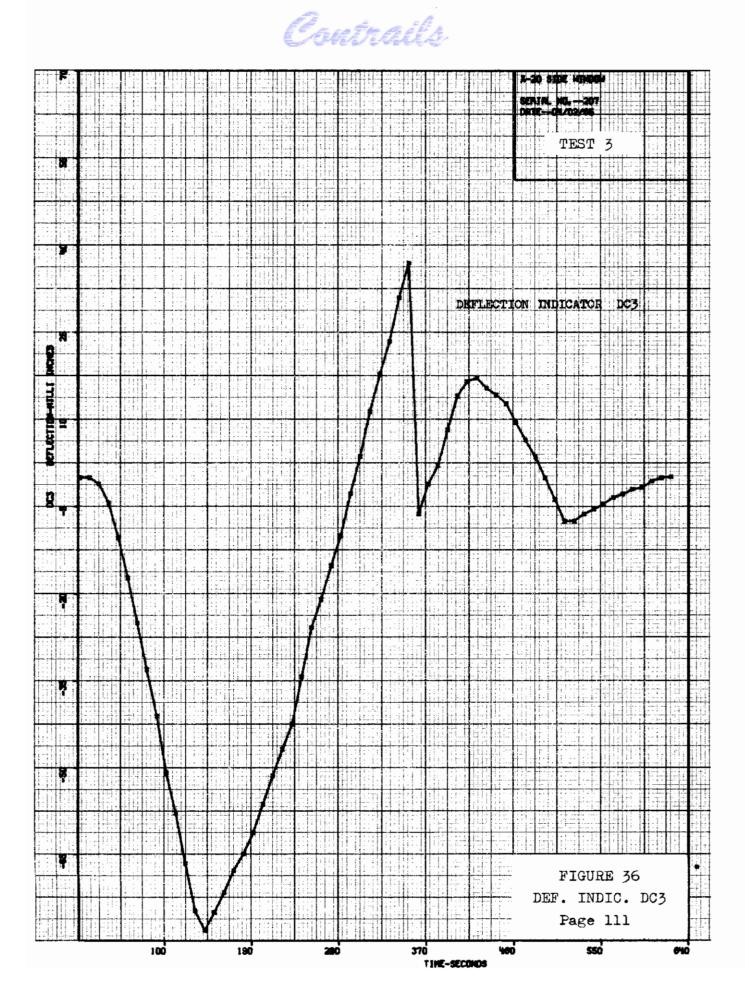


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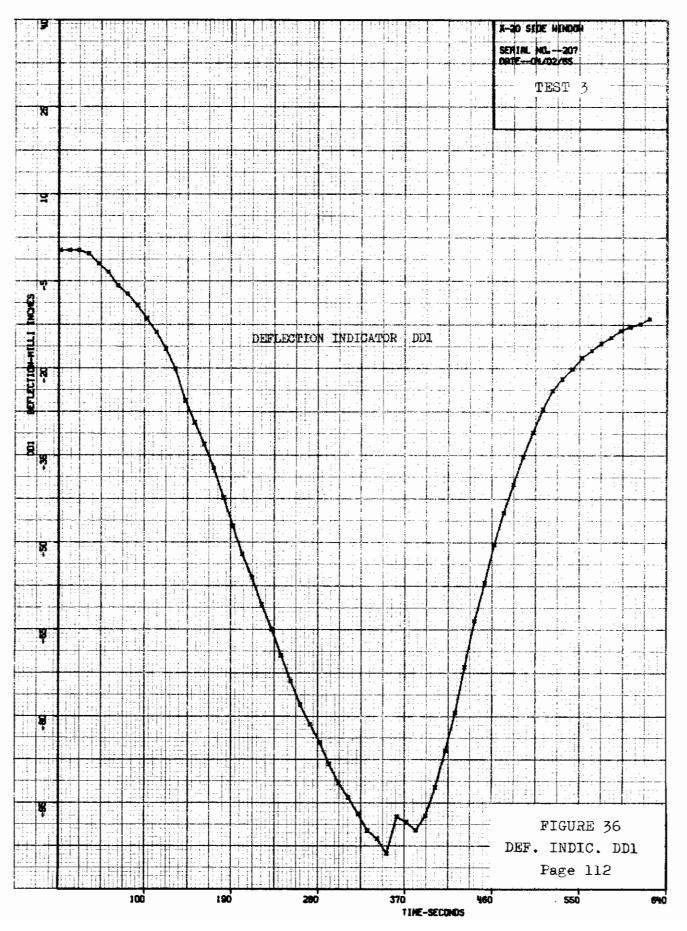




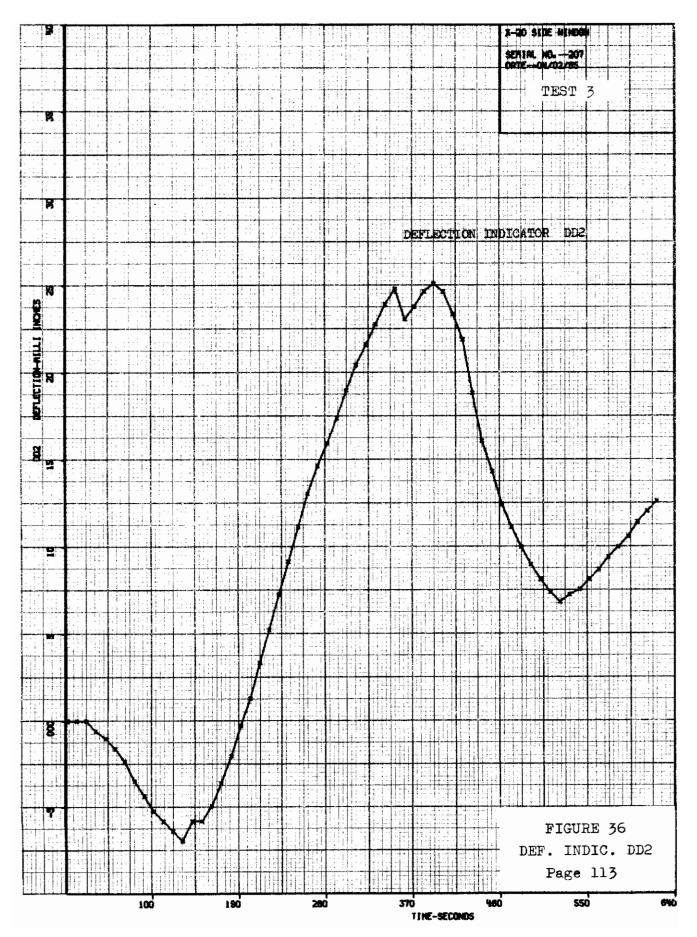
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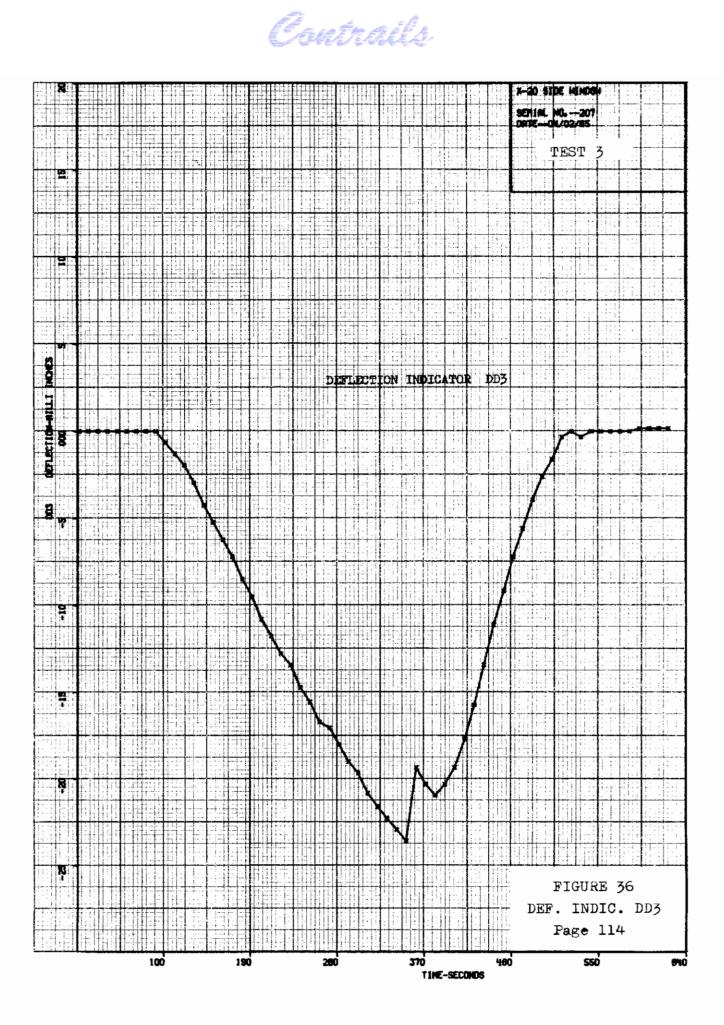


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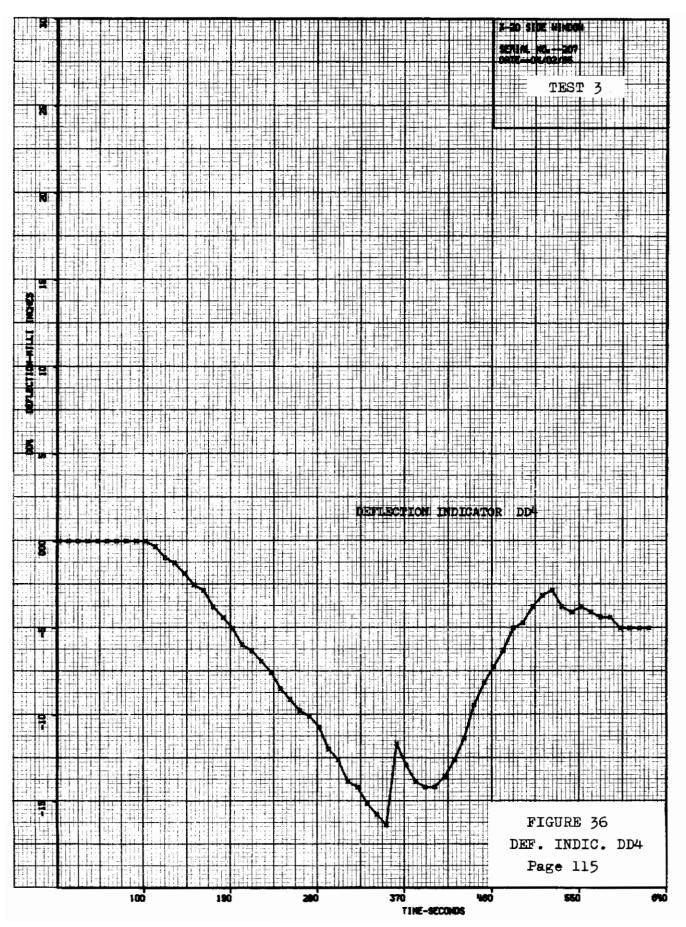


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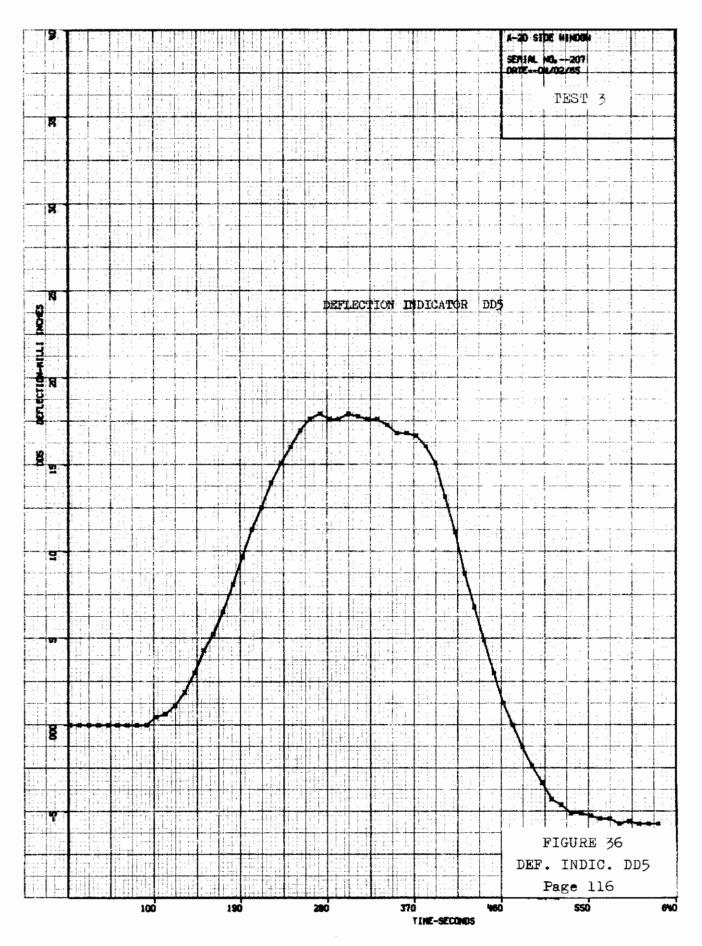




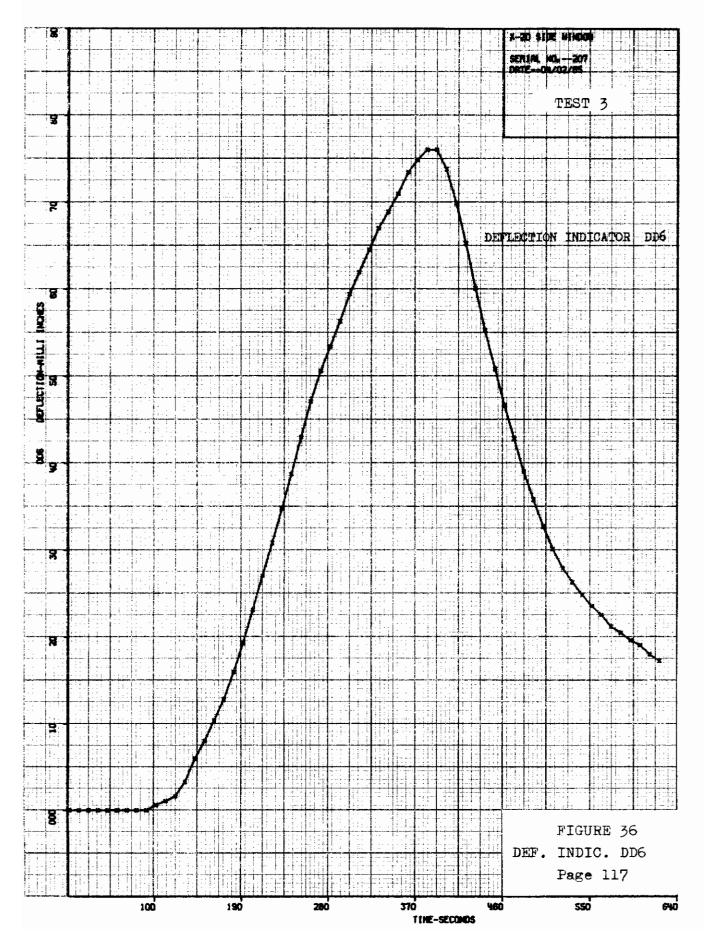
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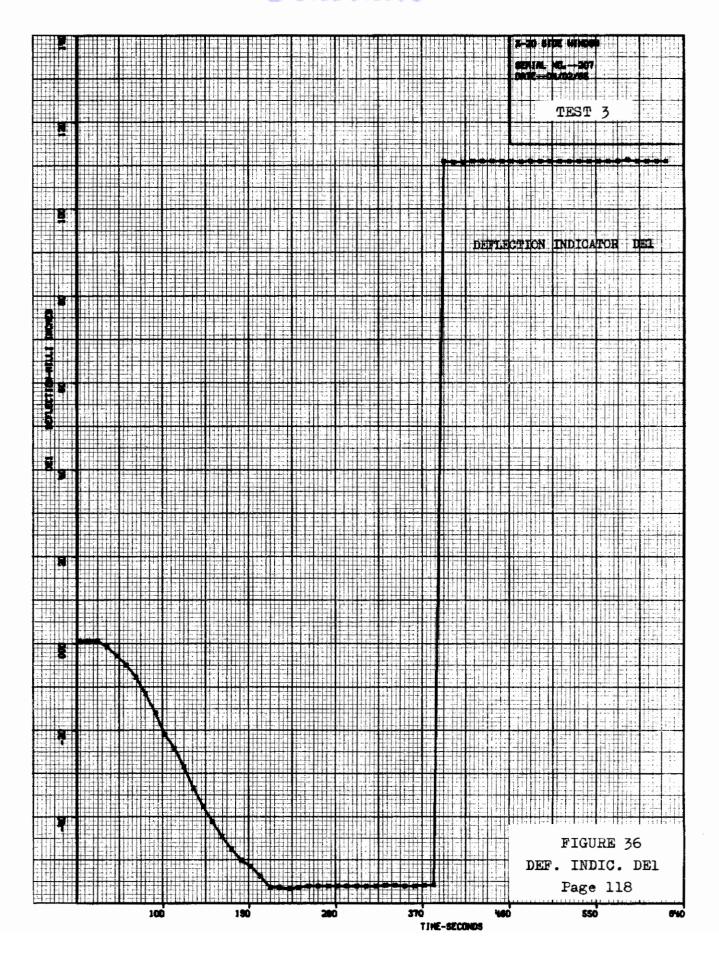
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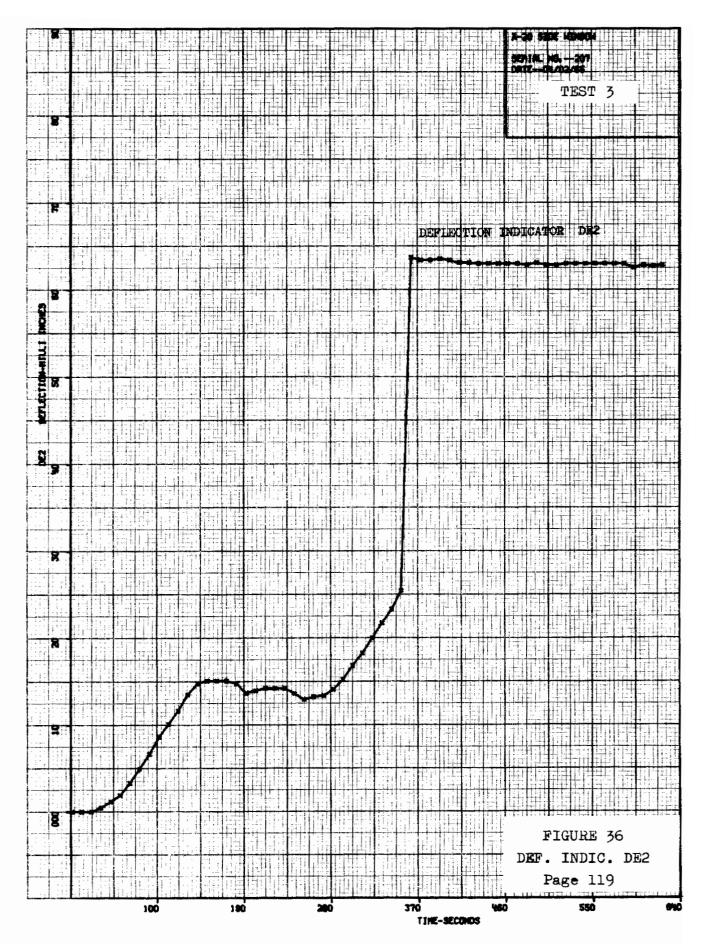
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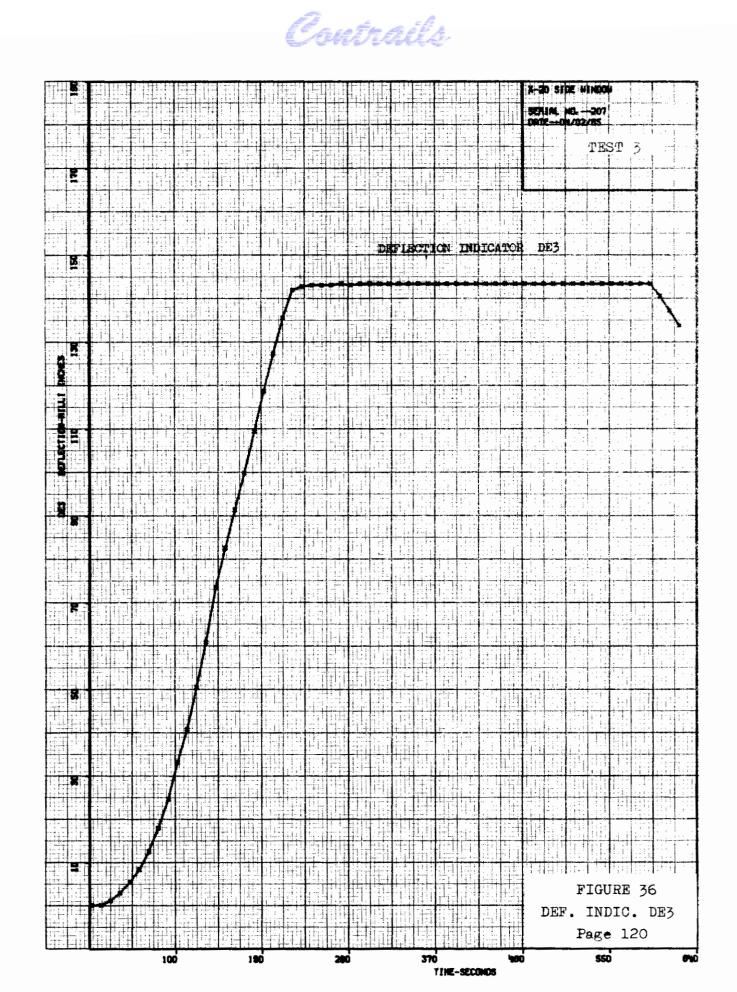


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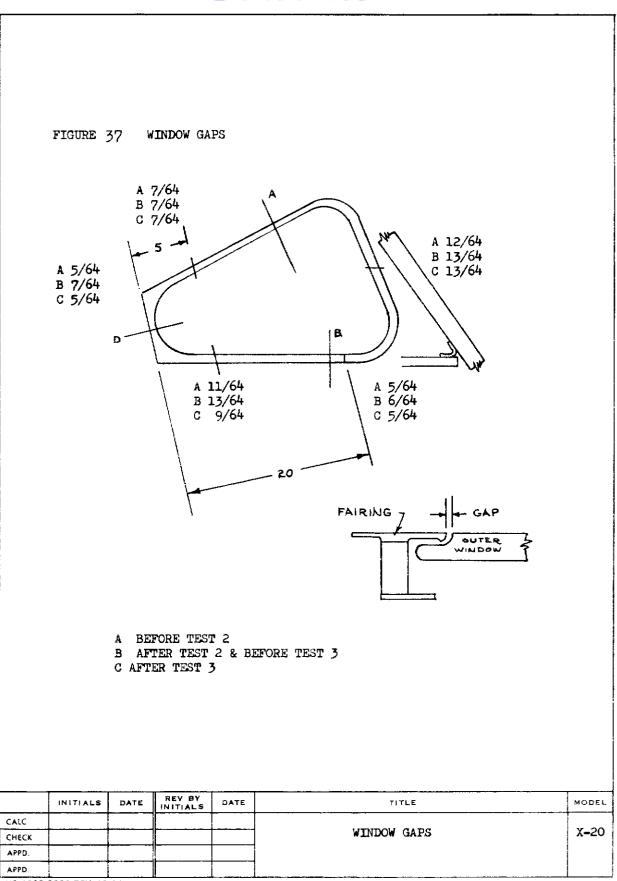


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4.4 DETERMINATION OF VISIBLE LIGHT TRANSMISSION FACTOR

4.4.1 INTRODUCTION

It was requested that a separate investigation of the light transmission factor of the window assembly be measured before and after heating the window.

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A device for making this measurement was obtained but found to be inoperative. The Structures Test Branch (FDTT) instrumentation personnel assembled a device to attempt to obtain readings so the test could continue.

Following the heat test a second set of readings was obtained with a different photoconductor. This was followed by a third set of readings which were obtained using a standard Photo Research Spectra Brightness Spot Meter.

A doubt exists as to the validity of the readings obtained from the first two set-ups due to lack of information relating current drop to attenuation of light in the visible spectrum.

4.4.2 TEST SET-UP AND PROCEDURE

a. Figure 38 is a sketch of the apparatus made by FDTT and used for the preheat and post heat measurements.

1. A current reading was made without the window in place (through air). The window was then placed between the light source and the photoconductor and a second reading was made.

b. Figure 39 is a sketch of the standard apparatus used to make the third set of readings. A series of readings were made with different light intensities through air and then through the window.

4.4.3 TEST RESULTS

a. Before heat test with FDTT apparatus with RCA 7163 Photoconductor.

 TABLE 2
 Thru Air
 Thru Window
 Ratio
 Window in Window out

 .210 amps
 .125 amps
 .595

 Light Intensity Increased:
 .165 amps
 .589

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4.4.3 TEST RESULTS (Continued)

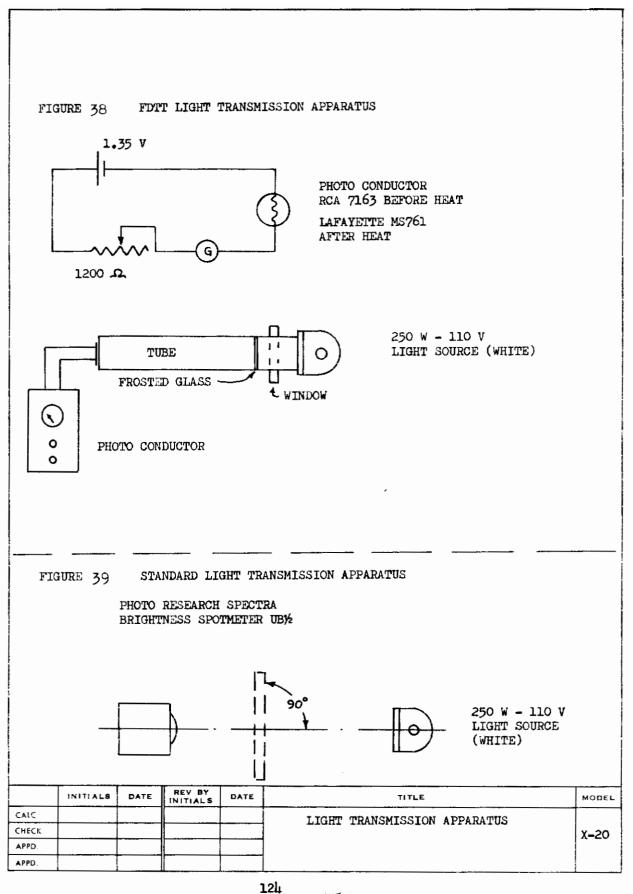
TABLE 2 (Continued) b. After heat test with FDTT apparatus with Layfette MS 791 Photoconductor.

<u>Thru Air</u>	Thru Window	Ratio Window in Window out
Light Intensity Increased:		
.770 amps	.490 amps	.636
.245 amps	.142 amps	.580
c. After heat test with	Photo Research Spectra	Brightness Spot Mete

c. After heat test with Photo Research Spectra Brightness Spot Meter UB1/2.

Thru Air Ft-Lamberts	Thru Window Ft-Lamberts	Ratio Window in Window out
1000	650	.65
500	310	.62
240	120	.50
150	100	.67

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### 5 ANALYSIS OF WINDOW FAILURE

#### 5.1 THERMAL DEFLECTIONS

It is well known that a flat plate of uniform thickness "t" and of any shape will normally assume a spherical curvature with radius  $t/\Delta\Delta T$  when subjected to a thickness temperature gradient. That is, one face is at a uniform temperature "T" and the other face is at a uniform temperature T +  $\Delta T$ , the temperature gradient between the faces being linear, where  $\Delta$  is the coefficient of thermal expansion. No thermal stresses are involved provided that the deflections are not restrained. The X-20 hot side window frame is designed on this principle. The three point suspension system as described on page 16 gives the window frame freedom to deflect thermally and also prevents thermal or load distortions of the cab frame from being induced into the window frame.

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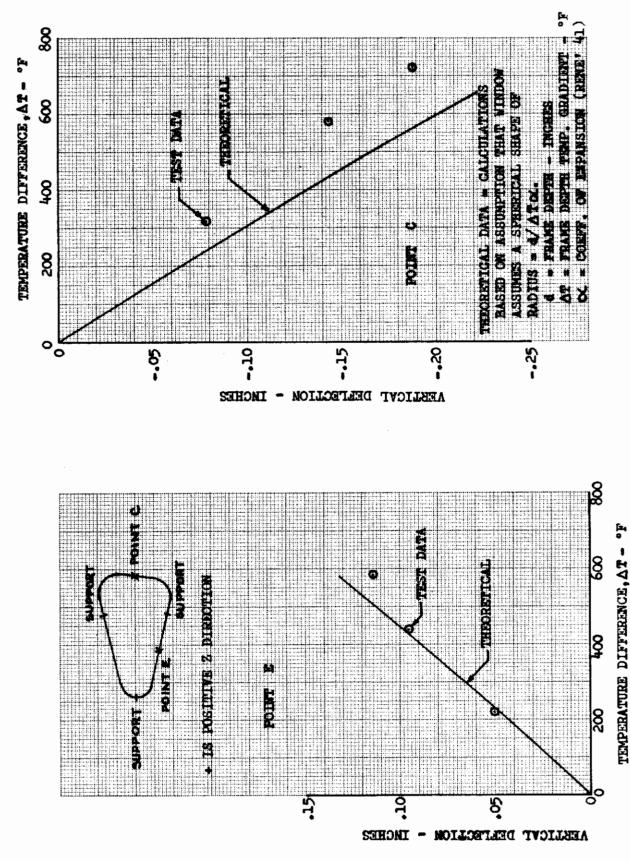
The .65 inch thick outer glass would require a thermal gradient through its depth of approximately 10 times that of the 1.62 inch deep Rene' 41 frame in order to have the same thermal curvature. This is because the coefficient of expansion of the Rene' 41 frame is approximately 25 times that of the fused silica glass. In actual test measurements, however, the thermal gradient through the depth of the glass was insignificant. Therefore the window panes want to remain essentially flat during the temperature cycle.

The stiffness (EI) of the frame is approximately 50 times that of the glass at the point of maximum span. Therefore the constraint offered by the glass to the frame is small.

The vertical frame deflections that were recorded during Test No. 3 were plotted versus the recorded frame temperature gradients. The data were plotted for both the short time rapid heat pre-test condition and the actual Test No. 3 condition. The short time-rapid heat deflections are shown on page 126. The actual Test No. 3 condition is shown on page 127. The test data has been corrected for rigid body movements as shown on page 195. In both of the test cases it can be seen that the recorded frame deflections agreed very closely with the theory discussed.

The actual deflection at the time of glass failure was obtained by extrapolation since some of the deflection indicators were inactive at that time. This deflection data is shown in Figure  $h^2$  on page 128. In Figure  $h^2$ page 128 the allowable glass curvature is shown based on the assumption of rigid seals.

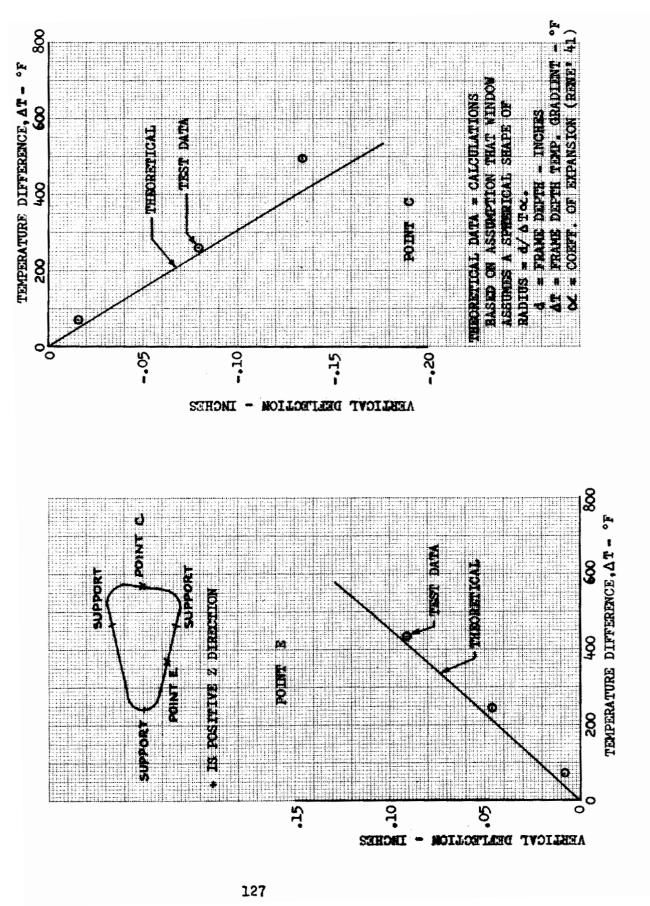
Reference 5, Side Window Strength Check Notes, page 1.13.11, predicted an allowable frame temperature gradient of  $260^{\circ}$ F/inch which would be equivalent to  $260 (1.62) = 420^{\circ}$ F for the total frame.



THERMAL DEFLECTION COMPARISON - RAPID HEAT SN 206

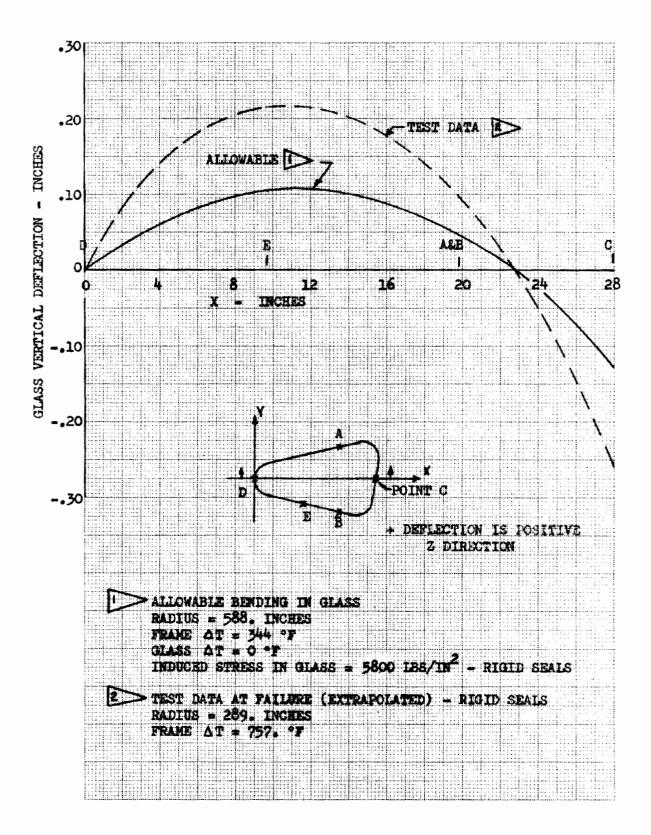
FIGURE 40

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FIGURE 42 GLASS THERMAL CURVATURE COMPARISON



5.1 THERMAL DEFLECTIONS (Continued)

The actual measured temperatures at the time of failure are shown pictorially on Figure 43, page 130. It can be seen from Figure 43 that the frame temperature gradients were greater than the allowable. For instance, Section D-D shows a gradient of  $1145^{\circ} - 171^{\circ} = 974^{\circ}F$ .

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In view of the good agreement between measured deflections and temperature gradients with elementary theory it is concluded that the primary cause of window failure was the high temperature gradient through the depth of the frame. The resulting frame temperature gradient produced window frame curvature which induced glass curvature in excess of allowable.

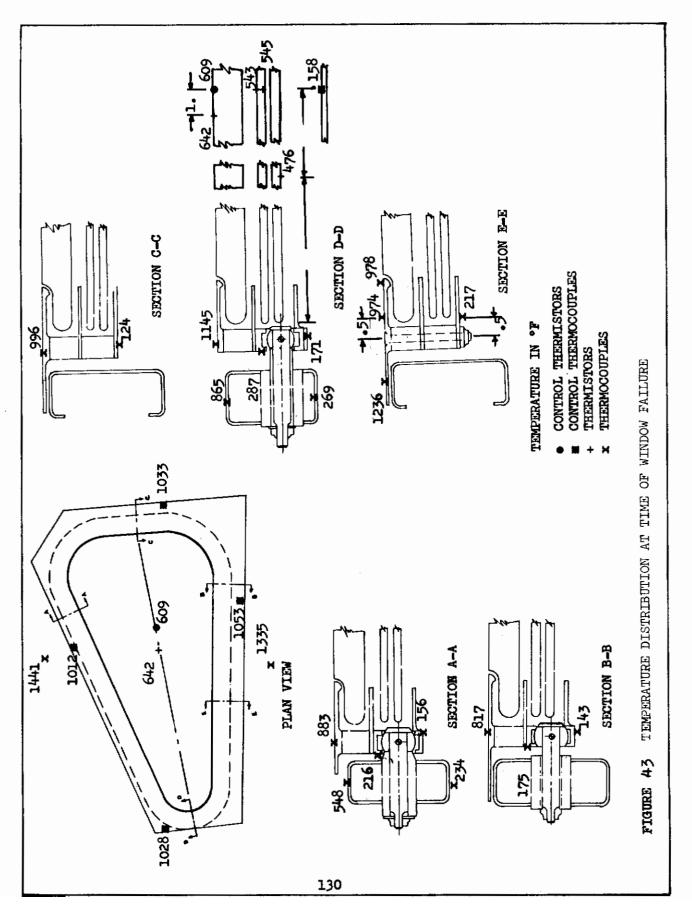
# 5.2 THERMAL ANALYSIS

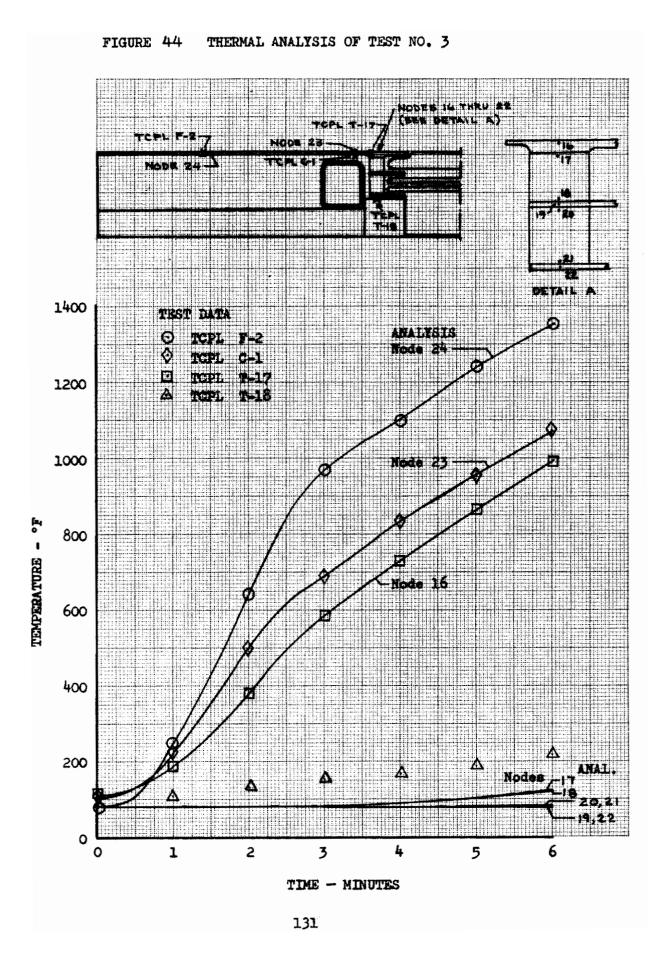
During the window design phase the frame temperature gradient predictions had been based on significant interface conduction. This, of course, produced relatively low overall thermal gradients.

A new two-dimensional thermal analysis of the window frame was performed after the window pane failure occurred during Test No. 3. This thermal analysis used some relatively new approaches, particularly in the handling of interface thermal resistance. A recent X-20 continuation effort, "Hot Structures Thermal Correlation", (Reference 6) indicated that for materials such as Rene' 41 at high temperatures, the radiation mode of heat transfer across an interface is highly dominant, i.e., conduction can and should be neglected. This analysis assumes all window frame interfaces (including those due to the seal system) have radiation heat transfer only.

Two cases were analyzed. The results are shown on Figure 44, page 131, and Figure 45, page 132. Figure 40, page 144, is based on the available data from Test Condition 3 up to a time of 6 minutes at which time the window failure occurred. All external temperature boundary nodes were driven from the actual test data for this case. Figure 45, page 132, shows temperature gradients for a complete test profile. Variances from the test case include insulation around the periphery of the specimen and a slightly different control location on the fairing.

Of prime interest in both cases, Figures 44 and 45, is the correlation between the analysis and test data and the relatively lower gradient existing through the bulk of the frame (Nodes 17 through 21). Evidently the major gradient which induced the pane failure was that shown between Nodes 16 and 17. The frame's outermost element or fairing (Node 16) being a continuous structural member drove most of the frame curvature which resulted in pane bending and failure. These results suggest that a possible solution would be to redesign the outer fairing and inner backup strip frame elements to allow for differential expansion such as by segmentation. This would require a relocation of the basic seal plane to a more internal location such as the inner surface of the outer pane.





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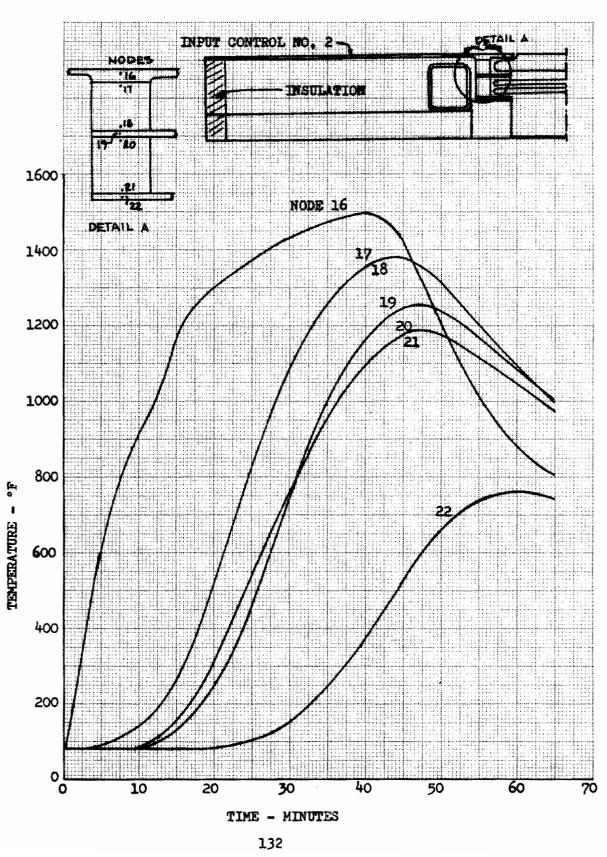


FIGURE 45 THERMAL ANALYSIS - REVISED TEST SET-UP

# 5.3 THERMISTOR LEADS

Upon examination of the crack pattern of the window pane as shown in Figure 35 page 63, it is evident that the crack originated at the location where four thermistor leads exited through the window seals. The wedge pattern of the crack near the thermistor leads indicates the outer surface of the glass was in tension as expected. The fissures indicate the crack traveled from the thermistor leads across the window then rebounded to a location approximately midway between the supports.

A secondary cause of failure is believed to be the hard point in the seals caused by the thermistor instrumentation leads running under the window seals as discussed on page 24. These leads would not be present on flight hardware, however.

6 CONCLUSIONS AND RECOMMENDATIONS

An X-20A (Dyna-Soar) high temperature side window assembly was fabricated from superalloys and fused silica panes. The window assembly was subjected to a series of tests simulating the X-20 environment to experimentally verify the design and to provide experience for improved window design. The window assembly successfully withstood a preliminary vibration survey and limit boost airload pressure. The outer window pane fractured during the simulated re-entry temperature cycle. The major cause of the window pane failure was the high temperature gradient through the depth of the window frame. The frame temperature gradient produced frame curvature which exceeded the allowable curvature of the glass. Although the full planned program of tests was not completed, limited tests were run for each of the three design environments-vibration, pressure, and temperature. The following specific conclusions and recommendations were made as a result of the limited tests and the analysis conducted on the window assembly:

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### 6.1 INSTRUMENTATION

a. The hard point in the window seals caused by the thermistor instrumentation leads running under the window seals is believed to have caused a stress concentration which added to the cause of failure. This, however, is considered to be a secondary factor. In future window testing it is recommended that methods be designed to prevent stress concentrations caused by the instrumentation leads running through the window seals. It is possible that grooves could be manufactured in the seals but this also may cause some stress concentrations, and would prevent sealing the outer window. With some development it is envisioned that the gold thin film thermistor leads could be continued around the edge of the glass. The contacts could then be made on the edge of the glass and thus not alter the seals. The present X-20 frame design does not have sufficient clearance for this application, however.

#### 6.2 TESTING

a. The test bed fixture weight for the vibration test was limited so as not to exceed the maximum load capability of the Ling A-300B shaker. The test bed fixture consisted of a two inch thick aluminum plate. High amplification factors were recorded during preliminary testing which indicated the test jig mounting plate had marginal stiffness.

It is recommended that future vibration testing of window specimens of equivalent weight and size be performed on a shaker of larger capacity so that the test bed could have a much greater stiffness. Such shakers as the Ling 249, L200, or MBC210 are recommended. 6.2 TESTING (Continued)

b. The heat control zone separation for the test was not sufficient to give ideal flight simulation. Results from Test No. 3 indicate that sufficient heat from Control Zone 2 was entering Control Zone 1 to heat the center of the window pane to the programmed levels. Thus the outer window pane regions were possibly hotter since they were closer to the energy source. This effect may have contributed to the window failure in a minor degree.

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Future testing of window specimens should consider special baffles or close lamp spacing to the specimen (this would require separate test set-up for tests run with and without vacuum-pressure box for clearance reasons) and methods to prevent lamp reflector overlaps.

c. The insufficient separation of the heat control zones required the removal of most of the silicon carbide powder from the outside window pane in order to prevent overheating. This allowed some direct penetration of the heat lamp radiant energy to the interior regions of the window system. Since flight plasma radiation is insignificant in the side window region, such penetration is less than ideal flight simulation. This effect did not contribute to the window failure as it actually reduced the frame thermal temperature gradient slightly.

## 6.3 STRENGTH ANALYSIS

a. The comparison of window frame rotations (torsional angular twist) and vertical deflections due to limit boost air load with analyses based on the direct stiffness method as programmed for the digital IEM 7094 Computer show good correlation. In most cases the values lie between the fixed and pinned glass to frame analyses cases.

It is concluded that the good agreement between the analysis and test data for boost limit airload is evidence that the window assembly has no structural weakness. Extrapolation of this data to ultimate load indicates that the window assembly could withstand the ultimate pressure load without failure.

# 6.4 THERMAL ANALYSIS

a. The measured thermal deflections can be approximated with reasonable accuracy by elementary theory.

b. The window frame design was based on interface thermal conduction which resulted in low overall frame thermal gradient predictions. A new thermal analysis based on radiation heat transfer only across the interfaces agrees with the test data and predicts the high thermal gradients that were measured, and was the primary cause of the window failure.

6.4 THERMAL ANALYSIS (Continued)

c. The high frame thermal gradients were caused by the many interfaces (laminations) created by the buildup of bars, plates, and shims in the construction of the frame. These interfaces resulted in poor thermal conductivity through the window frame. A large temperature drop occurs across the first interface (fairing).

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6.5 WINDOW DESIGN

a. The three point suspension system of the X-20 side window frame performed satisfactorily. The suspension system prevented the cab frame distortions from being induced into the window frame. The system also allowed relative movement of the window frame and the cab frame in the plane of the window without inducing redundant force systems.

b. Rene' 41 material is considered a suitable material for window frame material that must operate in the X-20 environment (1800°F) even though its coefficient of thermal expansion is somewhat larger than suitable refractory alloys. Thus Rene' 41 exhibits somewhat larger curvature due to frame thermal gradients. The problems of coatings, fabrication, and assembly of refractory alloys appear to offset the advantages offered by their somewhat lower coefficients of thermal expansion.

c. The use of the window leaf springs installed in series with the seals to maintain clamping forces after exposure to the heat environment and the side clamping and positioning springs are considered good design procedure.

d. The air leakage rate through the window seals exceeded the design target value by a factor of 10. The higher leakage rate is attributed to the thermistor lead wires passing across the window seal. The leakage rates are not considered conclusive of the sealing qualities of the window seals as the flight article would not have these thermistor leads. The use of the Hastelloy-X wire mesh high temperature seals is considered good design procedure.

e. The X-20A window design represents the most advanced technology for hypersonic re-entry vehicles. It is recommended that a redesign of the X-20A high temperature side window be considered incorporating design improvements based on the experience of this test program. The new design should then be subjected to the environmental tests as planned under this program. The potential value of such a program has application in many high temperature window requirements.

A redesign should consider the segmentation of the outer fairing (retainer) in order to allow this element to expand differentially. The other portions of the window frame should be made as continuous and homogeneous as possible.

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# APPENDIX I

# STRUCTURAL ANALYSIS

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I STRUCTURAL ANALYSIS

#### Summary

This section presents the deflection and internal loads analysis of the X-20 external side window for the critical design condition, boost ultimate net pressure of 10.5 psi.

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A description of the window and window environment, and the construction of a mathematical model for structural analysis are presented. The stiffness method as programmed for the digital IEM 7094 by The Boeing Company, and called "Cosmos", is used for analysis.

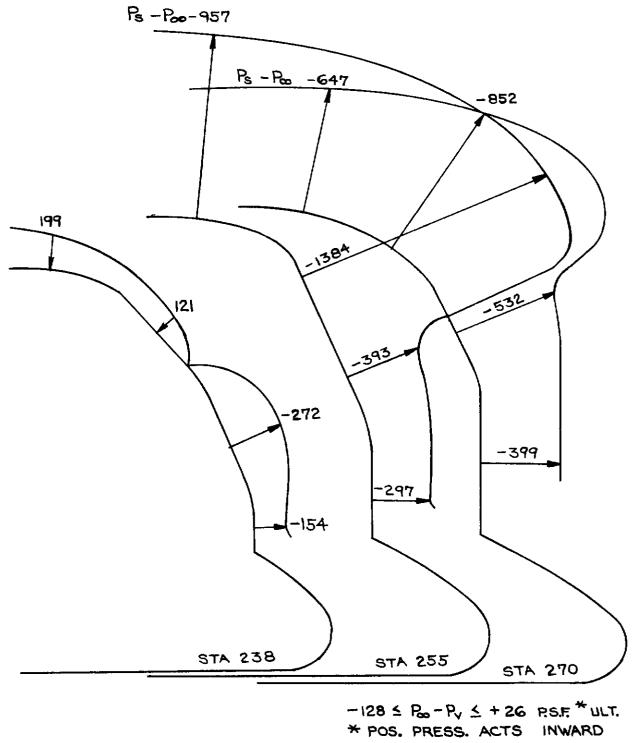
Results of the digital solution include translation and rotation, and internal loads in the glass pane and the window frame. A discussion of the stresses and strains in the critically stressed region of the glass pane is included.

#### External Loads

External loads are taken from D2-81142, "X-20 Boost, Hypersonic, Approach, and Air Launch Phase Load Conditions". The side window outer glass pane is critical for the boost environment. The critical condition during boost results in a net air load of 10.5 psi ultimate on the external side window.

The curve of page 140 shows hatch area boost pressures corresponding to the critical condition.

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REF. 3

# FIGURE 46 Boost Pressure Distribution - Hatch Area

## Internal Loads

The side window outer glass pane is critical for the boost environment. This includes effects of air load, vibration, and installation. This paper deals with the effects of air loads on the glass.

The internal loads in the glass pane are affected by several design features of the window assembly.

- 1) The window frame is supported at three points. This tends to concentrate the load in the glass at the three support regions.
- 2) As the window frame is stiffened, the tendency for the stress trajectories to concentrate at support regions is reduced.
- 3) Support of the window by a system of seals and springs in series cushions the window edge as it is clamped in the frame.
- 4) The glass bears on the window frame through the seals. The center of action of the bearing force is conservatively estimated to be .92 inch from the shear and torsion center of the window frame. (See Figure 47 , page 143 ) Torsion moments are applied to the window frame when air load is transferred from the glass to the frame. The torsional rotation of the frame under these moments will force the glass to carry more of the airload toward the frame support points.
- 5) Springs around the periphery of the window are designed to fill the gap between the window pane and window frame. These springs position the window for all times during flight of the X-20, cushioning against vibration and inertia loads.

#### Idealization of the X-20 Side Window for the Stress Analysis

The mathematical model which simulates the structural behavior of the X-20 side window is shown in Figure 1/7, page 1/43. The model is made up of four types of structural elements which together simulate the stiffnesses of the real structure. They are quadrilateral and triangular plate elements, six degree of freedom beam elements, and spar elements.

The quadrilateral and triangular plate elements are used to simulate the .65 inch thick fused silica glass pane. Quadrilateral plates are used in all areas except where a change in size of quadrilateral elements is desired, or where geometry of the real plate is such that it is naturally simulated by a triangular element (as in the case around the boundary of the side window).

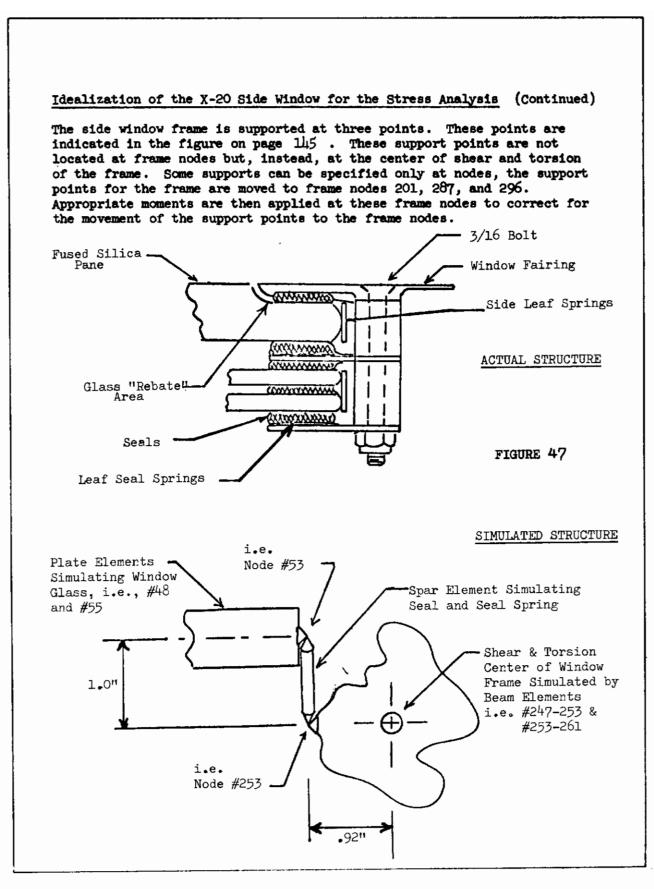
The six degree of freedom beam elements are used to simulate the window frame bending and torsion stiffness. They also have the capability of defining the locus of the centers of shear and torsion to lie away from the points of load transfer from glass to frame by any dimension. This permits proper simulation of the coupling of torsion and bending in the window frame with the load transfer from glass to frame.

The spar elements are used to force displacement compatibility between the boundary of the real plate and the frame at the points of load transfer between glass and frame. Essentially the spar elements are used as a device for pinning the glass to the frame. Spar elements may be used to simulate seal and seal spring flexibility. The one inch length for spar elements is arbitrary as long as axial area is adjusted accordingly.

The actual assemblage of window pane and window frame with seals is shown for comparison with the idealized structure simulating the actual assemblage on page 143.

Nodes may be defined as points in the idealized structure at which loads may be applied, the structure may be supported, deflections and rotations of the structures may be obtained, continuity between the common structural elements may (or may not) be enforced (at the user's discretion).

Nodes for the plate elements are numbered 1 through 129. Nodes for the window frame six degree of freedom beam elements are located one inch "below" the boundary of the plate elements. The frame nodes are obtained simply by adding 200 to the corresponding window boundary node number. The spar elements simulating seal stiffness connect the window boundary nodes to their corresponding frame nodes.

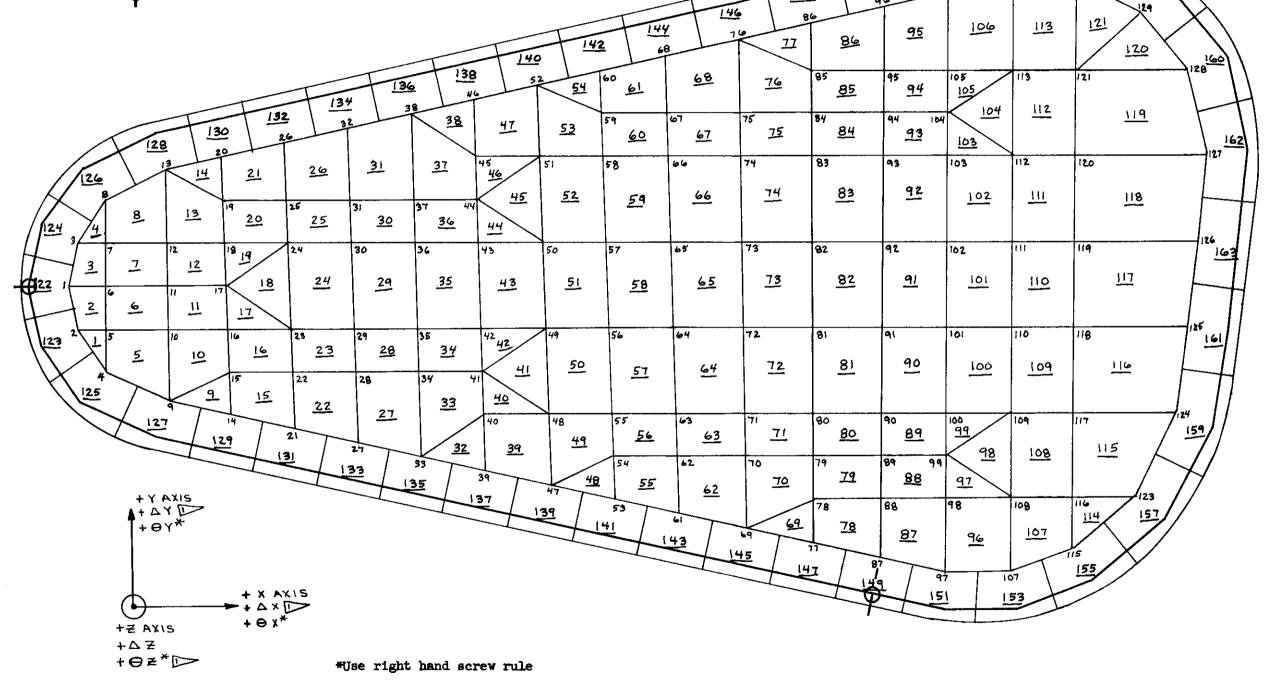


Contrails The following figure shows the arrangement of structural elements for the stress and deflection analysis of the X-20 side window. Also shown is the coordinate system and sign convention for displacement and rotation at the nodes. An illustration of the simulation of the frame and pane is shown on page 143. 144

NOMENCLATURE

Contrails

- 1. Node numbers for the glass plate elements are numbered 1 through 229.
- 2. To obtain window frame beam element node numbers, add 200 to the node numbers assigned to the glass plate periphery.
- 3. All panel numbers are underlined. Panels numbered 1 thru 121 represent the side window outer pane, .65 inch thick. Panels numbered 122 thru 163 are used only for proper allocation of airload on the window fairing to nodes.
- 4. Indicates beam elements representing window frame. This line coincides with the locus of points lying on the window frame shear center.
- 5. Indicates locations of three support points for window frame.



These node deformations are zero for this analysis

154

114

152

30

148

156

122

Contrails

## Description of Mathematical Model Structural Properties

The window glass is supported around its periphery by the window frame which, in turn, rests on three spherical bearings at the three support points. The glass bears on the frame through the seals and seal springs. The center of action of the bearing force is conservatively estimated to be .92 inch from the shear and torsion center of the frame.

A soft window frame in bending or in torsion will force the glass to carry more of the air load toward the window frame support points. Bending and torsion stiffnesses of the window frame are calculated on page 176.

Use of soft seals and seal springs around the edge of the glass results in a more uniform transfer of load from the glass to the frame. Becuase of the non-linearity expected for seal spring rates, seals and seal springs are simulated to be approximately 25 times stiffer than is expected at room temperature. Flexing of the window frame protruding flanges is conservatively neglected in calculating seal stiffness.

Elastic properties of Rene' 41 and fused silica glass are presented in the Appendix on pages 203 to 215.

## External Loads for the Idealized Structure

A net uniform pressure of 4.3 psi is applied to the mathematical model. The pressure is applied in the positive z-direction. For other pressures a direct ratio may be employed as this solution is not non-linear. I.e., for the boost ultimate net pressure of 10.5 psi, external loads, internal loads, deflections, etc. may be obtained by multiplying the results presented here by the ratio of 10.5/4.3 = 2.442.

External loads can be applied to the mathematical model only at node points. To accomplish the transformation of uniform pressure to node loads, the surface of the window is simply divided into air load panels, and the resolution of load to the nodes is performed using principles of statics and engineering judgment.

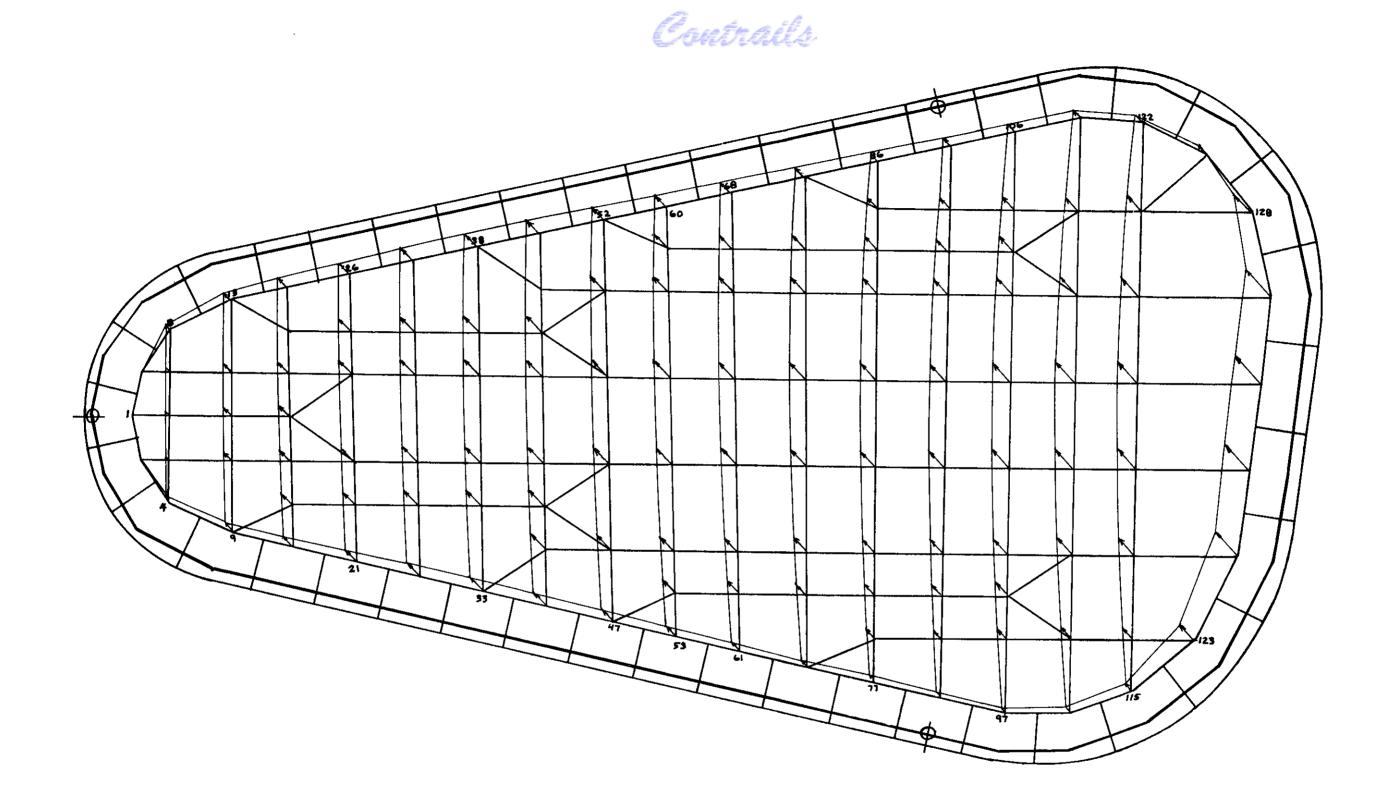
#### Deflections

Deflection patterns of the glass pane and window frame when subjected to a uniform air load are shown on pages 149 and 151 respectively for z-axis translations. Translation vectors drawn slanting upward and to the left are in the positive z-direction.

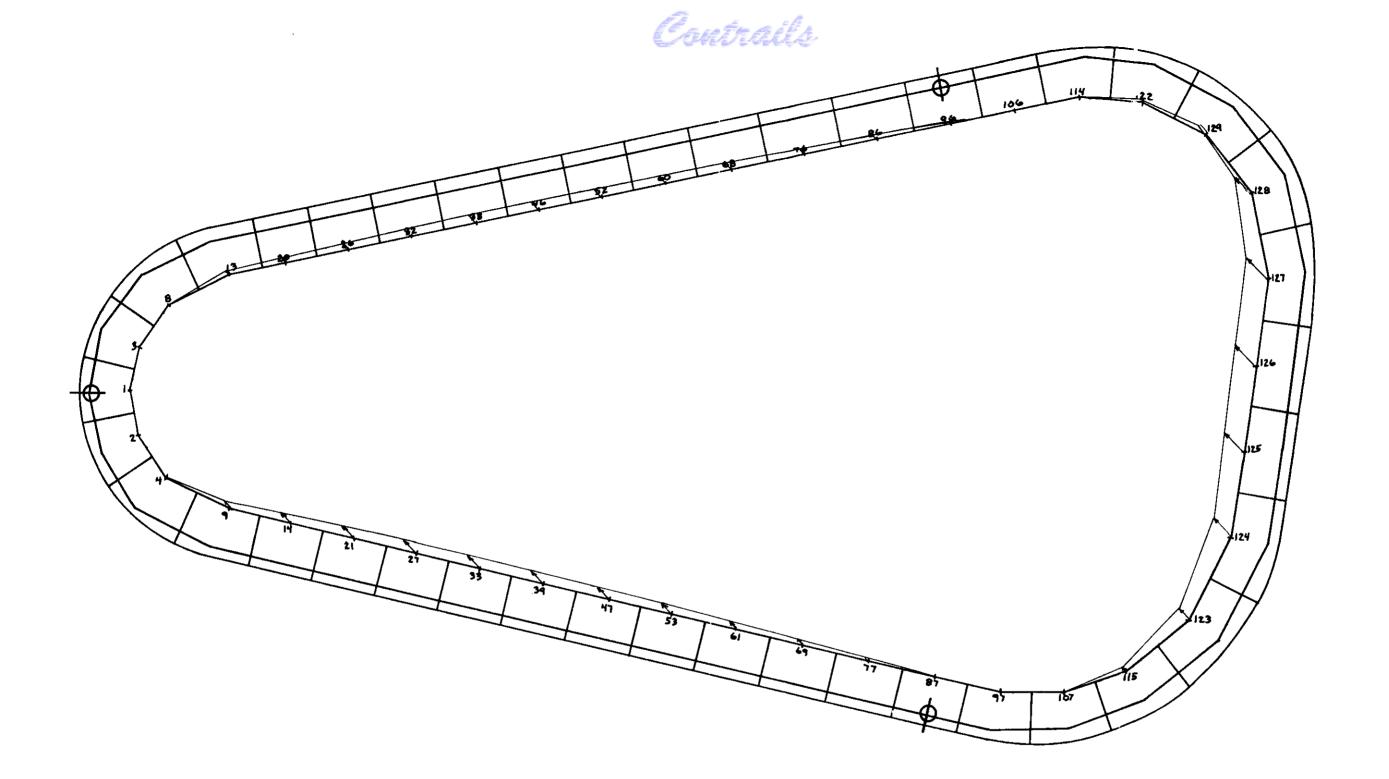
Translations and rotations of all nodes for a uniform air load of 4.3 psi acting in the positive z-direction are tabulated on pages 153 through 162. The right hand screw rule is followed for rotations. See page 145 for pictorial presentation of deflection sign convention.

To obtain translations and rotations of the window structure when subjected to boost ultimate net pressure of 10.5 psi, multiply by 2.442.

Contrails



Load is normal to the window and toward the reader. FIGURE 49 AIRLOAD DEFLECTION PATTERN Pinned Case - Airload = 4.3 Lbs/In<sup>2</sup>



Load is normal to the frame and toward the reader. FIGURE 50 FRAME AIRLOAD DEFLECTION PATTERN Pinned Case - Airload = 4.3 Lbs/In<sup>2</sup>

TABLE 3 ROTATIONS AND DEFLECTIONS - PINNED CASE  $RY = \Theta_y - RADIANS$  $RX = \Theta x - RADIANS$ Pressure = 4.3 psi  $Z = \Delta Z - INCHES$ NODE NODE FREEDOM -2 +.41737234 1RY -2 -. 10309921 18RY -3 -.87060937 1RX -3 -.1000861018RX -3 -.13587298 1 2 -3 +.59392566 18 Z -2 +.40351832 -2 -. 10263542 2RY 19RY -3 -.86751173 2RX -4 -.75697320 19RX -3 -.16833000 2 Z -3 +.89787785 19 2 -2 +.38457096 3RY -2 -.10307034 20RY -3 -.85654965 3RX -3 -.12229998 -3 -.17271722 20R X -3 +.68795080 3 Z 20 Z 4RY -2 ~.10024731 -2 +.36454800 21RY -3 -.62627717 -4 -.53730180 4RX 21RX -4 +.46174014 4 Z -2 +.16451625 21 Z -2 +.53869758 5RY -2 -.10181153 22RY -3 -.67815602 -4 -.70609816 5RX 22R X -4 +.32485974 -2 +.15749265 5 Z 22 Z -2 +.54256400 6RY -2 -.10254908 23RY -3 -.70644380 6RX -4 -.98444681 -2 +.14812860 23R X -4 -.16039641 6 Z 23 Z -2 +.54097900 7R Y -2 -.10237956 24RY -3 -.72406521 -3 -.12571457 7 R X 24RX -3 -.14135247 7 Z -2 +.13578398 24 Z -2 +.52092281 -2 -.10144813 8RY 25RY -3 -.71632650 8RX -3 -.14083086 25RX -3 -.18638586 -2 +.12119790 8 Z -2 +.50128611 25 Z 9RY -3 -.93087357 26RY -3 -.68701922 9R X -4 -.27537489 26RX -3 -.19547176 9 Z -2 +.30729662 26 Z -2 +.47260937 **10RY** -3 -.96043775 27RY -4 -.53679347 -3 -.41748154 10RX 27RX -3 +.12709813 -2 +.29944174 10 Z 27 L -2 +.61182206 **11RY** -3 -.97064738 -3 -.50111958 -4 -.93476823 28RY 11RX -4 +.83829669 28RX -2 +.29023760 11 Z 28 Z -2 +.62863291 -3 -.97039144 12RY 29RY -3 -.13328395 -3 -.53507935 12RX 29RX -4 +.12977459 -2 +.27786387 12 Z 29 Z -2 +.63277687 13RY -3 -.95404546 30RY -3 -. 55318845 -3 -.15894785 13RX 30R X -3 -.15381867 -2 +.25106772 13 Z 30 Z -2 +.61537906 14RY -3 -.80702765 31RY -3 -.53523647 14RX -5 +.40839874 31RX -2 +.43312814 -3 -.22046464 14 Z -2 +.59520029 -3 -.83301001 31 Z 15RY -3 -.48052887 32RY 15RX -5 -.21248197 32RX -3 -.25076304 15 Z -2 +.43197529 32 Z -2 +.55200559 16RY -3 -.85411555 33RY -4 -.36964402 -3 -.20192301 16RX -3 +.24800835 33RX -2 +.42689141 16 Z -2 +.64959300 33 Z -3 -.86781731 17RY 34R Y -3 -. 32764988 17RX -4 -.86817950

TABLE 3	ROTATIONS AND DEFLECTIONS - PI	INNED CASE (CONT	INUED)
		51RY	-432809761
34RX	-3 + .15001886	51RX	-351381425
34 Z	-2 +.68923364	51 Z	-2 +.67737799
35R Y	-3 36457602	52R Y	-4 +.90026937
35RX	-4 +.46533804	52RX	-363013775
35 Z	-2 +.69819922	52 Z	-2 +.58122235
36RY	-338009824 -317133888	53RY	-3 +.28259008
36RX	-2 +.68419038	53RX	-3 +.74444868
36 2	-335975929	53 Z	-2 +.55994278
37RY	-327184229	54R Y	-3 +.19218273
37RX	-2 +.66109669	54R X	-3 +.67799352
37 Z	-3 26474787	54 Z	-2 +.63305202
38RY	-335774896	55RY	-4 +.98269913
38RX 38 Z	-2 +.59581754	55R X	-3 +.54585299
30 Z 39RY	-6 +.21925155	55 Z	-2 +.69502193
39RX	-3 +.36473948	56RY	-413621109
39 Z	-2 +.65267010	56RX	-3 +.17655541
40R Y	-310192926	56 Z	-2 +.76829990
40RX	-3 +.31716936	57RY	-431082725
40 Z	-2 +.69913317	57RX	-324503373
41RY	-316703102	57 Z	-2 +.76126374
41R X	-3 +.21401341	58RY	-4 +.45110592
41 Z	-2 +.72561017	58RX	-360347797
42RY	-320812735	58 Z	-2 +.67556442
42RX	-4 +.84016229	59RY	-3 +.11975667
42 Z	-2 +.74036001	59RX	-372497398 -2 +.60890620
43RY	-322430736	59 Z	-3 +.19336330
43RX	-319214028	60RY 60RX	-377629087
43 Z	-2 +.72841124	60 Z	-2 +.53545007
44R Y	-319976423	61RY	-3 +.33352270
44RX	-331949539	61RX	-3 +.93237685
44 Z	-2 +.70196886	61 Z	-2 +.48215083
45RY	-315202709	62RY	-3 +.20666553
45RX	-341655161	62RX	-3 +.82262414
45 Z	-2 +.66428757	62 Z	-2 +.60258567
46RY	-470248733	63RY	-3 +.12069840
46RX	-345293559	63RX	-3 +.65937919
46 Z	-2 +.60620146	63 Z	-2 +.67784908
47RY	-3 +.17066587	64RY	-4 +.12155835
47RX	-3 +.56088387 -2 +.62026625	64R X	-3 +.22296612
47 Z	-4 +.20399831	64 Z	-2 +.76722962
48RY	-3 +.43364610	65RY	-549049096
48RX	-2 +.70475454	65R X	-3 26675640
48 Z 49RY	-4 87683460	65 Z	-2 +.76281545
49R 1 49R X	-3 +.13146668	66RY	-4 +.70369760
49KX 49 Z	-2 +.76189357	66RX	-369327376
49 Z 50RY	-310491385	66 Z	-2 +.66599491
50RX	-322115402	67RY	-3 +.13978958
50 Z	-2 +.75229362	67RX	-384929786
-	154		

TABLE 3 ROTATIONS AND DEFLECTIONS - PINNED CASE (CONTINUED) 84R X -2 -.10847418 67 Z -2 +.58841393 84 Z -2 +.56260579 68R Y -3 + .2496061485RY -4 +.28519461 68RX -3 -.94872858 85RX -2 -.12593830 68 Z -2 +.47053329 85 Z -2 +.44961270 69RY -3 +.30761772 86RY -4 +.96947350 69RX -2 +.11893346 86RX -2 -.13666565 69 Z -2 +.38861536 86 Z -2 +.30136469 70RY -3 +.15698143 87RY -5 +.14578138 70RX -3 +.97805571 -2 +.15203237 87RX 70 Z -2 +.57271875 87 Z -2 +.23258860 -4 +.80133190 71 R Y 88R Y -4 - 65209238 -3 +.77330908 71RX -2 +.13789223 88RX 71 Z -2 +.66104437 -2 +.43512320 88 Z -4 -.16574134 72RY 89RY -3 -.11372473 -3 +.27018857 72RX 89RX -2 + 11842522 72 Z -2 +.76630638 89 Z -2 +.56415816 -4 -.33601539 73RY -3 -.15371427 90R Y -3 -.28537647 73RX 90RX -3 +.93914265 -2 +.76466944 73 Z -2 +.66880729 90 Z +.29736617 74RY -4 91RY -3 -.20926967 74RX -3 -.78285876 91RX -3 +.34690268 74 Z ~2 +.65682915 -2 +.79834668 91 Z 75RY -4 +.90436687 92RY -3 -.23221889 -3 -.98110553 75RX -3 -.29917855 92RX -2 +.56813674 75 Z -2 +.80356660 92 Z -3 +.22711385 76RY 93RY -3 -.21937623 -2 -.11801937 76R X -3 -.89545207 93R X -2 +.38164026 76 Z -2 +.68385667 93 Z 77RY -3 +.18690543 -3 -.19768953 94R Y 77RX -2 +.13788087 -2 -.11501650 94R X -2 +.29995273 77 Z 94 Z -2 +.58133918 -3 +.12028893 78RY 95RY -3 -.16855103 -2 +.12797491 78RX 95RX -2 -.13438476 -2 +.43693718 78 Z 95 Z -2 +.46115996 -4 +.43718634 79RY 96R Y -3 -.11148242 -2 + .1100354379R X 96RX -2 -.15115433 -2 +.55648584 79 Z -2 +.24156549 96 Z -4 -.16769635 80RY 97RY -3 -.23005770 80R X -3 +.86855803 97RX -2 +.16503145 80 Z -2 +.65543180 97 Z -2 +.19064429 -4 -.95146873 81RY -3 -.25798275 98RY -3 +.31205117 81RX -2 +.14441735 98R X -2 +.77433093 81 Z 98 Z -2 +.45653337 -3 -.11458066 82RY -3 -.27883916 99RY -3 -.29718720 82RX -2 +.12363087 99RX 82 Z -2 +.77579797 99 Z -2 +.59133140 -4 -.73450568 83RY 100RY -3 -.29760279 -3 -.85268815 83RX 100RX -3 +.97889290 83 Z -2 +.65992005 100 Z -2 +.70277603 84RY -4 -.28775979

TABLE 3	ROTATIONS AND DEFLECTIONS -	- PINNED CASE (CONTINUED)		
,				
	2 22026002		-	
101RY	-3 32925882	117 Z		+.83218078
101RX	-3 +.37156929 -2 +.83853352	118RY		55599718
101 Z 102RY	-3 35210505	118RX 118 Z		+.39372980 +.97205053
102RX	-329141563	119RY		57632198
102 Z	-2 +.84691139	119RX		25168300
103RY	-3 36218503	119 Z		+.98692706
103RX	-390681322	120RY		62376069
103 Z	-2 +.72681395	120RX		86055209
104RY	-336270267	120 Z		+.87629667
104RX	-211732768	121RY	-3	69433246
104 Z	-2 +.62280780	121RX	-2	13357959
105RY	-335783149	121 Z	-2	+.66102191
105RX	-213846206	122RY		76358078
105 Z	-2 +.49991595	122RX		15881489
106RY	-3 35049306	122 Z		+.35902887
106RX	-216103003	123RY		69921002
106 Z	-2 + .22247795	123RX		+.13232745
107RY 107RX	-344720769 -2 +.16539388	123 Z		+.71075109
107 Z	-2 +.24270626	124RY		73877188
108RY	-3 44493815	124RX		+.92513917
LOBRX	-2 +.14594174	124 Z 125RY		+•98599394 -•73202226
108 Z	-2 +.50980650	125RX		+.39040131
109RY	-343801882	125 Z		+.11405212
109RX	-3 +.99809057	126RY	_	76895763
109 Z	-2 +.75703833	126RX		20986233
11GRY	-344830631	126 Z		+.11788369
110RX	-3 +.38677681	127RY	-3	83686511
110 Z	-2 +.89694664	127RX	-3	76470302
111RY	-3 46948704	127 Z		+.10978080
111RX	-327453681	128RY		88074459
111 Z	-2 +.90821192 -350193895	128RX		12077401
112RY	-3 50145845	128 Z		+.86712015
112RX 112 Z	-2 +.79149691	129RY		86753212
113RY	-354151128	129RX 129 Z		14510742 +.59181687
113RX	-213822511	201RY		64759403
113 Z	-2 +.56788074	201RX		12149032
114RY	-3 58230963	202RY		59514164
114RX	-216419407	202RX		10485621
114 Z	-2 +.24357952	202 Z		+.20761655
115RY	-360352242	203RY		61485460
115RX	-2 +.15763146	203RX		14208567
115 2	-2 +.40329389	203 Z		23648766
116RY	-360628241	204R Y		61864796
116RX	-2 + .14343018	204RX		+.36923770
116 Z	-2 +.58731989 -356525872	204 Z		+.74907559
117RY 117RX	-3 +.98552745	208RY		64565829
	5	208RX		27973752

Contrails

TABLE 3	ROTATIONS AND	DEFLECTIONS - H	PINNED CASE (CONTINU	ED)	
208 Z	-3	+.26721636	261RX	-2 +.5214	3168
209RY		75433048	261 Z	-2 +.3398	6681
209RX		+.77490611	268RY	-34607	9500
209 Z		+.21200754	268RX	-25588	3835
213RY	-3	80056968	268 Z	-2 +.3283	4739
213RX	-2	10118558	269RY	-33419	1876
213 Z	-2	+.14836553	269RX	-2 +.5367	5856
214RY	-3	75108536	269 Z	+2 +.2229	4201
214RX	-2	+.15304324	276RY	-35387	
214 Z		+.35044945	276RX	-25768	
220RY		81378595	276 Z	-2 +.2030	
220RX		18162990	277RY	-34800	
220 Z		+.28310174	277RX	-2 +.5362	
221RY		70474838	277 Z	-2 +.1005	
221RX		+.22572339	286RY	-37223	
221 Z		+.46028554	286RX	-25750	
226RY		78061163	286 Z	-3 +.9104	
226RX		25544239	287RY	-37290	
226 Z		+.39401040	287RX	-2 +.5162	
227RY		63165675	296RY	-21051	
227RX		+.29207156	296RX	-2 -5526	
227 Z		+.53126081	297RY	-3 -, 9455	
232RY		71861664	297RX 297 Z	-2 +.4788	
232RX		32509736	297 Z 306RY	-21323	
232 Z		+.47358515	306RX	-25182	
233RY		54329042 +.35265288	306 Z	-31935	
233RX 233 Z		+.56651571	307RY	-21094	
238RY		64427326	307RX	-2 +.3790	
238RX		38787092	307 Z	-4 - 4239	
238 Z		+.51160388	314RY	-21433	
239RY		45065335	314RX	-24607	
239RX		+.40680815	314 Z	-47069	
239 Z		+.55501044	315RY	-21537	4946
246RY		56854842	315RX	-2 +.2480	7035
246RX	-2	- 44365730	315 Z	-2 +.2178	5628
246 Z	-2	+.51549821	322RY	-21596	2569
247RY	-3	36536874	322RX	-23434	
247RX	-2	+.45674087	322 Z	-2 +.1473	
247 Z	-2	+.52256525	323RY	-22509	
252RY		50407526	323RX	-2 +.1161	
252RX	-2	49065028	323 Z	-2 +.6272	
252 Z		+.47163452	324RY	-23288	
253RY		31104715	324RX	-3 +.4096	
253RX		+.49342390	324 Z	-2 +.9437	
253 Z		+.43738387	325RY	-2 3396	
260RY		46215428	325RX	-4 +.7913	
260RX		52940942	325 Z	+1 +.1071	
260 Z		+.41232772	326RY	-23540	
261RY	- 3	29476332	326RX	-32457	0000

TABLE 3	ROTATIONS AND DEFLECTIONS - PINNED CASE (CONTINUED)
326 Z	-1 +.11245380
327RY 327RX	-236938127 -356045034
327 Z 328RY	-1 +.11001143 -231767382
328RX 328 Z	-398896342 -2 +.85973899
329RY 329RX	-222434835 -219804522
329 Z	-2 +.48608930
*	
	158

TABLE 4	ROTATIONS AND DEFLECTIONS - F	IXED CASE	RY = $\Theta_y$ - RADIANS
	Pressure = 4.3 psi		$RX = \Theta x - RADIANS$
			$Z = \Delta Z - INCHES$
IODE	EDOM	NODE FREEDOM	
1RY 1rx	-395399749	18RY	-374157756
2R Y	-579689990	18RX 18 Z	-491096547
2RX	-393058870	19RY	-2 + .30975214
2 2	-430525402 -3 +.20156564	19RX	-371027529
3RY	-393157497	19 Z	-315418230 -2 +.29437892
3RX	-4 +.14182351	20RY	-360317158
3 Z	-3 +.17621992	ZORX	-322262791
4RY	-386296415	20 Z	-2 +.27426890
4RX	-542780251	21RY	-3 42865405
4 Z	-3 +.79556379	21RX	-3 +.33078446
5RY	-3 90065696	21 Z	-2 +.36706737
5RX	-4 +.13582426	22RY	-356138557
5. Z	-3 +.80290130	22RX	-3 +.20759720
6RY	-391557047	22 2	-2 +.40098663
6RX	-580484200	23RY	-359925816
6 Z	-3 +.79804663	23RX	-3 +.10247112
7RY	-390134364	23 Z	-2 +.41436728
7RX	-4 29981052	24R¥	-360307090
7 Z	-3 +.76853149	24RX	-312282882
8RY	-386757003	24 Z	-2 +.40871488
8R X	-5 86261377	25RY	-357187177
8 Z	-3 +.72774473	25RX	-322509494
9RY	-373470877	25 Z	-2 +.38875596
9R X	-4 +.99458392	26RY	-344359216
9 Z	-2 +.19518753	26RX	-334238141
10RY	-384440306	26 Z	-2 +.34919386
10RX	-4 +.42889759	27RY	-325039452
10 Z	-2 +.20557820	27RX	-3 +.47076178
11RY	-385587845	27 Z	-2 + 41240133
11RX	-576986401	28RY	-340536900
11 Z	-2 +.20580354	28RX	-3 +.26705374
12RY	-384715978	28 Z	-2 +.47167335
12RX	-458368794	29RY	-3 43794745
12 Z	-2 +.20148593	29RX	-3 +.13152021
13RY	-374113403	29 Z	-2 +.49098235
13RX	-310610203	30RY	-3 44349532
13 Z	-2 +.18616260	30RX	-315409500
14RY	-359638211	30 Z	-2 +.48604375
14RX	-3 +.20974969	31RY	-341402874
14 Z	-2 +.29287463	31RX	-3 28744833
15RY	-370676172	31 Z	-2 + .46288020
15RX	-3 +.14143878	32RY 32RX	-326950181 -348300926
15 Z	-2 +.30832730	32 Z	-2 +.39768868
16RY	-373838777	33RY	-470854083
16RX	-4 +.76172529	33RX	-3 +.60518884
16 Z	-2 +.31656394	33 Z	-2 +.42656231
17RY	-375283040 -582662610	34RY	-323931535
17RX			

ROTATIONS AND DEFLECTIONS - FIXED CASE (Continued) TABLE 4 51RX -3 -.65141184 -2 +.51875354 34 Z 51 Z -2 +.48805492 -3 -.27330471 35RY 52RY -3 +.21705140 -3 +.16056428 35RX -3 -.90671860 52RX -2 +.54264179 35 Z 52 Z -2 +.35985409 -3 -.27751803 36RY 53RY -3 +.34819015 -3 -.18432819 36RX 53RX -2 +.10653785 -2 +.53913758 36 Z 53 Z -2 +.29624968 -3 -.24886867 37RY 54RY -3 +.19780194 -3 -.35228061 37R X 54RX -3 +.90024611 37 Z -2 +.51165842 54 Z -2 +.39464671 -4 -.91418547 38RY -3 +.14656964 55RY 38R X -3 -.61906225 55RX -3 +.71686572 38 Z -2 +.41425317 55 Z -2 +.47658605 39RY -3 +.10795766 56RY -4 + 77661927 -3 +.74453524 39RX 56R X -3 +.24491154 -2 +.40786825 39 Z 56 Z -2 +.57404824 -4 -.50156996 40RY 57RY -4 +.73989791 40RX -3 +.56572200 57RX -3 -.26553606 40 Z -2 +.49466316 57 Z -2 +.57237999 -4 -.92499468 41RY 58RY -3 +.13355034 -3 +.39078115 41RX 58RX -3 -.72451464 41 Z -2 +.54268547 58 Z -2 +.47333770 -3 -. 12234798 42RY 59RY -3 +.18069495 -3 +.18984875 42RX 59RX -3 -. 89907983 -2 +.57162420 42 Z -2 +.39205871 59 Z -3 -.12748392 43RY -3 +.31723509 60RY 43RX -3 -.21300316 60RX -2 -.10477657 -2 +.56863010 43 Z 60 Z -2 +.29889563 44RY -3 -.10317546 61RY -3 +.38308025 -3 -.41062566 44RX 61RX -2 +.12130981 -2 +.53697268 44 Z 61 Z -2 +.21376813 -4 -.66838596 45RY -3 +.22250625 62RY -3 -.58042900 45RX 62RX -3 +.99300286 45 Z -2 +.48674079 62 Z -2 +.36245561 -4 +.79274812 46RY 63RY -3 +.17111548 -3 -.74992652 46RX 63RX -3 +.78093287 46 Z -2 +.40067327 63 Z -2 +.45222543 47RY -3 +.24899802 -3 +.11295719 64RY -3 +.91067032 47RX -3 +.26865569 64RX 47 Z -2 +.36535954 64 Z -2 +.55858219 **48RY** -4 +.64964136 -3 +.11093550 65RY 48R X -3 +.63855361 65RX -3 -.28701128 -2 +.49361212 48 Z -2 +.55723465 65 Z -5 -.28184712 49RY -3 +.16561666 66RY -3 +.22026676 49RX -3 -.78581393 66RX -2 +.58046151 49 Z 66 Z -2 +.44989712 -5 -.76072481 **50**RY 67RY -3 +.21419226 -3 -.24241437 50RX 67RX -3 -.98758332 -2 +.57816043 50 Z 67 Z -2 +.36110332 **51RY** -4 +.48662954

TABLE 4 ROTATIONS AND DEFLECTIONS - FIXED CASE (Continued) 84 Z -2 +.31117350 -3 +.35769393 68RY 85RY -4 +.36024119 -2 -.11871152 68R X 85RX -2 -.12895827 68 Z -2 +.22060533 -2 +.19505480 85 Z 69RY -3 +.32906450 86RY -3 +.12501004 69RX -2 +.13616048 86RX -2 -.14178349 69 Z -2 +.12663122 86 Z -3 +.43818525 70RY -3 +.17380125 87RY -3 -.12711160 -2 +.10704354 70RX 87RX -2 +.15010656 70 Z -2 +.33075313 88RY -3 -.13653978 71RY -3 +.13688726 88RX -2 +.13201073 71RX -3 +.83853635 88 Z -2 +.19637168 -2 +.42698085 71 Z 89RY -3 -.11263511 72RY -4 +.94369470 89RX -2 +.11110460 72RX -3 +.28869615 89 Z -2 +.31857062 72 Z -2 +.54064692 90RY -4 -.90711373 -4 +.92339458 73RY 90RX -3 +.86730955 73RX -3 -.30374092 90 Z -2 +.41591587 73 Z -2 +.53936189 91RY -4 -.72609993 74RY -3 +.13153597 91RX -3 +.30492329 -3 -.84146753 74RX 91 Z -2 +.53375066 74 Z -2 +.42427547 92RY -4 -.87421608 75RY -3 +.16739727 92RX -3 -.29683897 75RX -2 -. 10617942 92 Z -2 +.53470474 75 Z -2 +.32875009 93RY -3 -.13025157 76RY -3 +.30272141 93RX -3 -.85255049 -2 -.13318396 76RX 93 Z -2 +.41941629 76 Z -2 +.12452557 94RY -3 -.16157232 77RY -3 +.16988413 94RX -2 -.10921892 -2 +.14616502 77RX 94 Z -2 +.32197502 -3 +.47159345 77 Z 95RY -3 -.19344274 -4 +.66509617 78RY 95RX -2 -.12775642 78RX -2 +.13199035 -2 +.20792220 95 Z 78 Z -2 +.18859123 96RY -3 -. 22320398 79RY ~4 +.55244975 96RX -2 -.14309760 79RX -2 +.11271656 -3 -.42568345 97RY 79 Z -2 +.31176669 97R.X -2 +.14790102 -4 +.42504887 80RY 97 Z -4 -.42552099 -3 +.87326893 80RX 98RY -3 -.31425910 80 Z -2 +.41211760 98RX -2 +.12449073 81RY -4 +.26321178 98 Z -2 +.22887764 -3 +.30134666 81RX 99RY -3 -.25408918 81 Z -2 +.53015963 99RX -2 +.10523429 82RY -4 +.19468759 99 Z -2 +.34432211 -3 -. 30915359 82RX 100RY -3 -.20968188 -2 +.52933691 82 Z 100RX -3 +.82727623 83RY -4 +.23375014 -2 +.43885583 100 Z -3 -.87042358 83RX -3 -.17005658 101RY -2 +.41068475 83 Z 101RX -3 +.30120150 -4 +.31920374 84R Y 101 Z -2 +.55224593 -2 -. 11142613 84RX

TABLE 4	ROTATIONS AND DEFLECTIONS -	FIXED CASE	(Continued)
102RY 102RX	-319034770 -326891086	118 Z 119ry	-2 +.63344082 -339477293
102 Z	-2 +.55568197	119RX	-319306829
103RY	-326308711	119 Z	-2 +.64339842
103RX	-379706541	120RY	-3 47260729
103 Z	-2 +.44877859	120RX	-363684074
104RY	-332046528 -210207467	120 Z	-2 +.56029441 -360324843
104RX	-2 +.35783415	121RY 121RX	-395939975
104 Z 105RY	-3 38632891	121 Z	-2 +.40364167
105RX	-211993646	122RY	-384365233
105 Z	-2 +.25124997	122RX	-2 11716590
106RY	-353207751	122 Z	-2 +.18600349
106RX	-213683681	123RY	-373448214
106 Z	-3 +.13133920	123RX	-3 +.96237187
107RY	-360755492	123 Z	-2 +.46184269
107RX	-2 +.13904404	124RY	-371334924
107 2	-3 +.69111637	124RX	-3 +.61043558
10BRY	-341875998	124 Z	-2 +.66180489
108RX	-2 +.11445198	125RY	-3 66384828
108 Z	-2 + .28430631	125RX	
109RY	-330563332 -3 +.77486975	125 Z 126RY	-2 +.76838745 -368568933
109RX 109 Z	-2 +.47715542	126RX	-497148760
110RY	-3 26732493	126 Z	-2 +.79671528
110RX	-3 +.29588217	127RY	-376802809
110 Z	-2 +.58537698	127RX	-3 45250329
111RY	-329004101	127 Z	-2 +.74792722
111RX	-323188165	128RY	-384701058
111 Z	-2 +.59181568	128RX	-378710416
112RY	-3 37192404	128 Z	-2 +.59118946
112RX	-372127184	129RY	-387817168
112 Z	-2 +.49660626	129RX	-2 10074193
113RY	-351334081 -210823735	129 Z	-2 +.38294418
113RX	-2 +.31956082		
113 Z 114RY	-373064109		
114RX	-2 12896709		
114 Z	-3 +.66033475		
115RY	-369489340		
115RX	-2 +.12428589		
115 Z	-2 +.21642043		
116RY	-352421848		
116RX	-2 +.10366528		
116 Z	-2 +.35357168		
117RY	-341601539		
117RX	-3 +.71665998 -2 +.53098116		
117 Z	-337665292		
118RY 118RX	-3 +.29100445		
TIOUN	3		
	······································		

## Glass Bending Moments and Shear

Bending moment patterns in the glass pane for  $M_X$  and  $M_Y$  when subjected to a uniform air load are shown on page 165. Ordinates of the moment diagrams are drawn slanting upward and to the left when moment is positive. Plate element bending moments are positive if tension is produced in the outside fiber (relative to glider).

Contrails

Bending moments for plate elements for a uniform air load of 4.3 psi acting in the + z-direction are presented on page 167.

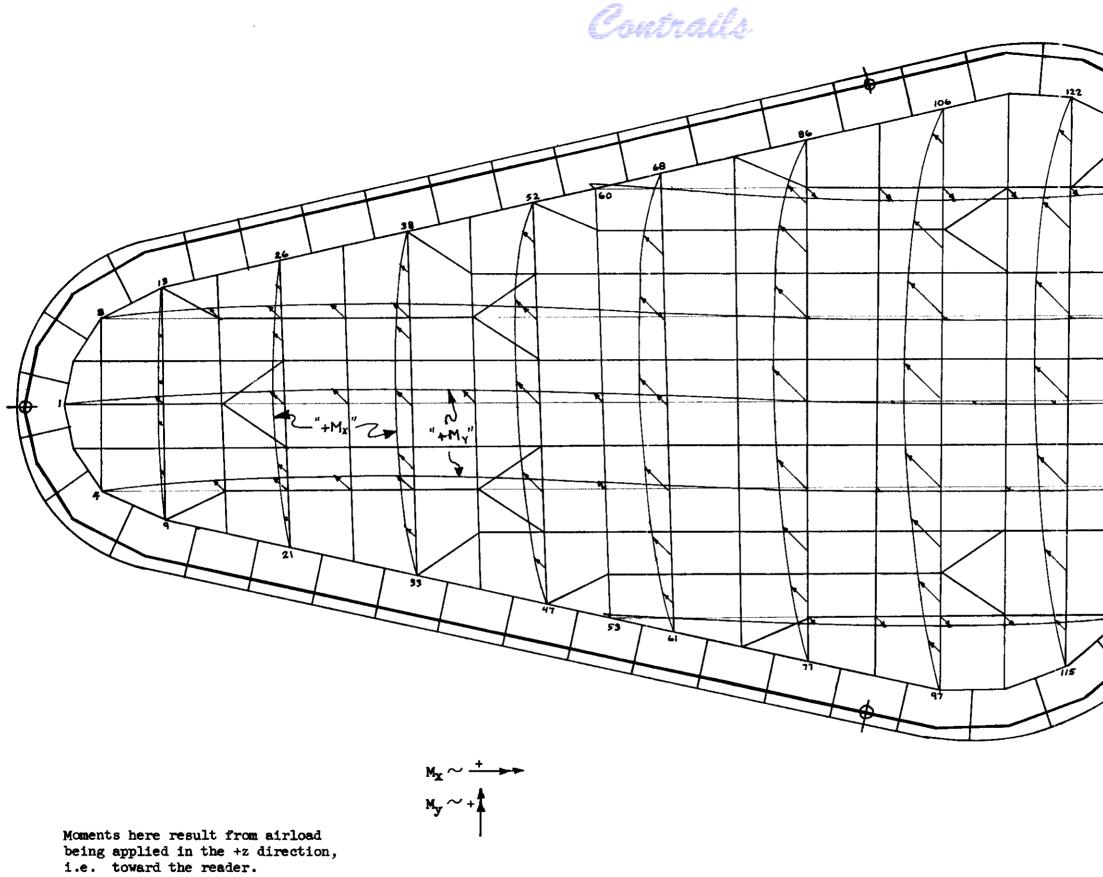
To obtain glass bending moments for the boost ultimate net pressure of 10.5 psi, multiply by 2.442. Glass bending stress is 14.2 x moment. Glass rebate bending stress is 2.085 x glass bending stress.

Contrails

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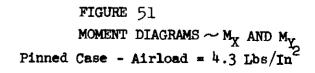
.

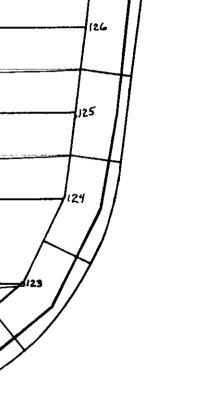
`



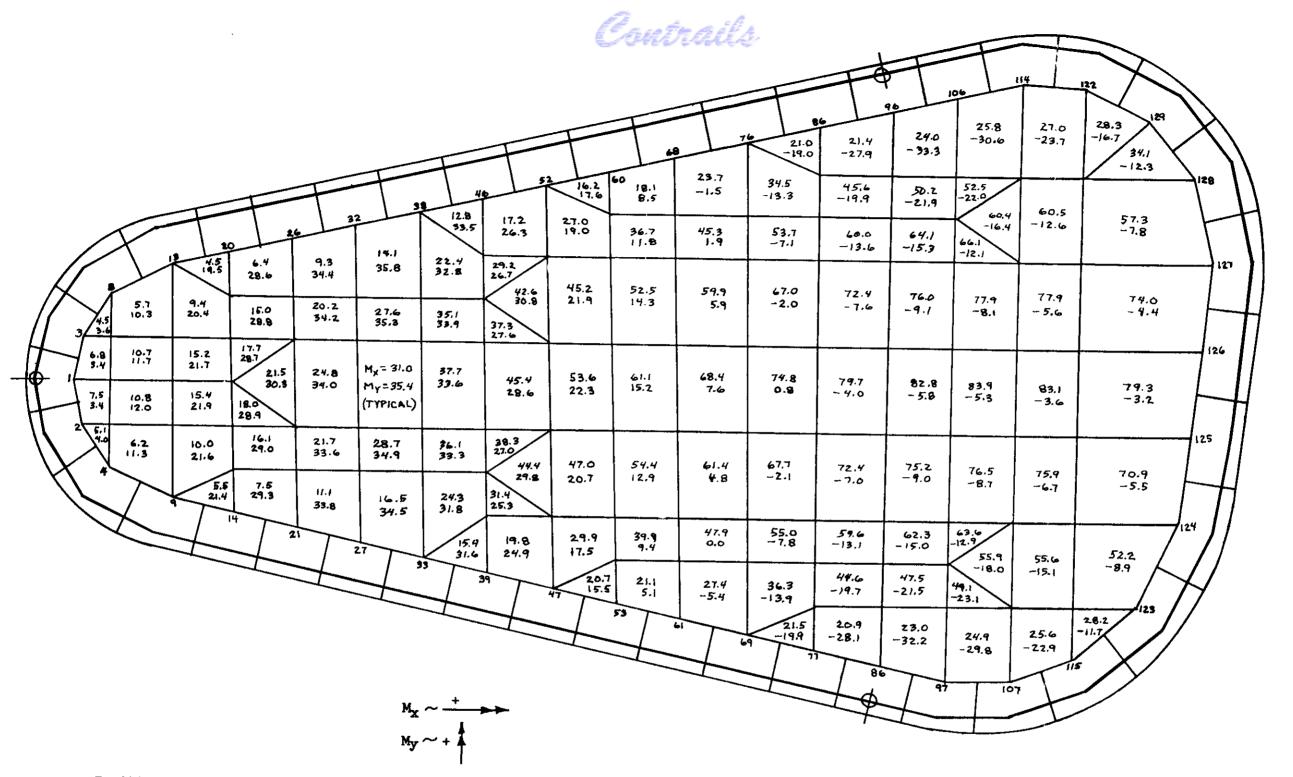
i.e. toward the reader. Positive moments result in tension in the glass on the side toward the reader.

165





128



Positive  $M_x$  produces tension in the outer surface Positive My produces tension in the outer surface Glass stress = 14.2 x moment Rebate stress = 2.085 x glass stress

FIGURE 52

MOMENTS  $M_x$  AND  $M_y \sim IN.LBS/IN$ . Pinned Case - Airload = 4.3 Lbs/In<sup>2</sup>

Glass Out-of-Plane Shear

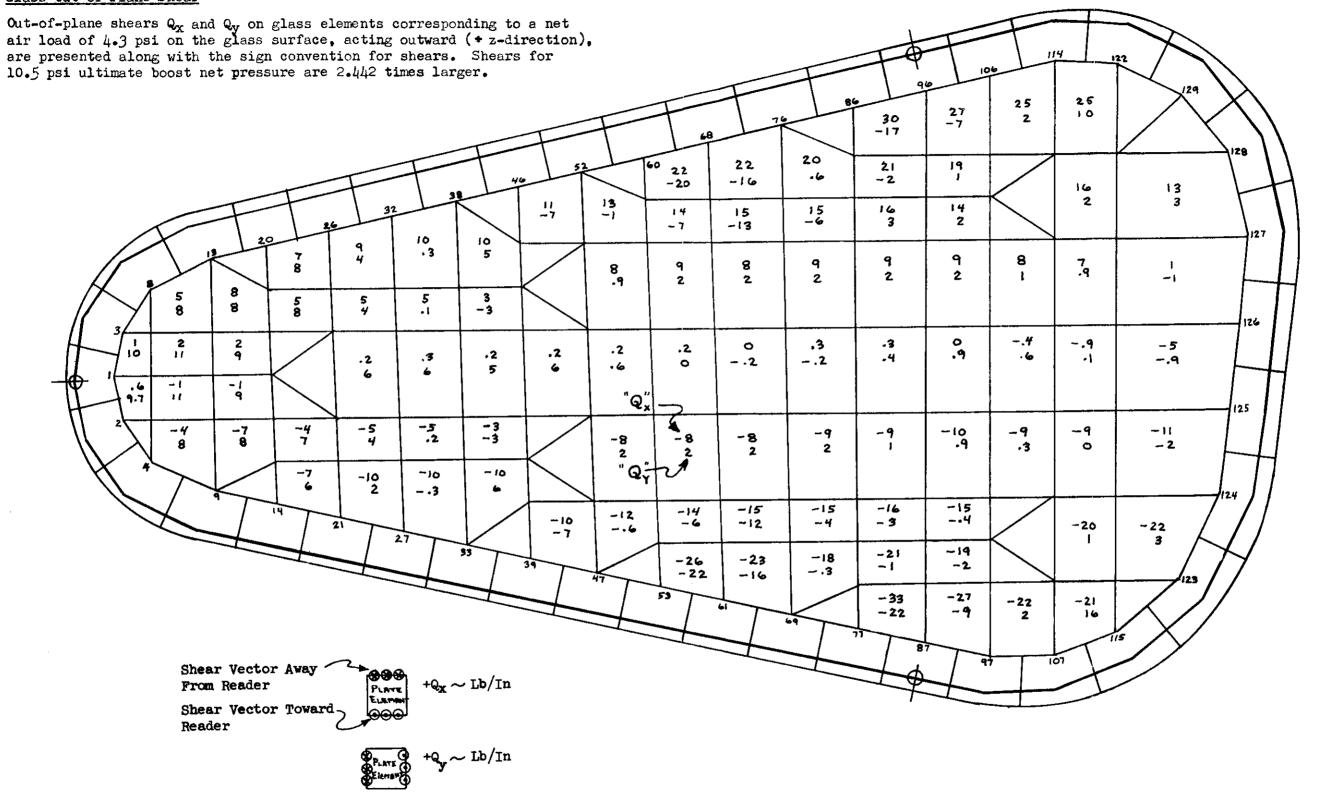
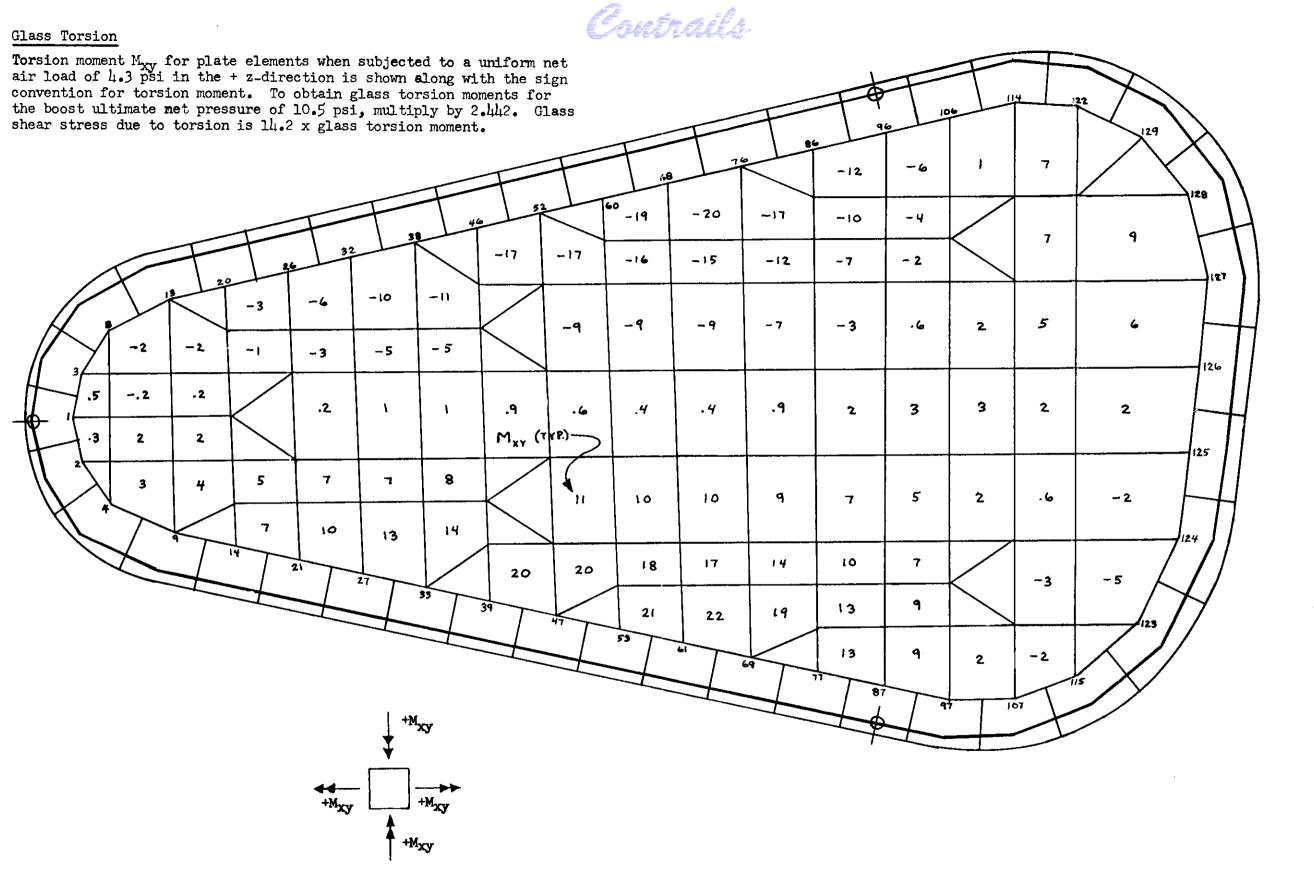


FIGURE 53 OUT-OF-PLANE SHEAR ON PLATE ELEMENTS Pinned Case - Airload = 4.3 Lbs/In<sup>2</sup>



Torsion on Plate Elements  $\sim In.Lb/In$ .

FIGURE 54 MOMENT  $M_{xy}$  (TORSION) ON PLATE ELEMENTS Pinned Case - Airload = 4.3 Lbs/In<sup>2</sup>

Contrails

Window Frame Bending Moment and Shear Bending moments and shears in the side window frame for  $\mu$ .3 psi net air load acting outward on the window are shown together with the moment and shear sign convention. Maximum bending moments and shears, occurring during boost when a net air load of 10.5 psi boost is applied to the window, may be obtained by multiplying by 2.442. +593 550 86 +223 -271 Bending Moment 512 (Typical Location) BENDING MOMENT Shear (Typical Location) 35 BENDING MOMEN 495 żΰ 548 569 31 -555 Z SHEAR **+V** (Shear) 238 Node "b" 767 +M\_ (Bending Moment) +115 Node "a" +V (Shear) (Bending Moment) Y

> Node "b" is always counterclockwise around the frame from node "a". Bending moments are written at nodes. Shear is written between nodes.

> > 173 Approved for Public Release

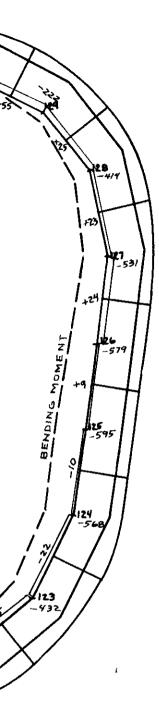


FIGURE 55 WINDOW FRAME SHEAR AND BENDING MOMENT Pinned Case - Airload =  $4.3 \text{ Lbs/In}^2$ 

Contrails

# Seal Loads

The seal and seal spring stiffness is simulated by the spar elements as discussed on page 142. The axial loads in the spar elements represent the load transferred from the glass to the frame.

Spar element axial loads are tabulated below. Axial load in a spar is positive when the spar is subjected to tension. See page 143 for a pictorial representation of the spar element.

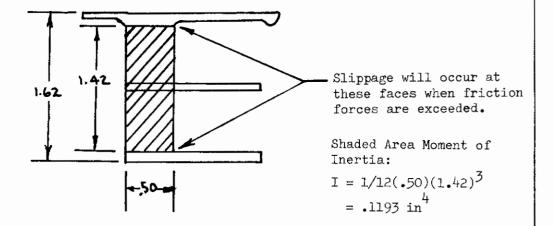
Spar Node Numbers	Axial Load	TABLE 5	Spar Node Numbers	Axial Load
1-201	16.5		86-286	58 <b>.</b> 5
2-202	19.2		87-287	64.7
3-203	19.8		96-296	67.2
4-204	24.9		97-297	72.7
8-208	26.3		106-306	67.2
9-209	26.5		107-307	68.7
13-213	28.6		114-314	69.7
14-214	23.0		115-315	51.6
20-220	22.6		122-322	58.9
21-221	21.8		123-323	23.2
26-226	21.8		124-324	11.7
27-227	22.4		125-325	19.2
32-232	21.8		126-326	15.1
33-233	23.1		127-327	0
38-238	23.4		128-328	2.1
39-239	27.1		129-329	29.4
46-246	25.2			
47-247	27.2			
52-252	30.5			
53 <b>-</b> 253	34.1			
60-260	34.2			
61-261	39.6			
68-268	39.5			
69-269	46.1			
<b>7</b> 6-276	49 <b>.7</b>			
77-277	55.4			

Contrails

#### STRESS ANALYSIS

#### FRAME SECTION

The frame section is not stress critical but is deflection critical. This is because small deflections can lead to high stresses in the glass. The 3/16 inch diameter frame clamping bolts in Class I holes do not develop sufficient friction between the frame elements to prevent unwanted shear slippage. The internal frame elements are riveted together with 1/4 inch diameter Rene' 41 rivets to provide shear continuity.



The 3/16 inch diameter clamping bolts and counterbores for the 1/4 inch diameter rivets reduce the stiffness of the frame section by 4%. The flanges (outer fairing and inner back-up strip) are only partially effective in bending because of the Class I holes. Using the effectiveness based on flange friction with bolts torqued to 20-25 inch-pound torque (700 pounds/ bolt) and  $\mathcal{M} = .40$  gives an increase in stiffness of 25%.

FINAL FRAME MOMENT OF INERTIA

I = .1193 x .96 x 1.25 = .1432 inch<sup>4</sup> (Computer Analysis used .1397)

FRAME TORSIONAL STIFFNESS

 $J_{a} = a b^{3} \left[ \frac{16}{3} - 3.36 \frac{b}{a} \left( 1 - \frac{b^{4}}{12a^{4}} \right) \right] = .04606 \text{ inch}^{4}$ 

STRESS ANALYSIS (Continued)

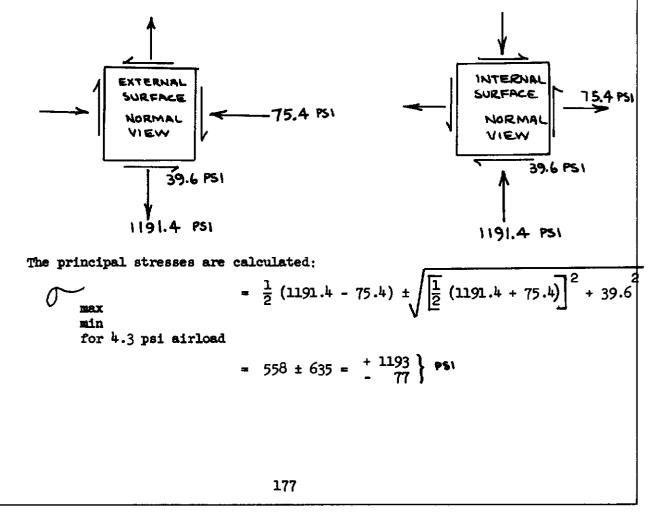
GLASS SECTION

The high stress condition for the center of the glass occurs when the glass edges are supported on knife edges, i.e. pinned case.

Using the results from the digital solution the critical stress element at the plate center is 102-101-111-110.

For 4.3 psi outward acting this plate element has the following stresses, from the digital solution:

Stress elements for external and internal surfaces:



STRESS ANALYSIS (Continued) GLASS SECTION (Continued) For 10.5 psi airload:  $\sim$ = 5800 psi Allowable in Bending  $= \frac{5800}{1193 \times \frac{10.5}{4.3}} - 1 = .991$ M.S. Max Stress Theory Examine the stress in the rebate - pinned boundary. The shear to rebate is maximum at elements 87-97-107 2 beams -1.02"  $=\frac{72.7\#}{1.5.1n}$  = 48.47#/in for 4.3 psi or = 48.47 x 2.442 = 118.4#/in for 10.5 psi The bending stress, using a stress concentration factor of 1.2, is:  $= \frac{118.4 \times 6 \times 1.2}{1 \times 45^2} = 4209 \text{ psi}$ Realistically, the force  $\vee$  will act at 2/3 of 1.02 or .68 inch =  $\frac{2}{3} \times 4209 = 2803$  psi (does not include installation stress) It is noted that rebate is critical since installation stresses are largest in the rebate area and are unknown.

Contrails

### APPENDIX II ·

# WINDOW SEAL AND SPRING TESTS

Contrails

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### II. WINDOW SEAL AND SPRING TESTS

#### PURPOSE

The purpose of these tests was to obtain stress relaxation and load-deflection data for one window seal configuration.

#### TEST SPECIMENS

Test 1: Two foil-jacketed "Hastelloy-X" mesh seals (per Drawing 25-86203-1) and one 5-leaf Rene' 41 spring (per Drawing 25-83879-1), all three inches in length.

Test 2: One foil-jacketed "Hastelloy-X" mesh seal, three inches in length (per Drawing 25-86203-1).

Test 3: One "Hastelloy-X" mesh seal with no jacket, three inches in length (per Drawing 25-83879).

#### INSTRUMENTATION

Specimen deflections were measured by recording the amount of head travel on the universal test machine.

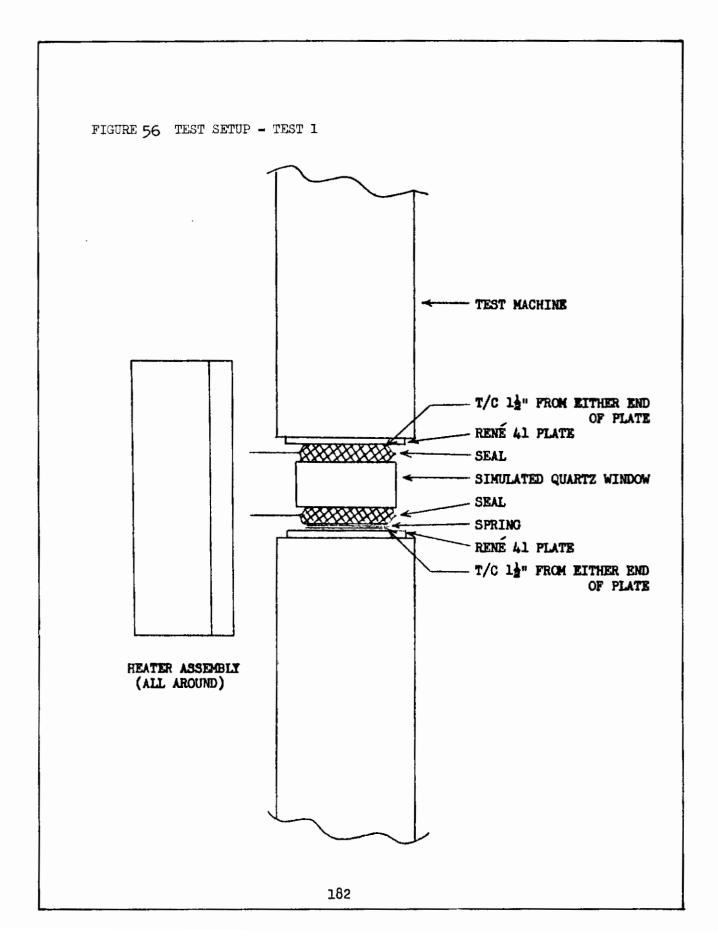
Specimen temperatures were measured using chromel-alumel thermocouples spot welded to the test specimen as shown in Figure 56 page 182.

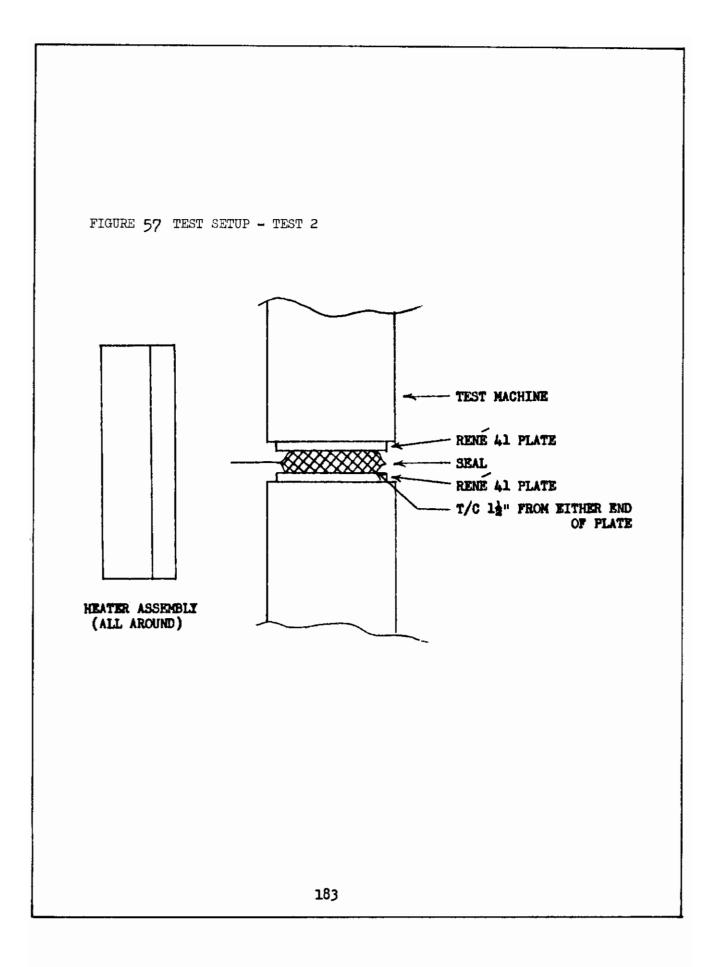
#### TEST SETUP

The test specimens were installed in a 120,000-pound Baldwin-Lima-Hamilton test machine. Refer to Figures 56, 57 and 58 for the test setup of each specimen.

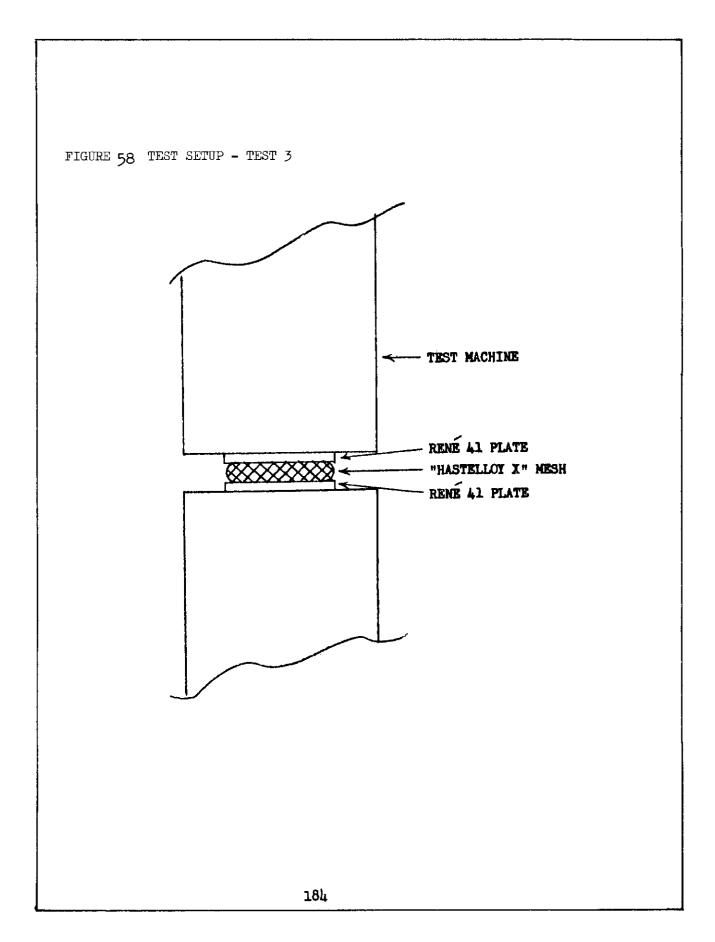
#### TEST PROCEDURE AND RESULTS

<u>Test 1</u>: The seal specimen was compressed at room temperature to a load of 90 pounds and a thickness of 0.28 inch was recorded. The load was then increased to 105 pounds and a thickness of 0.27 inch was recorded. The load was again increased to 220 pounds and a thickness of 0.22 inch was recorded. The specimen was unloaded and then compressed again to a thickness of 0.22 inch under a load of 225 pounds (refer to Figures 60 and  $6_{1}$ .) The heat cycle was then applied per Figure 59. The seal thickness was held constant and load decay was continuously recorded during the heat cycle (refer to Figure 61). Load and heat were removed and the seal thickness measured was 0.24 inch.

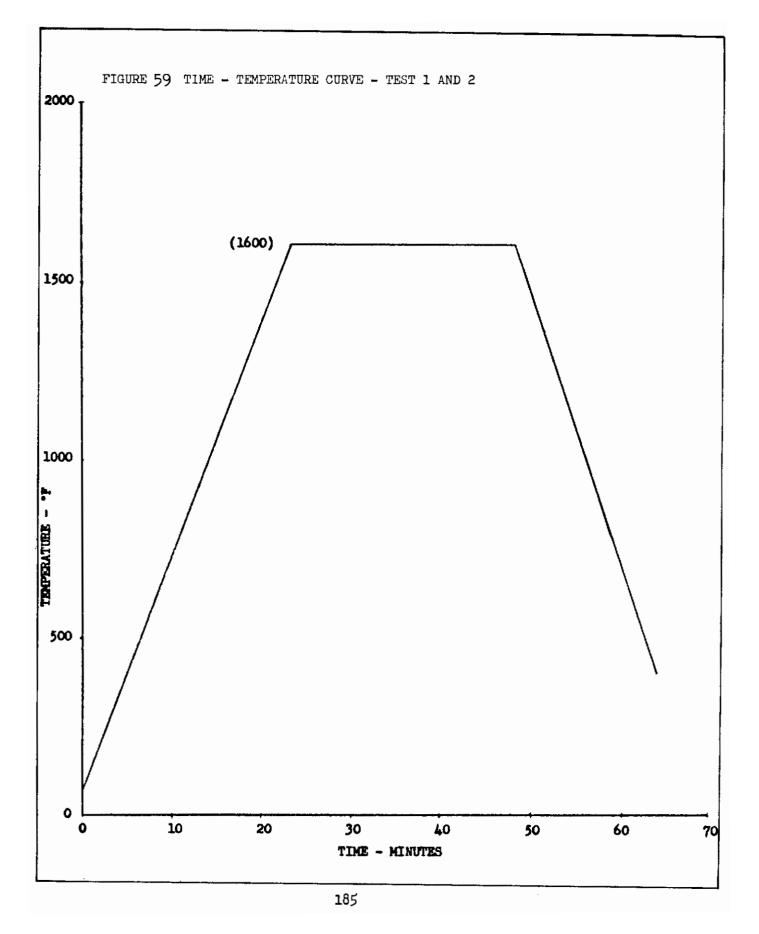




Contrails



Contrails



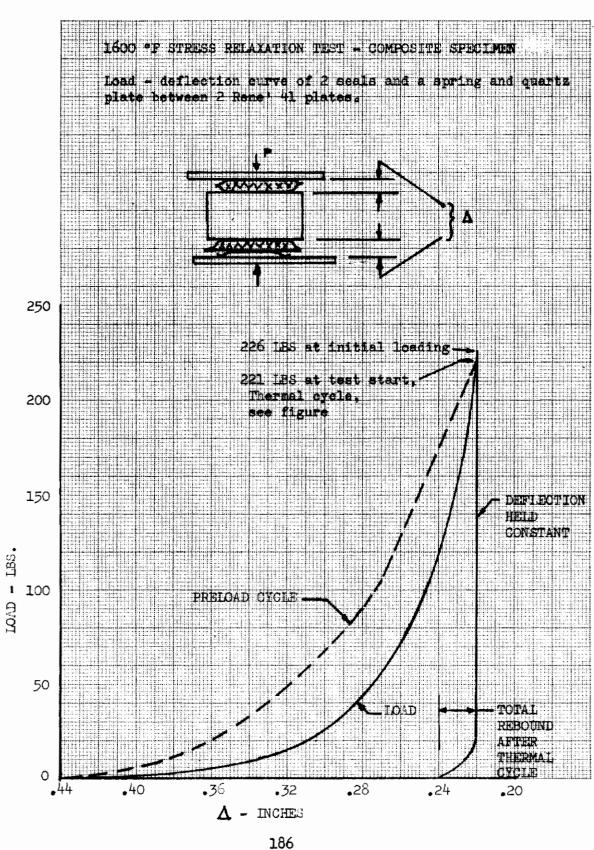
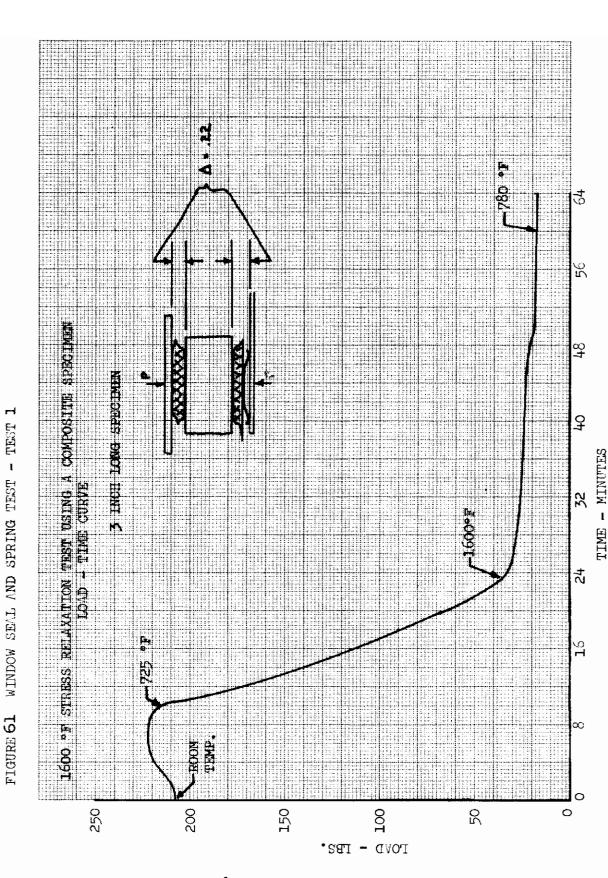


FIGURE 60 WINDOW SEAL AND SPRING TEST - TEST 1



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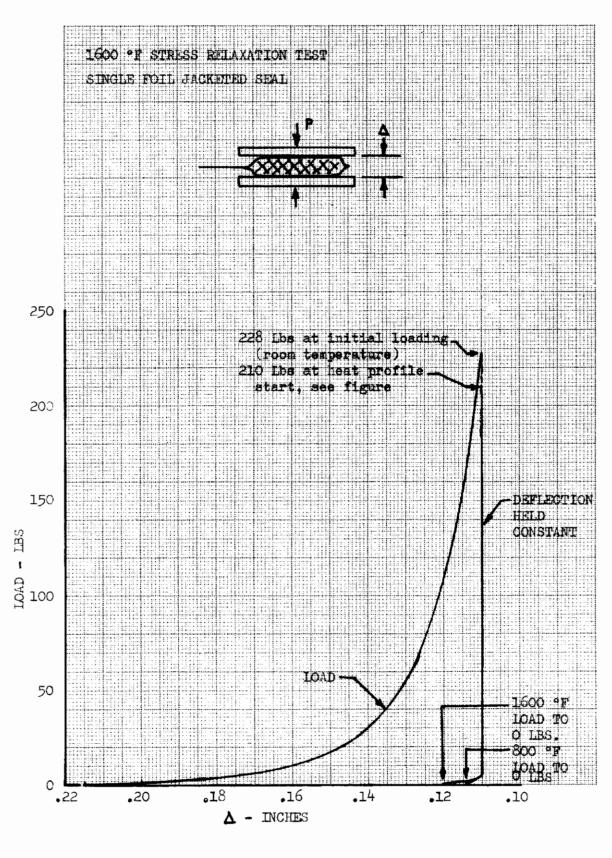


FIGURE 62 WINDOW SEAL AND SPRING TEST - TEST 2



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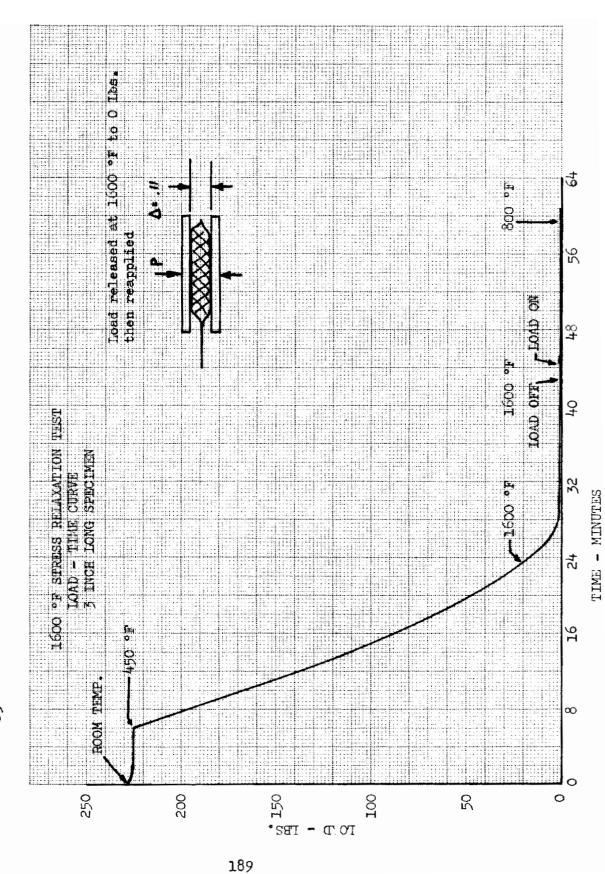


FIGURE 63 WINDOW SEAL AND SPRING TEST - TEST 2

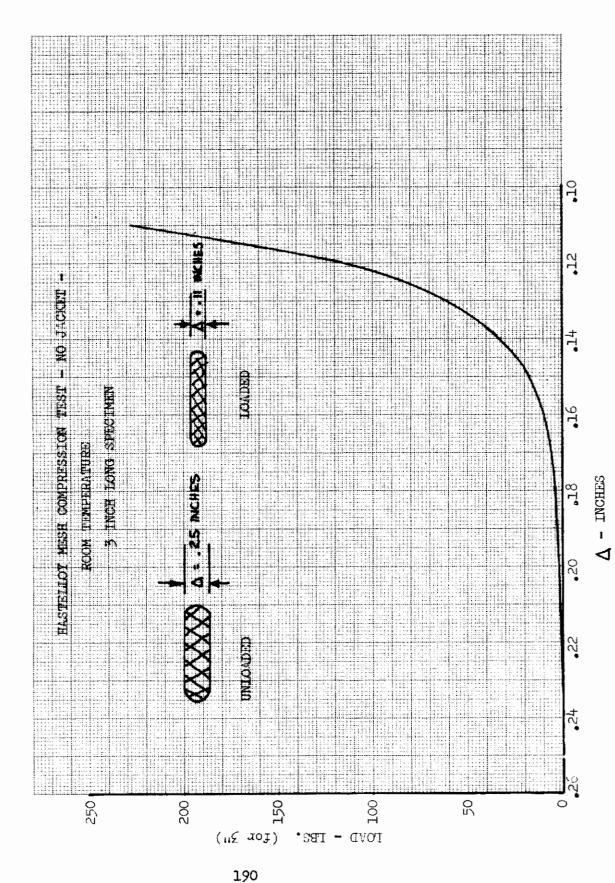
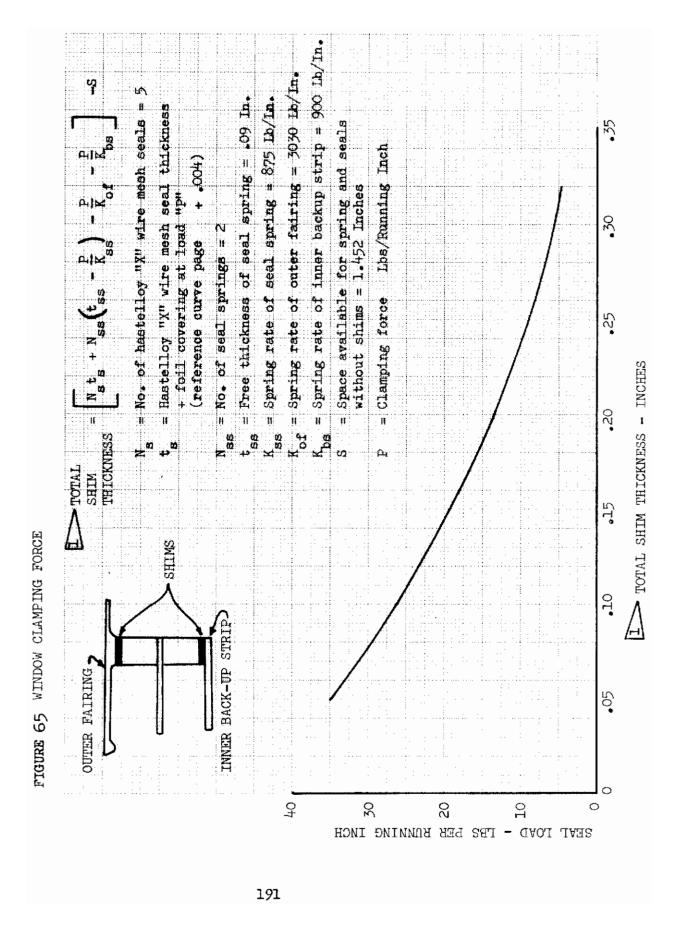


FIGURE 64 WINDOW SEAL AND SPRING TEST - TEST

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Contrails



TEST PROCEDURE AND RESULTS (Continued)

Test 2: The seal specimen was compressed at room temperature to a thickness of 0.11 inch at a load of 228 pounds. The load decayed to 210 pounds before heat was applied (see Figure 62 . With the thickness held constant at 0.11 inch, a heat cycle was applied (refer to Figure 59) and load decay continuously recorded (refer to Figure 63. After 15 minutes at  $1600^{\circ}$ F temperature, the load was reduced to 0 pounds and then reapplied until the seal thickness was 0.11 inch. The load was again reduced to 0 pounds when the heat cycle reached 800°F. The load was reapplied until the specimen was 0.11 inch thick again and the heat cycle was completed. Seal thickness after the load and heat were removed was 0.11 inch.

Contrails

<u>Test 3</u>: The test specimen was compressed at room temperature to a thickness of 0.11 inch and a load-deflection curve was recorded (refer to Figure 64).

#### CONCLUSION

Similar load-deflection data were obtained for all specimens at room temperature.

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# APPENDIX III

TEST DATA REDUCTION METHODS

Contrails

Contrails III. TEST DATA REDUCTION METHODS VERTICAL DEFLECTION COMPARISON Test data and analytic data were adjusted to the same reference for comparison as follows: 1. TEST DATA The vertical deflections were corrected for rigid body rotation.  $V_{\text{corrected}} = V - V_{\text{D}} + R_{\text{xx}}(\overline{Y}) + R_{\text{vv}}(\overline{X})$ V = Vertical deflection data - Inches  $V_{\rm D}$  = Vertical deflection at point D (DD6) - Inches  $R_{xx} = \frac{DA6 - DB6}{14.88}$  - Inches/Inch  $R_{yy} = \frac{DD6 - \frac{DA6 + DB6}{2}}{19.81} - Inches/Inch$  $\overline{X}$  = X-Distance from point D - Inches  $\overline{Y}$  = Y-Distance from point D - Inches 2. ANALYTIC DATA The vertical deflection at the node was corrected to the deflection gage.  $V = V_{\alpha} + Rd$  $V_{\alpha}$  = Vertical deflection from analysis - Inches R = Rotation - Inches/Inch (see page 50 ) d = Distance from node to point - Inches DEFLECTION GAGE which is then corrected for rigid body movement.  $V_{\text{corrected}} = V - V_{\text{D}} + R_{\text{xx}}(\overline{Y}) + R_{\text{yy}}(\overline{X})$ V = Vertical deflection at gage - Inches  $V_D = Vertical deflection at gage (point D) - Inches$  $<math>R_{xx} = \frac{V_A - V_B}{14.88}$  - Inches  $R_{yy} = \frac{V_D - \frac{V_A + V_B}{2}}{\frac{19.81}{2}} - Inches$  $\overline{X}, \overline{Y} = X$ - and  $\overline{Y}$ -Distance from point D - Inches

Contrails

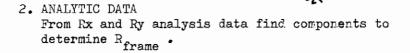
### ROTATION COMPARISON

Test data and analytic data were adjusted to the same reference for comparison as follows:

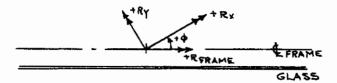
1. TEST DATA From  $D_1$  and  $D_2$  find  $R_{frame}$ .  $R_{frame} = \frac{D_1 + D_2}{T_1}$  - Radians.

which is then corrected for rigid body rotation.

 $R_{\text{frame corr.}} = R_{\text{frame}} - (R_{\text{xx}} \cos \phi - R_{\text{yy}} \sin \phi) - \text{PADIANS}$   $R_{\text{xx}} = \frac{DA6 - DB6}{14.7} - \text{RADIANS}$   $R_{\text{yy}} = \frac{DD6 - (\underline{DA6 + DB6})}{19.6} * \text{RADIANS}$ 



 $R_{frame} = Rx COS \phi - Ry SIN \phi - RADIANS$ 



Contrails THERMAL DEFLECTION COMPARISON Test data and analytic data were adjusted to the same reference for comparison as follows: 1. TEST DATA The vertical deflections were corrected for rigid body rotation. See page 195. 2. ANALYTIC DATA The vertical deflections were calculated based on the assumption that the window frame assumes a spherical shape of radius  $d/\Delta T \alpha$ . d = Frame depth - Inches  $\Delta T$  = Frame depth temperature gradient - °F  $\propto$  = Coefficient of thermal expansion of Rene! 41. Inch/Inch/°F With points A, B and D fixed at Z = 0, determind  $Z_{C}$ and  $\mathbf{Z}_{_{\mathbf{F}}}$  from the equation of a sphere:  $(X - h)^2 + (Y - k)^2 + (Z - 1)^2 = R^2$ where (h,k,1) is the center of the sphere.

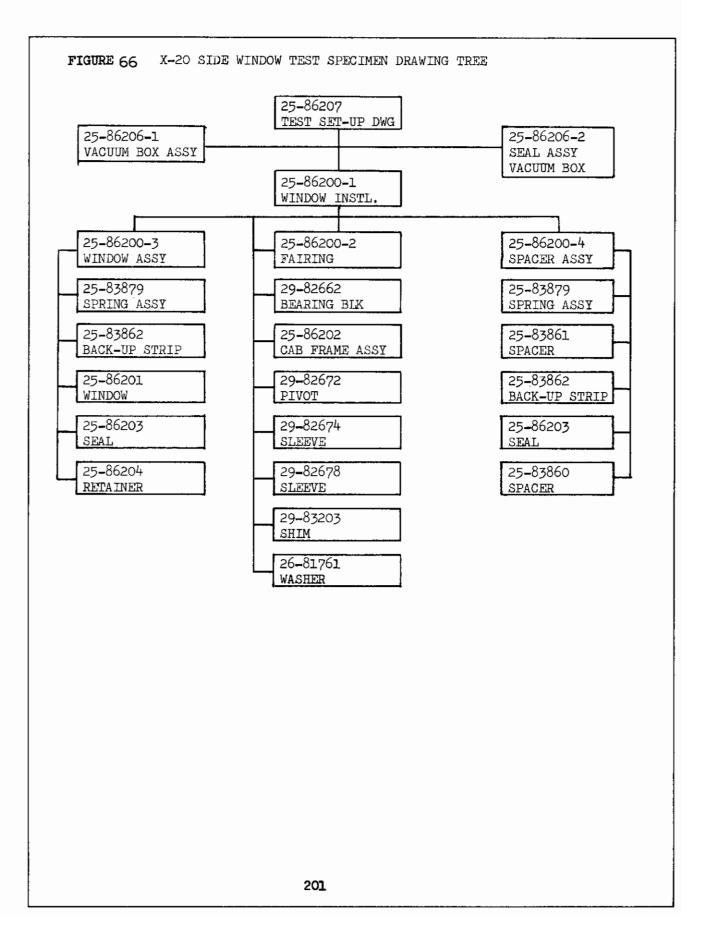
Crutrails GLASS THERMAL CURVATURE COMPARISON The allowable bending of the glass was compared with the extrapolated thermal deflection analysis assuming rigid seals and a spherical shape as follows: 1. ALLOWABLE BENDING OF THE GLASS The allowable radius of curvature of the glass  $R = \frac{C E}{F} = 588$ . Inches C = .325 Inches (half the thickness of the glass)  $E = 10.5 \times 10^6$  PSI (modulus of elasticity) f = 5800. PSI (allowable bending stress) and the allowable frame temperature gradient ( $\Delta$ T) was calculated  $\Delta T = d/R\alpha = 344$  °F d = 1.62 Inches (frame depth) R = 588. Inches (radius of curvature)  $\propto = 8 \cdot \times 10^{-6}$  Inches/Inch/°F (coeff. of expansion) (Rene' 41) The glass vertical deflection along the X-axis was calculated from the equation of a sphere. See figure 42 page 128 . 2. TEST DATA AT FAILURE The frame depth temperature gradient (AT) = 757 °F at the time of failure with a resultant radius of curvature  $R = d \Delta T = 289$ . Inches d = 1.62 Inches (frame depth)  $\Delta T = 757$ °F  $= 7.4 \times 10^{-6}$  Inches/Inch/°F (coeff. of expansion - Rene: 41) The glass vertical deflection along the X-axis was calculated from the equation of a sphere. See figure 42 page 128.

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### APPENDIX IV

# TEST SPECIMEN DRAWING LIST

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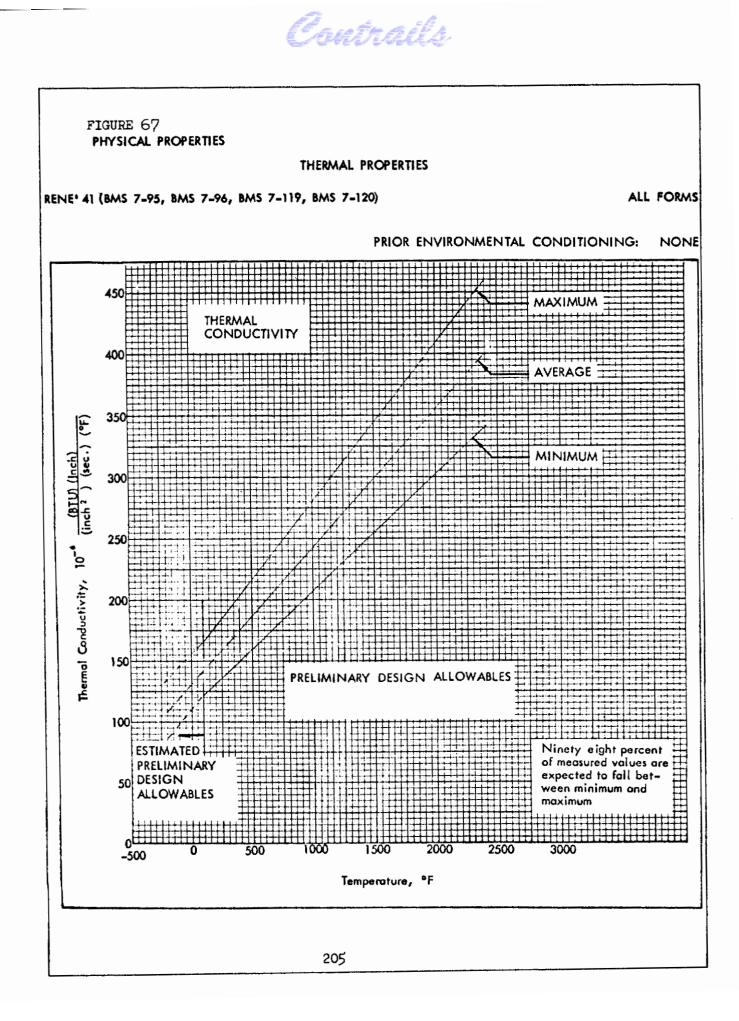
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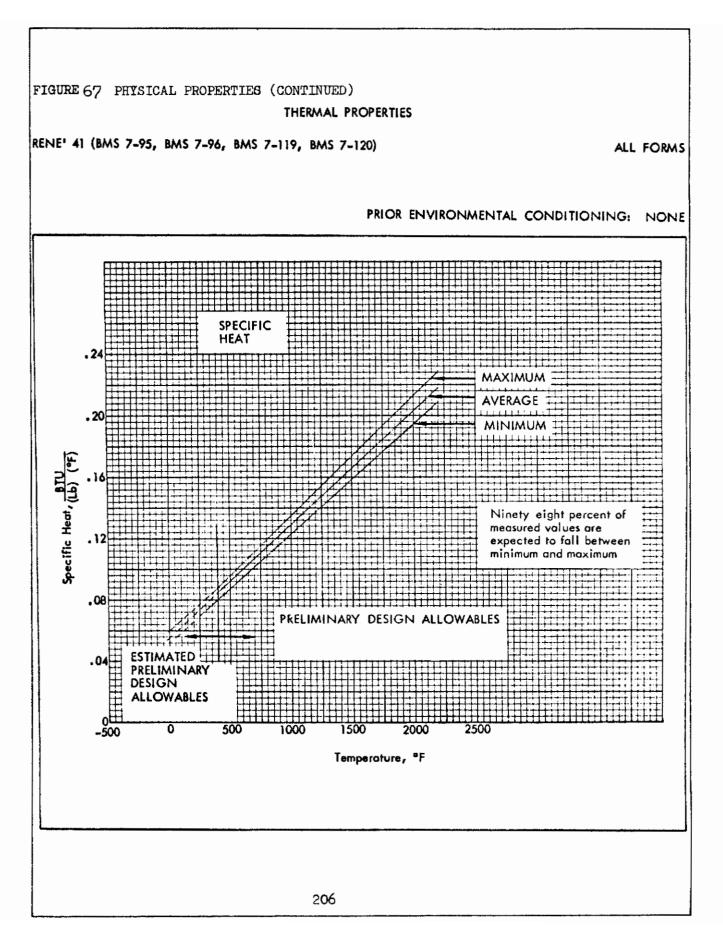
# APPENDIX V

# MATERIAL PROPERTIES AND ALLOWABLES DATA

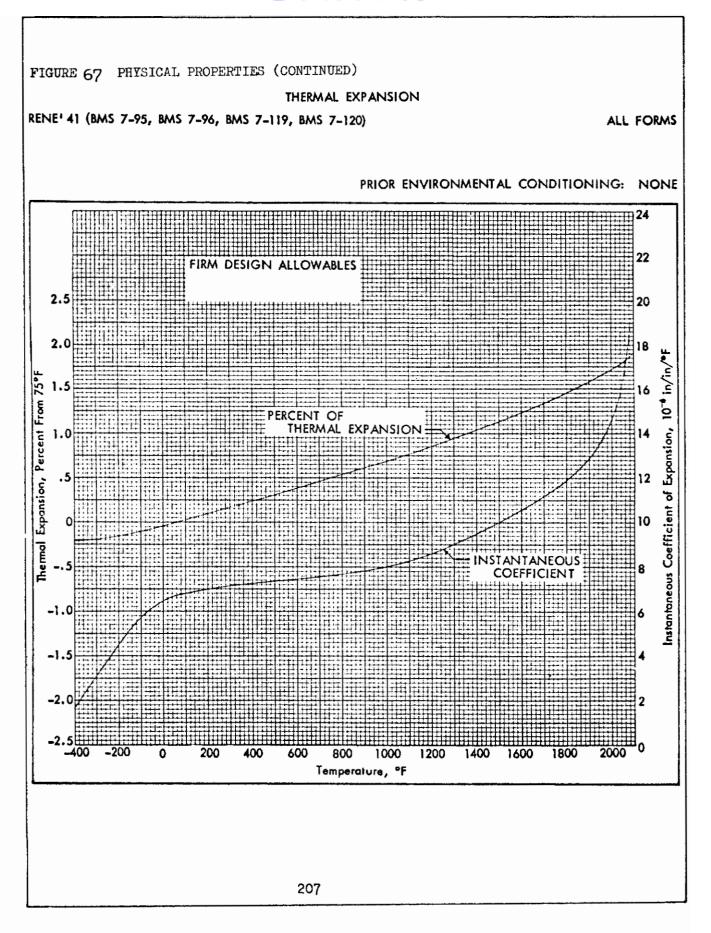
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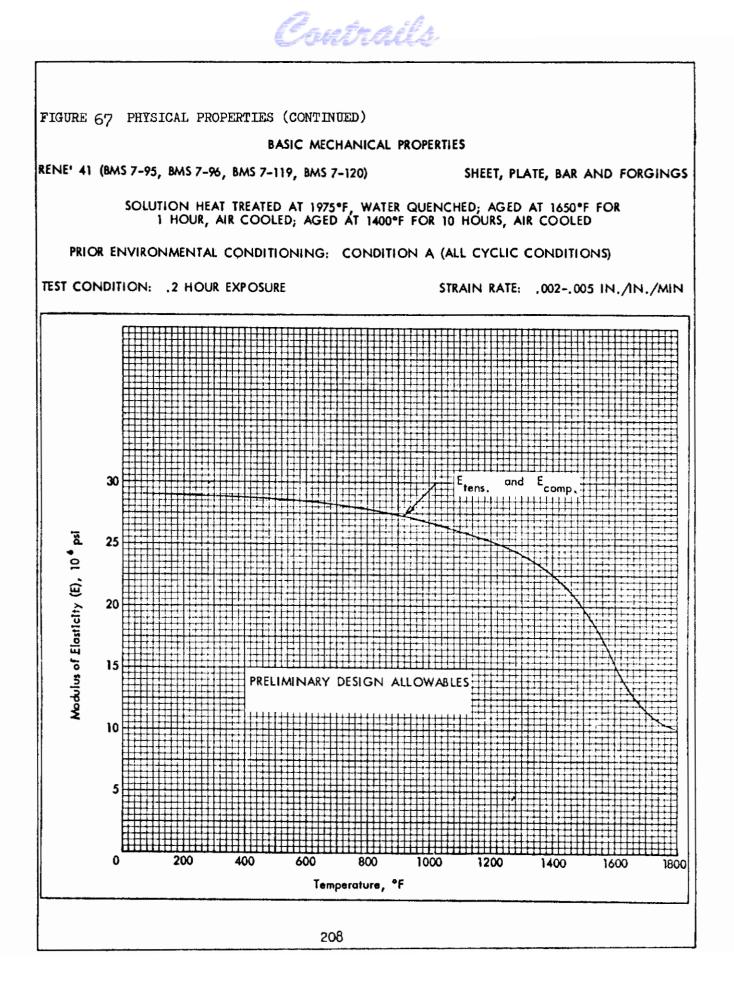


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### FUSED SILICA

### GENERAL NOTES

Fused silica is an extremely pure 100% SiO<sub>2</sub> glass. The 2860°F softening point is the highest temperature capability of all the materials commonly considered for aircraft glazing.

### MANUFACTURING PROCESSES

Regular glass cutting methods may be used to cut this material.

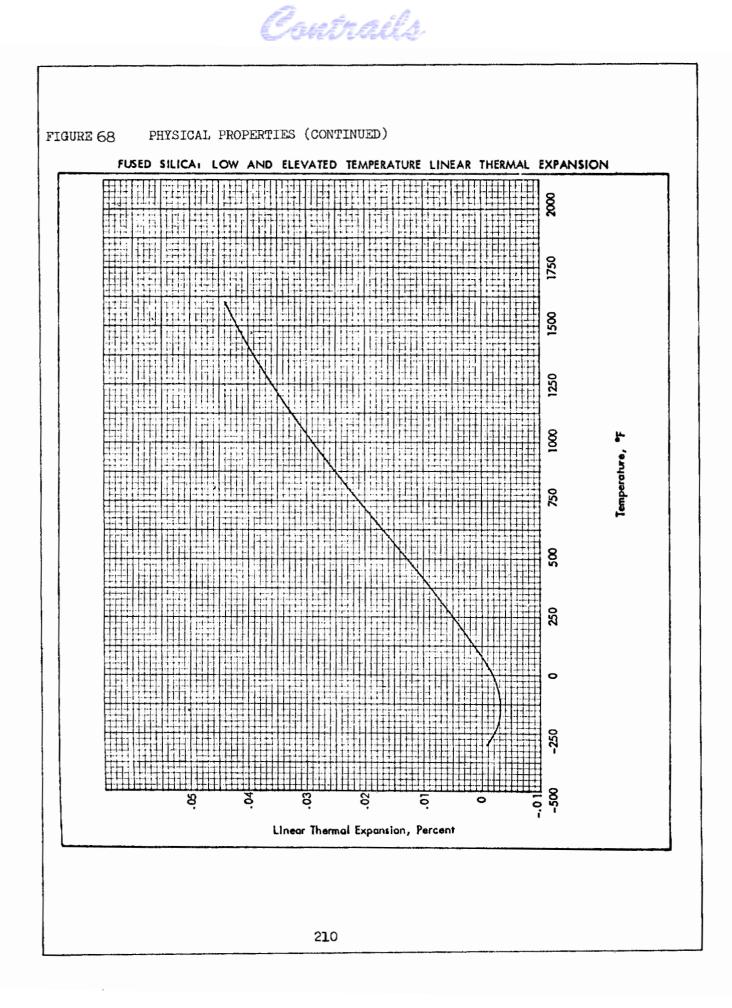
THICK NESS	COST/IN <sup>2</sup>
1/8 "	\$ 3.75
1/4"	5.25
3/8"	6.50
1/2"	7.80
5/8"	8.60
3/4"	10.30
7/8"	11.70
1"	12.85

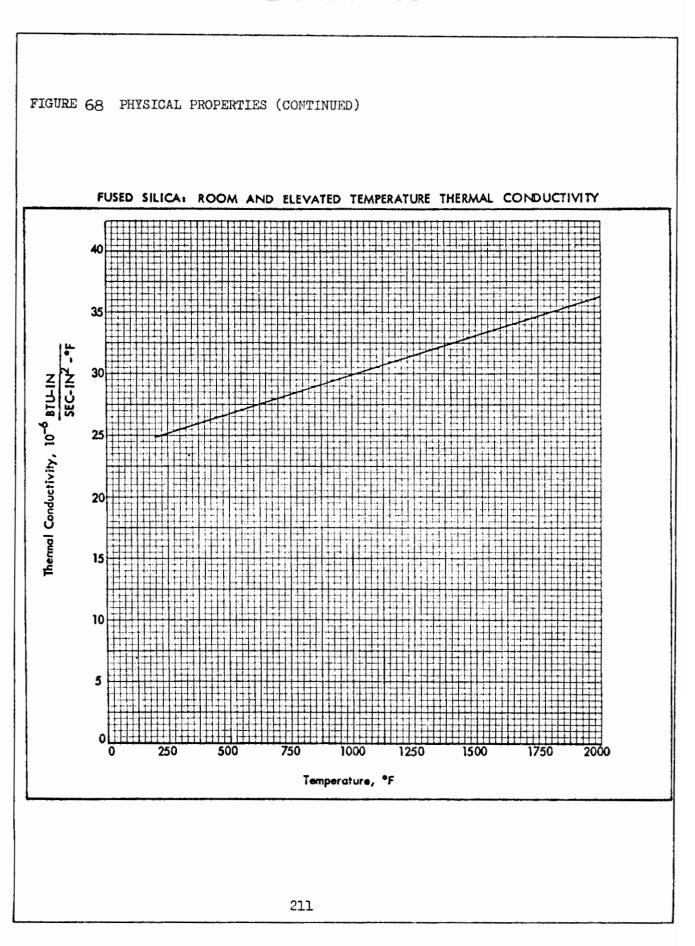
### FIG 68 PHYSICAL PROPERTIES

### PROCUREMENT INFORMATION

Fused silica produced by Corning Glass Works is designated No. 7940 and is manufactured in industrial, optical, and ultrasonic grades. It is available in diameters up to 60 inches. Prices listed are typical for the optical grade.

Density	.0796 lb/In <sup>3</sup>
Softening Point	2880°F





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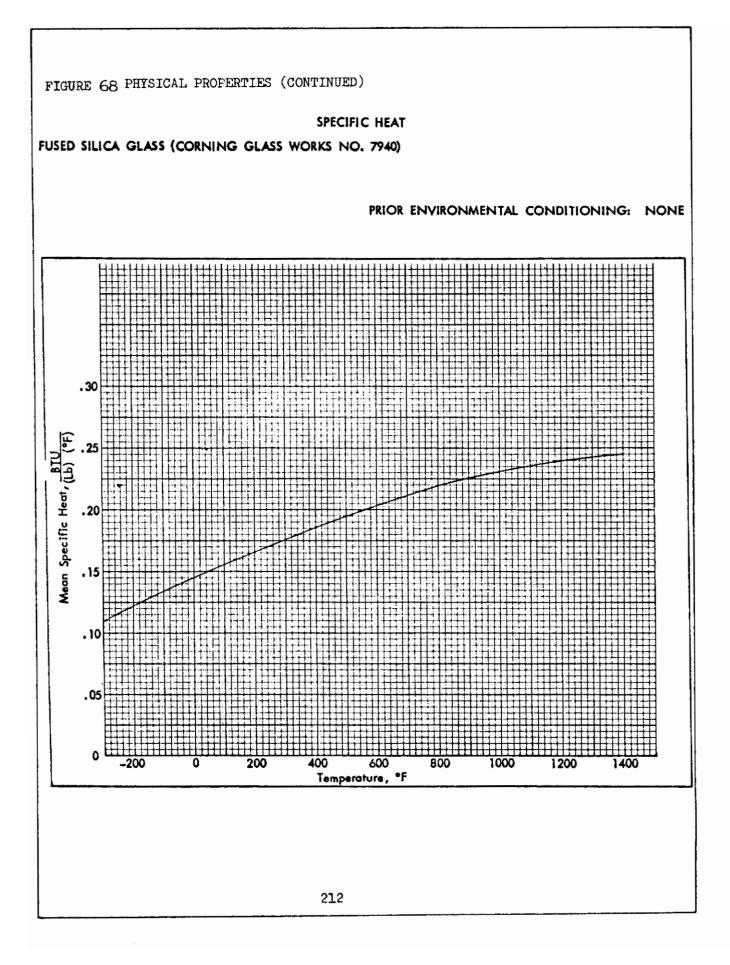
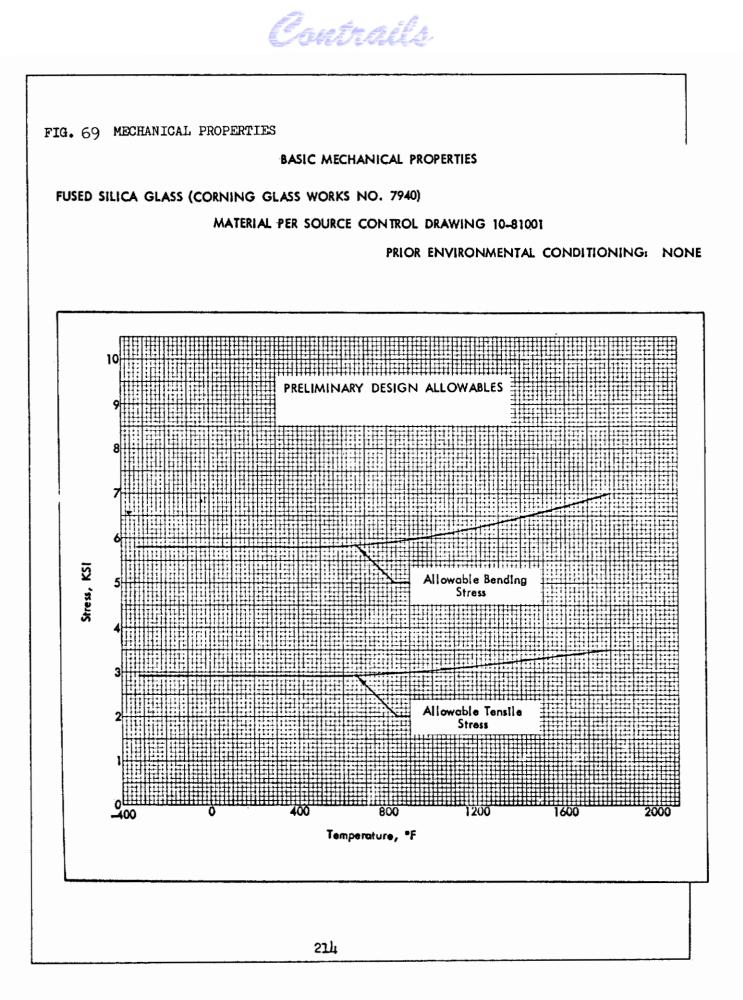
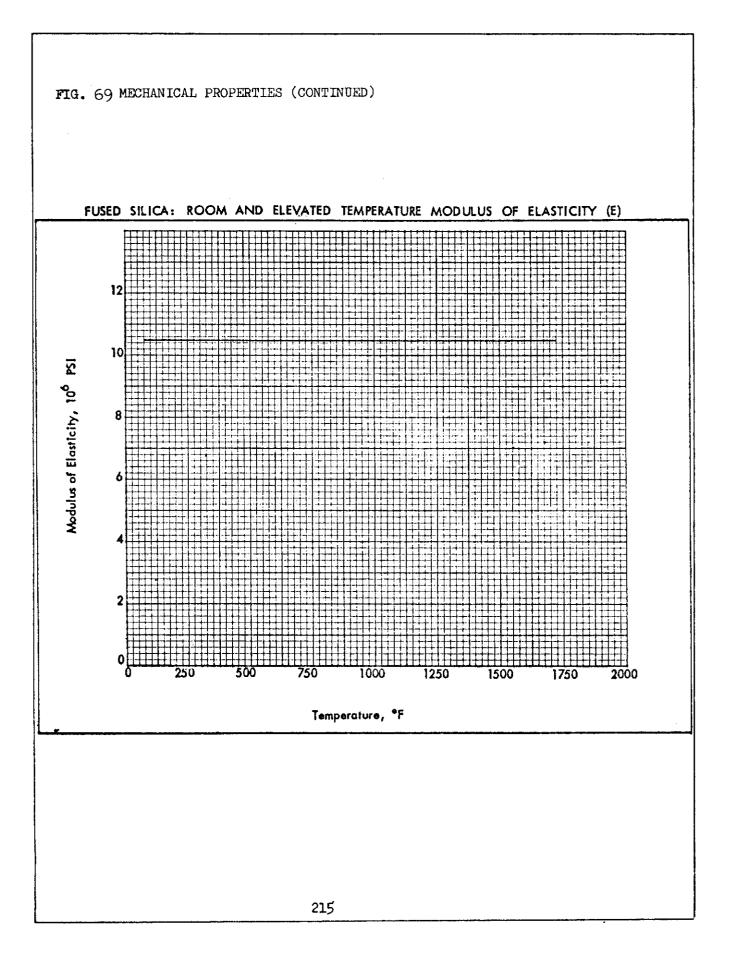


FIG. 68 PHYSICAL PROPERTIES (CONTINUED) TOTAL NORMAL EMITTANCE FUSED SILICA GLASS (CORNING GLASS WORKS NO. 7940) MATERIAL AND COATING PER SOURCE CONTROL DRAWING 10-81001 PRIOR ENVIRONMENTAL CONDITIONING: NONE PRELIMINARY DESIGN ALLOWABLES COND. TOTAL UNCOATED COND. 2 STANNIC OXIDE 1.0 IΕ COATING, 40 OHM TOTA .9 COND. 3 FIFFI TOTAL .8 COND. 2 .50 THICK **Jotal Normal Emittance** COND. 1 .50 THICK •7 COND. 2.25 THICK COND. 1.25 THICK i di sun i COATING FAILS COND. 3 .25 - .50 THICK NOTE These are typical property curves. They should be adjusted vertically plus or minus 10 percent in a direction conservative for the particular application. 800 1600 400 1200 2000 2400 Temperature, °F 213





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### REFERENCES

- 1. D2-80088, Window Development Dyna-Soar
- 2. D2-80706, Smoothness, Sealing and Venting Specifications for X-20 Glider and Transition
- 3. D2-81142, X-20 Boost, Hypersonic, Approach, and Air Launch Phase Load Conditions
- 4. D2-81293, X-20 Side Window Vibration, Heat, and Load Test Plan
- 5. D2-81300, Side Window Strength Check Notes Model X-20
- 6. D2-90709-1, Hot Structures Thermal Correlation
- 7. 10-81001, Code Ident. No. 81205 Size A Source Control Drawing, Dyna-Soar Transparent Structures

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Con	trails				
Unclassified					
Security Classification					
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N/A	Design Conce AFFDL - Wrig		terson AFB, Ohio.		
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The purpose of this program was to ex assembly and provide experience for i program was to verify the structural	mproved window	design.	. The objective of this		
window design in the X-20A flight env the design analysis and development p			test data to evaluate		
The window was subjected to a low-lev acting (partial vacuum) limit boost p entry heating time-temperature histor	ressure of 7.7				
The window failed during the re-entry failure was the high temperature grad of approximately 850°F which exceeded The extreme thermal gradient caused t induced glass curvature in excess of	ient through th by a factor of hermal curvatur	ne depth 2 the	n of the window frame ultimate design value.		
Measured temperature and deflections values. A thermal analysis is presen iencies of the X-20 window design as pointed out and suggested methods of	ted and compare determined <b>fr</b> om	ed with 1 the te	test values. Defic- est program are		
DD					

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14. KEY WORDS		LIN	LINK A		LINK B		LINK C	
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